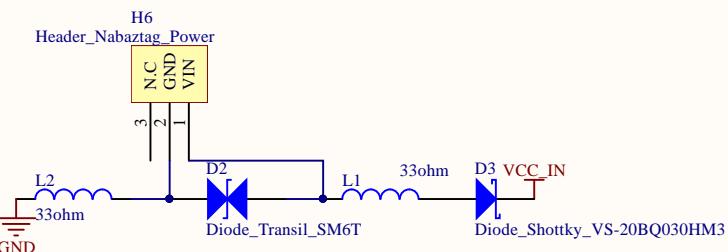


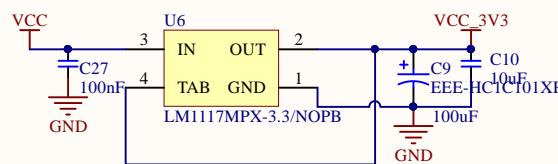
A

Power input



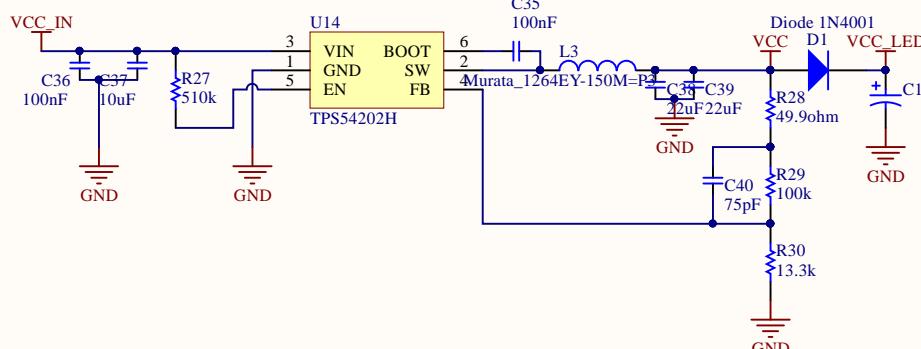
B

3V3 Power regulator



C

5V Power regulator



D

Title **PyNab - Power**Size: **A4**Number: Revision **2.0**

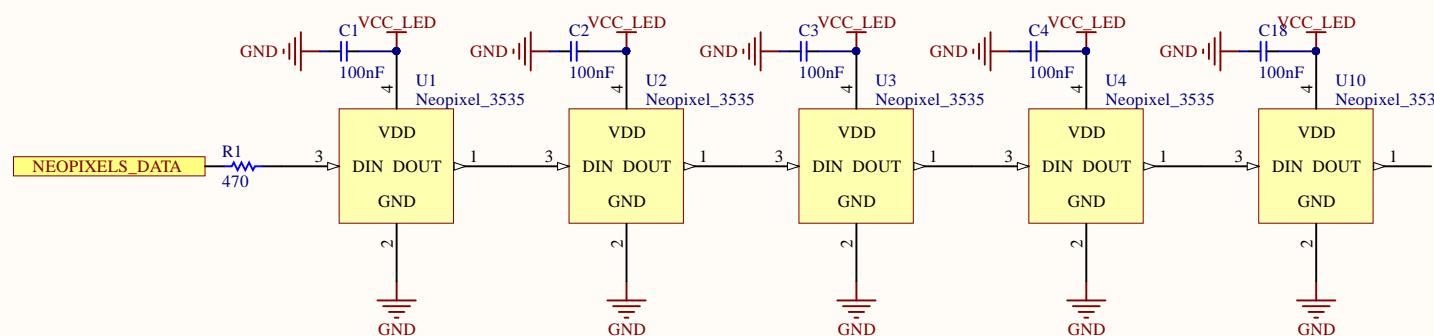
ENERO
7, rue ambroise thomas
75009
Paris
France



