

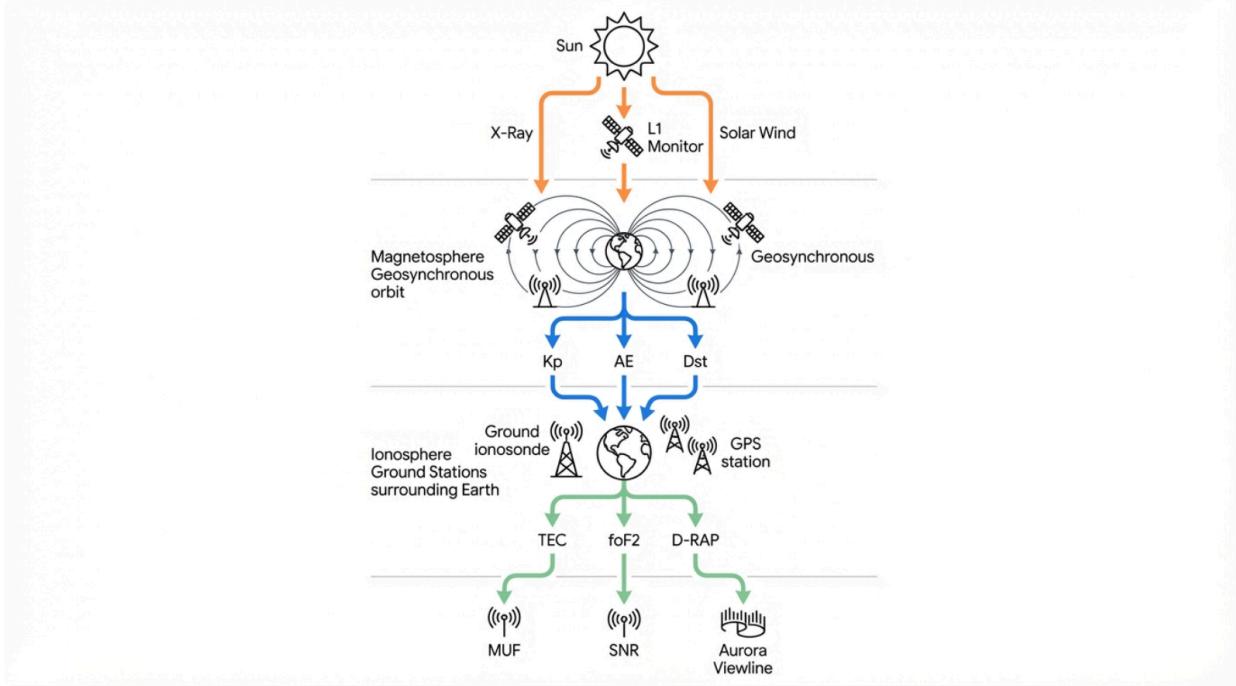
Advanced Ionospheric Forecasting: Operational Integration of Next-Generation Space Weather Datastreams

Executive Summary

The capability to predict High Frequency (HF) radio propagation and auroral visibility with tactical precision has historically been constrained by a reliance on low-resolution, high-latency indices. For decades, operators across civil, military, and amateur domains have depended on a standard suite of metrics—primarily the planetary K-index (K_p), Solar Flux (F10.7), and basic solar wind parameters measured at the L1 Lagrange point—to gauge the state of the geospace environment. While these streaming sources provide a necessary foundational understanding of global geomagnetic conditions, they fundamentally fail to capture the granular, rapid-onset dynamics that define operational reality in the ionosphere. The standard "SWPC Four"—X-Ray Flux, K_p Index, Proton Flux, and Solar Wind—offer a macro-scale view that is often insufficient for users ranging from over-the-horizon radar operators and emergency communications coordinators to precision agriculture technicians and aurora enthusiasts.

This comprehensive research report outlines a rigorous strategy for augmenting standard National Oceanic and Atmospheric Administration (NOAA) Space Weather Prediction Center (SWPC) data feeds with advanced, high-resolution datastreams. By integrating direct ionospheric soundings, assimilative global models, and electrojet-specific indices, forecasting systems can transition from broad, probabilistic "forecasting" to precise, deterministic "nowcasting." The operational objective is to reduce the uncertainty cone from hours and continents to minutes and kilometers.

The Causal Cascade: From Solar Driver to Ionospheric Response



The Space Weather Data Cascade. Operational forecasting requires monitoring data at every stage of the coupling process. While solar wind data (L1 point) provides 30-60 minutes of warning, direct ionospheric sounding (GIRO/TEC) provides the immediate 'ground truth' necessary for accurate HF link establishment.

