Optimization & Deep Learning Packages

Felix Kreuk & Yossi Adi

University of Bar-Ilan

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No derivatives today!

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Just kidding. Maybe a little bit.



Overview

- Optimization
 - SGD
 - Momentum
 - AdaGrad
 - RMSprop
 - Adam
- Deep Learning Packages
 - Tensors
 - Loading MNIST
 - First Model
 - Training & Testing

Outline

- Optimization
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We outline some variants of Gradient Descent widely used by the deep learning community.



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Momentum

SGD has trouble navigating ravines, i.e. areas where the surface curves much more steeply in one dimension than in another. In these scenarios, SGD oscillates across the slopes of the ravine while only making hesitant progress along the bottom towards the local optimum as in Image 2.





Figure: SGD with and without momentum

Momentum Update

$$v_t = \gamma v_{t-1} + \eta \frac{\partial L}{\partial \theta_i}$$
$$\theta_i = \theta_i - v_t$$

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AdaGrad Update

$$c_{t,i} = \left(\sum_{k=0}^{t} \frac{\partial L}{\partial \theta_{k,i}}\right)^{2}$$
$$\theta_{t+1,i} = \theta_{t,i} - \frac{\frac{\partial L}{\partial \theta_{t,i}}}{\sqrt{c+\epsilon}}$$

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RMSprop Update

$$c_{t,i} = \gamma c_{t-1,i} + (1 - \gamma) \left(\frac{\partial L}{\partial \theta_{t,i}}\right)^{2}$$

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- \bullet Typical values for γ are 0.9, 0.99 and 0.999.
- Unlike AdaGrad, updates do not get monotonically smaller.



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Adam Update

$$m_{t,i} = \gamma_1 m_{t-1,i} + (1 - \gamma_1) \frac{\partial L}{\partial \theta_{t,i}}$$

$$v_{t,i} = \gamma_2 v_{t-1,i} + (1 - \gamma_2) \left(\frac{\partial L}{\partial \theta_{t,i}}\right)^2$$

$$\theta_{t+1,i} = \theta_{t,i} - \frac{m_{t,i}}{\sqrt{v_{t,i} + \epsilon}}$$

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- Practically, it is the default algorithm in many packages.
- Recommended values in paper are $\gamma_1 = 0.9$, $\gamma_2 = 0.99$.



Visual Example

PyTorch

- In this course we will use **PyTorch**.
- PyTorch is a deep learning package by Facebook.
- Installation instructions can be found at https://pytorch.org

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Hello World - Tensors I

- Forget about vectors/matrices we will use Tensors from now on.
- Tensors are n-dimensional vectors.
- Very similar to ndarrays in numpy.
- Used to represent data and parameters in PyTorch.

Hello World - Tensors II

Let's define 2 tensors:

```
>>> w = torch.FloatTensor([1,2,3])
>>> x = torch.FloatTensor([4,5,6])
```

We can multiply them element-wise

```
>>> w * x

4
10
18
[torch.FloatTensor of size 3]
```

Add:

```
>>> w + x

5
7
9
[torch.FloatTensor of size 3]
```

Hello World - Tensors III

Concat:

```
>>> torch.cat([w,x])

1
2
3
15
5
6
[torch.FloatTensor of size 6]
```

Assign value:

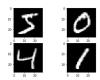
```
>>> x[0] = 15
>>> x
15
5
6
[torch.FloatTensor of size 3]
```

You can read more in the official documentation.

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Hello World - Loading MNIST

First, we need to load the data. Fortunately, PyTorch makes it easy.



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Hello World - Model

Let's create our first model, it will be a simple one.

```
class FirstNet(nn.Module):
    def __init__(self,image_size):
        super(FirstNet, self).__init__()
        self.image_size = image_size
        self.fc0 = nn.Linear(image_size, 1000)
        self.fc1 = nn.Linear(1000, 50)
        self.fc2 = nn.Linear(50, 10)

def forward(self, x):
        x = x.view(-1, self.image_size)
        x = F.relu(self.fc0(x))
        x = F.relu(self.fc1(x))
        x = F.relu(self.fc2(x))
        return F.log_softmax(x)
model = FirstNet(image_size=28*28)
```

Note that we didn't have to define "backward" – it was already written for us.

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Hello World - Training Loop I

So now that we have our model, we can write a training loop for it:

```
optimizer = optim.SGD(model.parameters(), lr=lr)

def train(epoch, model):
    model.train()
    for batch_idx, (data, labels) in enumerate(train_loader):
        optimizer.zero_grad()
        output = model(data)
        loss = F.nll_loss(output, labels)
        loss.backward()
        optimizer.step()
```

- Loop through all training examples
- Calculate model's output
- Calculate loss
- Backprop the error
- Update model's parameters

Hello World - Training Loop II

You can swap SGD with any other optimizer:

```
optimizer = optim.Adam(model.parameters(), lr=lr)
optimizer = optim.AdaDelta(model.parameters(), lr=lr)
optimizer = optim.RMSprop(model.parameters(), lr=lr)
...
```

Hello World - Testing Loop

```
def test():
    model.eval()
    test_loss = 0
    correct = 0
    for data, target in test_loader:
        output = model(data)
        test_loss += F.nll_loss(output, target, size_average=False).data[0] # sum up batch loss
        pred = output.data.max(1, keepdim=True)[1] # get the index of the max log-probability
        correct += pred.eq(target.data.view_as(pred)).cpu().sum()

test_loss /= len(test_loader.dataset)
    print('\nTest_set:_Average_loss:_(:.4f},_Accuracy:_{{}}/{{}_{u}((:.0f)%)}\n'.format(
        test_loss, correct, len(test_loader.dataset),
        100. * correct / len(test_loader.dataset)))
```

- No weight updates
- Accumulating metrics (accuracy and average loss)

Putting it all together

```
for epoch in range(1, 10 + 1):
    train(epoch)
    test()
```

```
Train Epoch: 1 [0/60000 (0%)] Loss: 2.308621
Train Epoch: 1 [6400/60000 (11%)] Loss: 2.285088
Train Epoch: 1 [12800/60000 (21%)] Loss: 2.263519
Train Epoch: 1 [19200/60000 (32%)]
                                 Loss: 2.210358
Train Epoch: 1 [25600/60000 (43%)]
                                 Loss: 2.217742
Train Epoch: 1 [32000/60000 (53%)]
                                 Loss: 2.140791
                                  Loss: 2.171224
Train Epoch: 1 [38400/60000 (64%)]
                                  Loss: 2.134961
Train Epoch: 1 [44800/60000 (75%)]
Train Epoch: 1 [51200/60000 (85%)]
                                    Loss: 2.020994
Train Epoch: 1 [57600/60000 (96%)]
                                    Loss: 1.994740
Test set: Average loss: 2.0090, Accuracy: 4920/10000 (49%)
. . .
```