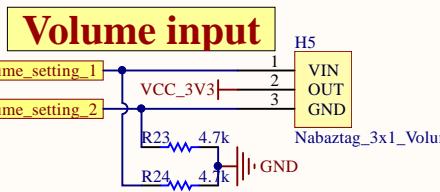
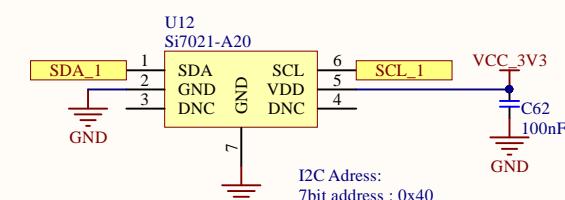
Date: 25/09/2019 Time: 15:33:11 Sheet 1 of 4

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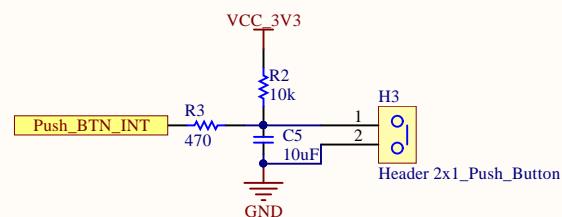
NEOPIXELS



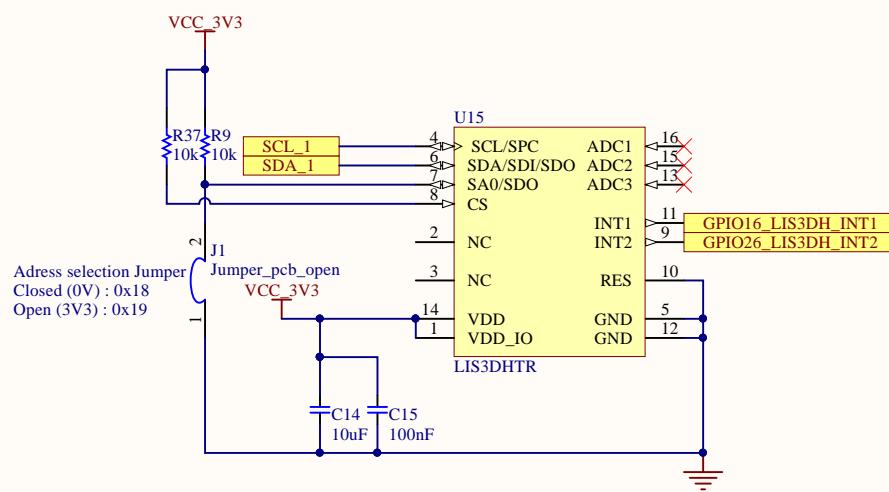
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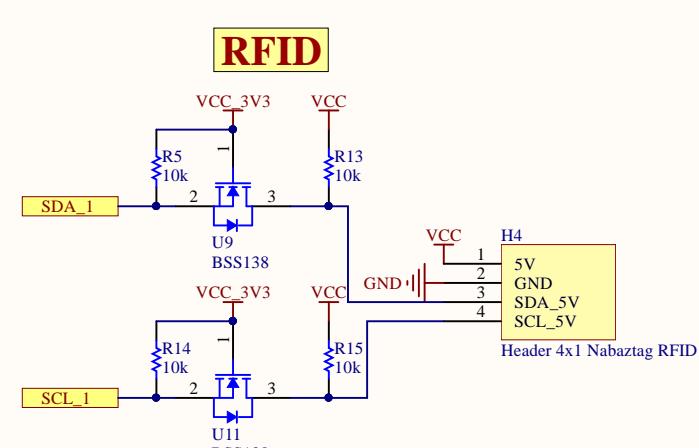
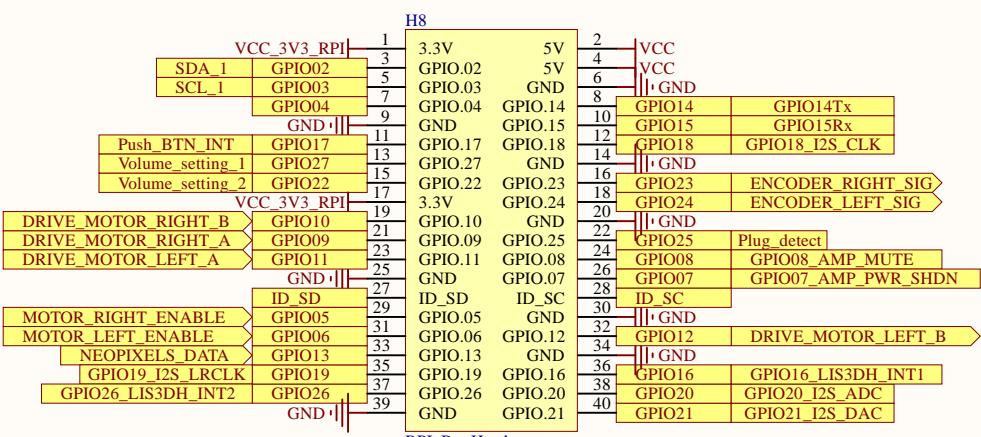
Push Button