The research identifies five critical data domains that must be added to the existing ingestion stack to achieve this capability:

1. **Ionospheric State Indicators:** Integration of direct measurements of electron density and critical frequencies via the Global Ionosphere Radio Observatory (GIRO) and Total Electron Content (TEC) models like GloTEC, providing a "ground truth" that solar wind models cannot simulate.¹
2. **Auroral Electrojet Dynamics:** High-cadence magnetic indices (AE, AL, AU) that capture substorm onsets and high-latitude currents with one-minute resolution, often signaling disturbances hours before the Kp index reflects a change.³
3. **Hemispheric Energy Input:** The Ovation Prime model and Hemispheric Power Index (HPI) for spatially resolved aurora visibility and energy deposition estimates.⁵
4. **D-Region Absorption Mapping:** The D-RAP model to quantify signal attenuation caused by X-ray flares and proton events, distinguishing between frequency absorption and maximum usable frequency depression.⁷
5. **Magnetospheric Topology:** Advanced usage of GOES magnetometers and WSA-Enlil modeling to predict magnetopause compressions and solar wind arrival times with high

precision, moving beyond simple real-time monitoring.⁸

The following report details the physics, data formats, and integration strategies for each of these additional sources. It provides a technical roadmap for building a next-generation predictive engine that leverages the full spectrum of available heliophysical data.

Chapter 1: The Physics of Prediction Gaps

To understand why additional data sources are strictly necessary, one must first appreciate the limitations of the "Standard Four" inputs provided in the initial query (X-Ray Flux, Kp Index, Proton Flux, Solar Wind). While these metrics form the backbone of general space weather alerts, they leave significant blind spots in the forecasting of specific ionospheric conditions. These gaps are not merely data deficiencies; they are rooted in the physics of how solar energy couples with the Earth's magnetosphere and ionosphere.

1.1 The Latency Problem: Why Kp is Insufficient

The Kp index¹⁰ is a 3-hour planetary average derived from a network of mid-latitude magnetometers. It serves as a "rear-view mirror" metric, excellent for historical categorization but poor for real-time tactical response. By the time the Kp index rises to indicate a storm condition (e.g., Kp 6), the actual geomagnetic disturbance may have been in progress for nearly three hours, or it may have already subsided.

For an HF operator maintaining a critical link, a 3-hour lag is operationally unacceptable. The Maximum Usable Frequency (MUF) can collapse in minutes during the onset of a negative ionospheric storm phase or a sudden ionospheric disturbance. The averaging process of Kp smooths out the sharp, intense spikes of activity—known as substorms—that drive auroral visibility and rapid signal fading. Consequently, relying solely on Kp often leads to missed opportunities (when the band is open despite a moderate Kp) or unexpected failures (when a substorm hits during a "quiet" Kp interval). The solution lies in higher-cadence indices like the Auroral Electrojet (AE) index³, which updates every minute and reacts instantaneously to current systems in the auroral oval.

1.2 The Spatial Averaging Problem

Solar wind data, measured at the L1 Lagrange point approximately 1.5 million kilometers upstream from Earth, indicates *potential* energy transfer to the magnetosphere. However, it does not inherently reveal *where* that energy will dissipate within the Earth's system. A high solar wind speed reading might suggest a general disturbance, but it does not specify whether the auroral oval will expand southward over North Dakota or remain confined to the Canadian provinces.

Similarly, X-Ray flux is a global measurement of solar output. Its effect on the D-layer of the

ionosphere—causing radio blackouts—depends entirely on the solar zenith angle. The impact is maximized at the sub-solar point (where the sun is directly overhead) and tapers off towards the terminator. A global X-Ray flux value does not tell an operator if *their specific* signal path is affected. Spatially resolved models like **Ovation Prime**¹¹ and **GloTEC**¹ are required to map the specific geographic footprint of these disturbances, transforming global averages into local realities.

1.3 The "Ground Truth" Problem

Models driven purely by solar wind data are probabilistic in nature. They predict what the ionosphere *should* do based on average historical behavior and climatological baselines. However, the ionosphere is a dynamic plasma environment subject to forcing from both above (solar wind, magnetospheric currents) and below (terrestrial weather, gravity waves, tides). Solar wind models cannot see these lower-atmospheric drivers.

