

$$\sqrt{pp2019} / A \cos(2\alpha) + F = B \sin(2\alpha) \quad \therefore$$

$$\frac{A \cos(2\alpha)}{\sin(2\alpha)} + \frac{F}{\sin(2\alpha)} = B \quad \therefore$$

$$R u(r, \phi) = A \cos(2\phi) + \frac{A \cos(2\alpha) \sin(2\phi)}{\sin(2\alpha)} + \frac{F \sin(2\phi)}{\sin(2\alpha)} + F \quad \therefore$$

$$\text{at } \phi = \alpha: u(r, \alpha) = 0 \quad \therefore$$

$$R(0) = A \cos(2\alpha) + \frac{A \cos(2\alpha) \sin(2\alpha)}{\sin(2\alpha)} + \frac{F \sin(2\alpha)}{\sin(2\alpha)} + F =$$

$$A \cos(2\alpha) + A \cos(2\alpha) + F + F = 2A \cos(2\alpha) + 2F = 0 = A \cos(2\alpha) + F \quad \therefore$$

$$F = -A \cos(2\alpha) \quad \therefore$$

$$R u(r, \phi) = A \cos(2\phi) + \frac{A \cos(2\alpha) \sin(2\phi)}{\sin(2\alpha)} + \frac{F \sin(2\phi)}{\sin(2\alpha)} - A \cos(2\alpha) + -A \cos(2\alpha)$$

$$= A(\cos(2\phi) - \cos(2\alpha)) + \frac{A \cos(2\alpha) \sin(2\phi)}{\sin(2\alpha)} - \frac{A \cos(2\alpha) \sin(2\phi)}{\sin(2\alpha)} =$$

$$A(\cos(2\phi) - \cos(2\alpha)) = C(\cos 2\phi - \cos 2\alpha) = R u \quad \therefore$$

$$C R^{-1} (\cos 2\phi - \cos 2\alpha) = u$$

$\sqrt{2S}$ / radially inwards slow has $u < 0 \therefore u = u \hat{R} = (-ve) \hat{R} \quad \therefore$

$$u = C(\cos 2\phi - \cos 2\alpha) \frac{1}{R} \therefore C < 0 \therefore \text{for } u < 0:$$

$$\cos 2\phi - \cos 2\alpha > 0 \quad \therefore \cos 2\phi > \cos 2\alpha$$

$$\arccos(\cos 2\phi) > 2\alpha \quad \therefore 2\phi > 2\alpha \quad \therefore \alpha < \phi$$

$$\text{for } \phi \in [0, 2\pi)$$

$\sqrt{2S}$ / radially inwards slow has $u < 0 \therefore u = u \hat{R} = (-ve) \hat{R} \quad \therefore$

$$u = C(\cos 2\phi - \cos 2\alpha) \frac{1}{R} \quad \therefore$$

$$C < 0 \quad \therefore \text{for } u < 0:$$

$$C(\cos 2\phi - \cos 2\alpha) \frac{1}{R} < 0 \quad \therefore R \geq 0 \quad \therefore \frac{1}{R} \leq 0 \quad \therefore C(\cos 2\phi - \cos 2\alpha) < 0$$

$$\therefore C < 0 \quad \therefore \cos 2\phi - \cos 2\alpha > 0 \quad \therefore$$

$$\cos 2\phi > \cos 2\alpha \quad \therefore \text{arccos}(\cos 2\phi) > 2\alpha \quad \therefore$$

$2\phi > 2\alpha \quad \therefore \phi > \alpha$ the slow is radially inwards

$$\text{with } \phi \in [0, 2\pi)$$



3ai/ $\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} = -\nabla \left(\frac{1}{\rho} P \right) + \underline{f}$ $\underline{u} = \nabla \times (\frac{1}{\rho} P)$ $\nabla^2 \underline{u} + \underline{u} \cdot \nabla^2 \underline{u}$

taking the curl of the NS equation

$$\nabla \times \left(\frac{\partial \underline{u}}{\partial t} \right) = \frac{\partial}{\partial t} \nabla \times \underline{u} = \frac{\partial \omega}{\partial t}$$

$$\nabla \times \left(-\nabla \left(\frac{1}{\rho} P \right) \right) = -\nabla \times \left[\nabla \left(\frac{1}{\rho} P \right) \right] = 0$$

$$\nabla \times \left(\nabla \times \underline{u} \right) = \nabla \times \left(\nabla \times \underline{u} \right) = 0$$

$$\nabla \times \left[\nabla \nabla \times \underline{u} \right] = \nabla \nabla \times \left[\nabla \times \underline{u} \right] = \nabla^2 \left(\nabla \times \underline{u} \right) = \nabla^2 \omega$$

$$\therefore \frac{\partial \omega}{\partial t} + \nabla \times (\underline{u} \cdot \nabla \underline{u}) = \nabla^2 \omega$$

PP2019/

1: ($\omega \cdot \nabla$)

D

, 3b; B

1: $\nabla \cdot (\underline{u})$

1: $\partial_i (\underline{u})$

$\nabla \cdot \underline{u}$; D

$\nabla^2 (\underline{u})$

1: ($\underline{u}; \nabla$)

$\underline{u} \cdot (\underline{u} \cdot \nabla)$

, 3b; B; S

\underline{u}_i

$\underline{u}_i \cdot \partial_i (\underline{u})$

$\underline{u}_i \cdot \underline{u}_i \cdot \partial_i$

$\underline{u}_i \cdot \underline{u}_i \cdot \nabla$

3bii/

$\underline{u} \cdot \nabla (\underline{u})$

$\frac{\partial}{\partial t} (\underline{u} \cdot \underline{u})$

; .

$= \underline{u} \cdot (\omega)$

$\omega \cdot \nabla (\underline{u})$

$\underline{u} \cdot \nabla \times (\underline{u} \times \omega)$

$\nabla \cdot (\underline{u} \times \omega)$

$= -\underline{u} \cdot \nabla \times \omega$

$= -\nabla \cdot (\underline{u} \times \omega)$

$= -\nabla \cdot \omega$

3ai/ let $\frac{\partial \omega}{\partial t} = \nabla \times (\underline{u} \times \omega) + \nabla^2 \omega$, $\nabla \cdot \underline{u} = 0$

$$\nabla^2 \underline{u} = \nabla \cdot (\nabla \cdot \underline{u}) + \nabla \times (\nabla \times \underline{u}) = \nabla \cdot (\nabla \cdot \underline{u}) - \nabla \times \omega$$

$$\nabla \times \nabla \cdot \underline{u} - \nabla \times (\nabla \cdot (\nabla \cdot \underline{u}) - \nabla \times \omega) = \nabla \times \nabla \cdot (\nabla \cdot \underline{u}) + \nabla \times (-\nabla \times \omega) =$$

$$\nabla \times \nabla \cdot (\nabla \cdot \underline{u}) - \nabla \times (\nabla \times \omega) = -\nabla \times (\nabla \times \omega) \quad \therefore \nabla \times \nabla \omega = 0$$

$$= -\nabla (\nabla \cdot \omega) + \nabla^2 \omega = -\nabla (\nabla \cdot \omega) + \nabla^2 \omega$$

$$-\nabla (\nabla \cdot (\nabla \times \omega)) + \nabla^2 \omega = \nabla \times \nabla \omega$$

$$-\nabla (\nabla \cdot (\nabla \times \omega)) + \nabla^2 \omega = \nabla \times \nabla \omega$$

$$= \nabla^2 \omega$$

3ai/ let $\frac{\partial \omega}{\partial t} = \nabla \times (\underline{u} \times \omega) + \nabla^2 \omega$, $\nabla \cdot \underline{u} = 0$

$$\nabla \times (\underline{u} \times \omega) = \underline{u} (\nabla \cdot \omega) - \omega (\nabla \cdot \underline{u}) + (\omega \cdot \nabla) \underline{u} - (\underline{u} \cdot \nabla) \omega$$

$$\therefore \nabla \cdot \underline{u} = 0 \quad \therefore \nabla \times (\underline{u} \times \omega) = \underline{u} (\nabla \cdot \omega) - \omega (\nabla \cdot \underline{u}) + (\omega \cdot \nabla) \underline{u} - (\underline{u} \cdot \nabla) \omega$$

$$\therefore \nabla \times (\underline{u} \times \omega) = \underline{u} (\nabla \cdot \omega) + (\omega \cdot \nabla) \underline{u} - (\underline{u} \cdot \nabla) \omega$$

$\therefore \nabla \cdot \nabla \times \underline{u} = 0 \quad \therefore \nabla \cdot \omega = \nabla \cdot \nabla \times \underline{u} = 0 \quad \therefore \underline{u} (\nabla \cdot \omega) = \underline{u} (0) = 0 \quad ;$

$\nabla \times (\underline{u} \times \omega) = (\omega \cdot \nabla) \underline{u} - (\underline{u} \cdot \nabla) \omega \quad ;$

$\frac{\partial \omega}{\partial t} = (\omega \cdot \nabla) \underline{u} - (\underline{u} \cdot \nabla) \omega + \nabla^2 \omega = -(\underline{u} \cdot \nabla) \omega + (\omega \cdot \nabla) \underline{u} + \nabla^2 \omega = \frac{\partial \omega}{\partial t}$

NS: $\rho \left(\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} \right) = -\nabla P + \rho f + \mu \nabla^2 \underline{u} \quad \therefore \quad f = \gg \quad ;$

$\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} = -\frac{1}{\rho} \nabla P + f + \mu \nabla^2 \underline{u} \quad ;$

$\nabla \times \frac{\partial \underline{u}}{\partial t} = \frac{\partial}{\partial t} \nabla \times \underline{u} = \frac{\partial \omega}{\partial t}$

\therefore

$f = -\nabla \cdot \underline{u} \quad \therefore \nabla \times f = \nabla \times (-\nabla \cdot \underline{u}) = -\nabla \times (\nabla \cdot \underline{u}) = 0$

$\nabla \times \left(-\frac{1}{\rho} \nabla P \right) = -\frac{1}{\rho} \nabla \times \nabla P = -\frac{1}{\rho} (0) = 0 \quad , \quad \nabla^2 \underline{u} = \nabla \times (\mu \nabla^2 \underline{u}) = \mu \nabla \times \nabla^2 \underline{u}$

$\frac{\partial \omega}{\partial t} + \nabla \times (\underline{u} \cdot \nabla \underline{u}) = \mu \nabla \times \nabla^2 \underline{u}$

$\nabla^2 u$

$$\sqrt{PP2019} / \sqrt{3b} i A / u \cdot (\omega \cdot \nabla) u \rightarrow [u \cdot (\omega \cdot \nabla) u]_i = u_i (\nabla \cdot \omega) u_i =$$

$$u_i (\omega \cdot \nabla) u_j = u_i (\omega_j \partial_j) u_i = \omega_j \partial_j \left(\frac{u_i u_j}{2} \right) = \omega \cdot \nabla \left(\frac{u u^T}{2} \right)$$

$$\sqrt{3b} i B / u \cdot \nabla (u \cdot \omega) \rightarrow [u \cdot \nabla (u \cdot \omega)]_i = u_i (\nabla (u \cdot \omega))_i =$$

$$u_i \nabla_i (u \cdot \omega) = u_i \partial_i (u_j \omega_j) =$$

$$u_i \partial_i (u_j) \omega_j + u_i u_j \partial_i (\omega_j) =$$

$$u_j u_i \partial_i \omega_j - u_j u_i \partial_i \omega_j + \omega_j u_i \partial_i u_j =$$

$$u \cdot (\nabla u) \omega + \omega \cdot (\nabla u) u$$

$$u_j (u_i \nabla_i \omega_j) + \omega_j (u_i \nabla_i) u_j = [u \cdot (\nabla u) \omega]_i + [\omega \cdot (\nabla u) u]_i =$$

$$[u \cdot (\nabla u) \omega + \omega \cdot (\nabla u) u]_i \rightarrow u \cdot (\nabla u) \omega + \omega \cdot (\nabla u) u$$

$$\sqrt{3b} i B_{S01} / u \cdot \nabla (u \cdot \omega) \rightarrow [u \cdot \nabla (u \cdot \omega)]_i = u_i \nabla_i (u_j \omega_j) =$$

$$u_i \partial_i (u_j \omega_j) = u_i \partial_i (u_j) \omega_j + u_i \partial_i (\omega_j) u_j =$$

$$u_i \partial_i (\omega_j) u_j + u_i \partial_i (\omega_j) u_j =$$

$$u_j u_i \partial_i (\omega_j) + \omega_j u_i \partial_i (u_j) =$$

$$u_j u_i \nabla_i (\omega_j) + \omega_j u_i \nabla_i (u_j) = [u \cdot (\nabla u) \omega + \omega \cdot (\nabla u) u]_i$$

$$\sqrt{3b} ii / u \cdot (\omega \cdot \nabla) u = \omega \cdot \nabla \left(\frac{u u^T}{2} \right),$$

$$u \cdot \nabla (u \cdot \omega) = u \cdot (\nabla u) \omega + \omega \cdot (\nabla u) u$$

$$\frac{\partial}{\partial t} (u \cdot \omega) = u \cdot [\omega \cdot \nabla u - (\nabla \cdot \omega) u] - \omega \cdot [(\nabla \cdot u) \omega + \nabla P],$$

$$\therefore u \cdot [\omega \cdot \nabla u - (\nabla \cdot \omega) u] - \omega \cdot [(\nabla \cdot u) \omega] = u \cdot [\omega \cdot \nabla u] - \omega \cdot [(\nabla \cdot \omega) u]$$

$$= u \cdot (\omega \cdot \nabla u) - \omega \cdot (\nabla \cdot u) u =$$

$$\omega \cdot \nabla u - (\nabla \cdot u) u + \omega \cdot (\nabla \cdot u) u,$$

$$\omega \cdot \nabla u + (\nabla \cdot u) u - \omega \cdot (\nabla \cdot u) u =$$

$$\sqrt{3b} ii / S01 / \frac{\partial}{\partial t} (u \cdot \omega) - u \cdot [\omega \cdot \nabla u - (\nabla \cdot \omega) u] - \omega \cdot [(\nabla \cdot u) \omega + \nabla P]$$

$$= -u \cdot \nabla (u \cdot \omega) - \omega \cdot \nabla (P - \frac{u^2}{2}) =$$

$$- \nabla \cdot [u \cdot \omega u + P \omega - \frac{u^2 \omega}{2}],$$

$$u \cdot \nabla u - \omega \cdot \nabla u = \nabla \cdot u - \omega \cdot u;$$

$$u \cdot \nabla (u \cdot \omega) - \omega \cdot \nabla (u \cdot u) = \nabla \cdot u - \omega \cdot u = (\nabla \cdot u) u - (\omega \cdot u) u;$$

$$\omega \cdot \nabla (u \cdot \omega) - \omega \cdot \nabla (P - \frac{u^2}{2}) = \omega \cdot \nabla P - \omega \cdot \nabla (\frac{u^2}{2}) = (\omega \cdot \nabla P) - (\omega \cdot \nabla \frac{u^2}{2}),$$

$$\therefore \omega \cdot \nabla (u \cdot \omega) = - \nabla \cdot [(\omega \cdot \omega) u + P \omega - \frac{u^2 \omega}{2}],$$

$\frac{\partial \omega}{\partial t}$

$\tau_x(\nabla u) = 0$

u

$$\backslash 3bii / \therefore H = \int_V u \cdot \omega dV \therefore \frac{dH}{dt} = \frac{\partial}{\partial t} \int_V (u \cdot \omega) dV =$$

$$\int_V \frac{\partial}{\partial t} (u \cdot \omega) dV = \int_V -\nabla \cdot [u \cdot \omega] u + \rho \omega - \frac{u^2}{2} \omega dV = 0 \therefore$$

$H = \text{constant}$

$$\backslash 4a / \text{incompressible} \therefore \nabla \cdot u = 0$$

\therefore boundary conditions of solid as slip boundary \therefore

Fluid at same y value as boundary has equal velocity to boundary in x axis \therefore

Solid boundary means $u = u_i + u_f + \hat{o}_z$ and

Since no slip condition means $u = u(y, t)$.

$$u = (u(y, t)) \hat{i} + u_f \hat{j} + \hat{o}_z$$

$$\backslash 4b / N-S: \rho \left(\frac{\partial u}{\partial t} + u \cdot \nabla u \right) = -\nabla p + \rho g + \mu \nabla^2 u \quad ; \quad f = 0 \quad \checkmark$$

$$\rho \left(\frac{\partial u}{\partial t} + u \cdot \nabla u \right) = -\nabla p + \mu \nabla^2 u \quad \therefore$$

$$\frac{\partial u}{\partial t} + (u \cdot \nabla) u = -\frac{1}{\rho} \nabla p + \frac{\mu}{\rho} \nabla^2 u = -\nabla \frac{p}{\rho} + \nu \nabla^2 u \quad \therefore$$

$$(u \cdot \nabla) = u(y, t) \frac{\partial}{\partial x} \therefore (u \cdot \nabla) u = u(y, t) \frac{\partial}{\partial x} (u(y, t)) = 0 \quad \therefore$$

$$\frac{\partial u}{\partial t} = -\nabla \frac{p}{\rho} + \nu \nabla^2 u \quad \therefore$$

$$\frac{\partial u}{\partial t} = \frac{\partial u}{\partial t} \hat{i}, \quad -\nabla \frac{p}{\rho} = 0 \quad \therefore \quad 2\nabla^2 u = \nabla^2 (u(y, t), 0, 0) =$$

$$2\nabla^2 u(y, t) \hat{i} = 2u_{yy} \hat{i} \quad \therefore \quad y\text{-component is } \hat{o}_y = u_f \hat{j},$$

$$x\text{-component is } \frac{\partial u}{\partial t} \hat{i} = 2u_{yy} \hat{i} \quad \therefore \quad u_t = 2u_{yy}$$

From SOT, the motion of the fluid is caused by the moving boundary which moves in the x -direction, so $u_t = u_i$

\therefore Fluid velocity does not depend of x coordinate \therefore is independent of x . The fluid at the y coordinate of the plate obeys the no slip \therefore it is dependent on y .

The velocity of the plate is different at $t=0$ and $t>0$.

\therefore as no slip, the fluid is also dependent on time

$$\backslash 4b / (u \cdot \nabla) = u(y, t) \frac{\partial}{\partial x} \therefore (u \cdot \nabla) u = u(y, t) \frac{\partial}{\partial x} u(y, t) = 0$$

$\therefore \frac{\partial u}{\partial x}$ is independent of x $\therefore p = \text{constant}$.

$$u_t = 2u_{yy} \quad \therefore \quad D = \frac{M}{\rho}$$

$$\nabla \cdot \mathbf{B} = 0 \quad \therefore \frac{\partial B_x}{\partial t} - \partial R \frac{\partial \omega}{\partial R} = 2\alpha \omega$$

$$\omega = e^{2at} F(\xi) = e^{2at} F(R e^{at})$$

$$\frac{\partial \omega}{\partial t} = 2a e^{2at} F'(R e^{at}) + e^{2at} F'(R e^{at}) R a e^{at}$$

$$\frac{\partial \omega}{\partial R} = e^{2at} F'(R e^{at}) e^{at}$$

$$\frac{\partial \omega}{\partial R} - \alpha R \frac{\partial \omega}{\partial R} - 2\alpha \omega =$$

$$2a e^{2at} F'(R e^{at}) + e^{2at} F'(R e^{at}) R a e^{at} - \alpha R e^{2at} F'(R e^{at}) e^{at} - 2a e^{2at} F'(R e^{at}) =$$

$$F(R e^{at})(2a e^{2at} - 2a e^{2at}) + F'(R e^{at})(e^{2at} R a e^{at} - \alpha R e^{2at} a e^{at}) =$$

$$F(R e^{at})(0) + F'(R e^{at})(0) = 0 + 0 = 0$$

$\omega = e^{2at} F(R e^{at})$ is a sol in the inviscid case

$\omega = \omega \hat{x} = \omega R, t = e^{2at} F(\xi) \quad \therefore \omega \text{ exponentially increases as } t \text{ increases}$

For $a > 0$ and vice versa for $a < 0$

$$\nabla \cdot \mathbf{A} / \underline{u} \cdot (\underline{\omega} \cdot \nabla) \underline{u} \rightarrow [\underline{u} \cdot (\underline{\omega} \cdot \nabla) \underline{u}]_i = u_i \cdot ((\underline{\omega} \cdot \nabla) \underline{u})_i =$$

$$u_i \cdot (\underline{\omega} \cdot \nabla) u_i = u_i \cdot (\omega_j \cdot \hat{x}_j) u_i = \omega_j \cdot \hat{x}_j \cdot \left(\frac{u_i u_i}{2} \right) = \underline{\omega} \cdot \nabla \left(\frac{|\underline{u}|^2}{2} \right)$$

$$\nabla \cdot \mathbf{B} / \underline{u} \cdot \nabla (\underline{u} \cdot \underline{\omega}) \rightarrow [\underline{u} \cdot \nabla (\underline{u} \cdot \underline{\omega})]_i = u_i \cdot \nabla (\underline{u} \cdot \underline{\omega})_i = u_i \cdot \hat{x}_i \cdot (u_j \cdot \omega_j) =$$

$$u_i \cdot \hat{x}_i \cdot \partial_i (\omega_j) u_j + u_i \cdot \hat{x}_i (\omega_j) u_j = u_i \cdot \hat{x}_i \cdot (\omega_j) u_j + u_i \cdot \hat{x}_i (\omega_j) \omega_j =$$

$$u_j \cdot u_i \cdot \partial_i (\omega_j) + \omega_j \cdot u_i \cdot \partial_i (u_j) =$$

$$u_j \cdot u_i \nabla_i (\omega_j) + \omega_j \cdot u_i \nabla_i (u_j) = [\underline{u} \cdot (\underline{\omega} \cdot \nabla) \underline{\omega}]_i + [\underline{\omega} \cdot (\underline{u} \cdot \nabla) \underline{u}]_i =$$

$$[\underline{u} \cdot (\underline{\omega} \cdot \nabla) \underline{\omega} + \underline{\omega} \cdot (\underline{u} \cdot \nabla) \underline{u}]_i$$

$$\nabla \cdot \mathbf{B} ii / \frac{\partial}{\partial t} (\underline{u} \cdot \underline{\omega}) = \underline{u} \cdot [(\underline{\omega} \cdot \nabla) \underline{u} - (\underline{u} \cdot \nabla) \underline{\omega}] - \underline{\omega} \cdot [(\underline{u} \cdot \nabla) \underline{u} + \nabla \cdot \underline{u}] =$$

$$\underline{u} \cdot (\underline{\omega} \cdot \nabla) \underline{u} - \underline{u} \cdot (\underline{u} \cdot \nabla) \underline{\omega} - \underline{\omega} \cdot [(\underline{u} \cdot \nabla) \underline{u} + \nabla \cdot \underline{u}]$$

$$-\underline{u} \cdot (\underline{u} \cdot \nabla) \underline{\omega} = -\underline{u} \cdot \nabla (\underline{u} \cdot \underline{\omega}) + \underline{\omega} \cdot (\underline{u} \cdot \nabla) \underline{u}$$

$$\underline{u} \cdot (\underline{\omega} \cdot \nabla) \underline{u} = \underline{\omega} \cdot \nabla \left(\frac{|\underline{u}|^2}{2} \right)$$

$$\frac{\partial}{\partial t} (\underline{u} \cdot \underline{\omega}) = \underline{\omega} \cdot \nabla \left(\frac{|\underline{u}|^2}{2} \right) - \underline{u} \cdot \nabla (\underline{u} \cdot \underline{\omega}) + \underline{\omega} \cdot (\underline{u} \cdot \nabla) \underline{u} - \underline{\omega} \cdot [(\underline{u} \cdot \nabla) \underline{u} + \nabla \cdot \underline{u}] =$$

$$-\underline{u} \cdot \nabla (\underline{u} \cdot \underline{\omega}) + \underline{\omega} \cdot (\underline{u} \cdot \nabla) \underline{u} - \underline{\omega} \cdot (\underline{u} \cdot \nabla) \underline{u} - \underline{\omega} \cdot [(\underline{u} \cdot \nabla) \underline{u} + \nabla \cdot \underline{u}] =$$

$$-\underline{u} \cdot \nabla (\underline{u} \cdot \underline{\omega}) + \underline{\omega} \cdot (\underline{u} \cdot \nabla) \underline{u} - \underline{\omega} \cdot (\underline{u} \cdot \nabla) \underline{u} - \underline{\omega} \cdot [(\underline{u} \cdot \nabla) \underline{u} + \nabla \cdot \underline{u}] =$$

$$-\underline{u} \cdot \nabla (\underline{u} \cdot \underline{\omega}) - \underline{\omega} \cdot \nabla (\underline{u} \cdot \underline{\omega}) = \nabla (\underline{u} \cdot \underline{\omega}) \cdot \underline{u} - \nabla (\underline{u} \cdot \underline{\omega}) \cdot \underline{\omega} =$$

$$-\nabla \cdot [(\underline{u} \cdot \underline{\omega}) \underline{u}] - \nabla \cdot [(\underline{u} \cdot \underline{\omega}) \underline{\omega}] = -\nabla \cdot [(\underline{u} \cdot \underline{\omega}) \underline{u}] - \nabla \cdot [(\underline{u} \cdot \underline{\omega}) \underline{\omega}] =$$

$$-\nabla \cdot [(\underline{u} \cdot \underline{\omega}) \underline{u} + \underline{\omega} \underline{\omega} - \frac{|\underline{u}|^2}{2} \underline{\omega}]$$

3biii) i. let $H = \int_V u \cdot \omega dV$..

$$\frac{\partial H}{\partial t} = \frac{\partial}{\partial t} \int_V u \cdot \omega dV = \int_V \frac{\partial}{\partial t} (u \cdot \omega) dV = \int_V -\nabla \cdot [u \cdot \omega] u + \rho \omega - \frac{u^2 \omega}{2} dV =$$

$$\int_V -\nabla \cdot (u \cdot \omega) u - \nabla \cdot \rho \omega - \nabla \cdot \left(-\frac{u^2}{2} \omega\right) dV =$$

$$-\int_V \nabla \cdot (u \cdot \omega) u dV + \int_V \rho \omega dV - \int_V \left(-\frac{u^2}{2} \omega\right) dV = 0 ..$$

$$\frac{\partial H}{\partial t} = 0 \therefore H = \text{constant}$$

4a) The motion of the fluid is caused by the moving boundary which moves in the x -direction $\therefore u = u \hat{i}$..
Fluid velocity does not depend on y coord \therefore is independent of y
The fluid at the y coord as the plate obeys the no slip \therefore it is dependent on y .

The ~~the~~ velocity of the plate is different at $t=0$ and $t>0$ \therefore

\therefore as no slip - the fluid is also dependent on time

\therefore The velocity of plate is different at $t=0$ and $t>0$ $\therefore u = u(y, t) \hat{i}$

4b) N-S: $\rho(\partial_t u + u \cdot \nabla u) = -\nabla p + \rho + \mu \nabla^2 u \therefore f = 0 \therefore$

~~$\rho(\partial_t u + u \cdot \nabla u) = -\nabla p + \mu \nabla^2 u \therefore$~~

$u \cdot \nabla = u(y, t) \frac{\partial}{\partial x} \therefore (u \cdot \nabla) u = u(y, t) \frac{\partial}{\partial x} (u(y, t)) = u(y, t)(0) = 0 \therefore u' =$

$\rho \frac{\partial u}{\partial t} = -\nabla p + \mu \nabla^2 u \therefore$

$\nabla^2 u = \nabla^2(u(y, t), 0, 0) = \nabla^2 u(y, t) \hat{i} = u_{yy} \hat{i} \therefore$

$x \text{ component } \therefore \frac{\partial u}{\partial t} = -\frac{\partial p}{\partial x} + \mu u_{yy} = u_{yy} \therefore \frac{\partial u}{\partial t} = \nu u_{yy}$

$y \text{ component } \therefore \frac{\partial u}{\partial t} = 0 = -\frac{\partial p}{\partial y} + \phi = 0 = \frac{\partial p}{\partial y} \therefore$

$\text{NS: } \frac{\partial u}{\partial t} = \nu u_{yy}$

4c) Fluid moves with the boundary on the boundary and that far away from the boundary, the fluid does know about the boundary motion at speed U

4d) let $u' = \frac{u}{U} \therefore \frac{\partial u'}{\partial t} = \frac{1}{U} \frac{\partial u}{\partial t}, \frac{\partial u'}{\partial y} = \frac{1}{U} \frac{\partial u}{\partial y} \therefore$

$U u_{yy} = \frac{1}{U} u_{yy} \therefore \frac{\partial u'}{\partial t} = \frac{1}{U} U u_{yy} \therefore U u_{yy} = u_{yy}, U u'_t = u_t \therefore$

$u_t = \nu u_{yy} = U u'_t \Rightarrow U u_{yy} \therefore u'_t = U u_{yy} \therefore$

$u(y, t=0) = 0 = U u'(y, t=0) = 0 = u'(y, t=0), u(y=0, t>0) = U = U u'(y=0, t>0) \therefore$

$u'(y=0, t>0) = 1, u(y \rightarrow \infty, t>0) = U u'(y \rightarrow \infty, t>0) \Rightarrow 0 \therefore u'(y \rightarrow \infty, t>0) \rightarrow 0$

$\nabla =$
 $\nabla^2 \text{PP2019} / 4e / [y] = L, [t] = T, \left[\frac{\partial u}{\partial t} \right] = \left[\frac{\partial}{\partial t} \right] [u] = T^{-1} [u] =$
 $T^{-1} \times LT^{-1} = L T^{-2} \therefore$
 $\left[\nabla^2 u \right] = \left[\frac{\partial^2 u}{\partial t^2} \right] = L T^{-2} = [y] [\nabla^2 u] = [y] L^{-2} [u] = [y] L^{-2} LT^{-1}$
 $= [y] L^{-1} T^{-1} = L T^{-2} \therefore$
 $[y] = L^2 T^{-1} \therefore$
 dary
 $y, t \text{ indep}, \nu \text{ dependent} \therefore$
 The quantity of interest is $u' \therefore$
 3 params $[y] = L, [t] = T, [\nu] = L^2 T^{-1} \therefore$
 $n=3, k=2, m=1 \therefore \alpha_1=y, \alpha_2=t \therefore$
 $\Pi_1 = \frac{\nu}{\alpha_1 \alpha_2^k} = \frac{\nu}{y^2 t^2} \therefore [\nu] = L^2 T^{-1} = [y]^{\alpha_1} [t]^{\alpha_2} = L^{\alpha_1} T^{\alpha_2} \therefore$
 $\alpha_1=2, \alpha_2=-1 \therefore \Pi_1 = \frac{\nu}{y^2 t^{-1}} \therefore$
 $\Pi = \underline{\Phi}(\Pi_1) = \underline{\Phi}\left(\frac{\nu}{y^2 t^{-1}}\right)$
 where Π is the quantity of interest made dimensionless \therefore
 Π_1 is the dependent params made dimensionless using the
 params with independent \therefore
 $\Pi = u', \Pi_1 = \frac{\nu}{y^2 t^{-1}} = \underline{\Phi} \therefore$
 $u' = \underline{\Phi}(\underline{\Phi}(\Pi)) = \underline{\Phi}\left(\frac{y}{\sqrt{1+2\Pi}}\right) \therefore$
~~let~~ $\Pi = \underline{\Phi}(\hat{\Pi}_1(\Pi)) = \hat{\Pi}_1\left(\frac{\nu}{y^2 t^{-1}}\right) = \hat{\Pi}_1\left(\left(\frac{y}{\sqrt{1+2\Pi}}\right)^{-1/2}\right) = \hat{\Pi}_1\left(\left(\frac{y^2 t^{-1}}{\nu}\right)^{1/2}\right) =$
~~let~~ $\hat{\Pi}_1\left(\left(\frac{y^2 t^{-1}}{\nu}\right)^{1/2}\right) = \hat{\Pi}_1\left(\sqrt{\frac{y^2 t^{-1}}{\nu}}\right) = \hat{\Pi}_1\left(\frac{y}{\sqrt{\nu t^{-1}}}\right) = \underline{\Phi}\left(\frac{1}{16} \frac{y}{\sqrt{\nu t^{-1}}}\right) =$
 $\underline{\Phi}\left(\frac{1}{16} \frac{y}{\sqrt{\nu t^{-1}}}\right) = \underline{\Phi}\left(\frac{y}{\sqrt{1+2\Pi}}\right) = u'$
 $\nabla^2 \text{PP2019} / 4e / u' = \underline{\Phi}\left(\frac{y}{\sqrt{1+2\Pi}}\right) \therefore u'_t = \underline{\Phi}'\left(\frac{y}{\sqrt{1+2\Pi}}\right) (-\frac{1}{2} t^{-3/2}) = -\frac{1}{2} t^{-3/2} \underline{\Phi}'(z) \therefore$
 $u'_y = \frac{1}{16} t^{-1/2} \underline{\Phi}'\left(\frac{y}{\sqrt{1+2\Pi}}\right) t^{-1/2} \therefore u'_y = \frac{1}{16} t^{-1} \underline{\Phi}''(z) \therefore$
 $u'_t \rightarrow u'_y = 0 = -\frac{1}{2} t^{-3/2} \underline{\Phi}' - \frac{1}{4} t^{-1} \underline{\Phi}''(z) = 0 = -\frac{1}{2} t^{-3/2} \underline{\Phi}' - \frac{1}{4} t^{-1} \underline{\Phi}''(z) \therefore$
 $\underline{\Phi}''(z) + 2t^{-3/2} t \underline{\Phi}''(z) = \underline{\Phi}''(z) + 2z \underline{\Phi}'(z) = 0 = \underline{\Phi}''(z) + 2z \underline{\Phi}' \therefore$
 BC: $u'(y, t=0) = 0, u'(y=0, t>0) = 1, u'(y \rightarrow \infty, t>0) \rightarrow 0 \therefore$
 $u' = \underline{\Phi}(z) = \underline{\Phi}\left(\frac{y}{\sqrt{1+2\Pi}}\right) \therefore u(y, t=0) =$
 $u'(y=0, t>0) = \underline{\Phi}(0) = 1, u'(y \rightarrow \infty, t>0) = \underline{\Phi}(\infty) = 0 \therefore$
 $\underline{\Phi}(z \rightarrow \infty) \rightarrow 0$