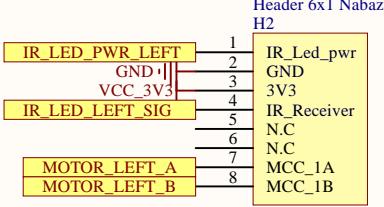
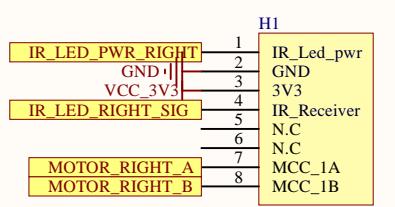
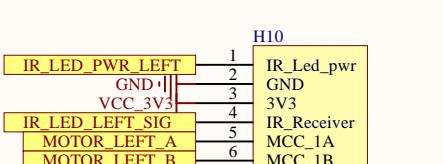
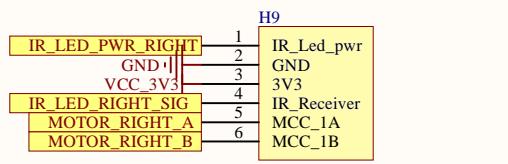
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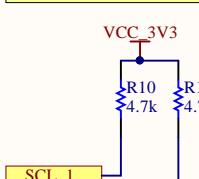
RPI ZERO W Header



