

Cylindrical Algebraic Decomposition for Nonlinear Arithmetic Problems

Gereon Kremer
PhD defense talk

12.03.2020

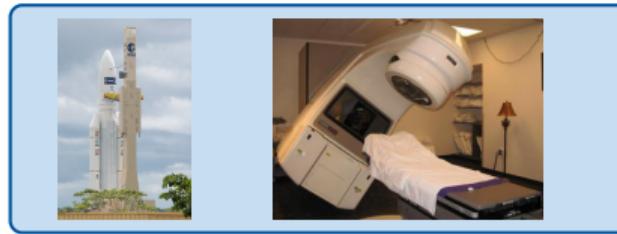
Grateful for the cooperation with and advise from:

Erika Ábrahám, Jens Brandt, Christopher Brown, Florian Corzilius, James H. Davenport, Matthew England, Vijay Ganesh, Rebecca Haehn, Marcel Hark, Einar Broch Johnsen, Sebastian Junges, Viktor Levandovskyy, Jacopo Mauro, Jasper Nalbach, Stefan Schupp, Tarik Viehmann, and many more.

Formal verification (with satisfiability modulo theories)



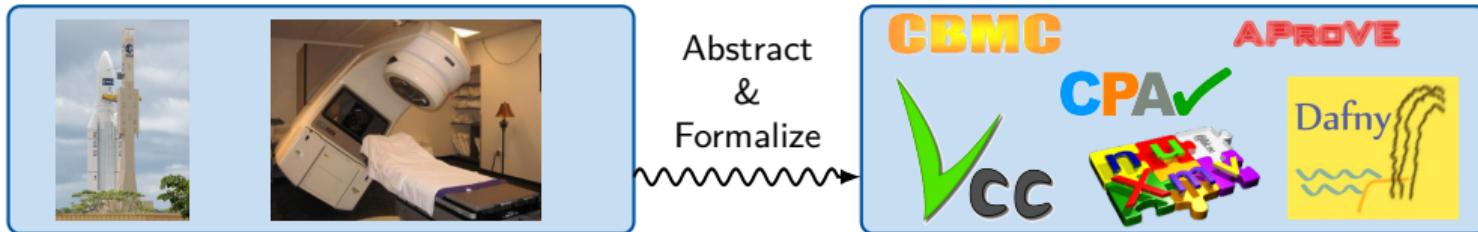
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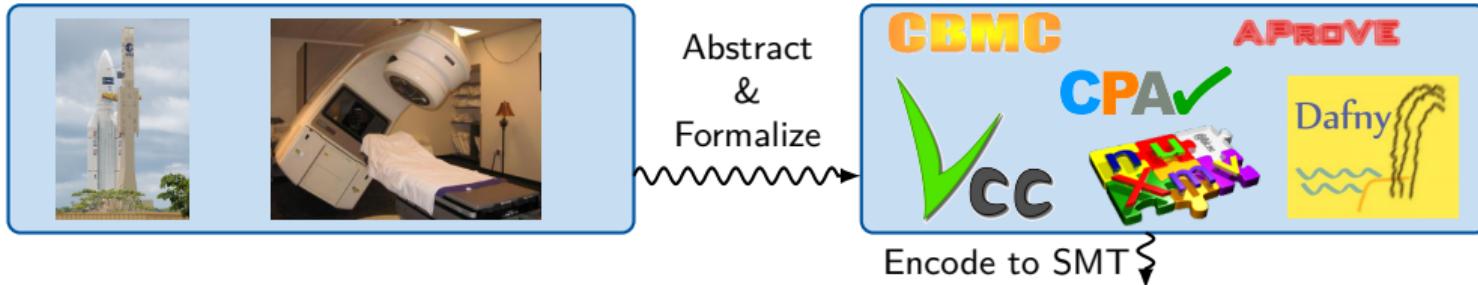
Abstract
&
Formalize

A black wavy arrow originates from the bottom right of the blue box and points towards the word "Formalize".

Formal verification (with satisfiability modulo theories)



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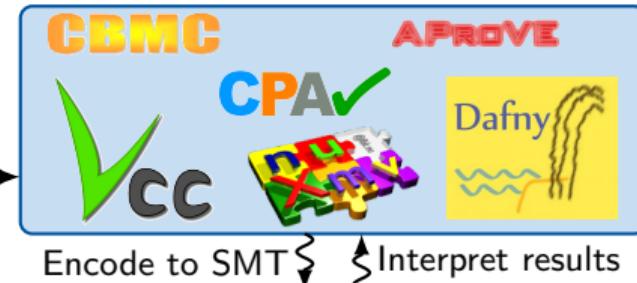
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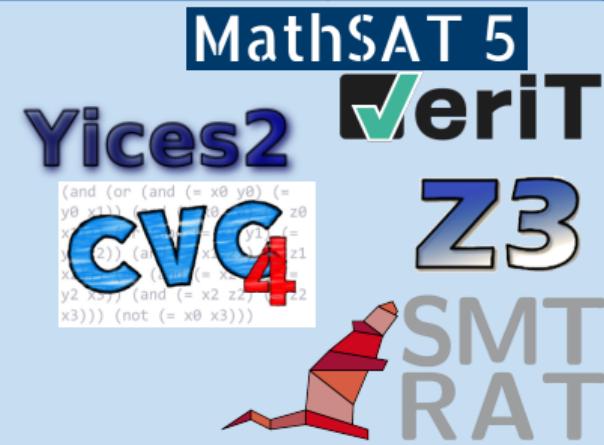
SMT formulae:

$$\exists x_1, \dots, x_n \in \mathbb{R}. \varphi(x_1, \dots, x_n)$$

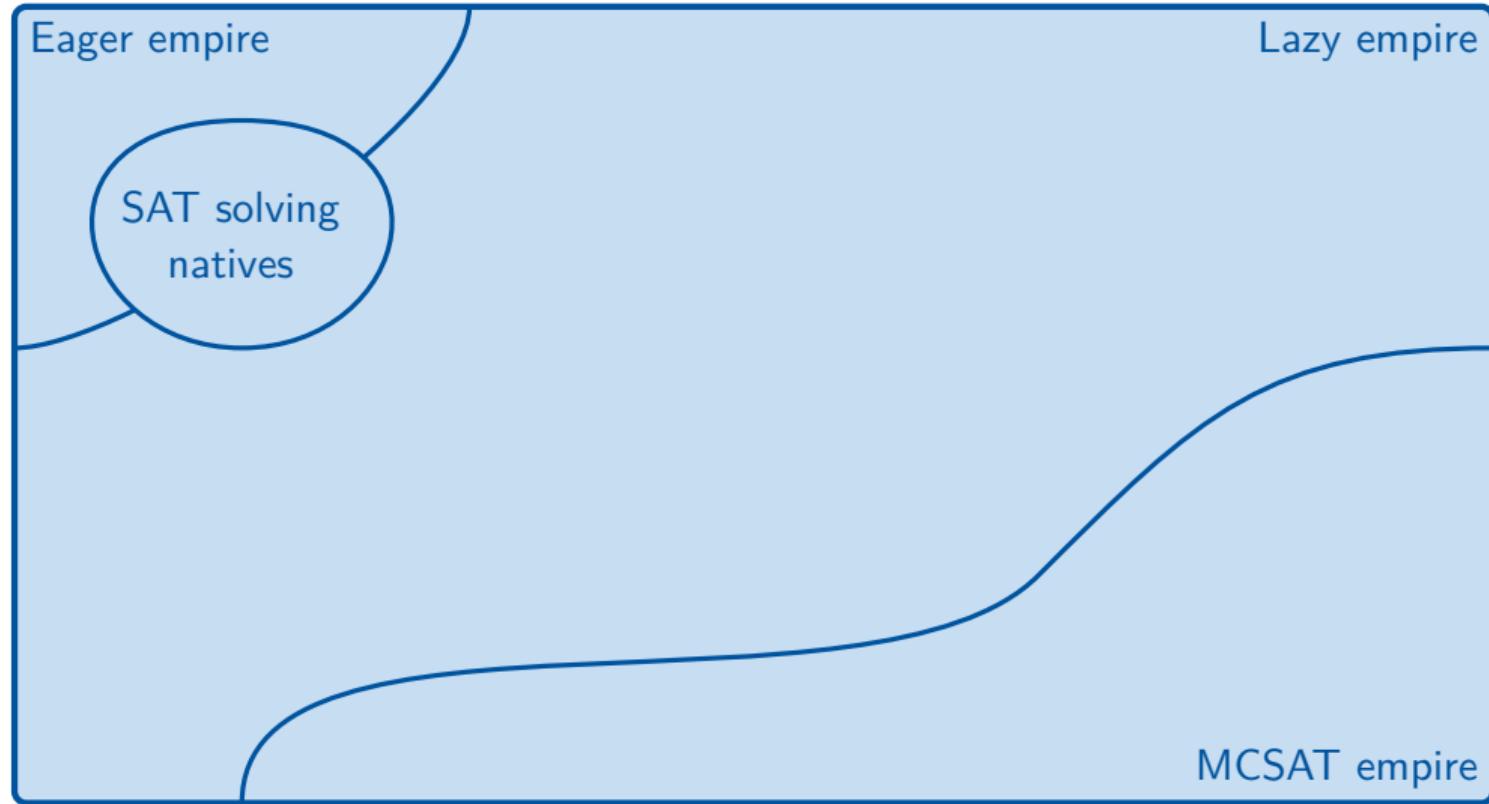
Theory constraints:

