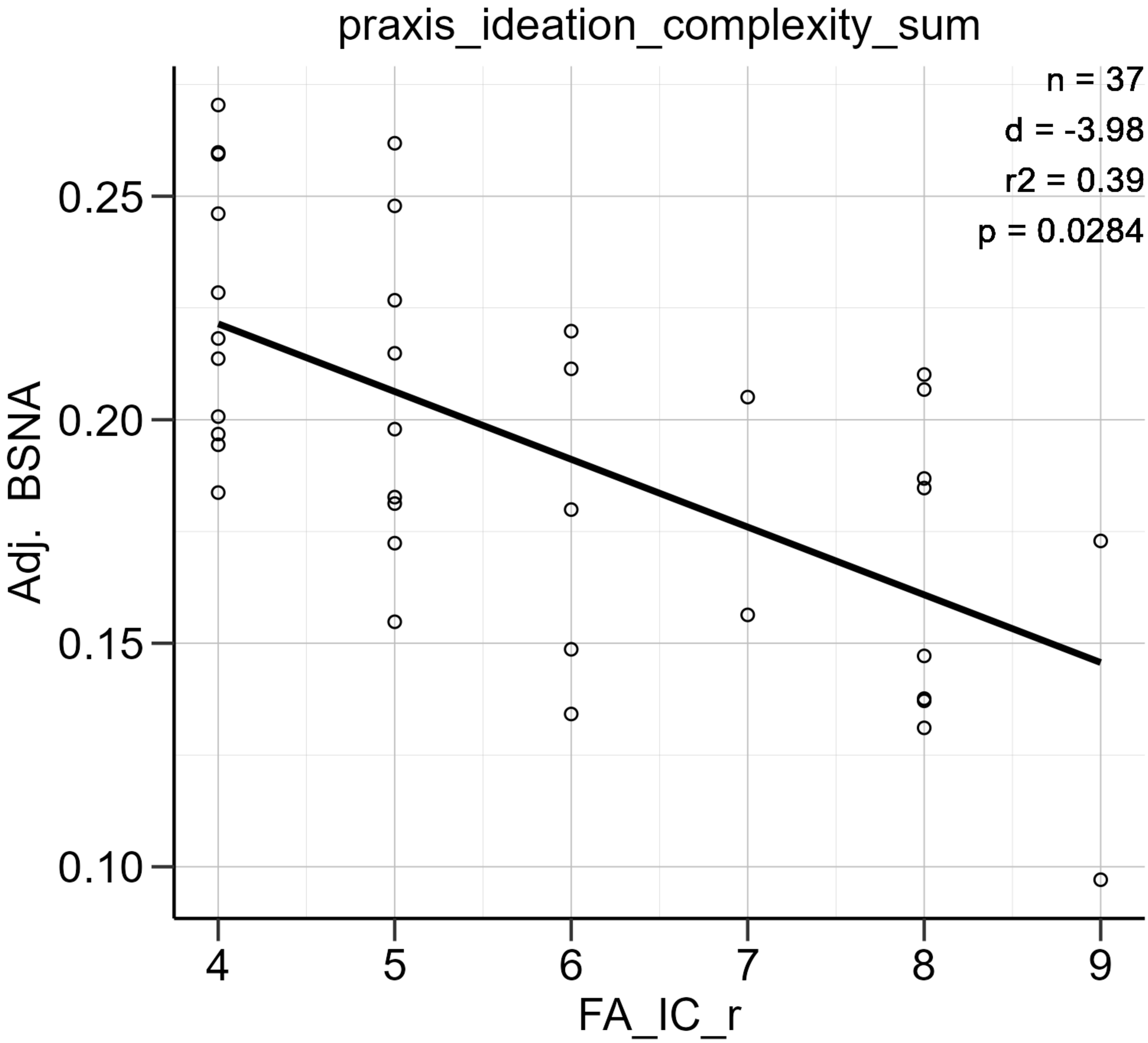
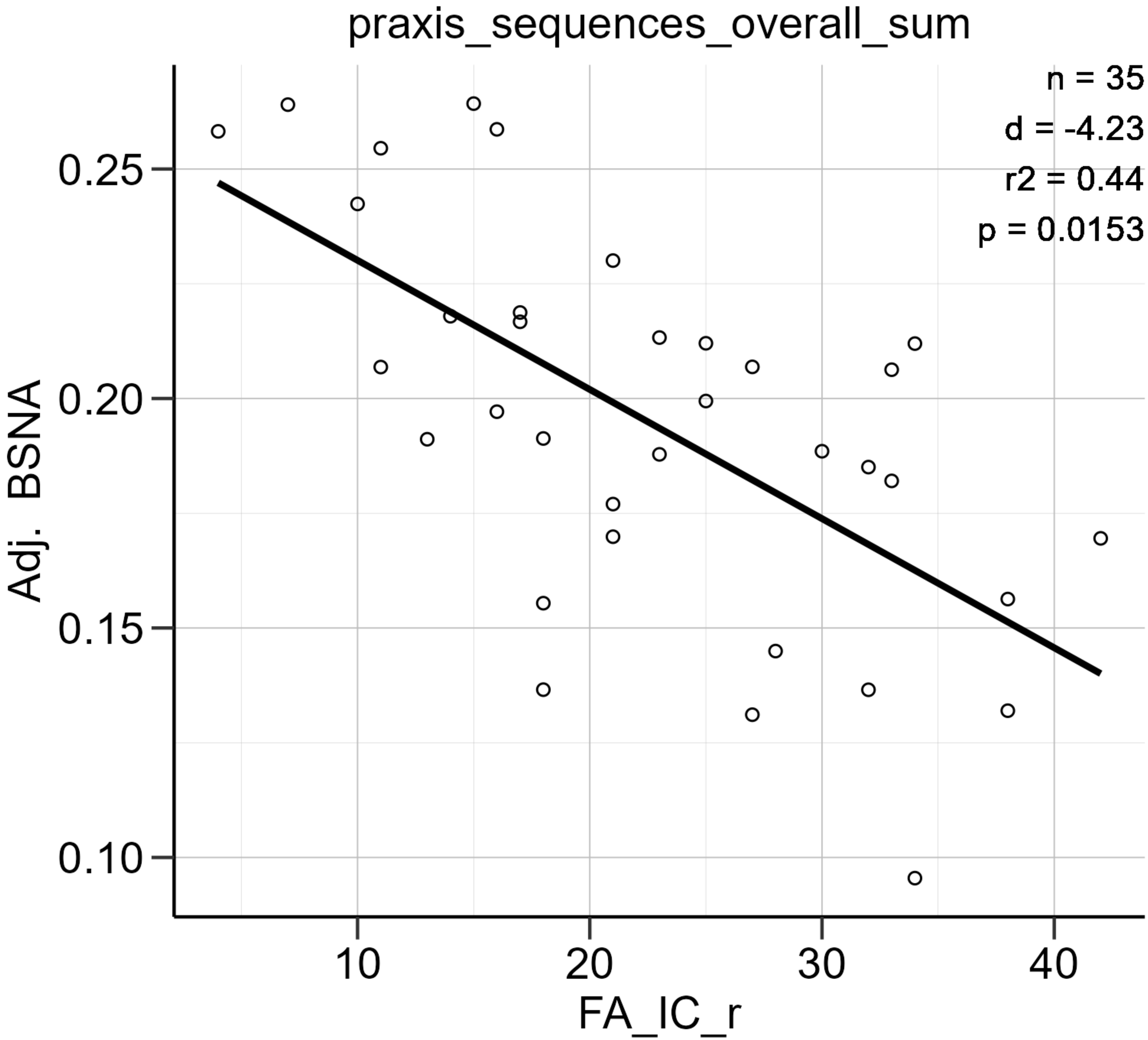
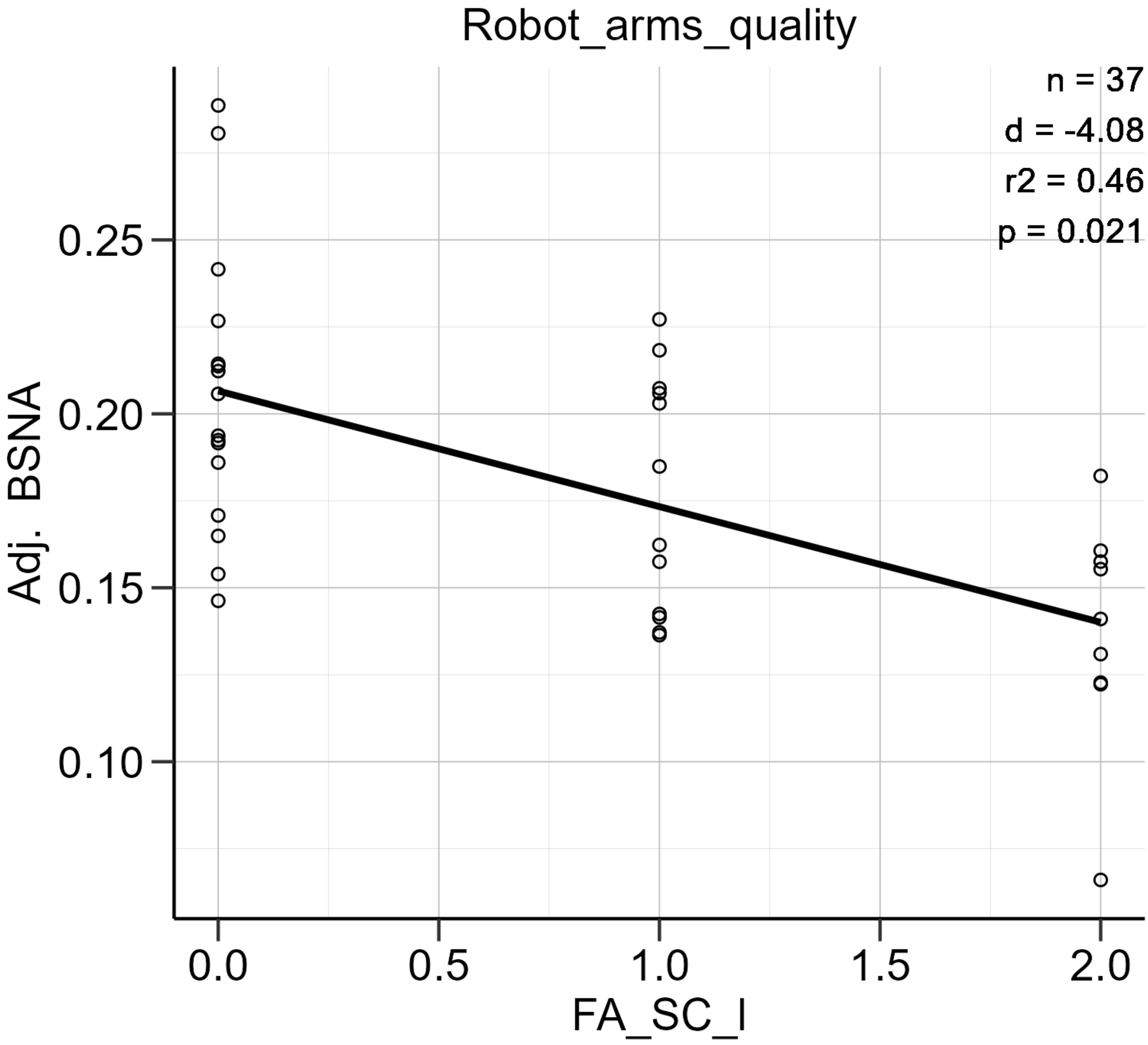
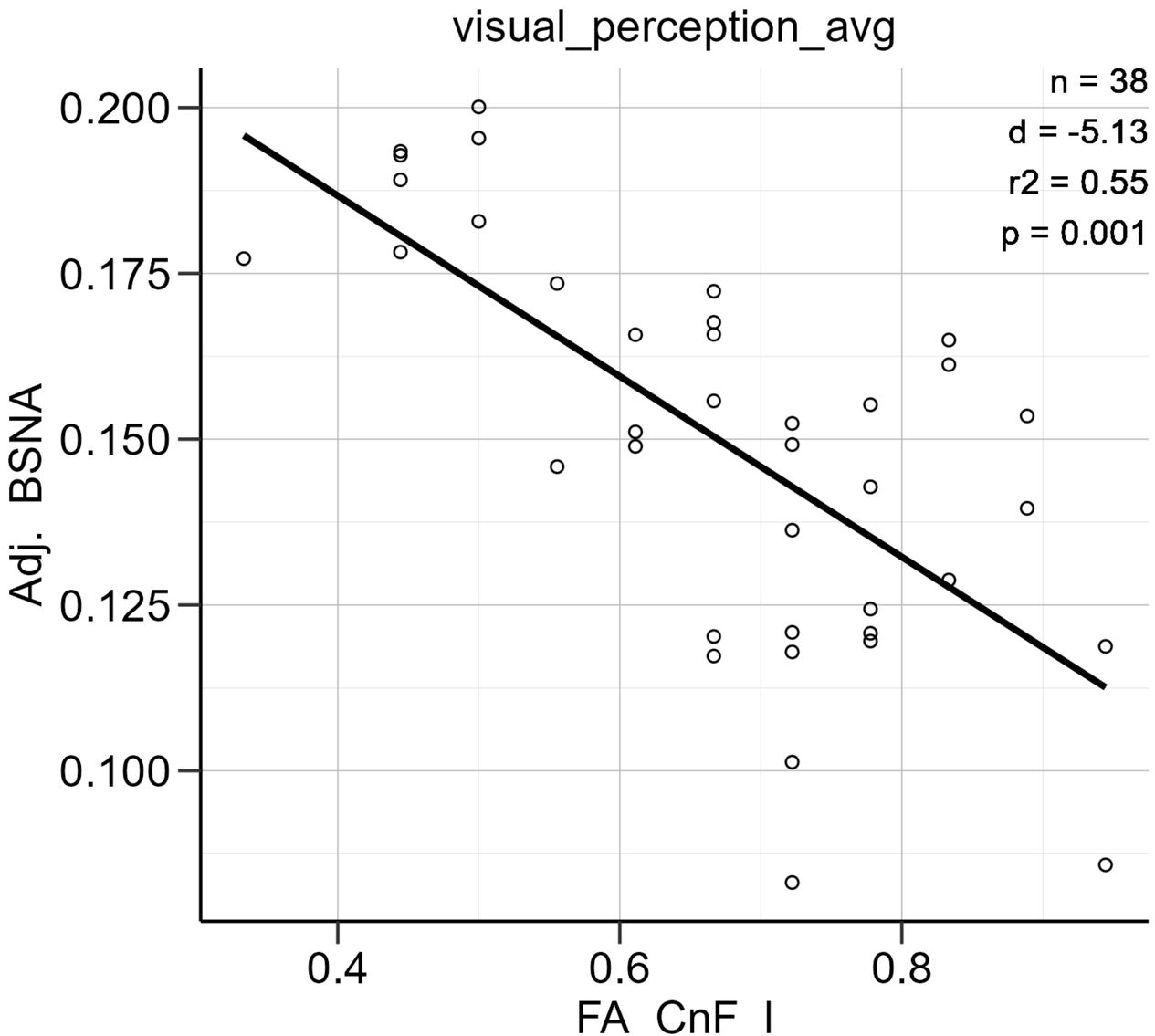
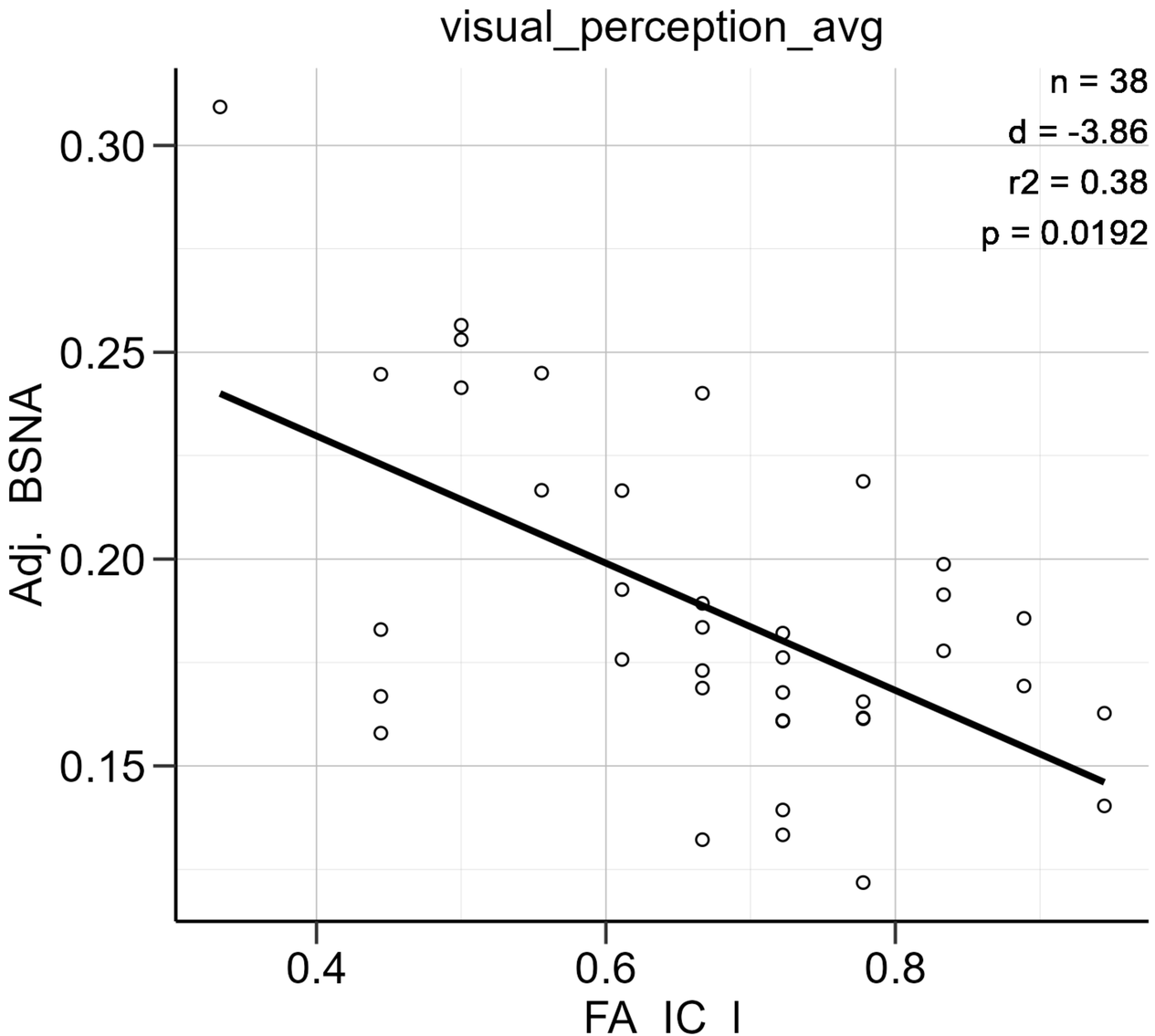