TOP - READY FOR 3D PC GAME

48
 ~~γ'~~ $\because \gamma = \Phi' \therefore \gamma' + 2\gamma \gamma = 0 = P(z)\gamma' + 2zP(z)\gamma = 0 =$
 ~~$\frac{d}{dz}(P(z)\Phi)$~~ $\therefore \frac{d}{dz}P(z) = 2zP(z) \therefore \int \frac{P(z)}{P(z)} dz = \int 2z dz = z^2 = \ln P(z) \therefore$
 $P(z) = e^{z^2} \therefore \frac{d}{dz}(e^{z^2}\gamma) = 0 \therefore$
 $e^{z^2}\gamma = e^{z^2}\Phi' = A \therefore \Phi = Ax \quad \Phi' = Ae^{-z^2}$
 $\therefore \int \Phi = A \int e^{-z^2} dz = \Phi(z) \therefore \Phi(z) = A \int_0^z e^{-s^2} ds$
 $\therefore \Phi(0) = 1 = A \int_0^0 e^{-s^2} ds$
 $\therefore \Phi(z) = A \int_0^z e^{-s^2} ds + B \therefore$
 $\Phi(0) = 1 = A \int_0^0 e^{-s^2} ds + B \Rightarrow B = 1 \therefore$
 $\Phi(z) = A \int_0^z e^{-s^2} ds + 1 \therefore$
 $\Phi(z \rightarrow \infty) = A \int_0^\infty e^{-s^2} ds + 1 = 0 = A(1) + 1 \therefore A = -1 \therefore$
 $\Phi(z) = -e^{-z^2} \quad \Phi(z) = - \int_0^z e^{-s^2} ds + 1$

49/ Since on area element dS with unit normal n is
 $dF = \sigma_{ij} n_j dS = \sum_i dS \quad \sigma_{ij}$ is the stress tensor
 n normal to surface $\therefore \sum_i \text{viscous} |_{y=0} = -U \left(\frac{\partial u}{\partial n}\right)^{1/2}$

$$U \left(\frac{\partial u}{\partial n} \right)^{1/2} = 1 \quad \text{and } U, \frac{\partial u}{\partial n}, \text{ etc.}$$

PP2022/1a/ $\frac{D\rho}{Dt} + \rho \nabla \cdot \underline{u}$ is continuity equation

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \underline{u}) = \frac{\partial \rho}{\partial t} + \rho \nabla \cdot \underline{u} + \underline{u} \cdot \nabla \rho = 0 \quad \therefore$$

incompressible: $\nabla \cdot \underline{u} = 0 \quad \therefore [\nabla \cdot \underline{u}]_i = \partial_i u_i = 0$

$$[\frac{\partial \rho}{\partial t} + \rho \nabla \cdot \underline{u}]_i = \left[\frac{\partial \rho}{\partial t} + \rho \nabla \cdot \underline{u} + \underline{u} \cdot \nabla \rho \right]_i = \left[\frac{\partial \rho}{\partial t} \right]_i + [\rho \nabla \cdot \underline{u}]_i + [\underline{u} \cdot \nabla \rho]_i =$$

$$(\frac{\partial \rho}{\partial t})_i + \rho \partial_i \cdot \underline{u}_i + \underline{u}_i \cdot \partial_i \rho = (\frac{\partial \rho}{\partial t})_i + \rho (\partial_i u_i) + u_i \partial_i \rho = 0$$

continuity equation \therefore incompressible $\therefore \frac{D\rho}{Dt} = 0 \quad \therefore$

$$[\frac{\partial \rho}{\partial t}]_i = \left[\frac{\partial \rho}{\partial t} + \underline{u} \cdot \nabla \rho \right]_i = \left(\frac{\partial \rho}{\partial t} \right)_i + \underline{u}_i \cdot \partial_i \rho = 0 \quad \therefore$$

$$(\frac{\partial \rho}{\partial t})_i + \rho (\partial_i u_i) + \underline{u}_i \cdot \partial_i \rho = 0 = \rho (\partial_i u_i) = 0 = \partial_i u_i = \frac{\partial u_i}{\partial x_i} = 0$$

1b i/ incompressible $\therefore \nabla \cdot \underline{u} = 0 \quad \therefore$

$$[\frac{\partial u}{\partial t}]_i = \frac{\partial u_i}{\partial t} \quad , \quad [\underline{u} \cdot \nabla \underline{u}]_i = [(\underline{u} \cdot \nabla) \underline{u}]_i = u_j \partial_j u_i = u_j \frac{\partial u_i}{\partial x_j}$$

$$[\nabla \rho]_i = \frac{\partial \rho}{\partial x_i} \quad [g]_i = g_i \quad [\nabla \times \underline{u}]_i = \nabla \cdot (\nabla \times \underline{u}) - \nabla \cdot (\nabla g)_i$$

$$[\nabla^2 \underline{u}]_i = \frac{\partial^2}{\partial x_i \partial x_j} u_i \quad \therefore$$

$$\rho \left(\frac{\partial u_i}{\partial t} + u_j \frac{\partial u_i}{\partial x_j} \right) = - \frac{\partial \rho}{\partial x_i} + \rho g_i + \mu \frac{\partial^2 u_i}{\partial x_j \partial x_j} \quad \text{is } i\text{th component of N-S}$$

$$1b ii/ \omega = \nabla \times \underline{u} \quad \therefore \omega_i = [\nabla \times \underline{u}]_i = \epsilon_{ijk} \partial_j u_k$$

1c i/ streamline equations: $\frac{dx}{dt} = \frac{dy}{dt} = \frac{dz}{dt} = \frac{d\underline{x}}{dt}$

$$\therefore \underline{u} = \left(\frac{x}{1+t}, \frac{y}{1+t}, \frac{z}{1+t} \right)$$

$$\frac{dx}{(x/1+t)} = \frac{dy}{(y/1+t)} + \frac{dz}{(z/1+t)} \quad \therefore \frac{1}{x} dx = \frac{1}{y} dy = \frac{1}{z} dz \quad \therefore$$

$$\int \frac{1}{x} dx = \int \frac{1}{y} dy = \int \frac{1}{z} dz = \ln|x| = \ln|y| + C_1 = \ln|z| + C_2 \quad \therefore$$

$$|x| = e^{\ln|y| + C_1} = A_1 |y| = e^{\ln|z| + C_2} = A_2 |z| \quad \therefore$$

$$x = \pm A, y = \pm A_2 z = B_2 z = B_2 z = x \quad \therefore (A, B_1, B_2) \quad B_1, B_2 \text{ are consts}$$

$$\text{is other streamlines} \quad \frac{dx_1}{u_1} = \frac{dx_2}{u_2} \quad , \quad \frac{dx_2}{u_2} = \frac{dx_3}{u_3} \quad \therefore$$

$$\frac{dx_1}{(x/1+t)} = \frac{dy}{(y/1+t)} \quad \therefore \frac{1}{x} dx = \frac{1}{y} dy \quad \therefore \ln x = \ln y + C_1 \quad \therefore x = A y$$

$$\frac{dx}{(x/1+t)} = \frac{dz}{(z/1+t)} \quad \therefore \frac{1}{x} dx = \frac{1}{z} dz \quad \therefore \ln x = \ln z + C_2 \quad \therefore x = B z$$

$$\frac{dy}{(y/1+t)} = \frac{dz}{(z/1+t)} \quad \therefore \frac{dy}{y} = \frac{dz}{z} \quad \therefore \ln y = \ln z + C_3 \quad \therefore y = C z \quad \therefore$$

$$\frac{x}{A} = C z \quad \therefore x = A C z = B z \quad , \quad A C = B \quad \therefore A z = \frac{B}{A} z \quad \therefore y = \frac{B}{A} z \quad \therefore (x, A y, B z)$$

$$\text{1Cii} \quad \therefore \frac{dx}{dt} = u, \frac{dy}{dt} = v, \frac{dz}{dt} = w \quad \therefore$$

$$u = \left(\frac{x}{1+t}, \frac{y}{1+t}, \frac{z}{1+t} \right) \quad \therefore$$

$$\frac{dx}{dt} = \frac{x}{1+t} \quad \therefore \int \frac{1}{x} dx = \int \frac{1}{1+t} dt = \ln x = \ln(1+t) + C_1 \quad \therefore$$

$$x = e^{\ln(1+t) + C_1} = A_1(1+t) = x,$$

$$\frac{dy}{dt} = \frac{y}{1+t} \quad \therefore \int \frac{1}{y} dy = \int \frac{1}{1+t} dt = \ln y = \ln(1+t) + C_2 \quad \therefore$$

$$y = e^{\ln(1+t) + C_2} = A_2(1+t) = y \quad \therefore$$

$$\frac{dz}{dt} = \frac{z}{1+t} \quad \therefore \int \frac{1}{z} dz = \int \frac{1}{1+t} dt = \ln z = \ln(1+t) + C_3 \quad \therefore$$

$z = e^{\ln(1+t) + C_3} = A_3(1+t) = z$ are the particle paths
 $(x, y, z) = (A_1(1+t), A_2(1+t), A_3(1+t))$

$$\text{1Ciii} \quad \therefore (1, 1, 0) = (A_1(1+0), A_2(1+0), A_3(1+0)) = (A_1, A_2, A_3) \quad \therefore$$

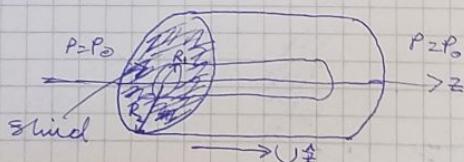
$$A_1 = 1, A_2 = 1, A_3 = 0 \quad \therefore \quad (x, y, z) = (1+t, 1+t, 0) \quad \therefore$$

$$\text{at } t=2: (x, y, z)|_{t=2} = (1+2, 1+2, 0) = (3, 3, 0)$$

\text{1d i} / incompressible $\therefore \nabla \cdot \underline{u} = 0$

neglect gravity $\therefore g = 0$

open to atmosphere $\therefore \# p \neq 0$



\text{1d ii} / no-slip boundary conditions \therefore

no special θ or ϕ coordinates \therefore flow independent of θ and ϕ .

speed: no-slip BCs \therefore flow speed different at R_2 and R_1 and $R = R_2 \therefore$ flow dependent on R .

flow: no pressure gradient \therefore flow only dependent on R directed in the \hat{z} direction due to boundary movement $\therefore u = w\hat{z}$ $\therefore w = w(R) \therefore u = w(R)\hat{z}$

$$\text{1d iii} / \text{condition is } \nabla \cdot \underline{u} = 0 \quad \therefore \nabla \cdot \underline{u} = \nabla \cdot w(R)\hat{z} = \nabla \cdot (0, 0, w(R)) = \\ \frac{\partial}{\partial R} \left(\frac{\partial w(R)}{\partial R} \right) - \frac{1}{R} \frac{\partial}{\partial R} (R \cdot 0) + \frac{1}{R} \frac{\partial (0)}{\partial R} + \frac{\partial w(R)}{\partial z} = \frac{1}{R} \frac{\partial}{\partial R} (0) + \frac{1}{R} (0) + 0 = 0 + 0 + 0 = 0$$

$$\text{PP2022} \quad \text{1dV/NS: } \rho \left(\frac{\partial u}{\partial t} + u \cdot \nabla u \right) = \mu \nabla^2 u - \frac{1}{\rho} \nabla P \quad \frac{F}{\rho} = 0$$

$$\frac{\partial u}{\partial t} + u \cdot \nabla u = \mu \nabla^2 u - \frac{1}{\rho} \nabla P \quad \therefore$$

$$\therefore z\text{-component: } \frac{\partial u}{\partial t} = 0$$

$$u \cdot \nabla u = u \nabla u \quad \therefore \left[\nabla^2 u \right]_z = \nabla^2 w(R) = \frac{1}{R} \frac{\partial}{\partial R} \left(R \frac{\partial w(R)}{\partial R} \right) \quad \therefore$$

$$u \cdot \nabla u = u \cdot \nabla (0, 0, w(R)) = (0, 0, w(R)) \cdot \nabla (0, 0, w(R)) =$$

$$w(R) \frac{\partial}{\partial z} w(R) = \cancel{\partial} w(R) \times 0 = 0 \quad \therefore$$

$$\frac{\partial u}{\partial t} = \frac{\partial}{\partial t} (0, 0, w(R)) = (0, 0, 0) \quad \therefore$$

$$\mu \nabla^2 u - \frac{1}{\rho} \nabla P = 0 \quad \therefore \nabla P = \nabla^2 u \quad \therefore$$

$$\nabla^2 u = \nabla^2 (0, 0, w(R)) = \left(\frac{1}{R} \frac{\partial}{\partial R} \left(R \frac{\partial w(R)}{\partial R} \right) + \frac{1}{R^2} \frac{\partial^2 w(R)}{\partial R^2} + \frac{\partial^2 w(R)}{\partial z^2} \right) \hat{z} = \\ \left(\frac{1}{R} \frac{\partial}{\partial R} \left(R \frac{\partial w(R)}{\partial R} \right) \right) \hat{z} \quad \therefore$$

$$\mu \frac{1}{R} \frac{\partial}{\partial R} \left(R \frac{\partial w}{\partial R} \right) \hat{z} = \nabla P \quad \therefore$$

$$R\text{ component: } \frac{\partial P}{\partial x} = 0 \quad , \cancel{x}\text{ component: } \frac{\partial P}{\partial y} = 0$$

$$z\text{ component: } \frac{\partial P}{\partial z} = \frac{\mu}{R} \frac{d}{dR} \left(R \frac{dw}{dR} \right)$$

\backslash dV/cylinders are open at both sides

and at both ends $P = P_0$:

$$\lim_{z \rightarrow -\infty} P = P_0, \lim_{z \rightarrow \infty} P = P_0 \quad \therefore \nabla P = 0 = \frac{\partial P}{\partial R} \hat{R} + \frac{\partial P}{\partial x} \hat{x} + \frac{\partial P}{\partial z} \hat{z} \quad \therefore$$

$$z\text{ component: } \frac{\partial P}{\partial z} = 0 \quad \therefore \frac{P_0 - P_0}{L} = \frac{0}{L} = 0$$

\therefore There is no pressure differential in the cylinders along the z axis

$$\backslash \text{dV}/ \frac{1}{\mu} \frac{dP}{dz} = 0 \quad \therefore 0 = \frac{\mu}{R} \frac{d}{dR} \left(R \frac{dw}{dR} \right) \quad \therefore \frac{d}{dR} \left(R \frac{dw}{dR} \right) = 0 \quad \therefore$$

$$R \frac{dw}{dR} = A \quad \therefore \frac{dw}{dR} = A \frac{1}{R} \quad \therefore w = A \ln R + B$$

$$\text{but } R \geq 0 \quad \therefore \ln |R| = \ln R \quad \therefore w = A \ln R + B$$

$$\backslash \text{dV}, \text{BCS: at } R=R_1: \quad u(R=R_1) = 0$$

$$\text{at } R=R_2: \quad u(R=R_2) = U \hat{z} \quad \therefore$$

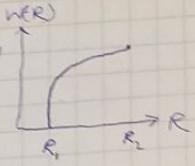
$$(i) \quad u = w(R) \hat{z} \quad \therefore wR \quad \therefore u = (A \ln R + B) \hat{z} \quad \therefore$$

$$u(R=R_1) = 0 = (A \ln R_1 + B) \hat{z} = 0 = A \ln R_1 + B \quad \therefore -A \ln R_1 = B \quad \therefore$$

$$u = (A \ln R - A \ln R_1) \hat{z} \quad \therefore u(R=R_2) = U = A \ln R_2 - A \ln R_1 = A \ln \left(\frac{R_2}{R_1} \right) \quad \therefore A = \frac{U}{\ln \left(\frac{R_2}{R_1} \right)}$$

$$u = \left(\frac{U}{\ln \left(\frac{R_2}{R_1} \right)} \ln \left(\frac{R}{R_1} \right) \right) \hat{z}$$

$$\frac{1}{2} \rho u^2 / \frac{R_2}{R_1} \therefore w = \frac{u}{\ln(\frac{R_2}{R_1})} \ln\left(\frac{R}{R_1}\right) \therefore u$$



$$\therefore w(R_2) = u, \quad w(R_1) = 0 \quad \therefore$$

The profile agrees with no fluid movement at $R=R_1$ and fluid speed u at $R=R_2$

\therefore no slip boundaries.

$$2a/NS: \rho \left(\frac{\partial u}{\partial t} + u \cdot \nabla u \right) = -\nabla p + \rho g + \mu \nabla^2 u \therefore \frac{\partial u}{\partial t} = \dots$$

$$\frac{\partial u}{\partial t} + u \cdot \nabla u = -\nabla \frac{p}{\rho} + g + \mu \nabla^2 u$$

$$\therefore \omega = \nabla \times u \therefore g = 0 \therefore$$

$$\frac{\partial u}{\partial t} = u \cdot \nabla u - u \cdot \nabla u - \mu \nabla^2 u \therefore$$

$$\therefore u^2 = u \cdot u \therefore$$

$$-u \cdot \nabla u = u \times \omega - \nabla \left(\frac{u^2}{2} \right) = u \times (\nabla \times u) - \nabla \left(\frac{u \cdot u}{2} \right) = -u \cdot \nabla u \therefore$$

$$2u \times (\nabla \times u) - \nabla(u \cdot u) = -2u \cdot \nabla u$$

$$\text{At } g = 0 \therefore \frac{\partial u}{\partial t} + u \cdot \nabla u = -\nabla \frac{p}{\rho} + \nu \nabla^2 u$$

$$\therefore \omega = \nabla \times u \therefore \frac{\partial u}{\partial t} = -u \cdot \nabla u - \nabla \frac{p}{\rho} + \nu \nabla^2 u \therefore$$

$$-2(u \cdot \nabla)u = -2u \cdot \nabla u = u \times (\nabla \times u) + u \times (\nabla \times u) - \nabla(u \cdot u) = 2u \times (\nabla \times u) - \nabla(u^2)$$

$$\therefore -(u \cdot \nabla)u = u \times (\nabla \times u) - \nabla\left(\frac{u^2}{2}\right) = -(\nabla \times u)u \cdot \nabla u = u \times \omega - \nabla\left(\frac{u^2}{2}\right) \therefore$$

$$\frac{\partial u}{\partial t} = u \times \omega - \nabla\left(\frac{p}{\rho} + \frac{u^2}{2}\right) - \nabla\left(\frac{p}{\rho}\right) + \nu \nabla^2 u = u \times \omega - \nabla\left(\frac{p}{\rho} + \frac{u^2}{2}\right) + \nu \nabla^2 u$$

$$2b/\text{steady} \therefore \frac{\partial u}{\partial t} = 0 \text{ inviscid} \therefore \mu = 0 \therefore \nu = 0 \therefore$$

$$0 = u \times \omega - \nabla\left(\frac{p}{\rho} + \frac{u^2}{2}\right) \therefore$$

$$\nabla u \times \omega = \nabla\left(\frac{p}{\rho} + \frac{u^2}{2}\right) z \therefore$$

$$u = (u_1, u_2, u_3) \therefore \text{along streamlines } u \times \omega = 0 \therefore$$

$$\nabla\left(\frac{p}{\rho} + \frac{u^2}{2}\right) = 0 \text{ or } \therefore \frac{p}{\rho} + \frac{u^2}{2} = \text{constant} \therefore p = \frac{p}{\rho} + \frac{u^2}{2} = \text{constant}$$

$$2c/\frac{\partial u}{\partial t} = u \times \omega - \nabla\left(\frac{p}{\rho} + \frac{u^2}{2}\right) + \nu \nabla^2 u \therefore$$

$$\nabla \times \left(\frac{\partial u}{\partial t} \right) = \frac{\partial}{\partial t} (\nabla \times u) = \frac{\partial \omega}{\partial t}$$

$$\nabla \times \nabla^2 u = \nabla \times (\nabla(p/\rho) - \nabla \times (\nabla \times u)) = \nabla \times (\nabla(p/\rho) - \nabla \times (\nabla \times u)) = -\nabla \times (\nabla \times (\nabla \times u))$$

$$-\nabla \times (\nabla \times \omega) = -\nabla \times (\nabla \times \omega) - \nabla^2 \omega = -\nabla \times (\nabla \times \omega) - \nabla^2 \omega = -\nabla \times (\nabla \times \omega) - \nabla^2 \omega$$

$$-\nabla \times \left(\frac{p}{\rho} + \frac{u^2}{2} \right) = -\nabla \times \left(\frac{p}{\rho} + \frac{u^2}{2} \right) = 0$$

$$\nabla \times (u \times \omega) = \nabla \times (u \times \omega) - \nabla \times (u \times \omega) + \nabla \times (u \times \omega) = u \times \omega =$$

$$\nabla \times (\underline{u} \times \underline{\omega}) = -\underline{\omega}(\nabla \cdot \underline{u}) + (\underline{\omega} \cdot \nabla) \underline{u} - (\underline{u} \cdot \nabla) \underline{\omega}$$

$$\frac{D\omega}{Dt} = \frac{\partial \omega}{\partial t} + \underline{u} \cdot \nabla \omega$$

$$\frac{\partial \omega}{\partial t} = -\underline{\omega}(\nabla \cdot \underline{u}) + (\underline{\omega} \cdot \nabla) \underline{u} - (\underline{u} \cdot \nabla) \underline{\omega} + 2\nabla^2 \underline{\omega}$$

$$\therefore \nabla \cdot \underline{u} = 0 \therefore -\underline{\omega}(\nabla \cdot \underline{u}) = -\underline{\omega}(0) = 0 \therefore$$

$$(\underline{\omega} \cdot \nabla) \underline{u} = \underline{\omega} \cdot \nabla \underline{u}, \quad -(\underline{u} \cdot \nabla) \underline{\omega} = -\underline{u} \cdot \nabla \underline{\omega} \therefore$$

$$\frac{\partial \omega}{\partial t} + \underline{u} \cdot \nabla \omega = \underline{\omega} \cdot \nabla \underline{u} + 2\nabla^2 \underline{\omega} = \frac{D\omega}{Dt} = \left(\frac{\partial}{\partial t} + \underline{u} \cdot \nabla \right) \omega$$

$$\frac{D}{Dt} = \frac{\partial}{\partial t} + \underline{u} \cdot \nabla$$

2 ✓ $\frac{D}{Dt}$ is the material derivative

$\therefore \frac{D\omega}{Dt}$ is the material derivative of ω : is the rate of change of vorticity following the fluid motion

$2\nabla^2 \underline{\omega}$ is the kinematic viscosity multiplied by the gradient squared vector of the vorticity

$\underline{\omega} \cdot \nabla \underline{u}$ is the vector of the vorticity dot product with the gradient operator operated on the velocity

$$\text{e.i. } \underline{\omega} = \nabla \times \underline{u} = \nabla \times (U(y, t), -ay, az) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ U(y, t) & -ay & az \end{vmatrix} =$$

$$\begin{aligned} & \hat{i} \left(\frac{\partial}{\partial y}(az) - \frac{\partial}{\partial z}(-ay) \right) - \hat{j} \left(\frac{\partial}{\partial x}(az) - \frac{\partial}{\partial z}(U(y, t)) \right) + \hat{k} \left(\frac{\partial}{\partial x}(-ay) - \frac{\partial}{\partial y}(U(y, t)) \right) = \\ & \hat{i}(0-0) - \hat{j}(0-0) + \hat{k}(0 - \frac{\partial U(y, t)}{\partial y}) = \hat{k} - \frac{\partial U(y, t)}{\partial y} \hat{k} = (0, 0, \omega_U(y, t)) \end{aligned}$$

$$\text{for } \omega_U(y, t) = -\frac{\partial U(y, t)}{\partial y}$$

$$\text{e.ii. } \frac{\partial \omega}{\partial t} + \underline{u} \cdot \nabla \omega = \underline{\omega} \cdot \nabla \underline{u} + 2\nabla^2 \underline{\omega} \quad \underline{\omega} = \omega \hat{z}$$

$$\text{z component: } \frac{\partial \omega}{\partial t} + (\omega \hat{z}) \frac{\partial \omega}{\partial z} = (\omega) \frac{\partial}{\partial z}(\omega \hat{z}) + 2 \frac{\partial^2 \omega}{\partial y^2} \hat{z} = \frac{\partial \omega}{\partial t} + \omega \frac{\partial^2 \omega}{\partial z^2} \hat{z}$$

\therefore steady, independent of t : $\omega = \omega(y)$

$$\frac{\partial \omega}{\partial t} = 0; \quad \omega \frac{\partial}{\partial z}(\omega \hat{z}) = \omega \omega + \omega \frac{\partial^2 \omega}{\partial y^2} \hat{z} = 0$$

$$\frac{d\omega}{dy} \omega(y) + \omega \frac{\partial \omega}{\partial y} = 0 \quad \therefore \text{let } \omega = e^{qy}; \quad \omega' = q e^{qy}; \quad \omega'' = q^2 e^{qy}$$

$$\therefore q^2 e^{qy} + q e^{qy} = 0 = q^2 + q \quad \therefore q^2 = -\frac{q}{2} \quad \therefore q = \pm \sqrt{-\frac{q}{2}} i$$

$$\therefore \omega(y) = A_1 \cos(\sqrt{-\frac{q}{2}} y) + B_1 \sin(\sqrt{-\frac{q}{2}} y)$$

tant

$\omega(y)$

ω

2eii/ $\omega = \alpha y$: $\frac{\partial \omega}{\partial t} = 0 \Rightarrow \nabla \cdot \omega = \omega \nabla \cdot \nabla \times \omega$
 $\omega \cdot \nabla = (\omega_x \frac{\partial}{\partial x} + \omega_y \frac{\partial}{\partial y} + \omega_z \frac{\partial}{\partial z}) \cdot \nabla = \omega_x \frac{\partial}{\partial x} \omega = \omega_x \frac{\partial \omega}{\partial x}$
 $\omega \cdot \nabla \omega = (\omega_x \frac{\partial}{\partial x} + \omega_y \frac{\partial}{\partial y} + \omega_z \frac{\partial}{\partial z}) \omega(y) \hat{z} = -\omega_y \frac{\partial \omega}{\partial y} \hat{z}$
 $\omega \cdot \nabla = (\omega_x \hat{x} + \omega_y \hat{y} + \omega_z \hat{z}) \cdot (\frac{\partial}{\partial x} \omega, \frac{\partial}{\partial y} \omega, \frac{\partial}{\partial z} \omega) = \omega_z \frac{\partial}{\partial z} \omega$
 $\omega \cdot \nabla \omega = \omega(y) \frac{\partial}{\partial z} (\omega_x, \omega_y, \omega_z) = (\omega_x, \omega_y, \omega_z) \frac{\partial \omega}{\partial z} = \omega(y) \omega \hat{z}$
 $\therefore \hat{z}$ component: $\omega_z(y) = \omega_0(y) + \nu \frac{\partial \omega}{\partial y}$
 $\omega = (\omega_x, \omega_y, \omega_z) = \omega_0(y) + \nu \frac{\partial \omega}{\partial y} \hat{z}$
 let $\omega(y) = A e^{-jy/\delta^2}$: $\omega' = -2y A e^{-jy/\delta^2}$
 $\omega'' = 4y^2 A e^{-jy/\delta^2}$:
 $(A-1) A e^{-jy/\delta^2} + 2y A e^{-jy/\delta^2} - C e^{-jy/\delta^2}$
 2eii/ $\omega(y) = A e^{-jy/\delta^2}$: $\omega(y) = A e^{-jy/\delta^2}$
 $\omega = (\omega_x, \omega_y, \omega_z) = \omega(y) \hat{z} = A e^{-jy/\delta^2} \hat{z}$
 $\omega|_{y=0} = \omega_0 = \omega(0) \hat{z} = A e^{-0/\delta^2} = A e^0 = A = 0 \times$
 $\omega(y) = A e^{-jy/\delta^2}$
 2eiii/ $\omega(y) = A e^{-jy/\delta^2}$:
 $-\frac{\partial U(y)}{\partial y} = \omega(y) = A e^{-jy/\delta^2}$
 $+U(y) = - \int_0^y A e^{-S/\delta^2} dS + C_1$
 $U(0) = U(y=0) = - \int_0^0 A e^{-S/\delta^2} dS + C_1 = 0 = C_1$
 $U(y) = - \int_0^y A e^{-S/\delta^2} dS = -A \int_0^y e^{-(S/\delta)^2} d(S/\delta) = -A e \operatorname{erf}(y/\delta) \frac{1}{4} \pi^{1/2} =$
 $\pi^{1/2} A e \operatorname{erf}(y/\delta)$
 3a/ $\frac{\partial \omega}{\partial t} = \nabla \cdot \omega \neq \nabla \times (\omega \times \omega)$
 $\omega = \nabla \times (\psi_k) \therefore \nabla \cdot \omega = \nabla \cdot \nabla \times \psi_k = \nabla \times \nabla \times \psi_k$
 3b/ $\psi = E \operatorname{erf}(y) \therefore \nabla^2 \psi = \frac{\partial^2}{\partial x^2} (E \operatorname{erf}(y)) + \frac{\partial^2}{\partial y^2} (E \operatorname{erf}(y)) = 0 + E \operatorname{erf}'' = E \operatorname{erf}'' = \frac{\partial}{\partial t} (\nabla^2 \psi) = \frac{\partial}{\partial t} (E \operatorname{erf}''(y)) = 0$
 $\frac{\partial \psi}{\partial x} = E \operatorname{erf}(y), \frac{\partial^2 \psi}{\partial x^2} = \frac{\partial}{\partial x} (E \operatorname{erf}''(y)) = E \operatorname{erf}'''$
 $\frac{\partial^2 \psi}{\partial x^2} (\nabla^2 \psi) = E \operatorname{erf}''' = E^2 \times 55'''$
 $\nabla^2 (\nabla^2 \psi) \nabla^2 (E \operatorname{erf}''') = \frac{\partial^2}{\partial y^2} (E \operatorname{erf}''') = \nabla^2 E \operatorname{erf}'''$

$\nabla \rho_{2022} / \frac{\partial^4}{\partial y^4} = \frac{\partial}{\partial y} (E \times S(y)) = E \times S'$, $\frac{\partial}{\partial n} (\nabla^2 \psi) = \frac{\partial}{\partial n} [E \times S''] = E S'''$;
 $\nabla E \times S'''' + E \times S' E S'' = \nabla E \times S'''' - E^2 S S''' + E^2 \times S' S'' =$
 $\nabla E S'''' = E^2 S' S'' - E^2 S S'''$;
 $\nabla S'''' = E S' S'' - S S'''$;
 $\frac{\partial}{\partial E} S'''' = S' S'' - S S'''$;
 $(S'^2 - S S'')' = 2 S' S'' - S' S'' - S S'''$;
 $+ \frac{\partial}{\partial E} S'''' = + S' S'' - S S''' = 2 S' S'' - S' S'' - S S''' = (2 S' S'') - (S' S'' + S S'') =$
 $((S')^2)' - (S S'')' = ((S')^2 - S S'')' = (S'^2 - S S'')' = \frac{\partial}{\partial E} S'''' = C S''''$;
 $C = \frac{\partial}{\partial E}$