$$p \sim 0 \quad p \in \mathbb{Z}[x_1, \dots, x_n]$$

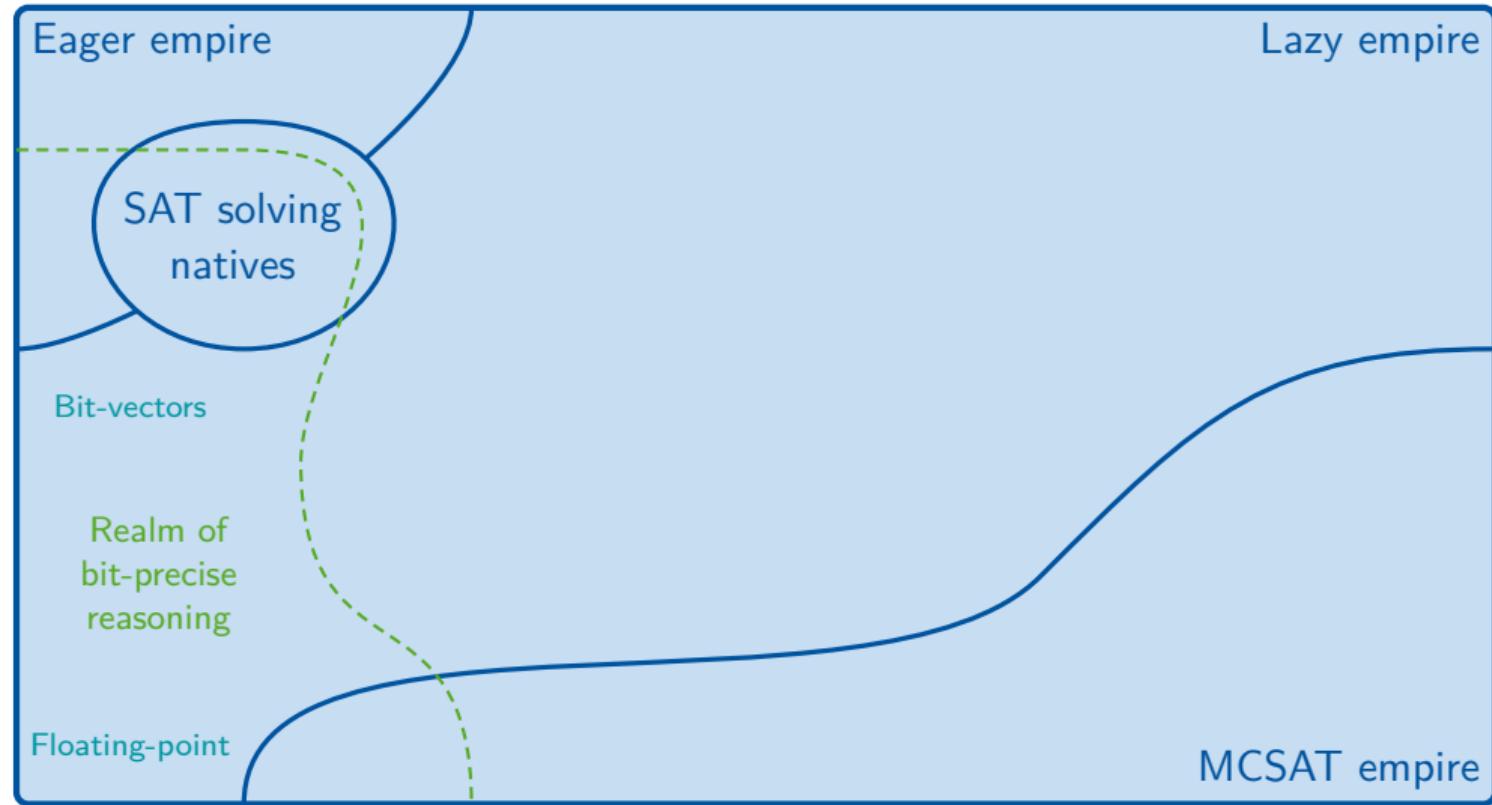
In SMT-LIB as QF_NRA since 2013



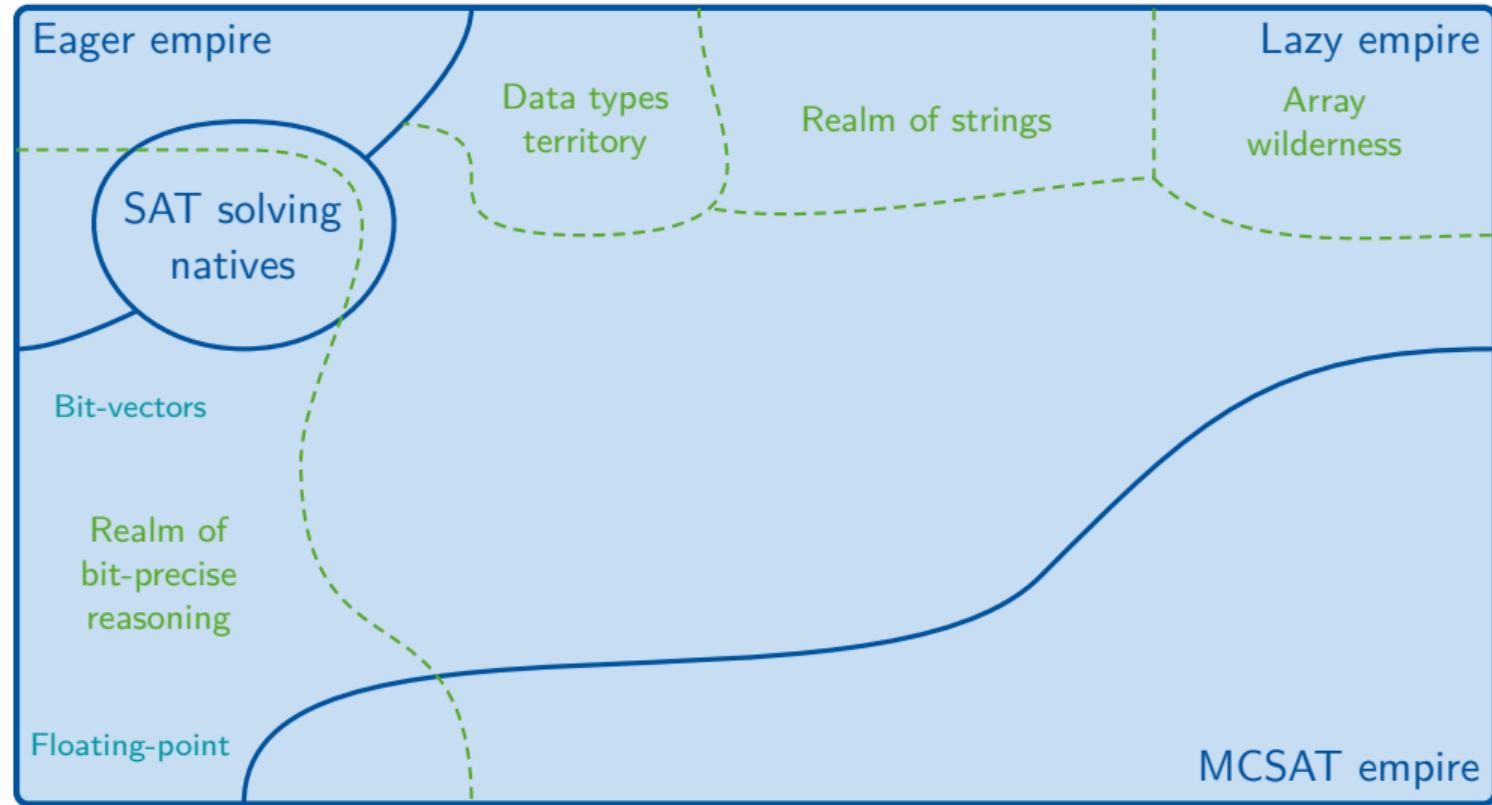
World Map of SMT



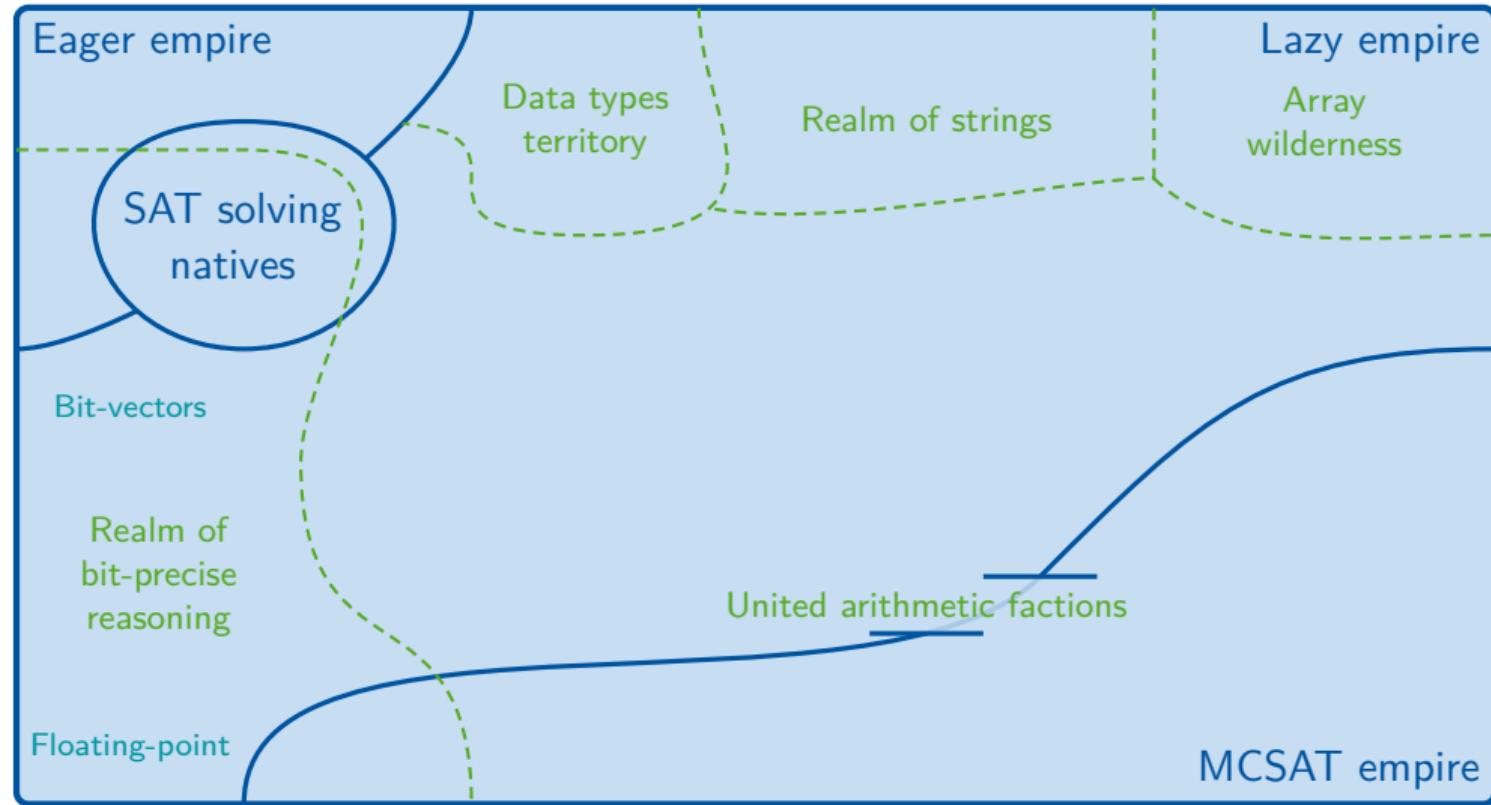
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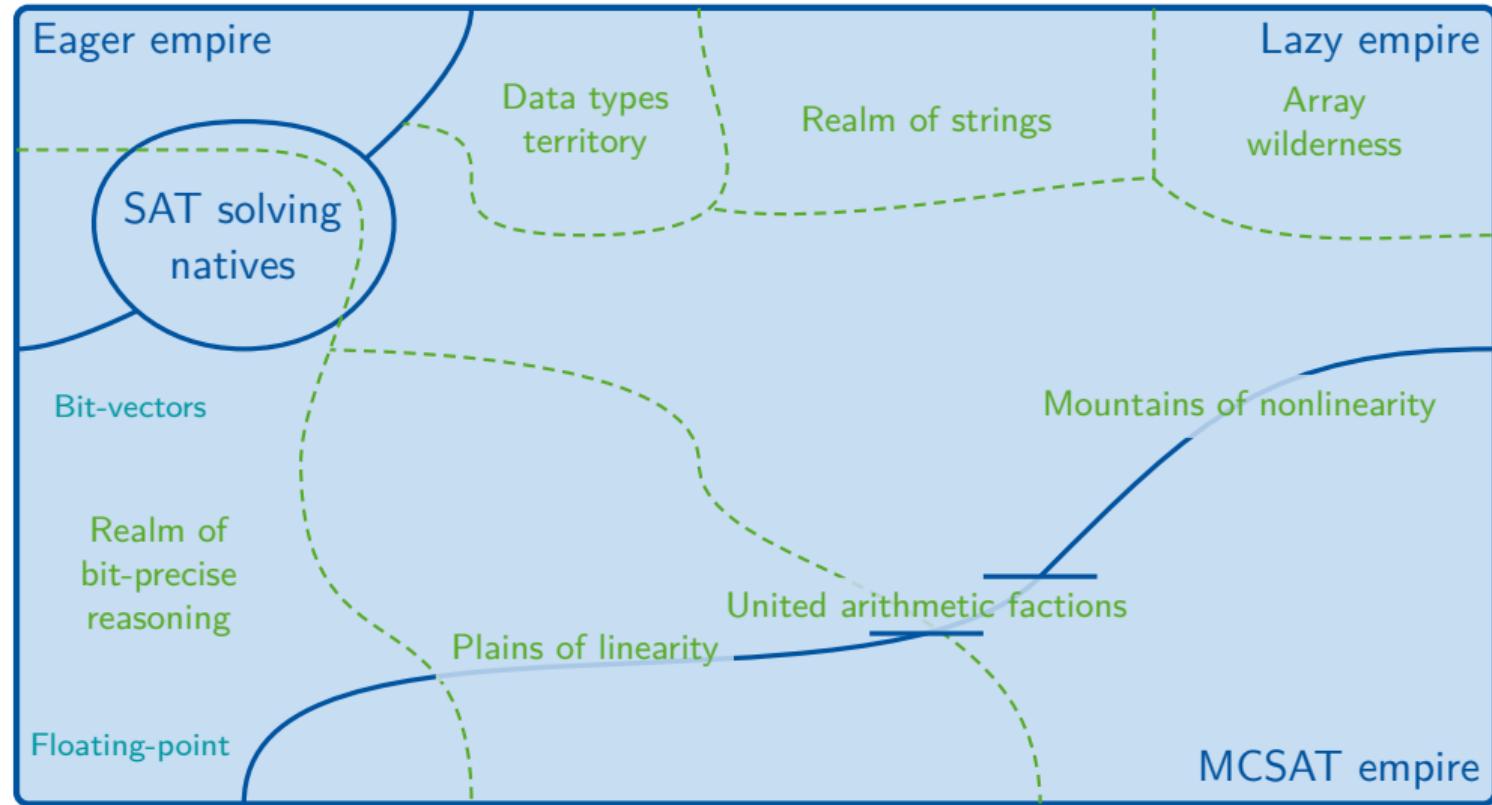
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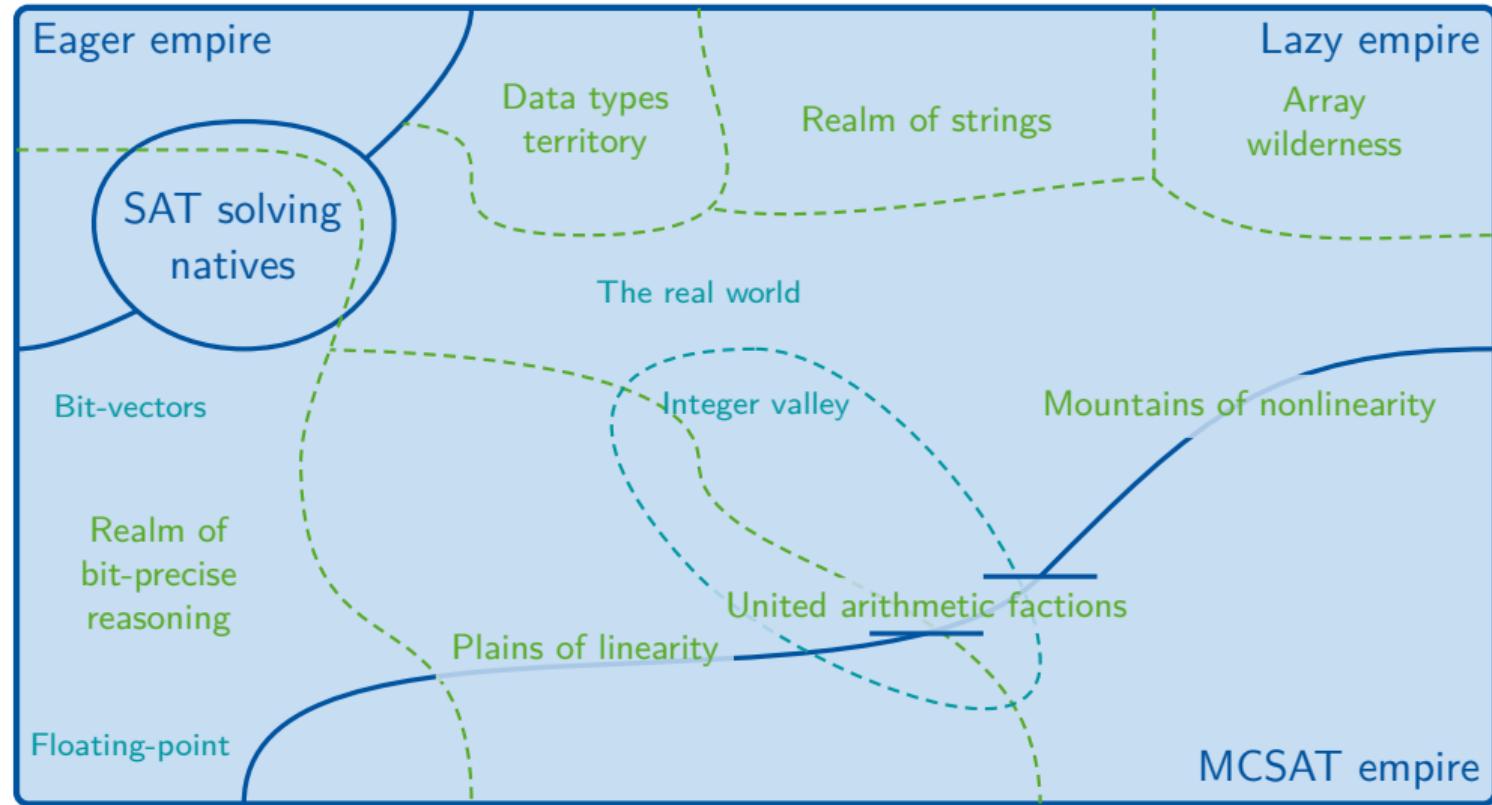
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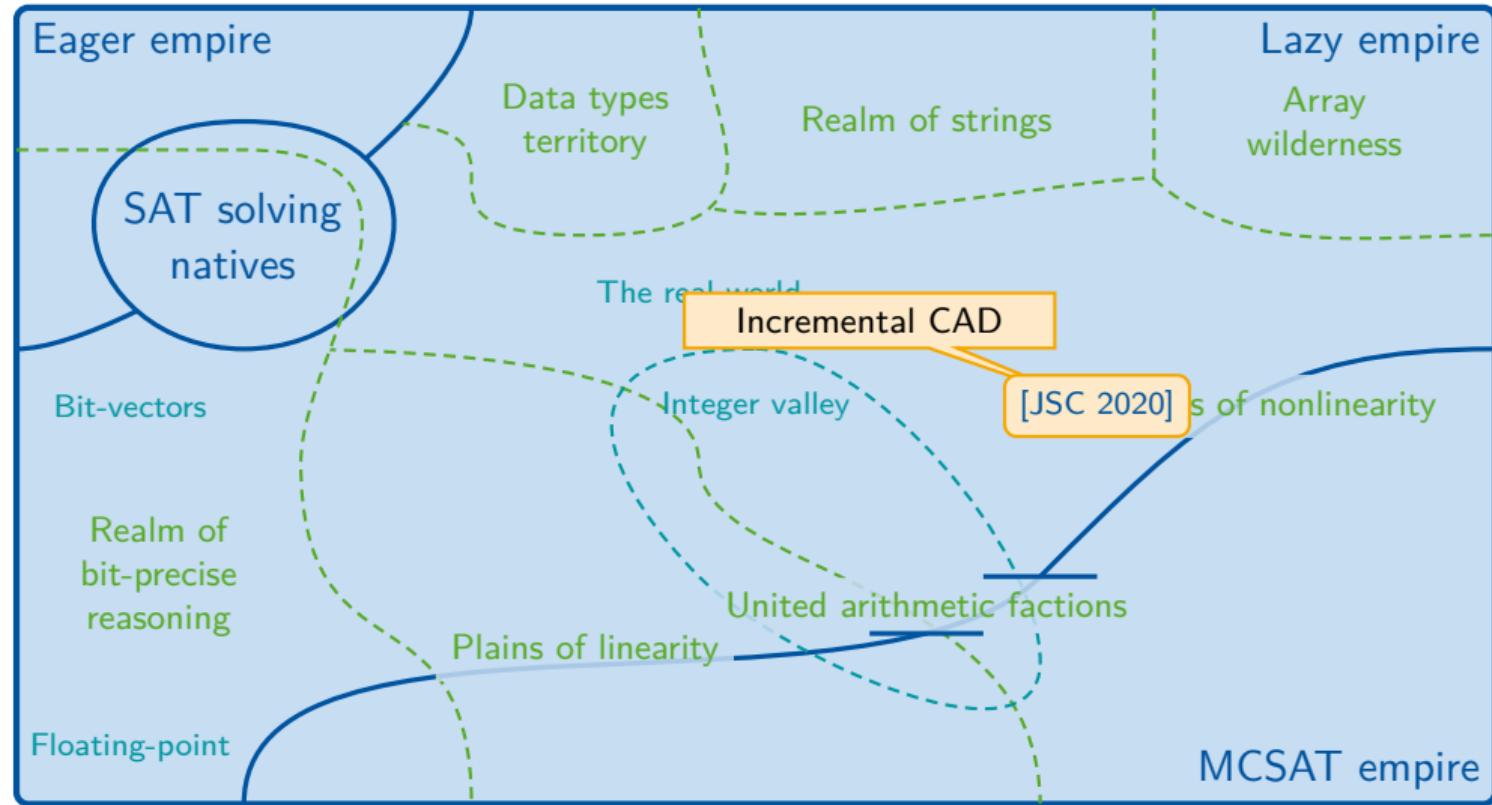
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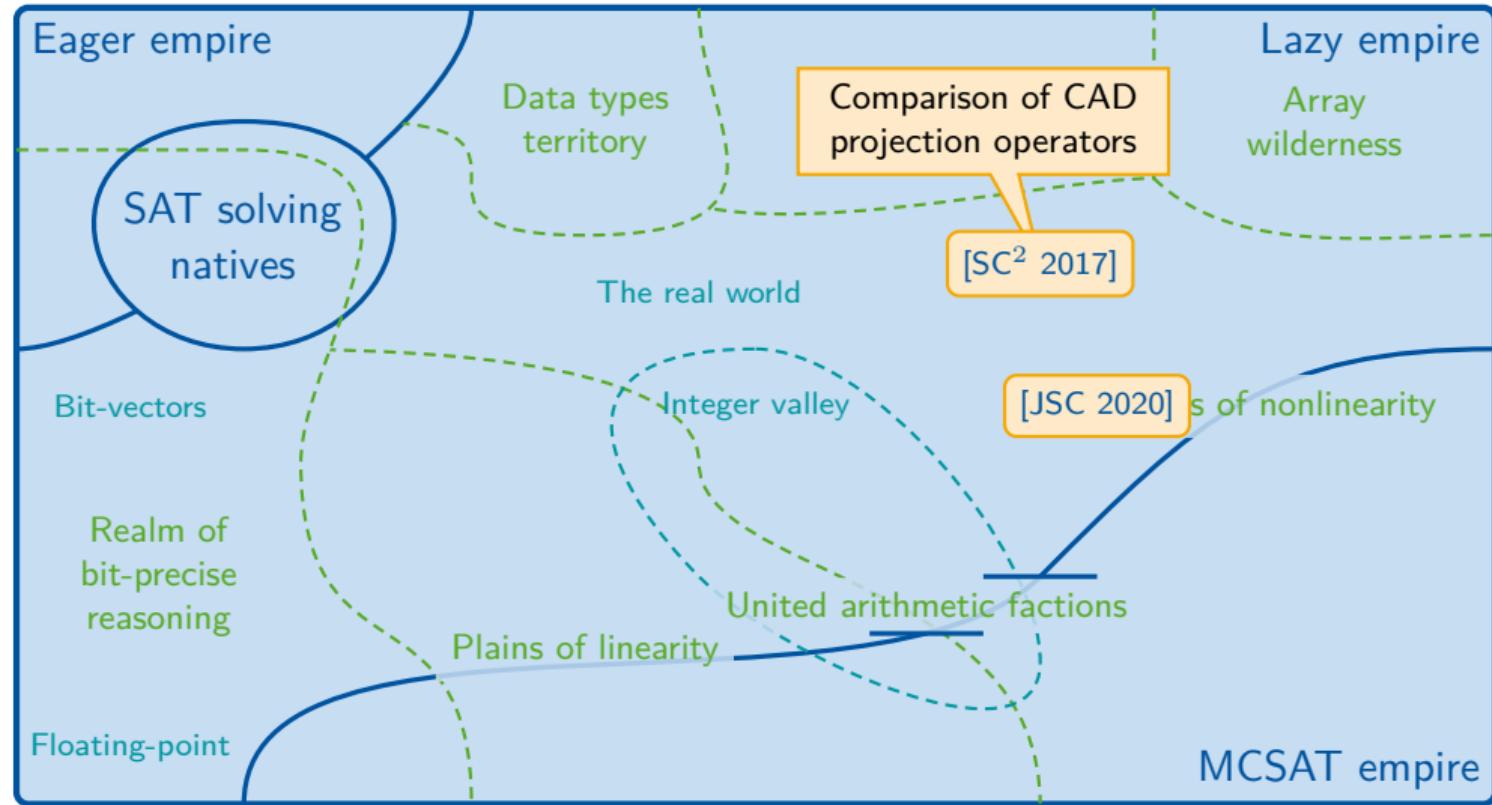
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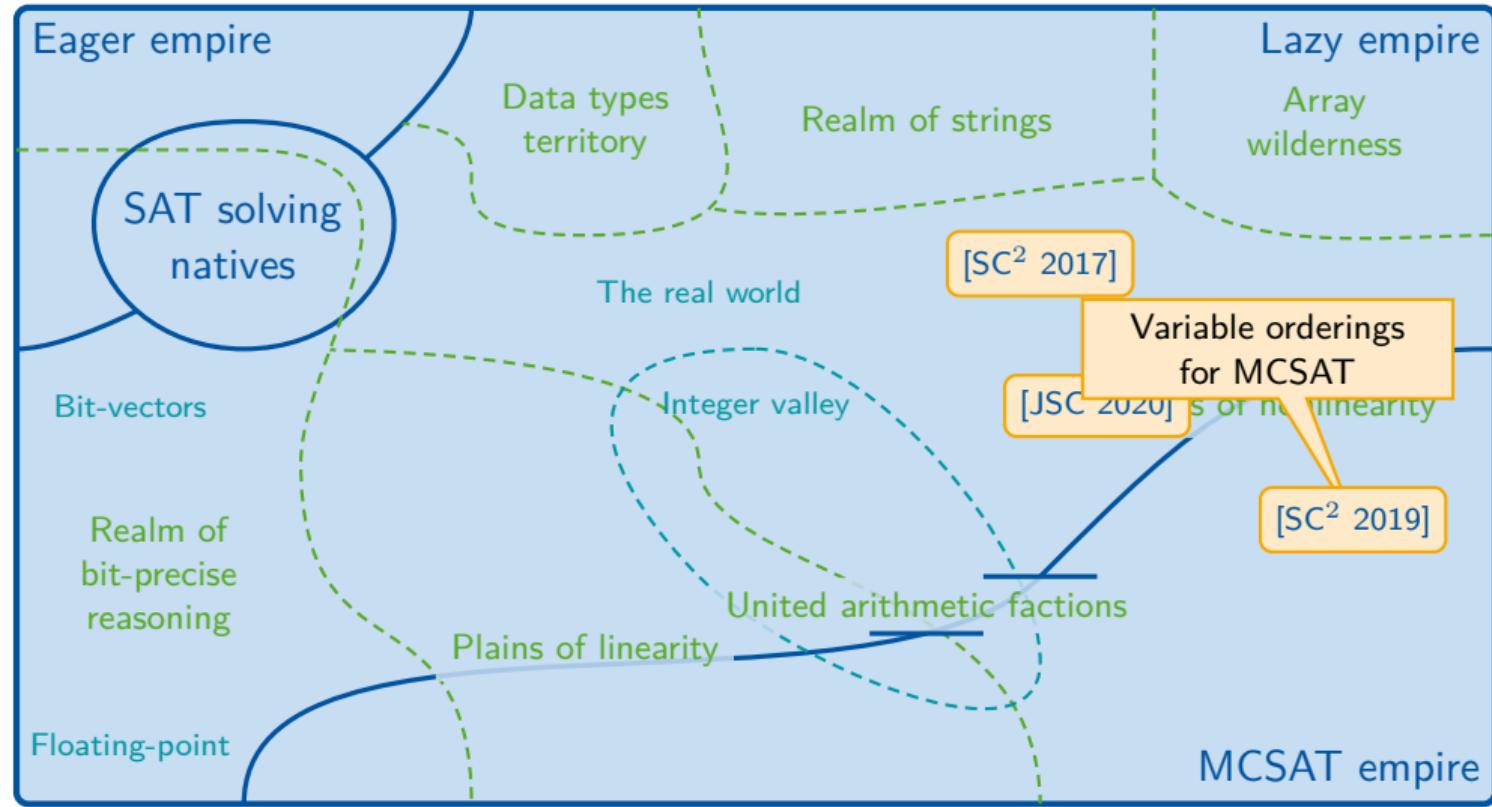
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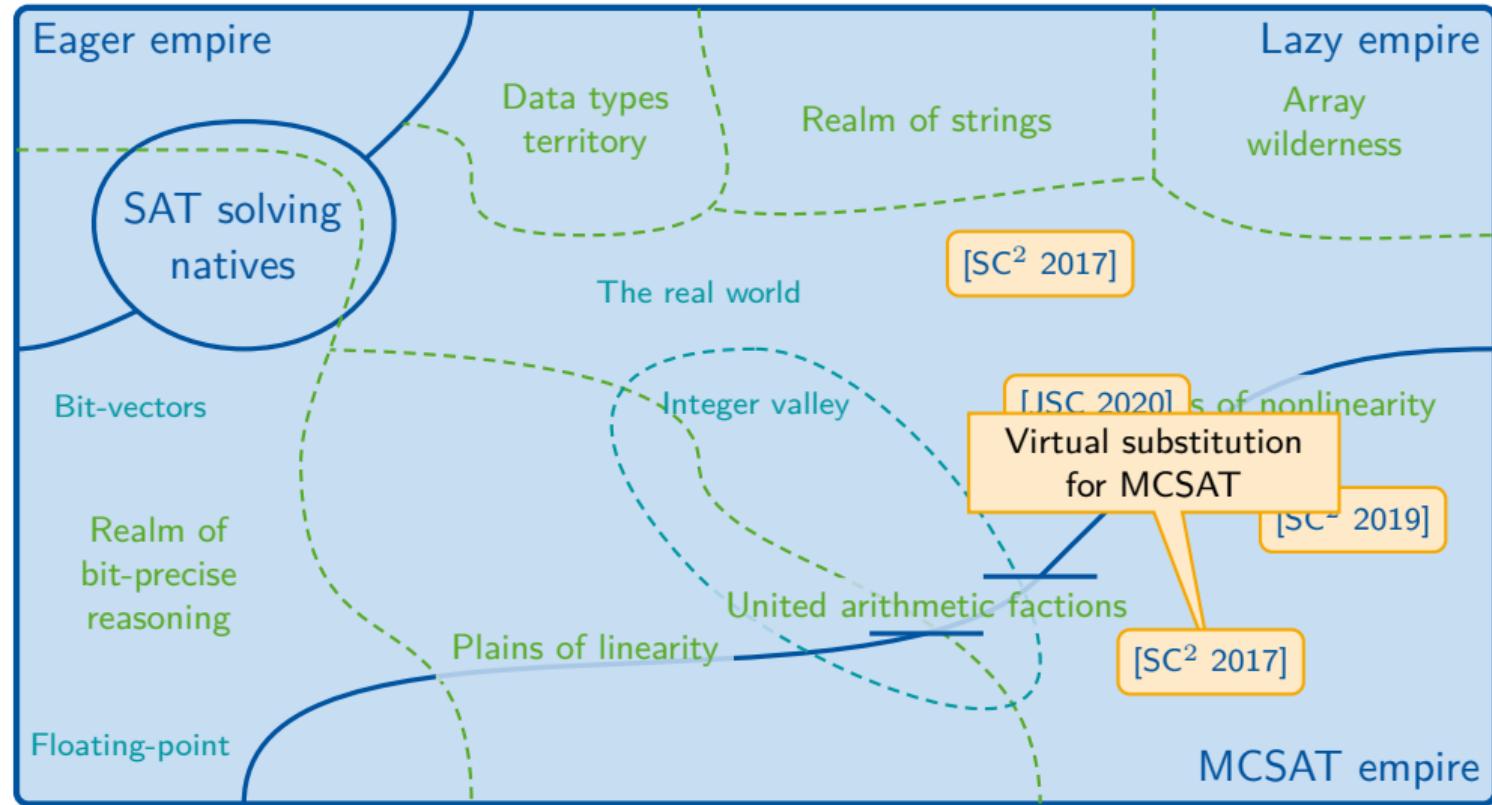
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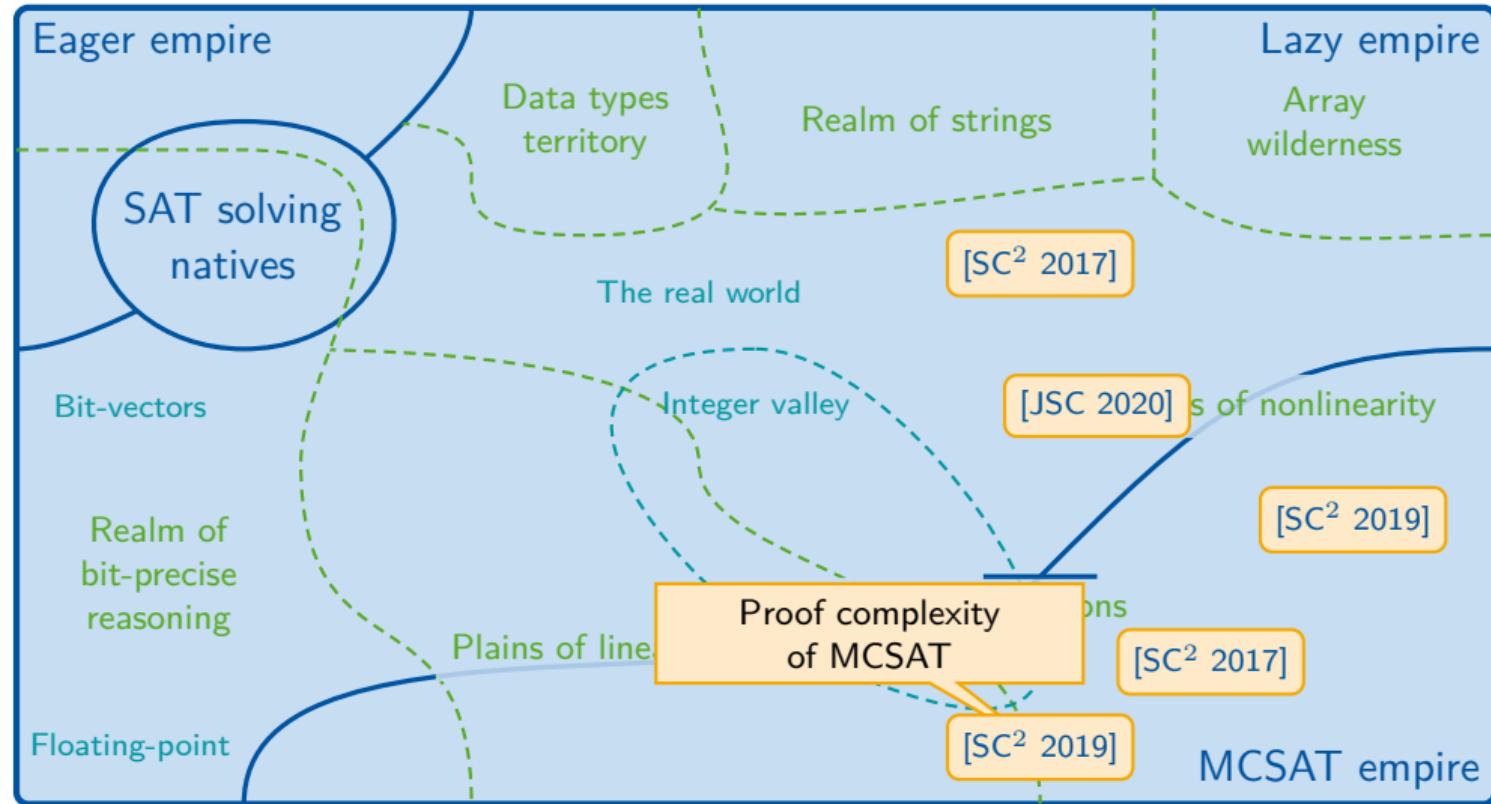
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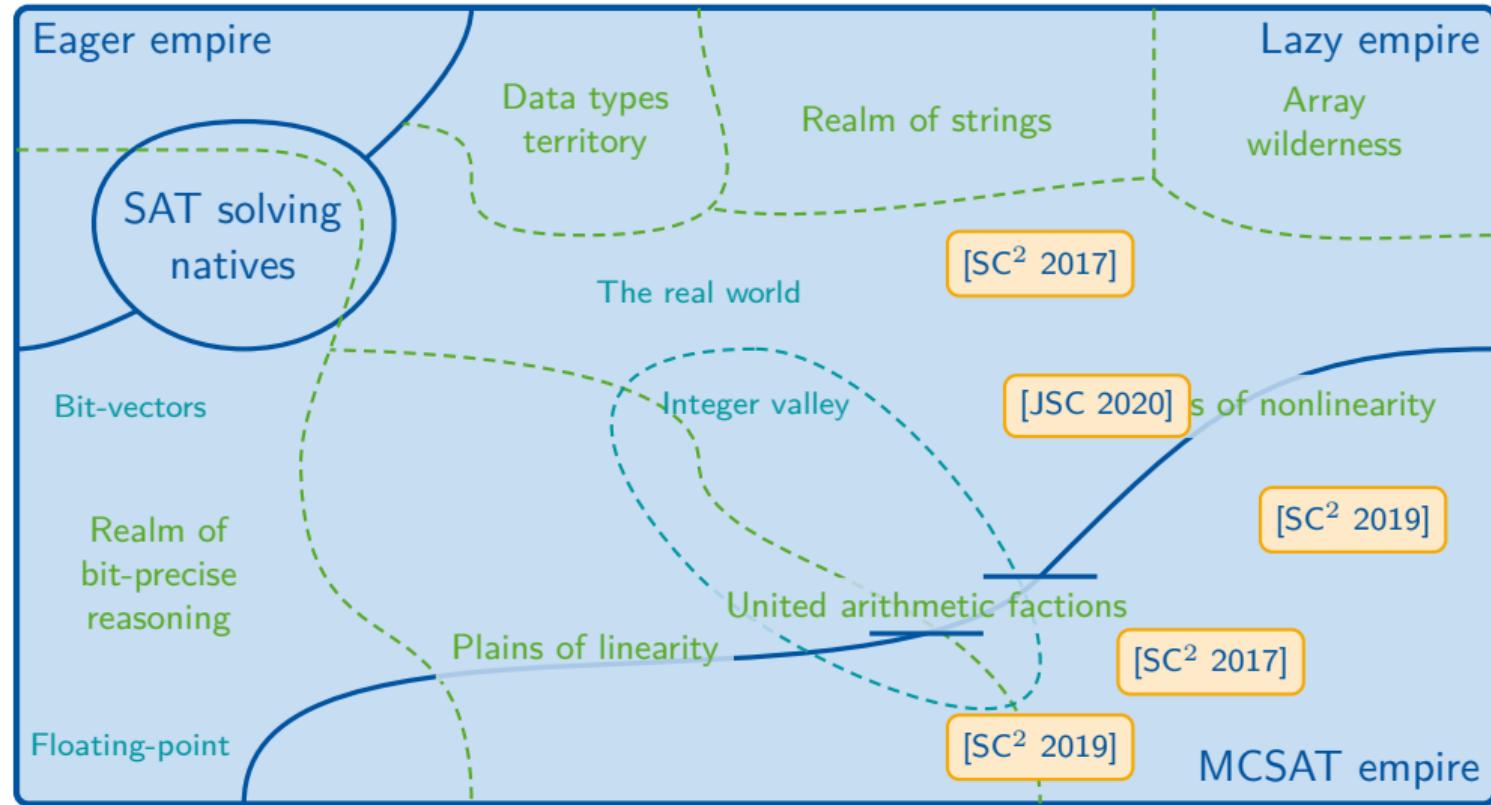
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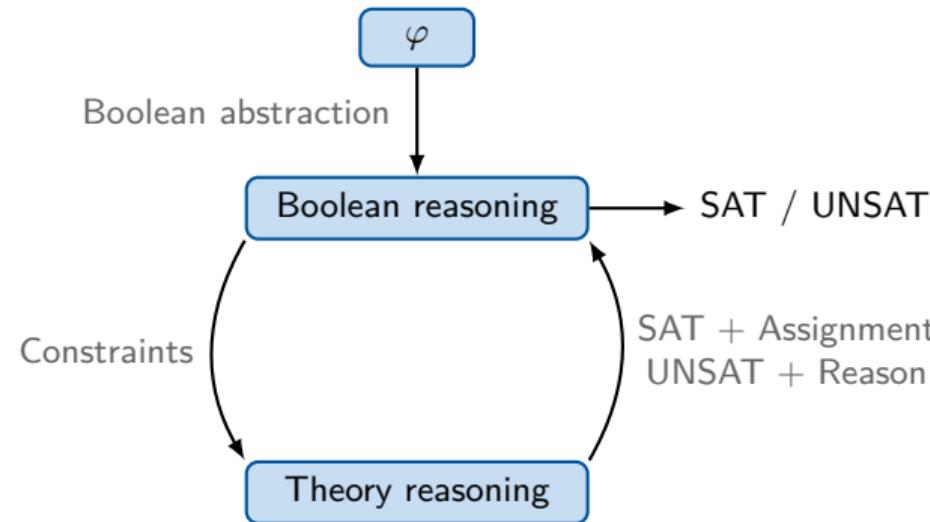
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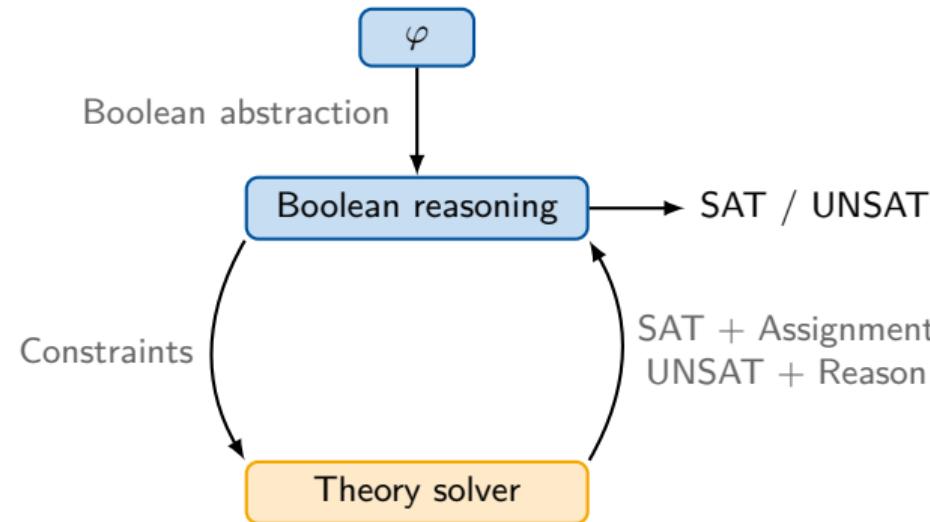
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Lazy SMT solving

