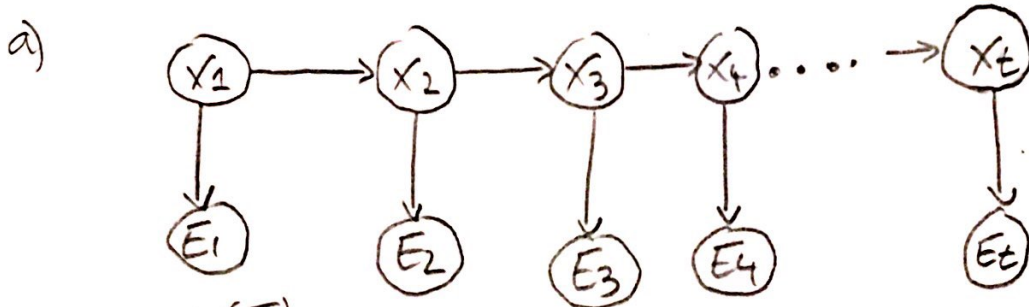


Q1) states: {High, Low} =  $X$   
observations: {Buy, Sell, keep} =  $E$



Initial Prob ( $\pi$ )

$X$	$P(X)$
high	0.6
low	0.4

Transition Prob  $P(X_{t+1} | X_t)$

$X_t$	$X_{t+1}$	
	high	low
high	0.3	0.7
low	0.6	0.4

Emission Probabilities  $P(E | X)$

$X$	$E$		
	Buy	Sell	keep
high	0.1	0.6	0.3
low	0.5	0.2	0.3

b)  $P(\text{Buy, keep, Sell})$

	$E_1 = \text{Buy}$	$E_2 = \text{keep}$	$E_3 = \text{Sell}$
$X = \text{high}$	0.06	0.0414	0.020628
$X = \text{low}$	0.2	0.0366	0.008724

$$\alpha_1(1) = P(E_1 = \text{Buy}, X = \text{high})$$

$$= P(\text{Buy} | X = \text{high}) P(X = \text{high})$$

$$= 0.1 (0.6) = 0.06$$

$$\alpha_2(1) = P(\text{Buy} | X = \text{low}) P(X = \text{low})$$

$$= 0.5 (0.4) = 0.2$$

$$\alpha_2(1) = 0.06(0.3)(0.3) + 0.2(0.6)(0.3)$$

$$= 0.0414$$

$$\alpha_3(1) = 0.0414(0.3)(0.6) + 0.0366(0.6)(0.6) = 0.020628$$

$$\alpha_2(2) = 0.06(0.7)(0.3) + 0.2(0.4)(0.3)$$

$$= 0.0366$$

$$\alpha_3(2) = 0.0414(0.7)(0.2) + 0.0366(0.4)(0.2) = 0.008724$$

$$\text{Answer: } 0.020628 + 0.008724$$

$$= 0.029352$$

$$c) \overset{\text{Filter}}{P(X_3 = \text{High} | E_{1:3})} = \frac{P(X_3 = \text{high}, E_1 = \text{buy}, E_2 = \text{keep}, E_3 = \text{sell})}{P(E_1 = \text{buy}, E_2 = \text{keep}, E_3 = \text{sell})} = \frac{0.020628}{0.029352}$$

$$\boxed{= 0.703}$$

Prediction

$$P(X_4 = \text{high} | E_{1:3})$$

$$= P(X_4 = \text{high} | X_3 = \text{high}) P(X_3 = \text{high} | E_{1:3})$$

$$+ P(X_4 = \text{high} | X_3 = \text{low}) P(X_3 = \text{low} | E_{1:3})$$

$$= 0.3 (0.703) + 0.6 \left( \frac{0.008724}{0.029352} \right)$$

$$\boxed{= 0.389}$$

d) Low, high, high

Q2

	Utilities	
	Accident	No. Acc
insured	-200	-10
not insured	-400	0

$$\begin{aligned}P(S=\text{true}, D=\text{true}) &= 0.02 \\P(S=\text{true}, D=\text{false}) &= 0.18 \\P(S=\text{false}, D=\text{true}) &= 0.08 \\P(S=\text{false}, D=\text{false}) &= 0.72\end{aligned}$$

a)  $\Rightarrow$  Expected utility given no info.

$$P(A) = \sum_{s,d} P(A=\text{true} | S=s, D=d) P(S=s, D=d)$$

$$= 0.5(0.02) + 0.3(0.18) + 0.2(0.08) + 0.1(0.72)$$

$$P(A) = 0.152$$

$$P(\neg A) = 0.848$$

$$\text{if not insured} \Rightarrow \text{Utility} = 0.152 * 400 = \$60.8$$

$$\text{if insured} \Rightarrow 0.152(-200) + 0.848(10) = \$38.88$$

$$\text{pay difference} = \$60.8 - \$38.88 = \$21.92$$



b)

insured

$$0.3(200) + 0.7(10) = 67$$

not insured

$$0.3(400) = 120$$

$$120 - 67 = \$53$$

c) not insured

$$\begin{aligned} P(A|D) &= P(A|D=\text{true}, S=\text{true})P(S=\text{true}) + P(A|D=\text{true}, S=\text{false})P(S=\text{false}) \\ &= 0.5(0.2) + 0.2(0.8) = 0.26 \end{aligned}$$

$$0.26(400) = 104$$

insured

$$0.26(200) + 0.74(10) = 59.4$$

$$\boxed{= \$44.6}$$

d) From part a) cost of insurance is 38.88

$$0.848(x) + 200(0.8)(0.152) + 400(0.2)(0.152) = 38.88$$

$$x = \$2.83$$

(23)

