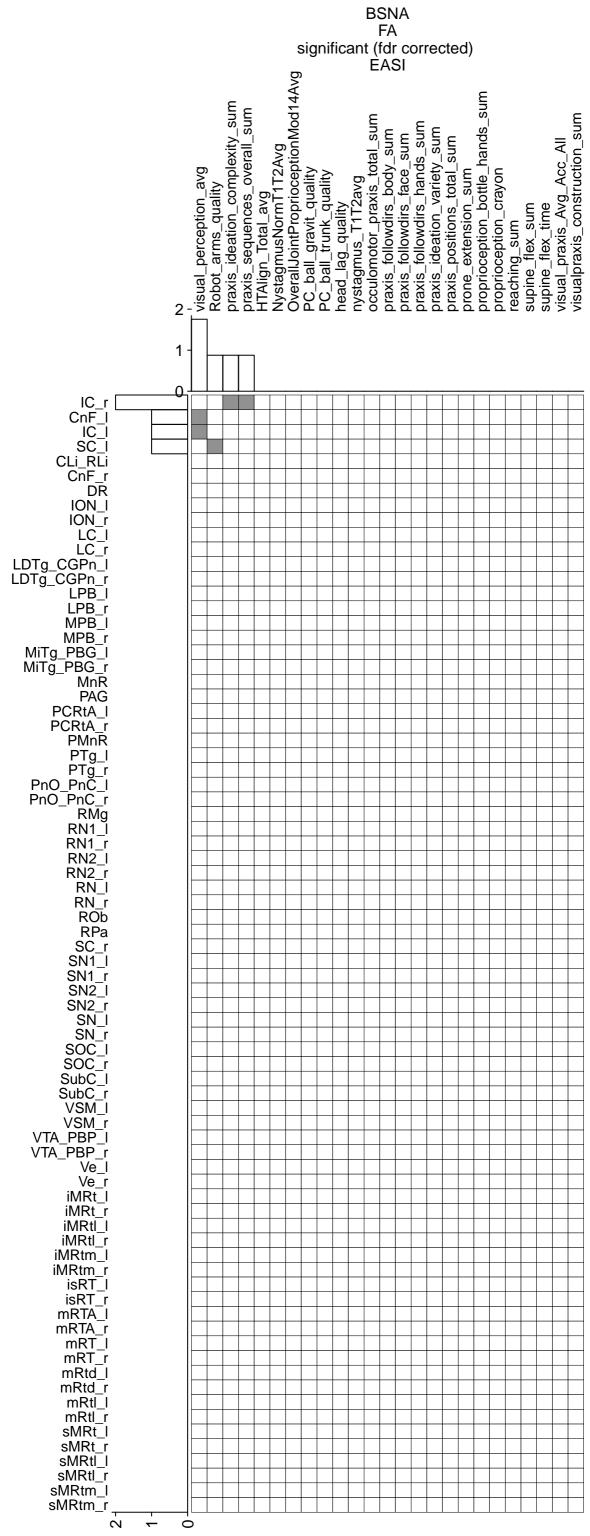
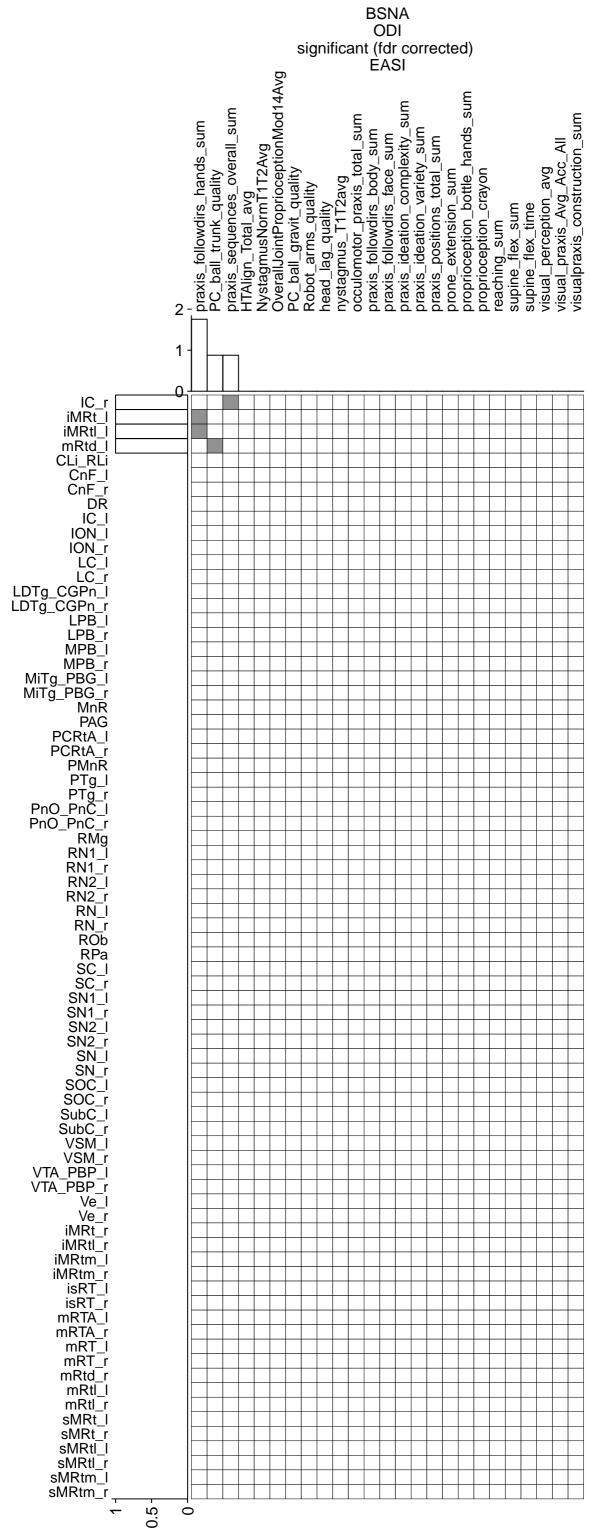
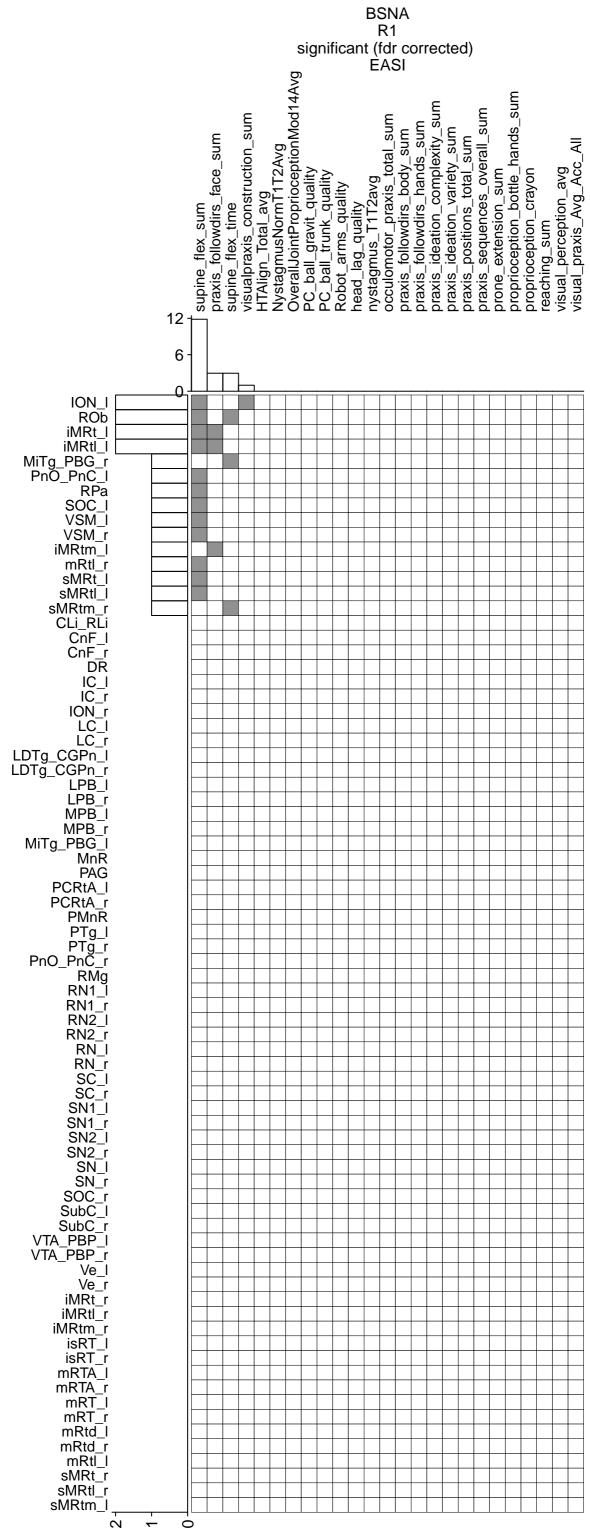
BSNA AD significant (fdr corrected) **EASI** Overall Joint Proprioception Mod 14 Avg proprioception_bottle_hands_sum praxis_ideation_complexity_sum praxis_sequences_overall_sum visualpraxis_construction_sum occulomotor_praxis_total_sum praxis_followdirs_hands_sum praxis_followdirs_body_sum praxis_ideation_variety_sum praxis_followdirs_face_sum praxis_positions_total_sum HTAlign_Total_avg NystagmusNormT1T2Avg visual_praxis_Avg_Acc_Al visual_perception_avg PC_ball_gravit_quality PC_ball_trunk_quality prone_extension_sum proprioception_crayon nystagmus_T1T2avg Robot_arms_quality head_lag_quality supine_flex_time supine_flex_sum reaching_sum 0 CLi_RLi CnF_I CnF_r DR IC_I IC_r ION_I ION_r LC LC_r LC_r LDTg_CGPn_I LDTg_CGPn_r LPB_I LPB_r MPB_I MPB_r MiTg_PBG_I MiTg_PBG_r MnR **PAG** PCRtA_I PCRtA_r PMnR PTg_l PTg_r PnO_PnC_l PnO_FnC_r PnO_PnC_r RMg RN1_Ĭ RN1_r RN2_I N2_I RN_I RN_r ROb RPa SC_I SC_r SN1_I SN1_r SN2_I SN2_I RN2_r SN2_r SN_I SN_r SOC_I SOC_r SubC_l SubC_r VSM_l VSM_r VTA_PBP PBP Ve Ve _r **iMRt** iMRt r iMRtl_I iMRtl_r iMRtm_I iMRtm_r isRT_I isRT_r mRTA_I mRTA_r nkı, mRT_I PT_r mRT. mRtd I mRtd_r $mRtl_l$ mRtl_r sMRt_I sMRt_r sMRtl I sMRtl_r sMRtm_I sMRtm_r 0