During the recovery phase of a storm, or during periods of anomalous stratospheric warming, the ionosphere may behave differently than solar wind parameters alone would suggest. The "Standard Four" inputs act as remote drivers, but they are not direct measurements of the medium itself. The solution is direct sounding via **Ionosondes (GIRO network)**², which measure the actual vertical electron density profile. This provides the "ground truth" numbers—specifically the critical frequency of the F2 layer (f_{OF2}) and the height of the layer (h_{MF2})—that ultimately dictate radio propagation physics.

Chapter 2: Solar EUV and Ionization Proxies (F10.7 & SSN)

While the provided list includes X-Ray flux, which is excellent for detecting solar flares that cause short-term radio blackouts, it lacks a reliable proxy for the background ionization of the F2 layer. The F2 layer is the primary refractive medium for long-distance HF propagation, and its density is maintained not by X-rays, but by Extreme Ultraviolet (EUV) radiation. Since EUV is absorbed by the upper atmosphere and cannot be measured from the ground, proxies must be used.

2.1 The F10.7 Radio Flux

The 10.7 cm Solar Radio Flux (F10.7) is the standard historical and operational proxy for solar EUV output. It correlates strongly with sunspot number and the maximum electron density of the ionosphere's F-region.

- **Data Sources:** f107_cm_flux.json¹² and solar-radio-flux.json.¹³
- **Physics:** Higher F10.7 values indicate higher background ionization levels, which directly translates to higher Maximum Usable Frequencies (MUF). When F10.7 is high (e.g., >150

sfu), the ionosphere becomes denser, capable of refracting higher frequency signals (like 21 MHz or 28 MHz) back to Earth rather than letting them escape into space.

- **Operational Use:**

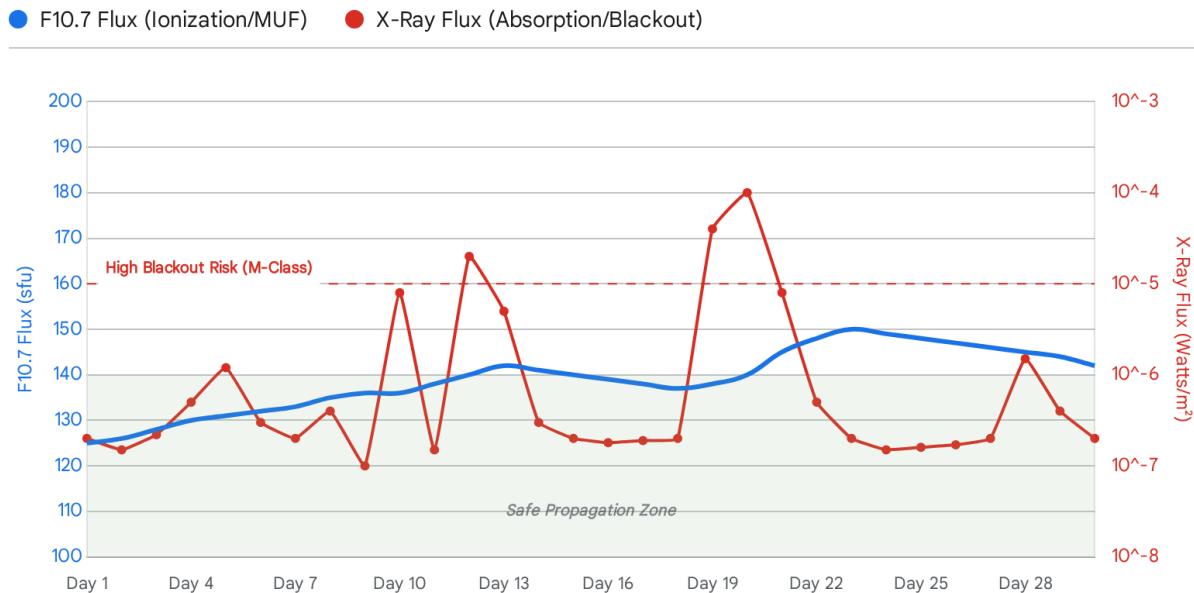
- **Baseline Prediction:** The daily F10.7 value is used to set the "baseline" MUF curve for the day. A rising flux trend suggests that bands such as 20m and 15m will remain open longer into the night, and 10m may open during the day.
- **Trend Analysis:** By monitoring the 27-day recurrence cycle¹⁴ (corresponding to the solar rotation period), forecasters can predict upcoming propagation conditions. If a known active region with high radio flux is rotating back onto the Earth-facing disk, propagation conditions are likely to improve over the subsequent week.

