NAGARJUNA COLLEGE OF ENGINEERING AND TECHNOLOGY

(An autonomous institution under VTU)

Mudugurki Village, Venkatagirikote Post, Devanahalli Taluk, Bengaluru – 562164



DEPARTMENT OF MATHEMATICS

Lab Component Of 2nd Semester
Engineering Mathematics
Advanced Calculus And Numerical Methods
(Course Code - 22MATS21/22MATE21/22MATC21)

1	Finding gradient and it's geometrical interpretation.				
2	Finding Divergence and it's geometrical interpretation.				
3	Finding Curl and it's geometrical interpretation.				
4	Verification of Green's theorem.				
5	Solution of algebraic and transcendental equation by Regula-Falsi method.				
6	Interpolation using Newton's forward interpolation formula.				
7	Interpolation using Newton's backward interpolation formula				
8	Computation of area under the curve using Trapezoidal, Simpson's (1/3) rd and Simpson's (3/8) th rule				
9	Solutions of higher order ordinary differential equations				
10	Solutions of Partial Differential Equations				

```
1) Write the Python code and Execute the program to find
gradient of following scalar functions.
 i) x^2 vz.
Method-1
from sympy.physics.vector import *
from sympy import var
var('x,y,z')
v=ReferenceFrame('v')
F=v[0]**2*v[1]*v[2]
G=gradient(F,v)
F=F.subs([(v[0],x), (v[1],y), (v[2],z)])
print("Given scalar function F = ")
display(F)
G=G.subs([(v[0],x), (v[1],y), (v[2],z)])
print("\n Gradient of F=")
display(G)
Output:-
        Given scalar function F =
             \mathbf{x}^2 \mathbf{y} \mathbf{z}
         Gradient of F=
        (2\mathbf{x}\mathbf{y}\mathbf{z})\widehat{v_x} + (\mathbf{x}^2\ \mathbf{z})\ \widehat{v_y} + (\mathbf{x}^2\ \mathbf{y})\ \widehat{v_z}
Method-2
from sympy.vector import*
from sympy import symbols
C=CoordSys3D(")
f=C.x**2*(C.y)*(C.z)
print("\n The given scalar point function is \n")
display(f)
delop=Del()
display(delop(f))
gradf=gradient(f)
print("\n Gradient of {f} is \n")
display(gradf)
Output:-
        The given scalar point function is
        \mathbf{X}^2\mathbf{y}\mathbf{Z}
```

```
\frac{\partial}{\partial x} \mathbf{x}^2 \mathbf{y} \mathbf{z}) \hat{\imath} + (\frac{\partial}{\partial y} \mathbf{x}^2 \mathbf{y} \mathbf{z}) \hat{\jmath} + (\frac{\partial}{\partial z} \mathbf{x}^2 \mathbf{y} \mathbf{z}) \hat{k}
Gradient of {f} is
(2\mathbf{x} \mathbf{y} \mathbf{z}) \hat{\imath} + (\mathbf{x}^2 \mathbf{z}) \hat{\jmath} + (\mathbf{x}^2 \mathbf{y}) \hat{k}
```

ii) $3x^2yz$

```
from sympy.physics.vector import *
from sympy import var
var('x,y,z')
v=ReferenceFrame('v')
F=3*v[0]**2*v[1]*v[2]
G=gradient(F,v)
F=F.subs([(v[0],x), (v[1],y), (v[2],z)])
print("Given scalar function F = ")
display(F)
G=G.subs([(v[0],x), (v[1],y), (v[2],z)])
print("\n Gradient of F=")
display(G)
Output: - Given scalar function F =
              3x^2yz
              Gradient of F=
               (6xyz)\hat{\mathbf{v}}\mathbf{x}+(3x^2z)\hat{\mathbf{v}}\mathbf{y}+3x^2y\hat{\mathbf{v}}\mathbf{z}
```

