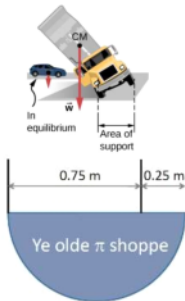




## Review



### FIRST EQUILIBRIUM CONDITION

The first equilibrium condition for the static equilibrium of a rigid body expresses translational equilibrium:

$$\sum_i \vec{F}_i = \vec{0}.$$

12.2

### SECOND EQUILIBRIUM CONDITION

The second equilibrium condition for the static equilibrium of a rigid body expresses rotational equilibrium:

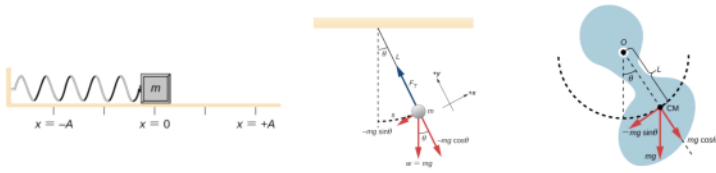
$$\sum_i \vec{r}_{i0} \times \vec{F}_i = \vec{0}.$$

12.5

Choose the origins = pivot points most advantageously!

## Learning Outcome

Find the Angular Frequency, Period of Motion, and Frequency of the following Oscillators:

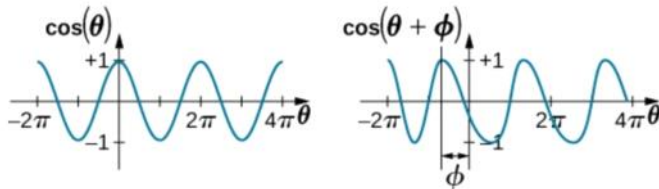


## Let's Fill our Toolbox!

What does this Equation describe?

$$x(t) = A \cos(\omega t + \phi)$$

position over time      frequency  
Amplitude      phase shift



amplitude  
starting position  
(without this, its just 1, which is why  $\cos(\theta)$  goes up to 1 and down to -1)

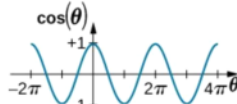
frequency  
how long it takes to complete a whole cycle.  
the larger this value, the more stretched out the wave is

phase-shift  
how far shifted left/right

## Let's Fill our Toolbox!

What else can we learn from this Equation?

$$x(t) = A \cos(\omega t + \phi)$$



$$v(t) = \frac{dx}{dt} = -A \sin(\omega t + \phi) \cdot \omega = -A \omega \sin(\omega t + \phi) \Rightarrow v_{\max} = A \cdot \omega$$

$$a(t) = \frac{dv}{dt} = -A \cos(\omega t + \phi) \cdot \omega^2 = -A \omega^2 \cos(\omega t + \phi) \Rightarrow a_{\max} = A \omega^2$$

## Let's Fill our Toolbox!

$$x(t) = A \cos(\omega t + \phi)$$

$$v(t) = -v_{\max} \sin(\omega t + \phi)$$

$$a(t) = -a_{\max} \cos(\omega t + \phi)$$

$$x_{\max} = A$$

$$v_{\max} = A \omega$$

$$a_{\max} = A \omega^2$$

$$[\omega] = \frac{\text{rad}}{\text{s}}$$

$$[\phi] = \text{rad}$$

$$v = \frac{dx}{dt}$$

$$\omega = \frac{2\pi}{T}$$

## Let's Fill Our Toolbox

- We define **periodic motion** to be any motion that repeats itself at regular time intervals. Angular speed (frequency) is cycle / time:

$$\omega = \frac{2\pi}{T} \quad T = \frac{2\pi}{\omega} : \quad f = \frac{1}{T}$$

$$1 \text{ Hz} = 1 \frac{\text{cycle}}{\text{s}} \quad \text{or} \quad 1 \text{ Hz} = \frac{1}{\text{s}} = 1 \text{ s}^{-1}$$

A cycle is one complete **oscillation**

here T is period not Tension

frequency is how many times it fulfills an oscillation in one second

## Let's Practice!

Given  $x(t) = \underline{5\text{m}} * \cos(10 \text{ rad/s} * t + 3)$ , what is the:

Amplitude = 5 m

Let's Practice!

Given  $x(t) = 5\text{m} * \cos(\underline{10 \text{ rad/s}} * t + 3)$ , what is the:

Angular Frequency =  $10 \text{ rad/s}$

Let's Practice!

Given  $x(t) = 5\text{m} * \cos(\underline{10 \text{ rad/s}} * t + 3)$ , what is the:

Period

$$T = \frac{2\pi}{\omega} = \frac{2\pi \cdot s}{10 \text{ rad}} \approx 0.6s$$

Let's Practice!