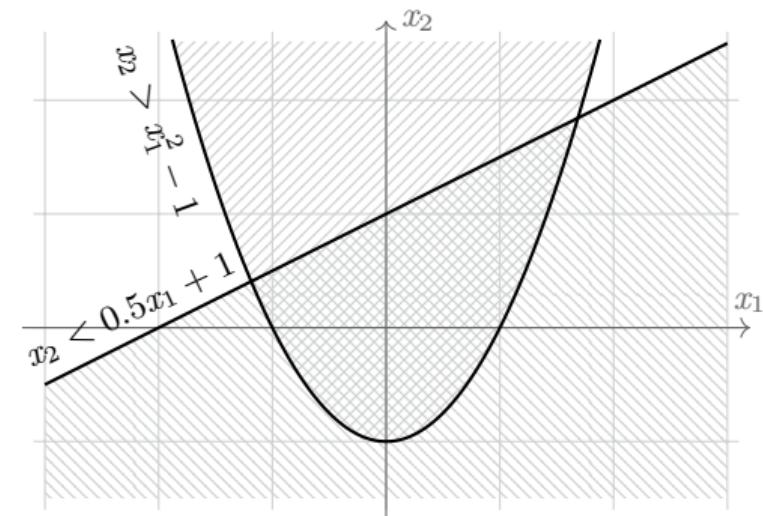


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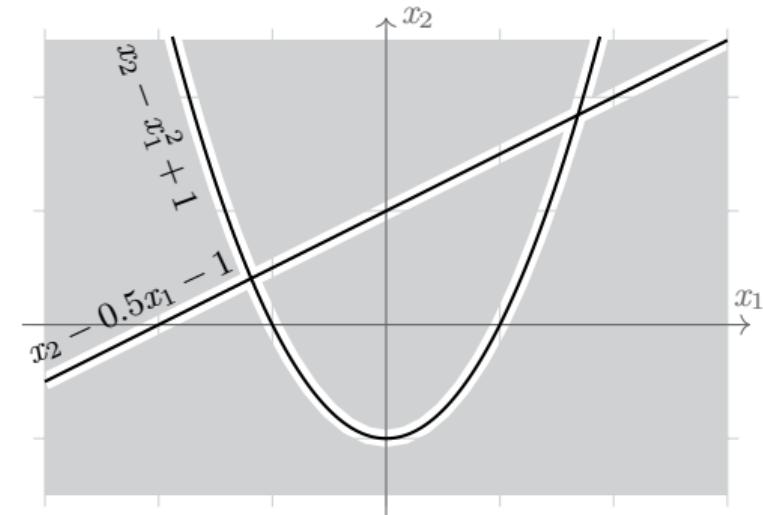
Core ideas of CAD

- Input: set of constraints



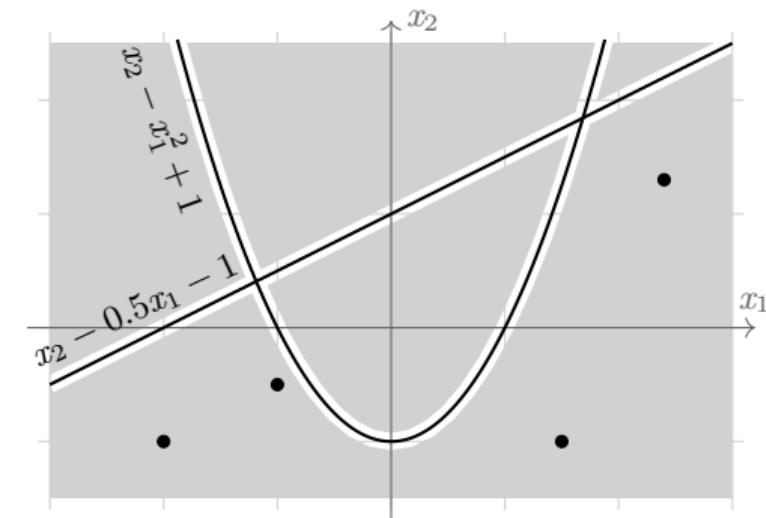
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- Identify **sign-invariant** regions



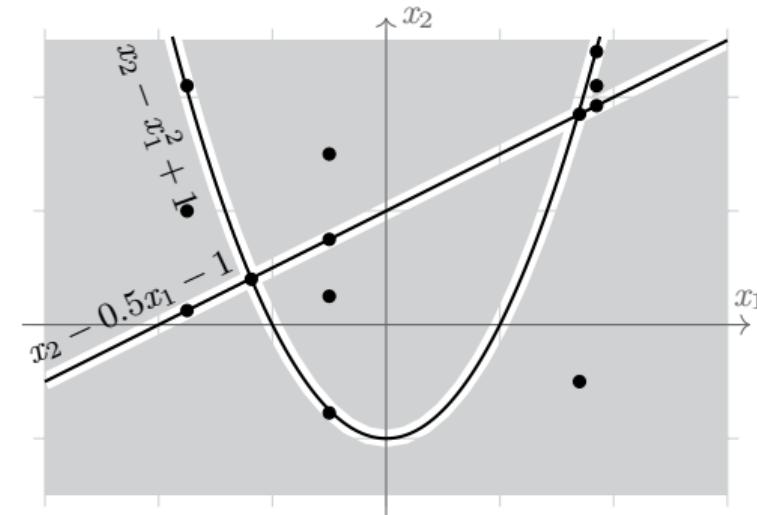
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Core ideas of CAD

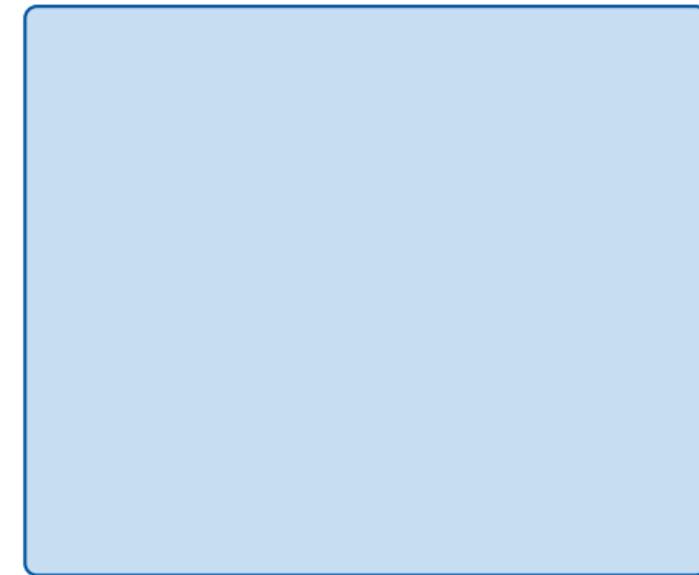
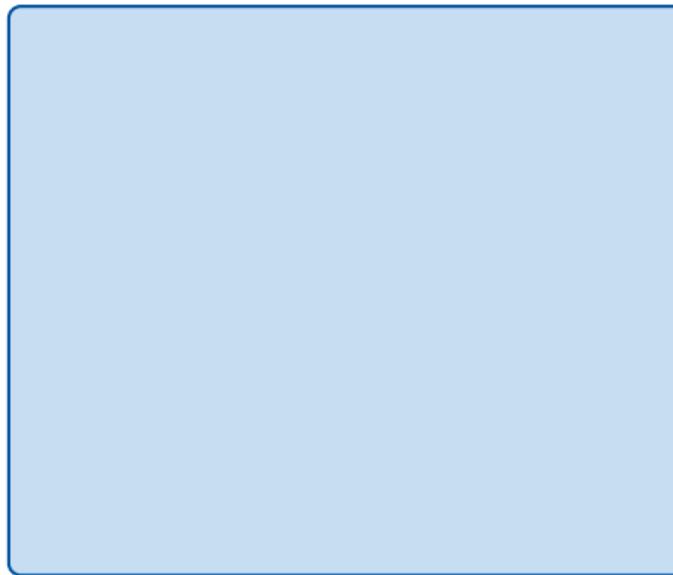
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- Sign-invariance (of polynomials) implies **truth-invariance** (of the formula)
- All samples in one region are **equivalent**
- Construct **one sample** per region
- Evaluate samples on constraints



CAD in a nutshell

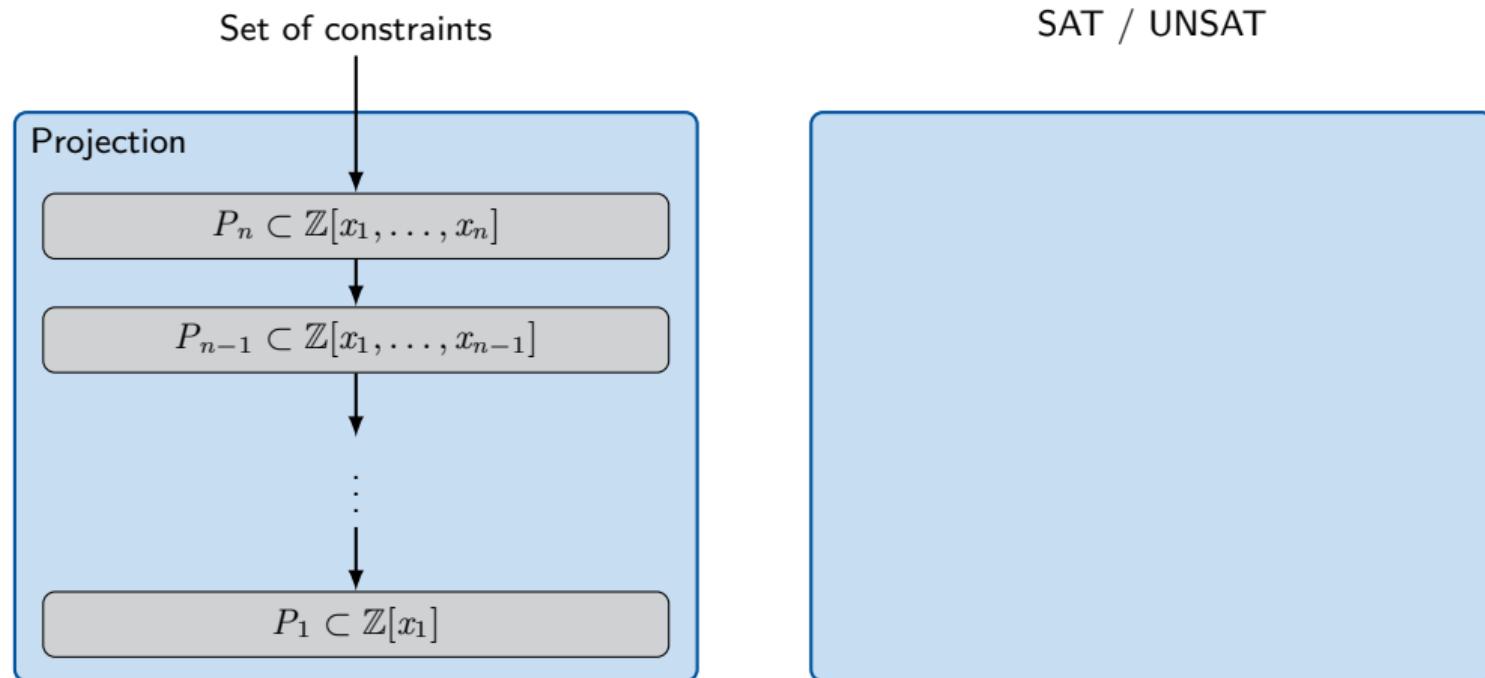
Set of constraints

SAT / UNSAT



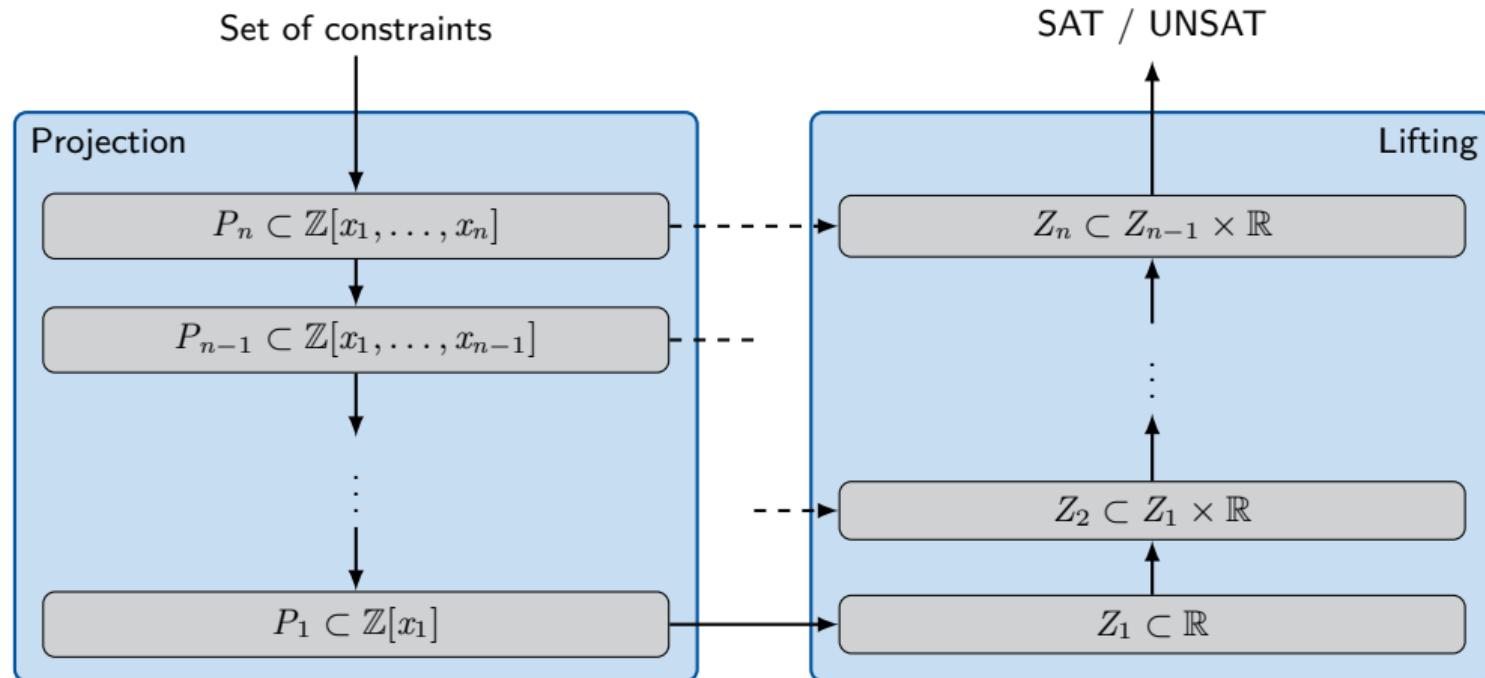
[Collins 1975]