3ci) no slip BC $\therefore u(y=0) = 0$;
 $u = \nabla \times (\psi \mathbf{B})$, $\psi = E \times S(y)$;
 $u = \nabla \times (E \times S(y) \mathbf{B}) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & E \times S \end{vmatrix} = \hat{i} \left(\frac{\partial}{\partial y} (E \times S(y)) - 0 \right) - \hat{j} \left(\frac{\partial}{\partial x} (E \times S(y)) - 0 \right) + \hat{k} (0 \cdot 0)$
 $= \hat{i} (E \times S'(y)) - \hat{j} (E S(y)) \stackrel{!}{=} u = (E \pi S'(y), -E S(y), 0)$;
 $\therefore \text{at } y=0: u = u(y=0) = (0, 0, 0)$;
 $E \times S'(y=0) = 0 = S'(y=0)$, $-E S(y=0) = 0 = S(y=0)$
 $u(y \rightarrow \infty) \rightarrow (E \pi, -E y, 0)$;
 $u(y \rightarrow \infty) = (E \pi, -E y, 0) = (E \times S'(y \rightarrow \infty), -E S(y \rightarrow \infty), 0)$;
 $E \times S'(y \rightarrow \infty) \rightarrow E \pi \therefore S'(y \rightarrow \infty) \rightarrow 1$,
 $-E S(y \rightarrow \infty) \rightarrow -E y \therefore S(y \rightarrow \infty) \rightarrow y$

3d) $(S'^2 - S S'')' = C S''''$;
 $\int \int \frac{d}{dy} \left(\left(\frac{dS(y)}{dy} \right)^2 - S(y) \frac{d^2 S(y)}{dy^2} \right) dy = \int C \frac{d^4 S(y)}{dy^4} dy =$
 $e^{\int C dy} \int d \frac{d^3 S(y)}{dy^3} + d = \left(\frac{dS(y)}{dy} \right)^2 - S(y) \frac{d^2 S(y)}{dy^2} =$
 $S'^2 - S S'' = C S'''' + d = S'(y)^2 - S(y) S''(y) = \frac{\partial}{\partial E} S''''(y) + d$;
 $\text{at } y=0: S(y=0) = 0, S'(y=0) = 0 \therefore S'(0)^2 - S(0) S''(0) = \frac{\partial}{\partial E} S''''(0) + d = 0$;
 $0^2 - 0 S''(0) = 0 = \frac{\partial}{\partial E} S''''(0) + d \therefore d = -\frac{\partial}{\partial E} S''''(0) = -C S''''(0)$

$$\sqrt{3e}/[y] = L, \quad c = \frac{y}{E}, \quad E = \text{constant} \quad \therefore [E] = 1 \quad \text{.}$$

$$[c] = \left[\frac{y}{E}\right] = [y] \quad \text{.}$$

$$\left[\frac{\partial u}{\partial t}\right] = [\nu \nabla^2 u] = T^{-1}[u] = [\nu][\nabla^2 u] = T^{-1}LT^{-1}[\nu]L^{-2}[u] = \text{O}$$

$$[\nu]L^{-2}LT^{-1} = [\nu]LT^{-1} = LT^{-2} \quad \text{.}$$

$$[\nu] = L^2T^{-1} \quad \text{.}$$

[y] and [\nu] are independent

$$\sqrt{3e}/[y] = L \quad , 2 \text{ parameters} \quad \text{.}$$

$$[c] = L = \left[\frac{y}{E}\right] = [\nu][E]^{-1} = L^2T^{-1}[E]^{-1} = L \quad \text{.}$$

$$LT^{-1} = [E] \quad \text{.}$$

$$[c] = L, [y] = L \quad \text{.}$$

y independent, c dependent $\therefore n=2, k=1, m=1 \quad \text{.}$

$$\Gamma_1 = \frac{c}{y^\alpha} \quad \therefore \quad \boxed{c} \quad [c] = L = [y]^\alpha = L^\alpha \quad \therefore \quad \alpha = 1 \quad \text{.}$$

$$\Gamma_1 = \frac{c}{y} \quad \therefore$$

$$\Gamma = \underline{\Phi}(\Gamma_1) = \underline{\Phi}\left(\frac{c}{y}\right) \quad \therefore \quad \Gamma = \underline{s} \text{ is quantity of interest} \quad \text{.}$$

$$s = \underline{\Phi}\left(\frac{c}{y}\right) = c^{1/2}g(z) = \underline{\Phi}(cy^{-1}) = \sqrt{c}y^{-1/2} = c^{1/2}y^{-1/2} = \underline{\Phi}g(z) = c^{1/2}\underline{\Phi}(y^{-1/2})$$

$$g(z) = \underline{\Phi}(y^{-1/2}) \quad \therefore \quad z = y^{-1/2}$$

$$\sqrt{3e}/Ns: \rho\left(\frac{\partial u}{\partial t}\right) + \rho(u \cdot \nabla)u = -\nabla p + \rho f + \mu \nabla^2 u \quad \text{.}$$

$$\nabla \cdot u = 0, \quad f = 0 \quad \therefore \quad \rho \frac{\partial u}{\partial t} + \rho u \cdot \nabla u = -\nabla p + \mu \nabla^2 u \quad \text{.}$$

$$\frac{\partial u}{\partial t} + u \cdot \nabla u = -\nabla p + \mu \nabla^2 u, \quad \frac{d}{dt} = D \quad \therefore \quad \underline{u} = \nabla \times \underline{u} \quad \text{.}$$

$$-\nabla \times \nabla p = -O = 0 \quad \text{.}$$

$$\nabla \times \frac{\partial u}{\partial t} = \frac{\partial}{\partial t} \nabla \times u = \frac{d}{dt} \nabla \times (\nabla \times (\nabla \times u)) \quad \text{.}$$

$$\nabla \times (\nabla \times (\nabla \times u)) = \nabla \cdot (\nabla \times (\nabla \times u)) - \nabla \times (\nabla \times (\nabla \times u)) = -\nabla \cdot \nabla \times (\nabla \times (\nabla \times u)) \quad \text{.}$$

$$\nabla \cdot \nabla \times (\nabla \times (\nabla \times u)) = \nabla \cdot (\nabla^2 \nabla \times (\nabla \times u)) = -\nabla \cdot (\nabla \times (\nabla \times (\nabla \times u)))$$

$$= \nabla \times \nabla \times \nabla^2 (\nabla \times u)$$

$$\cancel{\nabla \times} \quad \therefore \quad \frac{\partial u}{\partial t} = -\nabla p + \mu \nabla^2 u, \quad \nabla \cdot u = 0, \quad -\nabla \times \nabla p = -O = 0 \quad \therefore$$

$$\nabla \times \frac{\partial u}{\partial t} = \frac{d}{dt} \nabla \times u \quad \therefore \quad \nabla \times u = \nabla \times \nabla \times (\nabla \times u) \quad \text{.}$$

$$\nabla \nabla \times (\nabla^2 u) = \nabla \nabla \times (\nabla \cdot \nabla u) - \nabla \nabla \times \nabla \times (\nabla \times u) = -\nabla \nabla \times \nabla \times (\nabla \times u)$$

PP202

$$\nabla \times \nabla \times u$$

$$u \cdot \nabla u$$

$$u \cdot \nabla u$$

$$\left(\frac{\partial u}{\partial y} \frac{\partial^2 u}{\partial x^2}\right)$$

$$\nabla^2 u =$$

$$\text{coeffic}$$

$$\frac{\partial}{\partial t}$$

$$\underline{x} = \left(-\frac{\partial^4 u}{\partial x^4}\right)$$

$$\underline{x} \text{ comp}$$

$$\nabla \cdot u$$

$$Ns: \frac{\partial u}{\partial t}$$

$$\frac{df}{dx}$$

$$\therefore u(u)$$

$$\frac{\partial u}{\partial t} =$$

$$\underline{i} \text{ comp}$$

$$2x$$

$$(u(y, t))$$

$$u \frac{\partial u}{\partial x}$$

$$\nabla \nabla^2 u$$

$$\times \text{const}$$

$$\text{PP2022} \quad \nabla \times (\psi \hat{k}) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \psi & \psi & \psi \end{vmatrix} = \hat{i} \left(\frac{\partial \psi}{\partial y} \right) - \hat{j} \left(\frac{\partial \psi}{\partial x} \right) = \underline{u} \quad \therefore$$

$$\nabla \times \nabla \times (\psi \hat{k}) = \nabla \times \left(\hat{i} \frac{\partial \psi}{\partial y} - \hat{j} \frac{\partial \psi}{\partial x} \right) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial^2 \psi}{\partial x^2} & \frac{\partial^2 \psi}{\partial y^2} & \frac{\partial^2 \psi}{\partial z^2} \\ \frac{\partial^2 \psi}{\partial y \partial x} & \frac{\partial^2 \psi}{\partial x \partial y} & 0 \end{vmatrix} = \hat{k} \left(-\frac{\partial^2 \psi}{\partial x^2} - \frac{\partial^2 \psi}{\partial y^2} \right) = -\nabla^2 \psi \hat{k}$$

$$u = (0, 0, \underline{u}) \rightarrow \underline{u} = \left(\frac{\partial \psi}{\partial y}, -\frac{\partial \psi}{\partial x}, 0 \right) \therefore$$

$$\underline{u} \cdot \nabla = \frac{\partial \psi}{\partial y} \frac{\partial}{\partial x} - \frac{\partial \psi}{\partial x} \frac{\partial}{\partial y} \therefore$$

$$\underline{u} \cdot \nabla \underline{u} = \left(\frac{\partial \psi}{\partial y} \frac{\partial}{\partial x} - \frac{\partial \psi}{\partial x} \frac{\partial}{\partial y} \right) \left(\frac{\partial \psi}{\partial y}, -\frac{\partial \psi}{\partial x}, 0 \right) = \\ \left(\frac{\partial \psi}{\partial y} \frac{\partial^2 \psi}{\partial x^2} - \frac{\partial \psi}{\partial x} \frac{\partial^2 \psi}{\partial y^2} \right) \hat{i} + \left(\frac{\partial \psi}{\partial y} \frac{\partial^2 \psi}{\partial x \partial y} + \frac{\partial \psi}{\partial x} \frac{\partial^2 \psi}{\partial x \partial y} \right) \hat{j} \quad \therefore$$

$$\nabla^2 \underline{u} = \nabla^2 \left(\frac{\partial \psi}{\partial y}, -\frac{\partial \psi}{\partial x}, 0 \right) = \nabla^2 \left(\frac{\partial^3 \psi}{\partial x^2 \partial y} + \frac{\partial^3 \psi}{\partial y^3}, -\frac{\partial^3 \psi}{\partial x \partial y^2} - \frac{\partial^3 \psi}{\partial x \partial y^2}, 0 \right) \therefore$$

Coefficients component:

$$\frac{\partial}{\partial x} (\nabla^2 \psi) - \frac{\partial^4 \psi}{\partial x^2 \partial y} + \frac{\partial^4 \psi}{\partial y^2} = \nabla^2 (\nabla^2 \psi)$$

$$\therefore \nabla \times \nabla^2 \underline{u} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial^3 \psi}{\partial x^2 \partial y}, \frac{\partial^3 \psi}{\partial y^3} & -\frac{\partial^3 \psi}{\partial x \partial y^2}, \frac{\partial^3 \psi}{\partial x \partial y^2} & 0 \end{vmatrix} =$$

$$\hat{k} \left(-\frac{\partial^4 \psi}{\partial x^4} - \frac{\partial^4 \psi}{\partial x^2 \partial y^2} - \frac{\partial^4 \psi}{\partial x^2 \partial y^2} - \frac{\partial^4 \psi}{\partial y^4} \right) = \hat{k} (-\nabla^2 \nabla^2 \psi) = \hat{k} \nabla^2 (\nabla^2 \psi) \therefore$$

$$\hat{x} \text{ componente: } \partial_x \nabla^2 \psi - 2x^4 \partial_y \nabla^2 \psi + 2y^4 \partial_x \nabla^2 \psi = \nu \nabla^2 (\nabla^2 \psi)$$

$$\checkmark + \alpha \text{ incompressible} \therefore \nabla \cdot \underline{u} = 0 \quad \nu = \frac{P}{\rho} \quad \therefore$$

$$\text{NS: } \frac{\partial u}{\partial t} + \underline{u} \cdot \nabla \underline{u} = -\frac{\partial P}{\rho} + \nu \nabla^2 \underline{u} \quad \text{neglect gravity} \therefore g = 0 \therefore$$

$$\frac{dP}{dx} = 0 \quad u(y \rightarrow \infty) \rightarrow 0 \quad \therefore u(y \rightarrow \infty, t) \rightarrow 0$$

$\therefore u(u(y, t), -V, 0)$, $-V$ is constant \therefore

$$\frac{\partial u}{\partial t} = \frac{\partial u(y, t)}{\partial t} \hat{i} - \frac{\partial V}{\partial t} \hat{j} = \frac{\partial u(y, t)}{\partial t} \hat{i} - \frac{\partial V}{\partial t} \hat{i} \quad \therefore$$

$$\hat{i} \text{ component of NS: } \frac{\partial P}{\partial x} = 0 = \frac{\partial}{\partial x} \left(\frac{P}{\rho} \right) \therefore$$

$$\text{or } u \cdot \nabla u = (u(y, t) \partial_x - V \partial_y) (u(y, t), -V, 0) =$$

$$(u(y, t) \frac{\partial u(y, t)}{\partial x} - V \frac{\partial u(y, t)}{\partial y}) \hat{i} + (u \partial_x (-V) - V \partial_y (-V)) =$$

$$u \frac{\partial u}{\partial x} - V \frac{\partial u}{\partial y} \hat{i}$$

$$\nu \nabla^2 \underline{u} = \nu (\partial_{xx} + \partial_{yy} + \partial_{zz}) u(y, t) \hat{i} = \nu \partial_{yy} u(y, t) \hat{i} = \nu \frac{\partial^2 u}{\partial y^2} \hat{i} \quad \therefore$$

$$x \text{ component: } \frac{\partial u}{\partial t} - V \frac{\partial u}{\partial y} = \nu \frac{\partial^2 u}{\partial y^2}$$

$$4(b) \quad (u_t u_{yy}) = \operatorname{Re} [U \exp(-\frac{\lambda v y}{\nu} + i \omega t)] = \operatorname{Re} [U e^{-\frac{\lambda v y}{\nu} + i \omega t}] =$$

$$\operatorname{Re} [U e^{-\frac{\lambda v y}{\nu}} e^{i \omega t}] = \operatorname{Re} U e^{-\frac{\lambda v y}{\nu}}$$

$$\therefore \lambda^2 - \lambda - i^2 = \lambda^2 - \lambda - i \frac{\omega n}{\nu^2} \quad \therefore$$

$$\cancel{u_t - \lambda u_y = \nu u_{yy}} \quad \therefore$$

$$u_t = \operatorname{Re} [U \exp(-\frac{\lambda v y}{\nu} + i \omega t)]$$

$$u_y = \operatorname{Re} [U \frac{\lambda v}{\nu} e^{-\frac{\lambda v y}{\nu} + i \omega t}] \quad \therefore u_{yy} = \operatorname{Re} [U \frac{\lambda^2 v^2}{\nu^2} e^{-\frac{\lambda v y}{\nu} + i \omega t}]$$

$$\therefore u_t - \lambda u_y - \nu u_{yy} = 0 \quad \therefore$$

$$\Rightarrow \operatorname{Re} [U \exp(-\frac{\lambda v y}{\nu} + i \omega t)] + U \frac{\lambda v^2}{\nu} e^{-\frac{\lambda v y}{\nu} + i \omega t} + \operatorname{Re} [U \frac{\lambda^2 v^2}{\nu^2} e^{-\frac{\lambda v y}{\nu} + i \omega t}]$$

$$= \operatorname{Re} [U \exp(-\frac{\lambda v y}{\nu} + i \omega t) + U \frac{\lambda v^2}{\nu} e^{-\frac{\lambda v y}{\nu} + i \omega t} - U \frac{\lambda^2 v^2}{\nu^2} e^{-\frac{\lambda v y}{\nu} + i \omega t}] =$$

$$\operatorname{Re} [U (\ln + \frac{\lambda v^2}{\nu} - \frac{\lambda^2 v^2}{\nu^2}) e^{-\frac{\lambda v y}{\nu} + i \omega t}] \quad \therefore$$

$$\lambda^2 - \lambda - i^2 = 0 = \lambda^2 - \lambda - i \frac{\omega n}{\nu^2} \approx 0 = \nu^2 \lambda^2 - \lambda^2 - i \omega n = 0 = -\nu^2 \lambda^2 + \nu^2 \lambda + i \omega n;$$

$$\ln + \frac{\lambda v^2}{\nu} - \frac{\lambda^2 v^2}{\nu^2} = \frac{i \omega n + \nu^2 \lambda - \lambda^2 v^2}{\nu^2} = -\frac{\nu^2 \lambda^2 + \nu^2 \lambda + i \omega n}{\nu^2} = \frac{0}{\nu^2} = 0 \quad \therefore$$

$$\operatorname{Re} [U(0) e^{-\frac{\lambda v y}{\nu} + i \omega t}] = \operatorname{Re}(0) = 0 = 0 \text{ as required.}$$

$$u(y, t) = \operatorname{Re} [U \exp(-\frac{\lambda v y}{\nu} + i \omega t)] \text{ is a soln as } u_t - \lambda u_y - \nu u_{yy} = 0$$

$$4(c) \quad \text{mass flux} M(t) = \int_S \mathbf{u} \cdot \hat{\mathbf{n}} dS = \rho \int_S \mathbf{u} \cdot \hat{\mathbf{n}} dS = \rho \int_S (\hat{\mathbf{n}} \cdot \mathbf{u}) dS.$$

$dS = \hat{n} dS \quad \therefore$

$$\therefore \text{surface is } yz\text{-plane} \quad \therefore \hat{n} = \hat{\mathbf{i}} \quad \therefore$$

$$\therefore \mathbf{u} \cdot \hat{\mathbf{i}} = \mathbf{u} \cdot \hat{\mathbf{i}} = (u(y, t), -v, 0) \cdot (1, 0, 0) = u(y, t) = \operatorname{Re} [U e^{-\frac{\lambda v y}{\nu} + i \omega t}]$$

$$\therefore M(t) = \int_S \operatorname{Re} [U e^{-\frac{\lambda v y}{\nu} + i \omega t}] dS = \int_S \operatorname{Re} \left[\int_0^\infty U e^{-\frac{\lambda v y}{\nu} + i \omega t} dy \right] dS = \quad y > 0$$

$$\operatorname{Re} \left[\int_0^\infty U e^{-\frac{\lambda v y}{\nu} + i \omega t} dy \right] = \operatorname{Re} \left[\int_0^\infty U e^{-\frac{\lambda v y}{\nu} + i \omega t} dy \right]$$

$$\int_0^\infty \operatorname{Re} [U e^{-\frac{\lambda v y}{\nu} + i \omega t}] dy = \int_0^\infty u dy = \int_0^\infty \operatorname{Re} \left[\int_0^\infty U e^{-\frac{\lambda v y}{\nu} + i \omega t} dy \right]$$

$$= \operatorname{Re} \left[\int_0^\infty U e^{i \omega t} \int_0^\infty e^{-\frac{\lambda v y}{\nu}} dy \right] = \operatorname{Re} \left[\int_0^\infty U e^{i \omega t} \left[-\frac{v}{\lambda \nu} e^{-\frac{\lambda v y}{\nu}} \right]^\infty_0 \right] =$$

$$\operatorname{Re} \left[\int_0^\infty U e^{i \omega t} \left[0 + \frac{v}{\lambda \nu} e^0 \right] \right] = \operatorname{Re} \left[\int_0^\infty U e^{i \omega t} \frac{v}{\lambda \nu} \right] = \operatorname{Re} \left[\frac{\mu U}{\lambda \nu} e^{i \omega t} \right] \quad \therefore \mu = \frac{v}{\lambda \nu}$$

\PP2022

$$\checkmark \text{td} \quad \lambda^2 - \lambda - i\varepsilon = 0 \quad \therefore \quad \lambda x_1, \quad \lambda x - i\varepsilon - \varepsilon^2 \quad (\varepsilon \ll 1)$$

$$u(y, t) = \operatorname{Re} [U e^{-\frac{\lambda y}{\nu} + it\varepsilon}] \doteq \operatorname{Re} [U e^{-\frac{\lambda y}{\nu}} e^{it\varepsilon}] \approx$$

1. for small ε :

$$u(y, t) = \operatorname{Re} [U \operatorname{Re} [e^{-\frac{\lambda y}{\nu}} + e^{-\frac{\lambda y}{\nu}(-i\varepsilon - \varepsilon^2)}] e^{it\varepsilon}] =$$

$$\operatorname{Re} \varepsilon = \frac{2n}{\nu^2} \quad \lambda^2 - \lambda - i\varepsilon = 0 \quad \lambda = \lambda - i\frac{2n}{\nu^2}$$

~~so~~ $H\varepsilon / \varepsilon \ll 1 \quad \therefore \varepsilon \text{ is small}$

$$\lambda x_1, \quad \lambda x - i\varepsilon - \varepsilon^2 = -i\frac{2n}{\nu^2} - \left(\frac{2n}{\nu^2}\right)^2 = -i\frac{2n}{\nu^2} - \frac{4n^2}{\nu^4}$$

$$\lambda^2 - \lambda - i\varepsilon = 0 \quad \therefore$$

$$\lambda = \frac{1 \pm \sqrt{1+4(-i\varepsilon)}}{2(1)} = \frac{1}{2} \pm \frac{\sqrt{1+4\varepsilon^2}}{2} = \frac{1}{2} \pm \frac{\sqrt{1+4\frac{n^2}{\nu^2}}}{2}$$

$$\text{when } \nu > 0 : \quad u(y, t) = \operatorname{Re} [U e^{-\frac{\lambda y}{\nu} + it\varepsilon}] = \operatorname{Re} [U e^{it\varepsilon} e^{-\frac{\lambda y}{\nu}}] =$$

$$\operatorname{Re} [U e^{it\varepsilon} e^{-\frac{\lambda y}{\nu}}] = \operatorname{Re} [U e^{-\frac{\lambda y}{\nu}} (\cos nt + i \sin(nt))] =$$

$$U e^{-\frac{\lambda y}{\nu}} \cos nt$$

when $\nu < 0$. $\lambda \propto -i\varepsilon - \varepsilon^2$:

$$u(y, t) = \operatorname{Re} [U e^{-\frac{\lambda y}{\nu}} e^{it\varepsilon}] = \operatorname{Re} [U e^{-\frac{\lambda y}{\nu} (-i\varepsilon - \varepsilon^2)} e^{it\varepsilon}] =$$

$$\operatorname{Re} [U e^{\frac{\lambda y}{\nu} + 2n\varepsilon^2} e^{i(n\varepsilon + \frac{\lambda y}{\nu}\varepsilon)}] = \operatorname{Re} [U e^{\frac{\lambda y}{\nu} + \frac{4n^2\varepsilon^2}{\nu}} e^{i(n\varepsilon + \frac{\lambda y}{\nu}\varepsilon)}] =$$

$$\operatorname{Re} [U e^{\frac{2n^2y}{\nu^3}} e^{i(n\varepsilon + \frac{ny}{\nu})}] = \operatorname{Re} [U e^{\frac{2n^2y}{\nu^3}} (\cos(n\varepsilon + \frac{ny}{\nu}) + i \sin(n\varepsilon + \frac{ny}{\nu}))] =$$

$$U e^{\frac{2n^2y}{\nu^3} \cos(n\varepsilon + \frac{ny}{\nu})} \quad \therefore$$

$$u(y, t) = \begin{cases} U e^{-\frac{\lambda y}{\nu}} \cos(nt), & \text{when } \nu > 0, \\ U e^{\frac{2n^2y}{\nu^3} \cos(nt + \frac{ny}{\nu})}, & \text{when } \nu < 0. \end{cases}$$

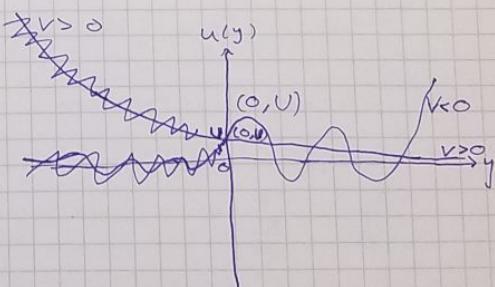
$$\checkmark \quad 4e$$

$$u(y, t=0) = \begin{cases} U e^{-\frac{\lambda y}{\nu}}, \\ U e^{\frac{2n^2y}{\nu^3} \cos(\frac{ny}{\nu})} \end{cases}$$

$$U e^{\frac{2n^2y}{\nu^3} \cos(\frac{ny}{\nu})} = 0 \quad \text{since } \cos(\frac{ny}{\nu}) = 0$$

$$\therefore \frac{ny}{\nu} = k\pi \quad (k \in \mathbb{Z})$$

$$\Rightarrow y = \frac{(2k+1)\pi}{2n} \quad \text{and} \quad \therefore y > 0$$



Var/ equation is $\frac{\partial \rho}{\partial t} + \nabla \cdot (\underline{u} \rho) = \frac{\partial \rho}{\partial t} \rho \nabla \cdot \underline{u} + \underline{u} \cdot \nabla \rho = 0$:

$$\nabla \cdot \underline{u} = 0$$

$$\Rightarrow \vec{O} = \left[\frac{\partial \vec{v}}{\partial t} + \nabla \cdot (\vec{u} \cdot \vec{v}) \right]_i = \frac{\partial \vec{u}}{\partial E} + \nabla_i (\vec{u} \cdot \vec{v}) =$$

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\mathbf{u}_i) \frac{\partial \rho}{\partial x_i} + \partial_i (\mathbf{u}_i \cdot \nabla \rho) = \frac{\partial \rho}{\partial t} + \rho \partial_i u_i + u_i \partial_i \rho =$$

$$\frac{\partial \rho}{\partial t} + \rho (\nabla \cdot \mathbf{u}) + (\mathbf{u} \cdot \nabla \rho);$$

incompressible flows; $\nabla \cdot \mathbf{v} = 0$

$$0 = \left[\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) \right]_i = \left[\frac{\partial \rho}{\partial t} + \mathbf{v} \cdot \nabla \rho \right]_i = \frac{\partial \rho}{\partial t}_i + \mathbf{v}_i \cdot \nabla \rho = 0$$

$$\mathcal{O} = \left[\frac{\partial \mathcal{P}}{\partial t} + \nabla \cdot (\underline{u} \mathcal{P}) \right]_i - \frac{\partial \mathcal{P}}{\partial t} + \mathcal{P} (\nabla \cdot \underline{u})_i + (\underline{u} \cdot \nabla) \mathcal{P}_i =$$

$$[\frac{\partial \nabla \rho}{\partial z} + (\nabla \cdot \nabla) \rho] = -\rho(\nabla \cdot \nabla) = 0$$

$$\partial_i u_i = \frac{\partial u_i}{\partial x^i} = 0$$

$$\nabla b_i / \sqrt{\frac{\partial u}{\partial z} + \mu u - \nabla u} = -\nabla P + \sqrt{\mu + \nabla^2 u} : \quad$$

$$\therefore \left[\rho \frac{\partial u_i}{\partial t} \right]_i = \rho \frac{\partial u_i}{\partial t}$$

$$[\rho \underline{u} - \nabla u]_i = [\rho (\underline{u} \cdot \nabla) \underline{u}]_i = \rho (\underline{u} \cdot \nabla) u_i = \rho (u_j \nabla_j) u_i = \rho u_j \partial_j u_i$$

$$[-\nabla P]_i = -\nabla_i P = -\partial_i P,$$

$$[\rho g]_i = \rho g_i, \quad [\mu \nabla^2 u]_i = \mu \nabla^2 u_i \equiv \mu \nabla_i \nabla_j u_{ij}$$

$$\mu[\nabla_j \nabla_j] u_i = \mu \partial_j \partial_j u_i$$

$$i^{\text{th}} \text{ Component: } \rho \frac{\partial u_i}{\partial t} + \rho u_j \frac{\partial u_i}{\partial x_j} = -\partial_i p + \rho g_i + \mu_d \cdot \delta \cdot u_i$$

$$\nabla \times \underline{u} = \underline{\omega}$$

$$c u_i = [\nabla \times \underline{u}]_i = \varepsilon_{ijk} \nabla_j u_k = \varepsilon_{ijk} \partial_j u_k$$

$$\text{Stream line equations : } \frac{\partial x}{u} = \frac{\partial y}{v} = \frac{\partial z}{w}$$

$$\frac{\frac{dx}{x}}{1+t} = \frac{dy}{y} = \frac{\frac{dz}{z}}{1+t} \Rightarrow \frac{1}{x} dx = \frac{1}{y} dy = \frac{1}{z} dz$$

$$\int \frac{1}{x} dx = \int \frac{1}{y} dy = \int \frac{1}{z} dz = (\ln|x|) = \ln|y| + C_1 \neq \ln|z| + C_2$$

$$|z|c = e^{\ln|z|c} = e^{\ln|y| + c_1} = e^{\ln|y| + c_2} = c_3|\ln|y|| = c_4|\ln|z||;$$

$$x = c_s y = c_s z$$

$$\text{PP2022} / \sqrt{C_{11}} / \frac{dx}{dt} = u, \frac{dy}{dt} = v, \frac{dz}{dt} = w \quad .$$

$$\frac{dx}{dt} = \frac{x}{1+t} \quad \therefore \int \frac{1}{x} dx = \int \frac{1}{1+t} dt = \ln|1+t| = \ln|1+t| + C_1 \quad .$$

$$|x| = e^{\ln|x|} = e^{\ln|1+t| + C_1} = C_2 e^{\ln|1+t|} = C_3 |1+t| \quad .$$

$$x = C_4 (1+t) \quad .$$

$$\text{by symmetry: } y = C_5 (1+t), z = C_6 (1+t) \quad .$$

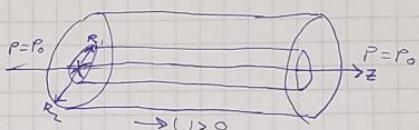
particle paths are $(x, y, z) = (C_4(1+t), C_5(1+t), C_6(1+t))$

$$\text{PP2022} / \text{at } t=0: (x, y, z) = (C_4, C_5, C_6) \doteq (1, 1, 0) \quad .$$

$$(x, y, z) = (1+t, 1+t, 0) \quad .$$

$$\text{at } t=2: (x, y, z) = (3, 3, 0)$$

$$\text{1dii} /$$



$\text{1dii} / \because \text{as no-slip boundary condition}$

slowlow has no special points in x or z .

Slow is independent of x and z .

No Slip BC: . Slow is parallel to movement of boundary .