Given  $x(t) = 5\text{m} * \cos(10 \text{ rad/s} * t + 3)$ , what is the:

Frequency

$$f = \frac{1}{T} = \frac{1}{0.6} = 1.6667$$

Let's Practice!

Given  $x(t) = 5\text{m} * \cos(10 \text{ rad/s} * t + \underline{3})$ , what is the:

Phase constant =  $3 \text{ rad}$

Let's Practice!

Given  $x(t) = 5\text{m} \cdot \cos(10 \text{ rad/s} \cdot t + 3)$ , what is the:

Position after 1 ms?  $1\text{ms} = 0.001\text{s} = \frac{1}{1000}\text{s}$

$$\begin{aligned} x(1\text{ms}) &= 5\text{m} \cdot \cos\left(10 \frac{\text{rad}}{\text{s}} \cdot \frac{1}{1000}\text{s} + 3\text{rad}\right) \\ &= 5\text{m} \cdot \cos\left(\frac{1}{100} + 3\right) \end{aligned}$$

Let's Practice!

Given  $x(t) = 5\text{m} \cdot \cos(10 \text{ rad/s} \cdot t + 3)$ , what is the:

Velocity after 1 ms?

$$\begin{aligned} v(t) &= 5\text{m} \cdot 10 \frac{\text{rad}}{\text{s}} \cdot -\sin\left(10 \frac{\text{rad}}{\text{s}} \cdot \frac{1}{1000}\text{s} + 3\right) \\ &= -50 \cdot \sin(3.1\text{rad}) \end{aligned}$$

Let's Practice!

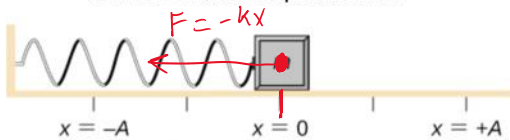
Given  $x(t) = 5\text{m} \cdot \cos(10 \text{ rad/s} \cdot t + 3)$ , what is the:

Acceleration after 1 ms?

$$a(1\text{ms}) = 5\text{m} \left(10 \frac{\text{rad}}{\text{s}}\right)^2 \cdot -\cos(3.14)$$

$$= -500 \frac{\text{m}}{\text{s}^2} \cdot \cos(3)$$

### Simple Harmonic Oscillator – Meet Differential Equations!



$$F_x = -kx$$

$$ma = -kx$$

$$m \frac{d^2x}{dt^2} = -kx$$

$$\frac{d^2x}{dt^2} = -\frac{k}{m}x$$

$$x(t) = A \cos(\omega t + \phi)$$

$$-A\omega^2 \cos(\omega t + \phi) = -\frac{k}{m}A \cos(\omega t + \phi)$$

$$\omega = \sqrt{\frac{k}{m}}$$

$$T = 2\pi \sqrt{\frac{m}{k}}$$

$$f = \frac{1}{T} = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$$

$$\omega^2 = \frac{k}{m}$$



## Facts about simple harmonic oscillator

Plugging a Guitar String harder will change the frequency?

- A) True
- ☒ B) False
- C) Can't be answered

*changes Amplitude  
not frequency*



$$f = \frac{1}{T} = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$$

*tension on string, from tuning pegs*  
*← mass or thickness of string*

## Facts about simple harmonic oscillator

Frequency of a SHO depends on:

- ☒ A) Mass
- ☒ B) Force Constant k
- C) Day of the week
- D) Amplitude
- ☒ E) More than one of the above



$$f = \frac{1}{T} = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$$

## Energy in a Simple Harmonic Oscillator

Total Energy = Potential Energy + Kinetic Energy

$$E_{\text{Total}} = U + K = \frac{1}{2}kx^2 + \frac{1}{2}mv^2$$

$$\begin{aligned} E_{\text{Total}} &= \frac{1}{2}kA^2\cos^2(\omega t + \phi) + \frac{1}{2}mA^2\omega^2\sin^2(\omega t + \phi) \\ &= \frac{1}{2}kA^2\cos^2(\omega t + \phi) + \frac{1}{2}mA^2\left(\frac{k}{m}\right)\sin^2(\omega t + \phi) \\ &= \frac{1}{2}kA^2\cos^2(\omega t + \phi) + \frac{1}{2}kA^2\sin^2(\omega t + \phi) \\ &= \frac{1}{2}kA^2(\cos^2(\omega t + \phi) + \sin^2(\omega t + \phi)) \\ &= \frac{1}{2}kA^2 \end{aligned}$$

Just plug in the  $x(t)$  and  $v(t)$  equations and do some chugging.

