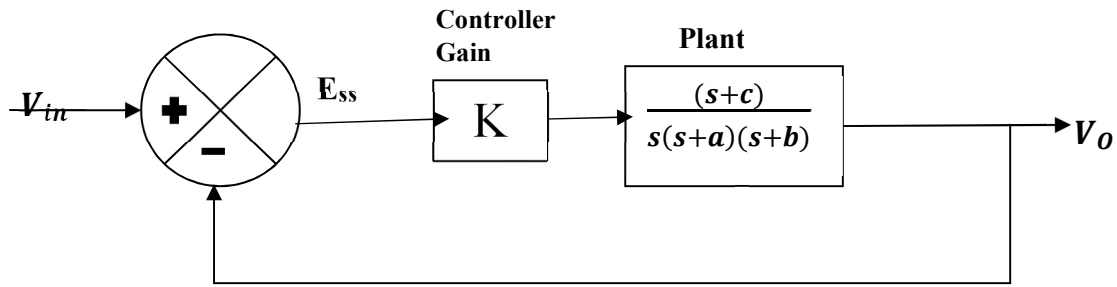


1. Consider the following closed loop system



- a) You are required to design the system in Simulink environment such that the percentage overshoot, **%OS=30%** and settling time, **T_s (2%) =3 seconds** with a steady-state error, **E_{ss}= 0.045** when a **unit step input** is provided and **the system remains second order**. The value of **E_{ss}** must be displayed in the design using “**Display**” block.

According to the criteria,
From mentioned equation

$$\% \text{ Overshoot ratio} = 100 \times e^{-\frac{\pi\zeta}{\sqrt{1-\zeta^2}}}$$

Overshoot = 30%

Damping Ratio = 0.34

And settling time 3s (for 2% error) gives natural frequency, $\omega_n = 3.92 \text{ rad/s}$, from the equation 4

