Connectionist Temporal Classification for Robust Speech Recognition Applications

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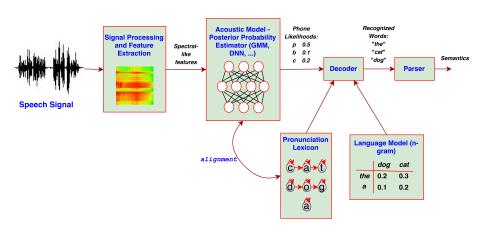




August 29, 2016

Speech Recognition Overview





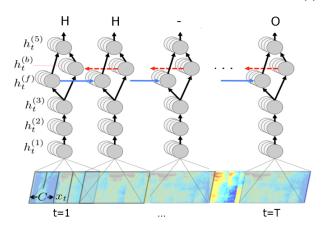
"There is at least one fundamental difficulty with supervised training of a (purely) connectionist network for continuous speech recognition: a target function must be defined, even though the training is done for connected speech units where the segmentation is generally unknown."

H. Bourlard and N. Morgan, 1994, in "Connectionist Speech Recognition: A Hybrid Approach"

HOW CTC?



- Alignment of inputs with outputs are not known ⇒ CTC considers all possible alignments.
- In addition to all label characters, a special blank label (-) is defined



HOW CTC?



- Let $L' = L \cup \{blank\}$
- Let y_k^t : probability of seeing label k at time t
- Define function $\mathcal{B}: L'^T \to L^{\leq T}$, that removes blank labels and consecutive characters
- To find probability of a certain label, sum over all possible alignments:

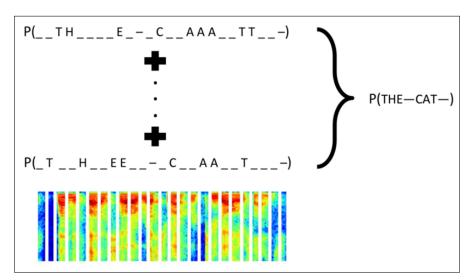
$$p(\mathbf{l}|\mathbf{x}) = \sum_{\pi \in \mathcal{B}^{-1}(\mathbf{l})} p(\pi|\mathbf{x}) = \sum_{\pi \in \mathcal{B}^{-1}(\mathbf{l})} \prod_{t=1}^T y_{\pi_t}^t$$

Define cost function:

$$E_{CTC} = -\sum_{(\mathbf{x}, \mathbf{I}) \in S} \log p(\mathbf{I}|\mathbf{x})$$

HOW CTC?







- l' is a modified version of the target label sequence l by adding blanks between every other label ("aab" \rightarrow "-a-a-b-")
- Set V(t, u) is defined as:

$$V(t,u) = \left\{ \pi \in L'^{t} : \mathcal{B}(\pi) = \mathbf{I}_{1:u/2}, \pi_{t} = I'_{u} \right\}$$

Forward variables are defined:

$$\alpha(t, u) = \sum_{\pi \in V(t, u)} p(\pi | \mathbf{x}) = \sum_{\pi \in V(t, u)} \prod_{i=1}^{t} y_{\pi_i}^i$$



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Finally:

$$p(\mathbf{I}|\mathbf{x}) = \alpha(\mathsf{T}, |\mathbf{I}'|) + \alpha(\mathsf{T}, |\mathbf{I}'| - 1)$$



Backward variables:

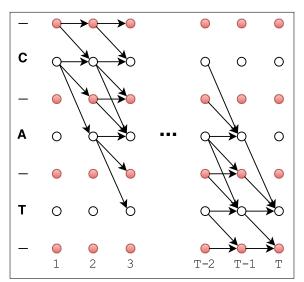
$$\beta(t,u) = \sum_{\pi \in W(t,u)} \prod_{i=1}^{T-t} y_{\pi_i}^{t+i}$$

where:

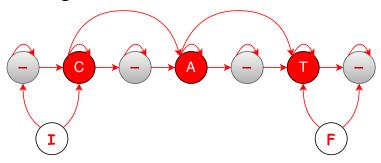
$$W(t,u) = \left\{\pi \in L'^{T-t} : \mathcal{B}(\hat{\pi} + \pi) = \mathbf{I} \ \forall \hat{\pi} \in V(t,u) \right\}$$

ullet Forward and backward variables at time t can be computed recursively using values at time $t-1 \Rightarrow$ forward-backward algorithm of HMM's

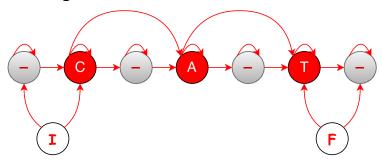




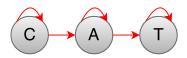
CTC Training



CTC Training



DNN/HMM Training





• By simple calculus, it can be shown that:

$$\alpha(t, u)\beta(t, u) = \sum_{\pi \in X(t, u)} \prod_{t=1}^{T} y_{\pi_t}^t = \sum_{\pi \in X(t, u)} p(\pi|\mathbf{x})$$

where
$$X(t, u) = \{\pi \in \mathcal{L}'^T : \mathcal{B}(\pi) = I, \pi_t = I'_u\}$$