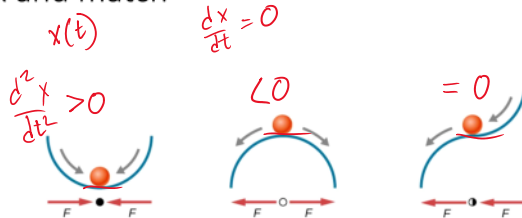
Use a trig identity!

$$\omega^2 = \frac{k}{m}$$

$$\cos^2 + \sin^2 = 1$$

$$E_{\text{Total}} = \frac{1}{2}kx^2 + \frac{1}{2}mv^2 = \frac{1}{2}kA^2$$

Mix and match



Stable equilibrium point

## Mix and match



Unstable equilibrium point

## Simple Harmonic Pendulum

$$\tau = -L(mg \sin \theta)$$

$$Ia = \sum \tau$$

$$= -Lmg \sin \theta$$

$$I \cdot \frac{d^2 \theta}{dt^2} = \dots$$

$$mL^2 \cdot \frac{d^2 \theta}{dt^2} = \dots$$

$$\frac{d^2 \theta}{dt^2} = -\frac{g}{L} \sin \theta$$

$$\tau = L \cdot F_w$$

$$= -L \cdot mg \cdot \sin \theta$$

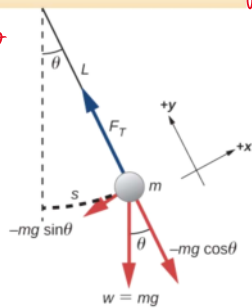
Small Angle Approximation:

$$\frac{d^2 \theta}{dt^2} = -\frac{g}{L} \theta$$

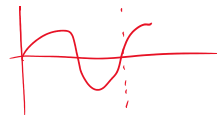
$$\omega = \sqrt{\frac{g}{L}}$$

$$\theta = A \cos(\omega t)$$

$$T = 2\pi \sqrt{\frac{L}{g}}$$



$$F_w = -W \cdot \sin \theta$$



Quiz: A simple pendulum has a length of 1m, what is it's frequency? Assume  $g = 10\text{m/s}^2$

A) 2s

B) 0.5 Hz

C) 3.16 rad / s

D) What is going on here?

$$T = 2\pi \sqrt{\frac{L}{g}} = 2\pi \sqrt{\frac{1}{10}}$$

$$= 2 \cdot \pi \cdot \sqrt{1/10} = 1.98691765315922$$

$$1 / 1.9869 = 0.5033 \text{ hz}$$

$$\omega = \sqrt{\frac{g}{L}}$$

## Physical Harmonic Pendulum

$$I\alpha = \tau_{\text{net}} = L(-mg) \sin \theta.$$

Small Angle Approximation:

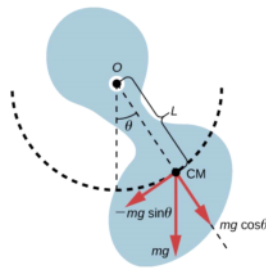
$$I\alpha = -L(mg) \theta;$$

$$I \frac{d^2 \theta}{dt^2} = -L(mg) \theta;$$

$$\frac{d^2 \theta}{dt^2} = -\left(\frac{mgL}{I}\right) \theta.$$

$$\omega = \sqrt{\frac{mgL}{I}}.$$

$$T = 2\pi \sqrt{\frac{I}{mgL}}.$$



## Physical Harmonic Pendulum – Homework hint

$$T = 2\pi \sqrt{\frac{I}{mgL}}$$

$I$  is the sum of all the  $I$  that make up the pendulum.

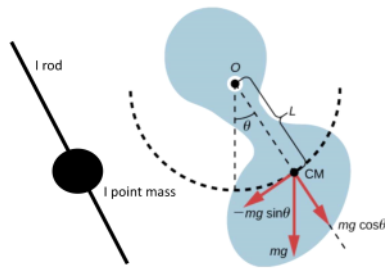
$$I_{\text{rod}} + I_{\text{pm}} = I$$

$L$  is the distance to Center of mass.

between  $CM_{\text{rod}}$  and  $CM_{\text{pm}}$

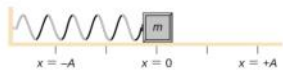
$m$  is the total mass of the pendulum.

$$m_{\text{rod}} + m_{\text{pm}} = m$$

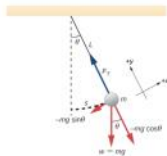


## Learning Outcome

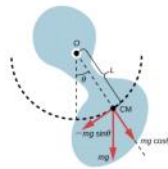
Find the Angular Frequency, Period of Motion, and Frequency of the following Oscillators:



$$\omega = \sqrt{\frac{k}{m}} \quad T = 2\pi \sqrt{\frac{m}{k}}$$



$$\omega = \sqrt{\frac{g}{L}} \quad T = 2\pi \sqrt{\frac{L}{g}}$$



$$\omega = \sqrt{\frac{mgL}{I}} \quad T = 2\pi \sqrt{\frac{I}{mgL}}$$

## Exit Poll

- Please provide a letter grade for todays lecture:

- A. A
- B. B
- C. C
- D. D
- E. Fail