Slow is only in \hat{z} direction . . SB

$$\therefore u = u \hat{z} \quad u = w \hat{z} \quad .$$

Slow no-slip BC: . Slow at $R=R_2$

does not equal slow at $R=R_1$. . Slow has special points

in R . . Slow depends on R : - $w = w(R)$.

$$u = w \hat{z} = w(R) \hat{z}$$

$\text{1diii} / \text{incompressible} \Rightarrow \nabla \cdot u = 0 \quad .$

$$\nabla \cdot u = \nabla \cdot w(R) \hat{z} = \frac{\partial}{\partial z} w(R) = 0$$

$$\text{1diii} / \therefore \frac{1}{\mu} P_z R = \frac{d}{dR} (R \frac{dw}{dr}) \therefore A + \frac{1}{2\mu} P_z R^2 = R \frac{dw}{dr} \quad .$$

$$\frac{dw}{dr} = \frac{1}{2\mu} P_z R + \frac{A}{R} \quad .$$

$$w = w(R) = \frac{1}{4\mu} P_z R^2 + \ln|R| + B = \frac{1}{4\mu} P_z R^2 + \ln R + B \quad \therefore R \geq 0 \quad .$$

$\text{1dvi} / \text{both ends of cylinder are open to atmosphere with equal pressure } P = P_0 \quad .$ there is no pressure gradient . along any coordinate . along z there is equal pressure everywhere in the cylinder . $\frac{dp}{dz} = 0$

$$\text{M dR} / \frac{1}{\rho} \frac{dp}{dz} R = \frac{d}{dR} \left(R \frac{dw}{dR} \right) : \quad 1992$$

$$A + \frac{1}{2\rho} \frac{dp}{dz} R^2 = R \frac{dw}{dR} : \quad D \frac{dp}{dt} +$$

$$+ \frac{1}{2\rho} \frac{dp}{dz} R + A \frac{1}{R} = \frac{dw}{dR} : \quad - \nabla \cdot$$

$$W = w(R) = \frac{1}{4\rho} \frac{dp}{dz} R^2 + A \ln |R| + B = \frac{1}{4\rho} \frac{dp}{dz} R^2 + A \ln R + B : \quad R \geq 0 \quad D \cdot \omega$$

$$\text{At } R_i : \quad \frac{dp}{dz} = 0 \quad \therefore \quad w = w(R) = A \ln R + B \quad : \quad \omega \propto$$

$$\text{M dR} : \quad w(R=R_2) = U, \quad w(R=R_1) = 0 \quad \therefore \text{no slip} : \quad \omega \propto$$

$$U(R=R_2) = U \hat{\underline{z}}, \quad U(R=R_1) = 0 : \quad \frac{\partial \omega}{\partial t} =$$

$$\text{M dR} : \quad w(R=R_1) = 0 = A \ln(R_1) + B \quad \therefore \quad -A \ln(R_1) = B : \quad \frac{\partial \omega}{\partial z} =$$

$$w(R) = A \ln R - A \ln R_1 = A \ln \left(\frac{R}{R_1} \right) : \quad \frac{\partial \omega}{\partial r} =$$

$$w(R=R_2) = U = A \ln \left(\frac{R_2}{R_1} \right) : \quad A = \frac{U}{\ln \left(\frac{R_2}{R_1} \right)} : \quad w(R) = \frac{U}{\ln \left(\frac{R}{R_1} \right)} \quad : \quad \text{2d}, \quad \omega \propto$$

$$\underline{U} = \frac{U}{\ln \left(\frac{R_2}{R_1} \right)} \ln \left(\frac{R}{R_1} \right) \hat{\underline{z}} \quad \text{2d}$$

M dR iii/ it agrees with my expectations since

the there's no flow at R_1 , then it starts increases to U as $R \rightarrow R_2$

$$\text{2a/ NS} : \quad \frac{\partial u}{\partial t} + u \cdot \nabla u = -\nabla \frac{p}{\rho} + f + \nu \nabla^2 u, \quad f = \frac{dp}{dt}, \quad D = \frac{f}{\nu} \quad \text{2d}$$

constant density & gravity : neglect gravity : $g=0$:

$$2 \underline{u} \times (\nabla \times \underline{u}) = \nabla (u \cdot \underline{u}) - 2 \underline{u} \cdot \nabla u : \quad \text{2d al}$$

$$\underline{u} \cdot \nabla u = \frac{1}{2} \nabla |u|^2 - u \times (\nabla \times u) = \nabla \frac{u^2}{2} - \underline{u} \times \nabla \times u : \quad \omega = \nabla \times \underline{u} : \quad \text{2d}$$

$$\frac{\partial u}{\partial t} + \nabla \frac{u^2}{2} - \underline{u} \times \nabla \times u = \frac{\partial u}{\partial t} + \nabla \frac{u^2}{2} - \underline{u} \times \omega = -\nabla \frac{p}{\rho} + \nu \nabla^2 u : \quad \text{2d}$$

$$\frac{\partial u}{\partial t} = \underline{u} \times \omega - \nabla \left(\frac{p}{\rho} \right) - \nabla \frac{u^2}{2} + \nu \nabla^2 u = \underline{u} \times \omega - \nabla \left(\frac{p}{\rho} + \frac{u^2}{2} \right) + \nu \nabla^2 u : \quad \text{2d}$$

12b/ : steady & kind : $\frac{\partial u}{\partial t} = 0$, incompressible : $D=0$:

$$0 = \underline{u} \times \omega - \nabla \left(\frac{p}{\rho} + \frac{u^2}{2} \right) : \quad \omega =$$

$$\nabla \left(\frac{p}{\rho} + \frac{u^2}{2} \right) = \nabla H = \underline{u} \times \omega : \quad \omega =$$

$$\underline{u} = (u_1, u_2, u_3) : \quad \text{along streamlines} \quad \frac{dx}{u_1} = \frac{dy}{u_2} = \frac{dz}{u_3} : \quad \text{2d}$$

along streamlines $\underline{u} \times \omega = 0$:

$$\nabla(H) = 0 : \quad H = \text{constant} = \frac{p}{\rho} + \frac{u^2}{2}$$

$$12c/ \quad \frac{\partial u}{\partial t} = \underline{u} \times \omega - \nabla \left(\frac{p}{\rho} + \frac{u^2}{2} \right) + \nu \nabla^2 u : \quad \nabla \times \nabla \phi = 0 : \quad \text{2d}$$

$$\text{Taking curls: } \nabla \times \frac{\partial u}{\partial t} = \frac{\partial}{\partial t} \nabla \times \underline{u} = \frac{\partial \omega}{\partial t}, \quad -\nabla \times \nabla \left(\frac{p}{\rho} + \frac{u^2}{2} \right) = 0,$$

$$\nabla \times \nu \nabla \times \nabla^2 u = \nu \nabla \times (\nabla(\nabla \cdot \underline{u})) - \nu \nabla \times (\nabla \times (\nabla \times \underline{u})) : \quad \omega =$$

$$\text{PP2022} / \because \rho = \text{constant} \therefore \frac{D\rho}{Dt} = 0 \therefore$$

$$\frac{Du}{Dt} + \rho \nabla \cdot u = 0 \therefore \nabla \cdot u = 0 \quad \text{!}$$

$$\begin{aligned} \textcircled{1} \quad \nabla \cdot \nabla^2 \omega &= \nabla \cdot (\nabla \times (\nabla \times \omega)) - \nabla \times (\nabla \times \omega) = -\nabla \times (\nabla \times \omega) = \\ &= -\nabla \cdot (\nabla \cdot \omega) + \nabla \cdot \nabla^2 \omega = -\nabla \cdot \omega + \nabla \cdot \omega = 0 \quad \nabla^2 \omega \quad \text{!} \end{aligned}$$

$$\nabla \cdot \omega = \nabla \cdot (\nabla \times u) = 0$$

$$\therefore \text{visc} \nabla \cdot \nabla^2 (\underline{\omega} \times \underline{\omega}) = \underline{\omega} \cdot \nabla \underline{\omega} - \underline{\omega} \cdot \nabla \underline{\omega} + (\underline{\omega} \cdot \nabla) \underline{\omega} - (\underline{\omega} \cdot \nabla) \underline{\omega} = \\ \underline{\omega} \cdot (\underline{\omega}) - \underline{\omega} \cdot (\underline{\omega}) + (\underline{\omega} \cdot \nabla) \underline{\omega} - (\underline{\omega} \cdot \nabla) \underline{\omega} = \underline{\omega} \cdot \nabla \underline{\omega} - \underline{\omega} \cdot \nabla \underline{\omega} \quad \text{!}$$

$$\frac{D\omega}{Dt} = \underline{\omega} \cdot \nabla \underline{u} - \underline{u} \cdot \nabla \underline{\omega} + \nu \nabla^2 \underline{\omega} \quad \text{!}$$

$$\frac{D\omega}{Dt} + \underline{u} \cdot \nabla \underline{\omega} = \frac{D\omega}{Dt} = \underline{\omega} \cdot \nabla \underline{u} + \nu \nabla^2 \underline{\omega} \quad \therefore \frac{D}{Dt} = \frac{\partial}{\partial t} + \underline{u} \cdot \nabla$$

\(2d/\frac{D\omega}{Dt}\) is the material derivative of vorticity \(\underline{\omega}\) :

\(\cancel{\text{visc}} \frac{D\omega}{Dt} \neq 0\) then vorticity changes with time and/or space.
 $\underline{u} \cdot \nabla \underline{\omega}$ is the dot product of vorticity and gradient operator
 operated on the velocity \(\underline{u}

R₂ $\nu \nabla^2 \underline{\omega}$ is the viscosity times the gradient squared of the
 vorticity :

\(\cancel{\text{visc}} \nabla^2 \omega \neq 0\) then \(\omega\) changes with spatial with its rate of change
 or also changing with space

$$(2e) \quad \therefore \underline{\omega} = \nabla \times \underline{u} = \nabla \times (U \hat{i} + ay \hat{j} + az \hat{k}) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ U \hat{i} + ay \hat{j} + az \hat{k} \end{vmatrix} =$$

$$\hat{i} \left(\frac{\partial(az)}{\partial y} - \frac{\partial(-az)}{\partial y} \right) - \hat{j} \left(\frac{\partial(az)}{\partial x} - \frac{\partial(U \hat{i})}{\partial z} \right) + \hat{k} \left(ax(-ay) - ay(U \hat{i}, t) \right) =$$

$$\hat{i}(0, 0) - \hat{j}(0, 0) + \hat{k}(0 - \frac{\partial U(y, t)}{\partial y}) = \hat{k}$$

$$- \frac{\partial U(y, t)}{\partial y} \hat{k} = (0, 0, - \frac{\partial U(y, t)}{\partial y}) = (0, 0, \omega) \quad \therefore$$

$$\omega = - \frac{\partial U(y, t)}{\partial y}$$

$$\text{Verif} \quad \frac{D\omega}{Dt} = \underline{\omega} \cdot \nabla \underline{u} + \nu \nabla^2 \underline{\omega} = \frac{\partial \omega}{\partial t} + \underline{u} \cdot \nabla \underline{\omega} \quad \text{!}$$

$$\underline{\omega} = (0, 0, \omega(y, t)) \quad \text{!}$$

$$\text{z component only: } \frac{\partial \omega}{\partial t}, \quad \nabla^2 \omega = \frac{\partial^2 \omega}{\partial y^2},$$

$$(u \cdot \nabla) \omega = ((U, -ay, az) \cdot \nabla) \omega = (U \frac{\partial}{\partial x} - ay \frac{\partial}{\partial y} + az \frac{\partial}{\partial z}) \omega(y, t) =$$

$$-ay \frac{\partial \omega}{\partial y}$$

$$\underline{\omega} \cdot \nabla \underline{u} = (\omega(y, t) \frac{\partial}{\partial z}) \underline{u} = \omega \frac{\partial}{\partial z} (U(y, t), -ay, az) = \omega \frac{\partial}{\partial z} (az) \hat{k} = ev \omega \hat{k}$$

$$\therefore z\text{ component: } \frac{\partial \omega}{\partial t} - \alpha y \frac{\partial^2 \omega}{\partial y^2} = \omega \alpha + \nu \frac{\partial^2 \omega}{\partial y^2} \quad \therefore$$

Steady solution: $\therefore \frac{\partial \omega}{\partial t} = 0 \therefore$

$$-\alpha y \frac{\partial^2 \omega}{\partial y^2} = \alpha \omega + \nu \frac{\partial^2 \omega}{\partial y^2} \quad \therefore$$

$$\nu \frac{\partial^2 \omega}{\partial y^2} + \alpha y \frac{\partial^2 \omega}{\partial y^2} + \alpha \omega = 0 \quad \therefore$$

$$\text{let } \omega(y) = A e^{-y^2/\delta^2} \quad \therefore$$

$$\frac{\partial \omega}{\partial y} = -\frac{2y}{\delta^2} A e^{-y^2/\delta^2} \quad \therefore$$

$$\frac{\partial^2 \omega}{\partial y^2} = -\frac{2}{\delta^2} A e^{-y^2/\delta^2} + \frac{4y^2}{\delta^4} A e^{-y^2/\delta^2} \quad \therefore$$

$$\nu \frac{-2y}{\delta^2} + e^{-y^2/\delta^2} + \frac{4y^2}{\delta^4} A e^{-y^2/\delta^2} + \frac{-2y^2}{\delta^2} A e^{-y^2/\delta^2} + \alpha \omega =$$

$$y^2 e^{-y^2/\delta^2} \left(\frac{4\nu}{\delta^4} A - \frac{2}{\delta^2} \right) - \frac{2\nu}{\delta^2} A e^{-y^2/\delta^2} + \alpha \omega = 0 \quad \therefore$$

$$\alpha \omega = A e^{-y^2/\delta^2} \quad \therefore$$

$$\therefore \omega = -\frac{\partial U}{\partial y} = A e^{-y^2/\delta^2} \quad \therefore$$

$$\frac{\partial U}{\partial y} = -A e^{-y^2/\delta^2} \quad \therefore$$

$$U(y) = \int_0^y -A e^{-t^2/\delta^2} dt + C_1 \quad \therefore$$

$$U(0) = 0 = \int_0^0 -A e^{-t^2/\delta^2} dt + C_1 = C_1 \quad \therefore$$

$$U(y) = \int_0^y -A e^{-t^2/\delta^2} dt = -A \int_0^y e^{-(t/\delta)^2} dt = -\frac{A\pi^{1/2}}{2} 2\pi^{-1/2} \int_0^{y/\delta} e^{-(t/\delta)^2} dt$$

$$\therefore \text{let } \frac{t}{\delta} = s \quad \therefore \frac{ds}{dt} = \frac{1}{\delta} \quad \therefore \delta ds = dt \quad \therefore$$

$$t=0 : \frac{0}{\delta} = s=0 \quad , \quad t=y : \frac{y}{\delta} = s \quad \therefore$$

$$U(y) = -\frac{A\pi^{1/2}}{2} 2\pi^{-1/2} \int_0^{y/\delta} e^{-s^2} \delta ds = -\frac{A\pi^{1/2}}{2} \delta 2\pi^{-1/2} \int_0^{y/\delta} e^{-s^2} ds =$$

$$-\frac{A\pi^{1/2}\delta}{2} e^{-s^2} \Big|_0^{y/\delta}$$

$$\sqrt{3\pi} / (\alpha \nu) Y = E \times 8(y) = E \times 8 \quad ; \quad \nabla^2 Y = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) Y \quad \therefore$$

$$\partial_x Y = \partial_x (E \times 8) = E \times 8 \quad ; \quad \partial_{x \times y} Y = \partial_x (E \times 8) = 0, \quad \partial_y Y = \partial_y (E \times 8) = E \times 8' \quad \therefore$$

$$\partial_y (E \times 8') = E \times 8'' \pm \partial_y Y \quad \therefore \quad \nabla^2 Y \neq E \times 8'' \quad \therefore$$

$$\nabla^2 \nabla^2 Y = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) E \times 8'' = E \times 8''' \quad \therefore$$

$$\frac{\partial}{\partial t} \nabla^2 Y = \frac{\partial}{\partial t} E \times 8'' = 0 \quad , \quad \frac{\partial}{\partial y} \nabla^2 Y = \frac{\partial}{\partial y} E \times 8'' = E \times 8''' \quad \therefore$$

$$\frac{\partial Y}{\partial x} \frac{\partial}{\partial y} \nabla^2 Y = E \times 8 E \times 8''' = E^2 \times 8''' \quad , \quad \frac{\partial}{\partial x} \nabla^2 Y = \frac{\partial}{\partial x} E \times 8'' = E \times 8'' \quad \therefore$$

$$\frac{\partial Y}{\partial y} \frac{\partial}{\partial x} (\nabla^2 Y) = E \times 8' E \times 8'' = E^2 \times 8' 8'' \quad \therefore$$

$$\text{PP2022} / \therefore \underline{\underline{u}} = E^2 n \underline{\underline{s}} s'' + E^2 n^3 \underline{\underline{s}}' \underline{\underline{s}}'' \Rightarrow E n \underline{\underline{s}}''' m ..$$

$$\Rightarrow \frac{1}{E} \left[-E \underline{\underline{s}} s'' + E^2 n \underline{\underline{s}}' \underline{\underline{s}}'' \right] = \frac{-\underline{\underline{s}}}{E} \frac{E}{n} [\underline{\underline{s}}' \underline{\underline{s}}'' - \underline{\underline{s}}'''] = \underline{\underline{s}}''' ..$$

$$s's'' - s's''' = \frac{v}{E} s''' \quad \text{as}$$

$$\therefore (s')^2 - s's'' = 2s's'' - s's'' - s's''' = s's'' - s's'''$$

$$(s'^2 - s's'')' = \frac{v}{E} s''' = C s''' \quad \therefore C = \frac{v}{E}$$

$$\text{by c.i. } \underline{\underline{u}} = \nabla \times (\underline{\underline{v}} \times \underline{\underline{s}}) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & v \end{vmatrix} =$$

$$\hat{i} \left(\frac{\partial v}{\partial y} - 0 \right) - \hat{j} \left(\frac{\partial v}{\partial z} - 0 \right) + \hat{k} (0 - 0) = \left(\frac{\partial v}{\partial y}, - \frac{\partial v}{\partial z}, 0 \right) = E x E y \hat{k}$$

$$\left(\frac{\partial}{\partial y} (E n s), - \frac{\partial}{\partial z} (E n s), 0 \right) = (E n s', - E s', 0) ..$$

at $y \rightarrow \infty$: $E n s' \rightarrow E x$, $-E s' \rightarrow -E y$. Solid boundary and no slip condition on stationary \therefore no slued motion: $\underline{\underline{u}} = \underline{\underline{0}}$.

$$\text{at } y = 0: \underline{\underline{u}} = (E n s'(0), -E s'(0), 0) = (0, 0, 0)$$

$$\therefore E n s'(0) = 0, -E s'(0) = 0 ..$$

$$s'(0) = 0, s(0) = 0$$

$$\text{by c.i. as } y \rightarrow \infty: \underline{\underline{u}} = (E n s', -E s', 0) \rightarrow (E n, -E y, 0) ..$$

$$E n s' \rightarrow E x, -E s' \rightarrow -E y ..$$

$$s' \rightarrow 1, s \rightarrow y \text{ as } y \rightarrow \infty$$

$$\text{by d. } (s'^2 - s's'')' = C s''' = \frac{\partial}{\partial y} (s'^2 - s's'') = C \frac{\partial}{\partial y} s''' ..$$

$$s'^2 - s's'' = C s''' + d ..$$

$$\text{at } y=0: s(0) = 0, s'(0) = 0 ..$$

$$\text{solid stationary boundary } \therefore (s'(0))^2 - s(0)s''(0) = C s'''(0) + d =$$

$$0^2 - 0 s''(0) = C s'''(0) + d = 0 \therefore d = C s'''(0) = \frac{v}{E} s'''(0) ..$$

$$\text{by e. } \therefore [y] = L, C = \frac{v}{E} \text{ is constant}$$

$[y]$ and $[c]$ are dependent ..

$$\left[\frac{\partial \underline{\underline{u}}}{\partial t} \right] = L T^{-1} T^{-1} = L T^{-2} = \left[\nabla \nabla^2 \underline{\underline{u}} \right] = [v] [\nabla^2] [\underline{\underline{u}}] = L^{-2} L T^{-1} = L^{-1} T^{-1} ..$$

$$L^{-2} T^{-1} = [v] \quad \therefore [c] = \left[\frac{v}{E} \right] = [v] [E]^{-1} = L = L^2 T^{-1} [E]^{-1} ..$$

$$[E]^{-1} = L L^{-2} T^{-1} = L^{-1} T^{-1} \therefore [E] = L T^{-1} ..$$

$$[c] = \left[\frac{v}{E} \right] = L ..$$

$n=2$, y is independent, c is dependent \therefore

$$\Pi_1 = \frac{c}{y^\alpha} \therefore$$

$\text{Be } [\text{force}] = MLT^{-2} \therefore [E] = MLT^{-2}L = M^2T^{-2} \therefore$

$$[\frac{\text{force}}{M^2T^{-2}}] = LT^{-1}T^{-1} = LT^{-2} = [\nabla^2 u] = [\nabla] L^{-2}LT^{-1} = L^{-1}T^{-1} \therefore$$

$$L^{-1}T^{-1} \therefore c = \frac{v}{E} \therefore [c] = [\nabla] [E]^{-1} = L^2 T^{-1} M^{-1} L^{-2} T^{-2} = M^{-1} T^{-1}$$

$\text{Be } n=2 \therefore y$ is independent, c is dependent \therefore

$$\Pi_1 = \frac{c}{y^\alpha} \therefore [c] = [y]^\alpha = L^\alpha \therefore$$

$$\Pi_2 = \frac{c}{y^\alpha} \therefore$$

$$\Pi = \Phi\left(\frac{c}{y^\alpha}\right) = c^{1/\alpha} g(y) = \Phi(c y^{-\alpha}) \therefore \Phi(x) = \sqrt{x} = x^{1/2} \therefore$$

$$\bar{s} = \bar{\Pi} = \Phi(c y^{-\alpha}) = c^{1/\alpha} (y^{-\alpha})^{1/2} = c^{1/\alpha} y^{-\frac{1}{2}\alpha} = c^{1/\alpha} g(y) \therefore$$

$$g(t) = y^{-\alpha/2}$$

$$s = c^{1/\alpha} g(y) \propto \Pi = \Phi(c y^{-\alpha}) = c^{1/\alpha} y^{-\alpha/2} \therefore$$

$$y = y^{-1/\alpha/2}$$

$\text{4a) incompressible } \therefore \nabla \cdot u = 0 \quad \text{neglect gravity } \therefore g = 0$

$$\frac{\partial P}{\partial x} = 0 \therefore \text{NS: } \frac{\partial u}{\partial t} + u \cdot \nabla u = -\nabla P + \nu \nabla^2 u, \quad \nu = \frac{M}{\rho} \therefore$$

$$\text{x component: } \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} - \frac{\partial P}{\partial x} = 0, \quad \nu \nabla^2 u = \nu \frac{\partial^2 u}{\partial y^2} = \nu \nabla^2 u(l, y)$$
$$\Rightarrow \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) u(y, t)$$

$$(u \cdot \nabla) u = (u, -v) \cdot \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, 0 \right) = \left(u \frac{\partial}{\partial x} - v \frac{\partial}{\partial y} \right) u(y, t) = -v \frac{\partial u}{\partial y} \therefore$$

$$\text{x component of NS: } \frac{\partial u}{\partial t} - v \frac{\partial u}{\partial y} = 0 + \nu \frac{\partial^2 u}{\partial y^2} = \nu \frac{\partial^2 u}{\partial y^2}$$

$$\text{4b) } \therefore u = R \left[U e^{-\frac{\lambda V y}{\nu} + \text{int}} \right] \therefore$$

$$u_t = R \left[U_i n e^{-\frac{\lambda V y}{\nu} + \text{int}} \right] \therefore$$

$$u_y = R \left[-\frac{\lambda V}{\nu} U e^{-\frac{\lambda V y}{\nu} + \text{int}} \right] \therefore u_{yy} = R \left[+ \frac{\lambda V^2 U}{\nu^2} e^{-\frac{\lambda V y}{\nu} + \text{int}} \right] \therefore$$

$$u_t - v u_y - \nu u_{yy} = 0 \therefore R \left[U_i n e^{-\frac{\lambda V y}{\nu} + \text{int}} \right] + R \left[-\frac{\lambda V^2 U}{\nu} e^{-\frac{\lambda V y}{\nu} + \text{int}} \right] + R \left[-\frac{\lambda^2 V^2 U}{\nu^2} e^{-\frac{\lambda V y}{\nu} + \text{int}} \right]$$
$$= R \left[\left(\text{int} + -\frac{\lambda V^2}{\nu} - \frac{\lambda^2 V^2}{\nu^2} \right) U e^{-\frac{\lambda V y}{\nu} + \text{int}} \right] \cancel{+ R} \therefore$$

$$\cancel{\text{int} + -\frac{\lambda V^2}{\nu} - \frac{\lambda^2 V^2}{\nu^2} = 0} \therefore \lambda^2 - \lambda - i\varepsilon = \lambda^2 - \lambda - i - \frac{2n}{\nu^2} = 0 = +\text{int} + \cancel{-\frac{\lambda^2 V^2}{\nu^2}} - \frac{\lambda^2 V^2}{\nu^2} = 0 \therefore$$

$$\text{PP 2022} \quad \therefore u_x - v_{xy} - \nabla u_{yy} = \mathbb{R}[0] \quad (0) \quad u e^{-\frac{\lambda xy}{\nu} + \text{int}} = \mathbb{R}[0] = 0$$

$$\therefore u = \mathbb{R}[u e^{-\frac{\lambda xy}{\nu} + \text{int}}]$$

\bullet $\forall c / \text{mass flux} = M(t) = \rho \int_S \underline{u} \cdot \hat{n} ds = \rho \int_S u \cdot \hat{n} ds$

$\Rightarrow y \in \text{plane} \quad \therefore \hat{n} = \hat{x} = \hat{i}$

$$M(t) = \rho \int_S \iint_S \underline{u} \cdot \hat{i} d\bar{x} dy = \rho \iint_S (u, -v, 0) \cdot (1, 0, 0) dz dy =$$

$$\cancel{\rho \iint_S u dz dy} = \iint_S [\mathbb{R}[u e^{-\frac{\lambda xy}{\nu} + \text{int}}] dz dy = \rho \int_0^\infty \int_0^1 [\mathbb{R}[u e^{-\frac{\lambda xy}{\nu} + \text{int}}]] dy$$

$$= \rho \int_0^\infty [\mathbb{R}[u e^{-\frac{\lambda xy}{\nu} + \text{int}}]] dy = \mathbb{R}\left[\int_0^\infty u e^{-\frac{\lambda xy}{\nu} + \text{int}} dy\right] = \mathbb{R}\left[u \int_0^\infty e^{-\frac{\lambda xy}{\nu} + \text{int}} dy\right]$$

$$= \mathbb{R}\left[u e^{\text{int}} \int_0^\infty e^{-\frac{\lambda xy}{\nu}} dy\right] = \mathbb{R}\left[u e^{\text{int}} \left[-\frac{\nu}{\lambda xy} e^{-\frac{\lambda xy}{\nu}}\right]_0^\infty\right] =$$

$$\mathbb{R}\left[u e^{\text{int}} \left[-\frac{\nu}{\lambda xy} (0-1)\right]\right] = \mathbb{R}\left[u e^{\text{int}} \left(\frac{1}{\lambda xy}\right)\right] = \mathbb{R}\left[\frac{M}{\lambda \nu} e^{\text{int}}\right]$$

$$\text{13a} \quad \nabla \cdot \underline{u} = 0 = \nabla \cdot \nabla \times (\underline{Y} \underline{k}) \quad \text{reflect gravity} \quad \therefore g = 0$$

$$\therefore \text{NS: } \frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} = -\nabla p + \nu \nabla^2 \underline{u}, \quad \nu = \frac{M}{\rho};$$

taking carts: $\nabla \times \frac{\partial \underline{u}}{\partial t} = \frac{\partial}{\partial t} \nabla \times \underline{u} = \frac{\partial}{\partial t} \nabla \times \nabla \times (\underline{Y} \underline{k}) \quad \therefore$

$$\nabla \times \nabla \times (\underline{Y} \underline{k}) = \nabla(\nabla \cdot \underline{Y} \underline{k}) - \nabla^2 \underline{Y} \underline{k} = \nabla \left(\frac{\partial}{\partial z} (\underline{Y}(x, y, z)) \right) - \nabla^2 \underline{Y} \underline{k} = \nabla(0) - \nabla^2 \underline{Y} \underline{k}$$

$$= -\nabla^2 \underline{Y} \underline{k} \quad \therefore$$

$$\nabla \times \frac{\partial \underline{u}}{\partial t} = \frac{\partial}{\partial t} (-\nabla^2 \underline{Y} \underline{k}) = -\frac{\partial}{\partial t} \nabla^2 \underline{Y} \underline{k}$$

$$\therefore \text{taking } \underline{k} \text{ components only: } \nabla \times \nabla^2 \underline{u} = \nabla^2 \nabla \times \underline{u} = \nabla^2 \nabla \times \nabla \times (\underline{Y} \underline{k}) \quad \therefore$$

$$\nabla^2 \left[\nabla(\nabla \cdot \underline{Y} \underline{k}) \right] - \nabla^2 \left[\nabla^2 \underline{Y} \underline{k} \right] = \nabla^2 \left[\nabla \left(\frac{\partial}{\partial z} \underline{Y}(x, y, z) \right) \right] - \nabla^2 \nabla^2 \underline{Y} \underline{k} =$$

$$\nabla^2 \left[\nabla(0) \right] - \nabla^2 \nabla^2 \underline{Y} \underline{k} = -\nabla^2 \nabla^2 \underline{Y} \underline{k}$$

$$-\nabla \cdot \nabla p = 0.$$

$$\underline{u} = \nabla \times (\underline{Y} \underline{k}) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & Y \end{vmatrix} = \left(\frac{\partial Y}{\partial y}, -\frac{\partial Y}{\partial x}, 0 \right);$$

$$(\underline{u} \cdot \nabla) \underline{Y} \underline{k} = \left(\frac{\partial Y}{\partial y} \frac{\partial}{\partial x} \underline{k} - \frac{\partial Y}{\partial x} \frac{\partial}{\partial y} \underline{k} \right)$$

$$\nabla \times \underline{B} = \nabla \times \nabla \times \underline{u} \quad \nabla \times [\underline{u} \cdot \nabla \underline{u}] = \nabla \times [(\underline{u} \cdot \nabla) \underline{u}] = (\underline{u} \cdot \nabla) \nabla \times \underline{u} + \nabla(\underline{u} \cdot \nabla) \times \underline{u}$$

$$\therefore (\underline{u} \cdot \nabla) \underline{u} = \left(\frac{\partial Y}{\partial y} \frac{\partial}{\partial x} - \frac{\partial Y}{\partial x} \frac{\partial}{\partial y} \right) \left(\frac{\partial Y}{\partial y}, -\frac{\partial Y}{\partial x}, 0 \right) \underline{u}$$

$$\therefore \nabla \times (\underline{u} \cdot \nabla) \underline{u} =$$

$$\nabla \times [u \cdot \nabla u] = \nabla \times [\nabla \times (\psi \mathbf{k}) \cdot \nabla (u)] = \nabla \times [\nabla \times (\psi \mathbf{k}) \cdot \nabla (\nabla \times (\psi \mathbf{k}))]$$

$$u \cdot \nabla u = \nabla \times (\psi \mathbf{k}) \cdot \nabla \nabla \times (\psi \mathbf{k}) = \left(\frac{\partial u}{\partial y}, -\frac{\partial u}{\partial x}, 0 \right) \cdot \nabla \nabla \times (\psi \mathbf{k}) =$$

$$\left(\frac{\partial u}{\partial y} \frac{\partial}{\partial x} - \frac{\partial u}{\partial x} \frac{\partial}{\partial y} \right) \nabla \times (\psi \mathbf{k}) =$$

$$\left(\frac{\partial u}{\partial y} \frac{\partial}{\partial x} - \frac{\partial u}{\partial x} \frac{\partial}{\partial y} \right) \left(\frac{\partial \psi}{\partial y}, -\frac{\partial \psi}{\partial x}, 0 \right) =$$

$$\left(\frac{\partial u}{\partial y} Y_{xy} - Y_x Y_{yy} \right) - \left(-Y_y Y_{xx} + Y_x Y_{xy} \right) =$$

$$[\nabla \times (u \cdot \nabla u)]_{z\text{ component}} =$$

$$\frac{\partial}{\partial x} (-Y_y Y_{xx} + Y_x Y_{xy}) - \frac{\partial}{\partial y} (Y_y Y_{xy} - Y_x Y_{yy}) =$$

~~Y_{xy} P_{xxx}~~

$$-Y_{xy} Y_{xx} - Y_y Y_{xxx} + \underbrace{Y_{xx} Y_{xy} + Y_x Y_{xxy}}_{\sim} + \underbrace{Y_{yy} Y_{xy} + Y_y Y_{yyy}}_{\sim} - Y_{xy} Y_{yy} - Y_x Y_{yyy}$$

$$= -Y_j Y_{xxx} + Y_n Y_{xxy} + Y_y Y_{yyy} - Y_n Y_{yyy} = \frac{\partial u}{\partial x} \frac{\partial}{\partial y} (\nabla^2 \psi) - \frac{\partial u}{\partial y} \frac{\partial}{\partial x} (\nabla^2 \psi)$$

\sim component:

$$-\frac{\partial}{\partial t} (\nabla^2 \psi) + \frac{\partial u}{\partial x} \frac{\partial}{\partial y} (\nabla^2 \psi) - \frac{\partial u}{\partial y} \frac{\partial}{\partial x} (\nabla^2 \psi) = -2 \nabla^2 (\nabla^2 \psi) \quad \therefore$$

$$\frac{\partial}{\partial t} (\nabla^2 \psi) - \frac{\partial u}{\partial x} \frac{\partial}{\partial y} (\nabla^2 \psi) + \frac{\partial u}{\partial y} \frac{\partial}{\partial x} (\nabla^2 \psi) = 2 \nabla^2 (\nabla^2 \psi)$$

$$\text{Sor } \lambda \approx 1: u = R [U e^{-\frac{\lambda^2}{V^2} t} e^{int}] = R [U e^{-\frac{\lambda^2}{V^2} t} [\cos(nt) + i \sin(nt)]] = U e^{-\frac{\lambda^2}{V^2} t} \cos nt$$

$$\text{Sor } \lambda \approx -i\varepsilon - \varepsilon^2: u = R [U e^{-\frac{(i\varepsilon - \varepsilon^2)Vy}{V^2} + int}] =$$

$$R [U e^{\frac{\varepsilon^2 Vy}{V^2} + \frac{\varepsilon Vy}{V^2} i} e^{int}] = R [U e^{\frac{\varepsilon^2 Vy}{V^2}} e^{i(nt + \frac{\varepsilon Vy}{V^2})}] =$$

$$R [U e^{\frac{(nt)^2 Vy}{V^2}} (\cos(nt + \frac{\varepsilon Vy}{V^2}) + i \sin(nt + \frac{\varepsilon Vy}{V^2}))] =$$

$$U e^{\frac{(nt)^2 Vy}{V^2}} \cos(nt + \frac{\varepsilon Vy}{V^2}) = U e^{\frac{V^2 n^2 Vy}{V^2}} \cos(nt + \frac{V^2 n^2 Vy}{V^2}) =$$