a)  $4^6 = 4096$  (4 actions, 6 states)

b)  $V^0(s_1) = 0 + 0.9(0.8(0) + 0.2(0)) = 0$

$V^0(s_2) = 0 + 0.9(0.8(+20) + 0.2(0)) = 14.4$

$V^0(s_3) = 20 + 0.9(1(20)) = 38$

$V^0(s_4) = 10 + 0.9(0.8(0) + 0.2(+10)) = 11.8$

$V^0(s_5) = 0 + 0.9(0.8(-10) + 0.2(0)) = -7.2$

$V^0(s_6) = -10 + 0.9(1(-10)) = -19$

c)  $\pi^1(s_1) = \text{Right}$

$\pi^1(s_2) = \text{Right}$

$\pi^1(s_3) = \text{Down}$

$\pi^1(s_4) = \text{Down}$

$\pi^1(s_5) = \text{UP}$

$\pi^1(s_6) = \text{UP}$

$$\left. \begin{array}{l} 0 + 0.9(0.8(14.4)) \\ 0 + 0.9(0.8(11.8)) \end{array} \right\} \begin{array}{l} s_1 \\ \text{Right} \end{array}$$

$$\left. \begin{array}{l} 14.4 + 0.9(0.8(38)) \\ 14.4 + 0.9(0.8(-7.2)) \end{array} \right\} \begin{array}{l} s_2 \\ \text{Right} \end{array}$$

d) using policy for C

$$V^1(s_1) = 0 + 0.9(0.8(14.4) + 0.2(0)) = 10.368$$

$$V^1(s_2) = 10 + 0.9(0.8(38) + 0.2(14.4)) = 29.952$$

$$V^1(s_3) = 20 + 0.9(1(38)) = 54.2$$

$$V^1(s_4) = 10 + 0.9(1(11.8)) = 20.62$$

$$V^1(s_5) = 0 + 0.9(0.8(14.4) + 0.2(-7.2)) = 9.072$$

$$V^1(s_6) = -10 + 0.9(0.8(38) + 0.2(-19)) = 13.94$$

One more iteration

$$\pi^2(s_1) = \text{Right}$$

$$\pi^2(s_2) = \text{Right}$$

$$\pi^2(s_3) = \text{Down}$$

$$\pi^2(s_4) = \text{Down}$$

$$\pi^2(s_5) = \text{UP}$$

$$\pi^2(s_6) = \text{UP}$$

$$V^2(s_1) = 0 + 0.9(0.8(29.952) + 0.2(10.368)) = 23.431$$

$$V^2(s_2) = 0 + 0.9(0.8(54.2) + 0.2(29.952)) = 44.14$$

$$V^2(s_3) = 20 + 0.9(1(54.2)) = 68.78$$

$$V^2(s_4) = 10 + 0.9(1(20.62)) = 28.558$$

$$V^2(s_5) = 0 + 0.9(0.8(29.952) + 0.2(9.072)) = 23.1984$$

$$V^2(s_6) = -10 + 0.9(0.8(54.2) + 0.2(13.94))$$

$$= 31.5332$$

↑ stop when policy does not change.

These are the optimal values  $V^*$

e) No. We did two iterations where the policy did not change, and both value functions were optimal. These functions were different and hence not unique.

f) As shown in part d) The optimal policy is (breaking ties alphabetically):

$\pi^*(s_1) = \text{Right}$

$\pi^*(s_2) = \text{Right}$

$\pi^*(s_3) = \text{down}$

$\pi^*(s_4) = \text{down}$

$\pi^*(s_5) = \text{up}$

$\pi^*(s_6) = \text{up}$

g) Yes, or else the policy would have changed in the two iterations shown in part d).

h) Changing  $s_6$  to  $-100$  would not change the policy as the optimal policy moves up from  $s_6$ .



Q4) a)

$$Q = \{1, 1, 3, 1, 1\}$$

$$A = \{1, 2, 3, 4, 5\}$$

$$Q_0 = \{1, 1, 3, 1, 1\}$$

t=1

$$Q_1(A=3) = Q_0(A=3) + (r_{n-1} - Q_0(A=3)) / 1$$
$$= 3 + \frac{(2-3)}{1}$$
$$= 2$$

$$Q_1 = \{1, 1, 2, 1, 1\}$$

t=2

$$Q_2(A=5) = 1 + \frac{0-1}{1}$$
$$= 0$$

$$Q_2 = \{1, 1, 2, 1, 0\}$$

t=3

$$Q_3(A=3) = 2 + \frac{1-2}{2}$$
$$= 1.5$$

$$Q_3 = \{1, 1, 1.5, 1, 0\}$$

t=4

$$Q_4(A=1) = 1 + \frac{0-1}{1}$$
$$= 0$$

$$Q_4 = \{0, 2, 1.5, 1, 0\}$$

t=5

$$Q_5(A=3) = 1.5 + \frac{0-1.5}{3}$$
$$= 1$$

$$Q_5 = \{0, 1, 1, 1, 0\}$$



- b)  $t=1$ : cannot be concluded  
 $t=2$ : can be concluded as best move is  $A=3$ , and we chose  $A=5$   
 $t=3$ : cannot be concluded since  $A=3$  is best and we chose it  
 $t=4$ : can be concluded as  $A=1$  is not the best move.  
 $t=5$ : cannot be concluded since we chose best move.