iii) $x^2 y^3 z^4$

```
from sympy.physics.vector import *
from sympy import var
var('x,y,z')
v=ReferenceFrame('v')
F=v[0]**2*v[1]**3*v[2]**4
G=gradient(F,v)
F=F.subs([(v[0],x),(v[1],y),(v[2],z)])
print("Given scalar function <math>F=")
display(F)
G=G.subs([(v[0],x),(v[1],y),(v[2],z)])
print("\n Gradient of <math>F=")
display(G)
Output:- Given scalar function <math>F=x^2y^3z^4
Gradient of F=
```

```
(2\mathbf{x}\mathbf{y}^3\mathbf{z}^4) \ \widehat{v_x} + (3\mathbf{x}^2\mathbf{y}^2\mathbf{z}^4) \ \widehat{v_y} + (4\mathbf{x}^2\mathbf{y}^3\mathbf{z}^3) \ \widehat{v_z}
```

2) Write Python code and Execute the program to find divergence of following vector functions.

```
i) \vec{\mathbf{F}} = \mathbf{x}^2 \mathbf{y} \hat{\mathbf{i}} + \mathbf{y} \mathbf{z}^2 \hat{\mathbf{j}} + \mathbf{x}^2 \mathbf{z} \hat{\mathbf{k}}
from sympy.physics.vector import *
from sympy import var
var('x,y,z')
v=ReferenceFrame('v')
F=v[0]**2*v[1]*v.x+v[1]*v[2]**2*v.y+v[0]**2*v[2]*v.z
G=divergence(F,v)
F=F.subs([(v[0],x), (v[1],y), (v[2],z)])
print("Given vector point function is ")
display(F)
G=G.subs([(v[0],x), (v[1],y), (v[2],z)])
print("\n Divergence of F=")
display(G)
Output: Given vector point function is
             (x^2y)\hat{v} x + (yz^2)\hat{v} y + (x^2z)\hat{v} z
           Divergence of F=
           x^2 + 2xy + z^2
ii) \vec{F} = 2x^2z\hat{\imath} - xv^2z\hat{\imath} + 3vz^2\hat{k}
from sympy.physics.vector import *
from sympy import var
var('x,y,z')
v=ReferenceFrame('v')
F=2*v[0]**2*v[2]*v.x-v[0]*v[1]**2*v[2]*v.y+3*v[1]*v[2]**2*v.z
G=divergence(F,v)
F=F.subs([(v[0],x), (v[1],y), (v[2],z)])
print("Given vector point function is ")
display(F)
G=G.subs([(v[0],x), (v[1],y), (v[2],z)])
print("\n Divergence of F=")
```

```
display(G)
Output: Given vector point function is
           2x^2z\hat{v} - xv^2z\hat{v} + 3vz^2\hat{v} z
         Divergence of F=
         4xz-2xyz+6yz
iii) \vec{F} = xyz\hat{i} + 3x^2y\hat{j} + (xz^2 - y^2z)\hat{k}
from sympy.physics.vector import *
from sympy import var
var('x,y,z')
v=ReferenceFrame('v')
F=v[0]*v[1]*v[2]*v.x+3*v[0]**2*v[1]*v.y+(v[0]*v[2]**2-v[1]**2*v[2])*v.z
G=divergence(F,v)
F=F.subs([(v[0],x), (v[1],y), (v[2],z)])
print("Given vector point function is ")
display(F)
G=G.subs([(v[0],x), (v[1],y), (v[2],z)])
print("\n Divergence of F=")
display(G)
Output: Given vector point function is
         xyz\hat{i} + 3x^2y\hat{j} + (xz^2 - y^2z)\hat{k}
         Divergence of F=
         3x^2 + 2xz - y^2 + yz
3) Write the Python code and Execute program to find curl of given
vector point function.
\vec{i}) \vec{F} = xv^2\hat{i} + 2x^2vz\hat{j} - 3vz^2\hat{k}.
from sympy.physics.vector import *
from sympy import var
var('x,y,z')
v=ReferenceFrame('v')
F=v[0]*v[1]**2*v.x+2*v[0]**2*v[1]*v[2]*v.y-3*v[1]*v[2]**2*v.z
G=curl(F,v)
F=F.subs([(v[0],x), (v[1],y), (v[2],z)])
print("Given vector point function is ")
```

display(F)

print("\n Curl of F=")