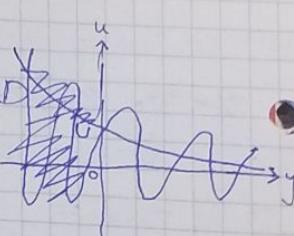
$$U e^{\frac{V^2 n^2 Vy}{V^2}} \cos(nt + \frac{V^2 n^2 Vy}{V^2})$$

$$\therefore \lambda^2 - \lambda - i\varepsilon = n^2 - 1 - i(\frac{V^2 n^2}{V^2}) = \lambda^2 - \lambda - (\frac{V^2 n^2}{V^2})i$$

$$\text{has discriminant: } (-1)^2 - 4(1)(-\frac{V^2 n^2}{V^2}i) = 1 + 4 \frac{V^2 n^2}{V^2} i = D$$

$$D \rightarrow 1 \text{ for large } V > 0, \therefore u(y, t)$$

$$u(y, t) = \begin{cases} U \exp(-\frac{V^2 n^2}{V^2} t) \cos(nt), & V > 0, \\ U \exp(\frac{V^2 n^2}{V^2} t) \cos(nt + \frac{V^2 n^2}{V^2} t), & V < 0. \end{cases}$$



$$\text{PP2020} / \text{1a) N-S: } \rho \left(\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} \right) = \mu^2 \nabla^2 \underline{u} + \nabla P - \underline{g} =$$

$$\nabla P + \nabla \cdot \underline{u} + \mu^2 \nabla^2 \underline{u}$$

$$\text{1a i) } \frac{dP}{dt} + \underline{u} \cdot \nabla \underline{u} = 0 \quad \therefore \quad \frac{dP}{dt} + \underline{u} \cdot \nabla \underline{u} = 0 \quad \therefore$$

$$\text{incompressible} \quad \therefore \quad \frac{dP}{dt} = 0 \quad \therefore \quad \underline{u} \cdot \nabla \underline{u} = 0, \quad \underline{\omega} = \nabla \times \underline{u} \quad \therefore$$

$$\underline{u} \cdot \nabla (\nabla \times \underline{u}) = 0 \quad \therefore \quad \cancel{\underline{\omega} \cdot \nabla \cdot (\nabla \times \underline{u})} = \cancel{\nabla \cdot \underline{u}} + \underline{u} \cdot \nabla \underline{\omega}$$

$$\therefore \nabla \cdot \underline{u} = 0$$

$$\text{1a ii) } \therefore (R, \theta, z), \quad \text{incompressible} \quad \nabla \cdot \underline{u} = 0 \quad \therefore$$

$$\nabla \cdot \underline{u} = \nabla \cdot \left(\frac{1}{R} \hat{R} + R \hat{\theta} \right) = \frac{1}{R} \frac{\partial}{\partial R} \left(R \frac{1}{R} \right) + \frac{1}{R} \frac{\partial}{\partial \theta} (R) = \frac{1}{R} \frac{\partial}{\partial R} (1) + \frac{1}{R} (0) =$$

$$\frac{1}{R} (0) + 0 = 0 \quad \therefore \text{flow is incompressible}$$

$$\text{1b i) irrotational} \quad \therefore \underline{\omega} = 0 \quad \therefore \nabla \times \underline{u} = 0 \quad \therefore$$

$$\nabla \times \left(\frac{1}{R} \hat{R}, R, 0 \right) = \frac{1}{R} \begin{vmatrix} \hat{R} & R \hat{\theta} & \hat{z} \\ \frac{\partial}{\partial R} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ \frac{1}{R} & R & 0 \end{vmatrix} = \frac{1}{R} \begin{vmatrix} \hat{R} & R \hat{\theta} & \hat{z} \\ \frac{\partial}{\partial R} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ \frac{1}{R} & R^2 & 0 \end{vmatrix} =$$

$$\hat{R} \frac{1}{R} \left[\hat{R} \left(\frac{\partial}{\partial \theta} (0) - \frac{\partial}{\partial z} (R^2) \right) - R \hat{\theta} \left(\frac{\partial}{\partial R} (0) - \frac{\partial}{\partial z} \left(\frac{1}{R} \right) \right) + \hat{z} \left(\frac{\partial}{\partial R} (R^2) - \frac{\partial}{\partial \theta} \left(\frac{1}{R} \right) \right) \right] =$$

$$\frac{1}{R} \left[\hat{R} (0 - 0) - R \hat{\theta} (0 - 0) + \hat{z} (2R - 0) \right] = \frac{1}{R} 2R \hat{z} = 2 \hat{z} \neq 0 \quad \therefore$$

flow is not irrotational.

$$\text{1b iii) } (\underline{u} \cdot \nabla) \underline{u}, \quad \nabla = \hat{R} \frac{\partial}{\partial R} + \hat{\theta} \frac{1}{R} \frac{\partial}{\partial \theta} + \hat{z} \frac{\partial}{\partial z} \quad \therefore$$

$$(\underline{u} \cdot \nabla) \underline{u} = \left(\frac{1}{R} \hat{R}, R, 0 \right) \cdot \left(\frac{\partial}{\partial R} \hat{R}, \frac{1}{R} \frac{\partial}{\partial \theta} \hat{\theta}, \frac{\partial}{\partial z} \hat{z} \right)$$

$$= \frac{1}{R} \frac{\partial}{\partial R} \hat{R} + \frac{\partial}{\partial \theta} \hat{\theta}$$

$$(\underline{u} \cdot \nabla) \underline{u} = \left(\frac{1}{R} \frac{\partial}{\partial R} \hat{R} + \frac{\partial}{\partial \theta} \hat{\theta} \right) \left(\frac{1}{R} \hat{R} + R \hat{\theta} \right) =$$

$$\frac{1}{R} \frac{\partial}{\partial R} \left(\frac{1}{R} \hat{R} + R \hat{\theta} \right) + \frac{\partial}{\partial \theta} \left(\frac{1}{R} \hat{R} + R \hat{\theta} \right) =$$

$$\frac{1}{R} \frac{\partial}{\partial R} \left(\frac{1}{R} \hat{R} \right) + \frac{1}{R} \frac{\partial}{\partial R} (R \hat{\theta}) + \frac{\partial}{\partial \theta} \left(\frac{1}{R} \hat{R} \right) + \frac{\partial}{\partial \theta} (R \hat{\theta}) =$$

$$\hat{R} \frac{1}{R} \frac{\partial}{\partial R} (R^{-1}) + \hat{\theta} \frac{1}{R} \frac{\partial}{\partial R} (R) + \hat{R} \frac{\partial}{\partial \theta} \left(\frac{1}{R} \right) + \hat{\theta} \frac{\partial}{\partial \theta} (R) + R \frac{\partial}{\partial \theta} (\hat{\theta}) =$$

$$\hat{R} (-1) \frac{1}{R} R^{-2} + \hat{\theta} \frac{1}{R} + 0 + \hat{R} \hat{\theta} + 0 + R (-1) \hat{R} =$$

$$-R^{-3} \hat{R} - R \hat{\theta} + \left(\frac{1}{R} + \frac{1}{R} \right) \hat{\theta} = \left(-\frac{1}{R^3} - R \right) \hat{R} + \frac{2}{R} \hat{\theta}$$

\therefore

$$\text{1c i) } \begin{array}{l} \text{flow is on solid boundary} \quad \therefore \text{at } y=0: \\ \underline{u}(y, 0) \quad \text{no slip means } \underline{u}(u(y=0), 0) = \underline{u}(0, 0) \\ \therefore \underline{u} = (u(y), 0) \end{array}$$

$y=0$ is a solid boundary \therefore at $y=0$:

$\underline{u}(y, 0)$, no slip means $\underline{u}(u(y=0), 0) = \underline{u}(0, 0)$

$\therefore \underline{u} = (u(y), 0)$

$$\nabla C_{ii} / N-S: \rho \left(\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} \right) = \nabla P - \underline{g} + \mu \nabla^2 \underline{u} .$$

$$\frac{\partial \underline{u}}{\partial t} = 0, \text{ is } \underline{u} \cdot \nabla \underline{u}, \underline{u} \cdot \nabla = u(y) \frac{\partial}{\partial x},$$

$$u(y) \frac{\partial}{\partial x} \cdot (u(y), 0) = u(y) \frac{\partial}{\partial x} u(y) = 0 \quad \therefore$$

$$0 = \nabla P - \underline{g} + \mu \nabla^2 \underline{u}, \text{ is } \nabla^2 \underline{u} = \frac{\partial^2}{\partial x^2} (u(y)) = 0 :$$

$$\therefore 0 = \frac{\partial P}{\partial x} - g \quad \therefore g = \left(\begin{array}{c} g \sin \theta \\ g \cos \theta \end{array} \right) = \left(\begin{array}{c} \partial P / \partial x \\ \partial P / \partial y \end{array} \right) ,$$

$$\nabla C_{ii} / u_r - g \cos \theta = \frac{dP}{dy} = \frac{d}{dy}(P) .$$

$$\int g \cos \theta dy = P = -g \cos(\theta)y + C \quad \therefore \text{ at } y = h: C =$$

$$P_0 = -g \cos(\theta)h + C \quad \therefore P_0 + g \cos(\theta)h = P_0 + h g \cos \theta = C .$$

$$P = P_0 + h g \cos \theta + -g \cos(\theta)y = P_0 + (h-y)g \cos \theta$$

$$\nabla C_{iv} / \text{let } \frac{d}{dy} \frac{dP}{dy} = -g - g \cos \theta .$$

$$P = -\rho g \cos(\theta)y + C \quad \therefore \text{ at } y = h: P = P_0 = -\rho g \cos(\theta)h + C .$$

$$P_0 + \rho g \cos(\theta)h = C \quad \therefore P = -\rho g \cos(\theta)y + P_0 + \rho g \cos(\theta)h = P_0 + (h-y)\rho g \cos \theta .$$

$$\nabla C_{iv} / \frac{d}{dy} P = -\rho g \cos \theta \quad \therefore \frac{d}{dx} P = \rho g \sin \theta .$$

$$P = \rho g \sin \theta dx = \rho g \sin(\theta)x + C .$$

$$\nabla C_{i} / \frac{D}{Dt} = \frac{\partial}{\partial t} + \underline{u} \cdot \nabla \quad \therefore N-S: \rho \frac{D \underline{u}}{Dt} = \nabla P - \underline{g} + \mu \nabla^2 \underline{u} \quad \therefore$$

$$\nabla \times (\rho \frac{D}{Dt} \underline{u}) = \rho \frac{D}{Dt} (\nabla \times \underline{u}) = \rho \frac{D}{Dt} \underline{\omega} = \nabla \times \nabla P - \nabla \times \underline{g} + \cancel{\mu \nabla \times \nabla^2 \underline{u}}$$

$$\nabla C_{ii-A} / vorticity: \nabla \times \underline{u} = \underline{\omega} \quad \therefore \underline{\omega} = \nabla \times \underline{u} = \nabla \times (0, \alpha R z, 0)$$

$$\frac{1}{R} \begin{vmatrix} \hat{R} & R \hat{z} & \hat{z} \\ \frac{\partial}{\partial R} & \frac{\partial}{\partial z} & \frac{\partial}{\partial z} \\ 0 & \alpha R z & 0 \end{vmatrix} = \frac{1}{R} \left[\hat{R} (\frac{\partial}{\partial z} 0) - \hat{z} (\alpha R^2 z) \right] - R \hat{z} \left[\frac{\partial}{\partial R} (0) - \frac{\partial}{\partial z} (0) \right] + \hat{z} \left[\frac{\partial}{\partial R} (\alpha R^2 z) \right]$$

$$= \frac{1}{R} \left[\hat{R} (-\alpha R^2 z) + \hat{z} (2\alpha R z) \right] = -\alpha R \hat{R} + 2\alpha z \hat{z} \quad \therefore$$

$$\nabla \cdot \underline{\omega} = \nabla \cdot (-\alpha R \hat{R} + 2\alpha z \hat{z}) = \frac{1}{R} \frac{\partial}{\partial R} (R(-\alpha R)) + \frac{\partial}{\partial z} (2\alpha z) = \frac{1}{R} \frac{\partial}{\partial R} (-\alpha R^2) + \frac{\partial (2\alpha z)}{\partial z}$$

$$= -\frac{2\alpha R}{R} + 2\alpha = -2\alpha + 2\alpha = 0$$

$$\nabla C_{ii-B} / \frac{dR}{R} = \frac{d\theta}{\theta} + \frac{dz}{z}$$

$$\text{PP2020} / \nabla \cdot \underline{u} = \nabla \times (\underline{\psi}) \quad \therefore$$

$$\underline{\omega} = \nabla \times \underline{u} = \nabla \times \nabla \times (\underline{\psi}) = \nabla(\nabla \cdot \underline{\psi}) - \nabla^2 \underline{\psi}$$

$$\text{D) } \begin{cases} x' = \frac{x}{r}, & t' = \frac{t}{r}, \\ \frac{dx'}{dt} = \end{cases} \quad u' = \frac{u}{r} \quad \therefore$$

\ 2ci) $\nabla \cdot \underline{u} = 0$ is incompressible easily seen \therefore

$$\nabla \cdot \underline{u} = \nabla \cdot \nabla \times \left(\frac{\underline{\psi}}{r \sin \theta} \right) \text{ and } \nabla \cdot (\nabla \times \underline{\psi}) \equiv 0 \quad \therefore \text{ easily see}$$

$$\underline{u} = (u, v, w) \quad \therefore \underline{u} = \nabla \times \left(\frac{\underline{\psi}}{r \sin \theta} \right) = \frac{1}{r \sin \theta} \begin{vmatrix} \hat{e}_r & \hat{e}_{\theta} & \hat{e}_{\phi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ 0 & 0 & \underline{\psi} \end{vmatrix} =$$

$$\frac{1}{r^2 \sin \theta} \left[\hat{e}_r \left(\frac{\partial \underline{\psi}}{\partial \theta} - \frac{\partial \underline{\psi}}{\partial \phi} \right) - r \hat{e}_{\theta} \left(\frac{\partial \underline{\psi}}{\partial r} - \frac{\partial \underline{\psi}}{\partial \phi} \right) + r \sin \theta \hat{e}_{\phi} \left(\frac{\partial \underline{\psi}}{\partial r} - \frac{\partial \underline{\psi}}{\partial \theta} \right) \right] =$$

$$\text{D) } \frac{1}{r^2 \sin \theta} \left[\hat{e}_r \left(\frac{\partial \underline{\psi}}{\partial \theta} - r \hat{e}_{\phi} \frac{\partial \underline{\psi}}{\partial r} \right) - r \hat{e}_{\theta} \left(\frac{\partial \underline{\psi}}{\partial r} - r \hat{e}_{\phi} \frac{\partial \underline{\psi}}{\partial \theta} \right) \right] = \frac{1}{r^2 \sin \theta} \hat{e}_r - \frac{1}{r \sin \theta} \hat{e}_{\theta} \quad \therefore$$

$$\text{D) } u = \frac{1}{r^2 \sin \theta} \frac{\partial \underline{\psi}}{\partial \theta}, \quad v = -\frac{1}{r \sin \theta} \frac{\partial \underline{\psi}}{\partial r}$$

$$\text{2ciii) } E^2 = \frac{\partial^2}{\partial r^2} + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \right) \quad \therefore \quad \underline{\psi} = r(r) \sin^2 \theta,$$

$$E^2 \underline{\psi} = E^2 (r(r) \sin^2 \theta) = \frac{\partial^2}{\partial r^2} (r(r) \sin^2 \theta) + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (r(r) \sin^2 \theta) \right) =$$

$$\sin^2 \theta \underline{\psi}''(r) + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (r(r) \sin^2 \theta) \right) =$$

$$\sin^2 \theta \underline{\psi}''(r) + \frac{\sin \theta}{r^2} \underline{\psi}'(r) 2 \frac{\partial}{\partial \theta} (\cos \theta) =$$

$$\sin^2 \theta \underline{\psi}''(r) + \frac{2 \sin \theta}{r^2} \underline{\psi}'(r) (-\sin \theta) = \sin^2 \theta \underline{\psi}''(r) - \frac{2 \sin^2 \theta}{r^2} \underline{\psi}'(r) \quad \therefore$$

$$\text{D) } \underline{\psi}(r) = r^\alpha, \quad \underline{\psi}''(r) = \alpha(\alpha-1)r^{\alpha-2} = \alpha^2 r^{\alpha-2} - \alpha r^{\alpha-2} \quad \therefore$$

$$E^2 \underline{\psi} = E^2 (E^2 \underline{\psi}) = E^2 \left(\sin^2 \theta \underline{\psi}''(r) - 2 \sin^2 \theta \underline{\psi}'(r) \frac{1}{r^2} \right) =$$

$$\frac{\partial^2}{\partial r^2} \left(\sin^2 \theta \underline{\psi}''(r) - 2 \sin^2 \theta \underline{\psi}'(r) \frac{1}{r^2} \right) + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin^2 \theta \underline{\psi}''(r) - 2 \sin^2 \theta \underline{\psi}'(r) \frac{1}{r^2} \right) \right) =$$

$$\sin^2 \theta \underline{\psi}'''(r) - 2 \sin^2 \theta \underline{\psi}''(r) + 6(-2) \sin^2 \theta \underline{\psi}'(r) \frac{1}{r^4} + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin^2 \theta \underline{\psi}''(r) - 2 \sin^2 \theta \underline{\psi}'(r) \frac{1}{r^2} \right) \right) =$$

$$\sin^2 \theta \underline{\psi}^{(4)}(r) - 2 \sin^2 \theta \underline{\psi}''(r) - 12 \sin^2 \theta \underline{\psi}'(r) \frac{1}{r^4} + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} (2 \underline{\psi}'(r) \cos \theta - 48(r) \frac{1}{r^2} \cos \theta) =$$

$$\sin^2 \theta \underline{\psi}^{(4)}(r) - 2 \sin^2 \theta \underline{\psi}''(r) - 12 \sin^2 \theta \underline{\psi}'(r) \frac{1}{r^4} + \frac{\sin \theta}{r^2} 2 \underline{\psi}'(r) (-\sin \theta) - \frac{4 \sin \theta \underline{\psi}'(r)}{r^4} (-\sin \theta) =$$

$$\sin^2 \theta \underline{\psi}^{(4)}(r) - 2 \sin^2 \theta \underline{\psi}''(r) - 12 \frac{1}{r^4} \underline{\psi}'(r) \sin^2 \theta - 2 \frac{2 \sin^2 \theta \underline{\psi}''(r)}{r^4} + \frac{4 \sin^2 \theta \underline{\psi}'(r)}{r^4} = 0 \quad \therefore$$

$$\text{D) } \underline{\psi}^{(4)}(r) - 2 \underline{\psi}''(r) - 12 \frac{1}{r^4} \underline{\psi}'(r) - 2 \frac{\underline{\psi}''(r)}{r^2} + \frac{4 \underline{\psi}'(r)}{r^4} = 0 =$$

$$r^4 \underline{\psi}^{(4)}(r) - 2 \underline{\psi}''(r) \left(r^4 + \frac{1}{r^2} \right) - 12 r^4 \underline{\psi}'(r) - 2 \underline{\psi}''(r) \frac{1}{r^2} + 4 \underline{\psi}'(r) \frac{1}{r^4} = 0$$

$$\underline{\psi}^{(3)}(r) = \alpha^2 (\alpha-2) r^{\alpha-3} - \alpha(\alpha-2) r^{\alpha-3} = \alpha^3 r^{\alpha-3} - 2\alpha^2 r^{\alpha-3} - \alpha^2 r^{\alpha-3} + 2 \alpha r^{\alpha-3}$$

$$\begin{aligned} \text{Q1iv} / \omega &= \nabla \times \underline{u} = \nabla \times \left(\frac{\underline{s}(r) \sin \theta}{r \sin \theta} \hat{\theta} \right) = \nabla \times \left(\frac{s(r) \sin^2 \theta}{r \sin \theta} \hat{\theta} \right) = \\ \nabla \times \left(\frac{1}{r} \sin \theta s(r) \hat{\theta} \right) &= \frac{1}{r^2 \sin \theta} \begin{vmatrix} \hat{r} & r\hat{\theta} & r \sin \theta \hat{\theta} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & 0 \\ 0 & 0 & \sin^2 \theta s(r) \end{vmatrix} = \\ \frac{1}{r^2 \sin \theta} \left[\hat{r} (s(r) \sin^2 \theta - s'(0)) - r \hat{\theta} (s(r) \sin^2 \theta - s'(0)) + r \sin \theta \hat{\theta} (0 - 0) \right] &= \\ \frac{1}{r^2 \sin \theta} \left[\hat{r} s(r) \sin^2 \theta - r \hat{\theta} s(r) \sin^2 \theta \right] &= \end{aligned}$$

$$2 \cos \theta \frac{1}{r^2} s(r) \hat{r} - \sin \theta \frac{1}{r} s'(r) \hat{\theta}$$

$$\text{Q1ai} / \text{NS: } \rho \left(\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} \right) = -\nabla P + \rho \underline{g} + \mu \nabla^2 \underline{u} \quad \therefore \underline{g} = -\nabla P \quad \dots$$

$$\rho \left(\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} \right) = -\nabla P - \rho \nabla P + \mu \nabla^2 \underline{u}$$

$$\text{Q1aii} / \text{equation is: } \frac{D \rho}{Dt} + \rho \nabla \cdot \underline{u} = 0 = \frac{\partial \rho}{\partial t} + \underline{u} \cdot \nabla \rho + \rho \nabla \cdot \underline{u}$$

\therefore for incompressible fluids the material derivative

$$\partial \rho / \partial t = 0 \quad \therefore \quad \partial \rho / \partial t = 0 \quad \therefore \quad \rho \nabla \cdot \underline{u} = 0 = \nabla \cdot \underline{u} = \underline{u}$$

$$\text{Q1bi} / \nabla \cdot \underline{u} = \nabla \cdot \left(\frac{1}{R} \hat{R} + R \hat{\theta} + \theta \hat{z} \right) = \frac{1}{R} \frac{\partial}{\partial R} \left(R \frac{1}{R} \right) + \frac{1}{R} \frac{\partial}{\partial \theta} (R) + \frac{\partial}{\partial z} (\theta) = \\ \frac{1}{R} \frac{\partial}{\partial R} (1) + \frac{1}{R} (0) + 0 = \frac{1}{R} (0) + 0 = 0 = \nabla \cdot \underline{u} \quad \therefore$$

\underline{u} is incompressible

$$\text{Q1bii} / \omega = \nabla \times \underline{u} = \nabla \times \left(\frac{1}{R} \hat{R} + R \hat{\theta} + \theta \hat{z} \right) = \frac{1}{R} \begin{vmatrix} \hat{R} & R \hat{\theta} & \hat{z} \\ \frac{\partial}{\partial R} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ \frac{1}{R} & R & 0 \end{vmatrix} = \\ \frac{1}{R} \left[\hat{R} \left(0 - 0 \right) - R \hat{\theta} \left(0 - 0 \right) + \hat{z} \left(\frac{\partial}{\partial R} (R) - \frac{\partial}{\partial \theta} \left(\frac{1}{R} \right) \right) \right] =$$

$$\frac{1}{R} \left[\hat{z} \left(2R - 0 \right) \right] = \frac{2R}{R} \hat{z} = 2 \hat{z} \neq 0 \quad \therefore \text{ vorticity } \omega \neq 0 \quad \therefore$$

the flow is not irrotational

$$\text{Q1biii} / (\underline{u} \cdot \nabla) \underline{u} = \left(\left(\frac{1}{R} \hat{R} + R \hat{\theta} + \theta \hat{z} \right) \cdot \left(\frac{\hat{R}}{R} \frac{\partial}{\partial R} + \frac{\hat{\theta}}{R} \frac{\partial}{\partial \theta} + \frac{\hat{z}}{R} \frac{\partial}{\partial z} \right) \right) \underline{u} = \\ \left(\frac{1}{R} \frac{\partial}{\partial R} + R \frac{\partial}{\partial \theta} \right) \underline{u} = \left(R \frac{\partial}{\partial R} + R \frac{\partial}{\partial \theta} \right) \left(\frac{1}{R} \hat{R} + R \hat{\theta} \right) = \\ \frac{1}{R} \frac{\partial}{\partial R} \left(R \hat{R} \right) + R \frac{\partial}{\partial R} \left(R \hat{\theta} \right) + R \frac{\partial}{\partial \theta} \left(\frac{1}{R} \hat{R} \right) + R \frac{\partial}{\partial \theta} \left(R \hat{\theta} \right) = \\ \frac{1}{R} (-1) \frac{1}{R^2} \hat{R} + \frac{1}{R} (1) \hat{\theta} + R \frac{1}{R} \hat{\theta} + RR (-\hat{R}) =$$

$$\frac{-1}{R^3} \hat{R} + \frac{1}{R} \hat{\theta} + \hat{\theta} - R^2 \hat{R} = \left(-R^2 - \frac{1}{R^3} \right) \hat{R} + \left(1 - \frac{1}{R} \right) \hat{\theta}$$

$$\text{Q1ci} / \therefore \nabla \cdot \underline{u} = 0 \quad \text{no-slip BC} \quad \therefore y=0 \text{ is solid boundary} \quad \therefore \text{ no special points in } x, \text{ the flow is only in } x\text{-direction}$$

$$\therefore \underline{u} = (u, 0) \quad \text{flow depends on } y \quad \therefore \text{ B.C.s} \quad \underline{u} = (u(y), 0) \quad \therefore$$

$$\text{PP2020} / \frac{\partial \underline{\omega}}{\partial z} - (\underline{\omega} \cdot \nabla) \underline{\omega} + (\underline{u} \cdot \hat{\underline{\omega}}) \underline{\omega} = 2\nabla^2 \underline{\omega} \therefore$$

$$\frac{\partial \underline{\omega}}{\partial z} + \underline{u} \cdot \nabla \underline{\omega} = (\underline{\omega} \cdot \nabla) \underline{\omega} + 2\nabla^2 \underline{\omega} = \frac{\partial \underline{\omega}}{\partial t}$$

$$\begin{vmatrix} \hat{R} & R\hat{z} & \hat{z} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ 0 & R^2 z & 0 \end{vmatrix}$$

$$\text{Vidi A: } \underline{\omega} = \nabla \times \underline{u} = \nabla \times (0\hat{R} + aRz\hat{\theta} + a\hat{z}) =$$

$$= \frac{1}{R} \left[\hat{R} (0 - aR^2) - R\hat{z} (0 - 0) + \hat{z} (2aRz - 0) \right] =$$

$$-aR\hat{R} + 2aRz\hat{z} \therefore$$

$$\nabla \cdot \underline{\omega} = \nabla \cdot (-R\hat{R} + 2aRz\hat{z}) = \frac{1}{R} \frac{\partial}{\partial R} (-R^2 a) + \frac{\partial}{\partial z} (2aRz) = 0$$

$$\text{Vidi A: } \underline{\omega} = \nabla \times \underline{u} = \nabla \times (0\hat{R} + aRz\hat{\theta} + a\hat{z}) = \frac{1}{R} \begin{vmatrix} \hat{R} & R\hat{z} & \hat{z} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ 0 & R^2 z & 0 \end{vmatrix} =$$

$$= \frac{1}{R} \left[\hat{R} (0 - aR^2) - R\hat{z} (0 - 0) + \hat{z} (2aRz) \right] =$$

$$-aR\hat{R} + 2aRz\hat{z} \therefore$$

$$\nabla \cdot \underline{\omega} = \frac{1}{R} \nabla \cdot (-aR\hat{R} + 2aRz\hat{z}) = \frac{1}{R} \frac{\partial}{\partial R} (-aR^2) + \frac{\partial}{\partial z} (2aRz) =$$

$$-\frac{1}{R} 2Ra + 2aRz = 2a - 2a = 0$$

$$\text{Vidi B: } \frac{\partial r}{\partial s} = \omega(r, t) \quad c = \text{constant}$$

$$\therefore \delta(R) = \text{constant} \therefore$$

$$\underline{\omega} = -aR\hat{R} + 2aRz\hat{z} \therefore$$

$$\frac{\partial \underline{\omega}}{\partial z} \therefore \frac{\partial}{\partial z} (\delta \delta(R)) = \frac{\partial}{\partial z} (c) = 0 \Rightarrow \delta(R)$$

$$\text{Vidi C: } \therefore \underline{u} = \nabla \times (\psi \hat{z}) = \frac{1}{R} \begin{vmatrix} \hat{R} & R\hat{z} & \hat{z} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ 0 & 0 & \psi \end{vmatrix} =$$

$$= \frac{1}{R} \left[\hat{R} \left(\frac{\partial \psi}{\partial \theta} \right) - R\hat{z} \left(\frac{\partial \psi}{\partial R} \right) - \hat{z} (0) \right] = \frac{1}{R} \left[\hat{R} \frac{\partial \psi}{\partial \theta} - R\hat{z} \frac{\partial \psi}{\partial R} \right] =$$

$$\hat{R} \frac{1}{R} \frac{\partial \psi}{\partial \theta} - \hat{z} \frac{\partial \psi}{\partial R} = 0\hat{R} + aRz\hat{\theta} \therefore$$

$$\frac{1}{R} \frac{\partial \psi}{\partial \theta} = 0 \therefore \frac{\partial \psi}{\partial \theta} = 0 \therefore \psi = \psi(R, z) \therefore$$

$$+ \frac{\partial \psi}{\partial R} = -aRz \therefore \psi = -\frac{a}{2} R^2 z = \psi(R, z)$$

$$\text{Vidi D: } M = \int_C \underline{u} \cdot d\underline{s}$$

$$\therefore \hat{z} \hat{\theta} \hat{R} \therefore \underline{u} \cdot d\underline{s} = \therefore \hat{R} = \hat{\theta} \therefore \underline{u} \cdot \hat{\theta} = aRz \therefore$$

$$\text{Vidi D: } d\underline{s} = \hat{\theta} dR \therefore M = \int_0^R aRz dR = \left[\frac{1}{2} aR^2 z \right]_{R=0}^R = \frac{1}{2} aR^2 z \therefore$$

action

$$\checkmark 2a) \quad \therefore u \sim U, \quad \frac{d}{dt} \sim \frac{1}{L} \frac{dU}{dt}, \quad \nabla \sim \frac{1}{L}$$

$$\therefore \frac{\partial u}{\partial t} \sim \frac{U}{L} U = \frac{U^2}{L}$$

$$u \cdot \nabla u \sim U \frac{1}{L} U = \frac{U^2}{L} \quad \therefore \frac{\partial u}{\partial t} \sim u \cdot \nabla u \quad \therefore$$

$$\therefore \mu \nabla^2 u \sim \mu \frac{1}{L^2} U = \mu \frac{U}{L} \quad \therefore R$$

$$\frac{\rho(\partial_t u)}{\mu \nabla^2 u} \approx \frac{1}{2} \left(\frac{U^2}{L} \right) = \frac{UL}{2} = Re \quad \therefore$$

For $Re \ll 1$ i.e.

$$\rho(\partial_t u) \sim \rho(u \cdot \nabla u) \ll \mu \nabla^2 u \quad \therefore$$

May neglect $\partial_t u$, $u \cdot \nabla u$ i.e.

$$\rho(\partial_t u) = G = -\nabla P + \mu \nabla^2 u$$

$\checkmark 2b)$ (i) toothpaste is very viscous $\therefore \nu \gg 1$

is very large very viscous fluid slow

(ii) toothpaste at $r \gg L$ honey is at small distance L \therefore very high Re \therefore Reynolds

$$\checkmark 2c) \quad \nabla \times \nabla \equiv 0 \quad \therefore \omega = \nabla \times u = \nabla \times \nabla \times \left(\frac{U}{r \sin \theta} \hat{\theta} \right)$$

