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Tarjan 强连通分量

```
#include <cstdio>
#include <cstring>
#include <stack>
using namespace std;
const int MAXN = 110;
const int MAXM = MAXN * MAXN;
struct edge {
    int v, nt;
} e[MAXM];
int head[MAXN], low[MAXN], dfn[MAXN], in[MAXN], out[MAXN], color[MAXN];
int cnte, cntc, idx, n;
stack<int> s;

void init()
{
    cnte = cntc = idx = 0;
    memset(head, 0, sizeof head);
    memset(dfn, 0, sizeof dfn);
    memset(color, 0, sizeof color);
    memset(in, 0, sizeof in);
    memset(out, 0, sizeof out);
}

void add (int u, int v)
{
    cnte ++;
    e[cnte].v = v;
    e[cnte].nt = head[u];
    head[u] = cnte;
}

void tarjan(int u)
{
    dfn[u] = low[u] = ++ idx;
    s.push(u);
    for (int i = head[u]; i; i = e[i].nt) {
        int v = e[i].v;
        if (!dfn[v]) {
            tarjan(v);
            low[u] = min(low[u], low[v]);
        } else if (!color[v]) {
```

```

        low[u] = min(low[u], dfn[v]);
    }
}
if (dfn[u] == low[u]) {
    ++ cntc;
    while (true) {
        int now = s.top(); s.pop();
        color[now] = cntc;
        if (now == u) {
            break;
        }
    }
}
}

int main()
{
    while (~scanf("%d", &n)) {
        init();
        for (int i = 1; i <= n; i++) {
            int v;
            while (scanf("%d", &v), v) {
                add(i, v);
            }
        }
        for (int i = 1; i <= n; i++) {
            if (!dfn[i]) {
                tarjan(i);
            }
        }

        for (int u = 1; u <= n; u++) {
            for (int i = head[u]; i; i = e[i].nt) {
                int v = e[i].v;
                if (color[u] != color[v]) {
                    in[color[v]]++;
                    out[color[u]]++;
                }
            }
        }
        int in0 = 0, out0 = 0;
        for (int i = 1; i <= cntc; i++) {
            if (in[i] == 0) ++ in0;
            if (out[i] == 0) ++ out0;
        }
    }
}

```

```
    }  
    printf("%d\n", in0);  
    if (cntc == 1) {  
        puts("0");  
    } else {  
        printf("%d\n", max(in0, out0));  
    }  
  
}  
return 0;  
}
```

Tarjan 双联通分量，桥

```
#include <iostream>
#include <cstdio>
#include <algorithm>
#include <cstring>
#include <stack>
#include <queue>
using namespace std;
const int MAX = 100010;

struct edge {
    int v, nt, used;
} e[MAX << 2];
int n, m, q, cnte, idx, cntb;
int head[MAX], dfn[MAX], low[MAX];
int isbridge[MAX], father[MAX];

void init()
{
    father[1] = cnte = idx = cntb = 0;
    memset(head, -1, sizeof head);
    memset(dfn, 0, sizeof dfn);
    memset(isbridge, 0, sizeof isbridge);
}

void add(int u, int v)
{
    e[cnte].v = v;
    e[cnte].nt = head[u];
    e[cnte].used = 0;
    head[u] = cnte;
    ++ cnte;
}

void tarjan(int u)
{
    dfn[u] = low[u] = ++ idx;
    for (int i = head[u]; i != -1; i = e[i].nt) {
        if (e[i].used)
            continue;
        e[i].used = 1;
        e[i ^ 1].used = 1;
```

```

    int v = e[i].v;
    if (!dfn[v]) {
        father[v] = u;
        tarjan(v);
        if (low[v] > dfn[u]) {
            // v 无法通过回边或者通过子女到达比 u 点更靠前的点,
            // 那么我们只需要标记 v 点即可表明割边 (桥)
            // 桥就是 u 到 v 的这条边
            isbridge[v] = 1;
            ++ cntb;
        }
        low[u] = min(low[u], low[v]);
    } else {
        low[u] = min(low[u], dfn[v]);
    }
}

}

void lca(int u, int v)
{
    while (u != v) {
        while (dfn[u] > dfn[v]) {
            if (isbridge[u]) {
                isbridge[u] = 0;
                -- cntb;
            }
            u = father[u];
        }
        while (dfn[v] > dfn[u]) {
            if (isbridge[v]) {
                isbridge[v] = 0;
                -- cntb;
            }
            v = father[v];
        }
    }
    //printf("lca : %d\n", u);
}

int main()
{
    int tc = 1;
    while (~scanf("%d%d", &n, &m), n || m) {
        init();
    }
}

```

```

    int u, v;
    for (int i = 1; i <= m; i++) {
        scanf("%d%d", &u, &v);
        add(u, v);
        add(v, u);
    }

    tarjan(1);

    scanf("%d", &q);
    printf("Case %d:\n", tc++);
    while (q--) {
        int u, v;
        scanf("%d%d", &u, &v);
        lca(u, v);
        printf("%d\n", cntb);
    }
    puts("");
}

return 0;
}

```

LCA 倍增

```
// 倍增求 LCA
#include <iostream>
#include <cstdio>
#include <cstring>
#include <algorithm>
#include <queue>
using namespace std;
const int MAX = 1e4 + 10;
// 最大深度对二取对数
const int MAXH = 16;
queue<int> q;
struct edge {
    int v, nt;
} e[MAX];
int n, isroot[MAX], head[MAX], cnte, dep[MAX];
// anc[i][j]表示第 i 个节点向上跳  $2^j$  层后的节点
// anc[i][0]就是父亲节点
// 如果跳  $2^j$  层后超过了 root, 那么 anc[i][j] = root
int anc[MAX][MAXH];

void init()
{
    cnte = 0;
    memset(head, 0, sizeof head);
    memset(isroot, -1, sizeof isroot);
}

void add(int u, int v)
{
    ++cnte;
    e[cnte].v = v;
    e[cnte].nt = head[u];
    head[u] = cnte;
}

// x 向上跳 h 层后的节点编号
int swim(int x, int h)
{
    int ret = x;
    // 从二进制角度看, 如 6=110, 那么先跳 2 层, 再跳 4 层
    for (int i = 0; h; i++, h >>= 1) {
```



```

        if (h & 1) {
            ret = anc[ret][i];
        }
    }
    return ret;
}

```

// 遍历整个树，打出 anc 表

```

void bfs(int root)
{
    dep[root] = 1;
    q.push(root);
    for (int i = 0; i < MAXH; i++) {
        anc[root][i] = root;
    }
    while (!q.empty()) {
        int u = q.front(); q.pop();
        for (int i = head[u]; i; i = e[i].nt) {
            int v = e[i].v;
            if (v != anc[u][0]) {
                dep[v] = dep[u] + 1;
                anc[v][0] = u;
                for (int i = 1; i < MAXH; i++) {
                    // 倍增
                    anc[v][i] = anc[anc[v][i - 1]][i - 1];
                }
                q.push(v);
            }
        }
    }
}