praxis_ideation_complexity_sum
n = 37
d = -3.98
r2 = 0.39
p = 0.0284
Adj. BSNA
0.25
0.20
0.15
0.10
4
5
6
7
8
9
FA_IC_r

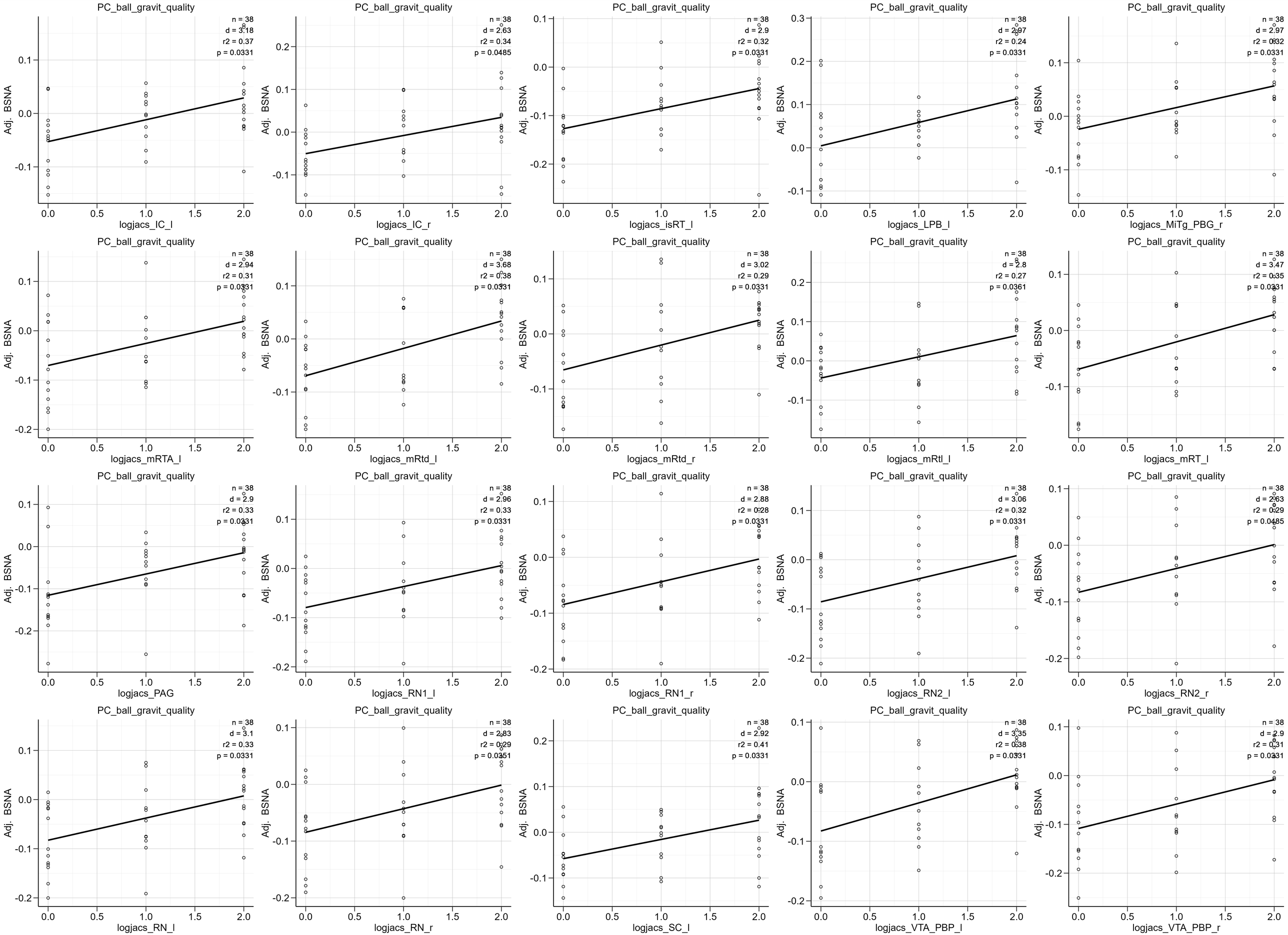

praxis_sequences_overall_sum
n = 35
d = -4.23
r2 = 0.44
p = 0.0153
Adj. BSNA
0.25
0.20
0.15
0.10
10
20
30
40
FA_IC_r


Robot_arms_quality
n = 37
d = -4.08
r2 = 0.46
p = 0.021
Adj. BSNA
0.25
0.20
0.15
0.10
0.0
0.5
1.0
1.5
2.0
FA_SC_I

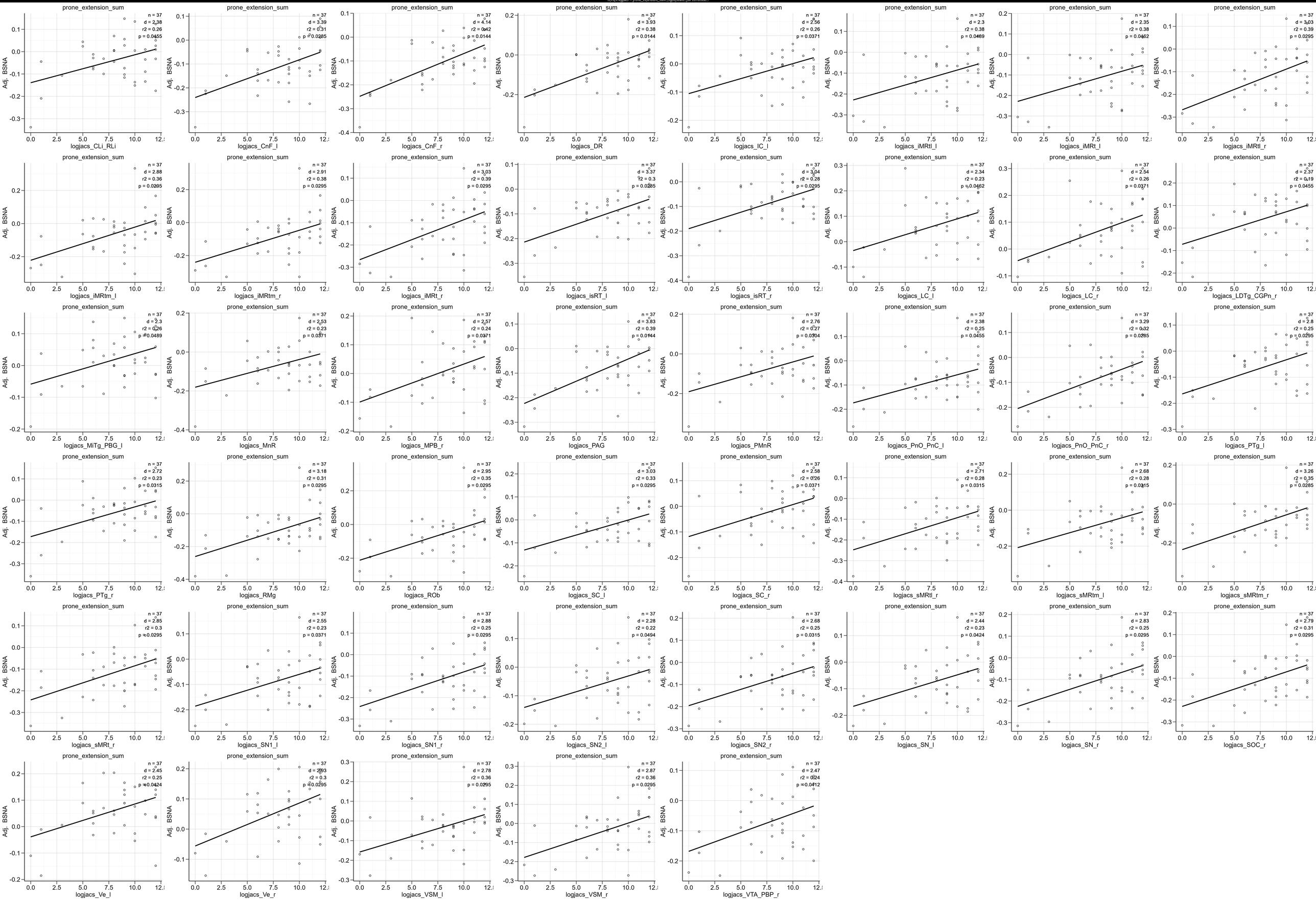

visual_perception_avg
n = 38
d = -5.13
r2 = 0.55
p = 0.001
Adj. BSNA
0.200
0.175
0.150
0.125
0.100
0.4
0.6
0.8
FA_CnF_l