$\therefore \nabla \cdot u = \nabla \cdot \nabla \times \left(\frac{U}{r \sin \theta} \hat{\theta} \right) \equiv 0 \quad \therefore$ flow is always incompressible

$$u = \nabla \times \left(\frac{U}{r \sin \theta} \hat{\theta} \right) = \frac{1}{r \sin \theta} \begin{vmatrix} \hat{r} & \hat{\theta} & \hat{z} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ 0 & \frac{U}{r \sin \theta} \hat{\theta} & 0 \end{vmatrix} =$$

$$\frac{1}{r \sin \theta} \left[\hat{r} \left(\frac{\partial U}{\partial \theta} \right) - r \hat{\theta} \left(\frac{\partial U}{\partial r} \right) + r \sin \theta \hat{z} (0) \right] =$$

$$\frac{1}{r \sin \theta} \left[\hat{r} \frac{\partial U}{\partial \theta} - r \hat{\theta} \frac{\partial U}{\partial r} - \hat{z} \right] = \frac{1}{r^2 \sin^2 \theta} \frac{\partial U}{\partial \theta} \hat{r} - \frac{1}{r \sin \theta} \frac{\partial U}{\partial r} \hat{\theta}$$

$$\checkmark 2cii) \quad \therefore u(R \rightarrow \infty) = U \hat{k} \quad \therefore$$

$$u = \frac{1}{r \sin \theta} \frac{\partial U}{\partial \theta} \hat{r} - \frac{1}{r \sin \theta} \frac{\partial U}{\partial r} \hat{\theta} = U \hat{r} + v \hat{\theta} \quad \therefore$$

$$E = xi + yj + zk = r \sin \theta \cos \theta \hat{i} + r \sin \theta \sin \theta \hat{j} + r \cos \theta \hat{k} = r \hat{r}$$

$$\hat{r} = \sin \theta \cos \theta \hat{i} + \sin \theta \sin \theta \hat{j} + \cos \theta \hat{k}$$

$$\hat{\theta} = \cos \theta \cos \theta \hat{i} + \cos \theta \sin \theta \hat{j} - \sin \theta \hat{k} \quad \therefore$$

$$\cos \theta \hat{r} + \sin \theta \hat{k} = \sin \theta \cos \theta$$

$$\sin \theta \cos \theta \cos \theta \hat{i} + \sin \theta \cos \theta \sin \theta \hat{j} + \cos^2 \theta \hat{k} = \sin \theta \cos \theta \cos \theta \hat{i} - \sin \theta \cos \theta \sin \theta \hat{j} + \sin^2 \theta \hat{k}$$

$$= \cos^2 \theta \hat{i} + \sin^2 \theta \hat{k} = \hat{k} \quad \therefore \cos \theta \hat{r} - \sin \theta \hat{\theta} = \hat{r} \quad \therefore \text{as } r \rightarrow \infty :$$

$$u(\hat{r}) = U(\cos \theta \hat{r} - \sin \theta \hat{\theta}) = U \cos \theta \hat{r} - U \sin \theta \hat{\theta} = U \hat{r} + v \hat{r} \quad \therefore$$

$$\text{PP 2020} / \nabla c_{ii} / \text{NS: } \frac{\partial u}{\partial t} + u \cdot \nabla u = -\nabla \frac{p}{\rho} + g + \nu \Delta^2 u, \nu = \frac{\mu}{\rho}$$

$$\nabla \cdot u = 0 \quad \therefore$$

$$\textcircled{1) } u = (u(y), 0) \therefore \frac{\partial u}{\partial t} = (\frac{\partial u}{\partial t} u(y), \frac{\partial u}{\partial t}(0)) = (0, 0) = 0$$

$$u \cdot \nabla = (u(y), 0) \cdot (\partial_x, \partial_y) = \cancel{u(y)} \frac{\partial}{\partial x} \quad \therefore$$

$$u \cdot \nabla u = u(y) \frac{\partial}{\partial x} (u(y), 0) = u(y) \frac{\partial}{\partial x} (u(y)) = u(y)(0) = 0 \quad \therefore$$

$$\nu \Delta^2 u = \nu \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) (u(y), 0) = \nu \frac{\partial^2 u(y)}{\partial y^2} \quad \therefore$$

$$-\nabla \frac{p}{\rho} = \cancel{\rho \frac{\partial p}{\partial t}} - \frac{1}{\rho} \frac{\partial p}{\partial x} \hat{i} + -\frac{1}{\rho} \frac{\partial p}{\partial y} \hat{j} \quad \therefore$$

$$x \text{ component: } 0 = -\frac{1}{\rho} \frac{\partial p}{\partial x} + g \sin \gamma + \nu \frac{\partial^2 u(y)}{\partial y^2}$$

$$y \text{ component: } 0 = -\frac{1}{\rho} \frac{\partial p}{\partial y} - g \cos \gamma$$

$$\textcircled{2) } \nabla c_{ii} \therefore 0 = -\frac{1}{\rho} \frac{\partial p}{\partial y} - g \cos \gamma \quad \therefore$$

$$\frac{1}{\rho} \frac{\partial p}{\partial y} = -g \cos \gamma \quad \therefore \quad \frac{\partial p}{\partial y} = -\rho g \cos \gamma \quad \therefore$$

$$p(y) = -\rho g \cos(\gamma) y + C_1 \quad \therefore$$

$$p(y=h) = P_0 = -\rho g \cos(\gamma) h + C_1 \quad \therefore \quad C_1 = P_0 + \rho g \cos(\gamma) h \quad \therefore$$

$$p(y) = -\rho g \cos(\gamma) y + P_0 + \rho g \cos(\gamma) h = P = P_0 + (h-y)\rho g \cos \gamma$$

$$\textcircled{3) } \nabla c_{ir} \therefore u(y=h) = (\text{constant}, v) \quad \therefore$$

$$p = P_0 + (h-y) \rho g \cos \gamma \quad \therefore \quad \frac{\partial p}{\partial x} = 0 \quad \therefore \quad -\frac{1}{\rho} \frac{\partial p}{\partial x} = 0 \quad \therefore$$

$$0 = g \sin \gamma + \nu \frac{\partial^2 u(y)}{\partial y^2} \quad \therefore$$

$$-\frac{g}{\nu} \sin \gamma = \frac{\partial^2 u(y)}{\partial y^2} \quad \therefore \quad -\frac{g}{\nu} \sin(\gamma) y + C_2 = \frac{\partial^2 u(y)}{\partial y^2} \quad \therefore$$

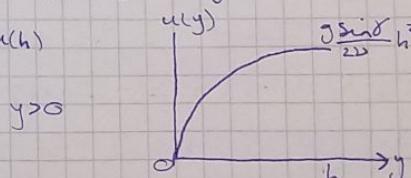
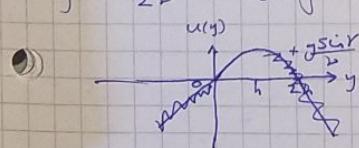
$$-\frac{g}{\nu} \sin(\gamma) h + C_2 = \frac{\partial u(y=h)}{\partial y} = 0 \quad \therefore \quad C_2 = \frac{g}{\nu} \sin(\gamma) h = \frac{gh}{\nu} \sin \gamma \quad \therefore$$

$$\frac{\partial u(y)}{\partial y} = -\frac{g}{\nu} \sin(\gamma) y + \frac{gh}{\nu} \sin \gamma \quad \therefore$$

$$u(y) = -\frac{g}{2\nu} \sin(\gamma) y^2 + \frac{gh}{\nu} \sin(\gamma) y + C_3 \quad \therefore$$

$$\text{At no-slip BC: } u(y=0) = 0 \Rightarrow -\frac{g}{2\nu} \sin(\gamma)(0)^2 + \frac{gh}{\nu} \sin(\gamma)(0) + C_3 = 0 \Rightarrow C_3 = 0 \quad \therefore$$

$$\therefore u(y) = -\frac{g}{2\nu} \sin(\gamma) y^2 + \frac{gh}{\nu} \sin(\gamma) y = \frac{g \sin \gamma}{\nu} \left[-\frac{1}{2} y^2 + h y \right] = \frac{g \sin \gamma}{\nu} \left[\frac{1}{2} h^2 - \frac{1}{2} y^2 + h y \right]$$



$$\nabla \cdot \mathbf{v} / \rho = \int_0^h -\frac{g}{2\rho} \sin(\theta) y^2 + \frac{gh}{2\rho} \sin(\theta) dy =$$

$$-\left[\frac{g}{2\rho} \sin(\theta) y^3 - \frac{gh}{2\rho} \sin(\theta) y^2 \right]_0^h =$$

$$-\frac{g}{2\rho} \sin(\theta) [h^3 - \theta^3] + \frac{gh}{2\rho} \sin(\theta) [h^2 - \theta^2] =$$

$$\frac{-gh^3 \sin \theta}{6\rho} + \frac{gh^3 \sin \theta}{2\rho} = \frac{gh^3 \sin \theta}{3\rho}$$

$$\nabla \cdot \mathbf{v} / \rho = \text{mass flux: } M = \rho \int_S \mathbf{u} \cdot \hat{n} dS = \rho \int_S u \cdot \hat{n} dS \therefore$$

$$\text{so } \hat{n} = \hat{i} \therefore \mathbf{u} \cdot \hat{n} = u \cdot (1, 0) = u(y), \text{ so } (1, 0) = \mathbf{u}(y) \therefore$$

$$M = \rho \int_0^h u(y) dy = \rho \int_0^h u(y) dy = \frac{\rho gh^3 \sin \theta}{3\rho} \therefore$$

$$M_x = \rho \int_0^h u(y) \frac{dy}{2} = \rho \int_0^{2h} u(y) \frac{dy}2 = \int_0^{2h} -\frac{g}{2\rho} \sin(\theta) y^2 + \frac{gh}{2\rho} \sin(\theta) y dy$$

$$= \frac{\rho g \sin \theta}{6\rho} [2h^3] + \frac{\rho gh \sin \theta}{2\rho} [2h^2 - \theta^2] =$$

$$\frac{-\rho g \sin \theta \theta h^3}{6} + \frac{\rho gh \sin(\theta) \theta h^2}{2\rho} = \frac{8\rho g h^3 \sin(\theta)}{3\rho} = \frac{\rho g h^3 \sin \theta}{3\rho} \therefore$$

$\sin \theta = \sin \theta \therefore \sin \theta \text{ is an increasing function} \therefore$

$$\theta < \tau \therefore \theta < \tau < \frac{\pi}{2}$$

which agrees with my expectations: a steeper angle θ would require a higher $y=h$ value for the fluid to not notice there is a slope.

$$\nabla \cdot \mathbf{v} / \frac{D\omega}{Dt} = \frac{\partial \omega}{\partial t} + \mathbf{u} \cdot \nabla \omega \therefore \frac{\partial \omega}{\partial t} + \mathbf{u} \cdot \nabla \omega = \nabla \times \mathbf{v} - \mathbf{v} \cdot \nabla \mathbf{v} + \mathbf{v} \cdot \nabla^2 \mathbf{u}$$

$$\therefore \omega = \frac{m}{\rho} \therefore \nabla \times \frac{\partial \omega}{\partial t} = \nabla \times \omega \therefore \nabla \times \omega = \frac{\partial}{\partial t} \nabla \times \mathbf{u} = \frac{\partial \omega}{\partial t}$$

$$\nabla \times \nabla^2 \mathbf{u} = \nabla \cdot \mathbf{u} = 0 \therefore \nabla \times \nabla^2 \mathbf{u} = \nabla \times (\nabla \times (\nabla \times \mathbf{u})) = (\nabla \times (\nabla \times (\nabla \times \mathbf{u}))) \times \nabla \times \mathbf{u} =$$

$$\nabla \times (\nabla \times (\nabla \times \mathbf{u})) - \nabla \times (\nabla \times (\nabla \times (\nabla \times \mathbf{u}))) = \nabla \times (\nabla \times (\nabla \times \mathbf{u})) + \nabla^2 \omega =$$

$$-\nabla \times (\nabla \cdot \nabla \times \mathbf{u}) + \nabla \nabla^2 \omega = \nabla \times (\nabla \cdot \mathbf{u}) + \nabla \nabla^2 \omega = \nabla \nabla^2 \omega$$

$$-\nabla \times \nabla^2 \mathbf{u} = 0 = 0, \quad -\nabla \times \nabla \mathbf{u} = 0 = 0 \therefore$$

$$\nabla \times \nabla^2 \omega = \therefore \frac{\partial \omega}{\partial t} + \nabla \times (\mathbf{u} \cdot \nabla \omega) = \nabla \nabla^2 \omega \therefore$$

$$2(\mathbf{u} \cdot \nabla) \omega = \nabla \cdot \mathbf{u} = \nabla \cdot (\underline{\mathbf{u}} \cdot \underline{\mathbf{u}}) - \mathbf{u} \times (\nabla \times \mathbf{u}) \therefore \underline{\mathbf{u}} \cdot \nabla \omega = \underline{\mathbf{u}} \cdot \nabla \underline{\mathbf{u}} - \mathbf{u} \times (\nabla \times \mathbf{u})$$

$$\therefore \nabla \times (\underline{\mathbf{u}} \cdot \nabla \underline{\mathbf{u}}) = \nabla \times (\underline{\mathbf{u}} \cdot \underline{\mathbf{u}}) - \nabla \times (\frac{\underline{\mathbf{u}} \cdot \underline{\mathbf{u}}}{2}) = \underline{\mathbf{u}} \cdot \nabla \times (\underline{\mathbf{u}} \times \underline{\mathbf{u}}) =$$

$$-\mathbf{u}(\nabla \cdot \underline{\mathbf{u}}) + \underline{\mathbf{u}}(\nabla \cdot \mathbf{u}) - (\underline{\mathbf{u}} \cdot \nabla) \mathbf{u} + (\mathbf{u} \cdot \nabla) \underline{\mathbf{u}} = -(\underline{\mathbf{u}} \cdot \nabla) \mathbf{u} + (\mathbf{u} \cdot \nabla) \underline{\mathbf{u}} \therefore$$

$$(PP2020) u = U \cos \theta, v = -U \sin \theta = \frac{-1}{r \sin \theta} \frac{\partial \psi}{\partial r},$$

$$U \cos \theta = \frac{1}{r \sin \theta} \frac{\partial \psi}{\partial r},$$

$$\therefore U \sin \theta) r = \frac{\partial \psi}{\partial r}, \therefore \psi = \frac{1}{2} Ur^2 \sin^2 \theta + f(\theta),$$

$$\frac{\partial \psi}{\partial \theta} = Ur^2 \cos \theta \sin \theta = \frac{1}{2} Ur^2 (\Rightarrow \sin \theta \cos \theta + f'(\theta)) = Ur^2 \cos \theta \sin \theta + f'(\theta)$$

$\therefore f'(\theta) = \text{constant}$ \therefore

$f(\theta)$ indep of $\theta \therefore f(\theta) = 0 \therefore$

$$\therefore \psi = \frac{1}{2} Ur^2 \sin^2 \theta \text{ as } r \rightarrow \infty \text{ with } U \rightarrow U \hat{\infty} \text{ as } r \rightarrow \infty$$

$$(2) E^2 \psi = E^2 \psi = \frac{\partial^2 \psi}{\partial r^2} + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial \psi}{\partial \theta} \right) \therefore$$

$$\therefore E^2 \psi = E^2 \psi = E^2 \psi =$$

$$\begin{aligned} (1) E^2 \psi &= \sin^2 \theta \psi'' + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{\sin \theta}{r^2} \frac{\partial \psi}{\partial \theta} \right) = \sin^2 \theta \psi'' + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} (2 \cos \theta \psi) \\ &= \sin^2 \theta \psi'' + \frac{\sin \theta}{r^2} (-2 \sin \theta \psi) = \sin^2 \theta \psi'' - \frac{2 \sin^2 \theta \psi}{r^2} = (\psi'' - \frac{2 \psi}{r^2}) \sin^2 \theta \end{aligned}$$

$$\therefore E^4 \psi = E^2 E^2 \psi = E^2 \left((\psi'' - \frac{2 \psi}{r^2}) \sin^2 \theta \right) \therefore$$

$$\sin^2 \theta \left(\psi'' - \frac{2 \psi}{r^2} \right)$$

$$\frac{\partial^2}{\partial r^2} \left(\psi'' - \frac{2 \psi}{r^2} \right) = \psi''' - 2r^{-2} \psi' + 4r^{-3} \psi$$

$$\therefore \frac{\partial^2}{\partial r^2} \left(\psi'' - \frac{2 \psi}{r^2} \right) = \frac{\partial}{\partial r} \left(\psi''' - 2r^{-2} \psi' + 4r^{-3} \psi \right) = \psi'''' - 2r^{-2} \psi'' + 4r^{-3} \psi' + 4r^{-3} \psi' - 12r^{-4} \psi$$

$$= \psi'''' - 2r^{-2} \psi'' + 8r^{-3} \psi' - 12r^{-4} \psi$$

$$\frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\psi'' - \frac{2 \psi}{r^2} \right) \sin^2 \theta \right) = \frac{\partial}{\partial \theta} \left(\sin \theta \left(\psi'' - \frac{2 \psi}{r^2} \right) \right) = \cos \left(\psi'' - \frac{2 \psi}{r^2} \right)$$

$$\therefore E^4 \psi = E^2 E^2 \psi = E^2 (E^2 \psi) = E^2 \left(\left(\psi'' - \frac{2 \psi}{r^2} \right) \sin^2 \theta \right) \therefore$$

$$\frac{\partial}{\partial \theta} \left(\left(\psi'' - \frac{2 \psi}{r^2} \right) \sin^2 \theta \right) = \left(\psi'' - \frac{2 \psi}{r^2} \right) 2 \sin \theta \cos \theta \therefore$$

$$\frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\left(\psi'' - \frac{2 \psi}{r^2} \right) \sin^2 \theta \right) \right) = \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \left(\psi''' - 2r^{-2} \psi'' + 8r^{-3} \psi' \right) \right) = \frac{\partial}{\partial \theta} \left(2 \left(\psi'' - \frac{2 \psi}{r^2} \right) \cos \theta \right) =$$

$$= -2 \left(\psi'' - \frac{2 \psi}{r^2} \right) \sin \theta = \left(\frac{4 \psi}{r^2} - 2 \psi'' \right) \sin \theta \therefore \sin \theta \left(4r^{-2} \psi'' + 4r^{-3} \psi' - 2r^{-4} \psi \right) \therefore$$

$$E^4 \psi = \psi'''' - 2r^{-2} \psi'' + 8r^{-3} \psi' - 12r^{-4} \psi + 4r^{-2} \psi'' \sin \theta - 2r^{-2} \psi \sin \theta = 0$$

$$\therefore \psi = r^\alpha \therefore \psi' = \alpha r^{\alpha-1}, \psi'' = \alpha(\alpha-1)r^{\alpha-2}, \psi''' = \alpha(\alpha-1)(\alpha-2)r^{\alpha-3}, \psi'''' = \alpha(\alpha-1)(\alpha-2)(\alpha-3)r^{\alpha-4}$$

$$\therefore E^4 \psi = \psi'''' + \psi'' (-2r^{-2} - 2\sin \theta) + \psi' (8r^{-3}) + \psi (-12r^{-4} + 4r^{-2}\sin \theta) =$$

$$\therefore \alpha(\alpha-1)(\alpha-2)(\alpha-3)r^{\alpha-4} + \alpha(\alpha-1)r^{\alpha-2}(-2r^{-2} - 2\sin \theta) + \alpha r^{\alpha-1}8r^{-3} + r^\alpha(-12r^{-4} + 4r^{-2}\sin \theta)$$

$$\begin{aligned}
 \nabla^2 \mathbf{c}_{\text{III}} / E^2 Y &= \frac{\partial^2 Y}{\partial r^2} + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial Y}{\partial \theta} \right) = \\
 \frac{\partial}{\partial r^2} (8 \sin^2 \theta) + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (8 \sin^2 \theta) \right) &= \\
 8'' \sin^2 \theta + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} 28 \sin \theta \cos \theta \right) &= 8'' \sin^2 \theta + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} (28 \cos \theta) = \\
 8'' \sin^2 \theta + \frac{\sin \theta}{r^2} 28 (-\sin \theta) &= 8'' \sin^2 \theta - 2r^2 \sin^2 \theta = \\
 \sin^2 \theta (8'' - 2r^2) &= \sin^2 \theta \left(\frac{d^2}{dr^2} S - 2r^2 S \right) = \\
 \sin^2 \theta \left(\frac{d^2}{dr^2} (r^\alpha) - 2r^2 r^\alpha \right) &= \sin^2 \theta \left(\frac{d}{dr} (r^\alpha \alpha^{-1}) - 2r^2 \right) = \\
 \sin^2 \theta (\alpha(\alpha-1)r^{\alpha-2} - 2r^{\alpha-2}) &= \sin^2 \theta (\alpha(\alpha-1)r^{\alpha-2}) = \\
 E^4 Y = E^2 (E^2 Y) &= E^2 (\sin^2 \theta (\alpha(\alpha-1)r^{\alpha-2})) = \\
 \frac{\partial}{\partial r^2} (\sin^2 \theta (\alpha(\alpha-1)r^{\alpha-2})) + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (\sin^2 \theta (\alpha(\alpha-1)r^{\alpha-2})) \right) &= \\
 \sin^2 \theta (\alpha(\alpha-1)r^{\alpha-2}) \frac{\partial}{\partial r} (r^{\alpha-3}) + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} 2 \sin \theta \cos \theta (\alpha(\alpha-1)r^{\alpha-2}) \right) &= \\
 \sin^2 \theta (\alpha(\alpha-1)r^{\alpha-2})(\alpha-3)r^{\alpha-4} + \frac{\sin \theta}{r^2} (\alpha(\alpha-1)r^{\alpha-2}) 2 \frac{\partial}{\partial \theta} (\cos \theta) r^{\alpha-2} &= \\
 \sin^2 \theta (\alpha(\alpha-1)r^{\alpha-2})(\alpha-2)(\alpha-3)r^{\alpha-4} - r^{\alpha-4} (\alpha(\alpha-1)r^{\alpha-2}) 2 \sin^2 \theta &= \\
 r^{\alpha-4} \sin^2 \theta [(\alpha(\alpha-1)r^{\alpha-2})(\alpha-2)(\alpha-3) - 2(\alpha(\alpha-1)r^{\alpha-2})] &= \\
 r^{\alpha-4} (\alpha(\alpha-1)r^{\alpha-2}) \sin^2 \theta [(\alpha-2)(\alpha-3) - 2] &= 0 \quad \therefore \\
 \alpha(\alpha-1)-2 &= 0 \quad \text{or} \quad (\alpha-2)(\alpha-3)-2 = 0 \quad \therefore \\
 \alpha^2 - \alpha - 2 &= (\alpha+1)(\alpha-2) = 0, \quad \alpha^2 + 6 - 5\alpha - 2 = \alpha^2 - 5\alpha + 4 = (\alpha-1)(\alpha-4) \quad \therefore \\
 \alpha = -1, \alpha = 2, \alpha = 1, \alpha = 4 & \quad \therefore \\
 S = r^\alpha & \quad \therefore
 \end{aligned}$$

General Solution: $S = A r^{-1} + B r^1 + C r^2 + D r^4$

$$\begin{aligned}
 \nabla^2 \mathbf{c}_{\text{IV}} / \omega &= \nabla \times \mathbf{u} = \nabla \times \left(\frac{1}{r^2 \sin \theta} \frac{\partial Y}{\partial \theta} \right) = -\frac{1}{r^2 \sin \theta} \frac{\partial Y}{\partial r} \hat{\theta} + \text{O}(\hat{\phi}) = \\
 \frac{1}{r^2 \sin \theta} \begin{vmatrix} \hat{r} & \hat{\theta} & \hat{\phi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ \frac{1}{r^2 \sin \theta} \frac{\partial Y}{\partial \theta} & -\frac{1}{r^2 \sin \theta} \frac{\partial Y}{\partial r} & 0 \end{vmatrix} &= \\
 \frac{1}{r^2 \sin \theta} \left[\hat{r} \left(\frac{1}{r^2 \sin \theta} \frac{\partial^2 Y}{\partial \theta^2} - \frac{2}{r^2} \left(\frac{1}{\sin \theta} \frac{\partial Y}{\partial \theta} \right) \right) \right] &= \\
 \frac{1}{r^2 \sin \theta} \left[\hat{r} (0-0) - \hat{r} \left(0-0 \right) + r \sin \theta \hat{\theta} \left(-\frac{1}{\sin \theta} \frac{\partial^2 Y}{\partial r^2} - \frac{2}{r^2} \left(r^{-2} (\sin \theta)^{-1} \frac{\partial Y}{\partial r} \right) \right) \right] &= \\
 \frac{1}{r^2 \sin \theta} \left[r \sin \theta \hat{\theta} \left(-\frac{1}{\sin \theta} \frac{\partial^2 Y}{\partial r^2} - r^{-2} (\sin \theta)^{-1} \frac{\partial^2 Y}{\partial \theta^2} - r^{-2} (-1) (\sin \theta)^2 (\cos \theta) \frac{\partial Y}{\partial r} \right) \right] &= \\
 \frac{1}{r} \hat{\theta} \left(-\frac{1}{\sin \theta} \frac{\partial^2 Y}{\partial r^2} - \frac{1}{r^2 \sin \theta} \frac{\partial^2 Y}{\partial \theta^2} + \frac{\cos \theta}{r^2 \sin^2 \theta} \frac{\partial Y}{\partial r} \right) & \quad \therefore
 \end{aligned}$$

$$\begin{aligned}
 Y &= 8 \sin^2 \theta, \quad \frac{\partial Y}{\partial r} = 8 \sin \theta \cos \theta, \quad \frac{\partial^2 Y}{\partial r^2} = 2 \sin \theta \cos \theta + 2 \sin \theta (-1) \sin \theta = \\
 2 \sin^2 \theta - 2 \sin^2 \theta, \quad \frac{\partial Y}{\partial \theta} &= 8 \sin(2\theta), \quad \frac{\partial^2 Y}{\partial \theta^2} = 2 \sin(2\theta),
 \end{aligned}$$

$$\text{PP2020} \quad \frac{\partial u}{\partial r} = S' \sin^2 \theta \quad \therefore \frac{\partial^2 u}{\partial r^2} = S'' \sin^2 \theta \quad .$$

$$S' = \frac{\partial S}{\partial r} = -Ar^{-2} + B + 2Cr + 4Dr^3$$

$$\therefore S'' = 2Ar^{-3} + 2C + 12Dr^2 \quad .$$

$$\frac{\partial^2 u}{\partial r^2} = (2Ar^{-3} + 2C + 12Dr^2) \sin^2 \theta \quad .$$

$$\omega = \left(-\frac{1}{r \sin \theta} \frac{\partial^2 u}{\partial r^2} - \frac{1}{r^3 \sin^2 \theta} \frac{\partial^2 u}{\partial \theta^2} + \frac{\cos \theta}{r^3 \sin^2 \theta} \frac{\partial u}{\partial \theta} \right) \hat{\theta} =$$

$$\underbrace{(2Ar^{-3} + 2C + 12Dr^2) \sin^2 \theta}_{r \sin \theta} -$$

$$\left(-\frac{1}{r \sin \theta} S'' \sin^2 \theta - \frac{1}{r^3 \sin^2 \theta} (2S \cos^2 \theta - 2S \sin^2 \theta) + \frac{\cos \theta}{r^3 \sin^2 \theta} 2S \sin \theta \cos \theta \right) \hat{\theta} =$$

$$\left(-\frac{\sin \theta}{r} S'' - \frac{2 \cos^2 \theta}{r^3 \sin^2 \theta} S + \frac{2 \sin \theta S + 2 \cos^2 \theta S}{r^3 \sin^2 \theta} \right) \hat{\theta} =$$

$$\left(-\frac{\sin \theta}{r} S'' + \frac{2 \sin \theta}{r^3} S \right) \hat{\theta}$$

The strength σ_ω a vortex tube through C is equal to the flux σ_ω vorticity the open surface S that is bounded by the closed curve C

$$\text{flux of vorticity} = \int_S \omega \cdot dS = \int_S \nabla \times u \cdot dS = \int_S (\nabla \times u) \hat{n} dS =$$

$$\int_C \hat{u} \cdot dL = \int_a^b u \cdot \hat{n} dF \int_a^b u \cdot \hat{n} dr = \int_a^b \left(\frac{1}{r^2 \sin \theta} \frac{\partial u}{\partial \theta} \hat{n} - \frac{1}{r \sin \theta} \frac{\partial u}{\partial r} \hat{\theta} \right) (1 \hat{e}_r + 0 \hat{e}_\theta) dr =$$

$$\int_a^b \frac{1}{r^2 \sin \theta} \frac{\partial u}{\partial \theta} dr = \int_a^b \frac{1}{r^2 \sin \theta} 2S \sin \theta \cos \theta dr =$$

~~$$\int_a^b \frac{2 \cos \theta}{r^2} \int_a^b 2r^{-2} \cos \theta (S) dr = \int_a^b 2r^{-2} \cos \theta (Ar^{-1} + Br + Cr^2 + Dr^4) dr =$$~~

$$2 \cos \theta \int_a^b r^{-3} + Br^{-1} + Cr^2 + Dr^4 dr =$$

$$2 \cos \theta \left[\frac{1}{2} r^{-2} + B \ln(r) + Cr + \frac{D}{3} r^3 \right]_a^b =$$

$$2 \cos \theta \left[-\frac{1}{2} \left(\frac{1}{b^2} - \frac{1}{a^2} \right) + B(\ln b - \ln a) + C(b-a) + \frac{D}{3}(b^3 - a^3) \right] =$$

$$2 \cos \theta \left[\frac{1}{2} \left(\frac{1}{a^2} - \frac{1}{b^2} \right) + B \ln \left(\frac{b}{a} \right) + C(b-a) + \frac{D}{3}(b^3 - a^3) \right]$$

$$\therefore u(|x|=\infty, t) = (0, 0, \omega(|x|=\infty, t)) = (0, 0, 0)$$

$$\frac{\partial u}{\partial x} = (0, 0, \frac{\partial \omega}{\partial x}) \quad \therefore \quad \frac{\partial u}{\partial x} (|x|=\infty, t) = (0, 0, \frac{\partial \omega}{\partial x} (|x|=\infty, t)) = (0, 0, 0)$$

$$\text{NS: } \rho \left(\frac{\partial u}{\partial t} + u \cdot \nabla u \right) = -\nabla p + \rho g + \mu \nabla^2 u \quad \therefore \quad \frac{m}{\rho} = \nu \quad \therefore$$

$$\frac{\partial u}{\partial t} = \frac{\partial}{\partial t} (0, 0, \omega) = (0, 0, \frac{\partial \omega}{\partial t}) = \frac{\partial \omega}{\partial t} \hat{k} \quad \therefore$$

$$+\nabla p = -\nabla p = 0 \quad , \quad g = 0 = \rho g \quad \therefore \quad \rho (u \nabla \cdot u + \frac{\partial u}{\partial t}) = \rho \nabla^2 u \quad .$$

$$\nabla^2 u = \nabla^2 (0, 0, \omega(x, t)) = \frac{\partial^2}{\partial x^2} \omega(x, t) = \frac{\partial^2 \omega}{\partial t^2} \hat{k} \quad \therefore$$

$$\underline{u} \cdot \nabla \underline{u} = (\underline{u} \cdot \nabla)(0, 0, \omega) = ((0, 0, \omega) \cdot (\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z})) (0, 0, \omega) =$$

$$\omega \frac{\partial}{\partial z} (0, 0, \omega(x, t)) = (0, 0, \omega \frac{\partial \omega(x, t)}{\partial z}) = (0, 0, 0)$$

$$\frac{\partial \omega}{\partial t} \hat{k} \Rightarrow \frac{\partial^2 \omega}{\partial x^2} \hat{k}$$

∴ taking \hat{k} component of NS: $\frac{\partial \omega}{\partial t} = \nu \frac{\partial^2 \omega}{\partial x^2}$

$$\sqrt{3} b / \frac{dQ}{dt} = \frac{\partial Q}{\partial t} = \int_{-\infty}^{\infty} \omega dx = \int_{-\infty}^{\infty} \frac{\partial \omega}{\partial x} dx = \int_{-\infty}^{\infty} \nu \frac{\partial^2 \omega}{\partial x^2} dx =$$

$$\nu \left[\frac{\partial \omega}{\partial x} \right]_{x=0}^{\infty} = \nu \left[\lim_{x \rightarrow \infty} \frac{\partial \omega}{\partial x} - \lim_{x \rightarrow -\infty} \frac{\partial \omega}{\partial x} \right] = \nu [0 - 0] = \nu (0) = 0$$

$$\sqrt{3c} / [x] = L, [t] = T$$

$$[\frac{d\omega}{dt}] = [\nu \nabla^2 \omega] = T^{-1} L T^{-1} = L T^{-2} = [\nu] L^{-2} L T^{-1} = [L^2 T^{-1}]$$

$$[\nu] = L L T^{-2} T = L^2 T^{-1}$$

∴ $n=3$, x, t independent, ν dependent

$$M_1 = \frac{\nu}{x^{\alpha} t^{\beta}} \therefore [\nu] = [x]^{\alpha} [t]^{\beta} = L^{\alpha} F^{\beta} = L^2 T^{-1} \therefore \alpha=2, \beta=-1$$

$$M_1 = \frac{\nu t}{x^2 t^{-1}} = \frac{\nu t}{x^2} \therefore$$

$$M = \omega' = \phi(\frac{\nu t}{x^2}) \therefore G((\frac{\nu t}{x^2})^{-1/2}) = G((\frac{x^2}{\nu t})^{1/2}) = G(\frac{x}{\sqrt{\nu t}}) = G(4)$$

$$y = \frac{x}{\sqrt{\nu t}}$$

$$\sqrt{3d} / Q = \int_{-\infty}^{\infty} \omega dx, \frac{dQ}{dt} = 0 \therefore Q = \text{constant}$$

$$\omega = \frac{Q}{\sqrt{4\nu t}} F(\frac{x}{\sqrt{4\nu t}}) = \frac{1}{x} Q \frac{x}{\sqrt{4\nu t}} F(\frac{x}{\sqrt{4\nu t}}) = c \omega = \frac{Q}{\sqrt{4\nu t}} F(\frac{x}{\sqrt{4\nu t}})$$