```

int lca(int x, int y)

```

{
    if (dep[x] < dep[y]) {
        swap(x, y);
    }
    // 先把较深的跳到较浅的同一高度
    x = swim(x, dep[x] - dep[y]);
    if (x == y) {
        return x;
    }
    // 后一次跳的高度一定比前一次跳的高度还小
    // 可以用反证法证明

```

```

    for (int i = MAXH - 1; i >= 0; i --) {
        if (anc[x][i] != anc[y][i]) {
            x = anc[x][i];
            y = anc[y][i];
        }
    }
    // 循环结束后，anc[x][0] = anc[y][0] = lca
    return anc[x][0];
}

```

```

int main()
{
    int t;
    scanf("%d", &t);
    while (t --) {
        init();
        scanf("%d", &n);
        int u, v;
        for (int i = 1; i < n; i ++){
            scanf("%d%d", &u, &v);
            add(u, v);
            isroot[v] = 0;
        }
        int root = -1;
        for (int i = 1; i <= n; i ++){
            if (isroot[i]) {
                root = i;
                break;
            }
        }
        bfs(root);
        scanf("%d%d", &u, &v);
        printf("%d\n", lca(u, v));
    }
    return 0;
}

```

LCA RMQ

```
/**
 * 通过记录 dfs 序，找到 lca
 * 思想是找 u 和 v 的 lca，手动模拟 dfs 可以发现，lca 一定在 dfs 的路线上
 * 而在这个区间中，lca 一定是深度最小的那个
 * 因此，可以维护区间最小值， $O(\log n)$  处理一个请求
 * 预处理的时间是  $O(n \log n)$  的
 */
#include <iostream>
#include <algorithm>
#include <cstdio>
#include <cstring>
using namespace std;
const int MAX = 1e4 + 10;

struct edge {
    int v, nt;
} e[MAX];
int n, isroot[MAX], head[MAX], cnte;
// in 记录 dfs 过程中第一次找到该节点时的时间戳
// order 记录每个时间戳对应的是哪个节点
// dep 记录每个时间戳所对应的节点的深度
// 注意，时间戳的最大值是节点个数的 2 倍减 1
int in[MAX], order[MAX << 1], dep[MAX << 1], idx;

// st 表，维护 dep 区间最小值，最多有时间戳个数的 dep
int st[MAX << 1][20], id[MAX << 1][20];

void init()
{
    cnte = 0;
    memset(head, 0, sizeof head);
    memset(isroot, -1, sizeof isroot);
}

void add(int u, int v)
{
    ++ cnte;
    e[cnte].v = v;
    e[cnte].nt = head[u];
    head[u] = cnte;
}
```

```

void dfs(int u, int d)
{
    in[u] = ++ idx;
    order[idx] = u;
    dep[idx] = d;
    for (int i = head[u]; i; i = e[i].nt) {
        int v = e[i].v;
        dfs(v, d + 1);
        ++ idx;
        order[idx] = u;
        dep[idx] = d;
    }
}

void build()
{
    for (int i = 1; i <= idx; i++) {
        st[i][0] = dep[i];
        id[i][0] = order[i];
    }
    for (int j = 1; j < 20; j++) {
        for (int i = 1; i + (1 << j) <= idx + 1; i++) {
            int halfloc = i + (1 << (j - 1));
            if (st[i][j - 1] < st[halfloc][j - 1]) {
                st[i][j] = st[i][j - 1];
                id[i][j] = id[i][j - 1];
            } else {
                st[i][j] = st[halfloc][j - 1];
                id[i][j] = id[halfloc][j - 1];
            }
        }
    }
}

// 返回的是区间 dep 最小的节点编号
int query(int l, int r)
{
    int k = 0;
    while (r - l + 1 >= (1 << (k + 1))) {
        ++ k;
    }
    if (st[l][k] < st[r - (1 << k) + 1][k]) {
        return id[l][k];
    }
}

```

```

    } else {
        return id[r - (1 << k) + 1][k];
    }
}

int lca(int u, int v)
{
    return query(min(in[u], in[v]), max(in[u], in[v]));
}

int main()
{
    int t;
    scanf("%d", &t);
    while (t --) {
        init();
        scanf("%d", &n);
        for (int i = 1; i < n; i ++) {
            int u, v;
            scanf("%d%d", &u, &v);
            // 题目保证了 u 是 v 的父亲
            add(u, v);
            isroot[v] = 0;
        }
        idx = 0;
        for (int i = 1; i <= n; i ++) {
            if (isroot[i]) {
                dfs(i, 1);
                break;
            }
        }
        build();
        int u, v;
        scanf("%d%d", &u, &v);
        printf("%d\n", lca(u, v));
    }
    return 0;
}

```

LCA Tarjan 离线

```
// tarjan lca 模板
/**
 * 核心思想：如果要求 u, v 的 lca，有一个点 a，
 * uv 分别在 a 的左右子树，那么 a 就是 uv 的 lca
 * 用到了并查集
 */
#include <bits/stdc++.h>
using namespace std;
const int MAX = 4e4 + 10;
struct edge {
    int v, w, nt;
} e[MAX << 1];
// 离线算法，需要存储所有查询
struct Query {
    int id, v;
    Query(int vv, int idd): id(idd), v(vv) {}
};
int head[MAX], father[MAX], vis[MAX];
// 用来存储询问的节点和答案
int lca[MAX], ulca[MAX], vlca[MAX];
long long dis[MAX];
int cnte, n, m;
// 存储所有询问
vector<Query> query[MAX];

void init()
{
    cnte = 0;
    memset(head, 0, sizeof head);
    memset(vis, 0, sizeof vis);
    for (int i = 1; i <= n; i++) {
        father[i] = i;
    }
}

int find(int x)
{
    while (x != father[x]) {
        father[x] = father[father[x]];
        x = father[x];
    }
}
```

```

        return x;
    }

// 并查集合并，注意 tarjan 求 lca 的时候，需要把孩子节点
// 并到父亲节点上，因此合并的时候谁并到谁的次序不能错！
// 把 y 并到 x
void merge(int x, int y)
{
    x = find(x);
    y = find(y);
    father[y] = x;
}

void add(int u, int v, int w)
{
    ++ cnte;
    e[cnte].v = v;
    e[cnte].w = w;
    e[cnte].nt = head[u];
    head[u] = cnte;
}

// 核心部分
void tarjan(int u, int fa)
{
    // dfs
    for (int i = head[u]; i; i = e[i].nt) {
        int v = e[i].v;
        if (v != fa) {
            dis[v] = dis[u] + e[i].w;
            tarjan(v, u);
        }
    }
}

// 可以把这些查询看作图的深度优先搜索树上的非树边
for (int i = 0; i < query[u].size(); i++) {
    int v = query[u][i].v;
    int id = query[u][i].id;
    // 如果 v 被访问过了，这条边如果相当于前向边（祖先指向孩子）
    // 此时 find(v) = u
    // 或者如果是交叉边（无祖先关系）
    // 此时 find(v) 是使 uv 在其不同子树的节点
    if (vis[v]) {
        lca[id] = find(v);
    }
}