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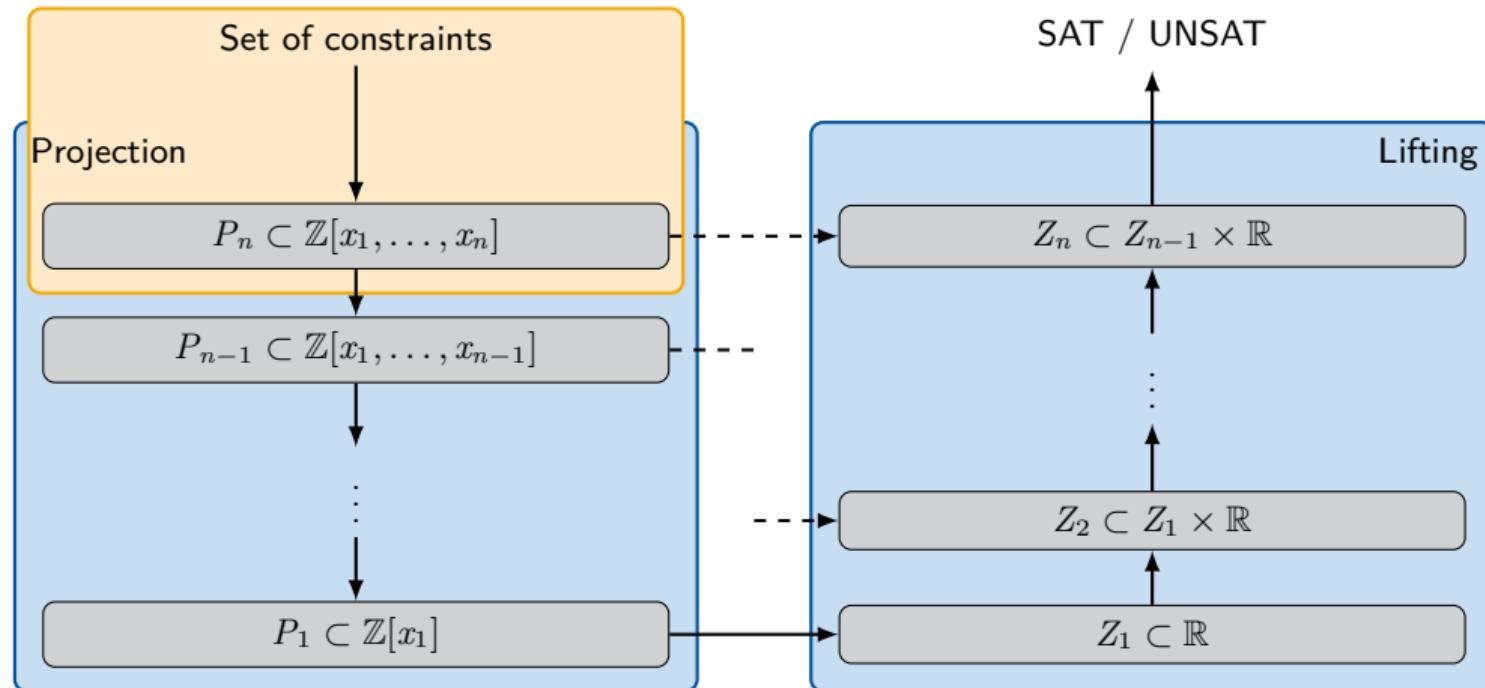
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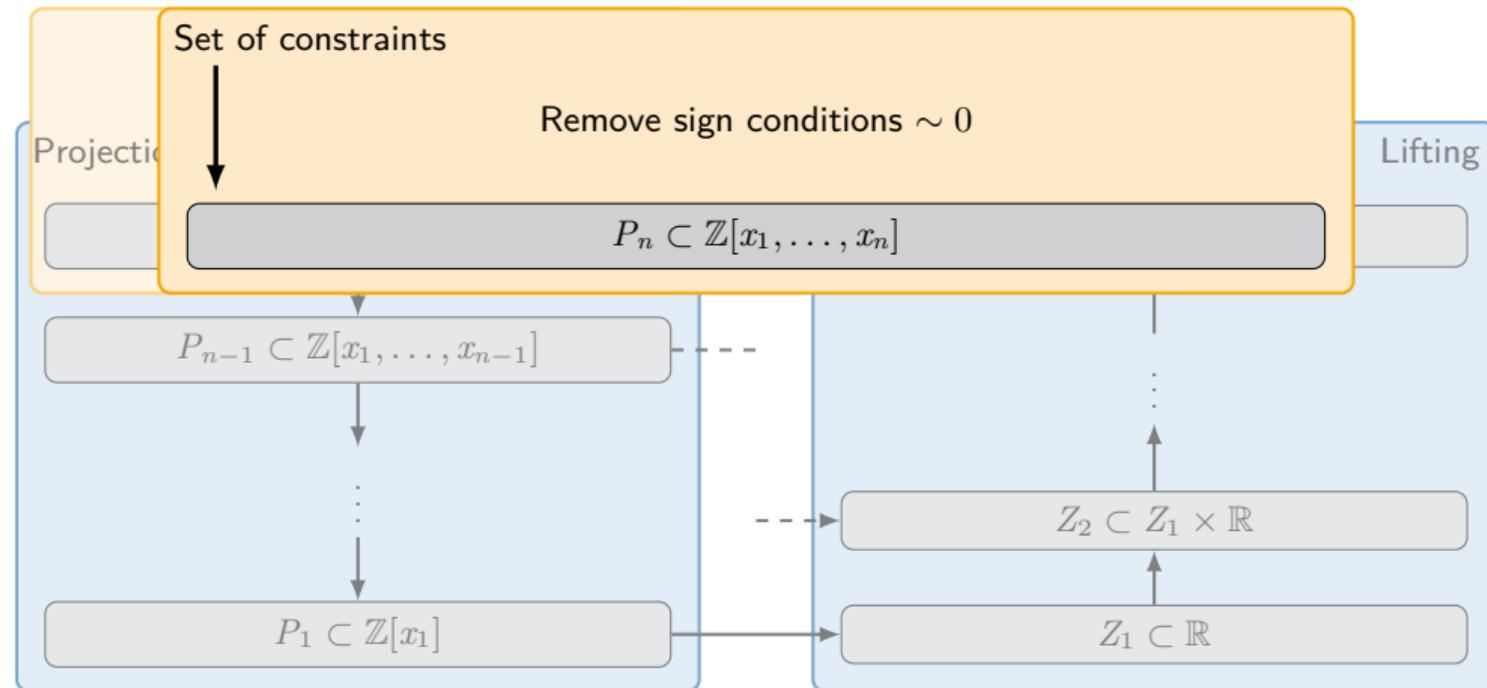
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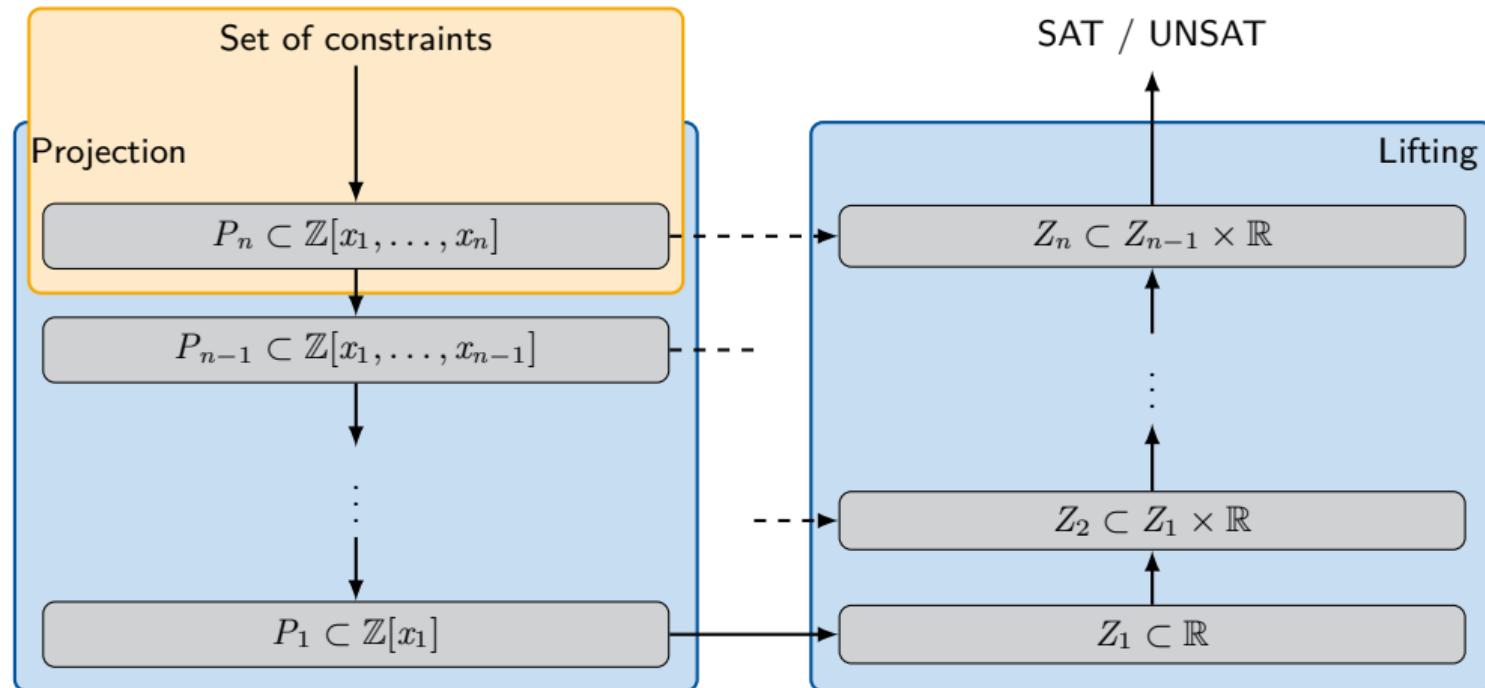
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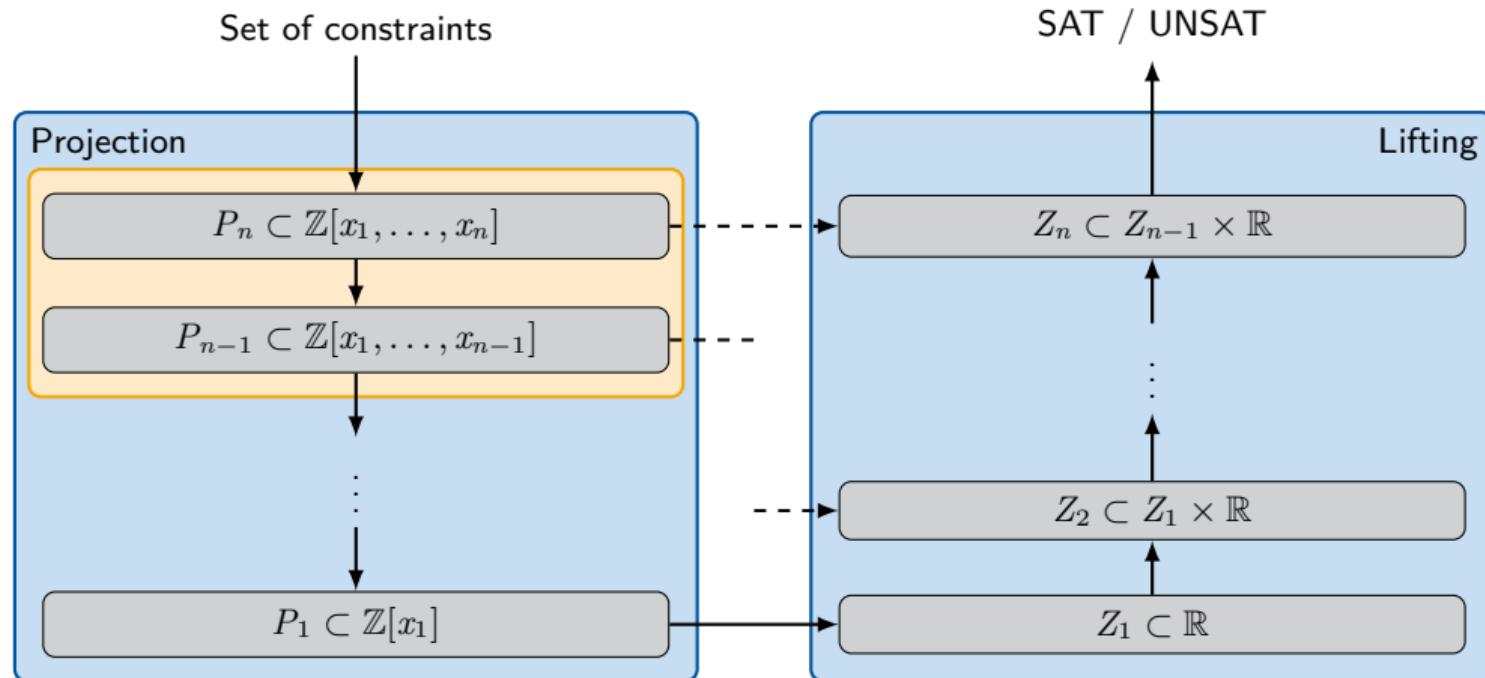
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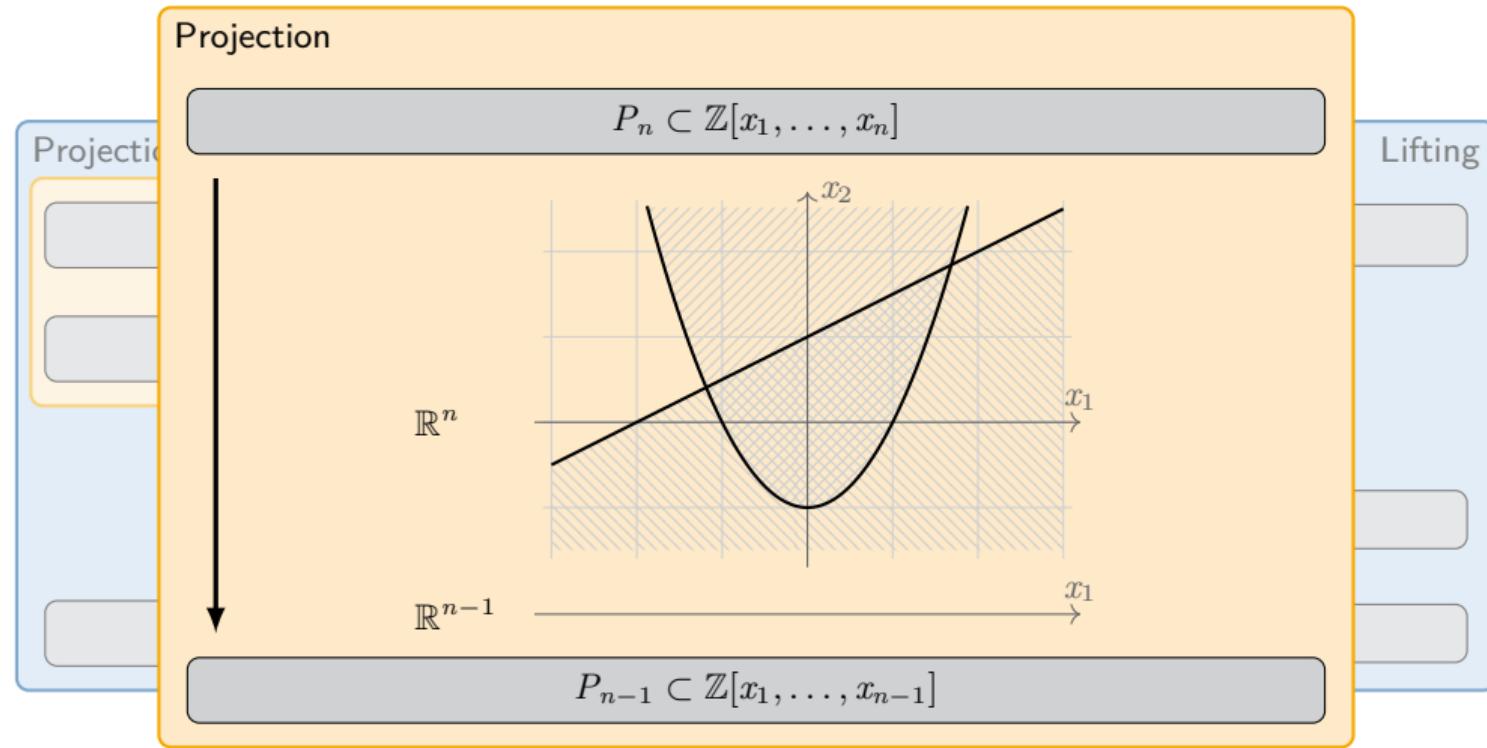
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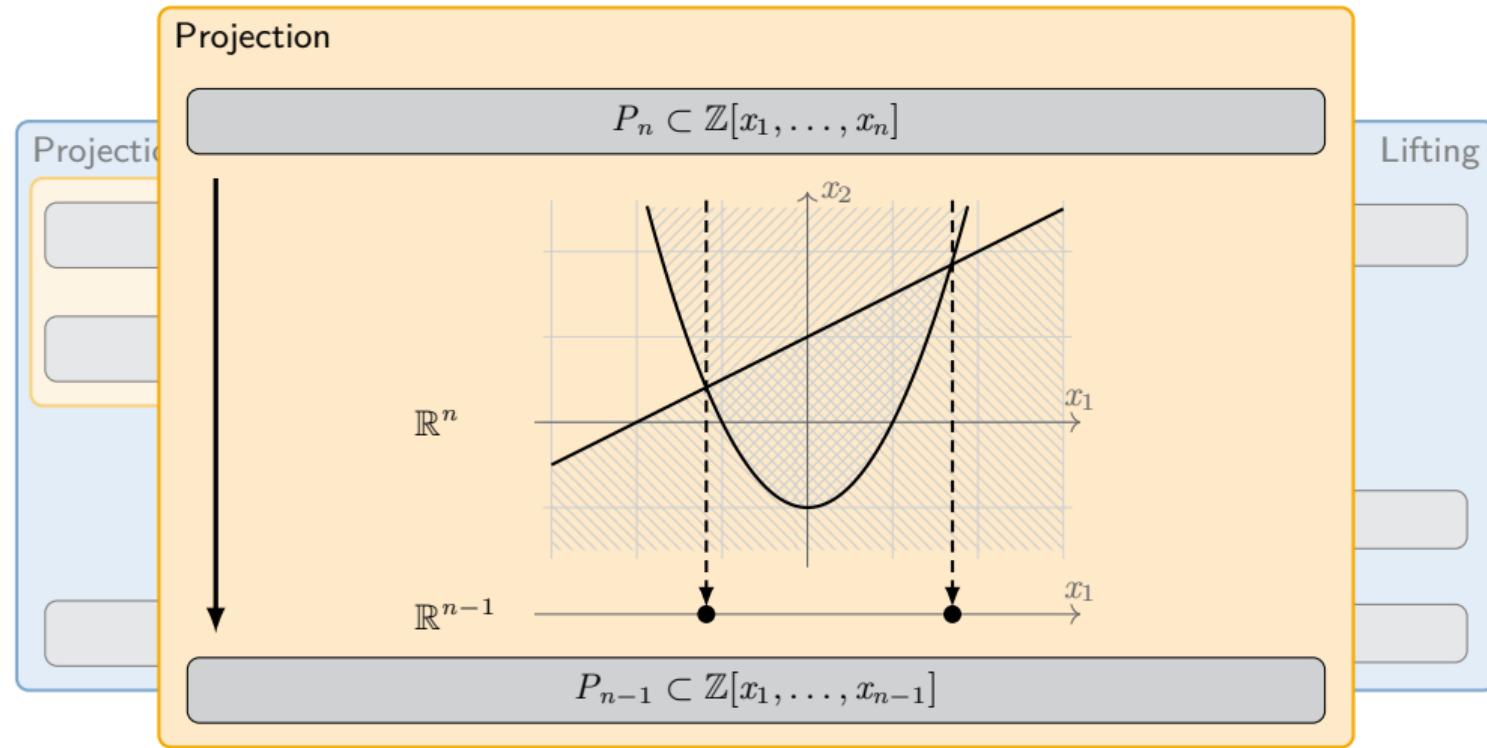
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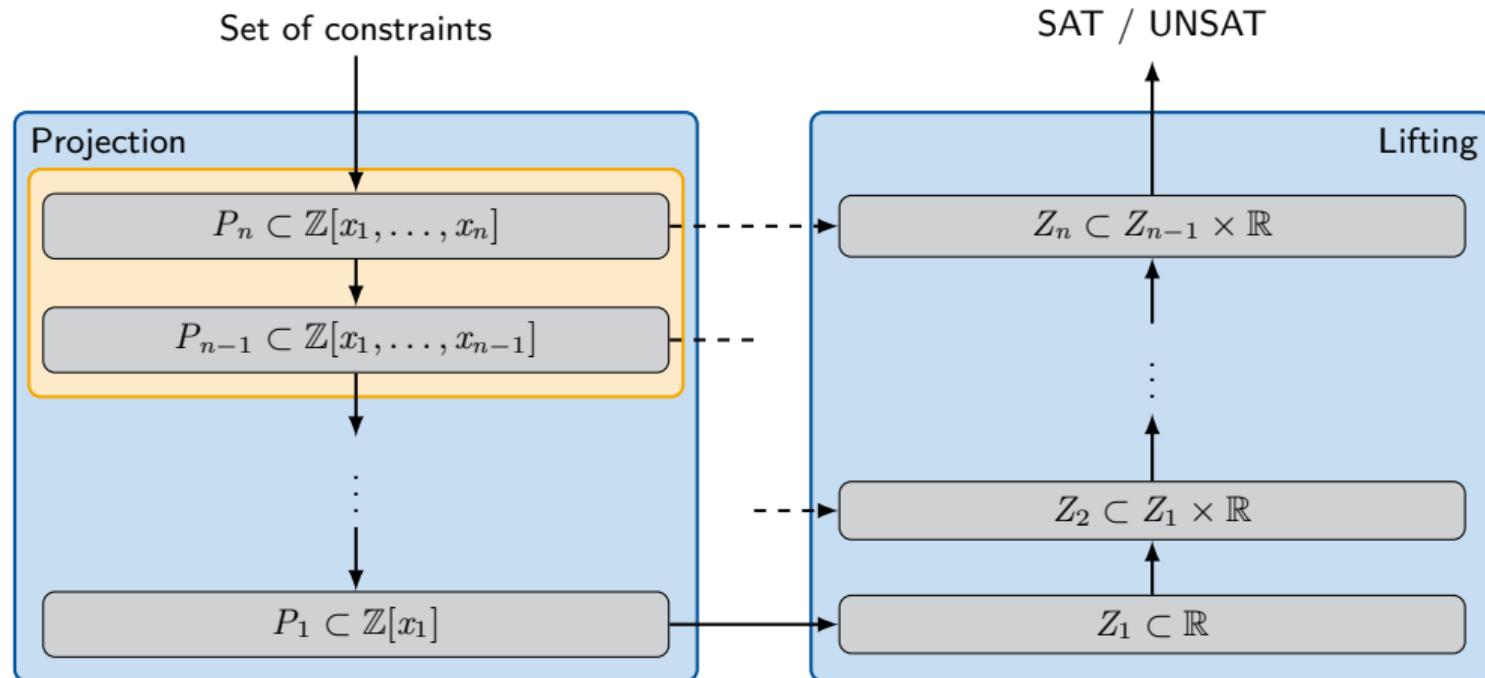
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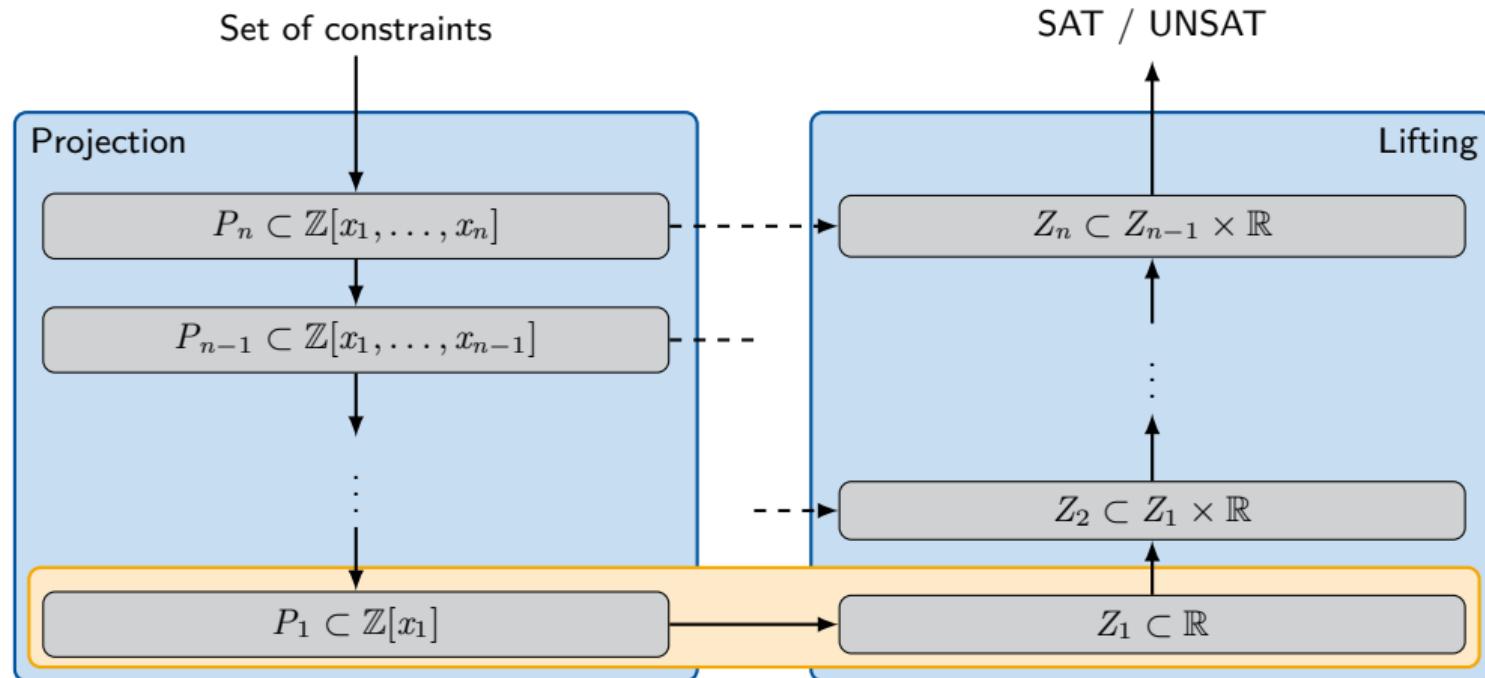
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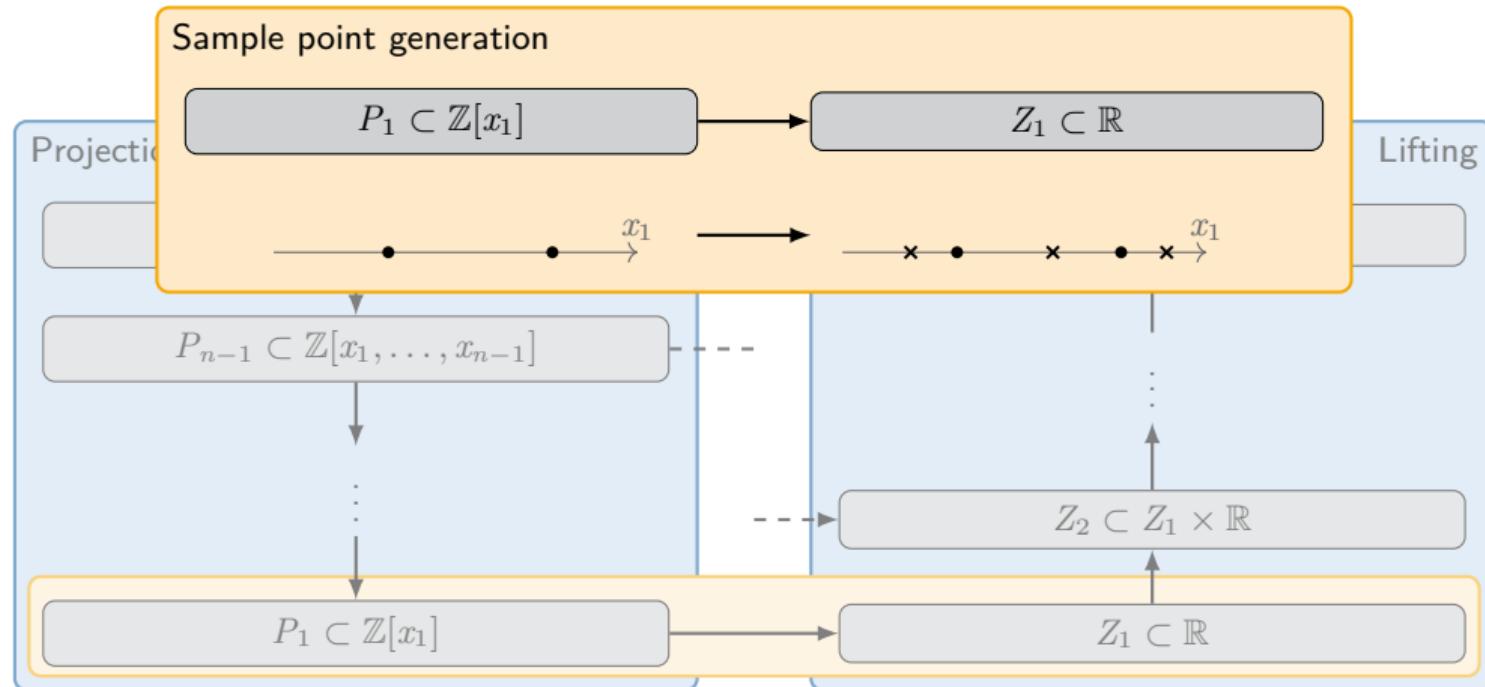
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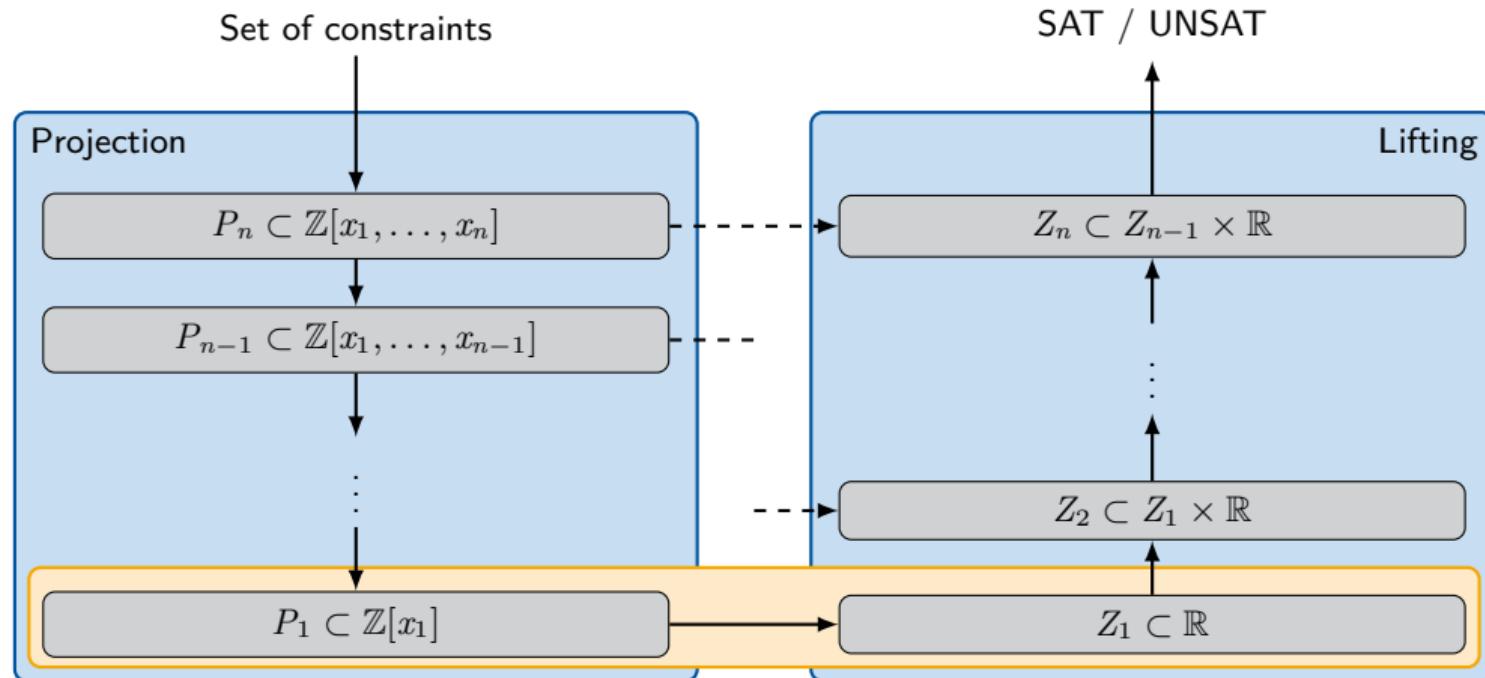
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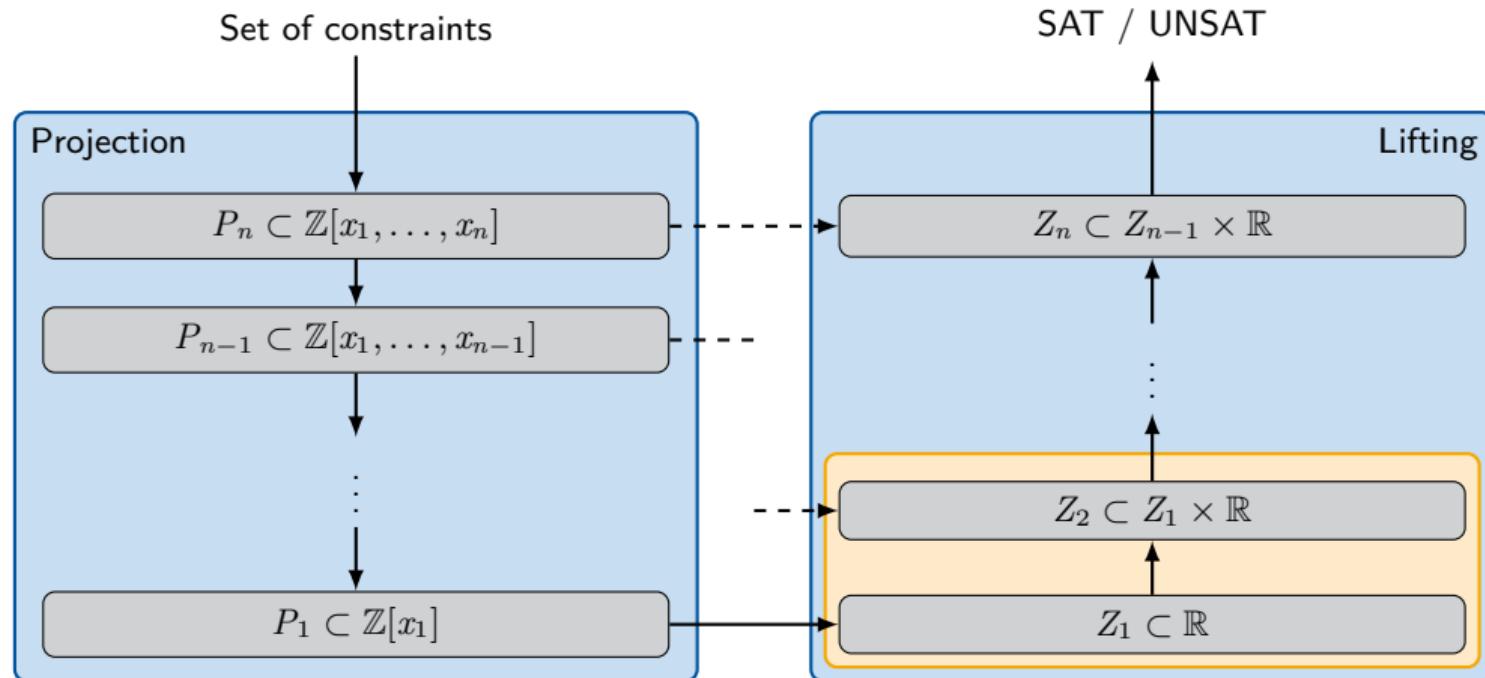
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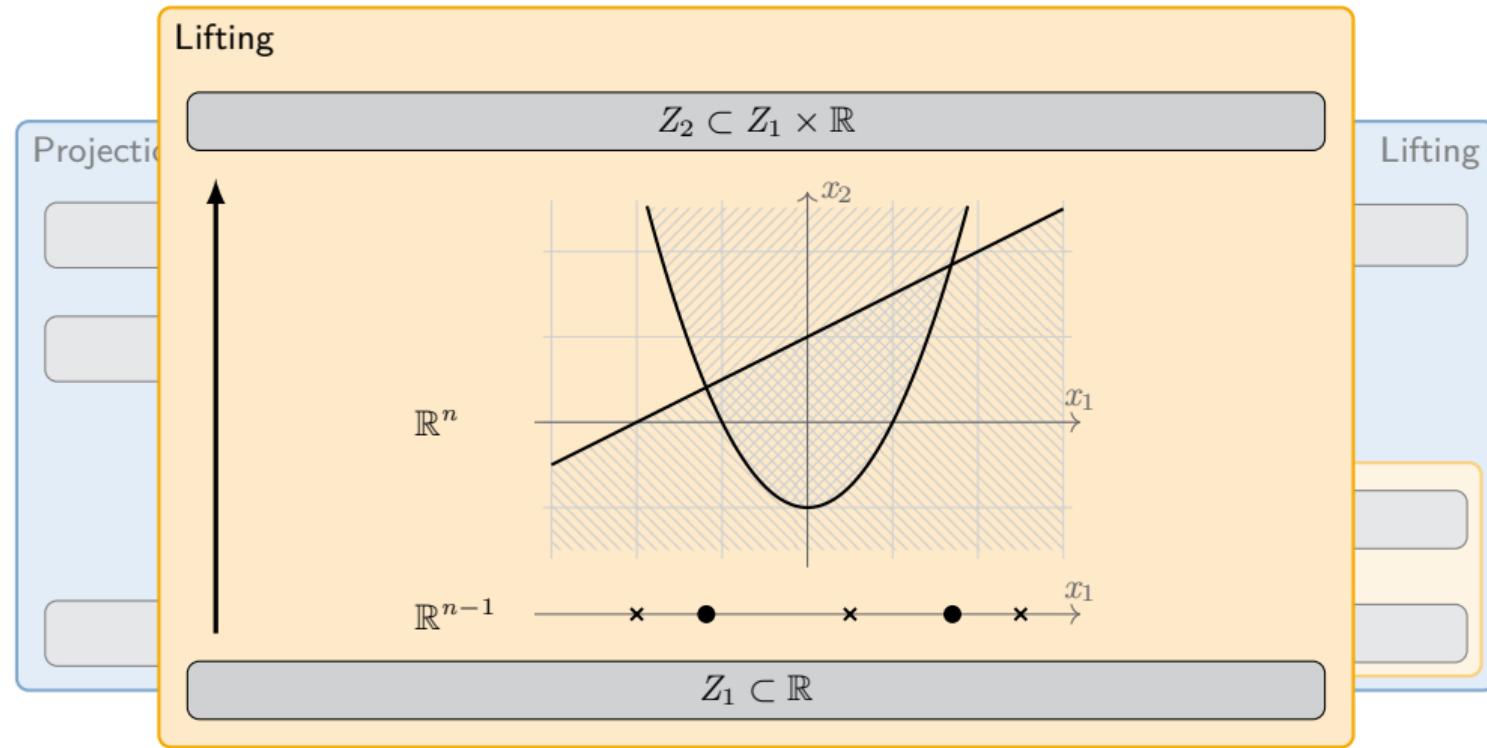
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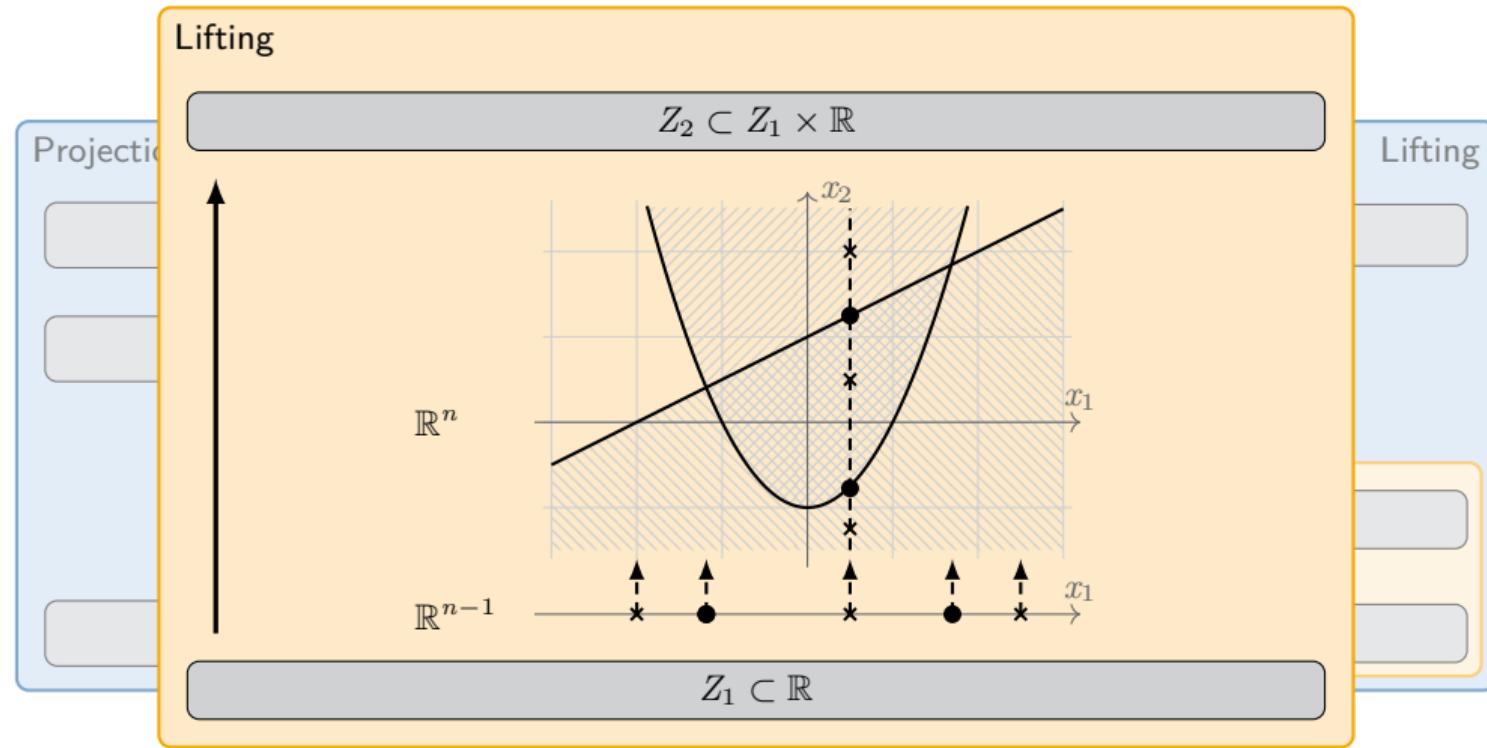
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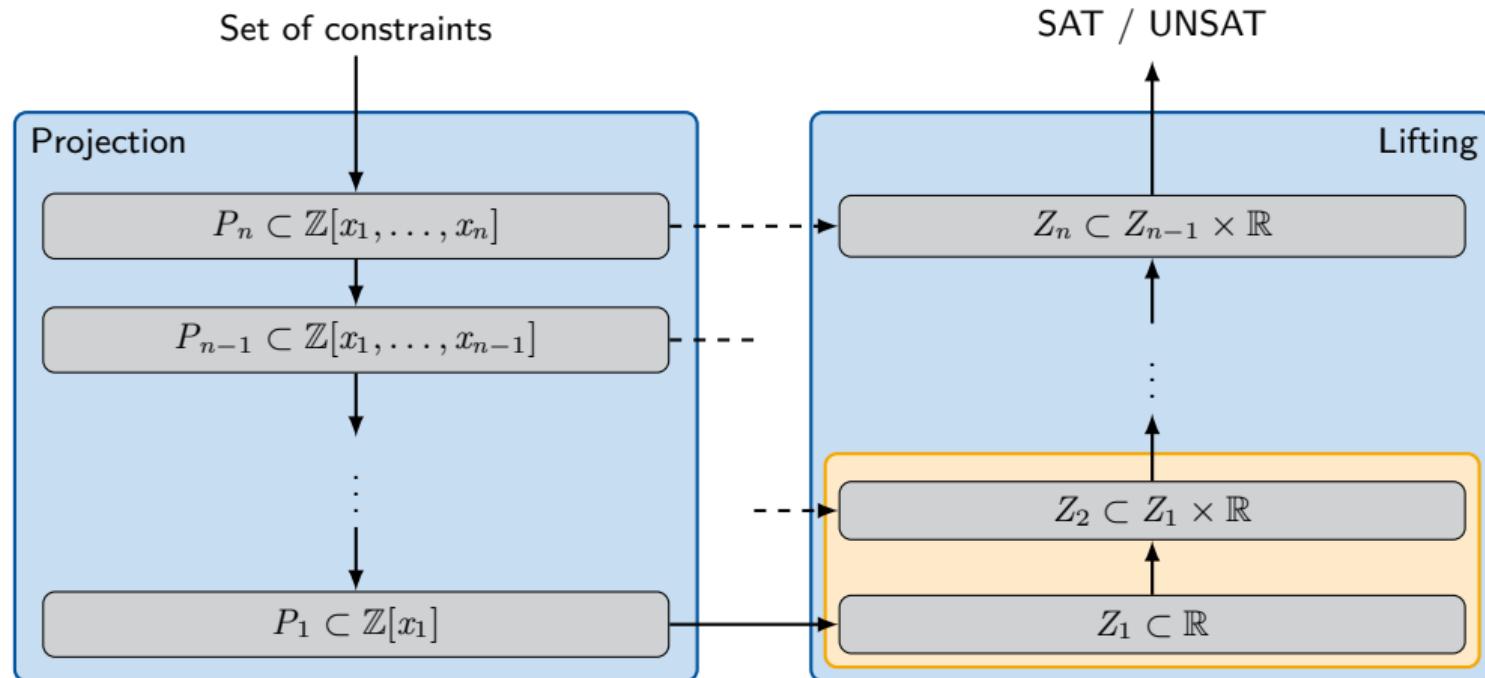
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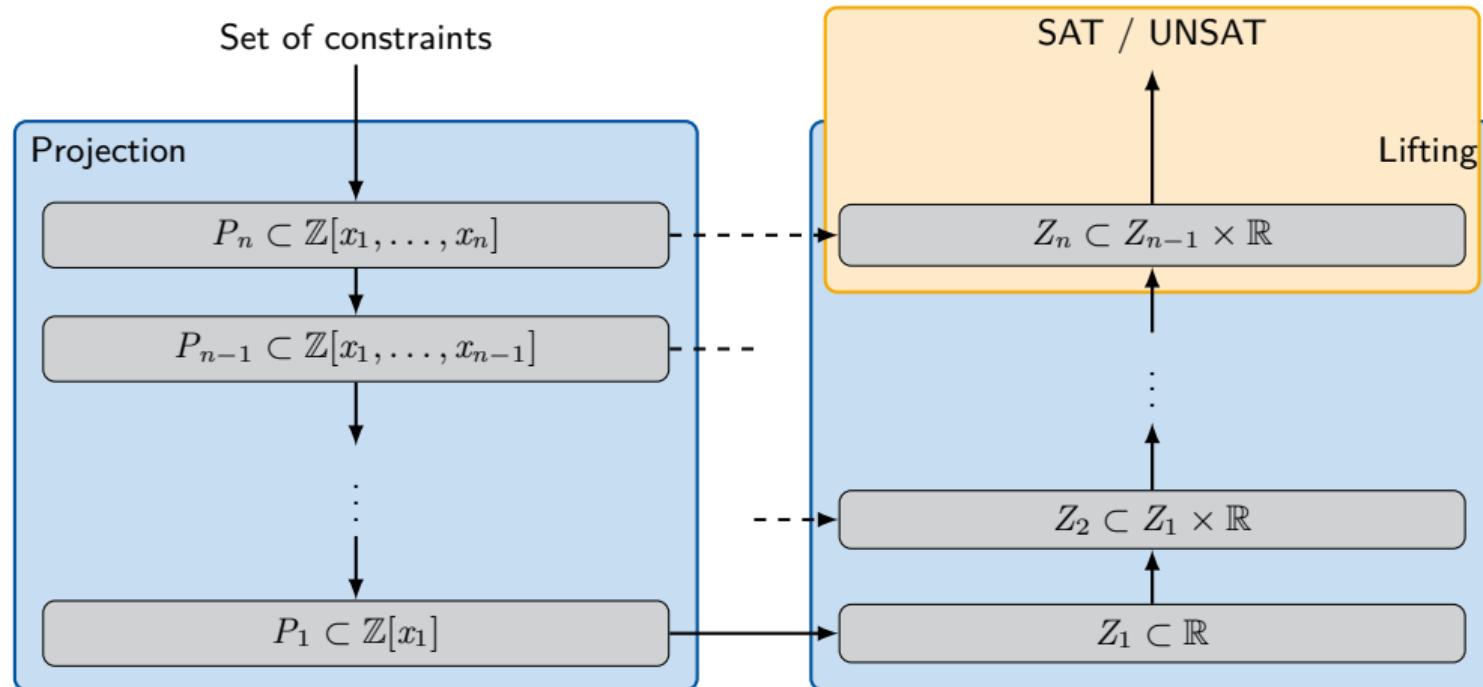
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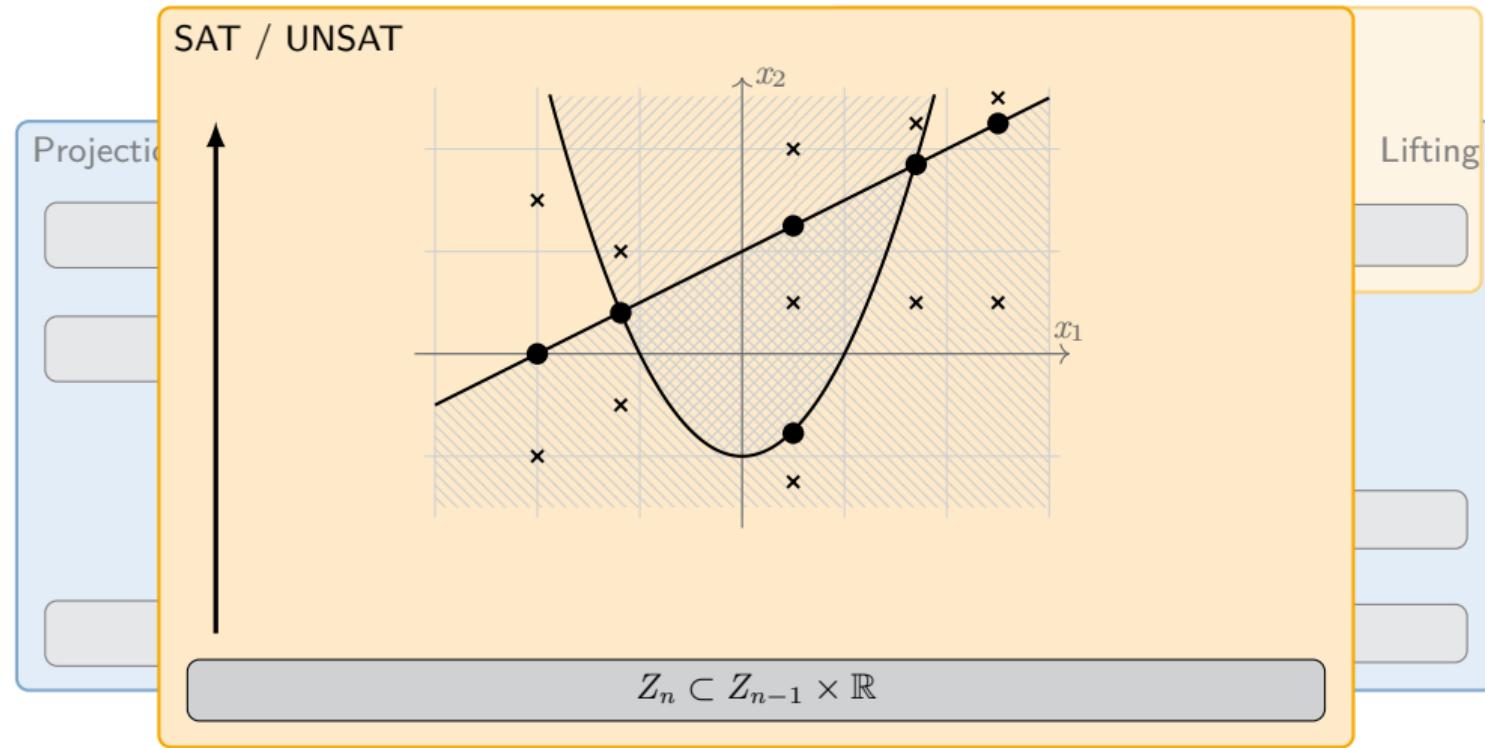
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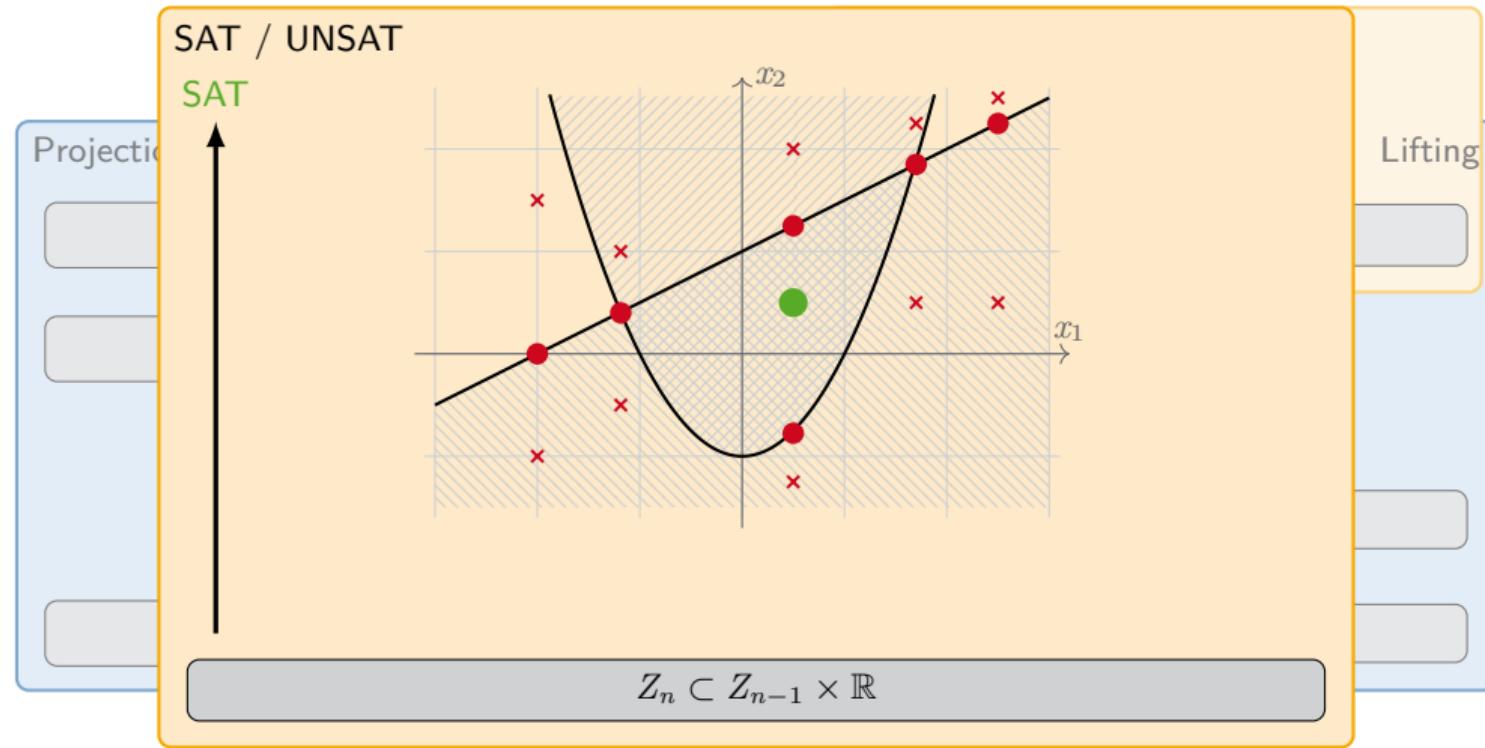
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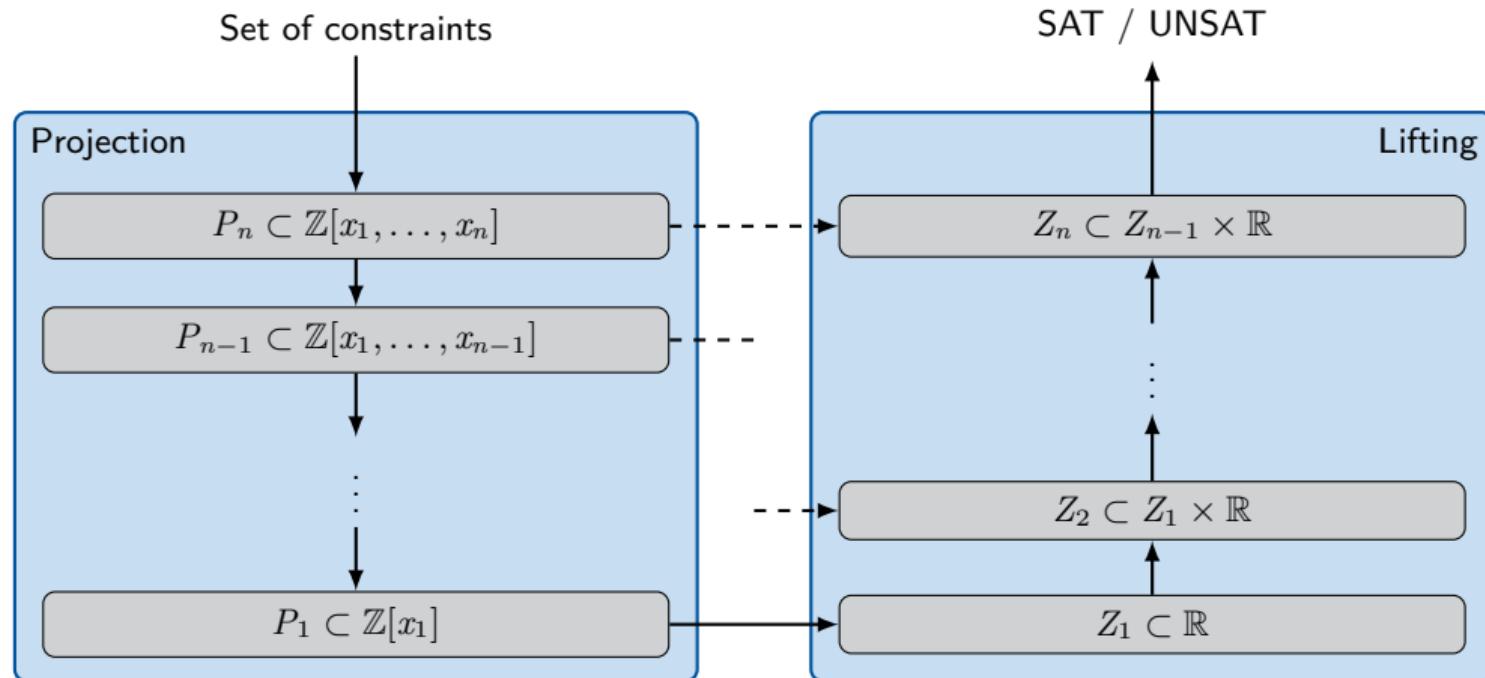
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CAD in a nutshell