$\omega \rightarrow 0$ as $|x| \rightarrow \infty$, $\frac{\partial \omega}{\partial x} \rightarrow 0$ as $|x| \rightarrow \infty$

$$\frac{\partial \omega}{\partial x} = \frac{Q}{\sqrt{4\nu t}} F'(\frac{x}{\sqrt{4\nu t}}) \frac{1}{\sqrt{4\nu t}} = \frac{Q}{4\nu t} F'(\frac{x}{\sqrt{4\nu t}}) = \frac{Q}{4\nu t} F'(\frac{x}{\sqrt{4\nu t}})$$

$$\therefore \omega = \frac{Q}{\sqrt{4\nu t}} F(\frac{x}{\sqrt{4\nu t}}) \rightarrow 0 \text{ as } |x| \rightarrow \infty$$

$$\therefore \frac{Q}{\sqrt{4\nu t}} F(\frac{x}{\sqrt{4\nu t}}) \rightarrow 0 \text{ as } |x| \rightarrow \infty$$

$$F(\frac{x}{\sqrt{4\nu t}}) \rightarrow 0 \text{ as } |x| \rightarrow \infty \therefore F(\frac{x}{\sqrt{4\nu t}}) \rightarrow 0 \text{ as } |x| \rightarrow \infty$$

$$\frac{\partial \omega}{\partial t} = \frac{Q}{4\nu t} F'(\frac{x}{\sqrt{4\nu t}}) \rightarrow 0 \text{ as } |x| \rightarrow \infty$$

$$F'(\frac{x}{\sqrt{4\nu t}}) \rightarrow 0 \text{ as } |x| \rightarrow \infty$$

$$\sqrt{3e} / (\nu b F(\frac{x}{\sqrt{4\nu t}}) = \pi^{-1/2} e^{-\frac{x^2}{4\nu t}} \approx \pi^{-1/2} e^{-\frac{(x/\sqrt{4\nu t})^2}{4\nu t}} = \pi^{-1/2} e^{-\frac{x^2}{16\nu t}}$$

$$\pi^{-1/2} e^{-\frac{x^2}{4\nu t}} \therefore$$

$$\omega = \frac{Q}{\sqrt{4\nu t}} F(\frac{x}{\sqrt{4\nu t}}) = \frac{Q}{\sqrt{4\nu t}} \pi^{-1/2} e^{-\frac{x^2}{16\nu t}} = \frac{Q}{\sqrt{4\pi\nu t}} e^{-\frac{x^2}{16\nu t}}$$

\PP2020 // e^{-x^2} is a decreasing function.

$$\max_x \omega = \omega|_{x=0} = \frac{Q}{\sqrt{4\pi\nu E}} e^{-\frac{\omega^2}{4\nu E}} = \frac{Q}{\sqrt{4\pi\nu E}} C^0 = \frac{Q}{\sqrt{4\pi\nu} \sqrt{E}} = \frac{Q}{\sqrt{4\pi\nu}} t^{-1/2}$$

$$\because t_2 > t_1 \therefore \frac{1}{t_1} > \frac{1}{t_2} \therefore -\frac{1}{t_2} > -\frac{1}{t_1} \therefore \frac{1}{\sqrt{t_1}} > \frac{1}{\sqrt{t_2}}$$

$$\therefore e^{-\frac{1}{t_2}} > e^{-\frac{1}{t_1}} \therefore \omega|_{t=t_2} > \omega|_{t=t_1}$$

$$\omega|_{x=0} = \frac{Q}{\sqrt{4\pi\nu E}} e^{-\frac{\omega^2}{4\nu E}} = \frac{Q}{\sqrt{4\pi\nu E}} \therefore$$

$$\omega|_{x=0} e^{-1} = \omega|_{x=x_*} = \frac{Q}{\sqrt{4\pi\nu E}} e^{-1} = \frac{Q}{\sqrt{4\pi\nu E}} e^{-\frac{x_*^2}{4\nu E}} \therefore$$

$$e^{-\frac{x_*^2}{4\nu E}} = e^{-1} \therefore -1 = \frac{x_*^2}{4\nu E} \therefore 4\nu E = x_*^2 \therefore$$

$x_* = \sqrt{4\nu E}$ is the distance x must travel for $e^{-\omega|_{x=0}} = \omega|_{x=x_*}$

$$\boxed{38 / E(t) = \int_{-\infty}^{\infty} |U|^2 dx}$$

$$\therefore \frac{dE(t)}{dt} = \frac{d}{dt} \int_{-\infty}^{\infty} |U|^2 dx = \int_{-\infty}^{\infty} \frac{d}{dt} |U|^2 dx = \int_{-\infty}^{\infty} 2 \frac{\partial |U|}{\partial t} \frac{\partial U}{\partial t} dx =$$

$$2 \int_{-\infty}^{\infty} \frac{\partial}{\partial t} |(0, 0, \omega)| \frac{\partial (0, 0, \omega)}{\partial t} dx = 2 \int_{-\infty}^{\infty} |(0, 0, \omega)| \frac{\partial}{\partial t} \omega \frac{\partial \omega}{\partial t} dx =$$

$$2 \int_{-\infty}^{\infty} \omega \frac{\partial}{\partial t} \omega \frac{\partial \omega}{\partial t} dx = 2 \int_{-\infty}^{\infty} \left| \frac{Q}{\sqrt{4\pi\nu E}} e^{-\frac{x^2}{4\nu E}} \right|^2 \frac{\partial \omega}{\partial t} dx =$$

$$2 \int_{-\infty}^{\infty} \frac{Q}{\sqrt{4\pi\nu E}} e^{-\frac{x^2}{4\nu E}} \frac{\partial \omega}{\partial t} dx = 2 \int_{-\infty}^{\infty} \omega \frac{\partial \omega}{\partial t} dx = 2 \int_{-\infty}^{\infty} \omega \nu \frac{\partial^2 \omega}{\partial x^2} dx =$$

$$2\nu \int_{-\infty}^{\infty} \omega \nu \frac{\partial^2 \omega}{\partial x^2} dx = 2\nu \left[\left[\omega \frac{\partial \omega}{\partial x} \right]_{x=-\infty}^{\infty} - \int_{-\infty}^{\infty} \frac{\partial \omega}{\partial x} \frac{\partial \omega}{\partial x} dx \right] =$$

$$2\nu \left(\left[\lim_{x \rightarrow \infty} \omega \frac{\partial \omega}{\partial x} - \lim_{x \rightarrow -\infty} \omega \frac{\partial \omega}{\partial x} \right] - \left[\frac{\partial(\omega)}{\partial x} \omega \right]_{x=-\infty}^{\infty} + \int_{-\infty}^{\infty} \frac{\partial^2 \omega}{\partial x^2} \omega dx \right) =$$

$$2\nu \left(\left[\omega \frac{\partial \omega}{\partial x} \right]_{x=-\infty}^{\infty} - \left[\omega \frac{\partial \omega}{\partial x} \right]_{x=\infty}^{\infty} \right) + 2\nu \int_{-\infty}^{\infty} \omega \frac{\partial^2 \omega}{\partial x^2} dx = 2\nu \int_{-\infty}^{\infty} \omega \nu \frac{\partial^2 \omega}{\partial x^2} dx$$

$$\frac{dE(t)}{dt} = \frac{\partial}{\partial t} \int_{-\infty}^{\infty} |(0, 0, \omega)|^2 dx = \int_{-\infty}^{\infty} \frac{\partial}{\partial t} |(0, 0, \omega)|^2 dx = \int_{-\infty}^{\infty} \frac{\partial}{\partial t} \omega^2 dx =$$

$$2 \int_{-\infty}^{\infty} \omega \frac{\partial \omega}{\partial t} dx = 2 \int_{-\infty}^{\infty} \omega \nu \frac{\partial^2 \omega}{\partial x^2} dx = 2\nu \int_{-\infty}^{\infty} \omega \frac{\partial^2 \omega}{\partial x^2} dx \therefore$$

$$\frac{dE}{dt} \propto t^p \therefore \frac{dE}{dt} = h(x) t^p \text{ where } h \text{ is a function independent of } t \therefore$$

$$\frac{dE}{dt} = h(x) t^{1/2} \therefore dE/h(x) t^p \therefore p = -1/2$$

$$\begin{aligned}
 & (4a) \quad \underline{u} \times (\nabla \times \underline{u}) + \underline{u} \times (\nabla \times \underline{u}) = \nabla(\underline{u} \cdot \underline{u}) - (\underline{u} \cdot \nabla) \underline{u} - (\underline{u} \cdot \nabla) \underline{u} = \\
 & 2\underline{u} \times (\nabla \times \underline{u}) \stackrel{?}{=} \nabla(\underline{u} \cdot \underline{u}) - 2(\underline{u} \cdot \nabla) \underline{u} \quad \therefore \\
 & \underline{u} \times (\nabla \times \underline{u}) = \frac{1}{2} \nabla(\underline{u} \cdot \underline{u}) - (\underline{u} \cdot \nabla) \underline{u} \\
 & \therefore [\underline{u} \times (\nabla \times \underline{u})] \rightarrow [\underline{u} \times (\nabla \times \underline{u})]_i = \epsilon_{ijk} u_j (\nabla \times \underline{u})_k = \epsilon_{ijk} u_j \epsilon_{klm} \partial_l u_m = \\
 & \cancel{\epsilon_{ijk} u_j} \cancel{\epsilon_{klm}} \partial_l u_m \\
 & [\underline{u} \cdot \underline{u}]_i = u_i u_i \\
 & [\frac{1}{2} \nabla(\underline{u} \cdot \underline{u})]_i = \frac{1}{2} \partial_i u_j u_j \\
 & [\underline{u} \cdot \nabla]_i = u_i \partial_i \\
 & [(\underline{u} \cdot \nabla) \underline{u}]_i = u_j \partial_j u_i \\
 & [\underline{u} \times (\nabla \times \underline{u})]_i = \epsilon_{ijk} u_j (\nabla \times \underline{u})_k = \epsilon_{ijk} u_j \epsilon_{lmn} \partial_m u_n = \\
 & \epsilon_{kj} \epsilon_{lmn} u_j \partial_m u_n = (\delta_{jm} \delta_{ln} - \delta_{jn} \delta_{lm}) u_j \partial_m u_n = \\
 & \delta_{jn} \delta_{lm} u_j \partial_m u_n - \delta_{jn} \delta_{lm} u_j \partial_m u_n = \\
 & u_j \partial_j u_i - u_j \partial_i u_j = u_j \frac{\partial u_i}{\partial x^j} - u_j \frac{\partial u_j}{\partial x^i} \\
 & [\frac{1}{2} \nabla(\underline{u} \cdot \underline{u})]_i - [(\underline{u} \cdot \nabla) \underline{u}]_i = \frac{1}{2} \partial_i (\underline{u} \cdot \underline{u}) - (\underline{u} \cdot \nabla) \underline{u}_i = \frac{1}{2} \partial_i (u_j u_j) - (u_j \partial_j) u_i = \\
 & \frac{1}{2} \partial_i (u_j) u_j + \frac{1}{2} u_j \partial_i u_j - u_j \frac{\partial u_i}{\partial x^j} = \cancel{\partial_i u_j} u_j \frac{\partial u_i}{\partial x^j} - u_j \frac{\partial u_i}{\partial x^j} \\
 & \therefore [\underline{u} \times (\nabla \times \underline{u})]_i = \epsilon_{ijk} u_j (\nabla \times \underline{u})_k = \epsilon_{ijk} u_j \epsilon_{lmn} \partial_m u_n = \\
 & \epsilon_{kij} u_j \epsilon_{lmn} \partial_m u_n = \epsilon_{kij} \epsilon_{lmn} u_j \partial_m u_n = \\
 & (\delta_{im} \delta_{jn} - \delta_{in} \delta_{jm}) u_j \partial_m u_n = \delta_{im} \delta_{jn} u_j \partial_m u_n - \delta_{jn} \delta_{im} u_j \partial_m u_n = \\
 & u_j \partial_i u_j - u_j \partial_i u_j = \frac{1}{2} u_j \partial_i u_j + \frac{1}{2} u_j \partial_i u_j - u_j \partial_i u_j = \\
 & \frac{1}{2} (u_j \partial_i u_j + u_j \partial_i u_j) - u_j \partial_j u_i = \\
 & \frac{1}{2} [\nabla(\underline{u} \cdot \underline{u})]_i - [\underline{u} \cdot \nabla \underline{u}]_i = \left[\frac{1}{2} \nabla(\underline{u} \cdot \underline{u}) - \underline{u} \cdot \nabla \underline{u} \right]_i \quad \therefore \\
 & \underline{u} \times (\nabla \times \underline{u}) = \frac{1}{2} \nabla(\underline{u} \cdot \underline{u}) - (\underline{u} \cdot \nabla) \underline{u}
 \end{aligned}$$

(4b) Unidirectional $\therefore D = M = 0$, irrotational $\therefore \nabla \times \underline{u} = \nabla \times \underline{u} = 0$

$$P = \text{constant} \quad \therefore \frac{D \rho}{Dt} = \frac{\partial \rho}{\partial t} + \underline{u} \cdot \nabla \rho = 0 \quad \therefore$$

Incompressible $\therefore \nabla \cdot \underline{u} = 0$

$$\text{red } \therefore \nabla \times \underline{u} = 0 \quad \therefore \underline{u} = \nabla \phi$$

Smooth flow is irrotational $\therefore \omega = \nabla \times \underline{u} = 0 \quad \therefore$

$\nabla \times \nabla \phi = 0 \quad \therefore \text{is } \nabla \phi = \nabla \theta \text{ then } \omega = \nabla \times \nabla \theta = 0 \text{ is always true}$

$$\begin{aligned} & \text{Incompressible } \therefore \nabla \cdot \underline{u} = 0; \quad \nabla^2 \phi = \nabla^2 \theta \quad \cancel{\nabla \cdot \nabla \phi = 0} \\ & \nabla \cdot \underline{u} = \nabla \cdot \nabla \phi = \nabla^2 \phi = 0 \end{aligned}$$

PP2020

$$\text{4b i) } \nabla \cdot \underline{v} = 0 \equiv \nabla^2 \underline{v} + \frac{\partial^2}{\partial t^2} \underline{v} = 0$$

$\therefore |\underline{v}| < \infty \text{ as } y \rightarrow \infty$

$$\underline{v} = \nabla \phi \equiv \underline{v} = \nabla S(y) \sin(kx - \omega t)$$

$$\begin{aligned} \frac{\partial}{\partial x} S(y) \sin(kx - \omega t) \hat{i} + \frac{\partial}{\partial y} S(y) \sin(kx - \omega t) \hat{j} = \\ S(y) k \cos(kx - \omega t) \hat{i} + S'(y) \sin(kx - \omega t) \hat{j} \end{aligned}$$

$v(y=\infty) < \infty$

$$S'(y) \sin(y=\infty) < \infty, S'(y=\infty) < \infty$$

$$|S(y)| < \infty \text{ as } y \rightarrow \infty, |S'(y)| < \infty \text{ as } y \rightarrow \infty$$

$$\therefore \text{let } S(y) = A e^{ky} \therefore S'(y) = A k e^{ky}$$

$$\nabla \cdot \underline{v} = 0 = \frac{\partial}{\partial x} (S(y) k \cos(kx - \omega t)) + \frac{\partial}{\partial y} S(y) \sin(kx - \omega t)$$

$$D \cdot S(y) k^2 \sin(kx - \omega t) + S''(y) \sin(kx - \omega t) = 0$$

$$-S(y) k^2 + S''(y) = 0 = S''(y) - k^2 S(y) = 0$$

$$\text{let } S(y) = e^{ky} \therefore S''(y) = k^2 e^{ky}$$

$$k^2 e^{2y} - k^2 e^{2y} = 0 = k^2 = 0 \therefore k = \pm i \quad \because k > 0$$

$$S(y) = B e^{ky} + C e^{-ky} \therefore S(y=\infty) = B e^{\infty} + C e^{-\infty} \approx 0$$

$$S(y) = A e^{ky} \therefore = B(0) + C e^{\infty} = C e^{\infty} \approx 0 \therefore C = 0$$

$$\therefore S(y) = A e^{ky}$$

$$\text{4b ii) NS: } \rho \left(\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} \right) = -\nabla P + \rho g + \mu \nabla^2 \underline{u}$$

$$\frac{\partial}{\partial t} \underline{u} = \frac{\partial}{\partial t} \nabla \phi = \nabla \frac{\partial \phi}{\partial t} = \frac{\partial}{\partial x} \frac{\partial \phi}{\partial t} \hat{i} + \frac{\partial}{\partial y} \frac{\partial \phi}{\partial t} \hat{j}$$

$$\nabla^2 \underline{u} = \nabla^2 (\nabla \phi) = \nabla \cdot \nabla (\nabla \phi) \quad g = -g \hat{j}, \quad \mu = 0$$

$$\text{initial: } \rho \left(\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} \right) = -\nabla P + \rho g$$

to \hat{j} component of NS:

$$\frac{\partial u_z}{\partial t} = \nabla \frac{\partial \phi}{\partial t} = \frac{\partial}{\partial x} \frac{\partial \phi}{\partial t} \hat{i} + \frac{\partial}{\partial y} \frac{\partial \phi}{\partial t} \hat{j} + \frac{\partial}{\partial z} \frac{\partial \phi}{\partial t} \hat{k}$$

$$\underline{u} = \nabla \phi = \frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} + \frac{\partial \phi}{\partial z} \hat{k}$$

$$\underline{u} \cdot \underline{u} = \frac{\partial \phi}{\partial x} \frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{\partial \phi}{\partial y} + \frac{\partial \phi}{\partial z} \frac{\partial \phi}{\partial z}$$

$$\text{three dimensional: } \underline{u} \cdot \nabla \underline{u} = \left(\frac{\partial \phi}{\partial x} \frac{\partial}{\partial x} + \frac{\partial \phi}{\partial y} \frac{\partial}{\partial y} \right) \left(\frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} \right) =$$

$$\left(\frac{\partial \phi}{\partial x} \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial \phi}{\partial y} \frac{\partial^2 \phi}{\partial x \partial y} \right) \hat{i} + \left(\frac{\partial \phi}{\partial x} \frac{\partial^2 \phi}{\partial x \partial y} + \frac{\partial \phi}{\partial y} \frac{\partial^2 \phi}{\partial y^2} \right) \hat{j}$$

$$\nabla \cdot \underline{u} = 0 \Rightarrow \nabla \cdot \left(\frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} \right) = \frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} = 0$$

$$\nabla P = \frac{\partial P}{\partial x} \hat{i} + \frac{\partial P}{\partial y} \hat{j}$$

$$\nabla^2 u = \nabla^2 \left(\frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} \right) = \left(\frac{\partial^2 \phi}{\partial x^2} \hat{i} + \frac{\partial^2 \phi}{\partial y^2} \hat{j} \right) + \left(\frac{\partial^2 \phi}{\partial x^2} \frac{\partial \phi}{\partial y} + \frac{\partial^2 \phi}{\partial y^2} \frac{\partial \phi}{\partial x} \right) \hat{k}$$

$\therefore \hat{k}$ component of NS:

$$\rho \frac{\partial \frac{\partial \phi}{\partial t}}{\partial y} + \rho \frac{\partial \phi}{\partial x} \frac{\partial^2 \phi}{\partial y^2} + \rho \frac{\partial \phi}{\partial y} \frac{\partial^2 \phi}{\partial x^2} = \frac{\partial P}{\partial y} + \rho g = 0$$

\therefore Integrating w.r.t. y :

$$\rho \frac{\partial \phi}{\partial t} + \rho \int \frac{\partial \phi}{\partial x} \frac{\partial^2 \phi}{\partial y^2} dy + \rho \int \frac{\partial \phi}{\partial y} \frac{\partial^2 \phi}{\partial x^2} dy + P + \rho gy = C_1(t)$$

$$\therefore \frac{\partial \phi}{\partial t} + \left(\frac{\partial \phi}{\partial x} \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial \phi}{\partial y} \frac{\partial^2 \phi}{\partial x^2} \right) dy + P + \rho gy = C_2(t)$$

$$\therefore \int \frac{\partial \phi}{\partial x} \frac{\partial^2 \phi}{\partial y^2} dy + \int \frac{\partial \phi}{\partial y} \frac{\partial^2 \phi}{\partial x^2} dy = \frac{1}{2} \int 2 \frac{\partial \phi}{\partial x} \frac{\partial^2 \phi}{\partial y^2} dy + \frac{1}{2} \int 2 \frac{\partial \phi}{\partial y} \frac{\partial^2 \phi}{\partial x^2} dy =$$

$$\frac{1}{2} \left(\frac{\partial (\partial \phi)}{\partial x} \right)^2 dy + \frac{1}{2} \left(\frac{\partial (\partial \phi)}{\partial y} \right)^2 dy = \frac{1}{2} \left[\left(\frac{\partial \phi}{\partial x} \right)^2 + \left(\frac{\partial \phi}{\partial y} \right)^2 \right] = \frac{1}{2} \left[\left(\frac{\partial \phi}{\partial x} \right)^2 + \left(\frac{\partial \phi}{\partial y} \right)^2 \right]^2 =$$

$$\frac{1}{2} \left| \frac{\partial \phi}{\partial y} \hat{i} + \frac{\partial \phi}{\partial x} \hat{j} \right|^2 = \frac{1}{2} |\nabla \phi|^2 \therefore$$

$$\frac{\partial \phi}{\partial t} + \frac{1}{2} |\nabla \phi|^2 + \rho g = C_2(t) = C(t)$$

$C(t)$ is independent of x \therefore there are no special points in x

\therefore IC and BC independent of x

4. b) i) ✓ on free surface $y = \gamma(x, t)$

$$\frac{\partial \phi}{\partial t} + g \gamma = 0, \quad \frac{\partial \phi}{\partial y} = \frac{\partial \gamma}{\partial t} \quad \text{on } y=0 \text{ is free surface}$$

group speed is C_g , phase speed is C_p

$$\therefore C_g = \frac{\omega}{k} \quad \therefore C_p = \frac{\omega}{k} \quad \therefore$$

$$\frac{\partial \phi}{\partial y} = -\frac{\partial \phi}{\partial t} \quad \therefore \gamma = -\frac{1}{g} \frac{\partial \phi}{\partial t} \quad \therefore \frac{\partial \gamma}{\partial t} = -\frac{1}{g} \frac{\partial^2 \phi}{\partial t^2} \quad \therefore$$

$$\frac{\partial \phi}{\partial y} = -\frac{1}{g} \frac{\partial^2 \phi}{\partial t^2} \quad \therefore \frac{\partial^2 \phi}{\partial t^2} = -g \frac{\partial \phi}{\partial y} \quad \therefore \frac{\partial^2 \phi}{\partial t^2} + g \frac{\partial \phi}{\partial y} = 0$$

$$\therefore \frac{\partial \phi}{\partial y} = g \frac{\partial^2 \phi}{\partial t^2}, \quad \frac{\partial^2 \phi}{\partial y^2} = \frac{\partial^2 \phi}{\partial t^2}$$

$$\phi = A e^{ky} \sin(kx - \omega t) \quad \therefore$$

$$\frac{\partial \phi}{\partial y} = A k e^{ky} \sin(kx - \omega t), \quad \frac{\partial \phi}{\partial t} = A \omega e^{ky} (-\cos(kx - \omega t)) \quad \therefore$$

$$\frac{\partial^2 \phi}{\partial t^2} = -A \omega^2 e^{ky} \sin(kx - \omega t) = -A e^{ky} \omega^2 \sin(kx - \omega t) \quad \therefore$$

$$-A k e^{ky} \sin(kx - \omega t) g = -A e^{ky} \omega^2 \sin(kx - \omega t) \quad \therefore \quad k y = \omega^2 \quad \therefore \quad \omega = \sqrt{k g}$$

\(\text{PP2020} \) vs dispersion relation . .

$$\omega = \pm \sqrt{k'} g^{1/2} = \pm \sqrt{g' k'^{1/2}} = \omega(k)$$

1) ~~group speed~~ group speed $C_g = \frac{d\omega}{dk} = \frac{d}{dk} (\pm \sqrt{g' k'^{1/2}}) = \pm \sqrt{g'} \left(\frac{1}{2}\right) k^{-1/2} = \pm \sqrt{g'} \frac{1}{2} \frac{1}{\sqrt{k}} = \pm \frac{1}{2} \sqrt{\frac{g'}{k}}$

Phase speed $C_p = \frac{\omega}{k} = \pm \sqrt{g' k'^{1/2}} / k = \pm \sqrt{g'} k^{-1/2} = \pm \sqrt{\frac{g'}{k}}$

\(4V \) width $= 3000 \times 10^3 \text{ m} = 3000000 \text{ m}$

depth $= 3 \times 10^3 = 3000 \text{ m}$

\(\because \) phase speed $= C_p = \pm \sqrt{\frac{g'}{k}}$

as waves have different wavelength λ then they have different wave number k \therefore phase speed are different for different wavelengths \therefore waves are dispersive

\(\therefore \) very long waves means very small wave number

\(\therefore \) phase speed $= C_p = \pm \sqrt{\frac{g'}{k}}$, group speed $C_g = \pm \frac{1}{2} \sqrt{\frac{g'}{k}}$

both phase and group speed are very big for these waves which is why they arrive at the coast first then waves with small speeds

\(\therefore T = 30 \text{ s} \quad \therefore \text{frequency} = \frac{1}{30} \text{ per second} = k \quad \therefore \)

$$\lambda = \frac{2\pi}{k} = \frac{2\pi}{\frac{1}{30}} = 60\pi = 188.5 \text{ is wavelength}$$

phase speed $= C_p = \frac{\omega}{k} = \pm \sqrt{\frac{g'}{k}} \quad \therefore$

$$T c = \lambda = 30 \times \left(\pm \sqrt{\frac{g'}{k}} \right) = 30 \times \sqrt{10} \frac{1}{\sqrt{k}} \quad \therefore T = 30 \text{ s}, \quad \frac{1}{T} = \frac{1}{30} = k \quad \therefore$$

$$30 \times \sqrt{10} \times \frac{1}{\sqrt{188.5}} = \lambda = 519.6 \text{ m} \quad \therefore$$

\(\therefore 519.6 \text{ m in } 30 \text{ seconds} \quad \therefore 17.32 \text{ ms}^{-1} \quad \therefore \)

Middle to coast $= \frac{1}{2} (3000 \times 10^3) = 1500000 \text{ m} \quad \therefore$

$$1500000 / 17.32 = 86602.5 \text{ seconds} = 1443.4 \text{ minutes} = 24.1 \text{ hours}$$

From Middle os Atlantic to shores .

2) $\vec{C}_{ii} = \hat{i} \cos \theta - \hat{j} \sin \theta =$
 $\cos \theta \cos \hat{i} + \sin \theta \cos \hat{j} + \cos^2 \theta - \sin \theta \cos \theta \hat{i} - \sin \theta \cos \theta \hat{j} + \sin^2 \theta \hat{k} =$
 $\cos^2 \theta \hat{k} + \sin^2 \theta \hat{k} = \hat{k} \quad \therefore$

$$\text{For large } r: \underline{u} \approx U \hat{u}_r = U(\cos\theta \hat{r} - \sin\theta \hat{\theta}) = U \cos\theta \hat{r} - U \sin\theta \hat{\theta} =$$

$$\frac{1}{r^2 \sin\theta} \frac{\partial \underline{u}}{\partial \theta} \hat{r} - \frac{1}{r \sin\theta} \frac{\partial \underline{u}}{\partial r} \hat{\theta} :.$$

$$\frac{1}{r^2 \sin\theta} \frac{\partial \underline{u}}{\partial \theta} = U \cos\theta \quad - \frac{1}{r \sin\theta} \frac{\partial \underline{u}}{\partial r} = -U \sin\theta \quad \therefore \frac{\partial \underline{u}}{\partial r} = Ur^2 \sin\theta \cos\theta \quad \therefore$$

$$\frac{\partial \underline{u}}{\partial r} = Ur \sin^2\theta \quad \therefore Y = \frac{1}{2} Ur^2 \sin^2\theta + S(\theta) :.$$

$$\frac{\partial \underline{u}}{\partial \theta} = \frac{1}{2} Ur^2 2 \sin\theta \cos\theta + S'(\theta) = Ur^2 \sin\theta \cos\theta + S'(\theta) = Ur^2 \sin\theta \cos\theta$$

i. $S'(\theta) = 0 \therefore S(\theta)$ is constant $\therefore S(\theta)$ is independent of θ
 $\therefore S(\theta) = 0 \therefore$

$$\Psi = \frac{1}{2} Ur^2 \sin^2\theta \text{ as } r \rightarrow \infty$$

$$E^2 \Psi = E^2 (r^\alpha \sin^2\theta) = \frac{\partial^2}{\partial r^2} (r^\alpha \sin^2\theta) + \frac{\sin\theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin\theta} \frac{\partial}{\partial \theta} (r^\alpha \sin^2\theta) \right) =$$

$$\sin^2\theta \frac{\partial^2}{\partial r^2} (\alpha r^{\alpha-1}) + \frac{\sin\theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin\theta} r^\alpha 2 \sin\theta \cos\theta \right) =$$

$$\sin^2\theta \alpha(\alpha-1) r^{\alpha-2} + \frac{\sin\theta}{r^2} \frac{\partial}{\partial \theta} (\cos\theta) r^{\alpha-2} =$$

$$\sin^2\theta \alpha(\alpha-1) r^{\alpha-2} + \sin\theta (-\sin\theta) 2r^{\alpha-2} =$$

$$\sin^2\theta \alpha(\alpha-1) r^{\alpha-2} - \sin^2\theta 2r^{\alpha-2} = \sin^2\theta r^{\alpha-2} [\alpha(\alpha-1) - 2] \quad \therefore$$

$$E^4 \Psi = E^2 (E^2 \Psi) = E^2 / [\sin^2\theta r^{\alpha-2} [\alpha(\alpha-1) - 2]]$$

NS to vorticity equation: NS: $\rho \left(\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} \right) = -\nabla p + \rho g + \mu \nabla^2 \underline{u}$

$$\frac{m}{\rho} = \nu, \nabla \times \underline{u} = \omega, \nabla \cdot \underline{u} = 0 \quad \therefore g = -\nabla \Pi \quad \therefore$$

$$\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} = -\frac{1}{\rho} \nabla p - \nabla \Pi + \mu \nabla^2 \underline{u}, \quad \underline{u} \cdot \nabla \underline{u} = \nabla \frac{\underline{u}^2}{2} - \underline{u} \times \omega \quad \therefore$$

$$\nabla \times \left(\frac{\partial \underline{u}}{\partial t} \right) = \frac{\partial}{\partial t} \nabla \times \underline{u} = \frac{\partial \omega}{\partial t} \quad \nabla \times (\underline{u} \cdot \nabla \underline{u}) = \nabla \times \nabla \frac{\underline{u}^2}{2} - \nabla (\underline{u} \times \omega) = -\nabla (\underline{u} \times \omega)$$

$$-\nabla \times \nabla \Pi \equiv 0 \quad \omega(\nabla \cdot \underline{u}) - (\omega \cdot \nabla) \underline{u} + (\omega \cdot \underline{u}) \nabla \omega = -(\omega \cdot \nabla) \underline{u} + (\underline{u} \cdot \nabla) \omega \quad \therefore$$

$$-\frac{1}{\rho} \nabla \times \nabla p \equiv 0 \quad \frac{\partial \omega}{\partial t} - \nabla (\underline{u} \times \omega) = \nu \nabla^2 \omega = \frac{\partial \omega}{\partial t} - (\omega \cdot \nabla) \underline{u} + (\underline{u} \cdot \nabla) \omega \quad \therefore$$

$$-\frac{1}{\rho} \nabla \times \nabla p = \frac{\partial \omega}{\partial t} - \nabla (\underline{u} \times \omega) = \nu \nabla^2 \omega, \quad \frac{\partial \omega}{\partial t} + (\underline{u} \cdot \nabla) \omega = (\omega \cdot \nabla) \underline{u} + \nu \nabla^2 \omega \quad \underline{m} \nabla^2 \omega =$$

$$\therefore \frac{\partial \omega}{\partial t} + \nabla \times (\underline{u} \cdot \nabla \underline{u}) = \nu \nabla^2 \omega \quad \therefore$$

$$\nabla^2 \underline{u} = \nabla (\nabla \cdot \underline{u}) - \nabla \times (\nabla \times \underline{u}) = \nabla (\nabla \cdot \underline{u}) - \nabla \times \omega \quad \therefore$$

$$\nabla \times \nabla^2 \underline{u} = \nabla \times \nabla (\nabla \cdot \underline{u}) - \nabla \times (\nabla \times \omega) \equiv 0 - \nabla \times (\nabla \times \omega) = -\nabla \times (\nabla \times \omega) =$$

$$-\nabla (\nabla \cdot \omega) + \nabla^2 \omega = -\nabla (\nabla \cdot \nabla \times \underline{u}) + \nabla^2 \omega \equiv -\nabla (\nabla \cdot \nabla \times \underline{u}) + \nabla^2 \omega =$$

$$\therefore \frac{\partial \omega}{\partial t} + \nabla \times (\underline{u} \cdot \nabla \underline{u}) = \nu \nabla^2 \omega$$

$$\therefore \underline{u} \times (\nabla \times \underline{u}) + \underline{u} \times (\nabla \times \underline{u}) = \nabla (\underline{u} \cdot \underline{u}) - (\underline{u} \cdot \nabla) \underline{u} - (\underline{u} \cdot \nabla) \underline{u} =$$

$$2 \underline{u} \times (\nabla \times \underline{u}) = \nabla (\underline{u}^2 - \underline{u} \cdot \nabla \underline{u}) \quad \therefore$$

$$\underline{u} \times (\nabla \times \omega) \underline{u} \cdot \nabla \underline{u} = \frac{1}{2} \nabla \underline{u}^2 - \underline{u} \times (\nabla \times \underline{u}) = \nabla \frac{\underline{u}^2}{2} - \underline{u} \times (\nabla \times \underline{u}) = \nabla \frac{\underline{u}^2}{2} - \underline{u} \times \omega$$

$$\text{PP2020/1a) NS: } \rho \left(\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} \right) = -\nabla P + \rho g + \mu \nabla^2 \mathbf{u} \quad \therefore$$

$$\therefore \rho g = -\nabla P - \mu \nabla^2 \mathbf{u} \quad \therefore$$

$$\rho \left(\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} \right) = -\nabla P - \frac{\mu}{\rho} \nabla^2 \mathbf{u} + \mu \nabla^2 \mathbf{u} \quad \therefore \rho = \frac{\mu}{P} \quad \therefore$$

$$\text{1a) equation } \frac{D\rho}{Dt} + \rho \nabla \cdot \mathbf{u} = \frac{\partial \rho}{\partial t} + \mathbf{u} \cdot \nabla \rho + \rho \nabla \cdot \mathbf{u} = 0 \quad \therefore$$

for incompressible: $\frac{D\rho}{Dt} = 0 \quad \therefore$

$$0 + \rho \nabla \cdot \mathbf{u} = 0 \Rightarrow \nabla \cdot \mathbf{u} = 0 \Rightarrow \nabla \cdot \mathbf{u} = 0$$