```

```

    }
    // 当该节点及其子树所有节点都访问过，才把当前节点并到父节点上
    // 并且这时才置访问标记
    merge(fa, u);
    // 第一次访问到该节点就置访问标记也对，
    // 不过会使 uv 有直接祖先关系的查询查询两次
    vis[u] = 1;
}

int main()
{
    int t;
    scanf("%d", &t);
    while (t --) {
        scanf("%d%d", &n, &m);
        init();
        for (int i = 1; i < n; i++) {
            int u, v, w;
            scanf("%d%d%d", &u, &v, &w);
            add(u, v, w);
            add(v, u, w);
        }
        for (int i = 1; i <= m; i++) {
            int u, v;
            scanf("%d%d", &u, &v);
            ulca[i] = u;
            vlca[i] = v;
            query[u].push_back(Query(v, i));
            query[v].push_back(Query(u, i));
        }
        dis[1] = 0;
        tarjan(1, 0);
        for (int i = 1; i <= m; i++) {
            printf("%lld\n", dis[ulca[i]] + dis[vlca[i]] - 2 * dis[lca[i]]);
        }
    }
    return 0;
}

```


KMP

```
#include <iostream>
#include <algorithm>
#include <cstring>
#include <cstdio>
using namespace std;
const int MAX = 1e6 + 10;
char pat[MAX];
char tar[MAX];
int nt[MAX], ans;

void getNext()
{
    int lenp = strlen(pat);
    int lent = strlen(tar);
    memset(nt, 0, sizeof nt);
    nt[0] = -1;
    int i = 0;
    int j = -1;
    while (i < lenp) {
        if (j == -1 || pat[i] == pat[j]) {
            nt[++i] = ++j;
        } else {
            j = nt[j];
        }
    }
}

void kmp()
{
    ans = 0;
    int i = 0, j = 0;
    int lent = strlen(tar);
    int lenp = strlen(pat);
    while (i < lent) {
        if (tar[i] == pat[j] || j == -1) {
            i++; j++;
        } else {
            j = nt[j];
        }
        if (j == lenp) {
            ans++;
        }
    }
}
```

```

        j = nt[j];
    }
}

int main()
{
    int t;
    scanf("%d", &t);
    while (t --) {
        scanf(" %s %s", pat, tar);
        getNext();
        kmp();
        printf("%d\n", ans);
    }
}

```

AC 自动机

```
#include <bits/stdc++.h>
using namespace std;
const int MAX = 1e6 + 10;
int n, ans;

struct acm {
    static int tot;
    int trie[MAX][26], sum[MAX], fail[MAX];
    void init() {
        memset(sum, 0, sizeof(int) * (tot + 1));
        memset(fail, 0, sizeof(int) * (tot + 1));
        for (int i = 0; i <= tot; i++) {
            for (int j = 0; j < 26; j++) {
                trie[i][j] = 0;
            }
        }
        fail[0] = 0;
        tot = 0;
    }
    void add(char *s, int len) {
        int x = 0;
        for (int i = 0; i < len; i++) {
            int id = s[i] - 'a';
            if (!trie[x][id]) {
                trie[x][id] = ++tot;
            }
            x = trie[x][id];
            if (i == len - 1) {
                sum[x]++;
            }
        }
    }
    int getfail(int x, int k) {
        if (trie[x][k]) return trie[x][k];
        if (x == 0) return 0;
        return getfail(fail[x], k);
    }
    void makefail() {
        queue<int> q;
        q.push(0);
        while (!q.empty()) {
```

```

        int now = q.front(); q.pop();
        for (int i = 0; i < 26; i++) {
            if (trie[now][i]) {
                if (now == 0) {
                    fail[trie[now][i]] = 0;
                } else {
                    fail[trie[now][i]] = getfail(fail[now], i);
                }
                q.push(trie[now][i]);
            }
        }
    }
}

void match(char *s, int len) {
    int x = 0;
    for (int i = 0; i < len; i++) {
        int id = s[i] - 'a';
        while (x && !trie[x][id]) x = fail[x];
        x = trie[x][id];
        int temp = x;
        while (temp) {
            if (sum[temp]) {
                ans += sum[temp];
                sum[temp] = 0;
            }
            temp = fail[temp];
        }
    }
}

} ac;
int acm::tot = MAX;
int main()
{
    int t;
    scanf("%d", &t);
    while (t--) {
        ans = 0;
        char s[MAX];
        ac.init();
        scanf("%d", &n);
        for (int i = 1; i <= n; i++) {
            scanf("%s", s);
            ac.add(s, strlen(s));
        }
    }
}

```

```
        ac.makefail();
        scanf(" %s", s);
        ac.match(s, strlen(s));
        printf("%d\n", ans);
    }
    return 0;
}
```

凸包

```
#include <iostream>
#include <algorithm>
#include <cstring>
#include <cstdio>
#include <stack>
using namespace std;
const int MAX = 110;
const int INF = 4e4 + 10;
const double EPS = 1e-6;
struct Point {
    double x, y;
    Point() {}
    Point(double xx, double yy): x(xx), y(yy) {}
    Point operator+(const Point& rhs) const {
        return Point(x + rhs.x, y + rhs.y);
    }
    Point operator-(const Point& rhs) const {
        return Point(x - rhs.x, y - rhs.y);
    }
    Point operator*(double rhs) const {
        return Point(x * rhs, y * rhs);
    }
} p[MAX];
int n;
stack<Point> s;

// 叉积，两向量角度为 p1 到 p2 逆时针旋转的角度，180 度以内叉积为正，否则为负
double det(const Point& p1, const Point& p2)
{
    return (p1.x * p2.y - p1.y * p2.x);
}

// 极角排序，atan2(y, x)求极角
bool cmp(const Point& p1, const Point& p2)
{
    double a = atan2(p1.y - p[1].y, p1.x - p[1].x);
    double b = atan2(p2.y - p[1].y, p2.x - p[1].x);
    if (a != b) {
        return a < b;
    } else {
        return p1.x < p2.x;
    }
}
```

```

    }
}

double dis(const Point& p1, const Point& p2)
{
    return sqrt( (p1.x - p2.x) * (p1.x - p2.x) + (p1.y - p2.y) * (p1.y - p2.y));
}

void graham()
{
    while (!s.empty()) {
        s.pop();
    }
    s.push(p[1]);
    s.push(p[2]);
    for (int i = 3; i <= n; i++) {
        while (s.size() >= 2) {
            Point mid = s.top();
            s.pop();
            Point last = s.top();
            if (det(mid - p[i], mid - last) > 0) {
                s.push(mid);
                break;
            }
        }
        s.push(p[i]);
    }
}

int main()
{
    while (~scanf("%d", &n), n) {
        Point bottom;
        bottom.x = INF;
        bottom.y = INF;
        int id = 0;
        for (int i = 1; i <= n; i++) {
            scanf("%lf%lf", &p[i].x, &p[i].y);
            if (p[i].x < bottom.x || (p[i].x == bottom.x && p[i].y < bottom.y)) {
                bottom = p[i];
                id = i;
            }
        }
        if (n == 1) {