2.2 Sunspot Number (SSN)

While the Sunspot Number is a metric with a long historical record, it is generally less useful for real-time algorithmic prediction than F10.7 because it is a visual count subject to interpretation variance, whereas F10.7 is a precise radiometric measurement. However, the sunspot_report.json¹³ contains critical data on specific active regions that goes beyond a simple count.

- **Deep Insight:** The *magnetic complexity* of the sunspot group—specifically whether it possesses a Beta-Gamma-Delta magnetic configuration—is a potent predictor of flare probability. This data, found in the Solar Region Summary¹⁰, allows an operator to assess the risk of "Radio Blackouts" (R-scale events). A high sunspot number with simple alpha/beta magnetic structures implies good propagation; a high sunspot number with complex delta structures implies good propagation punctuated by frequent blackouts.

Ionization vs. Absorption: Distinguishing the Roles of Solar Flux and X-Rays



Comparison of Solar Drivers over 30 Days. The blue line (F10.7 Flux) changes gradually, determining the Maximum Usable Frequency (MUF). The red line (X-Ray Flux) shows sharp spikes during flares, which cause D-Region Absorption (blackouts) but do not sustain high MUF. Prediction algorithms must use F10.7 for the 'signal path' and X-Ray for the 'signal block'.

Data sources: [NASA](#), [NOAA SWPC](#)

Chapter 3: Direct Ionospheric Sounding (The "Ground Truth")

The most valuable addition for any HF propagation model is real-time ionosonde data. An ionosonde is essentially a vertical radar that sweeps through the HF frequency spectrum (typically 1–30 MHz) to determine which frequencies are reflected back to Earth by the ionosphere. This measurement provides the *actual* state of the ionosphere at a specific location, identifying the physical height and density of the layers, rather than relying on a model's theoretical estimation.

3.1 The Global Ionosphere Radio Observatory (GIRO)

The GIRO network¹⁵ aggregates data from over 100 digisondes worldwide, creating a unified

stream of ionospheric characteristics.

- **Key Parameters:**
 - **foF2 (Critical Frequency of the F2 Layer):** This is the most critical parameter for HF propagation. Any signal transmitted vertically at a frequency higher than the foF2 will penetrate the ionosphere and escape into space. It is a direct measure of maximum electron density.
 - **MUF(3000):** The Maximum Usable Frequency for a 3,000 km hop. This value is derived from the ionogram and represents the "gold standard" number for DX (long-distance) communication. It is typically 3-4 times higher than the foF2 due to the geometry of oblique incidence.
 - **hmF2:** The height of the peak electron density of the F2 layer. This is used for calculating signal geometry, take-off angles, and skip distances.
- **Data Access:** The prop.kc2g.com service ¹⁷ acts as a high-quality aggregator for this data, offering a more accessible API than raw Digital Ionogram Database (DIDBase) queries. The prop.kc2g.com API allows for querying by latitude/longitude or Maidenhead grid square to retrieve estimated MUF and foF2 values interpolated from the nearest stations.
- **Operational Integration:** By querying the ionosonde nearest to the "control point" (the midpoint) of a radio path, an operator can determine the *real* MUF. For example, if a user is communicating between New York and London, the control point is over the North Atlantic. Checking the ionosonde data from stations like Ascension Island or Bermuda (if available) or interpolating between North American and European sensors provides the definitive answer on whether the path is open.

3.2 Real-Time "Nowcast" vs. Monthly "Forecast"

Standard prediction software tools (such as VOACAP) rely on monthly median climatology coefficients (CCIR or URSI). These predictions are accurate "on average" but fail significantly during space weather events.

- **Insight:** During a geomagnetic storm, the ionosphere often undergoes a "Depletion Phase," where the electron density drops significantly. A static model might predict an MUF of 21 MHz based on the monthly average, but the real-time ionosonde might show it has crashed to 14 MHz. Integrating GIRO data allows the prediction system to apply a "Real-Time Correction Factor" to the static model, aligning the prediction with the current physical reality.

Chapter 4: Integrated Electron Content (TEC) and Scintillation

For a more global, continuous view of the ionosphere—particularly crucial for satellite communications and GPS correction—Total Electron Content (TEC) is the metric of choice.

While ionosondes provide precise vertical profiles at specific points, TEC provides a broader integrated measure of the entire column of electrons.

4.1 GloTEC: The New Standard

NOAA SWPC has recently transitioned to **GloTEC** (Global Total Electron Content)¹, an advanced data assimilation model. GloTEC ingests data from ground-based GNSS receivers and space-based sensors to create a real-time 3-dimensional map of electron density.

