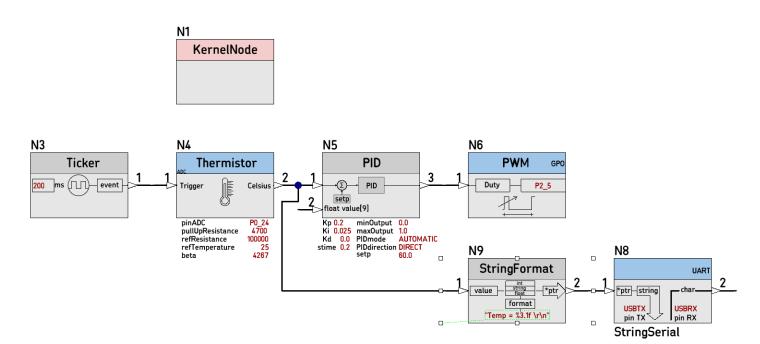
38D_PID_test

Testing program translated from schematic Design 38D_PID_test_SCHEMATIC for the Node PID, controlling a heating element with a PWM driven power MOSFET and a Thermistor for sensing element.

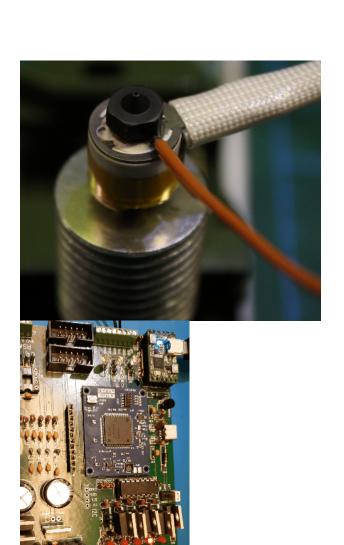
nBlocksStudio Schematic Design



Setup

Left: Hot End and thermocouple probe

Middle: n-3DP board Right: Overall setup



Temperature controll results

Left: Stabilized temeprature at 60 °C measured by Thermistor

Middle: Temeperature measured with an external Thermocouple probe

Right: Current consumption is stabilized at 163 mA



Thermistor Node

Thermistor Node with an added debugging printf(), prints the ADC value for the temperature value it exports.

```
File Edit Setup Control Window Help

adcread= 0.826129Temp = 59.9

adcread= 0.825885Temp = 59.8

adcread= 0.825885Temp = 59.9

adcread= 0.826129Temp = 59.9

adcread= 0.826129Temp = 59.8

adcread= 0.826129Temp = 59.8

adcread= 0.826129Temp = 59.8

adcread= 0.825885Temp = 59.8

adcread= 0.825885Temp = 59.8

adcread= 0.825885Temp = 59.9

adcread= 0.825885Temp = 59.9

adcread= 0.825885Temp = 59.9

adcread= 0.826129Temp = 59.9

adcread= 0.826129Temp = 59.8

adcread= 0.825885Temp = 59.8

adcread= 0.825885Temp = 59.8

adcread= 0.825885Temp = 59.8

adcread= 0.825885Temp = 59.9

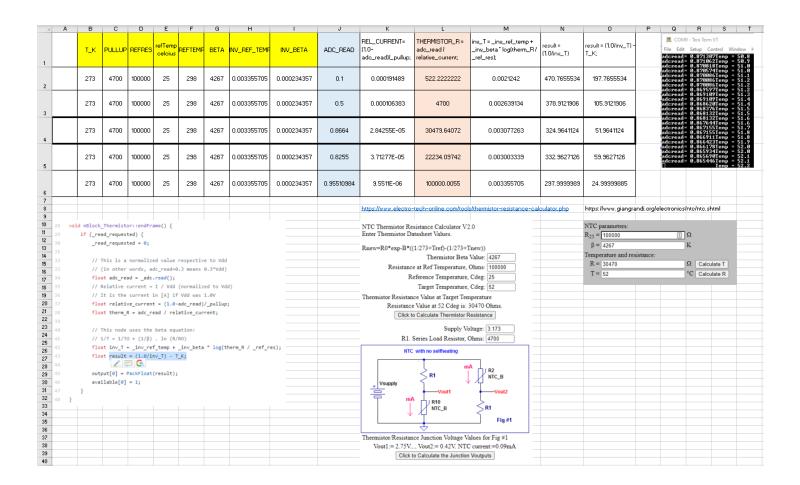
adcread= 0.825885Temp = 59.9
```

The formula used in the Node C++ code is validated and confirmed using and excel spreadsheet and online Thermistor calculators. The theoretical Temperature value for the corresponding ADC

measurement is precise. Measuring with the Multimeter indicates a slight difference from the measured voltage from ADC.							

Conclusion on Thermistor Node precision

The Thermistor Node works good, the ADC Hardware front-end needs some improvement, but the precision is still good for a hot-end temperature control.

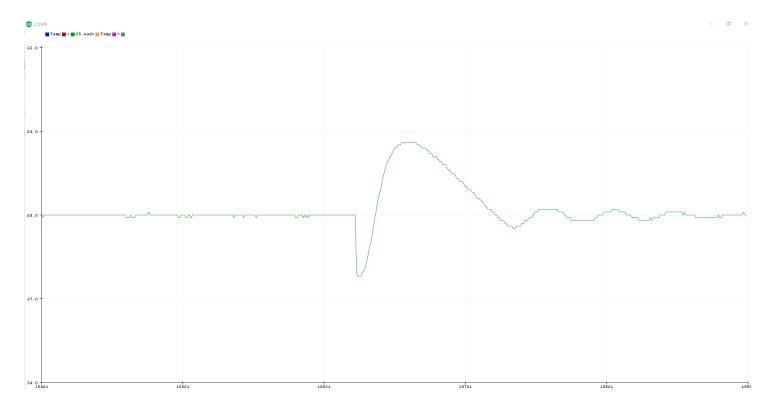


PID control evaluation

After trial and error, the values below result an acceptable controlling performance

- P = 0.2
- I = 0.025
- D = 0
- SamplingTime = 0.2 sec
- minOutput = 0
- maxOutput = 1
- setPoint = 60 °C

Powered-on at a temperature 40 °C, the PID controller tries to fix the temperature to the 60 °C set point fast, so we have an overshoot, then the system is stabilized with a slight oscillation around the 60 °C value.



Plotted with Arduino plotter.