```

```

        printf("0.00\n");
        continue;
    } else if (n == 2) {
        printf("%.2f\n", dis(p[1], p[2]));
        continue;
    }

    swap(p[1], p[id]);
    sort(p + 2, p + n + 1, cmp);
    graham();

    // 求凸包周长
    double ans = dis(s.top(), p[1]);
    Point last = s.top();
    s.pop();
    while (!s.empty()) {
        Point now = s.top();
        s.pop();
        ans += dis(now, last);
        last = now;
    }
    printf("%.2f\n", ans);
}
return 0;
}

```


旋转卡壳求对踵点

```
#include <iostream>
#include <cstdio>
#include <cstring>
#include <algorithm>
#include <vector>
#include <cmath>
using namespace std;
const int MAX = 5e4 + 10;
const int INF = 1e5 + 10;
const double EPS = 1e-6;
struct Point {
    double x, y;
    Point() {}
    Point(double xx, double yy): x(xx), y(yy) {}
    Point operator+(const Point& rhs) const {
        return Point(x + rhs.x, y + rhs.y);
    }
    Point operator-(const Point& rhs) const {
        return Point(x - rhs.x, y - rhs.y);
    }
    Point operator*(double rhs) const {
        return Point(x * rhs, y * rhs);
    }
    bool operator<(const Point& rhs) const {
        if (x != rhs.x) {
            return x < rhs.x;
        } else {
            return y < rhs.y;
        }
    }
} p[MAX];
int n;
vector<Point> s;

bool cmp(const Point& p1, const Point& p2)
{
    double a = atan2(p1.y - p[0].y, p1.x - p[0].x);
    double b = atan2(p2.y - p[0].y, p2.x - p[0].x);
    if (a != b) {
        return a < b;
    } else {
```

```

        return p1.x < p2.x;
    }
}

double dis2(const Point& p1, const Point& p2)
{
    return (p1.x - p2.x) * (p1.x - p2.x) + (p1.y - p2.y) * (p1.y - p2.y);
}

double det(const Point& p1, const Point& p2)
{
    return (p1.x * p2.y - p1.y * p2.x);
}

void graham()
{
    s.clear();
    s.push_back(p[0]);
    s.push_back(p[1]);
    for (int i = 2; i < n; i++) {
        while (s.size() >= 2) {
            Point mid = s.back();
            s.pop_back();
            Point last = s.back();
            if (det(mid - p[i], mid - last) > 0) {
                s.push_back(mid);
                break;
            }
        }
        s.push_back(p[i]);
    }
}

double rotation()
{
    int size = s.size();
    if (size == 1) {
        return 0;
    } else if (size == 2) {
        return dis2(s[0], s[1]);
    }

    int bg = 0;
    int ed = 0;

```

```

for (int k = 1; k < size; k++) {
    if (s[k] < s[bg]) {
        bg = k;
    }
    if (s[ed] < s[k]) {
        ed = k;
    }
}
int i = bg, j = ed;
double dis = -1;
while (i != ed || j != bg) {
    dis = max(dis, dis2(s[i], s[j]));
    if (det(s[(i + 1) % size] - s[i], s[(j + 1) % size] - s[j]) < 0) {
        i = (i + 1) % size;
    } else {
        j = (j + 1) % size;
    }
}
return dis;
}

int main()
{
    while (~scanf("%d", &n)) {
        Point bottom;
        int id;
        bottom.x = bottom.y = INF;
        for (int i = 0; i < n; i++) {
            scanf("%lf%lf", &p[i].x, &p[i].y);
            if (p[i].x < bottom.x || (p[i].x == bottom.x && p[i].y < bottom.y)) {
                bottom = p[i];
                id = i;
            }
        }
        swap(p[id], p[0]);

        sort(p + 1, p + n, cmp);
        graham();
        printf("%.0f\n", rotation());
    }
    return 0;
}

```

平板电视红黑树

```
#include <iostream>
#include <algorithm>
#include <cstdio>
#include <cstring>
#include <ext/pb_ds/assoc_container.hpp>

using namespace std;
using namespace __gnu_pbds;
const int MAX = 1e6 + 10;

int vis[MAX], occ[MAX];
int ans[MAX];
int n, m, minn;

struct node {
    int value;
    int curid;
    node() {}
    node(int vv, int cc): value(vv), curid(cc) {}
    bool operator< (const node& rhs) const {
        return curid < (rhs.curid);
    }
} nd[MAX];

bool cmp(const node& n1, const node& n2)
{
    return n1.curid < n2.curid;
}

tree<node, null_type, less<node>, rb_tree_tag, tree_order_statistics_node_update> rbt;

int main()
{
    scanf("%d%d", &n, &m);
    for (int i = 1; i <= n; i++) {
        nd[i].value = nd[i].curid = i;
        rbt.insert(nd[i]);
    }
    int flag = true;
    minn = 0;
    for (int i = 1; i <= m; i++) {
```

```

    int u, v;
    scanf("%d%d", &u, &v);
    if (!flag) {
        continue;
    }
    // 找第 v 大
    auto it = rbt.find_by_order(v - 1);
    if (vis[it -> value] && ans[it -> value] != u) {
        flag = false;
        continue;
    }
    if (occ[u] && ans[it -> value] != u) {
        flag = false;
        continue;
    }
    vis[it -> value] = 1;
    occ[u] = 1;
    ans[it -> value] = u;
    // 插入
    rbt.insert(node(it -> value, minn --));
    // 删除
    rbt.erase(it);
}
if (!flag) {
    puts("-1");
    return 0;
}
int id = 1;
for (int i = 1; i <= n; i++) {
    if (!ans[i]) {
        while (occ[id]) {
            ++id;
        }
        ans[i] = id;
        occ[id] = 1;
    }
    printf("%d ", ans[i]);
}
puts("");
return 0;
}