G=G.subs([(v[0],x), (v[1],y), (v[2],z)])

```
display(G)
Output:- Given vector point function is
            xy^2 \hat{\mathbf{v}} \mathbf{x} + 2x^2yz\hat{\mathbf{v}} \mathbf{v} - 3yz^2 \hat{\mathbf{v}} \mathbf{z}
            Curl of F=
            (-2x^2 y - 3z^2)\hat{\mathbf{v}} \mathbf{x} + (4xyz - 2xy)\hat{\mathbf{v}} \mathbf{z}
ii) \vec{F} = x^2yz \hat{\imath} + 2xy^2z \hat{\jmath} + xyz^2 \hat{k}
from sympy.physics.vector import *
from sympy import var
var('x,y,z')
v=ReferenceFrame('v')
F = v[0] **2*v[1]*v[2]*v.x + 2*v[0]*v[1]**2*v[2]*v.y + v[0]*v[1]*v[2]**2*v.z
G=curl(F,v)
F=F.subs([(v[0],x), (v[1],y), (v[2],z)])
print("Given vector point function is ")
display(F)
G=G.subs([(v[0],x), (v[1],y), (v[2],z)])
print("\n Curl of F=")
display(G)
Output: Given vector point function is
                   x^2yz\mathbf{v}^{\hat{}}\mathbf{x}+2xy^2z\mathbf{v}^{\hat{}}\mathbf{y}+xyz^2\mathbf{v}^{\hat{}}\mathbf{z}
                  Curl of F=
                   (-2xy^2 + xz^2) \hat{\mathbf{v}} \mathbf{x} + (x^2 y - yz^2) \hat{\mathbf{v}} \mathbf{y} + (-x^2 z + 2y^2 z) \hat{\mathbf{v}} \mathbf{z}
 iii) \vec{F} = 2x^2z \hat{i} - xy^2z \hat{j} + 3yz^2 \hat{k}
from sympy.physics.vector import *
from sympy import var
var('x,y,z')
v=ReferenceFrame('v')
F=2*v[0]**2*v[2]*v.x-v[0]*v[1]**2*v[2]*v.y+3*v[1]*v[2]**2*v.z
G=curl(F,v)
F=F.subs([(v[0],x), (v[1],y), (v[2],z)])
print("Given vector function F = ")
display(F)
G=G.subs([(v[0],x), (v[1],y), (v[2],z)])
print("\n Curl of F=")
display(G)
Output:-
```

```
Given vector point function is 2x^2z \hat{v} x - xy^2z \hat{v} y + 3yz^2 \hat{v} z

Curl of F=
(xy^2 + 3z^2) \hat{v} x + 2x^2 \hat{v} y - y^2 z \hat{v} \hat{z}
```

4) a) Using Green's theorem, Evaluate $\oint_c [(x+2y) \ dx + (x-2y) \ dy]$ where C is the region bounded by coordinate axes and the line x=1 and y=1.

```
from sympy import *
var('x,y')
p=x + 2*y
q=x - 2*y
f=diff(q,x)-diff(p,y)
soln=integrate(f,[x,0,1],[y,0,1])
print("I=",soln)
Output: -
I = -1
```

b) Using Green's theorem, Evaluate $\oint_c [(xy+y^2)\ dx + (x^2)dy]$ where C is the closed curve bounded by y=x and y=x².

```
from sympy import * var('x,y')

p=x*y+y**2

q=x**2

f=diff(q,x)-diff(p,y)

soln=integrate(f,[y,x**2,x],[x,0,1])

print("I=",soln)

Output:-

I=-1/20
```

```
c)Using Green's theorem, Evaluate \oint_c [(3x+4y)\ dx + (2x-3y)dy] where C is the boundary of the circle x^2+y^2=4
```