• Therefore, for any t:

$$p(\mathbf{I}|\mathbf{x}) = \sum_{u=1}^{|\mathbf{I}'|} \alpha(t, u)\beta(t, u)$$

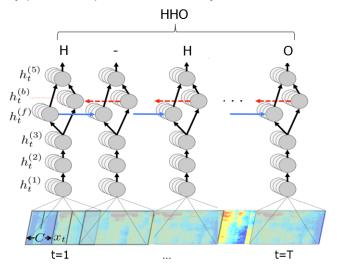
Back-propagated gradient:

$$\frac{\partial p(\mathbf{I}|\mathbf{x})}{\partial y_k^t} = \frac{1}{y_k^t} \sum_{u \in C(\mathbf{I},k)} \alpha(t,u) \beta(t,u), \text{ where } C(\mathbf{I},k) = \{u : l_u' = k\}$$

Best-Path Decoding



Most likely path corresponds to most likely label



Experimental Setup



• "Deep Speech" Motivation: CTC Training with huge amounts of training data

Dataset	Туре	Hours	
WSJ	read	80	
Switchboard	conversational	300	
Fisher	conversational	2000	
Baidu	read	5000	
		7380	

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 "Deep Speech" Results: Testing Set of 100 noisy and 100 noise-free utterances (SNR between 2 and 6 dB in noisy samples)

System	Clean	Noisy
Google API	6.64	30.47
Deep Speech	6.56	19.06

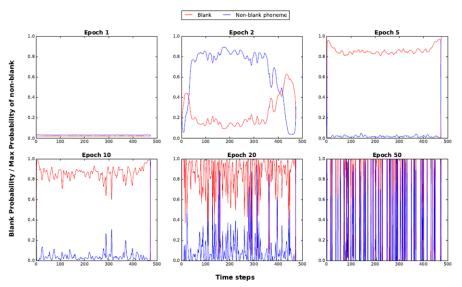
Experimental Setup



- Use MFCC features (dimensionality = 13)
- Use TIMIT dataset (≈ 5 hours of speech data)
- Phoneme-level transcriptions (48 phonemes)
- 3696 utterances for training set, 400 utterances for development set, 192 utterances for testing set
- Use Kaldi for DNN/HMM baseline: Fully connected network with 6 hidden layers, 512 neurons each, output layer of size 48
- Use Lasagne for CTC training: 2 B-LSTM layers with 832 cells per layer, 2 fully connected layers with 512 neurons each, output layer of size 49
- Phoneme-error rate as target comparison criterion

CTC Training





Experimental Results



PER Result over clean TIMIT:

	DNN/HMM	СТС
Clean Data	24.9%	26.9%

Robustness



- Got various noise samples (10 seconds long) from Aurora corpus (sounds recorded in car, airport, restaurant, . . .)
- Need more noise samples (at least proportional to training data size)
 in order not the network to learn the noise
- Generate new noise samples from existing ones by mixing
- Same experiments as before for the new "noisy" TIMIT
- Results generated for different SNR values: -10dB, -3dB, 0dB, 3dB, 10dB, 100dB

Experimental Results - 2



• PER Results over noisy TIMIT:

SNR (dB)	DNN/HMM	СТС	
-10	52.1%	54.83%	
-3	44.2%	47.04%	
0	40.3%	43.22%	
3	38.1%	41.33%	
10	31.1%	34.84%	
100	26.5%	32.3%	



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 - ⇒ can keep more hypotheses during beam search decoding
- Same order of decoding complexity as monophone training of GMM/HMMs

Experimental Results - 3



• PER Results over noisy TIMIT:

SNR (dB)	Monophone	СТС
-10	58.2%	54.83%
-3	54.7%	47.04%
0	50.5%	43.22%
3	48.0%	41.33%
10	41.6%	34.84%
100	35.6%	32.3%

Influence of Training Set Size



- Only kind of information given to the network is the sequence of target labels and sequence of feature vectors
- A lot of these training examples should be given to the network
- Perform same experiments on a subset of TIMIT (namely, 10% of the training examples: 370 utterances)

Experimental Results - 4



• PER Results over a smaller subset of TIMIT:

SNR (dB)	Monophone	DNN/HMM	СТС
-10	64.6%	65.1%	72.42%
-3	59.7%	61.9%	66.18%
0	56.8%	58.3%	64.25%
3	53.2%	54.4%	62.27%
10	47.3%	48.3%	57.73%
100	42.6%	44.1%	53.31%
∞ (Clean)	39.4%	42.7%	49.98%

CTC Robustness



- Main obstacle in speech recognition is the variability of speech features with respect to target labels pronounced (inter- and intra-speaker variations)
- For noisy speech, the variability is higher
- Forced alignments "confuse" the network: some noisy frames are not representative of any target label
- CTC has the option to map "unclear" frames to the blank symbol ⇒ less confusion
- Large training set still needed

Conclusions



- CTC "shines" when large training sets are available, especially for noisy data:
 - ⇒ As less amount of information is given to the network (no input-output segmentation), more training data should be given for the network to *learn* the alignment.

• Inherent benefits: faster and more scalable decoding

Thank You!