visual_perception_avg
n = 38
d = -3.86
r2 = 0.38
p = 0.0192
Adj. BSNA
0.30
0.25
0.20
0.15
0.4
0.6
0.8
FA_IC_l

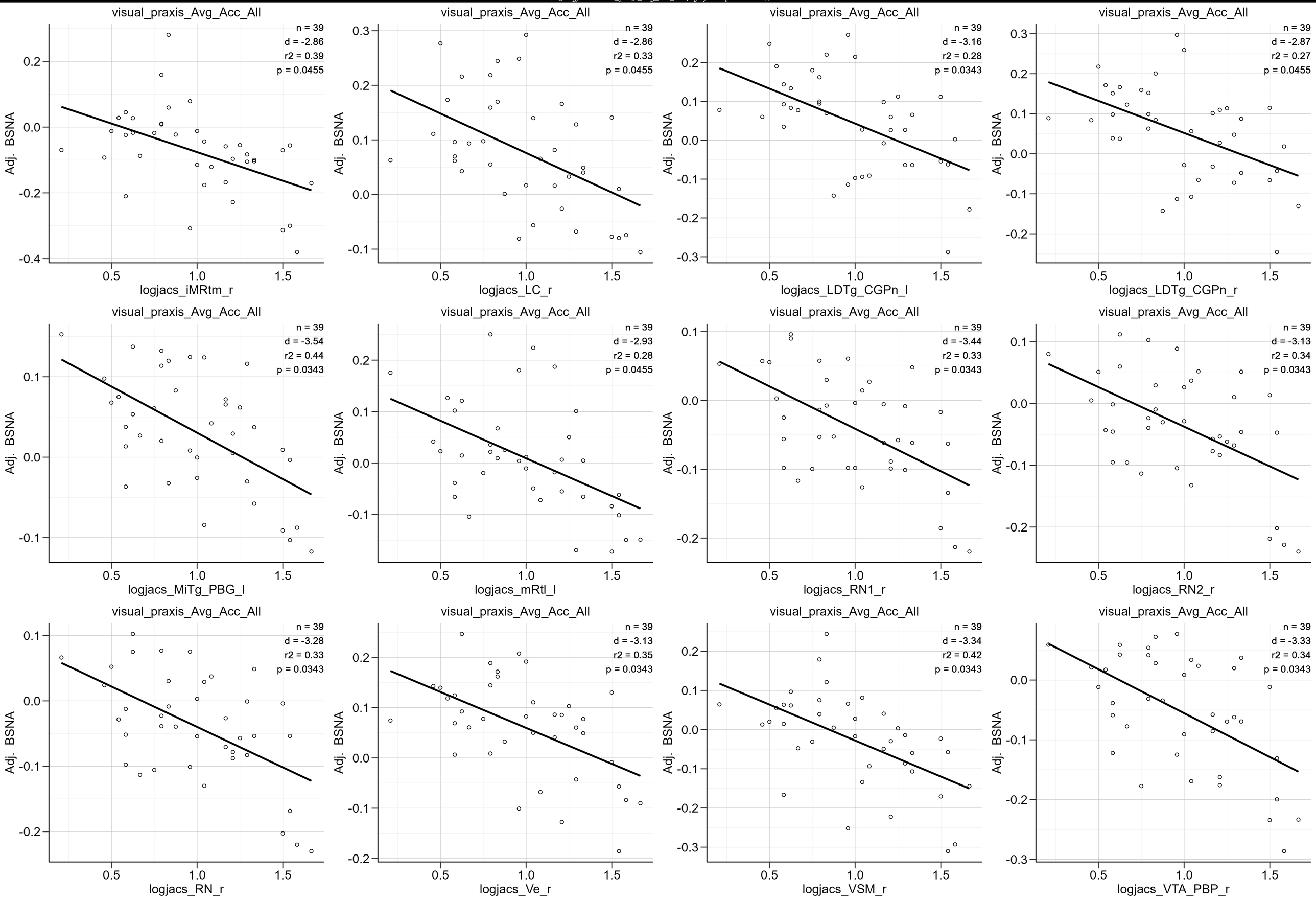
BSNA logjacs ~ PC_ball_gravit_quality (significant (fdr corrected))

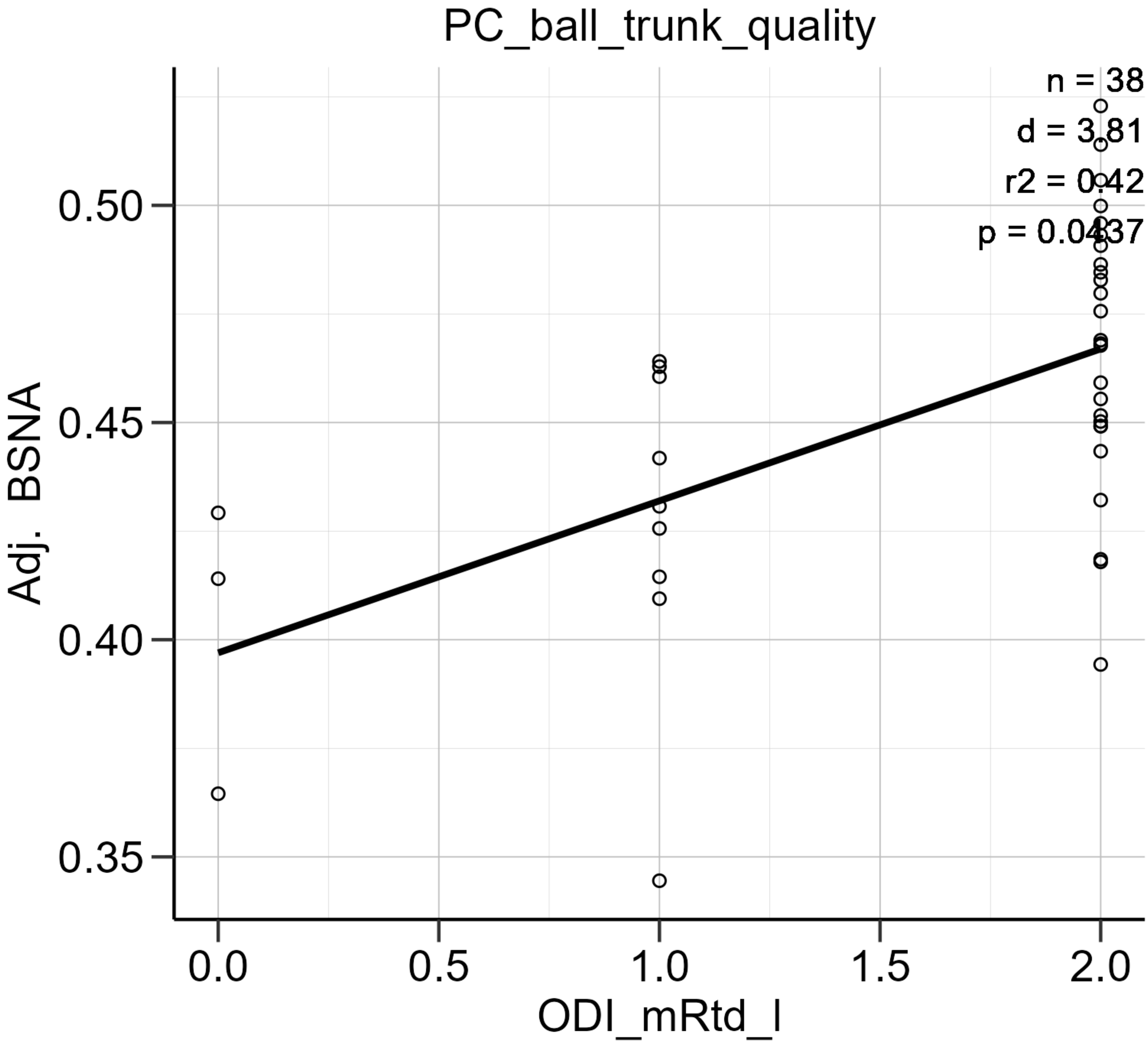


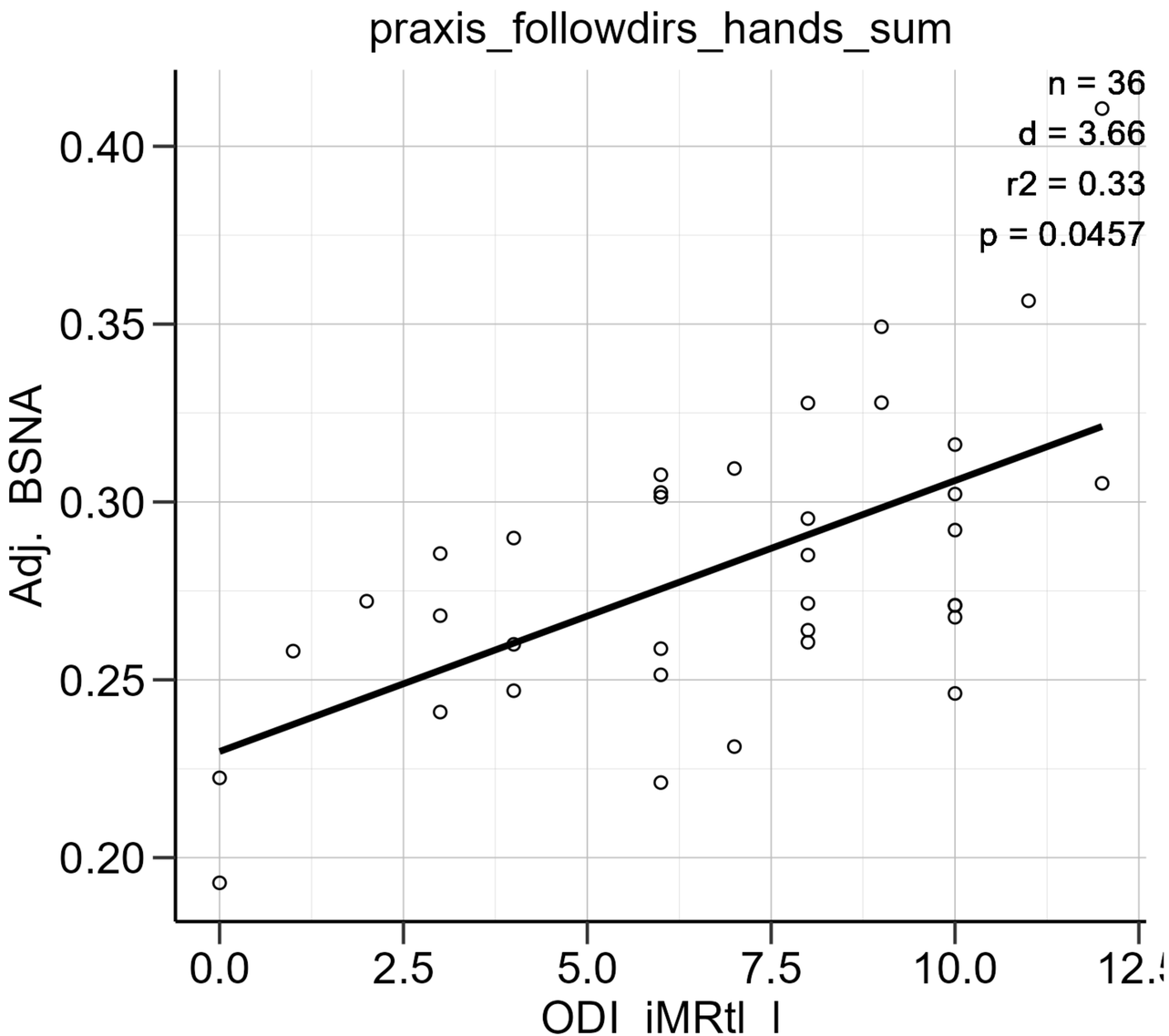
BSNA (logjacs ~ prone_extension_sum (significant (fdr corrected))