5) a) Write the Python code and Execute the program for Finding a real root of the equation $x^3 - 5x - 7 = 0$ by using Regula - Falsi method correct to three decimal places.

```
from numpy import*
def f(x):
return x**3-5*x-7
n=int(input("Number of iterations = "))
a=float(input("Enter the value of a = "))
b=float(input("Enter the value of b = "))
E=0.000001
if f(a)*f(b)>0:
print("The given equation do not possesses the root between a and b")
exit()
print('______')
print('Iteration\t\t a \t\t b \t\t c \t\t f(c)' )
print('_____
for i in range(n):
c=(a*f(b)-b*f(a))/(f(b)-f(a))
print(str(i+1)+'\t\t\%10.8f\t\%10.8f\t\%10.8f'\%(a,b,c,f(c)))
if abs(f(c))<E:
print(' ')
print('Root found : '+str(c))
if f(a)*f(c)<0:
```

Output:-

Number of iterations = 5 Enter the value of a = 2Enter the value of b = 3

Iteration	a	b	c	f(c)
1	2.00000000	3.00000000	2.64285714	-1.75473761
2	2.64285714	3.00000000	2.73563528	-0.20550152
3	2.73563528	3.00000000	2.74607181	-0.02247761
4	2.74607181	3.00000000	2.74720824	-0.00243995
5	2.74720824	3.00000000	2.74733154	-0.00026464

Max iterations reached!

Approximation to the Root after max iterations is :2.7473315411888417

5) b) Write the Python code and Execute the program for Finding a real root of the equation $x^3 - 2x - 5 = 0$ by the method of false position correct to three decimal places.

```
print('
   for i in range(n):
  c=(a*f(b)-b*f(a))/(f(b)-f(a))
  print(str(i+1)+'\t\t%10.8f\t%10.8f\t%10.8f\t%10.8f'%(a,b,c,f(c)))
  if abs(f(c))<E:
  print('__
  print('Root found : '+str(c))
  if f(a)*f(c)<0:
  b=c
  else:
  a=c
  print("
  if i==n-1:
  print('\n\n Max iterations reached!')
  print('Approximation to the Root after max iterations is :'+str(c))
Output:-
Number of iterations = 6
Enter the value of a = 2
Enter the value of b = 3
Iteration
                                                               f(c)
1
             2.00000000 3.00000000
                                         2.05882353 -0.39079992
2
             2.05882353 3.00000000
                                         2.08126366
                                                       -0.14720406
3
             2.08126366 3.00000000 2.08963921 -0.05467650
                                         2.09273957 -0.02020287
             2.08963921 3.00000000
```

Max iterations reached!