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Towards incrementality

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Our goal: make CAD as efficient as possible for SMT

Towards incrementality

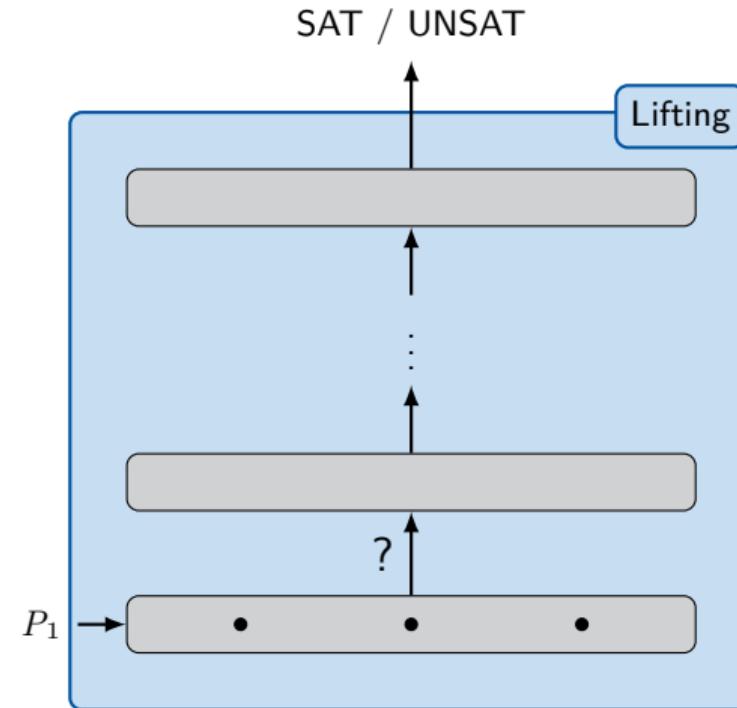
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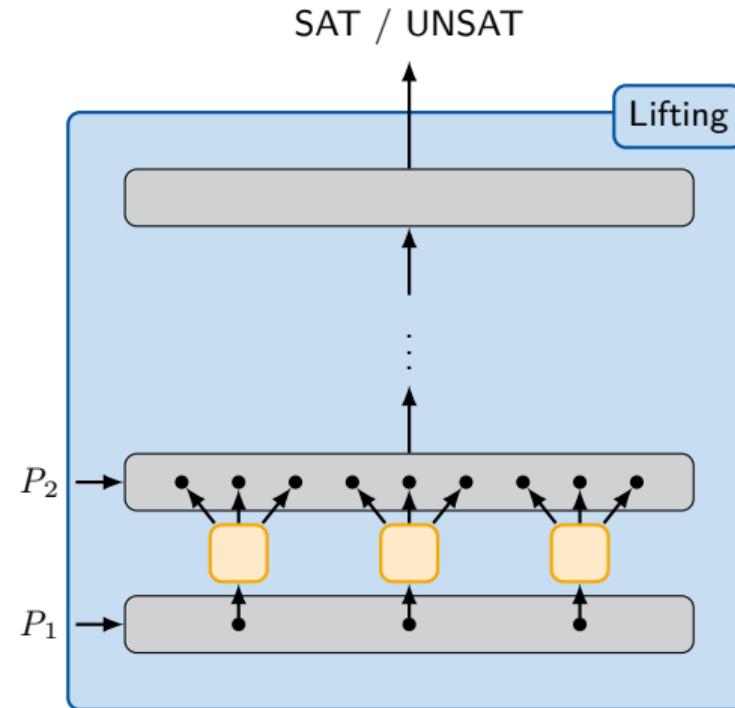
- Incrementality: reuse previously computed results
- Backtracking: remove part of the input efficiently
- Reasons for unsatisfiability: small infeasible subsets

Incremental lifting



[Collins + 1991]

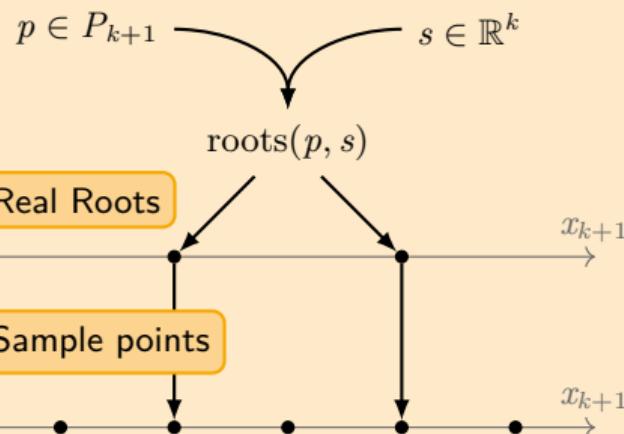
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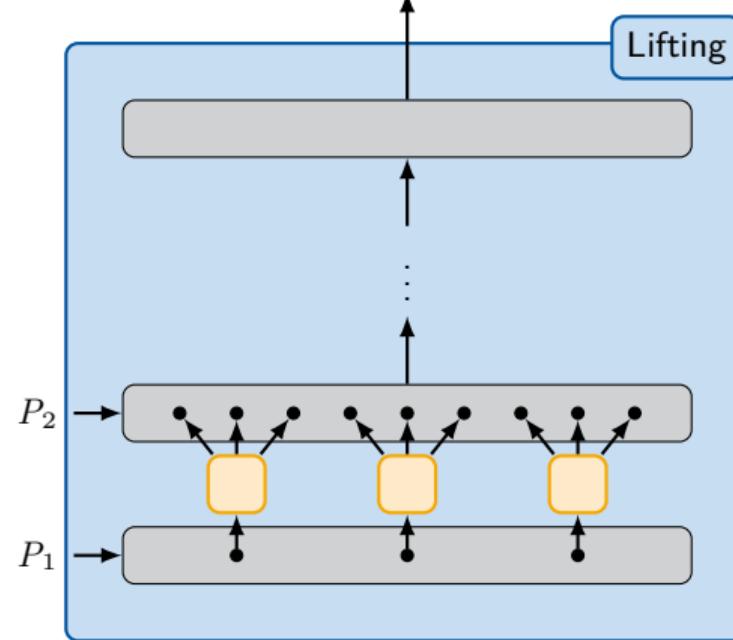
[Collins + 1991]

Incremental lifting

Lifting operator



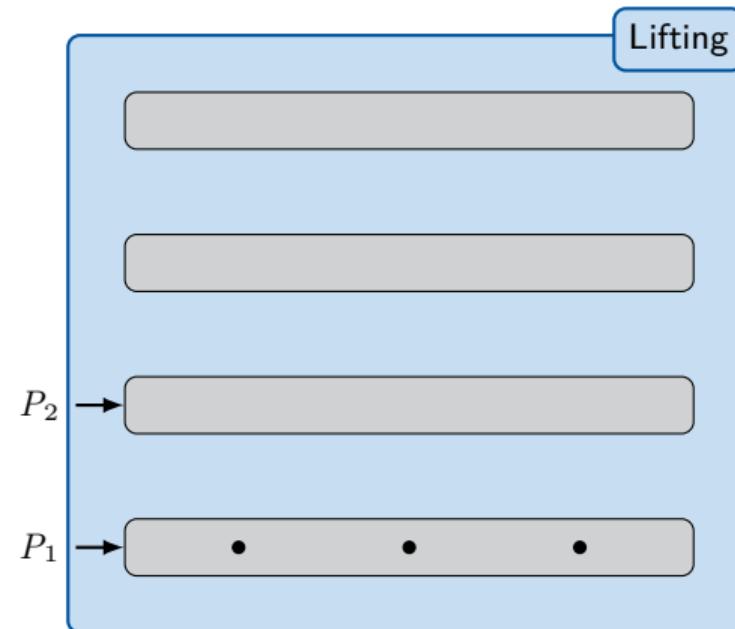
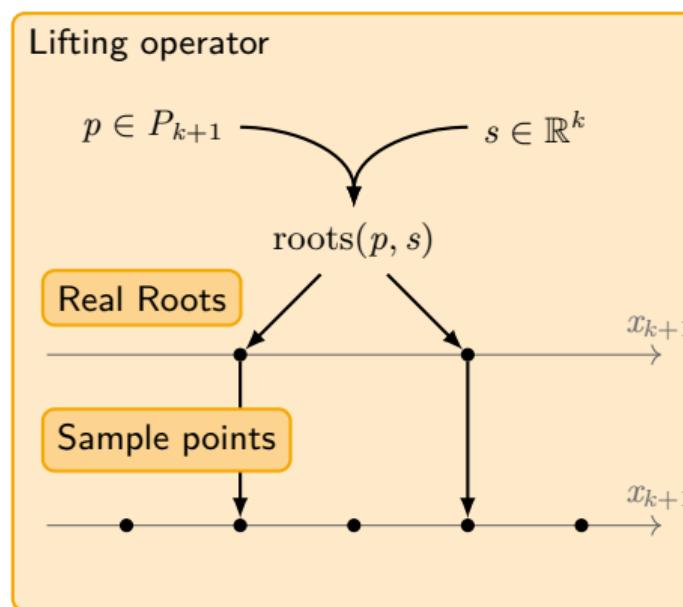
SAT / UNSAT