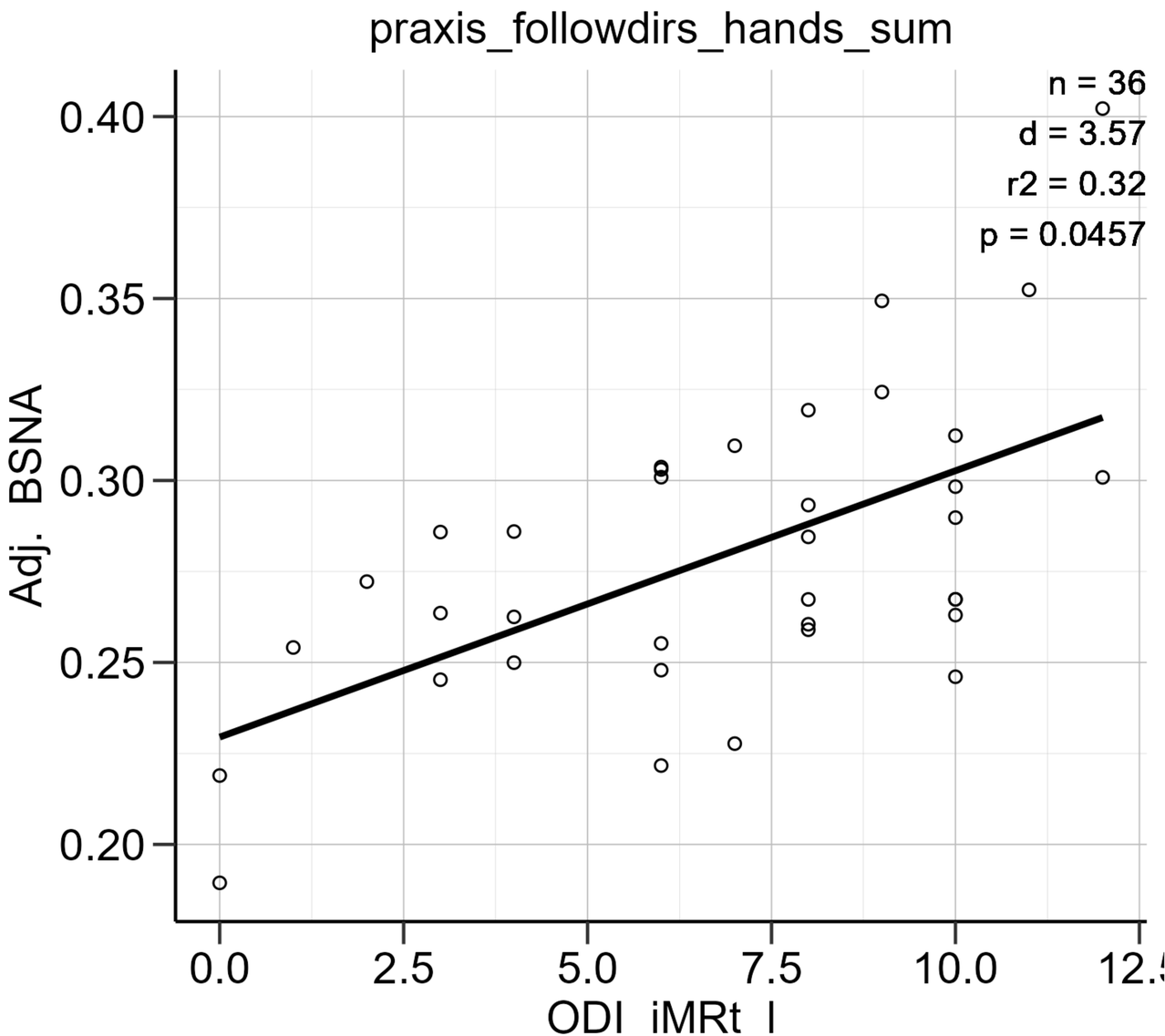


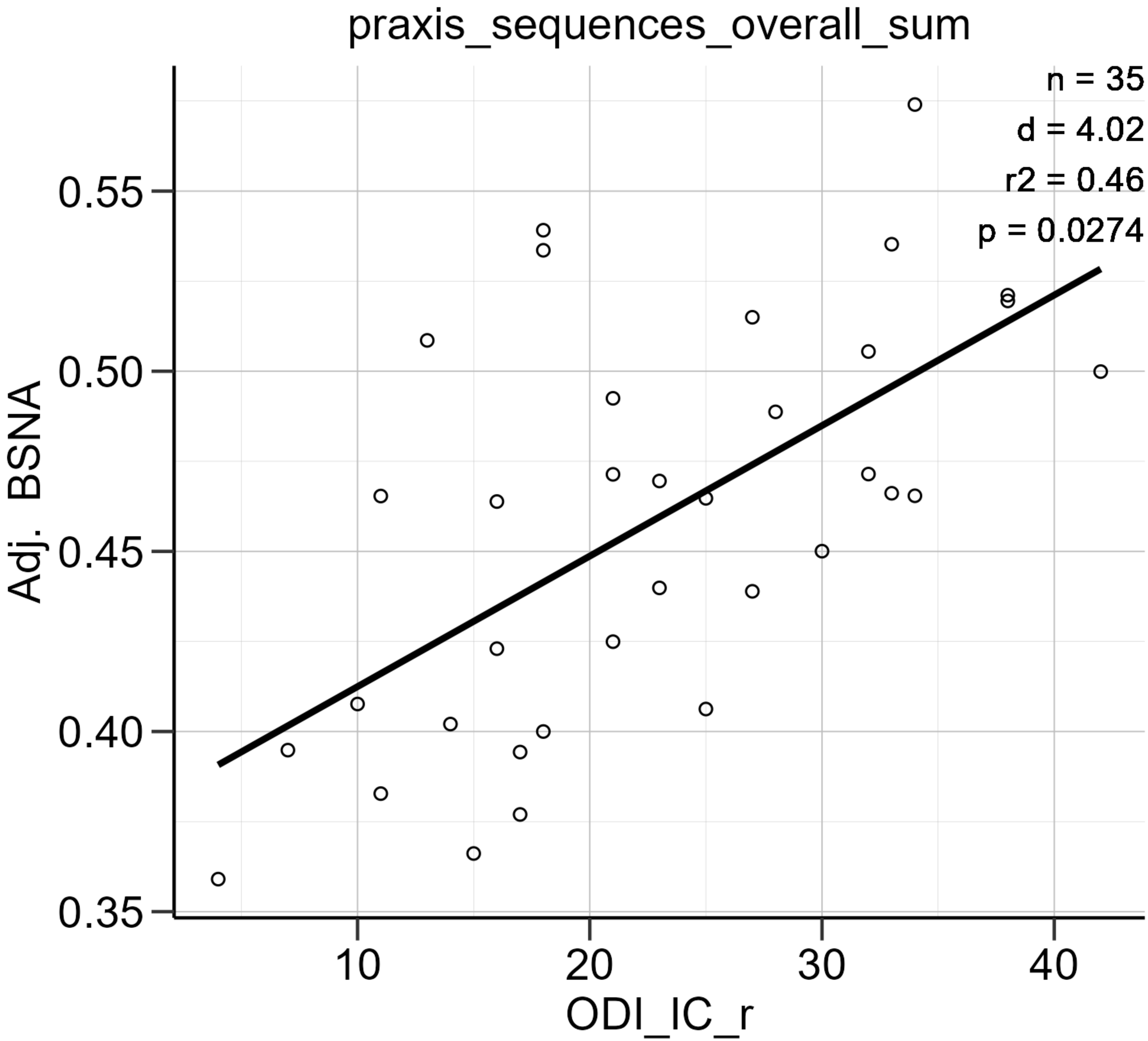
BSNA logjacs ~ visual_praxis_Avg_Acc_All (significant (fdr corrected))

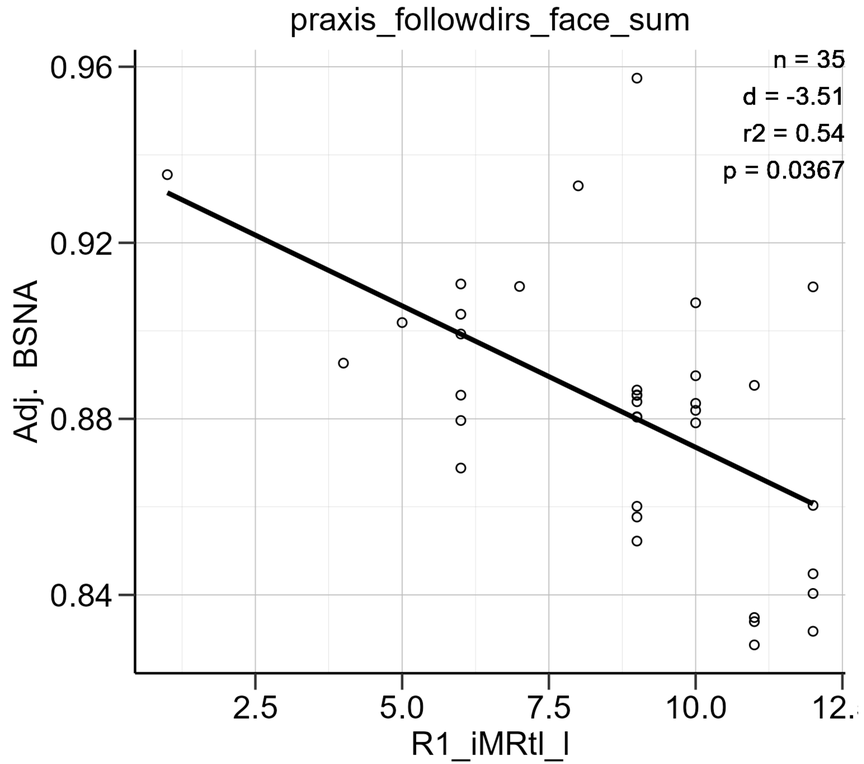


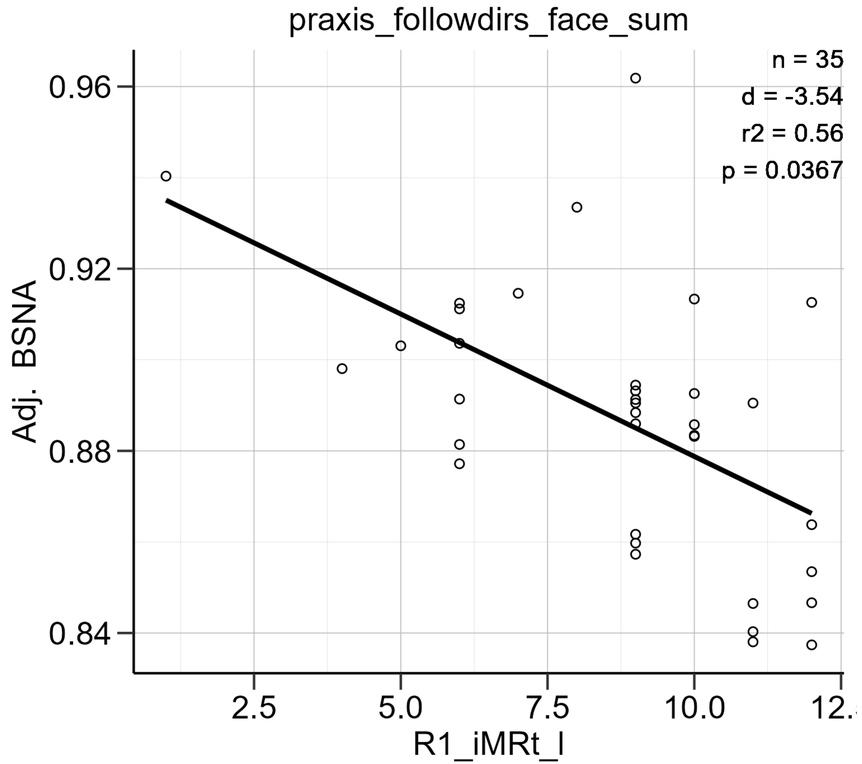

PC_ball_trunk_quality
n = 38
d = 3.81
r2 = 0.42
p = 0.0437
0.50
0.45
0.40
0.35
Adj. BSNA
0.0
0.5
1.0
1.5
2.0
ODI_mRtd_I

