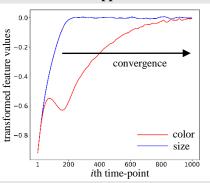


perception



consciousness





Perception is approximate Bayesian inference: at each point in time, the brain makes a "best guess" of size and color given the sensory data y by maximizing

$$P(c, s|y) = \frac{P(c, s|y) P(c, s)}{P(y)}$$

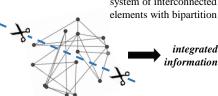
...and does so until these guesses converge.

black box representations and algorithms

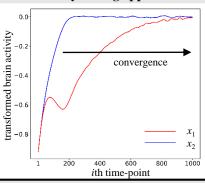
> enabling consciousness

information is integrated: a conscious system generates more information as a whole than the sum of a bipartition. system of interconnected

Representations and algorithms are such that



brain activity during approximate Bayesian inference



Evolution of feature values corresponds to brain activity as measured in (groups of) neurons x_1 , x_2 over time.

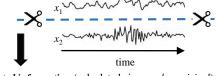
deriving evolution of x_1, x_2 with black box variational inference

black box neuronal implementation of representations

and algorithms

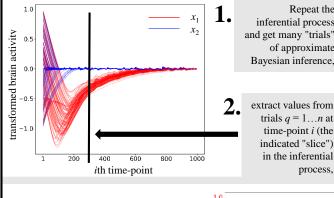
Neuronal implementation of representations and algorithms are such that information is integrated.

> measured activity in a system of interconnected (groups of) neurons x_1, x_2



integrated information (calculated via e. g. ϕ -empirical)

how we bring variational inference and integrated information together



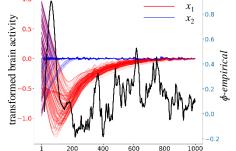
Repeat the inferential process and get many "trials" of approximate Bayesian inference,

> trials q = 1...n at time-point i (the indicated "slice") in the inferential process,

qth trial

treat them as a time-series and calculate ϕ empirical,

> do that for each time-point i.



ith time-point

We thereby obtain the dynamics of integrated information during approximate Bayesian inference.

> Or the dynamics of conscious level during perceptual inference.