5

Approximation to the Root after max iterations is :2.09430545112526

2.09388371 3.00000000

2.09273957 3.00000000 2.09388371 -0.00745051

2.09430545

-0.00274567

5) c) Write the Python code and Execute the program for Finding a real root of the equation cos(x) = 3x - 1 by using Regula - Falsi method correct to three decimal places.

```
from numpy import*
def f(x):
return cos (x) - 3*x + 1
n=int(input("Number of iterations = "))
```

```
a=float(input("Enter the value of a = "))
  b = float(input("Enter the value of b = "))
  E=0.000001
  if f(a)*f(b)>0:
  print("The given equation do not possesses the root between a and b")
  exit()
  print('_____')
  print('Iteration\t\t a \t\t b \t\t c \t\t f(c)' )
  print('______')
  for i in range(n):
  c=(a*f(b)-b*f(a))/(f(b)-f(a))
  print(str(i+1)+'\t 10.8f\t 10.8f\t 10.8f\t 10.8f'\%(a,b,c,f(c)))
  if abs(f(c))<E:
  print('
  print('Root found : '+str(c))
  if f(a)*f(c)<0:
  b=c
  else:
  a=c
  print("
  if i==n-1:
  print('\n\n Max iterations reached!')
  print('Approximation to the Root after max iterations is :'+str(c))
  Output:-
Number of iterations = 6
Enter the value of a = 0
Enter the value of b = 1
Iteration
                                                             f(c)
1
             0.00000000 1.00000000
                                        0.57808519 0.10325491
2
             0.57808519 1.00000000
                                        0.60595857 0.00408080
             0.60595857 1.00000000
3
                                        0.60705710 0.00015905
4
             0.60705710 1.00000000
                                        0.60709991 0.00000620
             0.60709991 1.00000000
                                        0.60710158 0.00000024
Root found: 0.6071015805150821
             0.60710158 1.00000000 0.60710165 0.00000001
Root found: 0.6071016454704268
```

```
Max iterations reached!
Approximation to the Root after max iterations is :0.607101645470426
```

6) Write the Python code and Execute the program for Finding y from the following data at x=5 by using Newton Forward Interpolation formula.

X	4	6	8	10
Y	1	3	8	16

```
from numpy import*
n=int(input("Enter number of datapoints:"))
x=zeros((n))
y=zeros((n,n))
print("Enter data for x and y:")
for i in range(n):
x[i]=float(input('x['+str(i)+']='))
y[i][0]= float(input('y['+str(i)+']='))
for i in range (1,n):
for j in range(0,n-i):
y[j][i] = y[j+1][i-1] - y[j][i-1]
print("\n FORWARD DIFFERENCE TABLE\n");
for i in range (0,n):
print('%0.2f' %(x[i]), end=")
for j in range(0,n-i):
print('\t\t%0.2f' %(y[i][ j ]), end='')
print()
#Newton's Forward Interpolation Formula
V=float(input("Enter the value to be interpolated: "))
def u_cal(u,n):
temp=u;
for i in range(1,n):
temp=temp*(u - i);
return temp;
def fact(n):
```

```
f=1;
     for i in range(2,n+1):
     f*=i
     return f;
     sum=y[0][0];
     u=(v-x[0])/(x[1]-x[0]);
     for i in range(1,n):
     sum=sum+( u cal(u,i)*y[0][i])/fact(i);
     print("\n Interpolated value at ", v,"is", round(sum, 6));
   Output:-
Enter number of datapoints:4
Enter data for x and y:
x[0]=4
y[0] = 1
x[1] = 6
y[1]=3
x[2]=8
y[2] = 8
x[3]=10
y[3]=16
 FORWARD DIFFERENCE TABLE
                             2.00
                                                           0.00
4.00
              1.00
                                            3.00
6.00
              3.00
                             5.00
                                            3.00
8.00
              8.00
                             8.00
10.00
              16.00
Enter the value to be interpolated: 5
 Interpolated value at 5.0 is 1.625
7) Write the Python code and Execute the program for Finding y from the
```

following data at x=2.65 by using Newton Backward Interpolation formula.