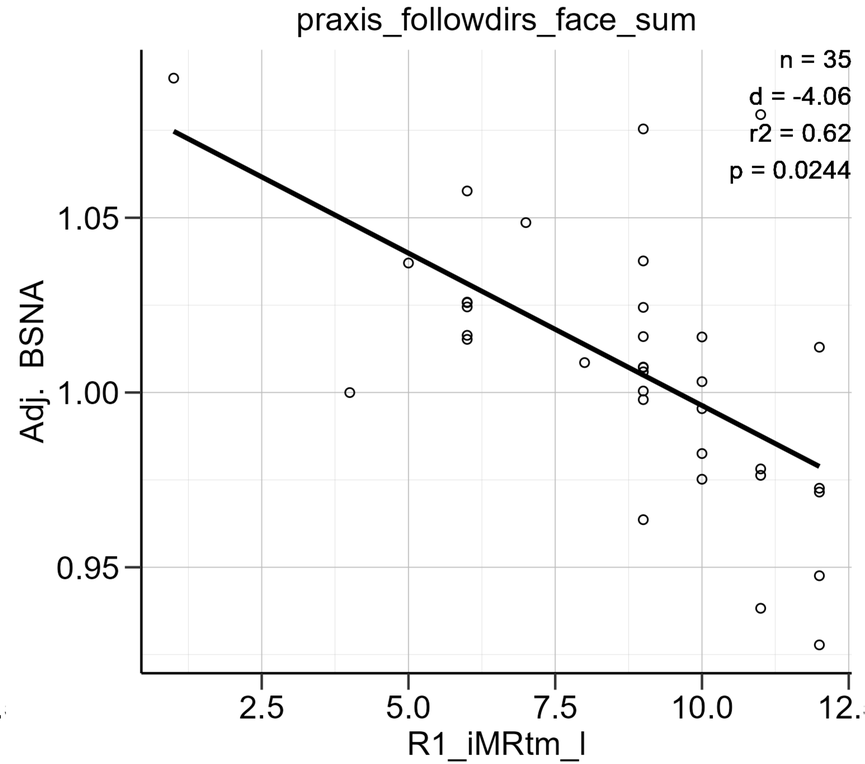

praxis_followdirs_hands_sum
n = 36
d = 3.66
r2 = 0.33
p = 0.0457
Adj. BSNA
0.40
0.35
0.30
0.25
0.20
0.0
2.5
5.0
7.5
10.0
ODI_iMRtl_l


praxis_followdirs_hands_sum
n = 36
d = 3.57
r2 = 0.32
p = 0.0457
Adj. BSNA
0.40
0.35
0.30
0.25
0.20
0.0
2.5
5.0
7.5
10.0
ODI_iMRt_l

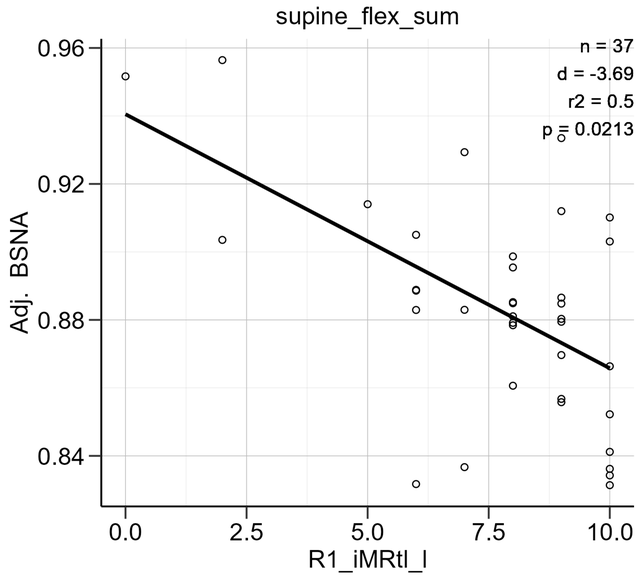

praxis_sequences_overall_sum
n = 35
d = 4.02
r2 = 0.46
p = 0.0274
Adj. BSNA
0.55
0.50
0.45
0.40
0.35
10
20
30
40
ODI_IC_r

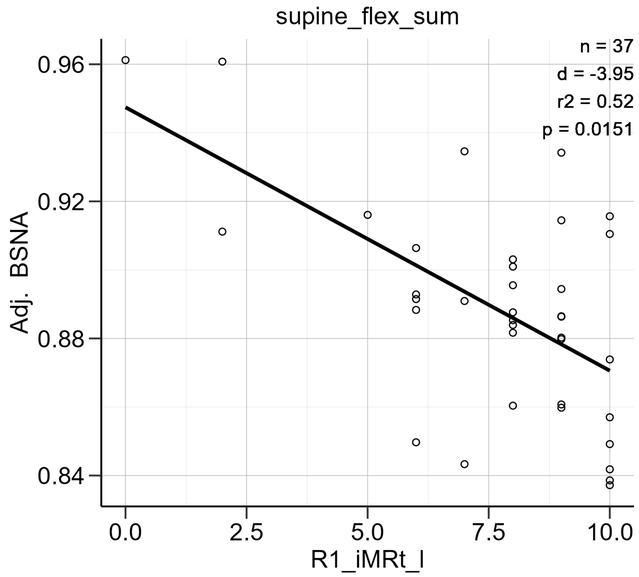

praxis_followdirs_face_sum
n = 35
d = -3.51
r2 = 0.54
p = 0.0367
Adj. BSNA
0.96
0.92
0.88
0.84
2.5
5.0
7.5
10.0
12.
R1_iMRtl_l

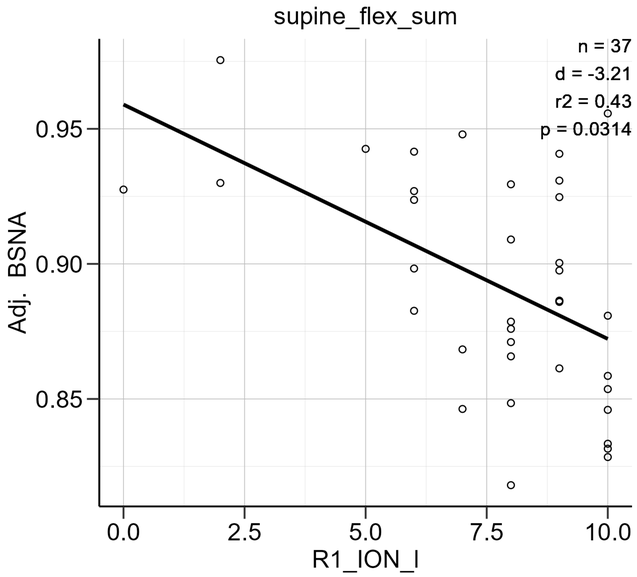

praxis_followdirs_face_sum
n = 35
d = -3.54
r2 = 0.56
p = 0.0367
Adj. BSNA
0.96
0.92
0.88
0.84
2.5
5.0
7.5
10.0
12.
R1_iMRt_l

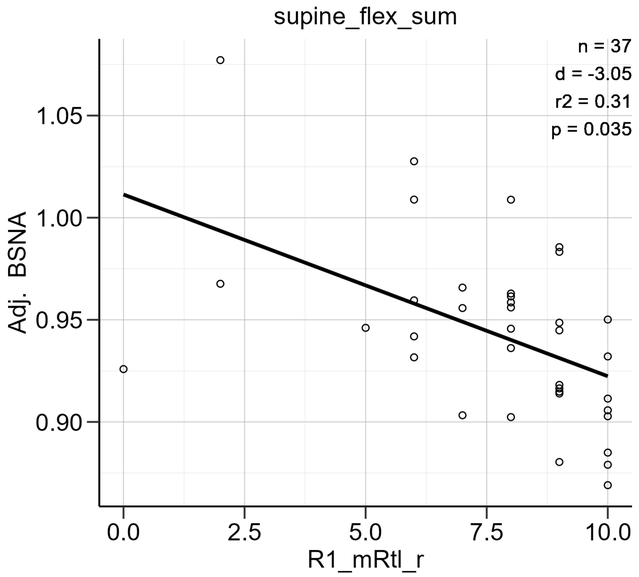

praxis_followdirs_face_sum
n = 35
d = -4.06
r2 = 0.62
p = 0.0244
Adj. BSNA
1.05
1.00
0.95
2.5
5.0
7.5
10.0
12.
R1_iMRtm_l

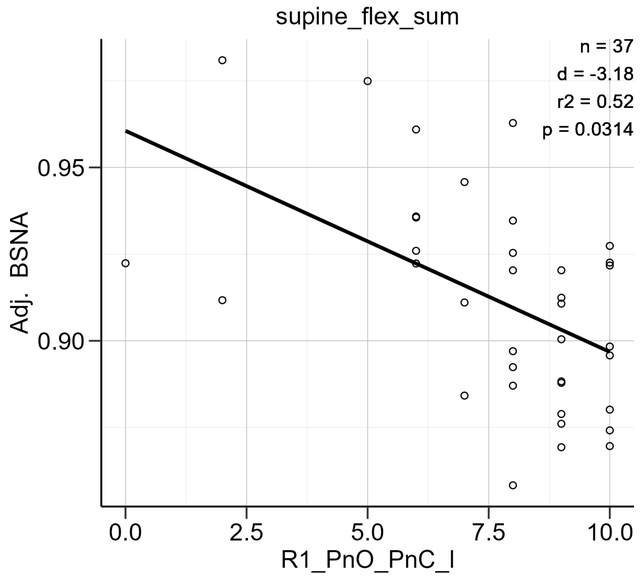
BSNA R1 ~ supine_flex_sum (significant (fdr corrected))

