

# Design Assignment 4

Student Name: Nathan Ramos

Student #: 5006437353

Student Email: ramosn8@unlv.nevada.edu

Primary Github address: <https://github.com/n8ramos/>

Directory: /atmega328pb

Video Playlist:

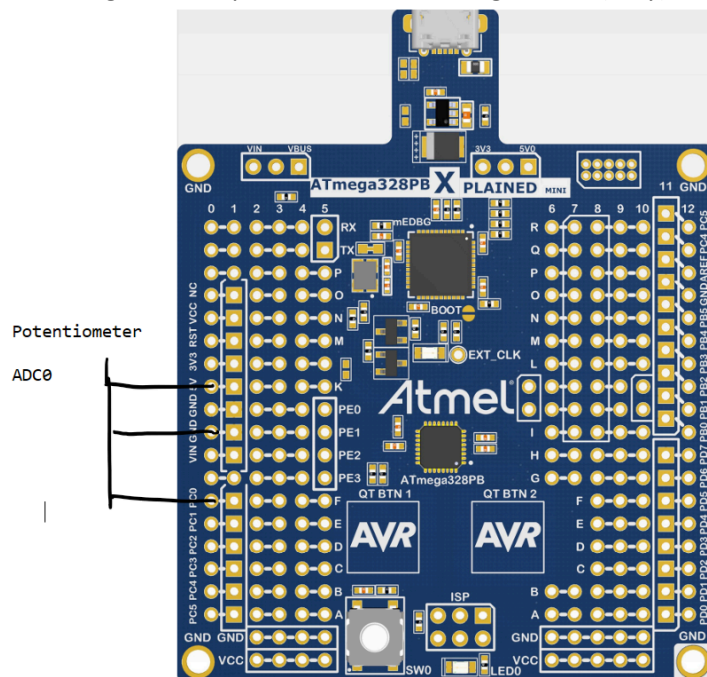
<https://www.youtube.com/playlist?list=PL2RpCRW8TC6YOj-NnLPqqfRTV48RcUe48>

## 1. COMPONENTS LIST AND CONNECTION BLOCK DIAGRAM w/ PINS

Components Used:

- potentiometer
- atmega328pb Xplained Mini
- microchip studio 7

Block diagram with pins used in the Atmega328PB (only)



## 2. DEVELOPED CODE OF TASK 1

```
#include <avr/io.h>
#include <avr/interrupt.h>
#define F_CPU 16000000UL
#define BAUD 9600
```

```

#define MYUBRR F_CPU/16/BAUD-1
#define VREF 5
#define STEPS 1024
#define STEPSIZE VREF/STEPS
#include <util/delay.h>
#include <stdio.h>
#include <stdlib.h>

// Global Vars
int dout;

void USART_init(unsigned int ubrr)
{
    //Set baud rate
    UBRR0H = (unsigned char)(ubrr>>8);
    UBRR0L = (unsigned char) ubrr;
    // enable transmitter
    UCSR0B = (1<<TXEN0);
    // Set frame format: async, no parity, 1 stop bit, , 8 data bits
    UCSR0C =
(0<<UMSEL01)|(0<<UMSEL00)|(0<<UPM01)|(0<<UPM00)|(0<<USBS0)|(1<<UCSZ01)|(1<<UCSZ00);
}

void USART_transmit(const char* data)
{
    while (*data) {
        //check if buffer is empty so that data can be written to transmit
        while (!(UCSR0A & (1 << UDRE0)));
        UDR0 = *data; //copy "data" to be sent to UDR0
        ++data;
    }
}

void USART_transmitChar(const char data)
{
    //check if buffer is empty so that data can be written to transmit
    while (!(UCSR0A & (1 << UDRE0)));
    UDR0 = data; //copy character to be sent to UDR0
}

ISR(TIMER1_COMPA_vect) {
    cli();
    int volt = dout/20; // scale dout from 0-1023 to 0-50
    for (int i = 0; i <= volt; i++) {
        USART_transmitChar(' '); // output # of spaces representing # of 0.1v
    }
    USART_transmitChar("**");
    // display min and max of oscilloscope
    switch (dout) {
        case 0:
            USART_transmit(" MIN");
            break;

