

April 18, 2023

$$\text{Area, } a = \int_{t_1}^{t_2} A e^{-\lambda t} dt = -\frac{A}{\lambda} [e^{-\lambda t_2} - e^{-\lambda t_1}]$$

$\lambda = \frac{\ln(2)}{T_{\text{eff}}}$

$= \frac{A}{\lambda} [e^{-\lambda t_1} - e^{-\lambda t_2}]$

$$\sigma_a^2 = \left(\frac{\partial a}{\partial A} \sigma_A \right)^2 + \left(\frac{\partial a}{\partial T} \sigma_T \right)^2 + 2 \left(\frac{\partial a}{\partial A} \right) \left(\frac{\partial a}{\partial T} \right) \text{cov}(A, T)$$

$$\frac{\partial a}{\partial A} = \frac{1}{\lambda} [e^{-\lambda t_1} - e^{-\lambda t_2}] = \frac{T}{\ln(2)} \left[e^{-\frac{t_1 \cdot \ln(2)}{T}} - e^{-\frac{t_2 \cdot \ln(2)}{T}} \right]$$

$$\frac{\partial a}{\partial T} = \frac{1}{\ln(2)} \left[e^{-\frac{t_1 \cdot \ln(2)}{T}} - e^{-\frac{t_2 \cdot \ln(2)}{T}} \right]$$

$$+ \frac{T}{\ln(2)} \left[\frac{t_1 \cdot \ln(2)}{T^2} e^{-\frac{t_1 \cdot \ln(2)}{T}} - \frac{t_2 \cdot \ln(2)}{T^2} e^{-\frac{t_2 \cdot \ln(2)}{T}} \right]$$

$$= \frac{1}{\ln(2)} \left[e^{-\frac{t_1 \cdot \ln(2)}{T}} - e^{-\frac{t_2 \cdot \ln(2)}{T}} \right]$$

$$+ \frac{1}{T} \left[t_1 e^{-\frac{t_1 \cdot \ln(2)}{T}} - t_2 e^{-\frac{t_2 \cdot \ln(2)}{T}} \right]$$

Simulation ($T_{eff} = 35.4$ h, $A = 2$)

t_i from 0 to 48 hours

- ① 5 points from 0 to 48 hours.
- ② 10 unique combinations of points.
- ③ For each combination \rightarrow 10,000 noise realizations.

Known $\left\{ \begin{array}{l} [0,1] \rightarrow \text{highest curvature along } A \text{ direction} \\ [2,3] \rightarrow \text{" " " " } T_{eff} \text{ "} \end{array} \right.$

Results:

$[0,1] \rightarrow$ most precise estimate for A
 $[2,3] \rightarrow$ " " " " T_{eff}

least bias from true A and true T_{eff}
both achieved by $[0,4]$