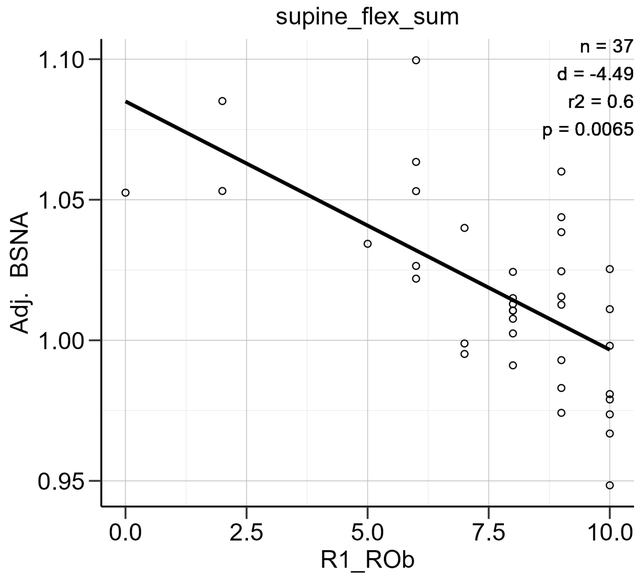


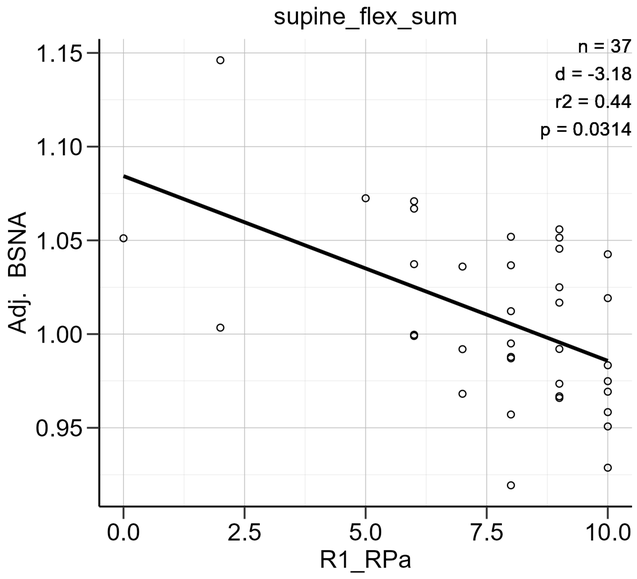


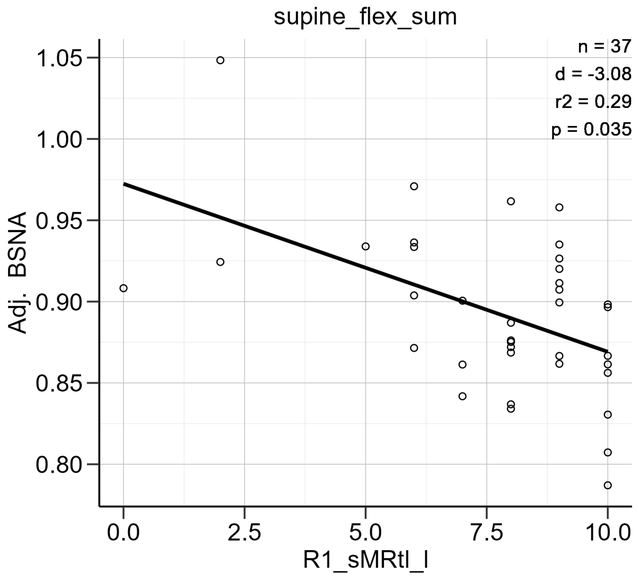


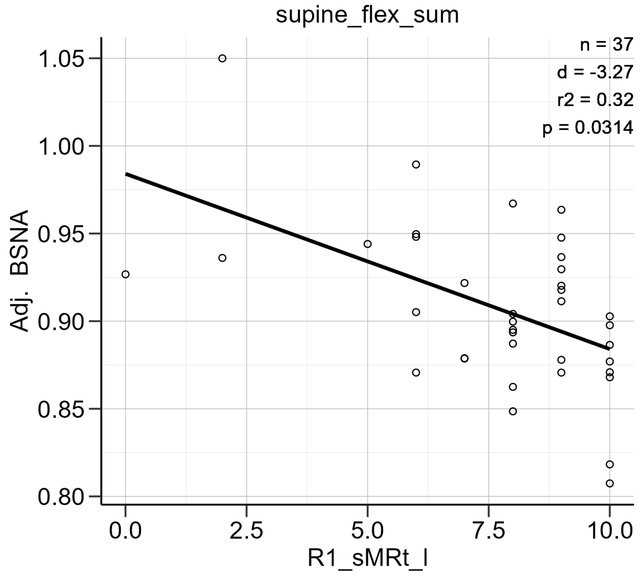


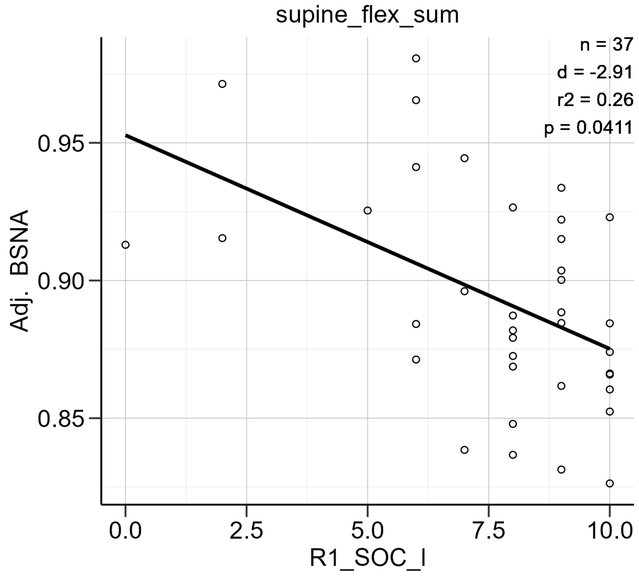


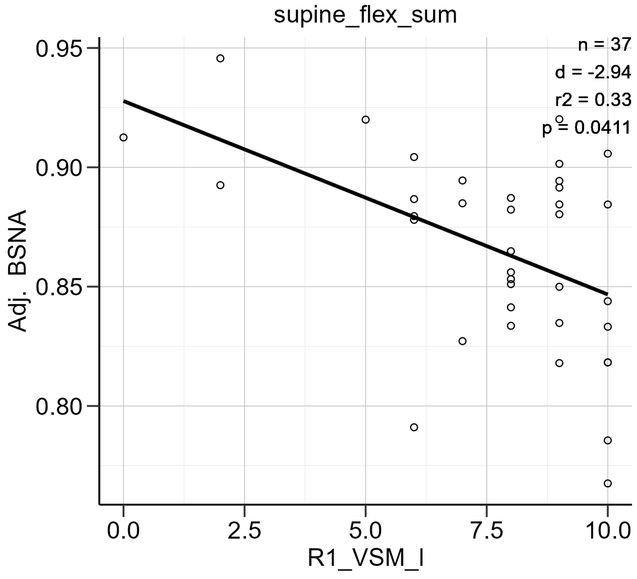


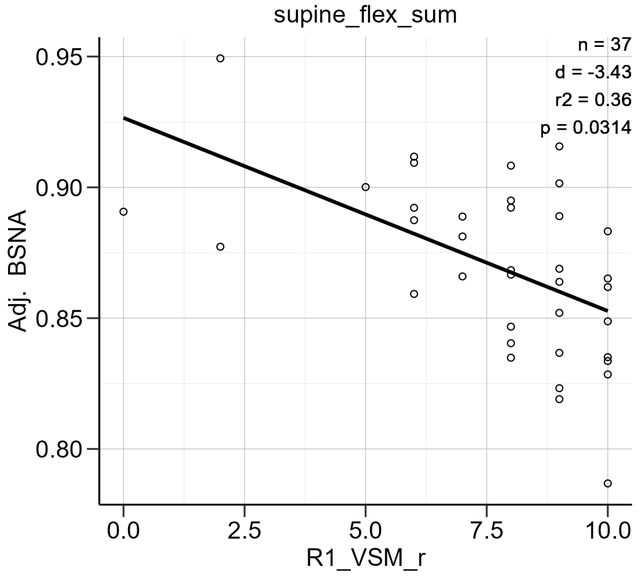




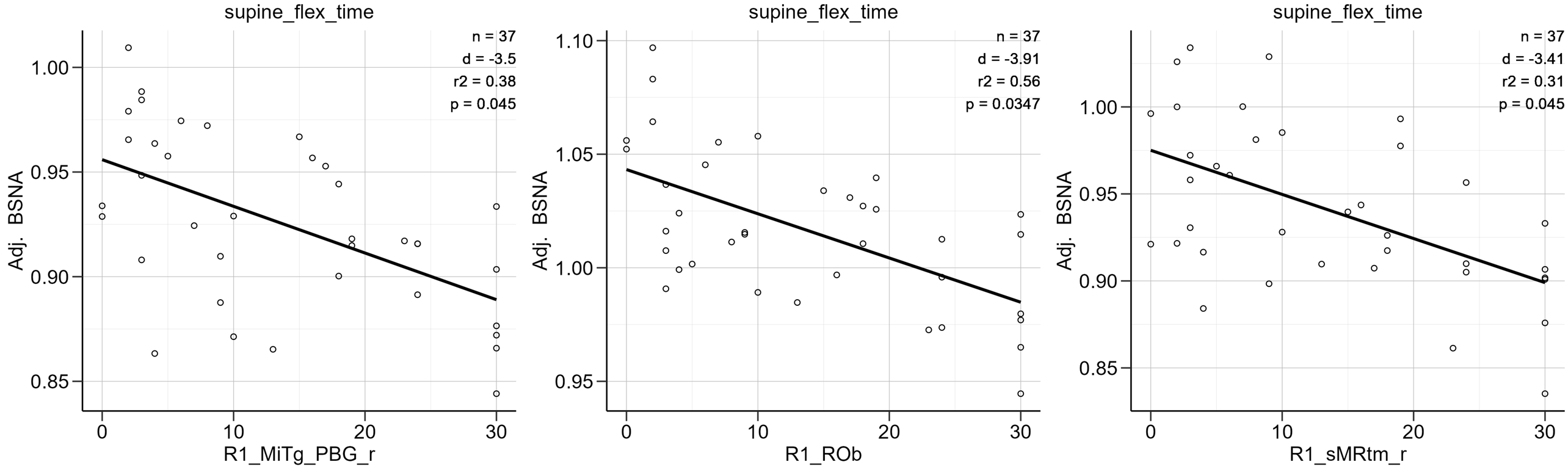


