

MICHAEL KWOK

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🌐 n30phyte

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📍 Edmonton, AB

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EDUCATION

BSc. Computer Engineering

University of Alberta

📅 September 2017

📍 Edmonton, AB, Canada

PROJECTS

BudgetPacman

📅 19 Jan 2020

🌐 loravocado/BudgetPacman

- A project for HackED 2020 with the goal of making a version of tag that used a phone and GPS locations.
- Implemented a server using Socket.io and Typescript, learning both technologies overnight.
- Won best use of Google Cloud Platform APIs.
- **Technologies:** React Native, Typescript, JavaScript

github.io Webpage

📅 Ongoing Project

🌐 n30phyte.github.io

- A playground for learning web technologies for single page applications.
- **Technologies:** Vue, HTML, CSS, JavaScript

AI Pong

📅 28 November 2018

🌐 n30phyte/HackEDBeta2018

- First large scale team project in C++, using SFML to write a Pong clone to be controlled by a Python AI agent.
- Written during HackED Beta 2018, a hackathon hosted by the University of Alberta Computer Engineering Club.
- Experienced becoming a leader for a small project group,
- **Technologies:** C++, SFML, Python, Keras, TensorFlow

SpotifyThing

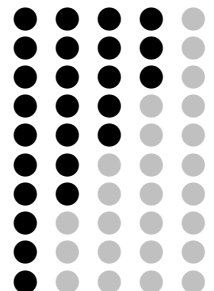
📅 2 January 2018

🌐 n30phyte/SpotifyThing

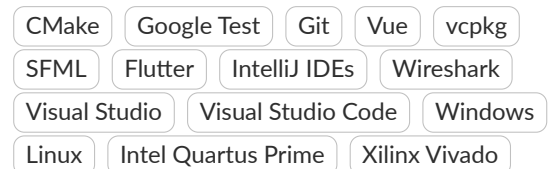
- Created a small script to automate the monotonous and repetitive task of turning Spotify playlists to CSV files.
- Gained experience in using RESTful Services.
- **Technologies:** C#, Spotify Web API

PROGRAMMING LANGUAGES

C++
Python
C#
LaTeX
Shell Scripting
JavaScript
TypeScript
Verilog
Matlab
VHDL



TECHNOLOGIES & PROGRAMS



VOLUNTEERING

VP Finance

Indonesian Students' Association Edmonton
PERMIKA Edmonton

📅 January 2019 – Present

- Helped restart the chapter after 2 years of inactivity due to lack of manpower.
- Manage finances and budgeting for events and fundraisers.
- Successfully budgeted a fundraisers that allowed us to operate comfortably.
- Secured funding in the form of grants and sponsorships that allowed our group to grow.

Software Team Member

Autonomous Robotic Vehicle Project

📅 May 2018 – December 2019

- Increased productivity by writing scripts that help automate various repetitive tasks, interfacing with Google App APIs, GitHub's API and simulation scripts for ROS in C++ and Python.
- Improved test coverage for robot's control systems by writing Google Test unit tests.
- Updated old and undocumented code to fix issues and add features.