BSNA ICVF significant (fdr corrected) **EASI** Overall Joint Proprioception Mod 14 Avg proprioception_bottle_hands_sum praxis_ideation_complexity_sum praxis_sequences_overall_sum visualpraxis_construction_sum occulomotor_praxis_total_sum praxis_followdirs_hands_sum praxis_followdirs_body_sum praxis_ideation_variety_sum praxis_followdirs_face_sum praxis_positions_total_sum HTAlign_Total_avg NystagmusNormT1T2Avg visual_praxis_Avg_Acc_Al visual_perception_avg PC_ball_gravit_quality PC_ball_trunk_quality prone_extension_sum proprioception_crayon nystagmus_T1T2avg Robot_arms_quality head_lag_quality supine_flex_time supine_flex_sum reaching_sum 0 CLi_RLi CnF_I CnF_r DR IC_I IC_r ION_I ION_r LC LC_r LC_r LDTg_CGPn_I LDTg_CGPn_r LPB_I LPB_r MPB_I MPB_r MiTg_PBG_I MiTg_PBG_r MnR **PAG** PCRtA_I PCRtA_r PMnR PIVILIN PTg_I PTg_r PnO_PnC_I PnO_PnC_r RMg RN1_Ĭ RN1_r RN2_I N2_I RN_I RN_r ROb RPa SC_I SC_r SN1_I SN1_r SN2_I SN2_I RN2_r SN2_r SN_I SN_r SOC_I SOC_r SubC_l SubC_r VSM_l VSM_r VTA_PBP PBP Ve Ve _r **iMRt** iMRt r iMRtl_I iMRtl_r iMRtm_I iMRtm_r isRT_I isRT_r mRTA_I mRTA_r nkı, mRT_I PT_r mRT. mRtd I mRtd_r $mRtl_l$ mRtl_r sMRt_I sMRt_r sMRtI I sMRtl_r sMRtm_I sMRtm_r 0