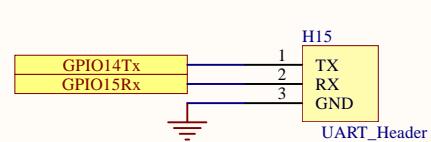
Headers Nabaztag V1 & V2



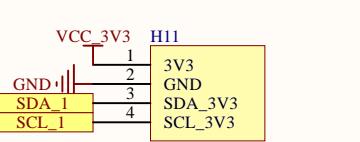
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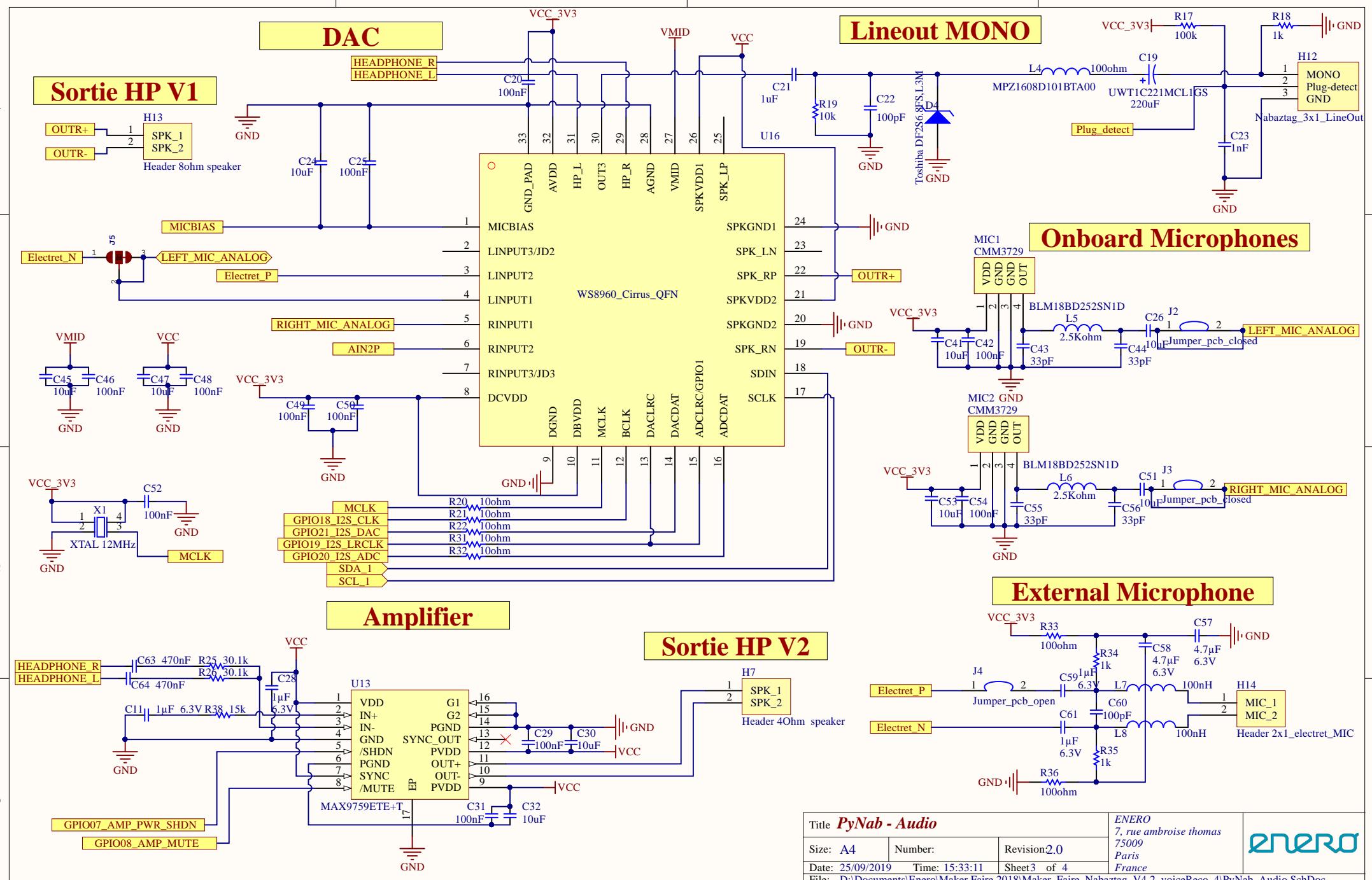