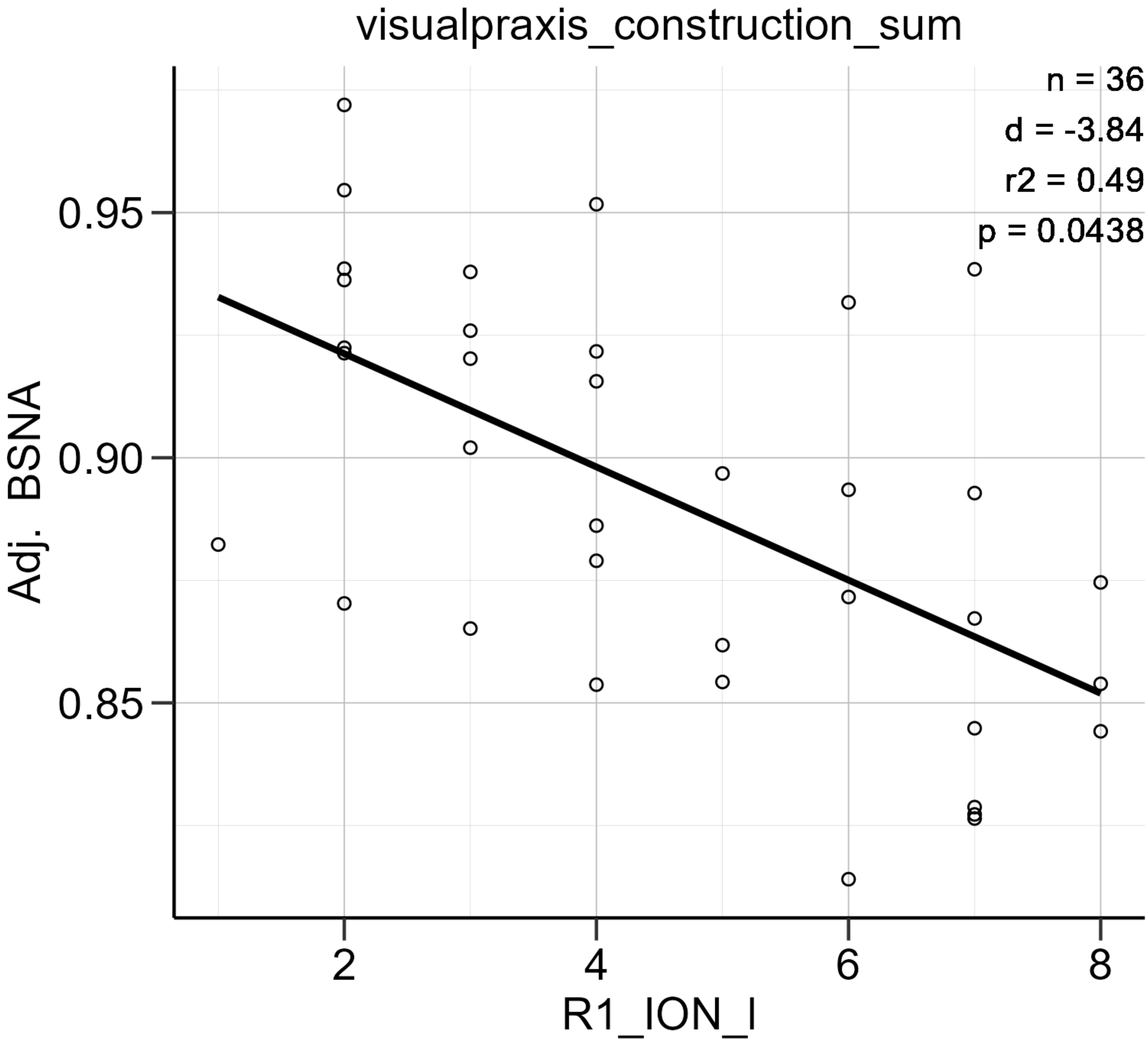


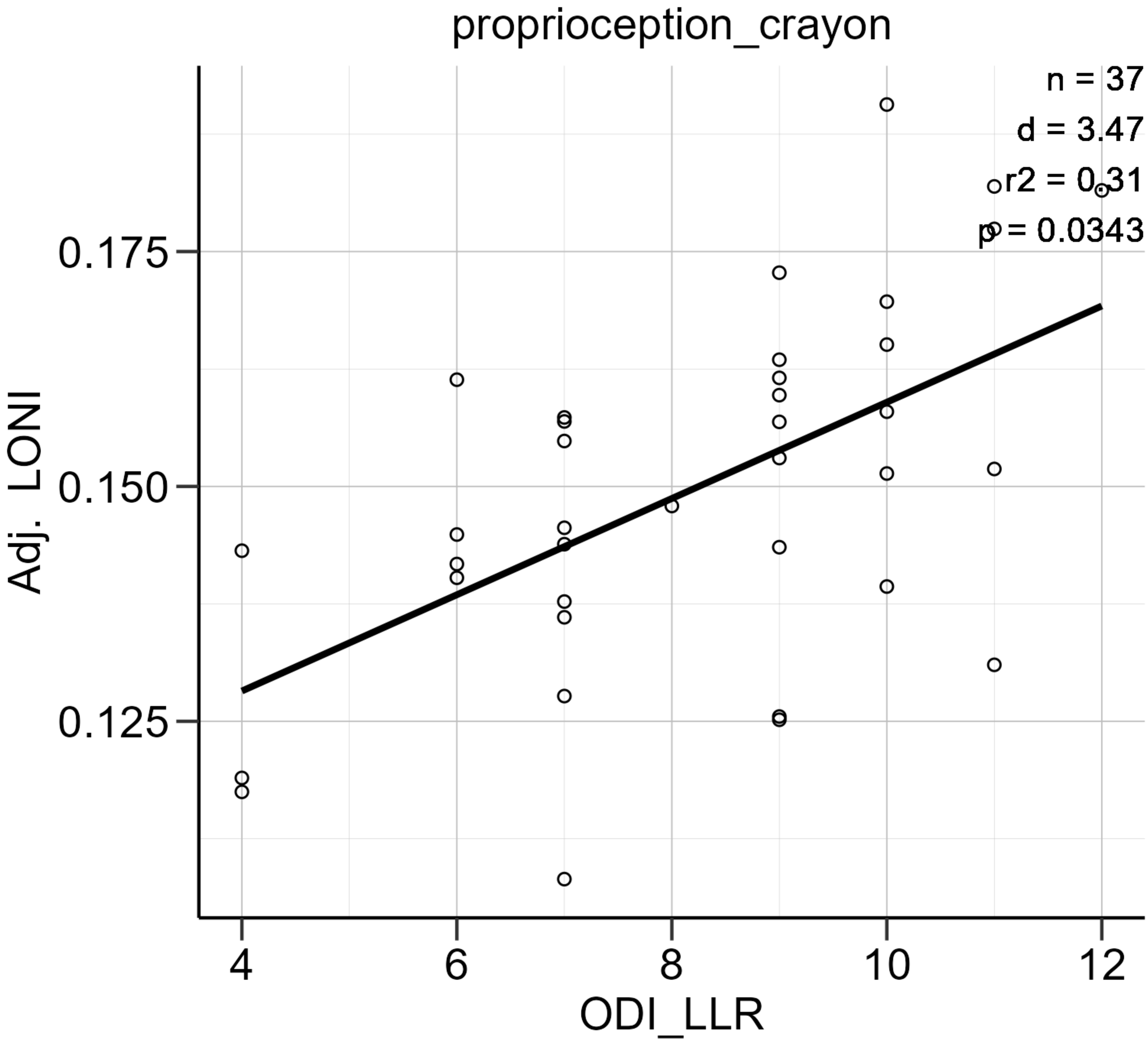




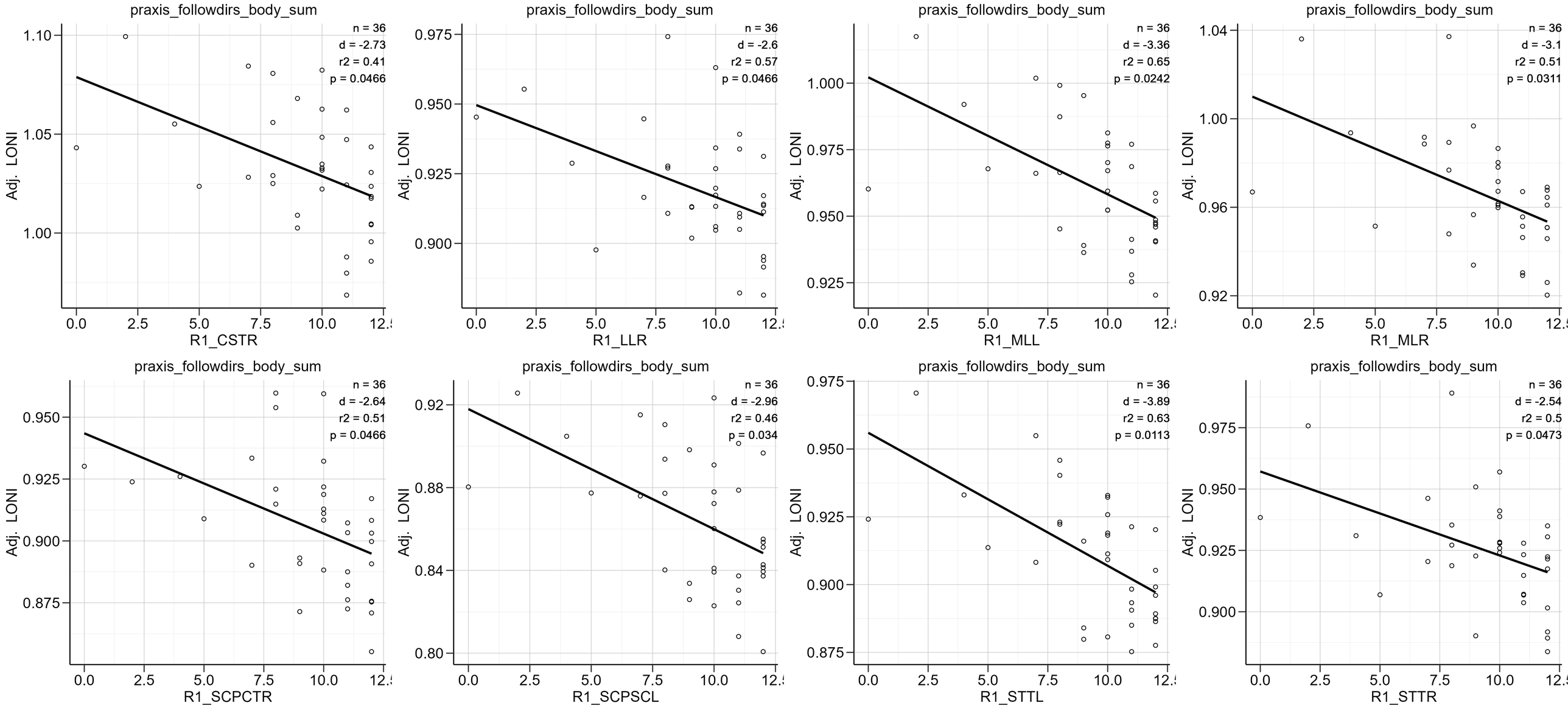
BSNA R1 ~ supine_flex_time (significant (fdr corrected))

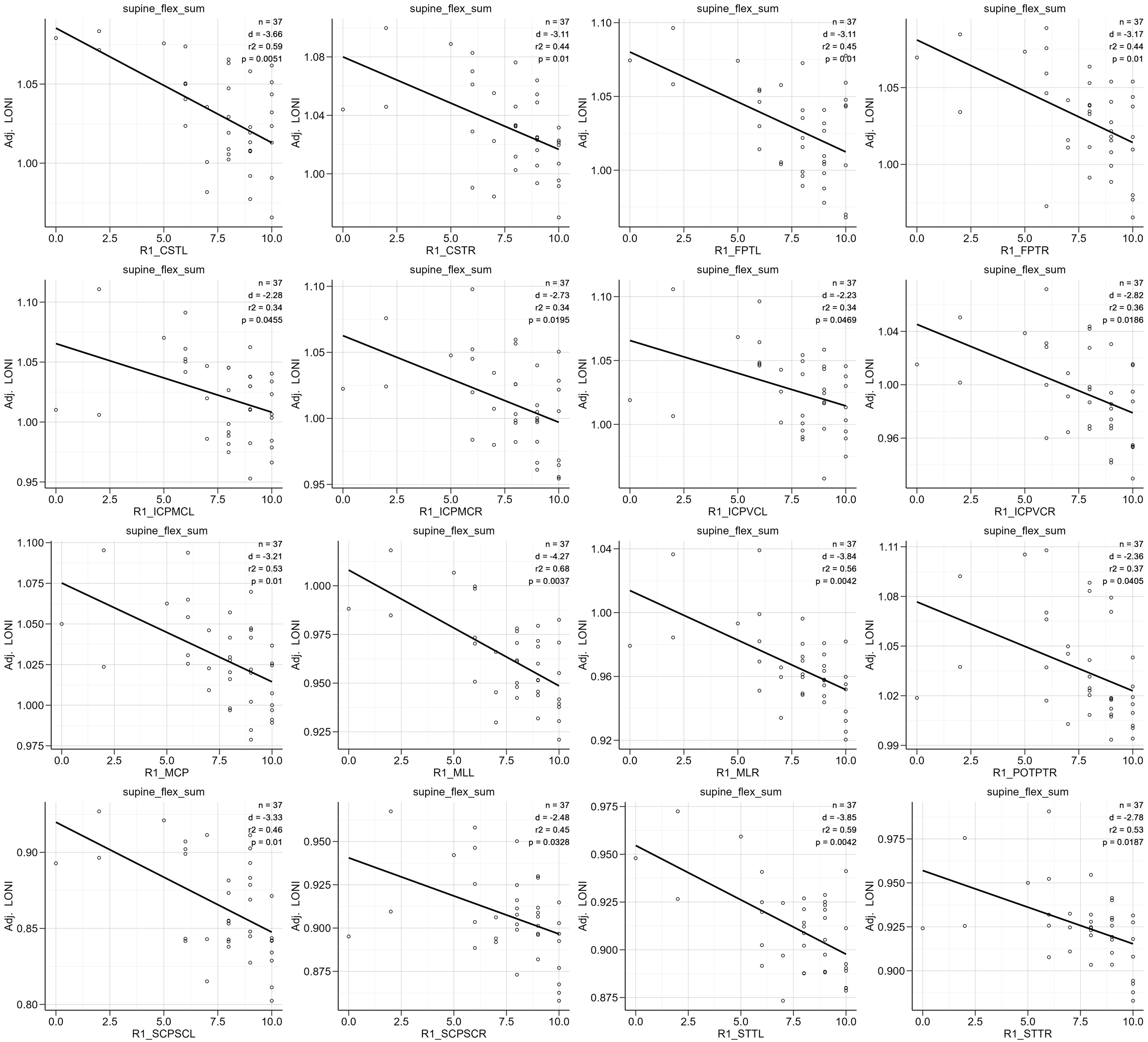


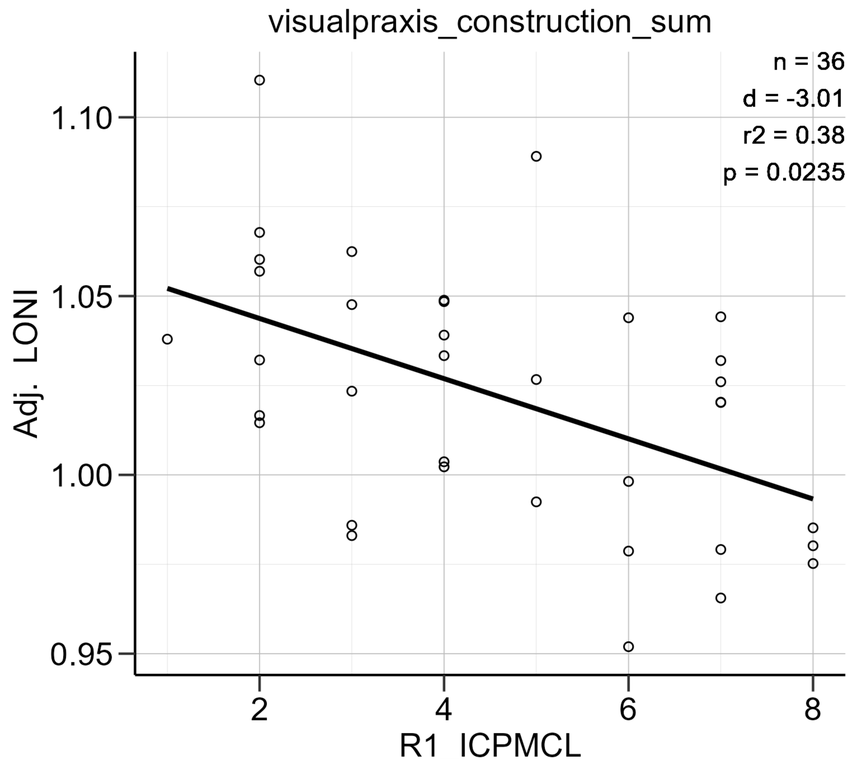

visualpraxis_construction_sum
n = 36
d = -3.84
r2 = 0.49
p = 0.0438
Adj. BSNA
0.95
0.90
0.85
2
4
6
8
R1_ION_I