```

笛卡尔树

```
// 笛卡尔树，中序遍历得到原数组，从数组元素的值来看是堆
#include <iostream>
#include <cstdio>
#include <algorithm>
#include <cstring>
#include <stack>
using namespace std;
const int MAX = 5e4 + 10;

struct Node {
    int idx; // 在数组中的下标
    int v;    // 数组元素的值
    int id;   // 输入时的顺序
} node[MAX];

int n;
int l[MAX], r[MAX], p[MAX];
stack<Node> s;

bool cmp(const Node& n1, const Node& n2)
{
    return n1.idx < n2.idx;
}

// 单调栈，保存建树过程中的右链，这里是小根堆
// 最后栈底元素就是整棵树的根
void build()
{
    while (!s.empty()) {
        s.pop();
    }
    s.push(node[1]);
    int id = node[1].id;
    l[id] = r[id] = p[id] = 0;
    // 由于是按照下标排序，故每次插入一定是在树右链的末端
    for (int i = 2; i <= n; i++) {
        Node now;    // 当前栈顶节点
        Node last;   // 最近一次弹出的节点
        last.id = 0; // 初始化
        // 寻找右链中第一个比待插入节点元素值小的节点
        while (!s.empty()) {
```

```

        now = s.top();
        if (now.v < node[i].v) {
            break;
        }
        last = s.top();
        s.pop();
    }

    if (s.empty()) {
        // 没有找到比待插入节点更小的元素，待插入的是当前最小的
        int curid = node[i].id;
        int lastid = last.id;
        // 把整棵树链到待插入节点的左儿子上，待插入的成为新的根
        p[curid] = r[curid] = 0;
        l[curid] = lastid;
        p[lastid] = curid;
    } else {
        // 找到了比待插入元素更小的节点
        int curid = node[i].id;
        int lastid = last.id;
        int fatherid = now.id;
        // 把待插入节点成为其右儿子
        p[curid] = fatherid;
        r[fatherid] = curid;
        // 原来的右子树变成待插入节点的左子树
        l[curid] = lastid;
        r[curid] = 0;
        p[lastid] = curid;
    }
    // 更新右链
    s.push(node[i]);
}

int main()
{
    while (~scanf("%d", &n)) {
        for (int i = 1; i <= n; i++) {
            scanf("%d%d", &node[i].idx, &node[i].v);
            node[i].id = i;
        }
        // 按照下标从小到大排序
        sort(node + 1, node + 1 + n, cmp);
        build();
    }
}

```

```
    puts("YES");
    for (int i = 1; i <= n; i++) {
        printf("%d %d %d\n", p[i], l[i], r[i]);
    }
}
return 0;
}
```


归并树求区间第 k 大 $O(n(\log n)^2)$

```
/**
 * 归并树，线段树中每个节点保存归并排序时对应区间内排序好的数列，
 * 即保存的是归并排序的过程
 */
#include <iostream>
#include <cstdio>
#include <cstring>
#include <algorithm>
#include <vector>
using namespace std;
const int MAX = 1e5 + 10;
struct Tree {
    vector<int> v;
    int l, r;
} t[MAX << 2];
int n, m, cnta;
int a[MAX];

// 归并排序中的合并
void maintain(int x)
{
    int lson = x << 1;
    int rson = x << 1 | 1;
    vector<int>::iterator i = t[lson].v.begin();
    vector<int>::iterator j = t[rson].v.begin();
    while (i != t[lson].v.end() && j != t[rson].v.end()) {
        if (*i < *j) {
            t[x].v.push_back(*i);
            ++i;
        } else {
            t[x].v.push_back(*j);
            ++j;
        }
    }
    while (i != t[lson].v.end()) {
        t[x].v.push_back(*i);
        ++i;
    }
    while (j != t[rson].v.end()) {
        t[x].v.push_back(*j);
    }
}
```

```

        ++ j;
    }
}

void build(int x, int l, int r)
{
    t[x].l = l;
    t[x].r = r;
    t[x].v.clear();
    if (l == r) {
        scanf("%d", &a[++ cnta]);
        t[x].v.push_back(a[cnta]);
        return ;
    }
    int mid = (l + r) >> 1;
    build(x << 1, l, mid);
    build(x << 1 | 1, mid + 1, r);
    maintain(x);
}

int query(int x, int l, int r, int value)
{
    int ret = 0;
    if (l <= t[x].l && t[x].r <= r) {
        ret = upper_bound(t[x].v.begin(), t[x].v.end(), value) - t[x].v.begin();
        return ret;
    }
    int mid = (t[x].l + t[x].r) >> 1;
    if (r <= mid) {
        ret = query(x << 1, l, r, value);
    } else if (l >= mid + 1) {
        ret = query(x << 1 | 1, l, r, value);
    } else {
        ret = query(x << 1, l, mid, value);
        ret += query(x << 1 | 1, mid + 1, r, value);
    }
    return ret;
}

int main()
{
    while (~scanf("%d%d", &n, &m)) {
        cnta = 0;
        build(1, 1, n);
    }
}

```

```

sort(a + 1, a + 1 + n);
// 对于答案 a[l], 当前区间内有 k 个数字小于等于 a[l], 且 a[l]是这样数字中最小
的那个
while (m --) {
    int left, right, k;
    scanf("%d%d%d", &left, &right, &k);
    int l = 1, r = n, mid;
    while (l <= r) {
        mid = (l + r) >> 1;
        int num = query(1, left, right, a[mid]);
        if (num <= k - 1) {
            l = mid + 1;
        } else {
            r = mid - 1;
        }
    }
    printf("%d\n", a[l]);
}
return 0;
}

```

平方分割求区间第 k 大 $O(n \log n + m * \sqrt{n} * (\log n)^2)$

```
#include <iostream>
#include <cstdio>
#include <algorithm>
#include <cstring>
#include <cmath>
using namespace std;
const int MAX = 1e5 + 10;
int a[MAX];
int sorted[MAX];
int bucket[MAX / 10][MAX / 10];
int n, m;
int num, size;

// 统计区间 l 到 r 中小于等于 x 的数字的个数
int Count(int l, int r, int x)
{
    int cnt = 0;
    int bound;

    // 首先处理区间 l 到 r 没有完全覆盖整个桶的部分，这部分暴力的查找
    if (l % size != 0) {
        bound = (l / size + 1) * size;

        while (l <= r && l < bound) {
            if (a[l] <= x) {
                ++ cnt;
            }
            ++ l;
        }
    }

    if ((r + 1) % size != 0) {
        bound = (r / size) * size;
        while (l <= r && r >= bound) {
            if (a[r] <= x) {
                ++ cnt;
            }
            -- r;
        }
    }
}
```