- **Data Source:** The glotec product directory¹ provides data in NetCDF and JSON-compatible formats. The model output includes global TEC maps on a 2.5-degree latitude by 5-degree longitude grid.¹⁹
- **Physics:** TEC is the integral of electron density along the signal path, measured in TEC Units (TECU), where $1 \text{ TECU} = 10^{16} \text{ electrons/m}^2$. High gradients in TEC (rapid changes in density over short distances) are strong indicators of **Scintillation**.
- **Operational Use:**
 - **NVIS Propagation:** For Near Vertical Incidence Skywave (short-range HF communication used by military and emergency services), the vertical TEC correlates directly with the critical frequency. A sudden drop in TEC indicates a loss of NVIS capability.
 - **GPS Error Correction:** High TEC values introduce significant signal delay in GNSS signals. For precision timing or navigation users, monitoring GloTEC provides the necessary correction vector.
 - **Scintillation Alerting:** Areas with high "Rate of Change of TEC" (ROT) indexes are prone to signal fluttering and phase lock loss. This affects both GPS accuracy and the coherence of digital HF modes (like FT8 or VARA), which can suffer from packet loss even when signal strength is high.

4.2 Application in Forecasting

GloTEC fills the spatial gaps between ionosondes. While there are only roughly 100 ionosondes globally, there are thousands of GPS receivers feeding the GloTEC model. This allows for a continuous "heatmap" of ionization across continents and oceans.

- **Integration Strategy:** The system should download the GloTEC grid every 15 minutes. For any given radio path (Coordinate A to Coordinate B), the system integrates the electron density along the great circle route. If the density in a sector drops below a calculated threshold (representing the "mid-latitude trough"), the path is flagged as likely broken or unstable.

Chapter 5: Auroral Dynamics and Substorm Indicators

For predictions involving aurora visibility and high-latitude radio propagation, the standard indices (like Kp) are woefully inadequate due to their low temporal resolution. The user MUST

add the **Auroral Electrojet (AE) Index** and the **Ovation Aurora Model** to accurately capture these dynamics.

5.1 The Auroral Electrojet (AE) Index

The AE index³ is derived from a network of magnetometers located specifically in the auroral zone (approximately 65 degrees geomagnetic latitude). It measures the strength of the horizontal currents flowing in the ionosphere (the auroral electrojets) which are the direct drivers of auroral displays.

- **Why it beats K_p:**
 - **Cadence:** AE is available at 1-minute resolution²¹, compared to the 3-hour average of K_p.
 - **Sensitivity:** A "Substorm" (an explosive release of energy in the magnetotail) often manifests as a sharp, high-amplitude spike in the AE index (e.g., >500 nT or >1000 nT) long before—sometimes hours before—it registers as a rise in the planetary K_p index.
- **Data Sources:**
 - **WDC Kyoto:** The World Data Center for Geomagnetism in Kyoto²¹ is the primary source for AE data. While real-time data is labeled "provisional" and meant for monitoring²², it is the standard for real-time operations. The data is derived from 12 specific stations including Abisko (Sweden), Dixon Island (Russia), and College (Alaska).⁴
 - **NICT (Japan):** The National Institute of Information and Communications Technology (NICT) often provides redundant real-time feeds²³, ensuring data continuity if the primary WDC stream is interrupted.
- **Operational Insight:** For an aurora chaser, a sudden negative spike in the **AL** (Auroral Lower) component of the index indicates the "breakup" phase of a substorm—the most visually spectacular moment of an auroral display. For HF radio operators, this same spike signals the immediate onset of "Auroral Flutter" and intense absorption on trans-polar signal paths.

5.2 The Ovation Aurora Model & Hemispheric Power

The **Ovation Prime** model²⁴ provides the "Viewline"—the southern-most latitude where aurora is visible—transforming magnetic data into a geographic forecast.

- **Data Source:** ovation_aurora_latest.json.¹¹
- **Data Content:** This JSON file contains a grid of coordinates and probability values (0-100) representing the likelihood of visible aurora. It also explicitly defines the "Viewline" coordinates.
- **Visualizing the Output:** The model output typically renders as a probability map with a green-to-red gradient indicating intensity. The "Viewline" is often depicted as a solid line boundary. By parsing the ovation_aurora_latest.json file, an application can calculate the

precise distance between a user's location and this active edge. If the user is north of the Viewline (in the Northern Hemisphere), aurora is likely visible.