```

```

        case 1023:
            USART_transmit(" MAX");
            break;
        }
        USART_transmitChar("\n");

        sei();
    }

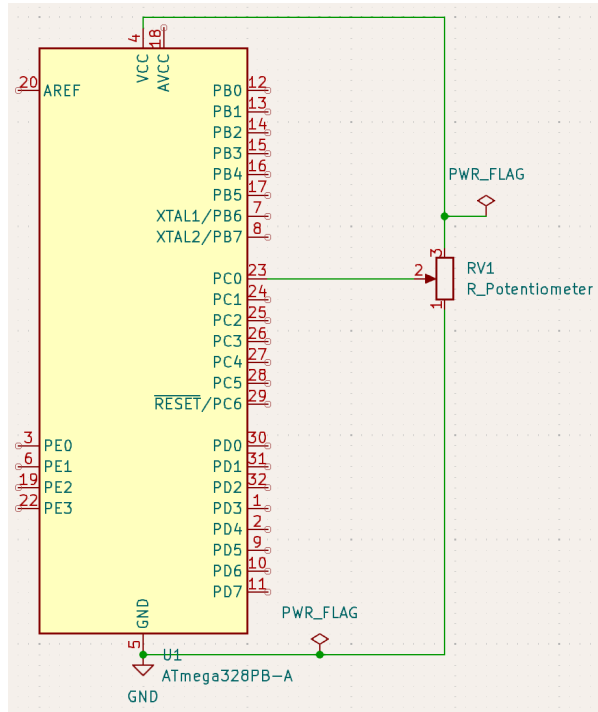
ISR (ADC_vect)
{
    cli();
    dout = ADC;
    // start ADC conversion
    ADCSRA |= (1 << ADSC);
    sei();
}

void timer1_CTC_init() {
    TCCR1A |= (0 << WGM11) | (0 << WGM10); // set bits WGM1[1:0] for CTC
    TCCR1B |= (0 << WGM13) | (1 << WGM12) | (0 << CS12) | (1 << CS11) | (0 << CS10); // set
WGM[3:2] for CTC & CS[2:0] for prescaler = 8
    TIMSK1 |= (1 << OCIE1A); // sets bit to enable CTC comparator A
    TCNT1 = 0; // initialize counter to 0
    OCR1A = 19999; // counter for 0.01 seconds
}

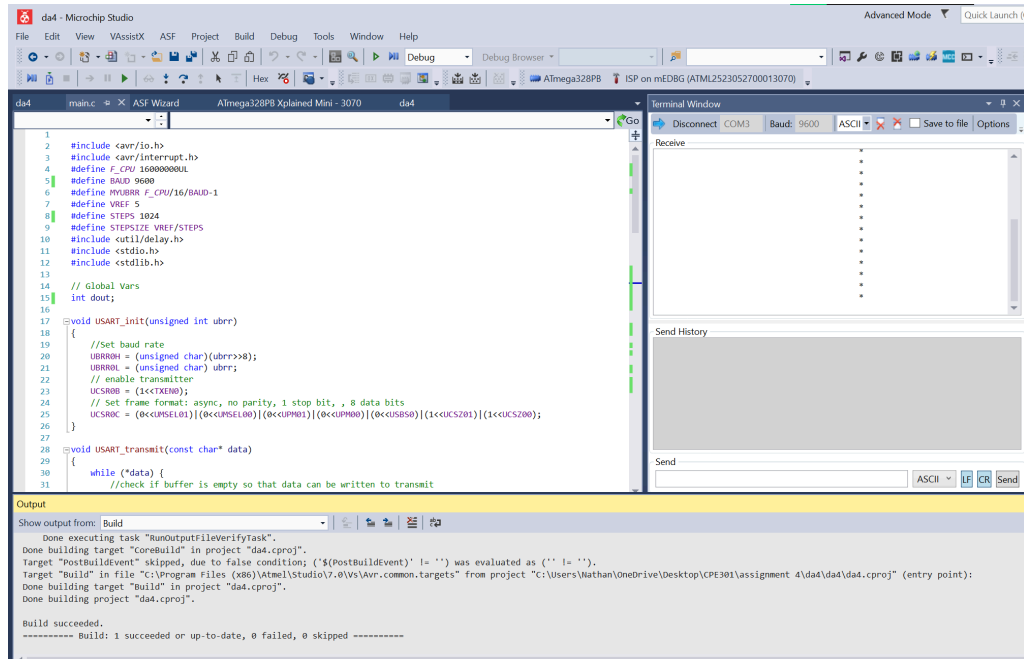
int main(void) {
    // For the USART output
    USART_init(MYUBRR);
    // initialize timer1 to 0.01 seconds
    timer1_CTC_init();
    sei();
    //set channel to take input for ADC0, right justified, AVcc with external cap at AREF
    ADMUX = (1 << REFS0) | (0 << MUX0); // Also defaults ADC0 reading
    //set prescaler to 64, enable ADC interrupt, enable ADC, start conversion
    ADCSRA |= (1 << ADEN) | (1 << ADIF) | (1 << ADPS2) | (1 << ADPS1) | (0 << ADPS0) | (1 << ADSC);
    while (1) {
        // start ADC conversion
        ADCSRA |= (1 << ADSC);
    }
}

```

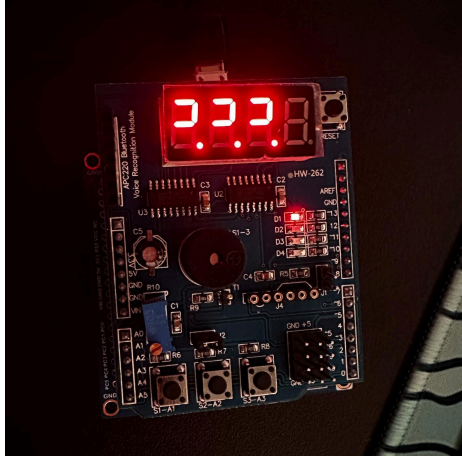
### 3. SCHEMATICS



#### 4. SCREENSHOTS OF EACH TASK OUTPUT (ATMEL STUDIO OUTPUT)



## 5. SCREENSHOT OF EACH DEMO (BOARD SETUP)



**6. VIDEO LINKS OF EACH DEMO**

<https://youtu.be/rtKgkxnpQP4>

**7. GITHUB LINK OF THIS DA**

<https://github.com/n8ramos/atmega328pb/tree/main>

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<http://studentconduct.unlv.edu/misconduct/policy.html>

*"This assignment submission is my own, original work".*

Nathan Ramos