BSNA MD significant (fdr corrected) **EASI** Overall Joint Proprioception Mod 14 Avg proprioception_bottle_hands_sum praxis_ideation_complexity_sum praxis_sequences_overall_sum visualpraxis_construction_sum occulomotor_praxis_total_sum praxis_followdirs_hands_sum praxis_followdirs_body_sum praxis_ideation_variety_sum praxis_followdirs_face_sum praxis_positions_total_sum HTAlign_Total_avg NystagmusNormT1T2Avg visual_praxis_Avg_Acc_Al visual_perception_avg PC_ball_gravit_quality PC_ball_trunk_quality prone_extension_sum proprioception_crayon nystagmus_T1T2avg Robot_arms_quality head_lag_quality supine_flex_time supine_flex_sum reaching_sum 0 CLi_RLi CnF_I CnF_r DR IC_I IC_r ION_I ION_r LC LC_r LC_r LDTg_CGPn_I LDTg_CGPn_r LPB_I LPB_r MPB_I MPB_r MiTg_PBG_I MiTg_PBG_r MnR **PAG** PCRtA_I PCRtA_r PMnR PTg_l PTg_r PnO_PnC_l PnO_FnC_r PnO_PnC_r RMg RN1_Ĭ RN1_r RN2_I N2_I RN_I RN_r ROb RPa SC_I SC_r SN1_I SN1_r SN2_I SN2_I RN2_r SN2_r SN_I SN_r SOC_I SOC_r SubC_l SubC_r VSM_l VSM_r VTA_PBP PBP Ve Ve _r **iMRt** iMRt r iMRtl_I iMRtl_r iMRtm_I iMRtm_r isRT_I isRT_r mRTA_I mRTA_r nkı, mRT_I PT_r mRT. mRtd I mRtd_r $mRtl_l$ mRtl_r sMRt_I sMRt_r sMRtl I sMRtl_r sMRtm_I sMRtm_r 0