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Incremental lifting

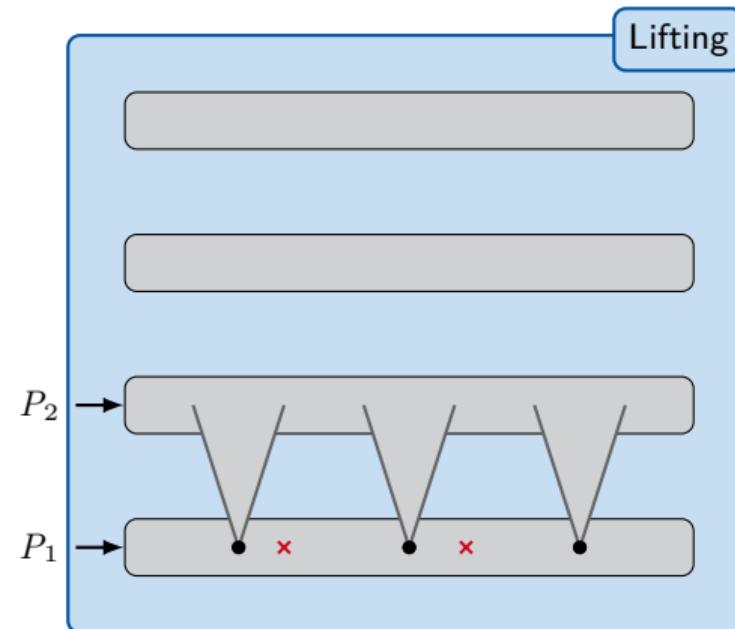
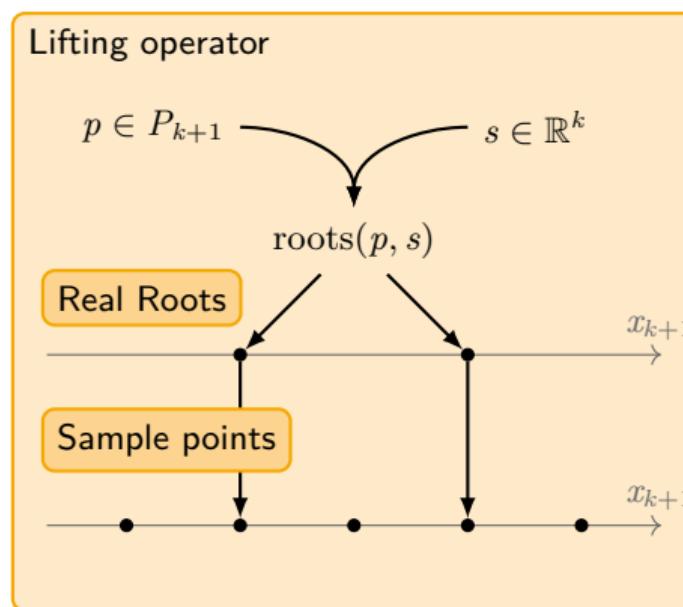
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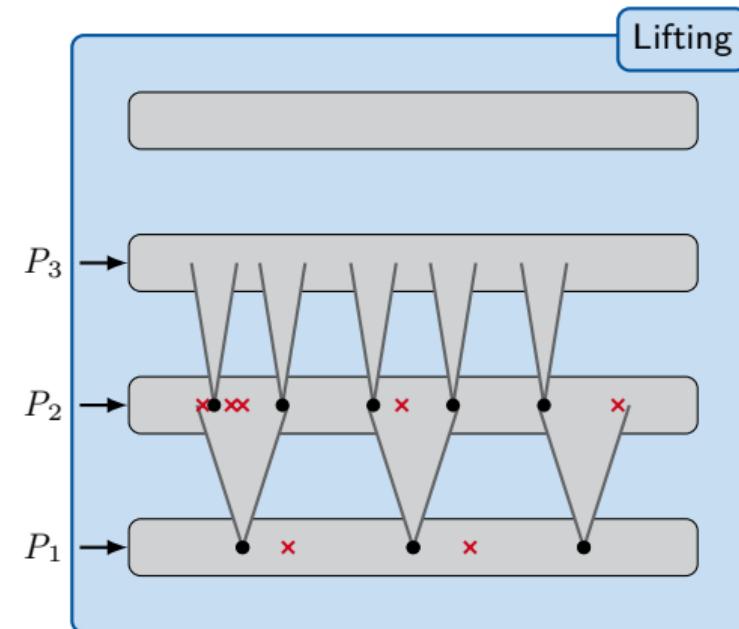
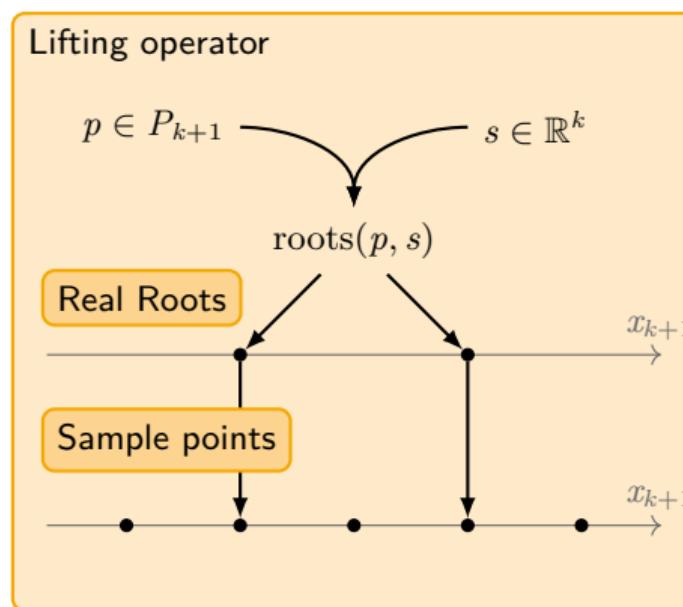
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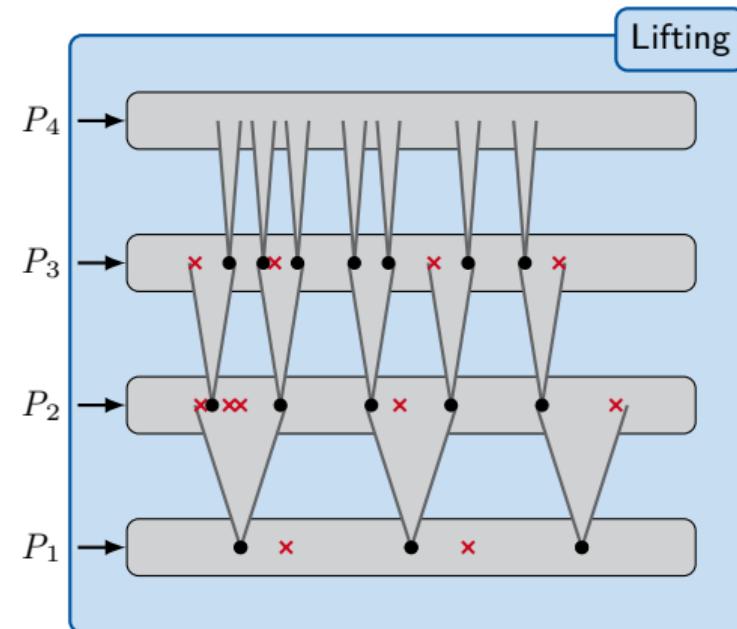
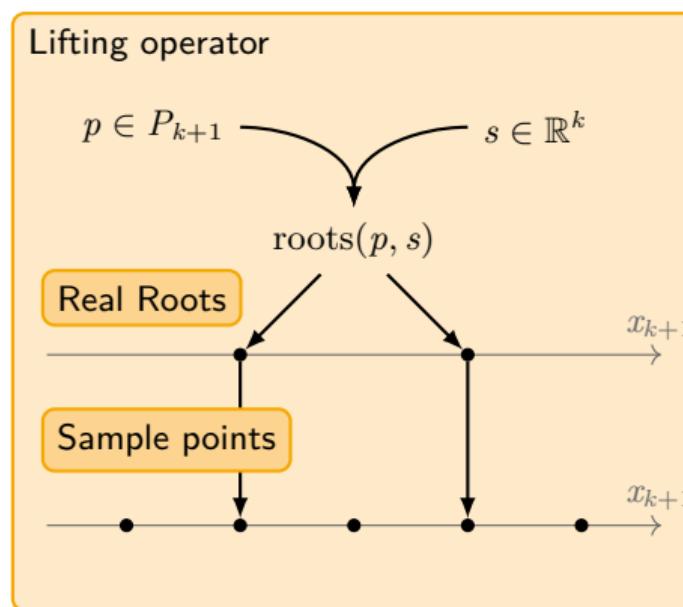
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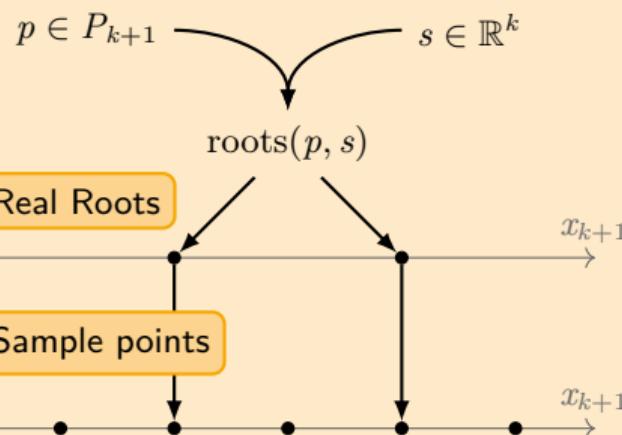
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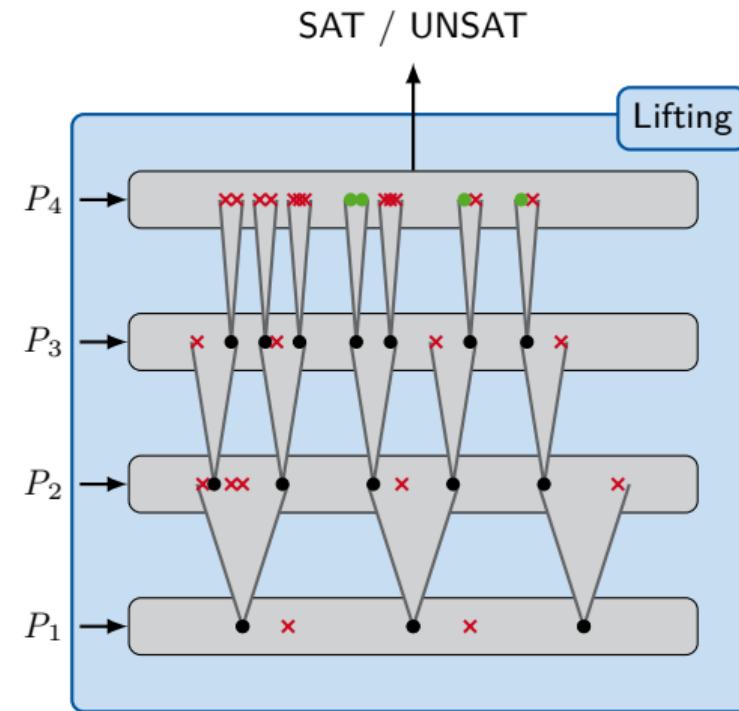
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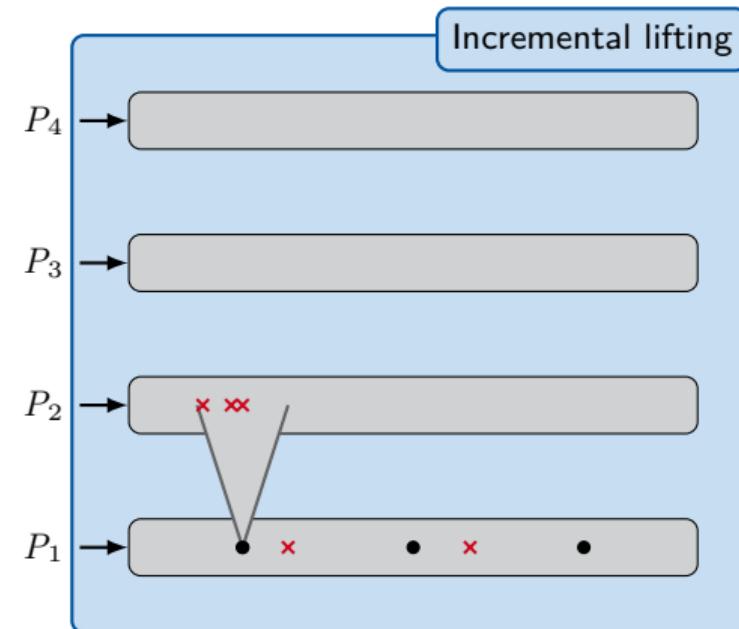
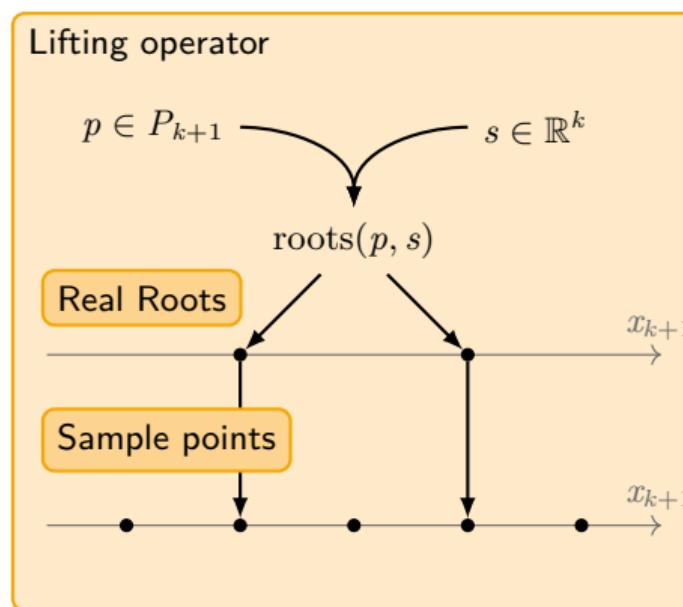


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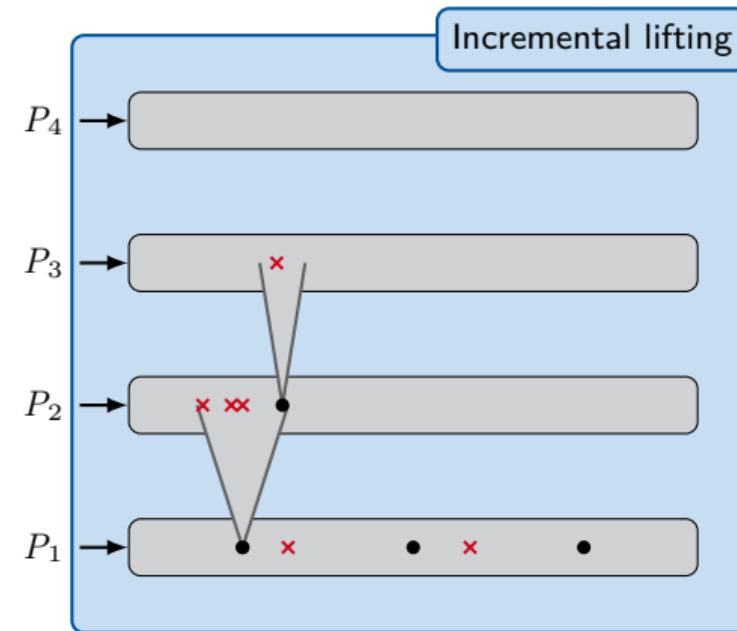
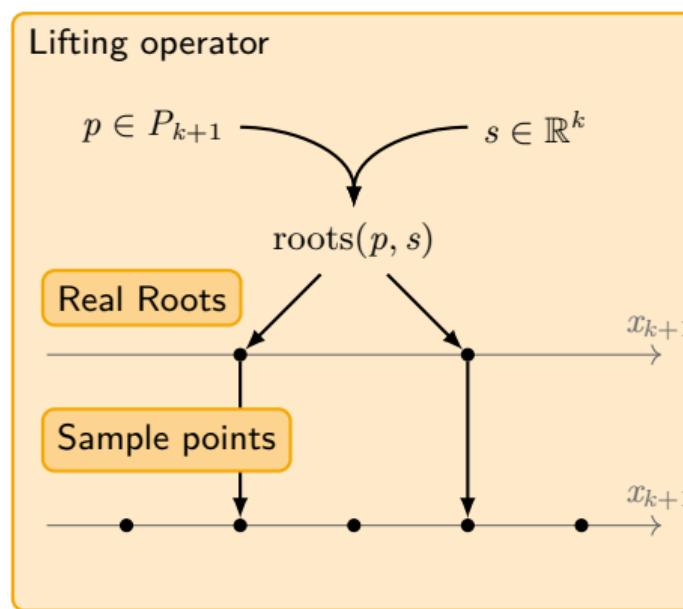
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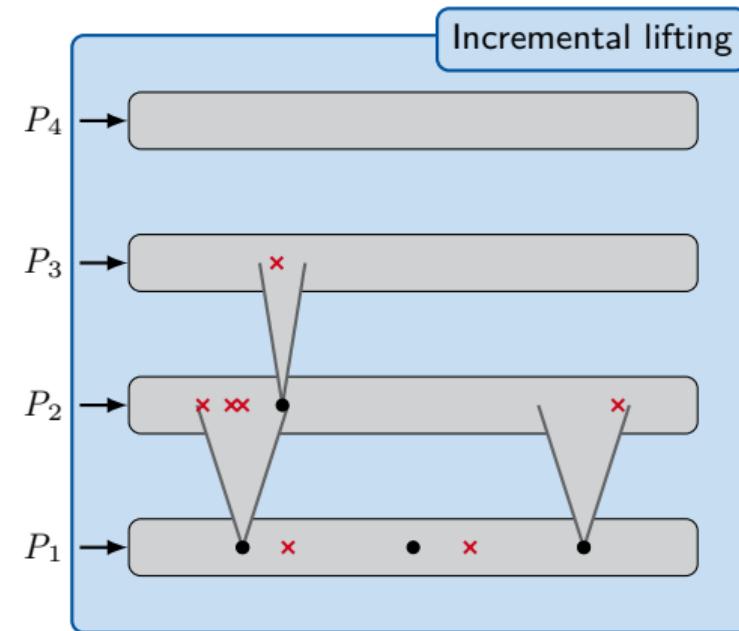
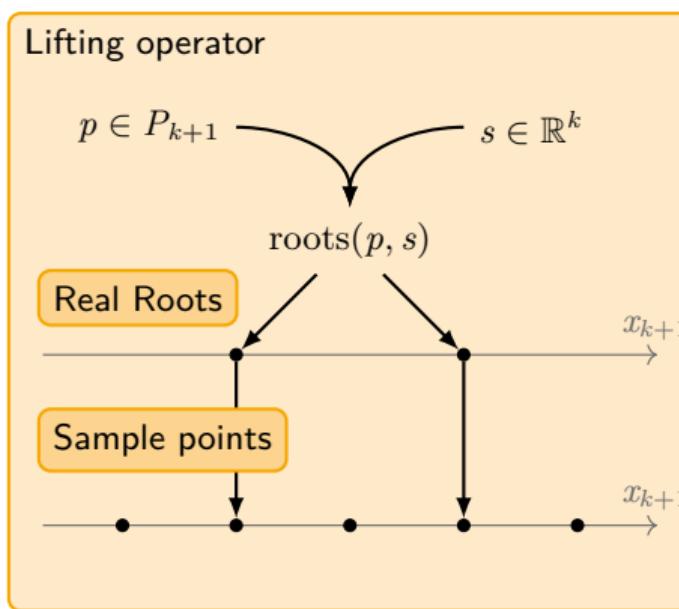
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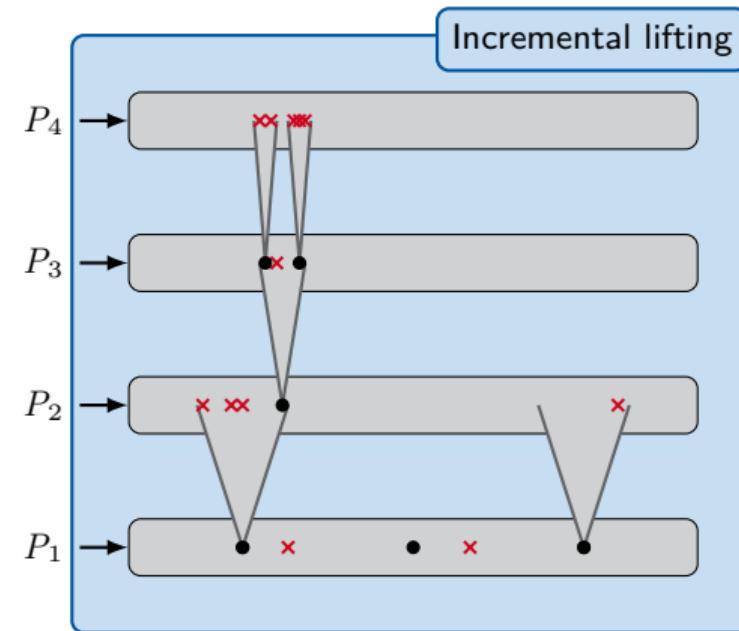
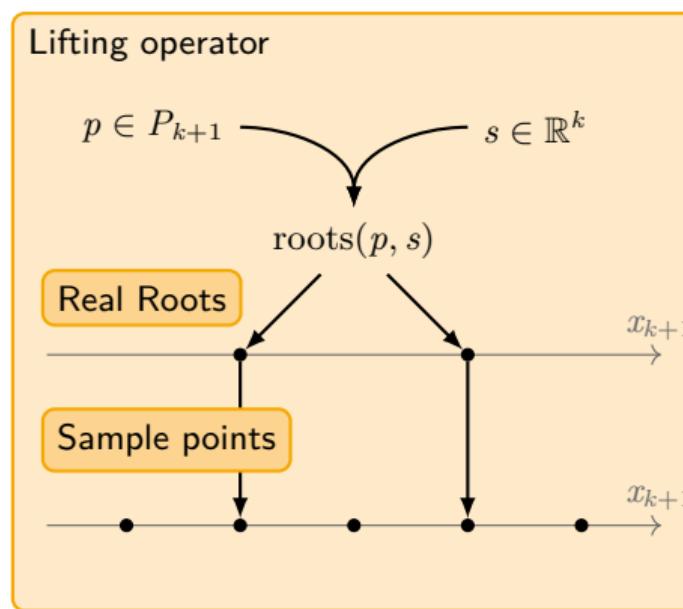
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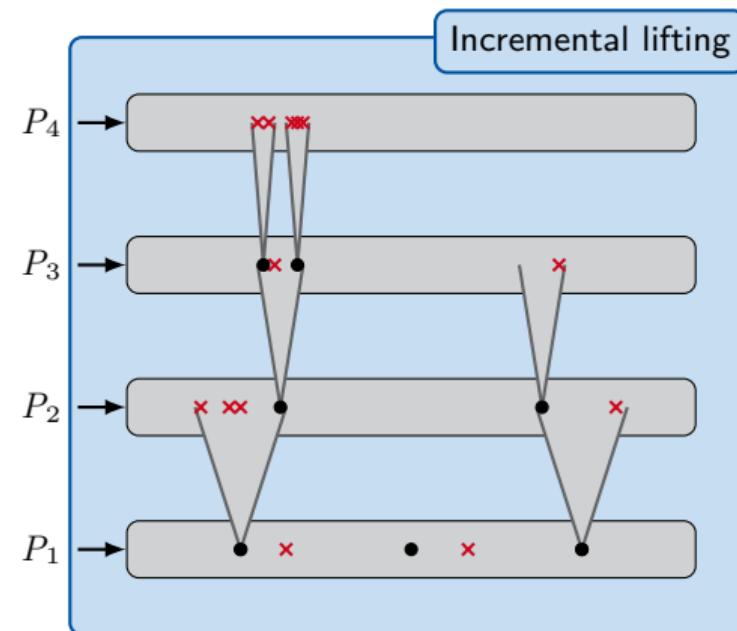
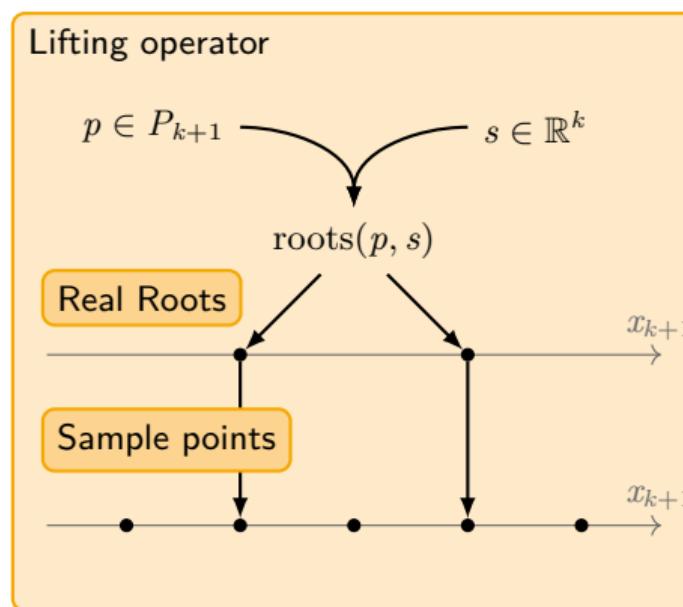
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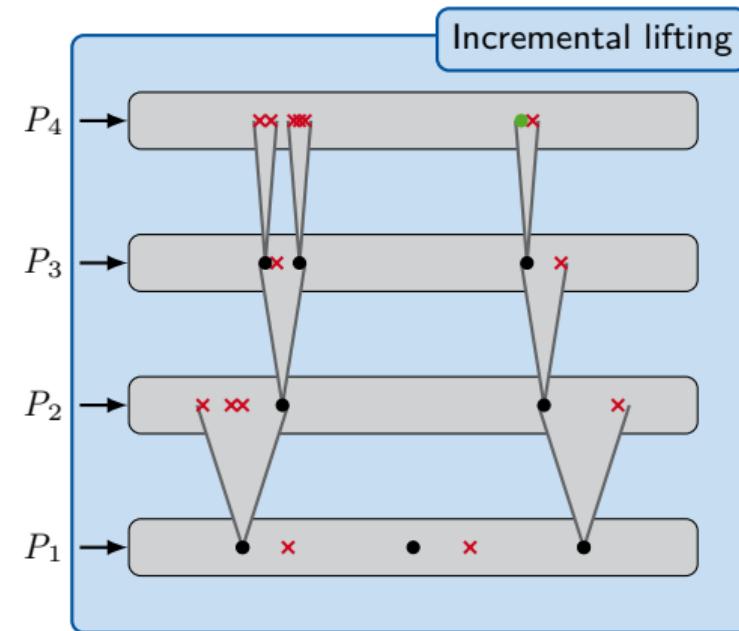
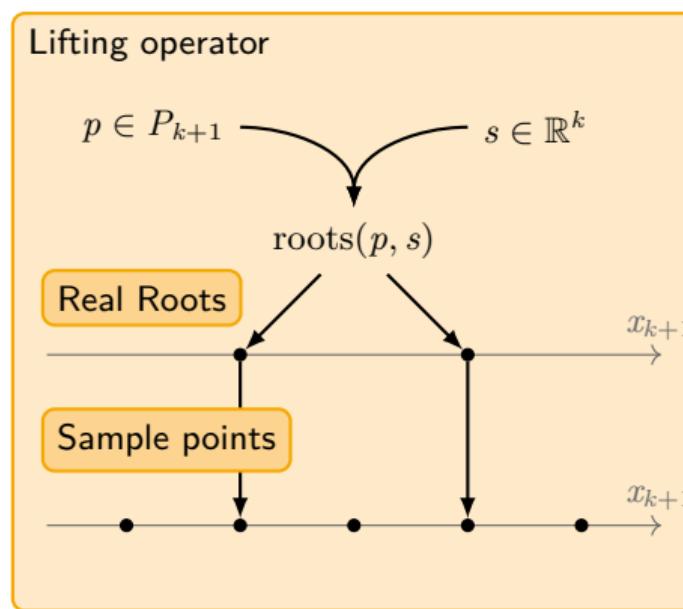
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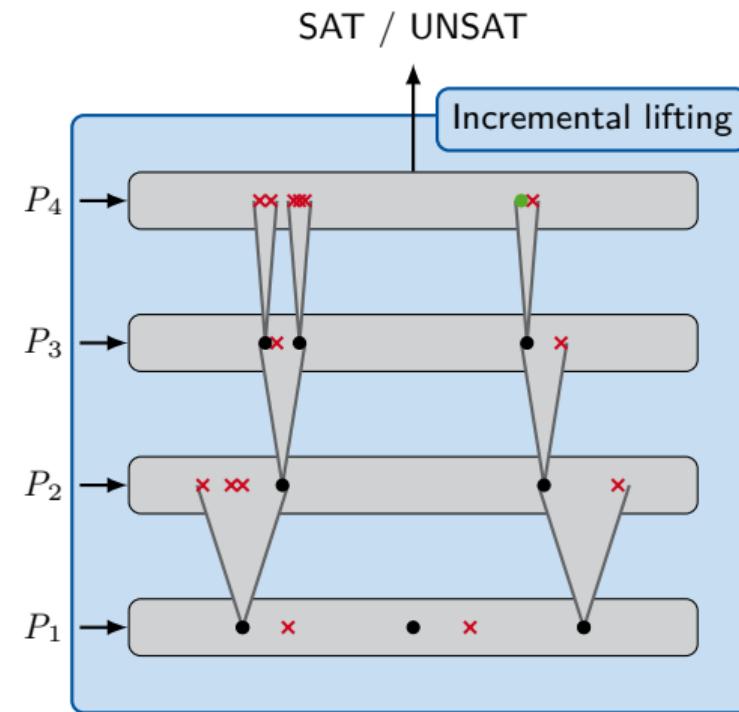
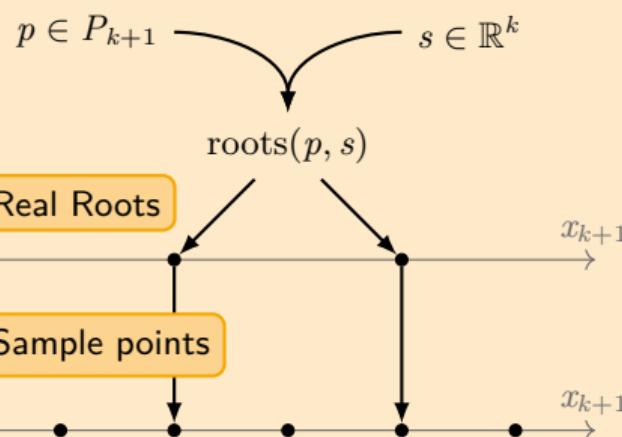
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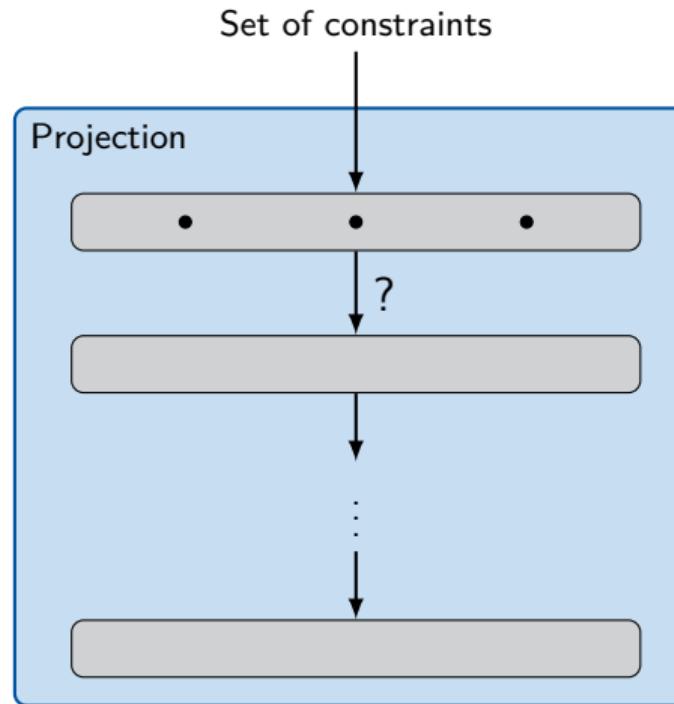
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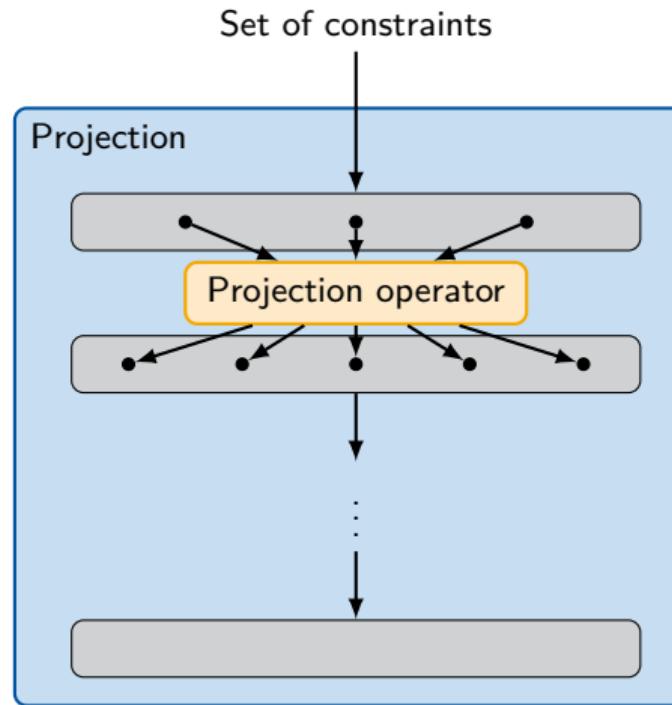