// 然后处理区间内的每个桶，由于桶内是有序的，故可以二分找到小于等于 x 的数的个数

```
if (l <= r) {
    int beg = l / size;
    int ed = r / size;
    for (int i = beg; i <= ed; i++) {
        cnt += upper_bound(bucket[i], bucket[i] + size, x) - (bucket[i]);
    }
}

return cnt;
}
```

```
int main()
{
    while (~scanf("%d%d", &n, &m)) {
        size = sqrt(n * log2(n));
        if (size == 0)
            size = 1;
        num = n / size;
        for (int i = 0; i < n; i++) {
            scanf("%d", &a[i]);
            sorted[i] = a[i];
        }
        sort(sorted, sorted + n);

        // 分桶，并在每个桶内排序
        for (int i = 0, cnt = 0; i < num; i++) {
            for (int j = 0; j < size; j++, cnt++) {
                bucket[i][j] = a[cnt];
            }
            sort(bucket[i], bucket[i] + size);
        }
    }
}
```

// 核心思想是二分找到区间中 恰有 k 个数字小于等于 `sorted[mid]` 中最小的那个，这样 `sorted[mid]` 就是答案

```
while (m--) {
    int left, right, k;
    scanf("%d%d%d", &left, &right, &k);
    -- left;
    -- right;
    int l = 0, r = n - 1, mid, ret = -1;
    while (l <= r) {
        mid = (l + r) >> 1;
```

```
        int num = Count(left, right, sorted[mid]);
        if (num <= k - 1) {
            l = mid + 1;
        } else {
            r = mid - 1;
        }
    }
    printf("%d\n", sorted[l]);
}

}

return 0;
}
```

线段树

```
#include <iostream>
#include <cstdio>
#include <algorithm>
#include <cstring>
using namespace std;
const int MAX = 1e5 + 10;
struct Tree {
    long long sum;
    int l, r, len;
    long long tag;
} t[MAX << 2];
int n, q;

void maintain(int x)
{
    t[x].sum = t[x << 1].sum + t[x << 1 | 1].sum;
}

void pushdown(int x)
{
    if (t[x].tag) {
        t[x << 1].sum += t[x].tag * t[x << 1].len;
        t[x << 1].tag += t[x].tag;
        t[x << 1 | 1].sum += t[x].tag * t[x << 1 | 1].len;
        t[x << 1 | 1].tag += t[x].tag;
        t[x].tag = 0;
    }
}

void build(int x, int l, int r)
{
    t[x].l = l;
    t[x].r = r;
    t[x].len = r - l + 1;
    if (l == r) {
        scanf("%lld", &t[x].sum);
        return ;
    }
    int mid = (l + r) >> 1;
    build(x << 1, l, mid);
    build(x << 1 | 1, mid + 1, r);
}
```

```

        maintain(x);
    }

void modify(int x, int l, int r, int del)
{
    if (l <= t[x].l && t[x].r <= r) {
        t[x].sum += t[x].len * del;
        t[x].tag += del;
        return ;
    }
    pushdown(x);
    int mid = (t[x].l + t[x].r) >> 1;
    if (r <= mid) {
        modify(x << 1, l, r, del);
    } else if (l >= mid + 1) {
        modify(x << 1 | 1, l, r, del);
    } else {
        modify(x << 1, l, mid, del);
        modify(x << 1 | 1, mid + 1, r, del);
    }
    maintain(x);
}

long long query(int x, int l, int r)
{
    if (l <= t[x].l && t[x].r <= r) {
        return t[x].sum;
    }
    pushdown(x);
    int mid = (t[x].l + t[x].r) >> 1;
    long long ret = 0;
    if (r <= mid) {
        ret = query(x << 1, l, r);
    } else if (l >= mid + 1) {
        ret = query(x << 1 | 1, l, r);
    } else {
        ret = query(x << 1, l, mid);
        ret += query(x << 1 | 1, mid + 1, r);
    }
    maintain(x);
    return ret;
}

int main()

```



```

{
    while (~scanf("%d%d", &n, &q)) {
        build(1, 1, n);
        while (q --) {
            char c;
            int l, r, del;
            scanf(" %c", &c);
            if (c == 'Q') {
                scanf("%d%d", &l, &r);
                printf("%lld\n", query(1, l, r));
            } else {
                scanf("%d%d%d", &l, &r, &del);
                modify(1, l, r, del);
            }
        }
    }
    return 0;
}

```

欧拉路

```
#include <iostream>
#include <algorithm>
#include <cstdio>
#include <cstring>
#include <stack>
#include <queue>
using namespace std;
const int MAX = 1e5 + 10;
struct E {
    int v, nt, id, vis;
} e[MAX << 2];
int head[MAX], cnte;
int father[MAX], size[MAX], sumodd[MAX], tmp[MAX << 2];
int degree[MAX];
int n, m, ans;

stack<int> s;

queue<int> q;
vector<int> outp;

void init()
{
    cnte = 0;
    memset(head, -1, sizeof head);
    for (int i = 1; i <= n; i++) {
        father[i] = i;
        size[i] = 1;
    }
    memset(degree, 0, sizeof degree);
    memset(sumodd, 0, sizeof sumodd);
    ans = 0;
}

int find(int x)
{
    while (x != father[x]) {
        father[x] = father[father[x]];
        x = father[x];
    }
    return x;
}
```

```
}
```

```
void merge(int x, int y)
```

```
{
```

```
    x = find(x);
```

```
    y = find(y);
```

```
    if (x > y) {
```

```
        father[y] = x;
```

```
        size[x] += size[y];
```

```
    } else if (x < y) {
```

```
        father[x] = y;
```

```
        size[y] += size[x];
```

```
    }
```

```
}
```

```
void add(int u, int v, int id)
```

```
{
```

```
    e[cnte].v = v;
```

```
    e[cnte].id = id;
```

```
    e[cnte].vis = 0;
```

```
    e[cnte].nt = head[u];
```

```
    head[u] = cnte;
```

```
    ++ cnte;
```

```
}
```

```
/**
```

```
 * dfs 找欧拉路，前提是存在欧拉路
```

```
 * 如果都是偶点，或者入度等于出度，则从任意一点开始都可以
```

```
 * 如果有两个奇点，则需要从其中一个开始 dfs
```

```
 * 如果有两个点入度不等于出度，这两个点必须其中一个出度比入度大 1，另一个入度比出度大 1，
```

```
 * 从出度比入度大 1 的点开始
```

```
 * 核心是递归返回时把边压入栈中
```

```
 * dfs 结束后从栈中依次弹出就是路径
```

```
 */
```

```
void dfs(int x)
```

```
{
```

```
    for (int i = head[x]; ~i; i = e[i].nt) {
```

```
        if (!e[i].vis) {
```

```
            e[i].vis = 1;
```

```
            e[i ^ 1].vis = 1;
```

```
            dfs(e[i].v);
```

```
            s.push(e[i].id);
```

```

    }
}

int main()
{
    while (~scanf("%d%d", &n, &m)) {
        init();
        for (int i = 1; i <= m; i++) {
            int u, v;
            scanf("%d%d", &u, &v);
            add(u, v, i);
            add(v, u, -i);
            merge(u, v);
            degree[u] ^= 1;
            degree[v] ^= 1;
        }

        int lastodd;
        int oddcnt = 0;
        for (int i = 1; i <= n; i++) {
            if (degree[i] & 1) {
                int x = find(i);
                sumodd[x] += 1;
                if (!oddcnt) {
                    oddcnt ^= 1;
                    lastodd = i;
                } else {
                    oddcnt ^= 1;
                    add(i, lastodd, MAX);
                    add(lastodd, i, MAX);
                }
            }
        }
    }

    /**
     * 一个连通分量需要的一笔画的笔数:
     * 1. 孤立点为 0
     * 2. 无奇点为 1
     * 3. 否则是奇点数目除以 2
     */
    for (int i = 1; i <= n; i++) {
        int x = find(i);
        if (i == x && size[x] != 1) {