UART Header



Optionnal I2C Sensor 3V3





Title **PyNab - Audio**

Size: **A4**

Number: **Revision 2.0**

Date: **25/09/2019**

Time: **15:33:11**

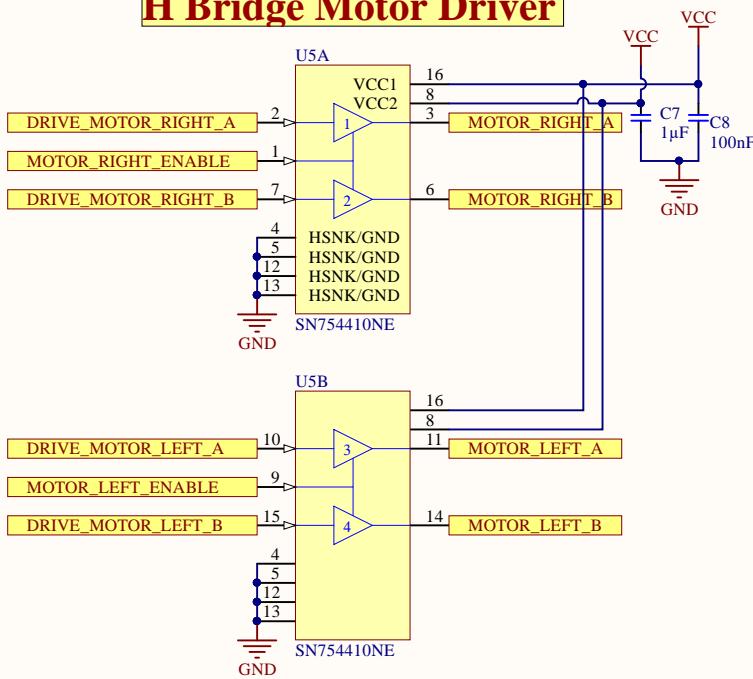
Sheet **3** of **4**

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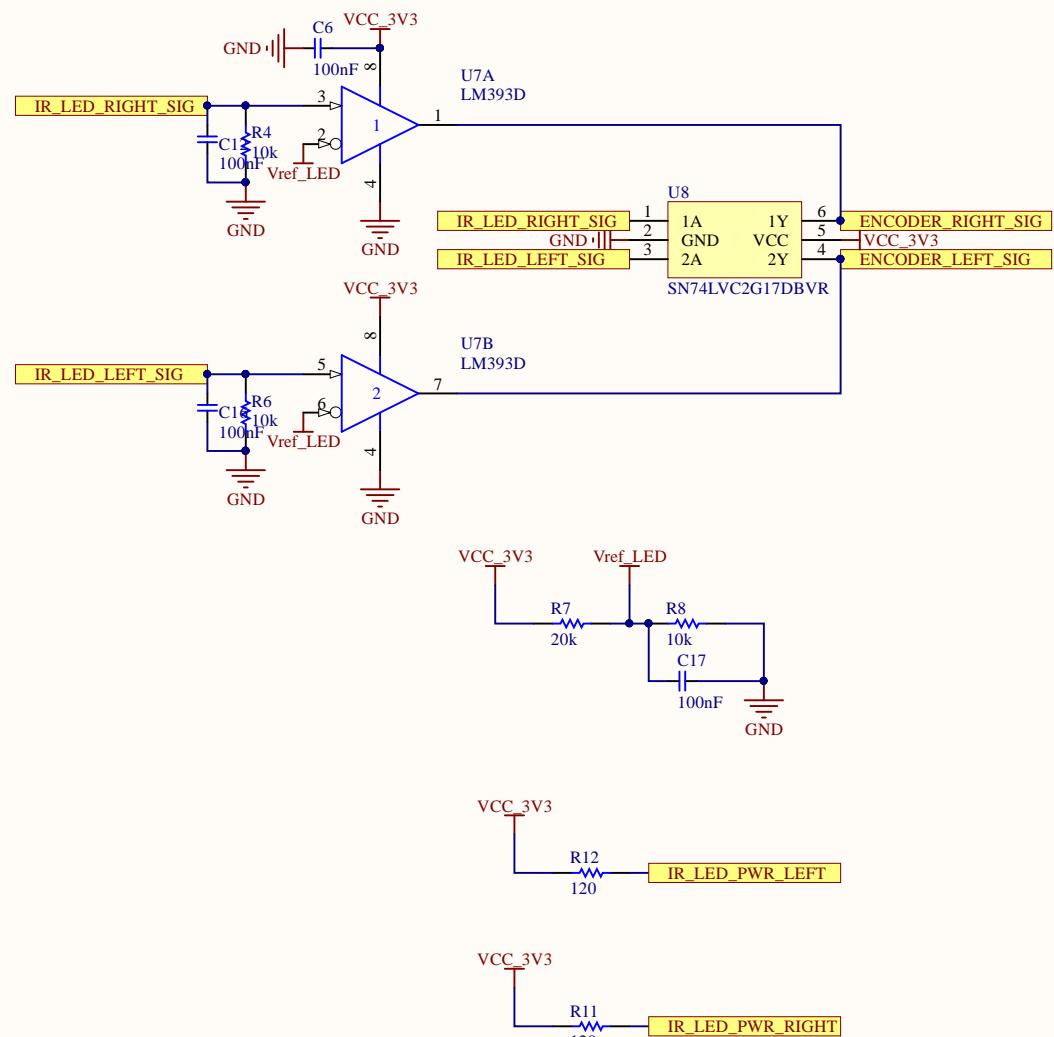
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Paris
France



A H Bridge Motor Driver



Ear Encoders



Title: **PyNab - Motor & Ear Encoders**

Size: **A4** Number: Revision: **2.0**

Date: **25/09/2019** Time: **15:33:12** Sheet **4** of **4**

File: **D:\Documents\Enero\Maker Faire 2018\Maker_Faire_Nabatag_V4.2_voiceReco_4\PyNab_Motor&Encoders.SchDoc**

Enero