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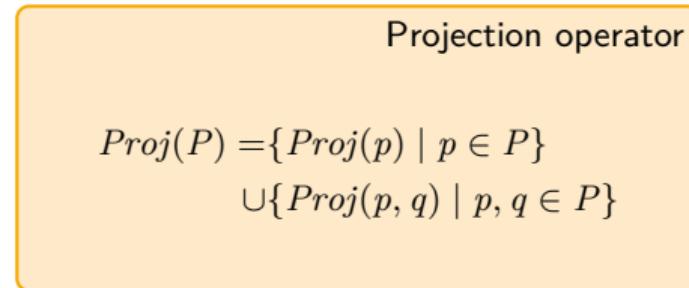
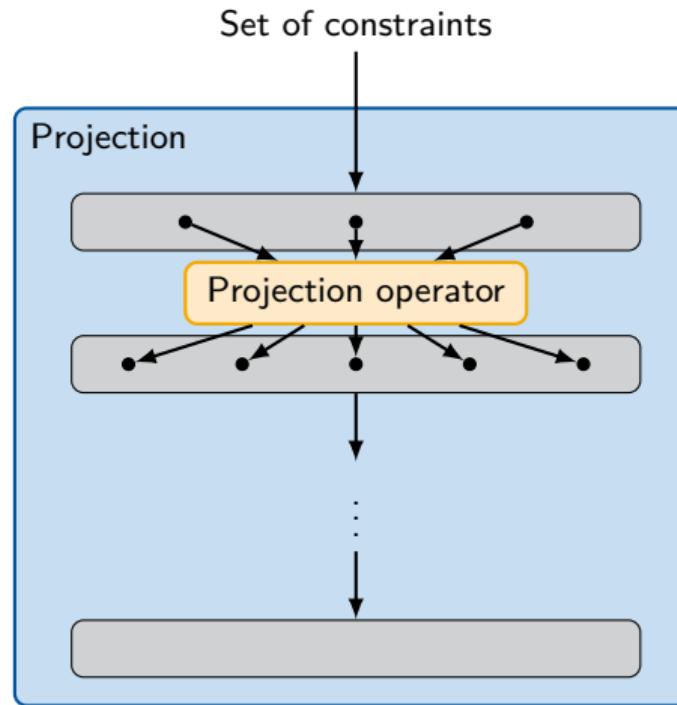
Incremental projection



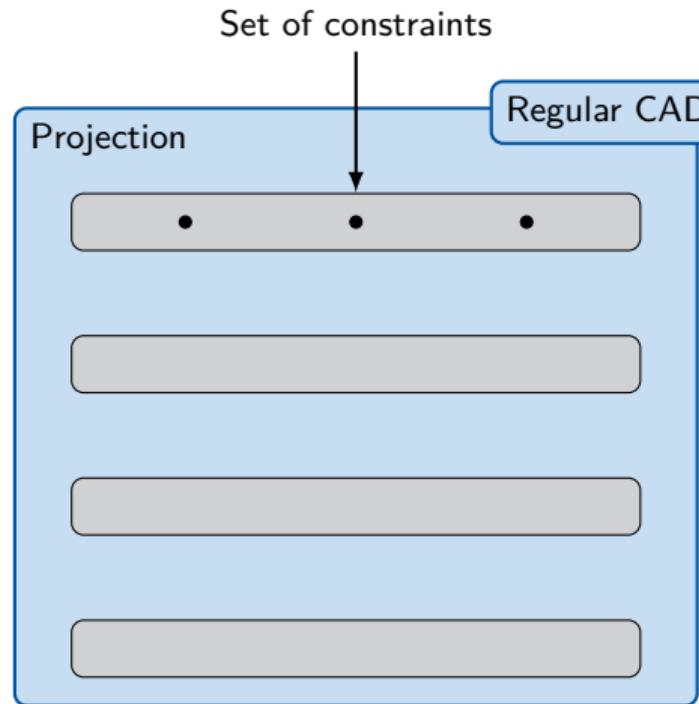
Incremental projection



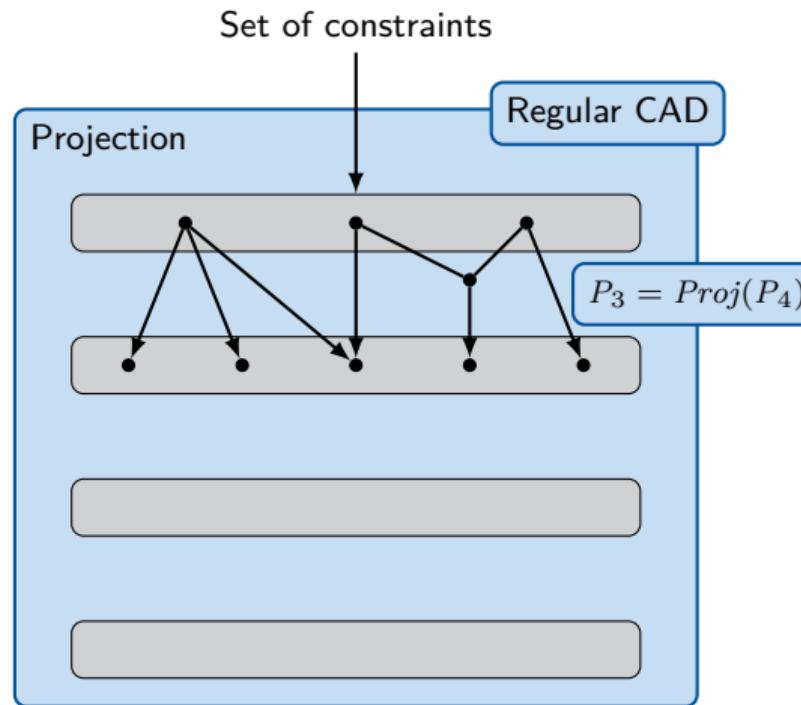
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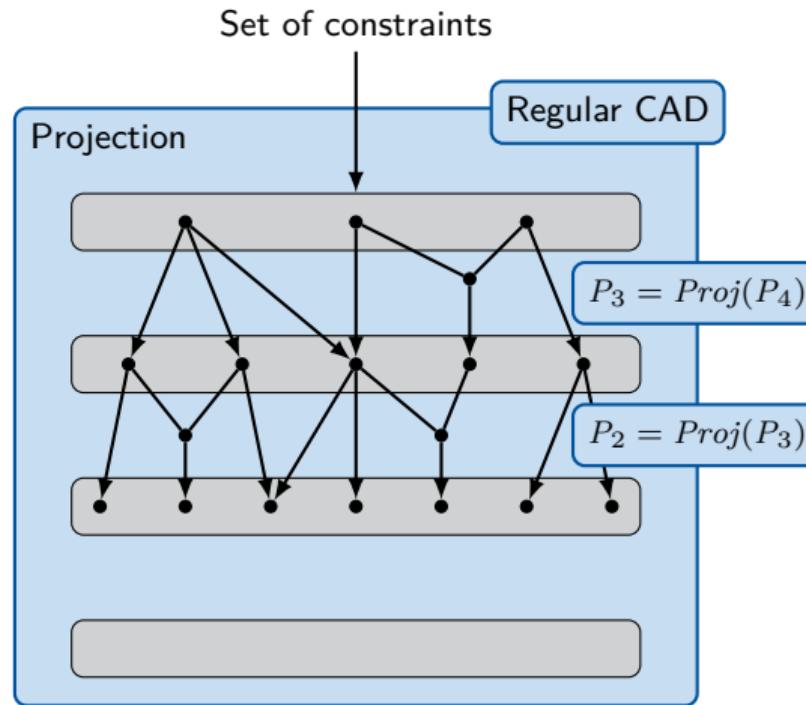
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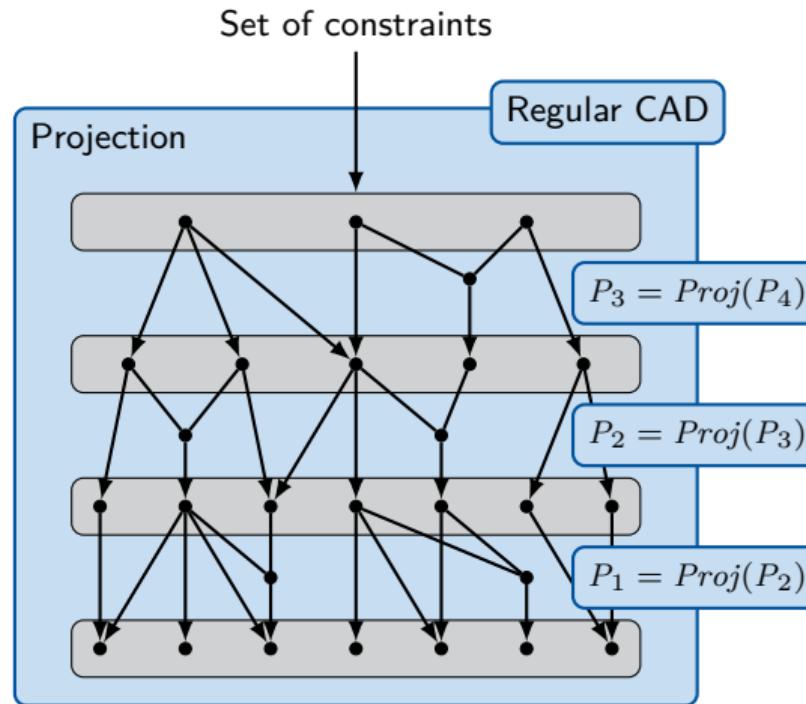
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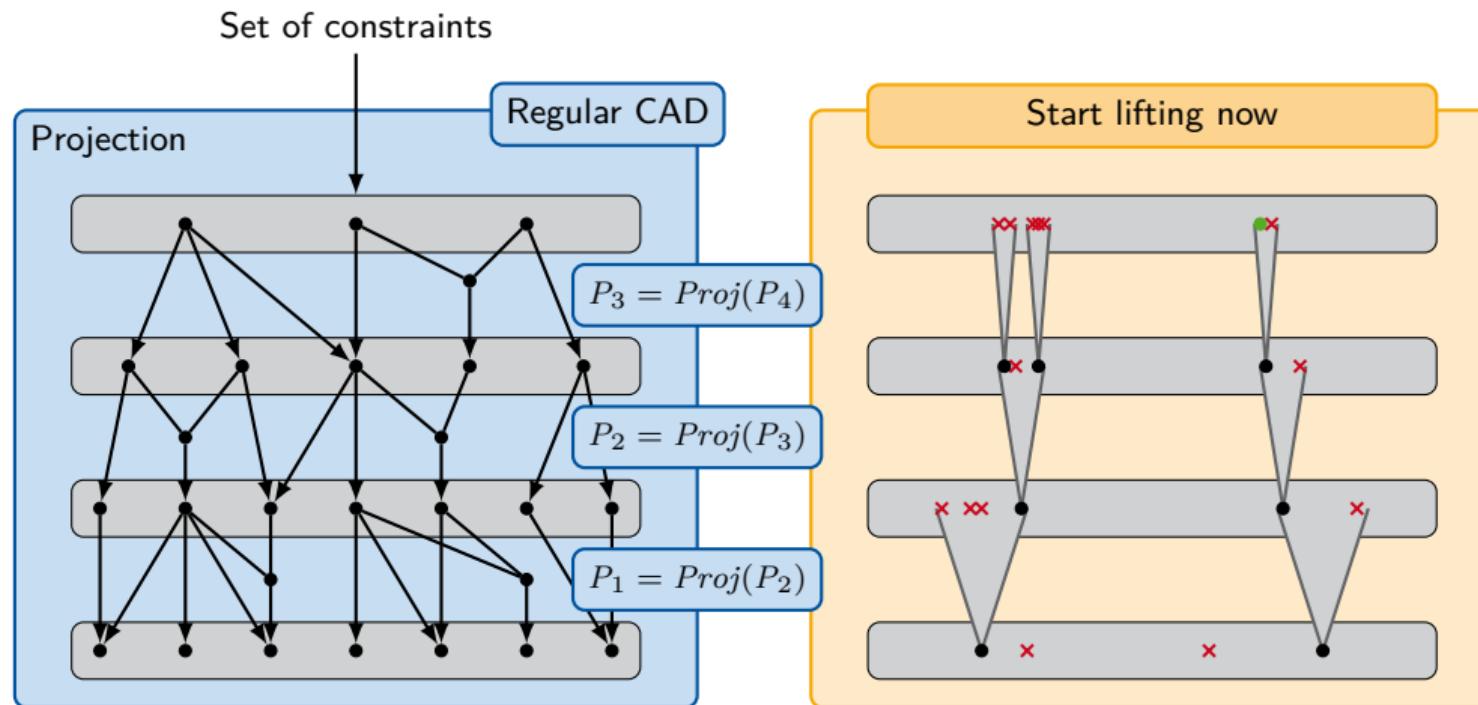
Incremental projection