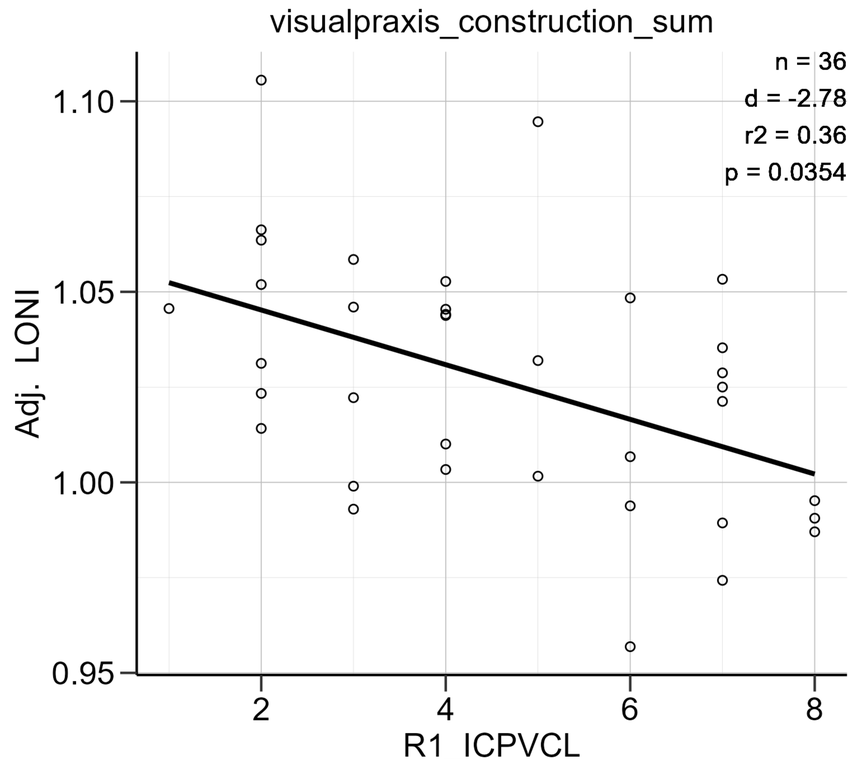

proprioception_crayon
n = 37
d = 3.47
r2 = 0.31
p = 0.0343
0.175
0.150
0.125
Adj. LONI
4
6
8
10
12
ODI_LLR

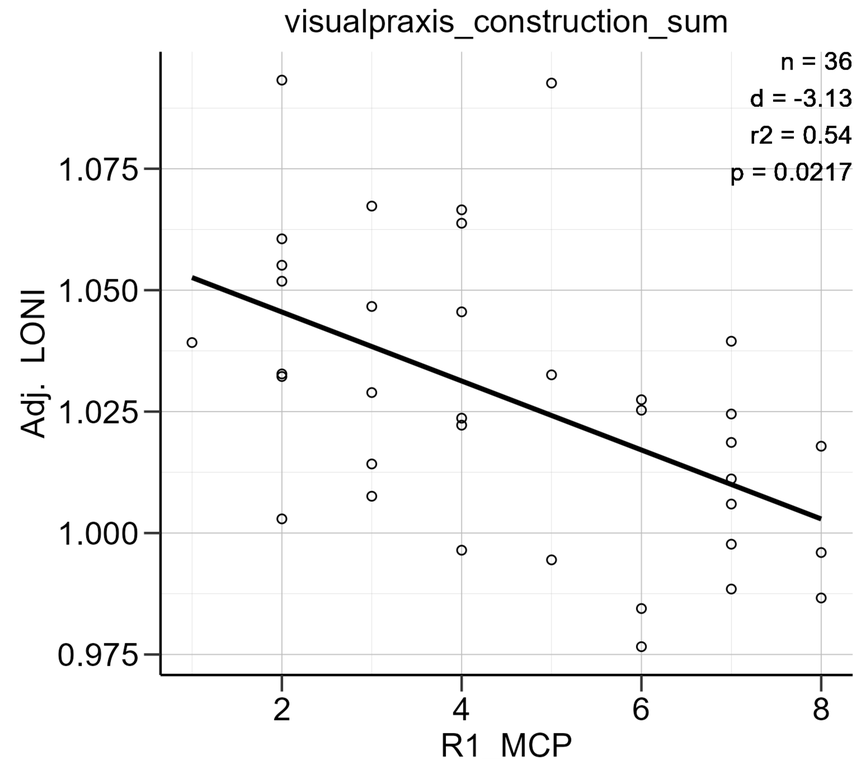
LONI R1 ~ praxis_followdirs_body_sum (significant (fdr corrected))

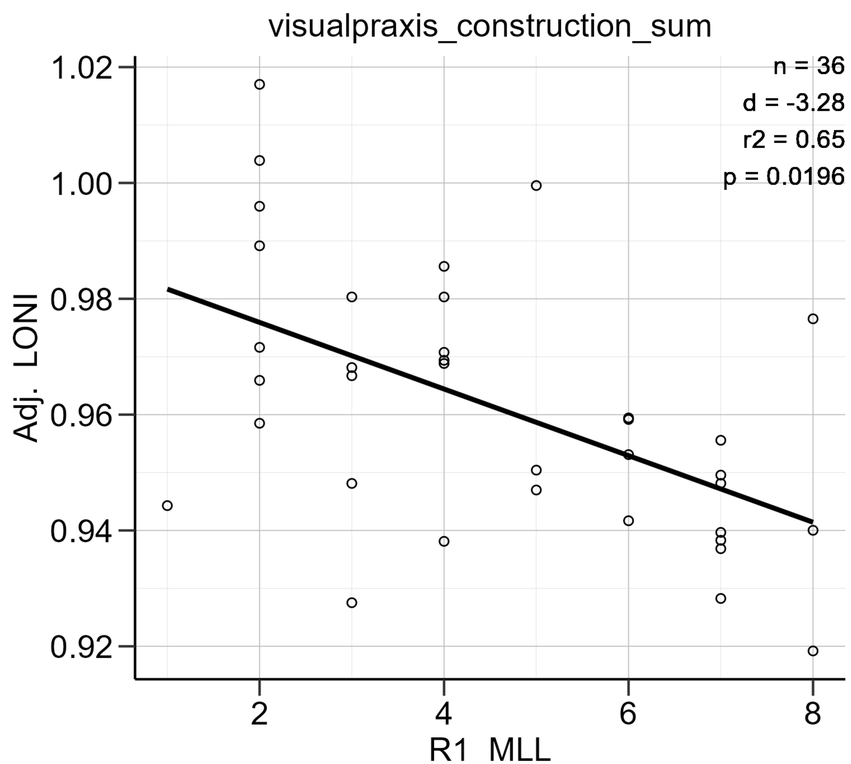


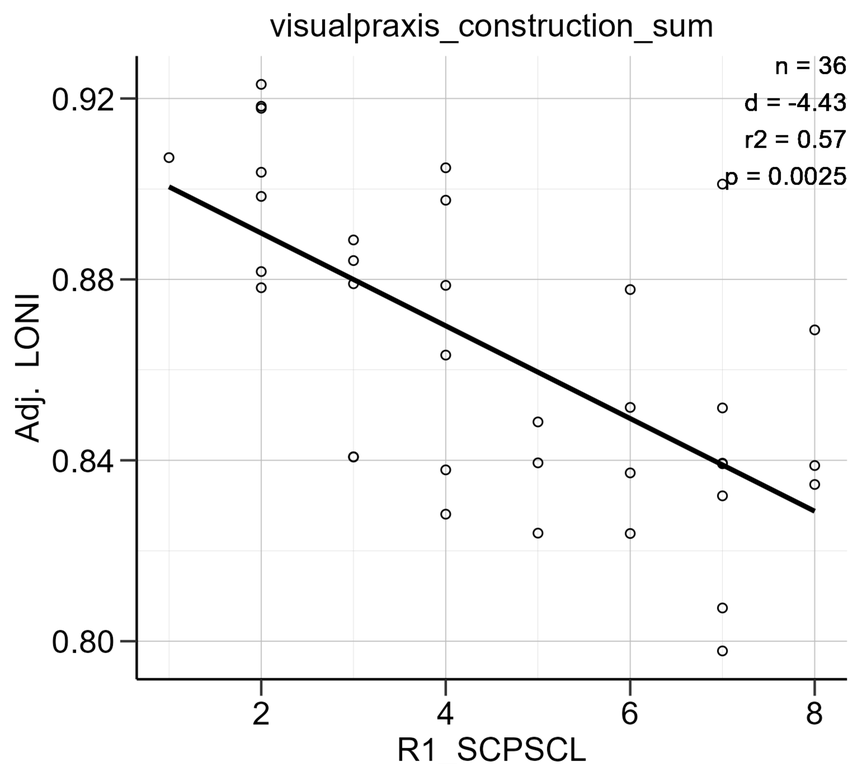

supine_flex_sum
n = 37
d = -3.66
r2 = 0.59
p = 0.0051
Adj. LONI
R1_CSTL
supine_flex_sum
n = 37
d = -3.11
r2 = 0.44
p = 0.01
Adj. LONI
R1_CSTR
supine_flex_sum
n = 37
d = -3.11
r2 = 0.45
p = 0.01
Adj. LONI
R1_FPTL
supine_flex_sum
n = 37
d = -3.17
r2 = 0.44
p = 0.01
Adj. LONI
R1_FPTR
supine_flex_sum
n = 37
d = -2.28
r2 = 0.34
p = 0.0455
Adj. LONI
R1_ICPMCL
supine_flex_sum
n = 37
d = -2.73
r2 = 0.34
p = 0.0195
Adj. LONI
R1_ICPMCR
supine_flex_sum
n = 37
d = -2.23
r2 = 0.34
p = 0.0469
Adj. LONI
R1_ICPVCL
supine_flex_sum
n = 37
d = -2.82
r2 = 0.36
p = 0.0186
Adj. LONI
R1_ICPVCR
supine_flex_sum
n = 37
d = -3.21
r2 = 0.53
p = 0.01
Adj. LONI
R1_MCP
supine_flex_sum
n = 37
d = -4.27
r2 = 0.68
p = 0.0037
Adj. LONI
R1_MLL
supine_flex_sum
n = 37
d = -3.84
r2 = 0.56
p = 0.0042
Adj. LONI
R1_MLR
supine_flex_sum
n = 37
d = -2.36
r2 = 0.37
p = 0.0405
Adj. LONI
R1_POTPTR
supine_flex_sum
n = 37
d = -3.33
r2 = 0.46
p = 0.01
Adj. LONI
R1_SCPSCL
supine_flex_sum
n = 37
d = -2.48
r2 = 0.45
p = 0.0328
Adj. LONI
R1_SCPSCR
supine_flex_sum
n = 37
d = -3.85
r2 = 0.59
p = 0.0042
Adj. LONI
R1_STTL
supine_flex_sum
n = 37
d = -2.78
r2 = 0.53
p = 0.0187
Adj. LONI
R1_STTR

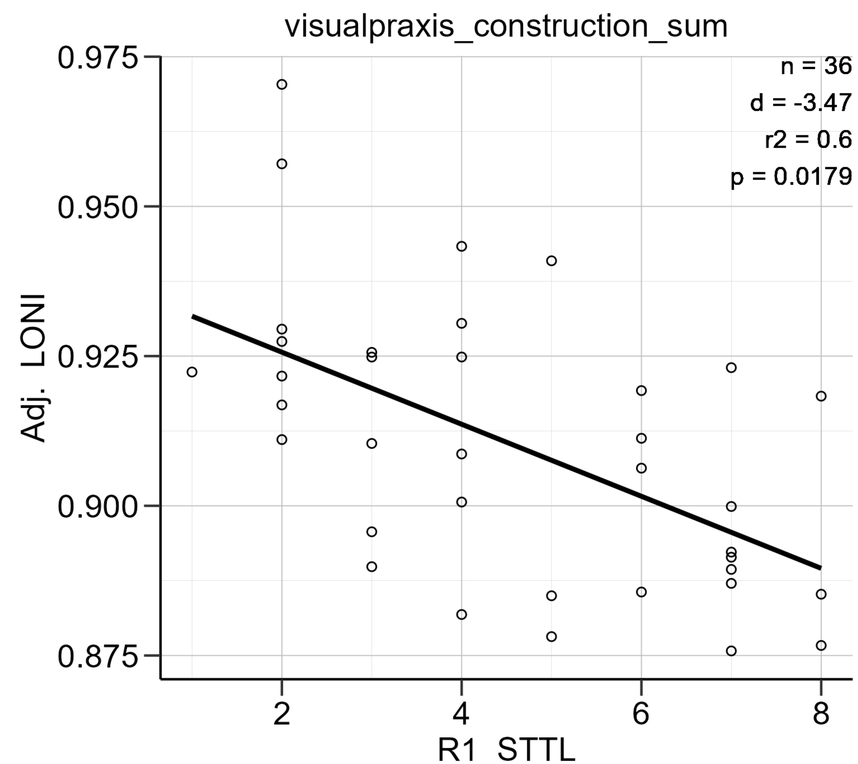

visualpraxis_construction_sum
n = 36
d = -3.01
r2 = 0.38
p = 0.0235
Adj. LONI
R1_ICPMCL


visualpraxis_construction_sum
n = 36
d = -2.78
r2 = 0.36
p = 0.0354
Adj. LONI
R1_ICPVCL


visualpraxis_construction_sum
n = 36
d = -3.13
r2 = 0.54
p = 0.0217
Adj. LONI
R1_MCP


visualpraxis_construction_sum
n = 36
d = -3.28
r2 = 0.65
p = 0.0196
Adj. LONI
R1_MLL


visualpraxis_construction_sum
n = 36
d = -4.43
r2 = 0.57
p = 0.0025
Adj. LONI
R1_SCPSCL


visualpraxis_construction_sum
n = 36
d = -3.47
r2 = 0.6
p = 0.0179
Adj. LONI
R1_STTL