```

```

        ans += max(1, sumodd[x] / 2);
    }
}
printf("%d\n", ans);

for (int i = 1; i <= n; i++) {
    if (i == find(i) && size[i] != 1) {
        dfs(i);

int maxcnt = 0;
while (!s.empty()) {
    int id = s.top();
    if (id == MAX) {
        if (maxcnt && outp.size()) {
            printf("%d ", outp.size());
            for (int i = 0; i < outp.size(); i++) {
                printf(i==(outp.size()-1)?"%d\n":"%d ", outp[i]);
            }
            outp.clear();
        }
        maxcnt++;
    } else {
        if (maxcnt == 0) {
            q.push(id);
        } else {
            outp.push_back(id);
        }
    }
    s.pop();
}
int ts = q.size() + outp.size();
if (ts) {
    printf("%d ", ts);
    for (int i = 0; i < outp.size(); i++) {
        if (i == outp.size() - 1) {
            if (i == ts - 1) {
                printf("%d\n", outp[i]);
            } else {
                printf("%d ", outp[i]);
            }
        } else {
            printf("%d ", outp[i]);
        }
    }
}
}

```

```

    }
    outp.clear();
    while (!q.empty()) {
        printf("%d", q.front());
        q.pop();
        if (!q.empty()) {
            putchar(' ');
        } else {
            puts("");
        }
    }
}

}

}

}
return 0;
}

```

2-sat

```
/**
 * 2-sat 是可满足性问题，化成合取范式之后，每个子句中文字个数不超过 2
 * 对于一个子句(a ∨ b)，若 a 为假则 b 必须为真，若 b 为假则 a 必须为真
 * 即!a 为真，b 必须为真，!b 为真，a 必须为真
 * 如此，一个文字分为两个节点 a 与!a，可以连两条有向边，一条是!a -> b，一条是!b -> a
 * 若 a !a 出现在同一强连通分量中，则一定无解
 * 否则有解，看 a !a 所处的强连通分量的拓扑序，若!a 在 a 之前，则 a 为真，否则 a 为假
 *
 * 当面对一个点只有两种状态，两种状态非此即彼的时候，可以考虑 2-sat
 */
#include <iostream>
#include <algorithm>
#include <cstdio>
#include <cstring>
#include <stack>
#include <queue>
using namespace std;
const int MAXN = 2e3 + 10;
const int MAXM = 4e6 + 10;

struct edge {
    int v, nt;
} e[MAXN];
int head[MAXN], cnte;
int dfn[MAXN], low[MAXN], idx, color[MAXN], cntc;
stack<int> s;

// tsort
queue<int> q;
int head2[MAXN], cnte2;
edge e2[MAXN];
int indeg[MAXN], corder[MAXN];

int n;
int beg[MAXN], ed[MAXN], len[MAXN];

void add(int h[MAXN], edge ed[MAXN], int &cnt, int u, int v)
{
    ++ cnt;
    ed[cnt].v = v;
```

```

        ed[cnt].nt = h[u];
        h[u] = cnt;
    }

bool overlap(int x1, int y1, int x2, int y2)
{
    return (x2 < x1 && x1 < y2) ||
           (x2 < y1 && y1 < y2) ||
           (x1 < x2 && x2 < y1) ||
           (x1 < y2 && y2 < y1) ||
           (x1 == x2) ||
           (y1 == y2);
}

void tarjan(int u)
{
    dfn[u] = low[u] = ++ idx;
    s.push(u);
    for (int i = head[u]; i; i = e[i].nt) {
        int v = e[i].v;
        if (!dfn[v]) {
            tarjan(v);
            low[u] = min(low[u], low[v]);
        } else if (!color[v]) {
            low[u] = min(low[u], dfn[v]);
        }
    }
    if (low[u] == dfn[u]) {
        ++ cntc;
        while (true) {
            int now = s.top();
            s.pop();
            color[now] = cntc;
            if (now == u) {
                break;
            }
        }
    }
}

void tsort()
{
    int ord = 0;
    for (int i = 1; i <= cntc; i++) {

```



```

        if (indeg[i] == 0) {
            q.push(i);
        }
    }
    while (!q.empty()) {
        int u = q.front();
        q.pop();
        corder[u] = ++ ord;
        for (int i = head2[u]; i; i = e2[i].nt) {
            int v = e2[i].v;
            indeg[v]--;
            if (!indeg[v]) {
                q.push(v);
            }
        }
    }
}

int main()
{
    while (~scanf("%d", &n)) {
        int h, m;
        for (int i = 0; i < n; i++) {
            scanf("%d:%d", &h, &m);
            beg[i] = 60 * h + m;
            scanf("%d:%d", &h, &m);
            ed[i] = 60 * h + m;
            scanf("%d", &len[i]);
        }
        cnte = 0;
        memset(head, 0, sizeof head);
        // 拆点，分别为 i, i + n
        for (int i = 0; i < n; i++) {
            for (int j = 0; j < i; j++) {
                if (overlap(beg[i], beg[i] + len[i], beg[j], beg[j] + len[j])) {
                    // !(a && b) == !a ∨ !b
                    add(head, e, cnte, i, j + n);
                    add(head, e, cnte, j, i + n);
                }
                if (overlap(beg[i], beg[i] + len[i], ed[j] - len[j], ed[j])) {
                    // !(a && !b) == !a ∨ b
                    add(head, e, cnte, i, j);
                    add(head, e, cnte, j + n, i + n);
                }
            }
        }
    }
}