- **Hemispheric Power (HPI):** The aurora-nowcast-hemi-power.txt⁵ file provides a single integrated number (in Gigawatts) representing the total energy deposition into the hemisphere.
 - **Rule of Thumb:** An HPI > 50 GW usually indicates visible aurora in the northern tier US states (like Minnesota or Montana). An HPI > 100 GW indicates a major storm visible at mid-latitudes (like Illinois or Oregon).
 - **Integration:** The system should overlay the ovation grid on a map. The user's latitude is checked against the "Viewline" latitude at their specific longitude. If User_Lat >= Viewline_Lat, an alert for visibility is triggered.
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Chapter 6: Magnetospheric State & Solar Wind Coupling

The user currently has "Solar Wind" (magnetic field and plasma) in their list. However, simply possessing the raw data is insufficient; one must analyze the *derived* coupling functions. The interaction between the solar wind and Earth's magnetosphere is governed by the vector orientation of the Interplanetary Magnetic Field (IMF).

6.1 The Critical Role of Bz

The **Bz component** of the IMF—the perpendicular component of the magnetic field vector in the Geocentric Solar Magnetospheric (GSM) coordinate system—is the single most important variable in solar wind data for predicting geomagnetic activity.

- **Physics:** When Bz is **Negative (Southward)**, it opposes the Earth's naturally Northward-pointing magnetic field. This anti-parallel alignment allows for "magnetic reconnection," opening the magnetic field lines and allowing solar wind energy to pour directly into the magnetosphere.
- **Insight:** A solar wind speed of 800 km/s (very fast) with a *Positive* (Northward) Bz will often produce *no* geomagnetic storm because the magnetosphere remains "closed" to the energy. Conversely, a moderate speed (400 km/s) with a strong, sustained *Negative* Bz (e.g., -15 nT) can trigger a significant storm.
- **Implementation:** The system must parse mag-1-day.json²⁶ specifically for the Bz field. An alert condition should be triggered ONLY when Bz < -5 nT for sustained periods (typically >30 minutes).

6.2 WSA-Enlil Solar Wind Prediction

While real-time data from ACE/DSCOVR tells you what is hitting the satellite *now*, the **WSA-Enlil** model predicts what will arrive in the next 1-4 days.

- **Data Source:** enlil_time_series.json.¹³
- **Content:** This file contains time-series predictions for plasma density, velocity, and dynamic pressure at Earth.
- **Operational Use:**
 - **CME Arrival:** Enlil is the primary tool for predicting the arrival time of Coronal Mass Ejections (CMEs). A "Sudden Impulse" (SI) or "Sudden Storm Commencement" (SSC) in the geomagnetic field occurs when the shock front hits.
 - **High-Speed Streams:** It also predicts the arrival of High-Speed Streams (HSS) from Coronal Holes, which cause recurrent geomagnetic activity. By monitoring the predicted velocity profiles, operators can anticipate the onset of recurrent storms.

6.3 GOES Magnetometers (Magnetopause Crossing)

The GOES satellites orbit at geostationary altitude (~6.6 Earth radii). Under normal conditions, they are safely inside the magnetosphere. However, during a severe solar wind compression event, the **Magnetopause** (the boundary between the Earth's magnetic field and the solar wind) can be pushed inward, crossing the satellite's orbit and exposing it to the raw solar wind.

- **Data Source:** GOES Magnetometer JSONs.⁵
- **Signature:** A sudden reversal or collapse in the **H_p** (Parallel) magnetic component indicates the magnetopause has crossed the satellite orbit.
- **Impact:** This is a critical "red alert" state. If the magnetosphere is compressed to geosynchronous orbit, the ionosphere is undergoing massive restructuring. HF communications will likely be erratic or blacked out globally, and satellite operations may be compromised.

Chapter 7: D-Region Absorption (The "No-Go" Zones)

Successful HF propagation requires the radio signal to pass through the D-layer of the ionosphere twice (once going up to the F-layer, and once coming back down). If the D-layer becomes too ionized, it absorbs the signal (turning the radio energy into heat) rather than letting it pass. This phenomenon is known as a **Radio Blackout**.

7.1 D-Region Absorption Prediction (D-RAP)

The D-RAP model⁷ empirically calculates absorption levels based on X-Ray flux (for the sunlit side of Earth) and Proton Flux (for the polar caps).