1b) incompressible $\Rightarrow \nabla \cdot \mathbf{u} = 0 \quad \therefore$

$$\nabla \cdot \mathbf{u} = \nabla \cdot \left(\frac{1}{R} \hat{R} + R \hat{\theta} + \theta \hat{z} \right) = \frac{1}{R} \frac{\partial}{\partial R} \left(R \frac{1}{R} \right) + \frac{1}{R} \frac{\partial}{\partial \theta} (R \hat{\theta}) + \frac{\partial}{\partial z} (0) =$$

$$\therefore \frac{1}{R} \left(\frac{\partial}{\partial R} (1) \right) + \frac{1}{R} (0) + 0 = \frac{1}{R} (0) + 0 = 0$$

1bii) irrotational is $\omega = \nabla \times \mathbf{u} = 0 \quad \therefore$

$$\omega = \nabla \times \mathbf{u} = \nabla \times \left(\frac{1}{R} \hat{R} + R \hat{\theta} + \theta \hat{z} \right) = \frac{1}{R} \begin{vmatrix} \hat{R} & R \hat{\theta} & \hat{z} \\ \frac{\partial}{\partial R} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ \frac{1}{R} & R & 0 \end{vmatrix} = \frac{1}{R} \begin{vmatrix} \hat{R} & R \hat{\theta} & \hat{z} \\ \frac{\partial}{\partial R} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ \frac{1}{R} & R^2 & 0 \end{vmatrix} =$$

$$\frac{1}{R} \left[\hat{R} (0 - 0) - R \hat{\theta} (0 - 0) + \hat{z} \left(\frac{\partial}{\partial R} (R^2) - 0 \right) \right] = \frac{1}{R} \hat{z} 2R = 2 \hat{z} \neq 0$$

\therefore flow is not irrotational

$$1biii) \mathbf{u} \cdot \nabla = \left(\frac{1}{R} \hat{R} + R \hat{\theta} + \theta \hat{z} \right) \cdot \left(\hat{R} \frac{\partial}{\partial R} + \hat{\theta} \frac{1}{R} \frac{\partial}{\partial \theta} + \hat{z} \frac{\partial}{\partial z} \right) =$$

$$\frac{1}{R} \frac{\partial}{\partial R} + \frac{\partial}{\partial \theta} + 0 = \frac{1}{R} \frac{\partial}{\partial R} + \frac{1}{R} \frac{\partial}{\partial \theta}$$

$$\frac{1}{R} \frac{\partial}{\partial R} + \frac{1}{R} \frac{\partial}{\partial \theta} = \left(\mathbf{u} \cdot \nabla \right) \mathbf{u} = \left(\frac{1}{R} \frac{\partial}{\partial R} + \frac{1}{R} \frac{\partial}{\partial \theta} \right) \left(\frac{1}{R} \hat{R} + R \hat{\theta} \right) =$$

$$\frac{1}{R} \frac{\partial}{\partial R} \left(\frac{1}{R} \hat{R} \right) + \frac{1}{R} \frac{\partial}{\partial R} (R \hat{\theta}) + \frac{1}{R} \frac{\partial}{\partial \theta} \left(\frac{1}{R} \hat{R} \right) + \frac{1}{R} \frac{\partial}{\partial \theta} (R \hat{\theta}) =$$

$$\frac{1}{R} \frac{\partial}{\partial R} \left(R^{-1} \right) \hat{R} + \frac{1}{R} \frac{\partial}{\partial R} (R) \hat{\theta} + \frac{1}{R} \frac{\partial}{\partial \theta} (R^{-1}) \hat{R} + \frac{1}{R} \frac{\partial}{\partial \theta} (\hat{R}) \frac{1}{R} + \frac{1}{R} \frac{\partial}{\partial \theta} (\hat{\theta}) R =$$

$$\frac{1}{R} (-1) \frac{1}{R^2} \hat{R} + \frac{1}{R} \hat{\theta} + 0 + \frac{1}{R^2} \hat{\theta} + (-\hat{R}) =$$

$$(-\frac{1}{R^2} - 1) \hat{R} + (\frac{1}{R^2} + \frac{1}{R}) \hat{\theta}$$

1ci) $y=0$ is a solid stationary boundary
 \therefore the flow being incompressible has

no \hat{y} component $\therefore \mathbf{u} = (u, 0)$ \therefore flow only in x direction by gravity

\therefore there are no special points in x \therefore flow independent of x .

there are special points in y \therefore flow at $y=0$ is 0 \therefore no slip BC.

1. flow dependent on y $\therefore \frac{u}{dt} = (u, 0) = (u(y), 0)$



$$\text{Vciii/ NS: } \frac{\partial u}{\partial t} + u \cdot \nabla u = -\nabla \frac{P}{\rho} + g + \nu \nabla^2 u, \quad \rho = \frac{P}{\rho} \therefore$$

$$\nabla \cdot u = 0 \therefore \frac{\partial u}{\partial t} = \frac{\partial}{\partial t} (u(y, 0)) = (0, 0)$$

$$\therefore \nu \nabla^2 u = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) (u(y), 0) = \left(\frac{\partial^2 u(y)}{\partial y^2}, 0 \right)$$

$$-\nabla \frac{P}{\rho} = \left(-\frac{1}{\rho} \frac{\partial P}{\partial x}, -\frac{1}{\rho} \frac{\partial P}{\partial y} \right)$$

$$g = (g \sin \gamma, -g \cos \gamma)$$

$$u \cdot \nabla = (u(y), 0) \cdot \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y} \right) = (u(y) \frac{\partial}{\partial x}, 0) = u(y) \frac{\partial}{\partial x} \therefore$$

$$u \cdot \nabla u = u(y) \frac{\partial}{\partial x} (u(y), 0) = (u(y) \frac{\partial}{\partial x} u(y), 0) = (0, 0) \therefore$$

$$\cancel{x \text{ component}}: 0 + 0 = -\frac{\partial P}{\partial y} - g \cos \gamma + 0 = 0 = -\frac{1}{\rho} \frac{\partial P}{\partial y} - g \cos \gamma$$

$$x \text{ component: } 0 + 0 = -\frac{1}{\rho} \frac{\partial P}{\partial x} + g \sin \gamma + \nu \frac{\partial^2 u(y)}{\partial y^2} = 0$$

no special points in x

$$\text{Vciii/ } y \text{ component: } 0 = -\frac{1}{\rho} \frac{\partial P}{\partial y} - g \cos \gamma \therefore$$

$$\frac{1}{\rho} \frac{\partial P}{\partial y} = -g \cos \gamma \therefore \frac{\partial P}{\partial y} = -\rho g \cos \gamma \therefore$$

$$P = \int -\rho g \cos \gamma dy = -\rho g \cos \gamma y + C \therefore$$

$$\therefore \text{at } y=h: P_0 = -\rho g \cos(\gamma) h + C \therefore P_0 + \rho g h \cos \gamma = C \therefore$$

$$P = -\rho g \cos(\gamma) y + P_0 + \rho g h \cos \gamma = \rho g \cos(\gamma) (h-y) + P_0 = P_0 + (h-y) \rho g \cos \gamma$$

$$\text{Vciv/ } P = P_0 + (h-y) \rho g \cos \gamma \therefore$$

$$\frac{\partial P}{\partial x} = 0 \therefore -\frac{1}{\rho} (0) + g \sin \gamma + \nu \frac{\partial^2 u(y)}{\partial y^2} = 0 = g \sin \gamma + \nu \frac{\partial^2 u(y)}{\partial y^2} \therefore$$

$$\frac{\partial^2 u(y)}{\partial y^2} = \frac{1}{\nu} g \sin \gamma \therefore \frac{\partial u(y)}{\partial y} = -\frac{1}{\nu} g \sin(\gamma) y + C_2 \therefore$$

$$\text{at } h=y: \frac{\partial u(y)}{\partial y} = -\frac{1}{\nu} g \sin(\gamma) h + C_2 = 0 \therefore C_2 = \frac{1}{\nu} h g \sin \gamma \therefore$$

$$\frac{\partial u(y)}{\partial y} = -\frac{1}{\nu} g \sin(\gamma) y + \frac{1}{\nu} h g \sin \gamma = \omega (h-y) \frac{g \sin \gamma}{\nu} \therefore$$

$$u(y) = (h y - \frac{1}{2} y^2) \frac{g \sin \gamma}{\nu} + C_3 \therefore$$

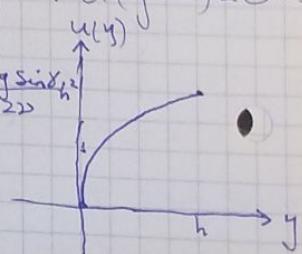
at $y=0$ is no-slip stationary solid boundary $\therefore u(y=0)=0 \therefore$

$$u(0) = 0 = (h(0) - \frac{1}{2}(0)^2) \frac{g \sin \gamma}{\nu} + C_3 = 0 + C_3 = C_3 = 0 \therefore$$

$$u(y) = (h y - \frac{1}{2} y^2) \frac{g \sin \gamma}{\nu} = y(h - \frac{1}{2} y) \frac{g \sin \gamma}{\nu} \therefore$$

$$u(y) = -\frac{1}{2} \frac{\partial}{\partial y} \sin(\gamma) y^2 + \frac{gh \sin \gamma}{\nu} y \therefore$$

$$y \geq 0 \text{ at } y=h: u(h) = h(h - \frac{1}{2} h) \frac{g \sin \gamma}{\nu} = \frac{g \sin \gamma}{\nu} h^2 \therefore$$



$$\text{PP2020} / \text{1C} / Q = \int_0^h u dy = \int_0^h -\frac{1}{2} \frac{g}{\rho} \sin(\gamma) y^2 + \frac{gh \sin \gamma}{\rho} y dy$$

$$= \left[-\frac{1}{6} \frac{g}{\rho} \sin(\gamma) y^3 + \frac{gh \sin \gamma}{\rho} y^2 \right]_0^h = -\frac{1}{6} \frac{g}{\rho} \sin(\gamma) h^3 + \frac{gh \sin \gamma}{\rho} h^2 =$$

$$-\frac{1}{6} \frac{g \sin(\gamma) h^3}{\rho} + \frac{1}{2} \frac{gh \sin(\gamma) h^3}{\rho} = \frac{gh^3 \sin \gamma}{3\rho}$$

$$\nabla u / \text{mass sum} = M = \rho \int_S \underline{u} \cdot \hat{n} dS = \rho \int_S \underline{u} \cdot \hat{n} ds$$

$$\therefore \hat{n} = \hat{i} \therefore \underline{u} \cdot \hat{n} = \underline{u} \cdot \hat{i} = \underline{u} \cdot (1, 0) = (u(y), 0) \cdot (1, 0) = u(y) \therefore$$

$$M = \rho \int_0^h u(y) dy = \frac{\rho g h^3 \sin \gamma}{3\rho} \therefore$$

~~$$M_x = \rho \int_0^h u(y) I_x dy = M_x = \rho \int_0^h \underline{u} |_{I_x} \cdot \hat{n} dS = \rho \int_0^h \underline{u} |_{I_x} \cdot \hat{n} ds$$~~

$$= \rho \int_0^h u(y) |_{I_x} dy = \rho \int_0^h \underline{u} |_{I_x} dy = \frac{\rho g h^3 \sin \gamma}{3\rho} = \frac{8 \rho g h^3 \sin \gamma}{3\rho}$$

$$= M = \frac{\rho g h^3 \sin \gamma}{3\rho} \therefore 8 \sin \gamma = \sin \gamma \therefore$$

$$\therefore \sin \gamma = \frac{1}{8} \sin \gamma \therefore \gamma = \sin^{-1} \left(\frac{1}{8} \sin \gamma \right) \therefore$$

$$x, \gamma > 0, \quad \gamma, \gamma \ll 1 \quad \therefore$$

\sin is increasing for very small angles $\therefore \sin \gamma = \frac{1}{8} \sin \gamma$.

$\therefore \gamma$ is smaller than γ which agrees with my expectations since a steeper angle would require a higher h for the $y=h$ value for the fluid rest to notice there is a slope.

$$\text{1d} / \text{AVS} : \frac{\partial u}{\partial t} + \underline{u} \cdot \nabla \underline{u} = -\frac{1}{\rho} \nabla p - \nabla \cdot \underline{F} + \nu \nabla^2 \underline{u} \therefore$$

$$\text{curls} : \nabla \times \frac{\partial \underline{u}}{\partial t} = \frac{\partial}{\partial t} \nabla \times \underline{u} = \frac{\partial \omega}{\partial t} \therefore \nabla \cdot \underline{u} = 0 \therefore$$

$$\nabla \times \nabla^2 \underline{u} = \nabla \times (\nabla \times \underline{u}) - \nabla \times [\nabla \times (\nabla \times \underline{u})] - \nabla \times (\nabla \times (\nabla \times \underline{u})) =$$

$$-\nabla \times (\nabla \times \omega) = -\nabla (\nabla \cdot \omega) + \nabla^2 \omega = -\nabla (\nabla \cdot \nabla \times \underline{u}) + \nabla^2 \omega \equiv \nabla^2 \omega$$

$$\nabla \times \nabla p \equiv 0, \quad \nabla \times \nabla \cdot \underline{u} \equiv 0 \therefore$$

$$2 \underline{u} \times (\nabla \times \underline{u}) + \cancel{\underline{u} \times \nabla \times \underline{u}} = \nabla (\underline{u} \cdot \underline{u}) - 2(\underline{u} \cdot \nabla) \underline{u} \therefore$$

$$\underline{u} \cdot \nabla \underline{u} = \nabla \left(\frac{\underline{u}^2}{2} \right) - \underline{u} \times (\nabla \times \underline{u}) \equiv \nabla \left(\frac{\underline{u}^2}{2} \right) - \underline{u} \times (\omega)$$

$$\therefore \nabla \times (\underline{u} \cdot \nabla \underline{u}) = \nabla \times \left(\frac{\underline{u}^2}{2} \right) - \nabla \times (\underline{u} \times \omega) \equiv -\nabla (\underline{u} \times \omega) \therefore$$

$$-\nabla (\underline{u} \times \omega) = -\underline{u} (\nabla \cdot \omega) + \omega (\nabla \cdot \underline{u}) \neq (\omega \cdot \nabla) \underline{u} + (\underline{u} \cdot \nabla) \omega \equiv$$

$$-(\omega \cdot \nabla) \underline{u} + (\underline{u} \cdot \nabla) \omega \therefore$$

$$\frac{\partial \underline{u}}{\partial t} - (\omega \cdot \nabla) \underline{u} + (\underline{u} \cdot \nabla) \omega \equiv \nu \nabla^2 \omega \therefore$$

$$\frac{\partial \omega}{\partial t} + (\underline{u} \cdot \nabla) \omega = (\omega \cdot \nabla) \underline{u} + \nu \nabla^2 \omega \equiv \frac{D \omega}{Dt} \therefore \frac{\partial}{\partial t} = \frac{\partial}{\partial t} + \underline{u} \cdot \nabla$$

$\rightarrow y$

1dii/ A) $\underline{u} = \alpha R z \hat{\underline{x}}$:

$$\omega = \nabla \times \underline{u} = \frac{1}{R} \begin{vmatrix} \hat{\underline{x}} & \hat{\underline{y}} & \hat{\underline{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & 0 \end{vmatrix} \nabla \times (0 \hat{\underline{x}} + \alpha R z \hat{\underline{x}} + 0 \hat{\underline{z}}) = \frac{1}{R} \begin{vmatrix} \hat{\underline{x}} & \hat{\underline{y}} & \hat{\underline{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & \alpha R^2 z \end{vmatrix} =$$

$$\frac{1}{R} \left[\hat{\underline{x}} (0 - \alpha R^2 z) - R \hat{\underline{y}} (0 - 0) + \hat{\underline{z}} (2 \alpha R z - 0) \right] =$$

$$\frac{1}{R} \left[-\alpha R^2 \hat{\underline{x}} + 2 \alpha R z \hat{\underline{z}} \right] = -\alpha R \hat{\underline{x}} + 2 \alpha z \hat{\underline{z}} \quad \dots$$

$$\nabla \cdot \underline{u} = \nabla \cdot (-\alpha R \hat{\underline{x}} + 2 \alpha z \hat{\underline{z}}) = \frac{1}{R} \frac{\partial}{\partial R} (-\alpha R^2) + \frac{\partial}{\partial z} (2 \alpha z) =$$

$$\frac{1}{R} (-2 \alpha R) + 2 \alpha = -2 \alpha + 2 \alpha = 0$$

~~W.B.~~ matrix lines: $\frac{dr}{ds} = \alpha(r, s)$, $c = \text{constant}$:

$$s = -\alpha R \hat{\underline{x}} + 2 \alpha z \hat{\underline{z}} \quad \dots$$

$$\therefore \text{let } z \delta(r) = c \quad \therefore \quad \delta'(r) = 0,$$

$$z \delta'(r) = c \quad \therefore$$

$$\frac{dr}{dR} = -\alpha R, \quad \frac{dR}{\alpha R} = \frac{dz}{\delta(r)}, \quad \therefore \quad \frac{dR}{-\alpha R} = \frac{dz}{2 \alpha z}$$

$$\therefore \int \frac{1}{-\alpha R} dR = \int \frac{1}{2 \alpha z} dz = \frac{1}{2} \ln z$$

$$-\frac{1}{\alpha} \ln |R| = 2 \alpha \ln \frac{1}{2} \ln |z| + C_1 \quad \therefore -\frac{1}{\alpha} \ln R \quad \therefore R \geq 0:$$

$$\therefore -\frac{1}{2} \ln |z| + C_2 = \ln R \quad \therefore \ln |z^{-1/2}| + C_2 \quad \dots$$

$$R = e^{\ln |z^{-1/2}| + C_2} = C_3 |z^{-1/2}| = C_4 z^{-1/2} \quad \dots$$

$$z^{1/2} R = C_5 \quad \therefore \quad z R^2 = z \delta(r) = C \quad \dots$$

$$\delta(r) = R^2$$

1dii/c) $\underline{u} = (0, \alpha R z, \delta) = \nabla \times (\psi \hat{\underline{z}}) = \frac{1}{R} \begin{vmatrix} \hat{\underline{x}} & \hat{\underline{y}} & \hat{\underline{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & R \delta \end{vmatrix} =$

$$\frac{1}{R} \left[\hat{\underline{x}} \left(0 - R \frac{\partial \delta}{\partial z} \right) - R \hat{\underline{y}} (0 - 0) + \hat{\underline{z}} \left(0 - 0 \right) \right] = \frac{1}{R} \begin{vmatrix} \hat{\underline{x}} & \hat{\underline{y}} & \hat{\underline{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & R \delta \end{vmatrix} =$$

$$\frac{1}{R} \left[\hat{\underline{x}} \left(\frac{\partial \delta}{\partial z} \right) - R \hat{\underline{y}} \left(\frac{\partial \delta}{\partial z} \right) - 0 \hat{\underline{z}} \right] = \left(\frac{1}{R} \frac{\partial \delta}{\partial z}, -\frac{\partial \delta}{\partial R}, 0 \right) \quad \dots$$

$$\frac{1}{R} \frac{\partial \delta}{\partial z} = 0 \quad \therefore \frac{\partial \delta}{\partial z} = 0, \quad \alpha R z = -\frac{\partial \delta}{\partial R} \quad \therefore \quad \frac{\partial \delta}{\partial R} = -\alpha R z \quad \dots$$

$$\delta = -\frac{1}{2} \alpha R^2 z + \delta(\infty) \quad \dots$$

$$\frac{\partial \delta}{\partial R} = \frac{\partial}{\partial R} \left(-\frac{1}{2} \alpha R^2 z + \delta(\infty) \right) = -\frac{1}{2} \alpha R^2 z + \delta'(\infty) = 0 \quad \therefore \quad \delta'(\infty) = 0$$

$$\therefore \delta(\infty) = 0 \quad \therefore \quad \delta = -\frac{1}{2} \alpha R^2 z = \delta(R, z)$$

$$\nabla \cdot \mathbf{u} = \int_C \mathbf{u} \cdot d\mathbf{l} = \int_S (\nabla \times \mathbf{u}) \cdot \hat{n} dS = \int_S \omega \cdot \hat{n} dS$$

$$= \int_C \alpha R z \hat{\mathbf{z}} \cdot \hat{n} d\mathbf{l} = \int_0^R \alpha R z \hat{\mathbf{z}} \cdot \hat{\mathbf{z}} dL = \int_0^R \alpha R z dR =$$

$$\left[\frac{\alpha}{2} R^2 z \right]_0^R = \frac{\alpha}{2} R^2 z$$

$$\nabla^2 \cdot \mathbf{u} = \frac{1}{L}, \quad \frac{\partial u}{\partial t} \sim \frac{1}{T}, \quad \nabla^2 \sim \frac{1}{L^2}, \quad \text{neglect } u \sim v$$

$$\therefore \frac{\partial u}{\partial t} \sim \frac{1}{T} = \frac{U}{L} \quad \nabla^2 \sim \frac{1}{L^2} \quad \therefore$$

$$\frac{\partial u}{\partial t} \sim \frac{1}{T} U = \frac{U}{L} U = \frac{U^2}{L}, \quad \mathbf{u} \cdot \nabla \mathbf{u} \sim U \frac{1}{L} U = \frac{U^2}{L} \sim \frac{\partial u}{\partial t}$$

$$\approx \nu \nabla^2 \mathbf{u} \sim \nu \frac{1}{L^2} U = \nu \frac{U}{L^2};$$

$$\frac{\partial u}{\nu \nabla^2 \mathbf{u}} \sim \frac{U \cdot \nabla U}{\nu \nabla^2 \mathbf{u}} \sim \frac{U^2/L}{\nu U/L^2} = \frac{UL}{\nu L} = Re \ll 1$$

for small Reynolds number \therefore

neglect $\frac{\partial u}{\partial t}, \mathbf{u} \cdot \nabla \mathbf{u} \quad \therefore \text{neglect gravity} \quad \therefore g=0 \quad \therefore$

$$\mathbf{u}(r) = -\nabla \varphi + \mu \nabla^2 \mathbf{u} = 0$$

$$\nabla \cdot \mathbf{u} / Re = \frac{UL}{\nu} \quad \text{honey has large kinematic viscosity.}$$

\therefore very viscous

toothbrush has very small $L \quad \therefore$ small distance

$$\nabla \cdot \mathbf{u} = 0 \quad \nabla \cdot \nabla \times \mathbf{u} = 0 \quad \therefore$$

$\nabla \cdot \mathbf{u} = \nabla \cdot \nabla \times \left(\frac{U}{r \sin \theta} \hat{\mathbf{z}} \right) = 0 \quad \text{always shows } \nabla \cdot \mathbf{u} = 0 \text{ incompressible}$

$$\mathbf{u} = (u, v, 0) = \nabla \times \left(\frac{U}{r \sin \theta} \hat{\mathbf{z}} \right) = \frac{1}{r \sin \theta} \begin{vmatrix} \hat{r} & \hat{\theta} & \hat{z} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ 0 & 0 & U \end{vmatrix}$$

$$= \frac{1}{r \sin \theta} \left[\hat{r} \left(\frac{\partial U}{\partial \theta} \right) - \hat{\theta} \left(\frac{\partial U}{\partial r} \right) \right] = \frac{1}{r \sin \theta} \frac{\partial U}{\partial \theta} \hat{r} - \frac{1}{r \sin \theta} \frac{\partial U}{\partial r} \hat{\theta} + v \hat{z}$$

$$\therefore u = \frac{1}{r \sin \theta} \frac{\partial U}{\partial \theta}, \quad -\frac{1}{r \sin \theta} \frac{\partial U}{\partial r} = v \quad \therefore$$

$$\text{as } r \rightarrow \infty: \quad u \approx U \hat{r} = U(\cos \theta \hat{r} - \sin \theta \hat{\theta}) = U \cos \theta \hat{r} - U \sin \theta \hat{\theta}$$

$$= \frac{1}{r \sin \theta} \frac{\partial U}{\partial \theta} \hat{r} - \frac{1}{r \sin \theta} \frac{\partial U}{\partial r} \hat{\theta} \quad \therefore$$

$$\bullet U \cos \theta = \frac{1}{r \sin \theta} \frac{\partial U}{\partial \theta}, \quad + \frac{\partial U}{r \sin \theta} \hat{\theta} = +U \sin \theta \quad \therefore \frac{\partial U}{\partial \theta} = U r^2 \sin \theta \cos \theta \quad \therefore$$

$$\frac{\partial U}{\partial r} = U r \sin^2 \theta \quad \therefore \quad U = \frac{1}{2} U r^2 \sin^2 \theta + f(\theta) \quad \therefore$$

$$\frac{\partial U}{\partial r} = U r \sin \theta \cos \theta + f'(r) = U r^2 \sin \theta \cos \theta \quad \therefore f'(r) = 0 \quad \therefore f(\theta) = 0 \quad \therefore$$

$$U = U r \sin^2 \theta$$

$$\begin{aligned}
 & \text{Let } g = r^\alpha, \quad \therefore g = r(\theta) \sin^2 \theta = r^\alpha \sin^2 \theta \quad \dots \\
 E^2 g = E^2 r^\alpha \sin^2 \theta &= \frac{\partial}{\partial r} (r^\alpha \sin^2 \theta) + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (r^\alpha \sin^2 \theta) \right) = \\
 \sin^2 \theta \frac{\partial}{\partial r} (\alpha r^{\alpha-1}) + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} r^\alpha 2 \sin \theta \cos \theta \right) &= \\
 \alpha \sin^2 \theta (\alpha-1) r^{\alpha-2} + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} (2 \cos \theta) r^\alpha &= \\
 \alpha(\alpha-1) r^{\alpha-2} \sin^2 \theta + -2r^{\alpha-2} \sin^2 \theta &= \\
 [\alpha(\alpha-1)-2] r^{\alpha-2} \sin^2 \theta &\quad \therefore
 \end{aligned}$$

$$\begin{aligned}
 E^4 Y &= E^2(E^2 Y) = E^2\left([\alpha(\alpha-1)-2]r^{\alpha-2}\sin^2\theta\right) = \\
 &= \frac{\partial}{\partial r}\left([\alpha(\alpha-1)-2]r^{\alpha-2}\sin^2\theta\right) + \frac{\sin\theta}{r^2}\frac{\partial}{\partial\theta}\left(\frac{1}{\sin\theta}\frac{\partial}{\partial\theta}([\alpha(\alpha-1)-2]r^{\alpha-2}\sin^2\theta)\right) = \\
 &= [\alpha(\alpha-1)-2]\sin^2\theta(\alpha-2)\frac{\partial}{\partial r}(r^{\alpha-3}) + \frac{\sin\theta}{r^2}\frac{\partial}{\partial\theta}\left(\frac{[\alpha(\alpha-1)-2]}{\sin\theta}r^{\alpha-2}2\sin\theta\cos\theta\right) = \\
 &= [\alpha(\alpha-1)-2](\alpha-2)(\alpha-3)r^{\alpha-4}\sin^2\theta + \frac{\sin\theta}{r^2}\frac{\partial}{\partial\theta}(\cos\theta)2[\alpha(\alpha-1)-2]r^{\alpha-2} = \\
 &= [\alpha(\alpha-1)-2]\left[(\alpha-2)(\alpha-3)r^{\alpha-4}\sin^2\theta - 2r^{\alpha-4}\sin^2\theta\right] = \\
 &= [\alpha(\alpha-1)-2]r^{\alpha-4}\sin^2\theta[(\alpha-2)(\alpha-3)-2] = 0;
 \end{aligned}$$

$$\alpha(\alpha-1)-2=0 \quad \text{or} \quad (\alpha-2)(\alpha-3)-2=0 \quad \therefore$$

$$\alpha^2-\alpha-2=0, \quad \alpha^2+6-5\alpha-2=\alpha^2-5\alpha+4=0 \quad \therefore$$

$$(\alpha - 2)(\alpha + 1) = 0 \quad , \quad (\alpha - 4)(\alpha - 1) = 0 \quad \dots$$

$$d=2, \quad d=-1, \quad d=4, \quad d=1; \quad$$

$$\Sigma(\Gamma) = \mathbb{Z} \Gamma^d = A\Gamma^{-1} + B\Gamma^0 + C\Gamma^1$$

Page 1

$$\text{Since } u = u^{\hat{x}} + v\hat{\theta}, \quad \omega = \nabla \times u = \nabla \times (u^{\hat{x}} + v\hat{\theta}) =$$

$$\frac{1}{r^2 \sin \theta} \begin{vmatrix} \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & r \sin \theta \frac{\partial}{\partial \phi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ u & r v & 0 \end{vmatrix} = \frac{1}{r^2 \sin \theta} \begin{vmatrix} \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} & r \sin \theta \frac{\partial}{\partial \phi} \\ \frac{\partial}{\partial r} & \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} & \frac{1}{r} \frac{\partial}{\partial \phi} & 0 \\ \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} & \frac{1}{r} \frac{\partial}{\partial \phi} & 0 & 0 \end{vmatrix}$$

$$\underline{U} = \underline{U} \hat{\theta} + r \underline{\phi} = \underline{U} = \frac{1}{r^2 \sin \theta} \frac{\partial \Psi}{\partial \theta} \hat{\theta} - \frac{1}{r \sin \theta} \frac{\partial \Psi}{\partial r} \hat{\phi}$$

$$\Psi = 8(1) \sin^2 \theta \therefore \Psi_\theta = 2 \delta \sin \theta \cos \theta , \quad \Psi_r = 8' \sin^2 \theta \therefore$$

$$\therefore u = \frac{1}{r^2 \sin \theta} 2r \sin \theta \cos \theta \hat{i} - \frac{1}{r \sin \theta} \theta' \sin^2 \theta \hat{j}$$

$$2 \frac{1}{r^2} s' \cos\theta \hat{e} - \frac{1}{r} s' \sin\theta \hat{\theta} \quad ;$$

$$\underline{w} = \nabla \times \underline{u} = \frac{1}{r^2} \quad \therefore \quad \underline{w} = \left(-\frac{\sin \theta}{r} S'' + \frac{z \sin \theta}{r^2} S \right) \hat{\underline{S}} :$$

$$\int_0^b \underline{u} \cdot d\underline{u} = \int_a^b \underline{u} \cdot \hat{\underline{n}} dr = \int_a^b \underline{u} \cdot \hat{\underline{r}} dr = \int_a^b \omega \cdot d\underline{s} = \int_c^d \nabla \times \underline{u} \cdot d\underline{s}$$

$$\int_a^b \frac{1}{r^2 \sin \theta} \frac{\partial y}{\partial \theta} dr = \int_a^b \frac{1}{r \sin \theta} 28 \sin \theta \cos \theta dr = 28 \int_a^b \left[\frac{1}{2} \left(\frac{1}{\tan \theta} \right)' + B \ln \left(\frac{b}{a} \right) + C(b-a) + \frac{C}{3} \left(\frac{1}{\tan \theta} \right) \right] dr$$