

# Rendering techniques

Tristan Gouge



# Contents

- 1 Global Illumination 1**
  - 1.1 What is Global illumination . . . . . 1
- 2 Physics 3**
  - 2.1 The physics behind the images . . . . . 3
    - 2.1.1 Electronic waves, light transport equation . . . . . 3
    - 2.1.2 Poynting vector, Radiance, Radiant energy... . . . . 3
    - 2.1.3 The rendering equation . . . . . 4



# 1 Global Illumination

## 1.1 What is Global illumination

**Definition 1.1.1** (Global Illumination). *Global illumination* or *indirect illumination* is a set of algorithms that take into account not only direct light (from light sources) but also indirect lights (reflections, diffusion, ...)



## 2 Physics

### 2.1 The physics behind the images

#### 2.1.1 Electronic waves, light transport equation

**Definition 2.1.1** (Electromagnetic radiation). It consists of waves of EM which propagate through space. Its behaviour is determined by the Maxwell equations:

- $\text{div } \vec{E} = \frac{\rho}{\epsilon_0},$
- $\text{rot } \vec{E} = -\frac{\partial \vec{B}}{\partial t},$
- $\text{div } \vec{B} = 0,$
- $\text{rot } \vec{B} = \mu_0 \left( \vec{j} + \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right).$

Where  $\vec{j}$  is the current density,  $\rho$  is the charge density.

**Theorem 2.1.1** (Light transport equation). *Every solution to Maxwell equation respects the following transport equation*

- $\Delta \vec{E} = \frac{1}{c_0^2} \frac{\partial^2 \vec{E}}{\partial t^2}$
- $\Delta \vec{B} = \frac{1}{c_0^2} \frac{\partial^2 \vec{B}}{\partial t^2}$

where  $c_0^2 = \mu_0 \epsilon_0$  and  $\Delta$  is the Laplacian.

#### 2.1.2 Poynting vector, Radiance, Radiant energy...

**Definition 2.1.2** (Poynting vector). The Poynting vector is the vector defined by:

$$\vec{\Pi} = \frac{\vec{E} \wedge \vec{B}}{\mu_0}.$$

**Theorem 2.1.2** (Poynting theorem).

$$-\frac{\partial u}{\partial t} = \text{div } \vec{\Pi} + \vec{j} \cdot \vec{E}$$

Where  $u = \frac{1}{2} \left( \epsilon_0 E^2 + \frac{B^2}{\mu_0} \right)$  is the local electromagnetic energy,  $j$  is the current density.

**Definition 2.1.3** (Radiant Energy). It is the energy of an electromagnetic radiation, given by The radiant energy flux is given by

$$\Phi_e = \frac{dQ_e}{dt}$$

where

$$Q_e = \int_{\Sigma} \vec{\Pi} \cdot \vec{n} \, dA$$

and  $\Sigma$  is a closed surface.

**Theorem 2.1.3.**

$$\Phi_e \approx \int_{\Sigma} \langle |\Pi| \rangle \cos \alpha \, dA$$

Where  $\alpha$  is the angle between  $\vec{\Pi}$  and  $\vec{n}$ .

**Definition 2.1.4** (Radiance). The radiance is the radiant flux emitted, reflected, transmitted or received by a given surface, per unit solid angle per unit projected area

$$L_{e,\Omega} = \frac{\partial^2 \Phi_e}{\partial \Omega \partial (A \cos \theta)},$$

where  $\Omega$  is the solid angle,  $A \cos \theta$  the projected area.

### 2.1.3 The rendering equation

**Definition 2.1.5.** The rendering equation is an equation that gives the relation between the outgoing radiance along an output direction  $\omega_o$  at a given point, and the incoming radiance:

$$L_o(\vec{x}, \omega_o, t) = L_e(\vec{x}, \omega_o, t) + \int_{\Omega} f_r(\vec{x}, \omega_i, \omega_o, t) L_i(\vec{x}, \omega_i, \omega_o, t) (\omega_i \cdot \vec{n}) \, d\omega_i.$$

where  $L_o$  is the total outgoing radiance along  $\omega_o$ ,  $\vec{x}$  the position,  $t$  the time,  $L_e$  the emitted radiance,  $L_i$  the incoming radiance,  $f_r$  is the BRDF function.

The equation can also be modified to take into account the wavelength

The previous equation has some limitations: it can't model non-linear effects, interference, polarization...

See transient rendering (Definition ??) and volume rendering (Definition ??).

**Definition 2.1.6** (Bidirectional reflectance distribution function — BRDF).



[1]



# Bibliography

- [1] Eric Haines. *Ray Tracing Gems*. URL: <https://link.springer.com/book/10.1007/978-1-4842-4427-2> (visited on 10/22/2022).