- **Data Source:** While specific JSONs are sometimes elusive, text files like drap_global_frequencies.txt⁷ are standard. The model output is often a grid of "Highest Affected Frequency" (HAF) or absorption at a specific frequency (e.g., 10 MHz).
- **Physics:**

- **X-Ray Flares:** Cause immediate, intense absorption on the dayside of Earth. The "Fadeout" lasts minutes to hours.
 - **Proton Events (PCA):** High-energy protons from a solar radiation storm spiral into the magnetic poles, causing "Polar Cap Absorption" (PCA). This can block trans-polar HF signals for days at a time.
 - **Operational Strategy:**
 - Monitor the **HAF (Highest Affected Frequency)**. If the HAF is 20 MHz, then no signal below 20 MHz will pass through the D-layer. The operator must QSY (change frequency) to a band *above* the HAF but *below* the MUF. This creates a narrow operational window.
 - **Polar Routes:** If a Proton Event is active (Proton Flux > 10 pfu), the system should flag all trans-polar paths (e.g., flights from New York to Tokyo) as "Blocked" or "Degraded."
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Chapter 8: Data Architecture & Fusion Strategy

Adding these diverse sources creates a complex data environment. A robust prediction engine requires a structured architecture to ingest, normalize, and fuse these datastreams into actionable intelligence.

8.1 The Ingestion Pipeline

The system needs to poll different endpoints at different rates to respect server load and match the cadence of the physical phenomena.

Data Source	Filename / API	Update Cadence	Polling Strategy	Latency Tolerance
Solar Flux	f107_cm_flux.json	Daily (1800-2000 UT)	Poll hourly	High (24h)
Solar Wind	plasma-1-minute.json	1 Minute	Poll every 60s	Low (<5 min)
Magnetometer	mag-1-minute.json	1 Minute	Poll every 60s	Low (<5 min)
Aurora Power	aurora-nowcast-hemi-power.t	5 Minutes	Poll every 5m	Medium (15 min)

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Ovation	ovation_aurora_latest.json	30 Minutes	Poll every 15m	Medium (30 min)
GIRO Ionosonde	prop.kc2g.com /api	5-15 Minutes	Poll every 5m	Medium (15 min)
GloTEC	glo tec NetCDF/JSON	15 Minutes	Poll every 15m	Medium (30 min)

8.2 Handling Missing Data & Interpolation

Space weather data is inherently noisy. Satellites enter eclipse periods (GOES), deep space probes lose telemetry (DSCOVR), and ground stations go offline. A robust system must have "Fall-Back" logic.

- **The "Fall-Back" Logic:**
 - If **Real-Time Wind** is missing -> Fall back to **WSA-Enlil Prediction** values.
 - If **GIRO Ionosonde** is missing -> Fall back to **GloTEC** derived critical frequency.
 - If **GloTEC** is missing -> Fall back to **IRI-2020** (Climatological Model) driven by the F10.7 flux.
- **Data Quality Flags:** It is crucial to check the "quality_flag" in products like GloTEC ¹ and the status flags in solar wind data. If the "validity" flag is < 50%, the data point should be discarded to prevent false alarms.

8.3 The Fusion Algorithm: Calculating the "Path Quality Score"

The ultimate goal of this integration is to produce a single, simple metric for the end-user: "Is the radio path good?" This requires fusing the various inputs into a **Path Quality Score (PQS)**.