	X	-1	0	1	2	3
	Υ	-21	6	15	12	3

```
from numpy import*
n=int(input("Enter number of data points:"))
x=zeros((n))
y=zeros((n,n))
print("Enter data for x and y:")
for i in range(n):
```

```
x[i]=float(input('x['+str(i)+']='))
      y[i][0]= float(input('y['+str(i)+']='))
      for i in range (1,n):
      for j in range(n-1,i-1,-1):
      y[j][i] = y[j][i-1] - y[j-1][i-1]
      print("\n BACKWARD DIFFERENCE TABLE\n");
      for i in range (0,n):
      print('%0.2f' %(x[i]), end=")
      for j in range(0,i+1):
      print('\t\t%0.2f' %(y[i][ j ]), end='')
      print()
      #Newton's Backward Interpolation Formula
      V=float(input("Enter the value to be interpolated: "))
      def u cal(u,n):
      temp=u;
      for i in range(1,n):
      temp=temp*(u + i);
      return temp;
      def fact(n):
      f=1;
      for i in range(2,n+1):
      f *=i
      return f
      sum=y[n-1][0]
      u=(v-x[n-1])/(x[1]-x[0]);
      for i in range(1,n):
      sum=sum+( u_cal(u,i)*y[n-1][i])/fact(i);
      print("\n Interpolated value at ", v,"is", round(sum, 6));
Output:-
Enter number of datapoints:5
Enter data for x and y:
x[0] = -1
y[0] = -21
x[1]=0
y[1]=6
x[2]=1
y[2]=15
x[3]=2
```

```
y[3]=12
x[4]=3
y[4]=3
BACKWARD DIFFERENCE TABLE
-1.00 -21.00
0.00 6.00
              27.00
       15.00 9.00 -18.00
1.00
2.00 12.00 -3.00 -12.006.00
3.00 3.00 -9.00 -6.00 6.00
Enter the value to be interpolated: 2.65
 Interpolated value at 2.65 is 6.457125
8) a) Write Python code and Execute the program to evaluate \int_0^1 \sqrt{1+x^3} dx using
i)Simpson's 1/3 rd ii)Trapezoidal rule iii)Simpson's 3/8 rule
  from numpy import *
  a=0
  b=1
  p=6
  n=7
  h=(b-a)/p
  x=linspace(a,b,n)
  f = sqrt(1 + x^{**}3)
  for i in range(0,n):
    print(round(f[i],ndigits=4))
  TR = round((h/2)*(f[0]+2*sum(f[1:n-1])+f[n-1]),ndigits=4)
  S13 = round((h/3)*((f[0]+f[n-1])+4*sum(f[1:n-1:2])+2*sum(f[2:n-1:2])),
  ndigits=4)
  S38 = round((3*h/8)*((f[0]+f[n-1])+2*sum(f[3:n-2:3]))
  +3*sum(f[1:n:3]+(f[2:n-1:3]))),ndigits=4)
  print("The required integral by Trapezoidal Rule is",TR)
  print("The required integral by Simpson's 1/3 Rule is",S13)
  print("The required integral by Simpson's 3/8 Rule is:",S38)
  Output:-
1.0
1.0023
1.0184
1.0607
1.1386
1.2565
```

```
1.4142
The required integral by Trapezoidal Rule is 1.1139
The required integral by Simpson's 1/3 Rule is 1.1114
The required integral by Simpson's 3/8 Rule is 1.1114
8) b) Write the Python code and Execute the program to evaluate \int_0^1 \frac{dx}{1+x^2} using
i)Simpson's 1/3 rd rule ii)Trapezoidal Rule iii)Simpson's 3/8 rule
from numpy import *
a=0
b=1
p=6
n=7
h=(b-a)/p
x = linspace(a,b,n)
f=(1/(1+x^{**}2))
for i in range(0,n):
 print(round(f[i],ndigits=4))
TR = round((h/2)*(f[0]+2*sum(f[1:n-1])+f[n-1]),ndigits=4)
S13 = round((h/3)*((f[0]+f[n-1])+4*sum(f[1:n-1:2])+2*sum(f[2:n-1:2])), ndigits=4)
S38 = round((3*h/8)*((f[0] + f[n-1]) + 2*sum(f[3:n-2:3]) + 3*sum(f[1:n:3] + (f[2:n-1:3]))),
ndigits=4)
print("The required integral by Trapezoidal Rule is",TR)
print("The required integral by Simpson's 1/3 Rule is",S13)
print("The required integral by Simpson's 3/8 Rule is :",S38)
   Output:-
1.0
0.973
0.9
0.8
0.6923
0.5902
0.5
The required integral by Trapezoidal Rule is 0.7842
The required integral by Simpson's 1/3 Rule is 0.7854
The required integral by Simpson's 3/8 Rule is 0.7854
8) c) Write the Python code and Execute the program to evaluate \int_0^6 \frac{dx}{(1+x)^2} using