$$T_s = 4 / (\omega_n \zeta)$$

From this equation $= (s^2 + 2\zeta\omega_n s + \omega_n^2)$

$$A = 0.291$$

$$B = 2.379$$

$$C = 0$$

$$K = 14.678$$

Designed Component Values will be

$$R1 = 100 \text{ K}\Omega$$

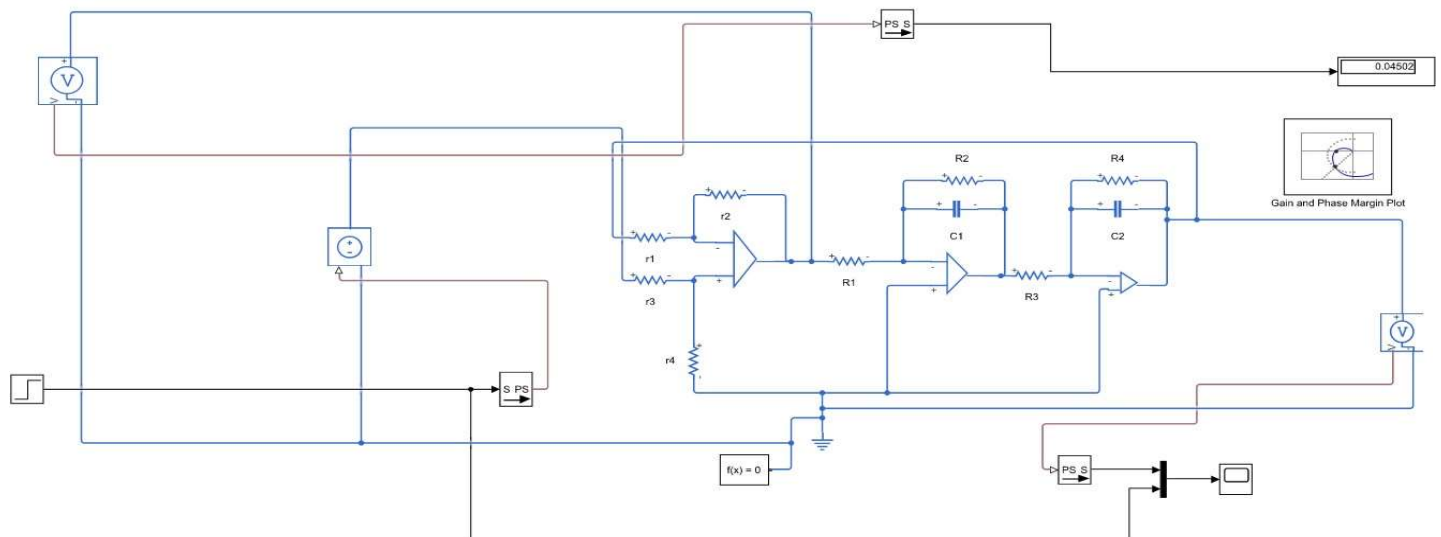
$$R2 = 343.64 \text{ K}\Omega$$

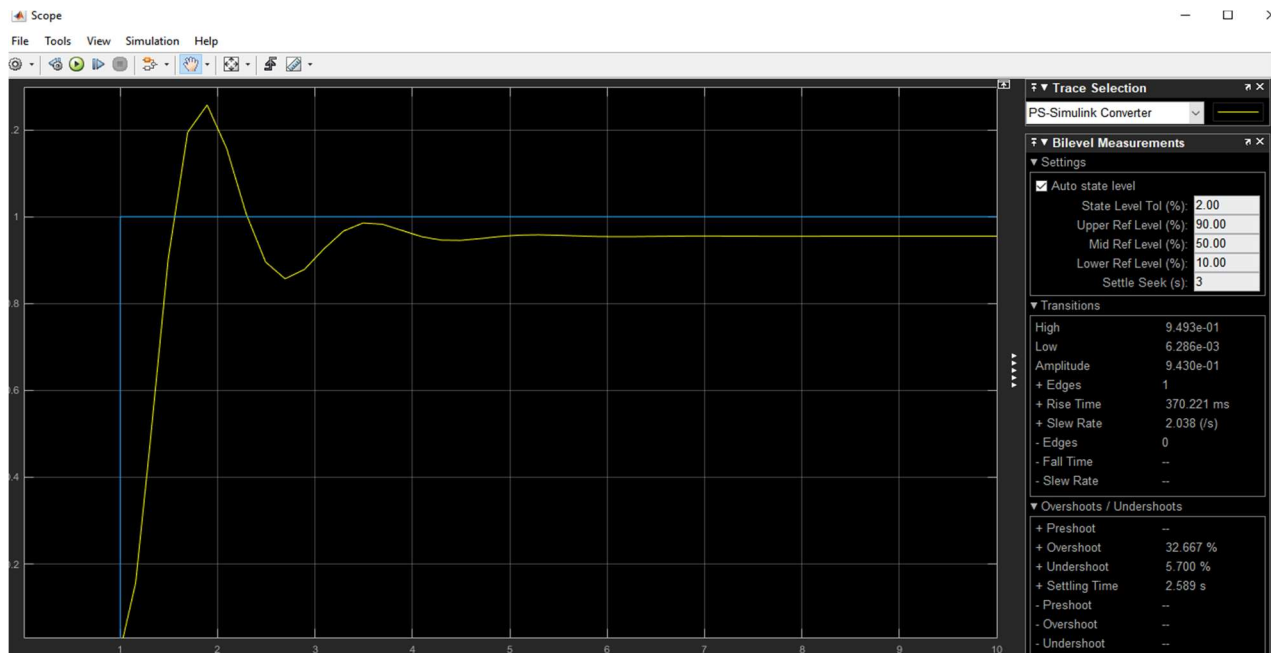
$$R3 = 6.81 \text{ K}\Omega$$

$$R4 = 42.034 \text{ K}\Omega$$

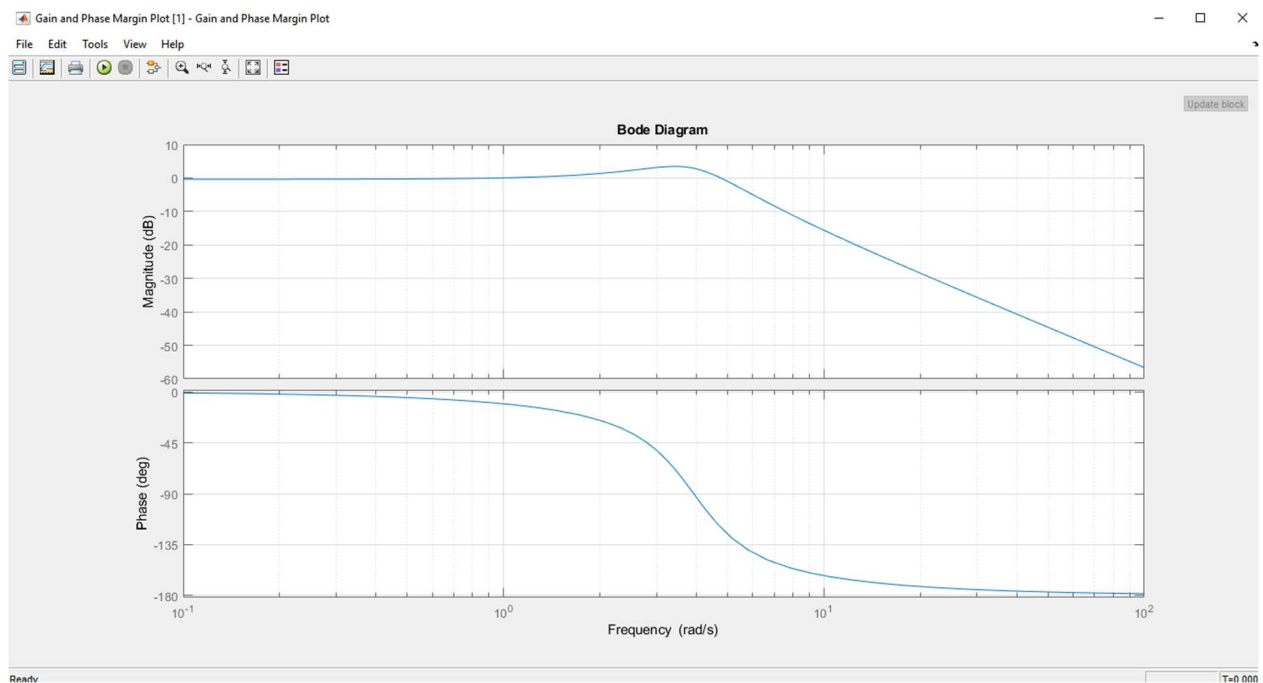
$$C1=C2 = 10 \text{ }\mu\text{F}$$

Desired Design :





- b) Show the **open loop Bode plot** for the aforementioned system and specify all the stability margins in the same Simulink model for question no. 1(a).



- c) Now compensate the existing plant you have designed without changing the initial parameters in question no. 1(a) for the following specifications: **%OS=40% and T_s (2%) =4 seconds**. And the compensated system should be **error free**.

From Calculation:

Damping Ratio = 0.28

Natural Frequency = 3.571 rad/s

$K = 12.755$

New Pole = 1.9998

$R1 = 343.64 \text{ K}\Omega$

$R2 = 42.034 \text{ K}\Omega$

$R3 = 50 \text{ K}\Omega$

$R4 = 100 \text{ K}\Omega$

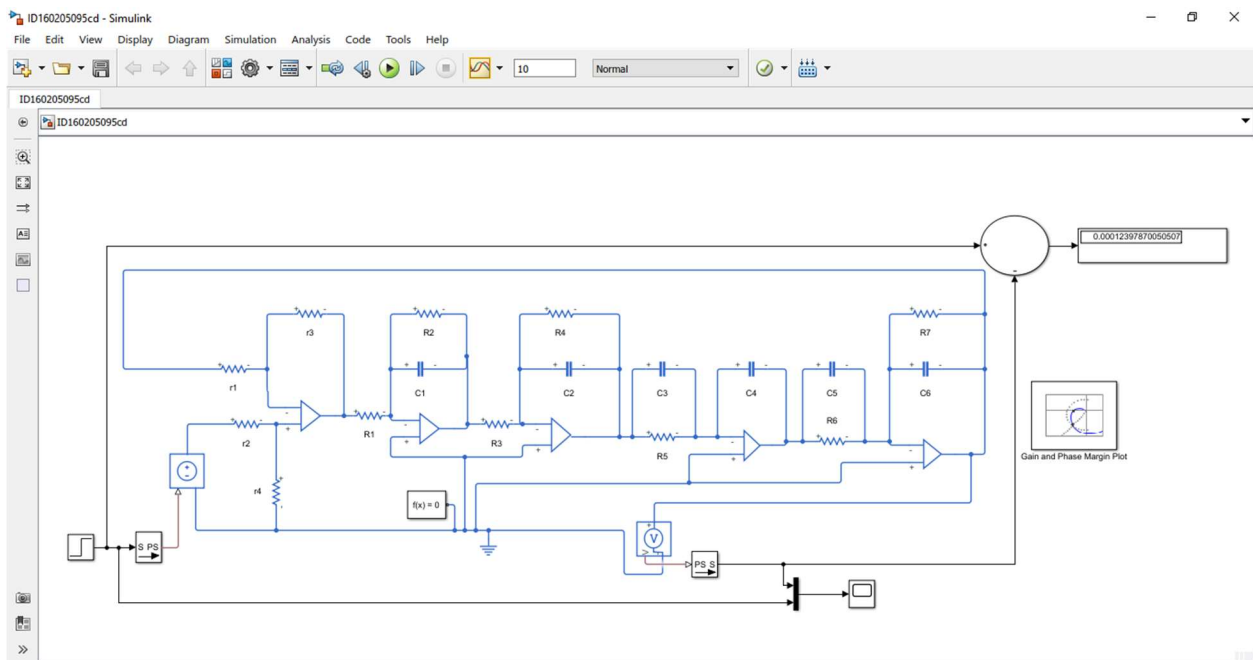
$R5 = 42.034 \text{ K}\Omega$

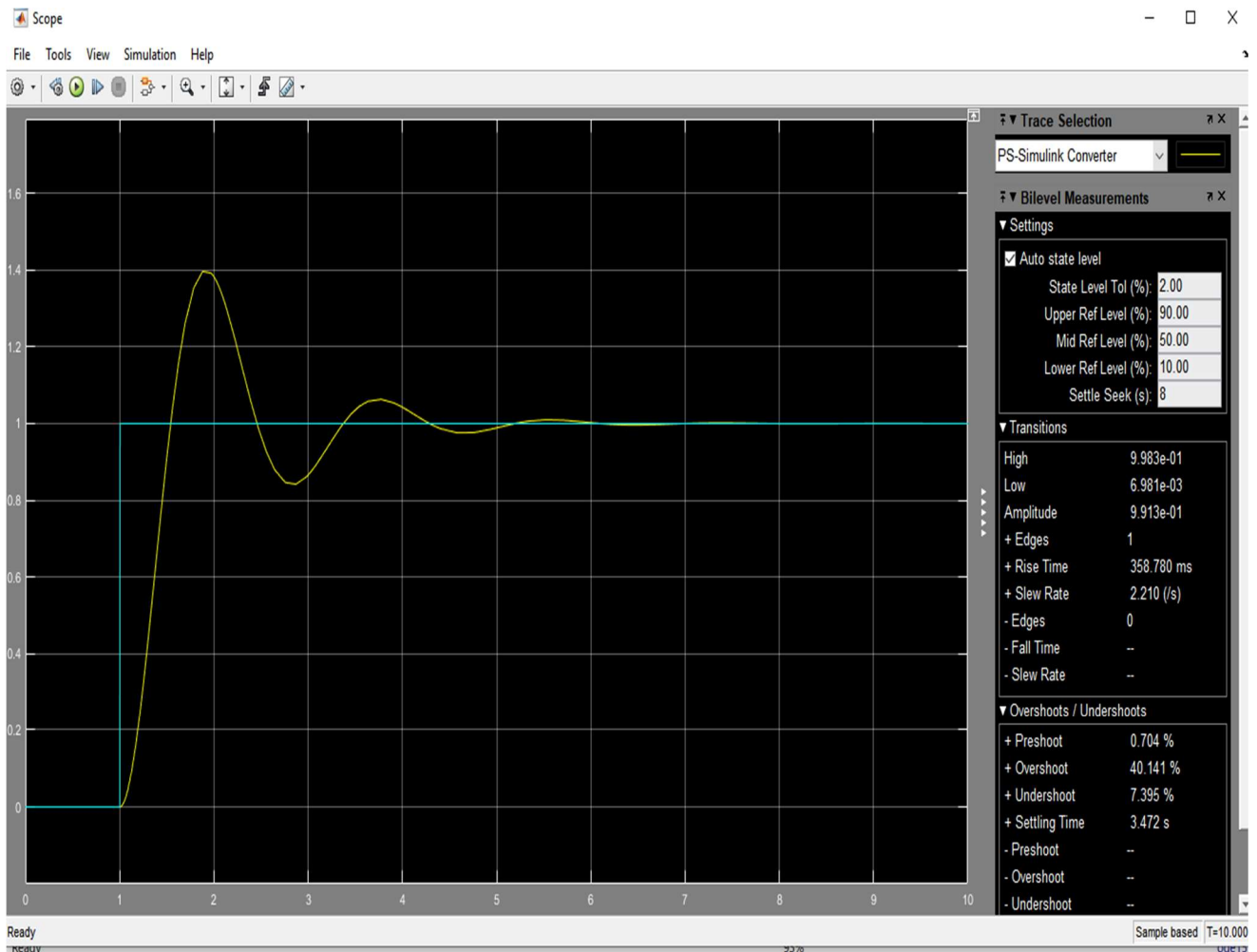
$R6 = 7.84 \text{ K}\Omega$

$R9 = 343.64 \text{ K}\Omega$

$C = 10 \mu\text{F}$

So the Desired Design :





- d) Show the **open loop Nyquist plot** for the aforementioned system and specify all the stability margins in the same Simulink model for question no. 1(c).