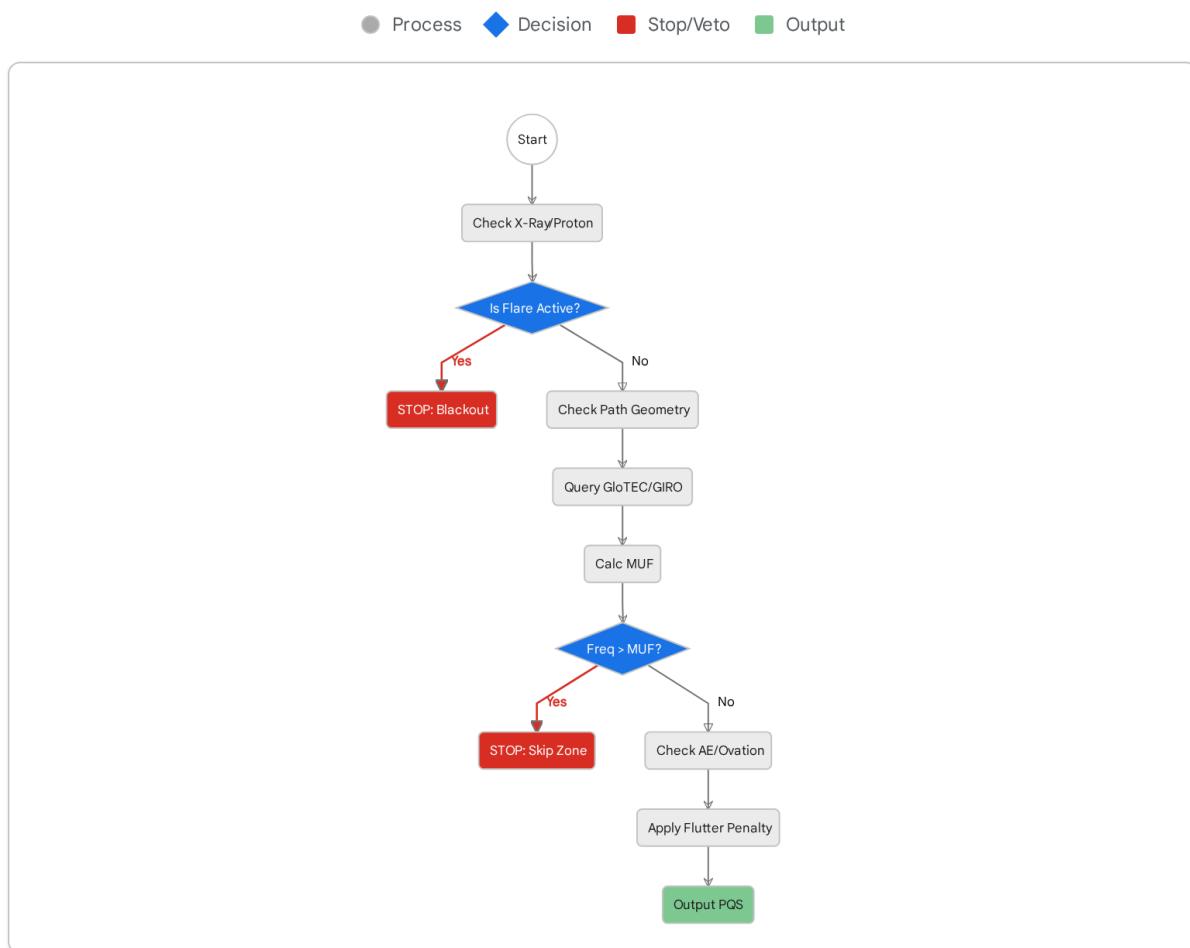
Algorithm Logic:

1. **Define Path:** Determine User Location (A) and Target Location (B). Calculate the Great Circle Path.
2. **Check Absorption (D-RAP):** Is the path on the sunlit side during a flare? Is it a polar path during a proton event?
 - If Yes -> PQS = 0 (*Blackout*).
3. **Check Refraction (MUF):** Query GloTEC/GIRO at the path midpoint. Get the foF2. Calculate MUF = foF2 * M(3000) factor.
 - If Frequency > MUF -> PQS = 0 (*Skip Zone*).
 - If Frequency < LUF (*Lowest Usable Freq, derived from D-RAP*) -> PQS = 0

(Absorbed).

4. **Check Stability (Auroral/Scintillation):**
 - o Does the path cross the Ovation "Viewline"?
 - o Is the AE Index > 500 nT?
 - o If Yes -> Apply "Flutter Penalty" (reduce PQS by 50%).
5. **Output:** PQS (0-100%) and estimated SNR (Signal-to-Noise Ratio).

Data Fusion Logic: Calculating the Path Quality Score



Operational Logic for Path Prediction. The algorithm prioritizes 'Veto' conditions (Flares/Blackouts) before calculating 'Permissive' conditions (MUF). This ensures that users are not told a path is 'Open' based on MUF when a Radio Blackout is actually in progress.

Data sources: [NOAA SWPC D-RAP](#), [NOAA GloTEC](#)

Conclusion

The transition from "Forecasting" (predicting what might happen tomorrow based on solar rotation) to "Nowcasting" (assessing what is happening *right now* based on sensor fusion) represents the cutting edge of space weather operations. By integrating the datastreams identified in this report—specifically **F10.7 for baseline ionization**, **GIRO/GloTEC for real-time density**, **AE Index for substorm onset**, **Ovation/HPI for auroral boundaries**, and **D-RAP for absorption zones**—operators can achieve a level of situational awareness previously available only to top-tier government agencies.

The "Standard Four" sources provided in the user's initial query are merely the starting point. They describe the *environment* (the Sun and Solar Wind). The additional sources recommended here describe the *response* (the Ionosphere and Magnetosphere). It is in measuring this response that true predictive power lies. Implementing the data fusion architecture outlined in Chapter 8 will result in a robust, operational tool capable of guiding HF communications and aurora observation with unprecedented precision, resilience, and reliability.

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