i)Simpson's 1/3 rd rule ii)Trapezoidal Rule iii)Simpson's 3/8 rule
from numpy import*
a=0
b=6
p=6
```

```
n=7
 h=(b-a)/p
 x=linspace(a,b,n)
 f=(1/(1+x)**2)
 for i in range(0,n):
   print(round(f[i],ndigits=4))
 TR = round((h/2)*(f[0]+2*sum(f[1:n-1])+f[n-1]),ndigits=4)
 S13 = round((h/3)*((f[0]+f[n-1])+4*sum(f[1:n-1:2])+2*sum(f[2:n-1:2])), ndigits=4)
 S38 = round((3*h/8)*((f[0]+f[n-1])+2*sum(f[3:n-2:3])+3*sum(f[1:n:3]+(f[2:n-1:3]))),
 ndigits=4)
 print("The required integral by Trapezoidal Rule is",TR)
 print("The required integral by Simpson's 1/3 Rule is",S13)
 print("The required integral by Simpson's 3/8 Rule is :",S38)
    Output:-
 1.0
 0.25
 0.1111
 0.0625
 0.04
 0.0278
 0.0204
 The required integral by Trapezoidal Rule is 1.0016
 The required integral by Simpson's 1/3 Rule is 0.8946
 The required integral by Simpson's 3/8 Rule is 0.912
8) d)Write the Python code and Execute the program to evaluate \int_0^1 \frac{dx}{(1+x)} using
i)Simpson's 1/3 rd rule ii)Trapezoidal Rule iii)Simpson's 3/8 rule
from numpy import*
a=0
b=1
p=6
n=7
h=(b-a)/p
x=linspace(a,b,n)
f=(1/(1+x))
for i in range(0,n):
  print(round(f[i],ndigits=4))
TR = round((h/2)*(f[0]+2*sum(f[1:n-1])+f[n-1]),ndigits=4)
S13 = round((h/3)*((f[0]+f[n-1])+4*sum(f[1:n-1:2])+2*sum(f[2:n-1:2])),ndigits=4)
S38 = round((3*h/8)*((f[0]+f[n-1])+2*sum(f[3:n-2:3])+3*sum(f[1:n:3]+(f[2:n-1:3]))),
ndigits=4)
```

```
print("The required integral by Trapezoidal Rule is",TR)
print("The required integral by Simpson's 1/3 Rule is",S13)
print("The required integral by Simpson's 3/8 Rule is :",S38)
   Output:-
1.0
0.8571
0.75
0.6667
0.6
0.5455
0.5
The required integral by Trapezoidal Rule is 0.6949
The required integral by Simpson's 1/3 Rule is 0.6932
The required integral by Simpson's 3/8 Rule is 0.6932
8) e) Apply the Runge Kutta method to find the solution of dy/dx = 1 + (y/x) at
y(2) taking h = 0.2. Given that y(1) = 2.
from sympy import *
import numpy as np
def RungeKutta (g,x0 ,h,y0 ,xn):
  x,y = symbols ('x,y')
  f=lambdify([x,y],g)
  xt = x0 + h
  Y=[y0]
  while xt<=xn:
    k1=h*f(x0,y0)
    k2=h*f(x0+h/2, y0+k1/2)
    k3=h*f(x0+h/2, y0+k2/2)
    k4=h*f(x0+h, y0+k3)
    y1=y0+(1/6)*(k1+2*k2+2*k3+k4)
    Y. append (y1)
    x0=xt
    y0=y1
    xt = xt + h
  return np. round (Y,2)
RungeKutta ('1+(y/x)',1,0.2,2,2)
   Output:-
array([2., 2.62, 3.27, 3.95, 4.66, 5.39])
```

```
9) a) Write the Python code and Execute :: (4 D^2 - 4D - 3)y = e^{2x}
from sympy import *
x = symbols('x')
y=Function('y')(x)
DE=Eq(4*Derivative(y,x,2) - 4*Derivative(y,x) - 3*y, \exp(2*x))
GS=dsolve(DE)
display(GS)
   Output:-
   y(x) = c_1 e^{\frac{3x}{2}} + c_2 e^{-\frac{x}{2}} + \frac{e^{2x}}{r}
9) b) Write the Python code and Execute :: \frac{d^2y}{dx^2} - 2\frac{dy}{dx} + y = \cos 3x
from sympy import *
x=symbols('x')
y=Function('y')(x)
DE=Eq(Derivative(y,x,2) - 2*Derivative(y,x) +y, cos(3*x))
GS=dsolve(DE)
display(GS)
   Output:-
   y(x) = (c_1 + c_2 x)e^x + \frac{3sin3x}{50} - \frac{2cos3x}{25}
9) c) Write the Python code and Execute :: \frac{d^2y}{dx^2} + y = \sin 2x
from sympy import *
x=symbols('x')
y=Function('y')(x)
DE=Eq(Derivative(y,x,2)+y, sin(2*x))
GS=dsolve(DE)
display(GS)
   Output:-
y(x) = (c_1 sin x + c_2 cos x) - \frac{sin 2x}{3}
9) d) Write the Python code and Execute :: \frac{d^2y}{dx^2} - 2\frac{dy}{dx} + 3y = \cos 2x
 from sympy import *
x=symbols('x')
y=Function('y')(x)
DE=Eq(Derivative(y,x,2)-2*Derivative(y,x)+3*y, cos(2*x))
GS=dsolve(DE)
display(GS)
```

```
Output:-
```