BSNA RD significant (fdr corrected) **EASI** Overall Joint Proprioception Mod 14 Avg proprioception_bottle_hands_sum praxis_ideation_complexity_sum praxis_sequences_overall_sum visualpraxis_construction_sum occulomotor_praxis_total_sum praxis_followdirs_hands_sum praxis_followdirs_body_sum praxis_ideation_variety_sum praxis_followdirs_face_sum praxis_positions_total_sum HTAlign_Total_avg NystagmusNormT1T2Avg visual_praxis_Avg_Acc_Al visual_perception_avg PC_ball_gravit_quality PC_ball_trunk_quality prone_extension_sum proprioception_crayon nystagmus_T1T2avg Robot_arms_quality head_lag_quality supine_flex_time supine_flex_sum reaching_sum 0 CLi_RLi CnF_I CnF_r DR IC_I IC_r ION_I ION_r LC LC_r LC_r LDTg_CGPn_I LDTg_CGPn_r LPB_I LPB_r MPB_I MPB_r MiTg_PBG_I MiTg_PBG_r MnR **PAG** PCRtA_I PCRtA_r PMnR PTg_l PTg_r PnO_PnC_l PnO_FnC_r PnO_PnC_r RMg RN1_Ĭ RN1_r RN2_I RN2_r RN RN_r RN_r ROb RPa SC_I SC_r SN1_I SN1_r SN2_I SN2_r SN2_r SN_I SN_r SOC_I SOC_r SubC_l SubC_r VSM_l VSM_r VTA_PBP PBP Ve Ve _r **iMRt** iMRt r iMRtl_I iMRtl_r iMRtm_I iMRtm_r isRT_I isRT_r mRTA_I mRTA_r nkı, mRT_I PT_r mRT. mRtd I mRtd_r $mRtl_l$ mRtl_r sMRt_I sMRt_r sMRtl I sMRtl_r sMRtm_I sMRtm_r 0