```

```

        if (overlap(ed[i] - len[i], ed[i], beg[j], beg[j] + len[j])) {
            // !(a && b) == a ∨ !b
            add(head, e, cnte, i + n, j + n);
            add(head, e, cnte, j, i);
        }
        if (overlap(ed[i] - len[i], ed[i], ed[j] - len[j], ed[j])) {
            // !(a && !b) == a ∨ b
            add(head, e, cnte, i + n, j);
            add(head, e, cnte, j + n, i);
        }
    }
}

// tarjan
memset(dfn, 0, sizeof dfn);
idx = 0;
memset(color, 0, sizeof color);
cntc = 0;
for (int i = 0; i < 2 * n; i++) {
    if (!dfn[i]) {
        tarjan(i);
    }
}

int ok = true;
for (int i = 0; i < n; i++) {
    if (color[i] == color[i + n]) {
        ok = false;
        break;
    }
}

if (!ok) {
    puts("NO");
} else {
    puts("YES");
    memset(indeg, 0, sizeof indeg);
    memset(head2, 0, sizeof head2);
    cnte2 = 0;
    for (int u = 0; u < 2 * n; u++) {
        for (int i = head[u]; i; i = e[i].nt) {
            if (color[u] != color[e[i].v]) {
                indeg[color[e[i].v]]++;
                add(head2, e2, cnte2, color[u], color[e[i].v]);
            }
        }
    }
}
}

```

```

// tsort
tsort();
for (int i = 0; i < n; i++) {
    int b, e;
    if (corder[color[i]] > corder[color[i + n]]) {
        // !a 在 a 之前, a 为真
        b = beg[i];
        e = beg[i] + len[i];
    } else {
        // !a 在 a 之后, a 为假
        b = ed[i] - len[i];
        e = ed[i];
    }
    printf("%02d:%02d %02d:%02d\n", b / 60, b % 60, e / 60, e % 60);
}
}
}
return 0;
}

```

树上点分治

```
/**
 * 分治常常能把一个  $n$  的复杂度降到  $\log n$ ，数列上的分治常常比较好实现，但是树上怎么办呢？
 * 树上如果随便找一个点的话，可能会退化，因此需要每次从重心分割然后分治
 *
 * 本题的思路是点对
 * (1) 在同一颗子树内，是一个子问题，那么就递归求解
 * (2) 在不同子树内，要求出每个点到重心的距离，然后合并之。
 *     考虑把所有点到重心的距离都放到一个 vector 里面，排好序，
 *     这样两个指针一个从头一个从尾扫一扫就能求出所有距离和小于  $k$  的点对数。
 *     不过这样会把同一棵子树的点对也算进去，需要再减出来，方法同上
 * (3) 一个在子树一个在重心，可以把重心当作一个距离重心为  $0$  的点
 *
 * 分治共  $\log n$  层，每一层都需要对所有节点排序，所以总复杂度是  $n \log^2 n$  的
 */
#include <iostream>
#include <cstdio>
#include <cstring>
#include <algorithm>
#include <vector>
using namespace std;
const int MAX = 1e4 + 10;
struct edge {
    int v, l, nt;
} e[MAX << 1];
int head[MAX], cnte;

int n, k, ans;
int centriod, censz;
int sz[MAX];
int vis[MAX]; // 标记这个点是否已经被作为重心去掉了
int dis[MAX]; // 标记这个点到其重心的距离
vector<int> disvec; // 记录点到重心的距离

void add(int u, int v, int l)
{
    ++ cnte;
    e[cnte].v = v;
    e[cnte].l = l;
    e[cnte].nt = head[u];
    head[u] = cnte;
}
```

```
}
```

```
// 求重心
```

```
void getCentriod(int u, int fa, int component)
```

```
{
    sz[u] = 1;
    int maxx = 0;
    for (int i = head[u]; i; i = e[i].nt) {
        int v = e[i].v;
        if (v == fa || vis[v]) {
            continue;
        }
        getCentriod(v, u, component);
        sz[u] += sz[v];
        maxx = max(maxx, sz[v]);
    }
    maxx = max(maxx, component - sz[u]);
    if (maxx < censz) {
        censz = maxx;
        centriod = u;
    }
    return ;
}
```

```
// 求各个点到重心的距离，同时求重心分割后各个子树的 size
```

```
void getdis(int u, int fa)
```

```
{
    disvec.push_back(dis[u]);
    sz[u] = 1;
    for (int i = head[u]; i; i = e[i].nt) {
        int v = e[i].v;
        if (vis[v] || v == fa) {
            continue;
        }
        dis[v] = dis[u] + e[i].l;
        getdis(v, u);
        sz[u] += sz[v];
    }
    return ;
}
```

```
/**
```

```
* u 传入重心，那么就是在计算
```

```
* 被分割的不同子树中所有到重心距离和不超过 k 的点对个数（包含同一子树的）
```

```

* 此时 initDis 传入 0
*
* u 传入的是重心分割后子树的根,
* 那么就是在计算这一棵子树中所有到重心距离和不超过 k 的点对个数
* 此时 initDis 传入重心到子树根的距离
*/
int getLessK(int u, int initDis)
{
    disvec.clear();
    dis[u] = initDis;
    getdis(u, -1);
    sort(disvec.begin(), disvec.end());

    int ret = 0;
    for (int i = 0, j = disvec.size() - 1; i < j;) {
        if (disvec[i] + disvec[j] <= k) {
            ret += j - i;
            ++ i;
        } else {
            -- j;
        }
    }
    return ret;
}

void solve(int cen)
{
    vis[cen] = 1;
    ans += getLessK(cen, 0);
    for (int i = head[cen]; i; i = e[i].nt) {
        int v = e[i].v;
        if (vis[v]) {
            continue;
        }
        // 之前算的时候会把在同一子树的点对也算进去, 这是不对的, 要减出来
        ans -= getLessK(v, e[i].l); // 此时已经将对应子树的 size 求出来了, 就是 sz[v]
        censz = MAX;
        getCentriod(v, cen, sz[v]);
        solve(centriod);
    }
}

int main()
{

```

```

while (~scanf("%d%d", &n, &k), n || k) {
    memset(head, 0, sizeof head);
    cnte = 0;
    for (int i = 1; i < n; i++) {
        int u, v, l;
        scanf("%d%d%d", &u, &v, &l);
        add(u, v, l);
        add(v, u, l);
    }
    memset(vis, 0, sizeof vis);
    censz = MAX;
    getCentriod(1, -1, n); // 获取最初重心
    ans = 0;
    solve(centriod); // 分治
    printf("%d\n", ans);
}
return 0;
}

```