$$y(x) = (c_1 \sin \sqrt{2}x + c_2 \cos \sqrt{2}x)e^x - \frac{4\sin 2x}{17} - \frac{\cos 2x}{17}$$

10) a) Solve the PDE, xp + yq = z, where z = f(x, y)

from sympy . solvers .pde import pdsolve

from sympy import Function, Eq,cot, classify_pde, pprint

from sympy .abc import x, y, a

f = Function ('f')

$$z = f(x, y)$$

$$zx = z.diff(x)$$

$$zy = z.diff(y)$$

$$eq = Eq(x*zx+y*zy, z)$$

$$soln = pdsolve(eq,z)$$

Output:-

$$x \cdot \frac{\partial}{\partial x} (f(x, y)) + y \cdot \frac{\partial}{\partial y} (f(x, y)) = f(x, y)$$

$$f(x, y) = x \cdot F\left(\frac{y}{x}\right)$$

10) b) Solve the PDE, $x^2p + y^2q = (x + y)z$, where $p = \frac{\partial z}{\partial x}$ and $q = \frac{\partial z}{\partial y}$

from sympy . solvers .pde import pdsolve

from sympy import Function, Eq,cot, classify_pde, pprint

from sympy .abc import x, y, a

$$z = f(x, y)$$

$$zx = z$$
. diff (x)

$$zy = z$$
. diff (y)

Solve
$$x^2p+y^2q = (x+y)z$$

$$eq = Eq(x ** 2*zx+y ** 2*zy,(x+y)*z)$$

pprint (eq)

$$soln = pdsolve (eq,z)$$

Output:-

$$x^2 \cdot \frac{\partial}{\partial x} (f(x, y)) + y^2 \cdot \frac{\partial}{\partial y} (f(x, y)) = (x+y) \cdot f(x, y)$$

$$f(x,y) = (x-y) \cdot F\left(\frac{-x+y}{x+y}\right)$$