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EDUCATION

• Uppsala University
Ph.D. Student in Embedded Systems

2024–present Uppsala, Sweden

• KTH Royal Institute of Technology

2021-2023

M.Sc. Mechatronics

Stockholm, Sweden

• City University of Hong Kong

2017-2021

B.Eng. Mechanical Engineering

Hong Kong SAR, China

RESEARCH INTERESTS

• Cyber-Physical Systems

• Control & Dynamics

· Reinforcement Learning

JOURNAL PUBLICATIONS

- Tan, K., Niu, X., Ji, Q., Feng, L., & Törngren, M. Learning-enhanced Optimal Gait Design for a Tendon-driven Soft Quadruped Robot via Multi-fidelity Bayesian Optimization, under review at Information Sciences.
- Xu, Y., Niu, J., Xi, G., **Niu, X.**, Wang, Y., Guo, M., ... & Tian, J. (2018). TGF-β1 resulting in differential microRNA expression in bovine granulosa cells. *Gene*, 663, 88-100.

CONFERENCE PUBLICATIONS

• Niu, X., Tan, K., & Feng, L.. Optimal Gait Control for a Tendon-driven Soft Quadruped Robot by Model-based Reinforcement Learning, under review at AIM/TMECH.

OTHER PUBLICATIONS

- Maser Thesis: N. Xuezhi, Optimal Gait Control of Soft Quadruped Robot by Model-based Reinforcement Learning, Dissertation, 2023. Available: https://www.diva-portal.org/smash/record.jsf?pid=diva2:1810127
- HK project: EGENÄS, C., EKMAN, F., MA, C., NASER, T., NIU, X., SERNELIN, A., ... & STRÖM, B. (2023). Electronically Vacuum Regulated Shut-off Valve for Milking System. Available: https://www.diva-portal.org/smash/record.jsf?pid=diva2:1738909

ACADEMIC ACTIVITIES

• Teaching assistant for master level courses at KTH (MF2007) and Uppsala (1DT106)

AWARDS & ACHIEVEMENTS

CN patent Grant (CN 113675454 A), City University of Hong Kong	2020.9
Talent Development Scholarship, Hong Kong SAR, China	2020.6
• CN patent Grant (CN 14180645 A), City University of Hong Kong	2020.6
• Second Prize in National Finals of the Challenge Cup Competition, Beijing, China	2019.11
• Silver Prize in National Finals of Internet + Competition, Hangzhou, China	2019.10
Second Prize in HK University Student Innovation and Entrepreneurship Competition	2019.4