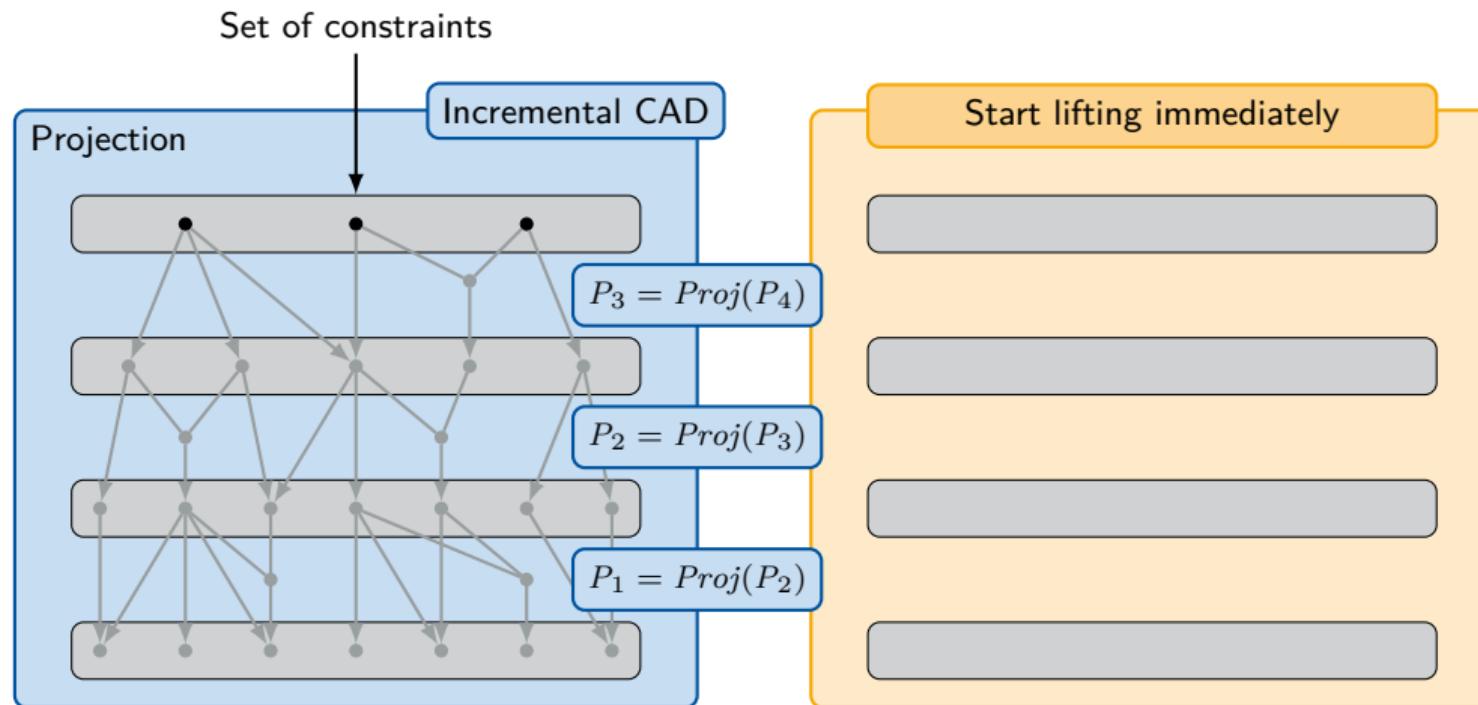
Incremental projection



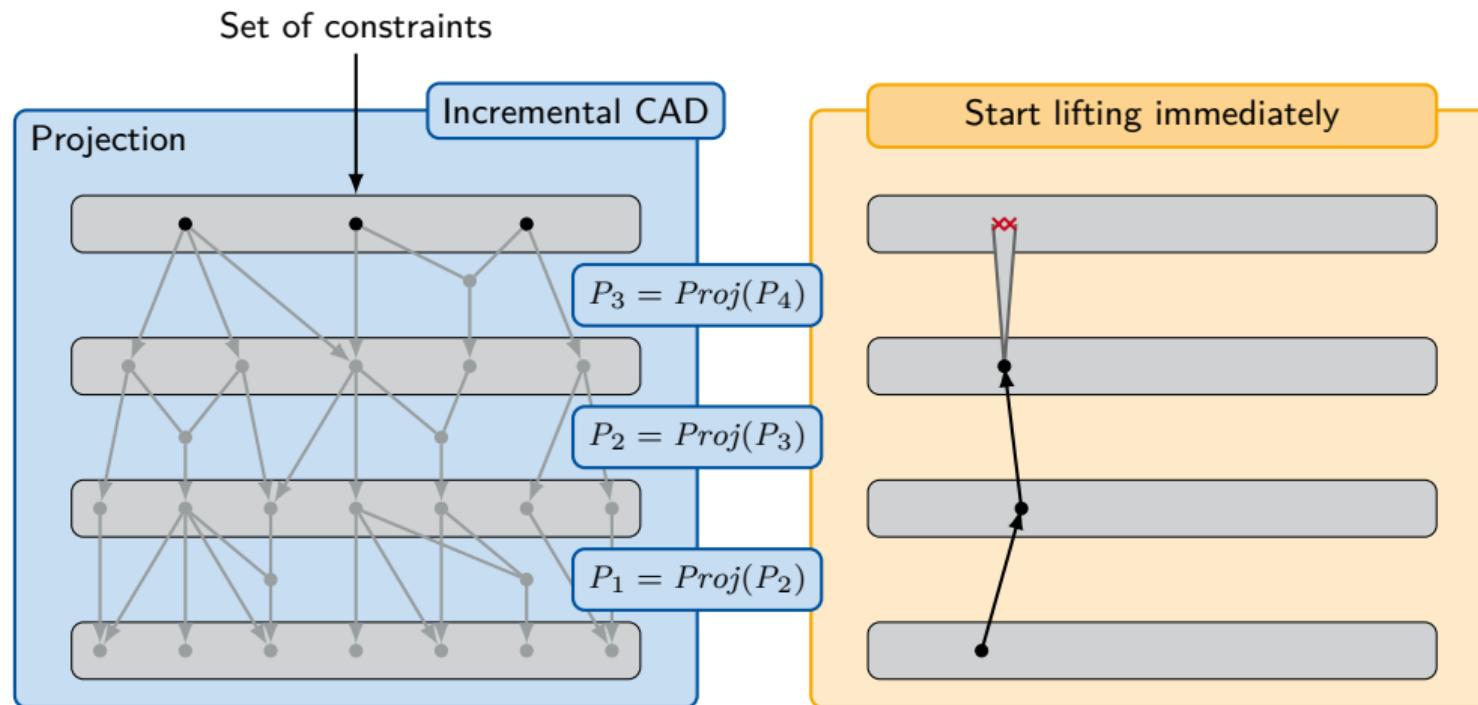
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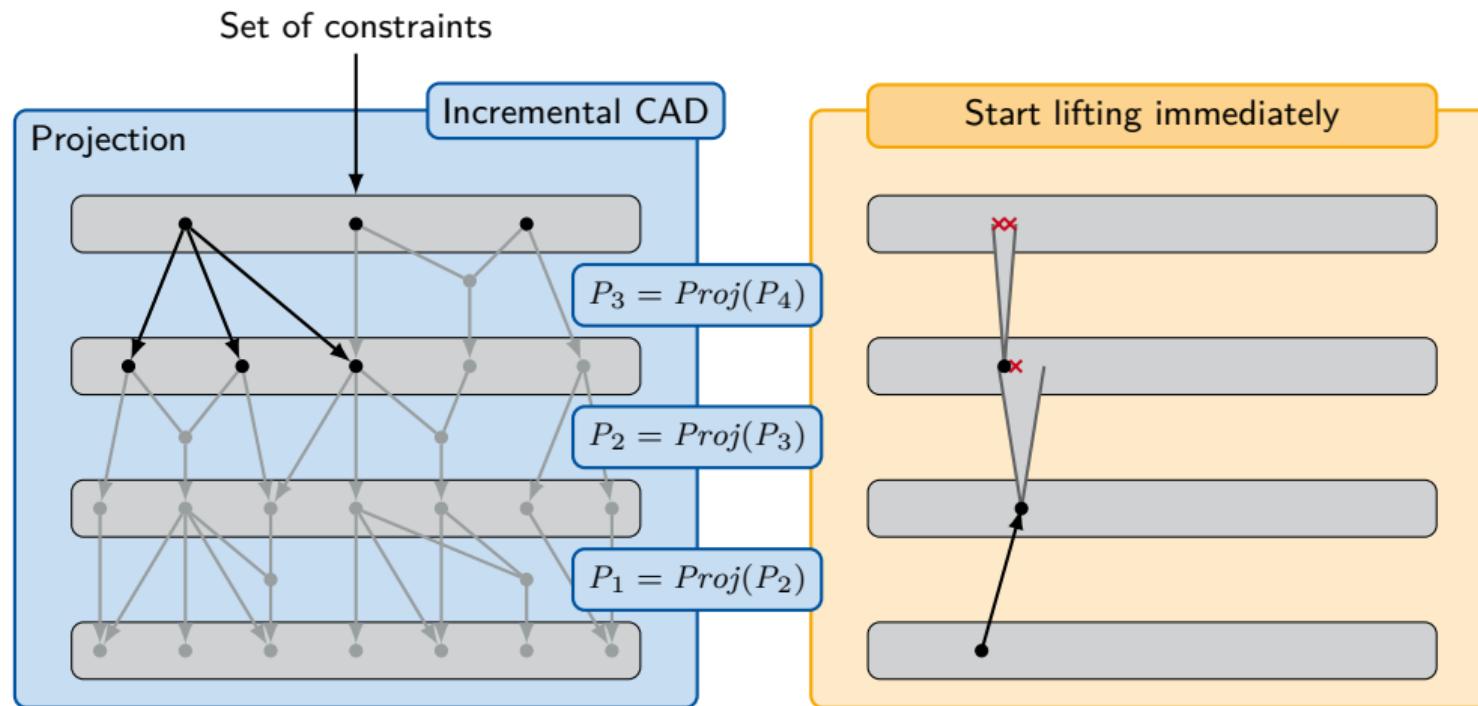
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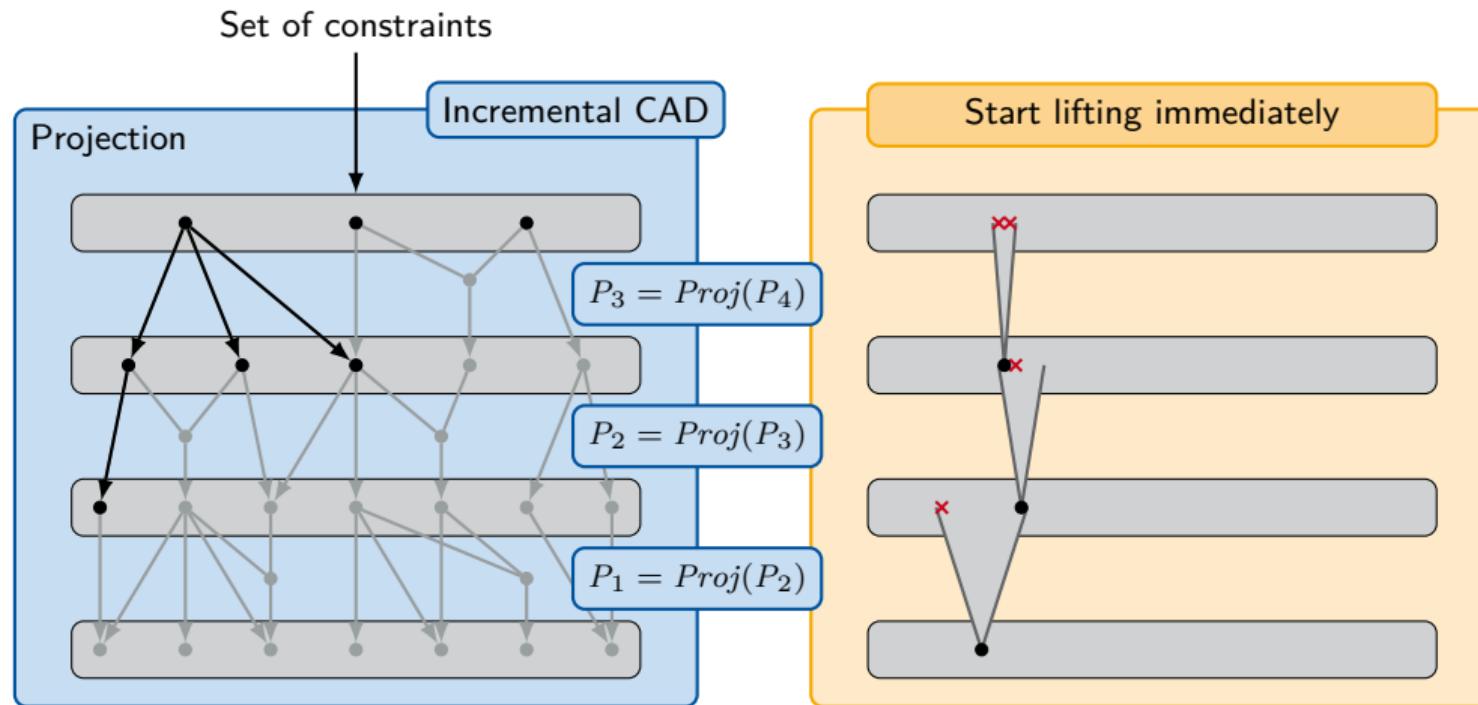
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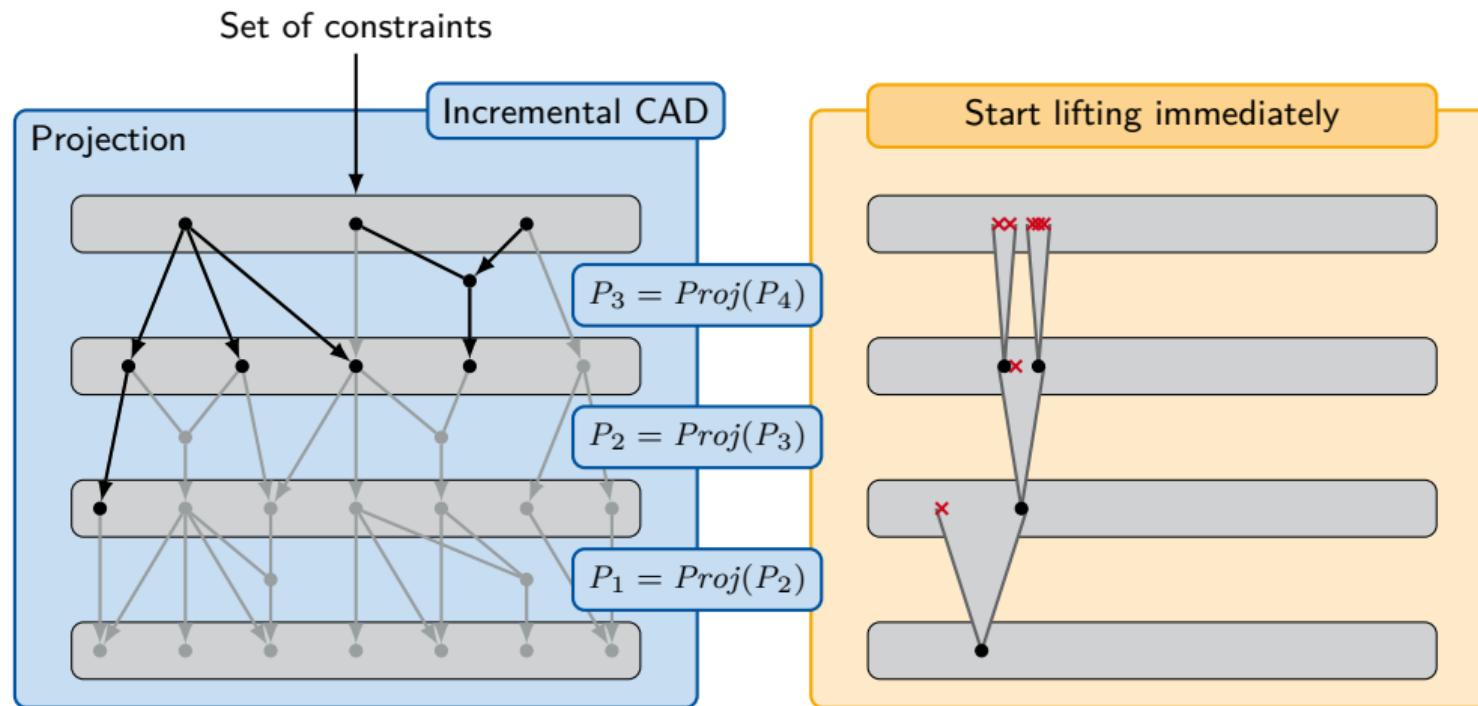
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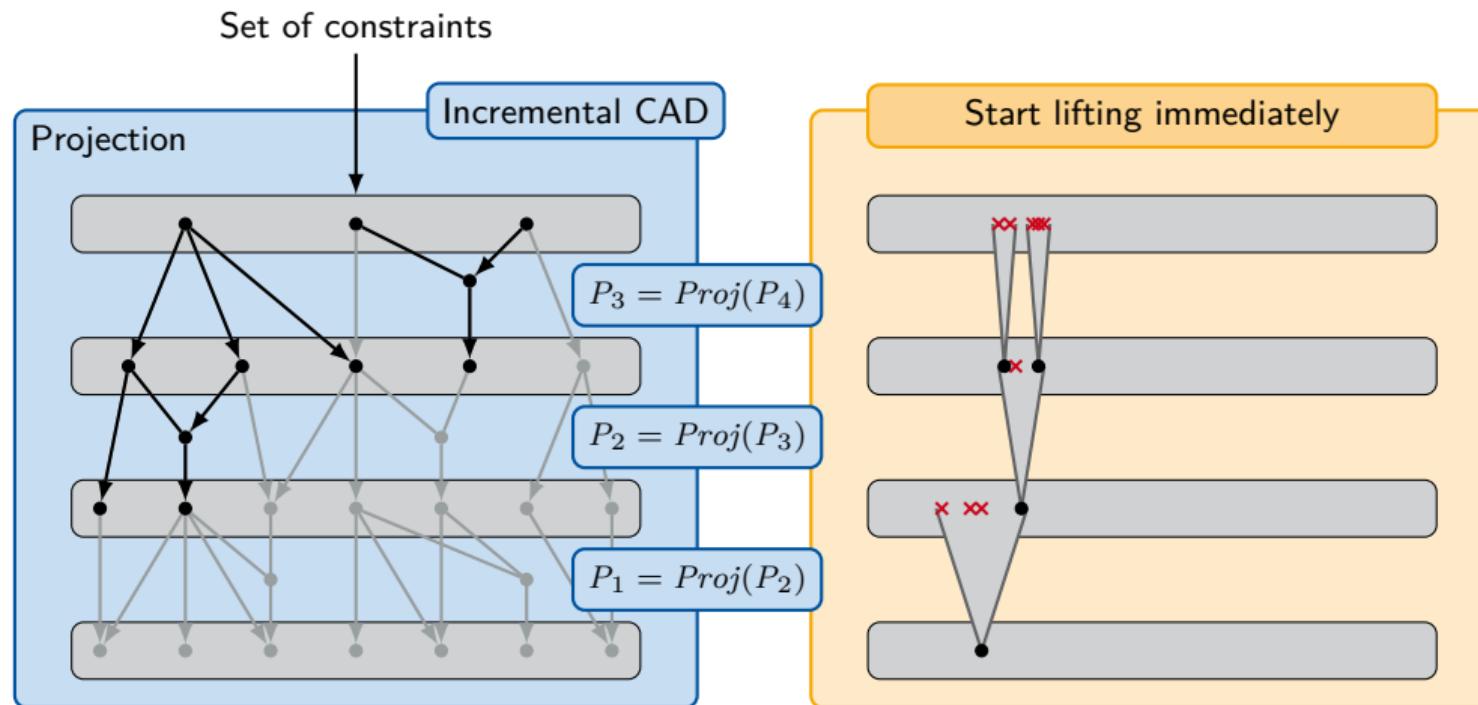
Incremental projection



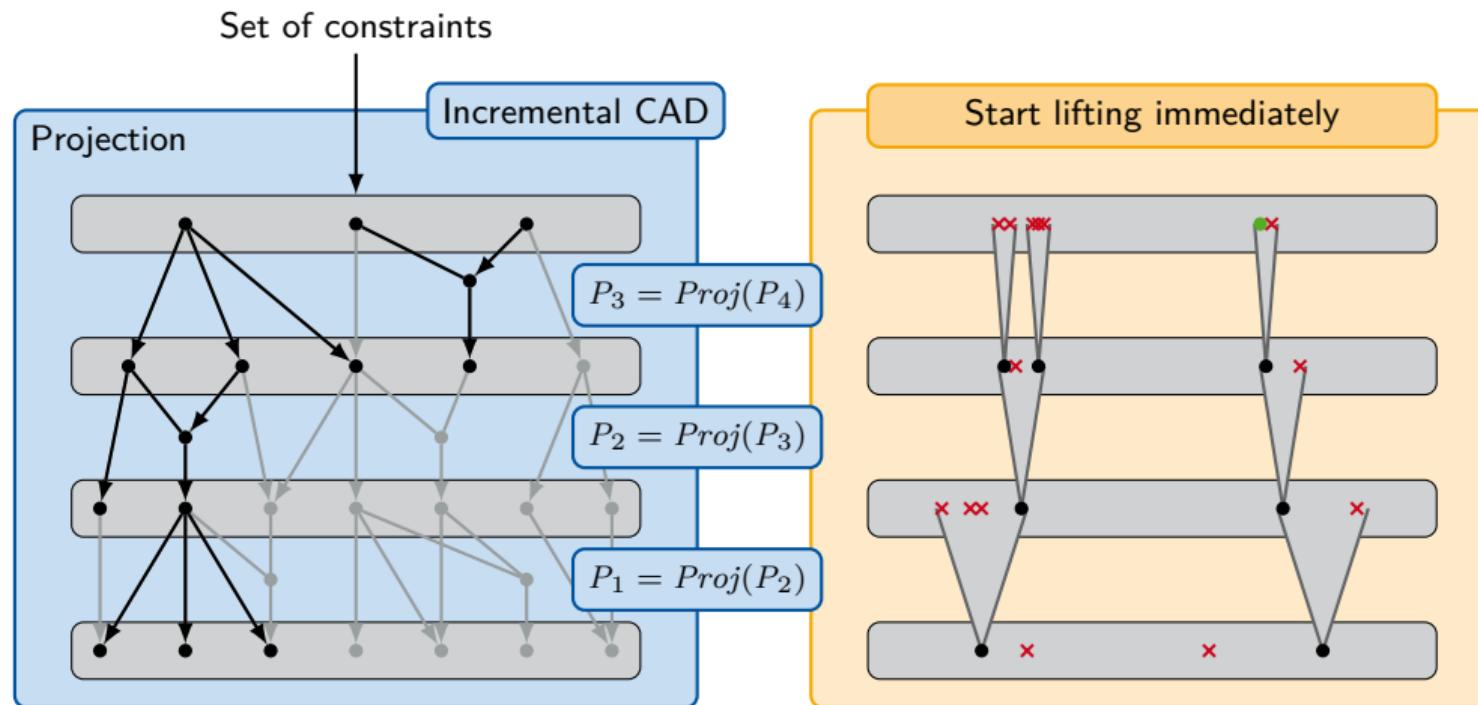
Incremental projection



Incremental projection



Incremental projection



Heuristics & Additions

■ Level of incrementality

Trade-off between potential [gains](#) and [bookkeeping](#)

■ Projection operators

Collins, Hong, McCallum, Lazard, Brown

[\[SC² 2017\]](#)

■ Variable ordering

[England + 2014] [Huang + 2014]

■ Scheduling of projection and lifting

Which polynomials and sample points to use first

■ Equational constraints

Exploits [equalities](#) to reduce projection

[McCallum 1999] [\[SC² 2018\]](#)

■ Factorization of polynomials

Ensures correctness, can reduce projection

■ Minimal infeasible subsets

Allow SAT solver to learn [smaller conflicts](#)

[Jaroschek + 2015][\[Hentze 2017\]](#)

Experimental results

- Timeout: 120s
- Benchmarks: QF_NRA from SMT-LIB

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Incrementality

Solver	SAT	UNSAT	overall
Naive	4285	3496	7781
None	4293	3507	7800
Simple	4281	3889	8170
Full	4328	4250	8578
Full-hide	4328	4255	8583

- Incrementality is **worth the effort**
- Bookkeeping **not that costly**

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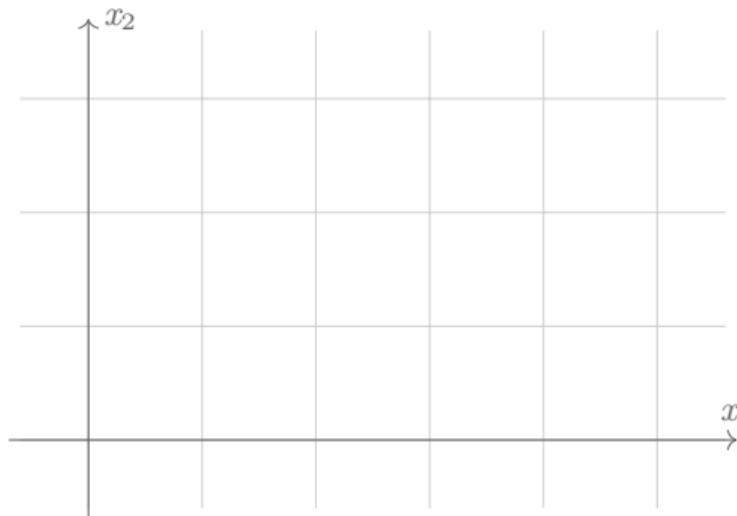
- Incrementality is **worth the effort**
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Projection operators

Solver	SAT	UNSAT	overall
Collins	4292	4150	8442
Hong	4301	4189	8490
McCallum	4320	4216	8536
Lazard	4322	4229	8551
Brown	4328	4250	8578

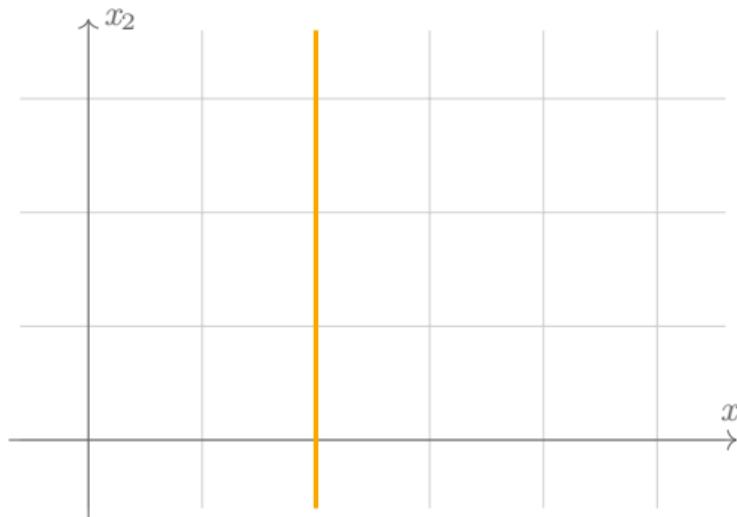
- **Confirms** conventional wisdom
- Margins **may be surprising**

Model-Constructing Satisfiability Calculus



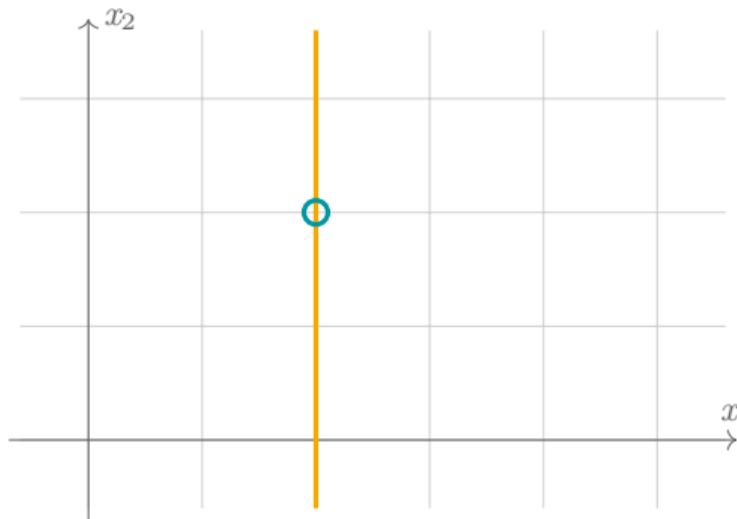
[Jovanović + 2012] [Moura + 2013]

Model-Constructing Satisfiability Calculus



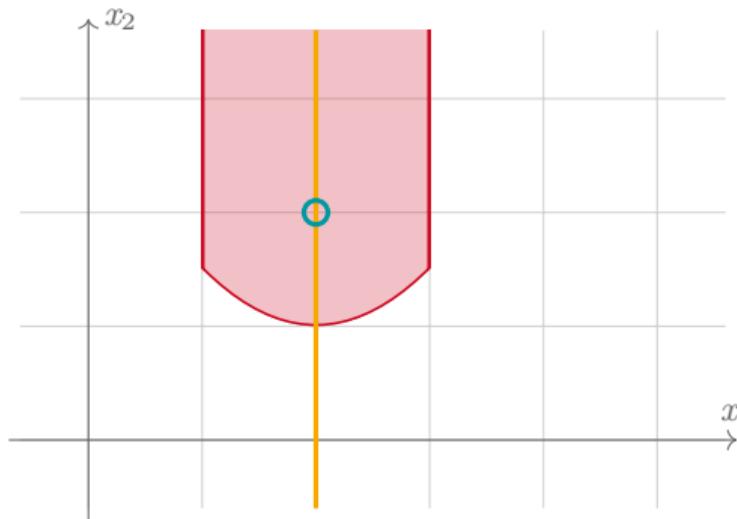
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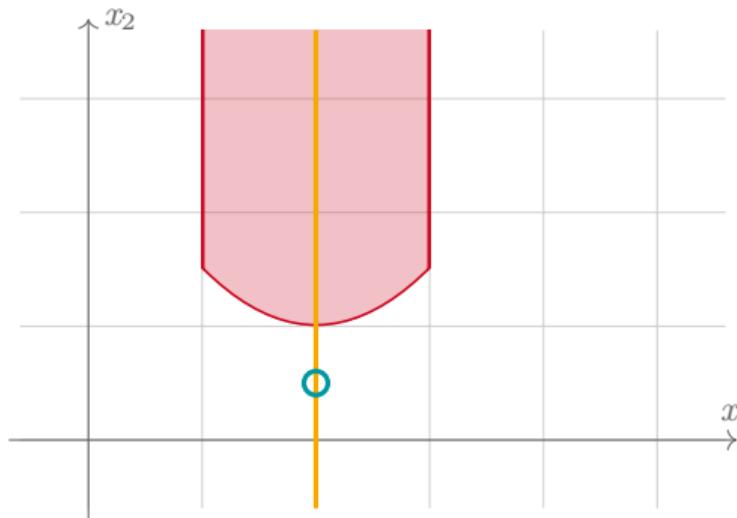
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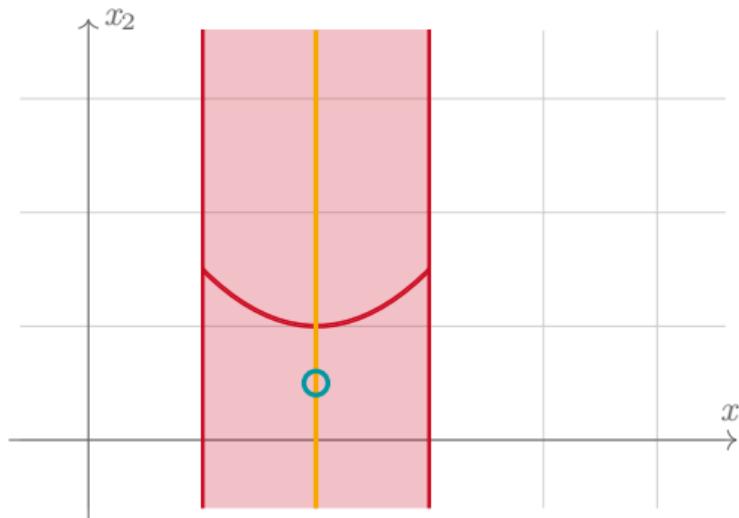
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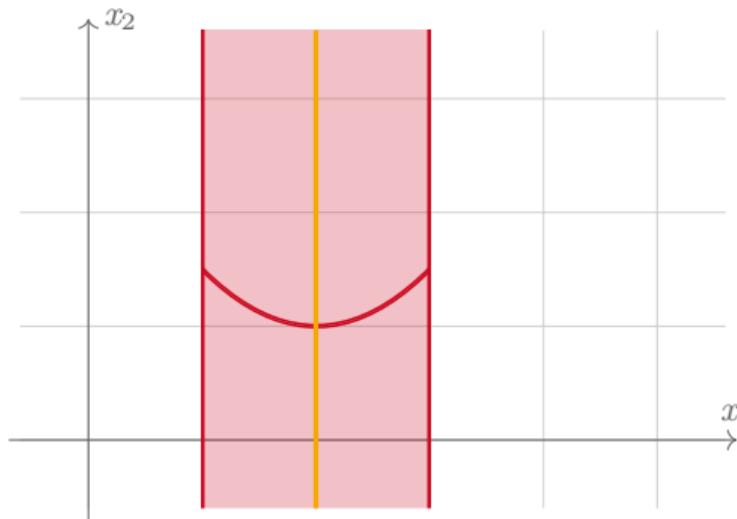
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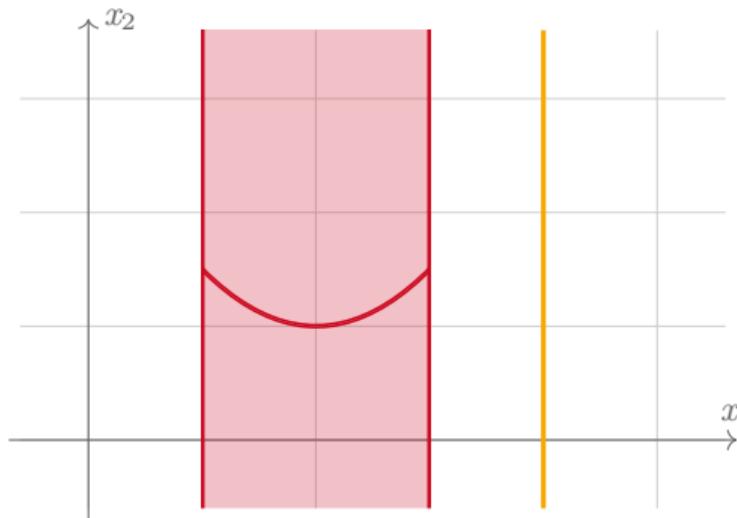
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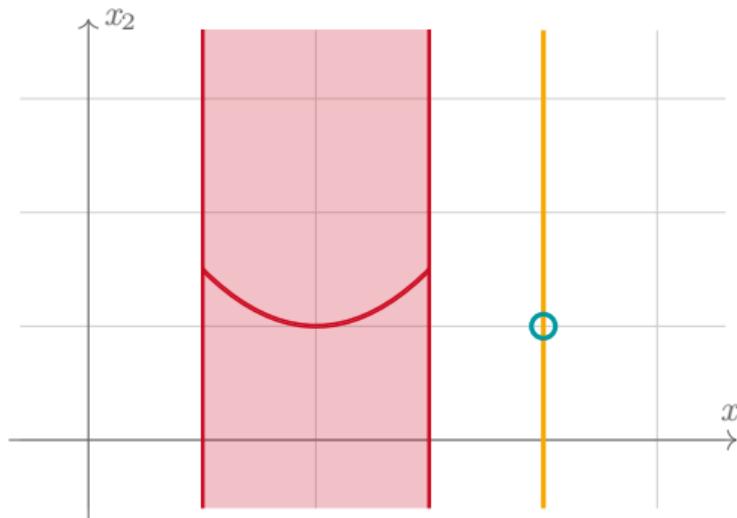
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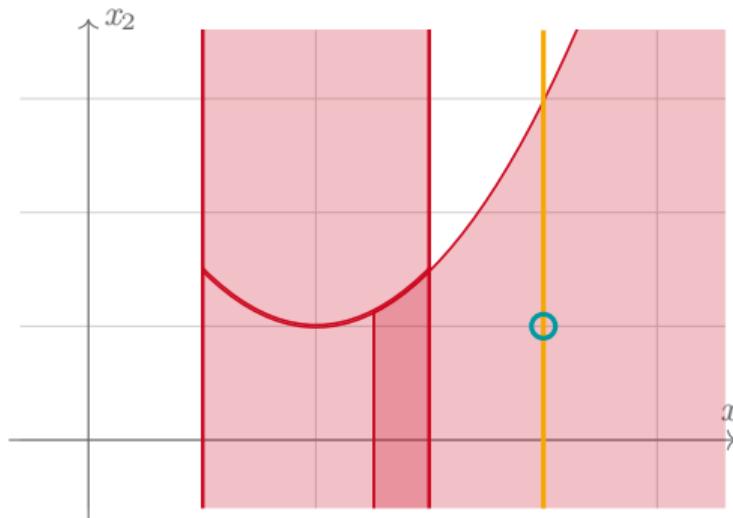
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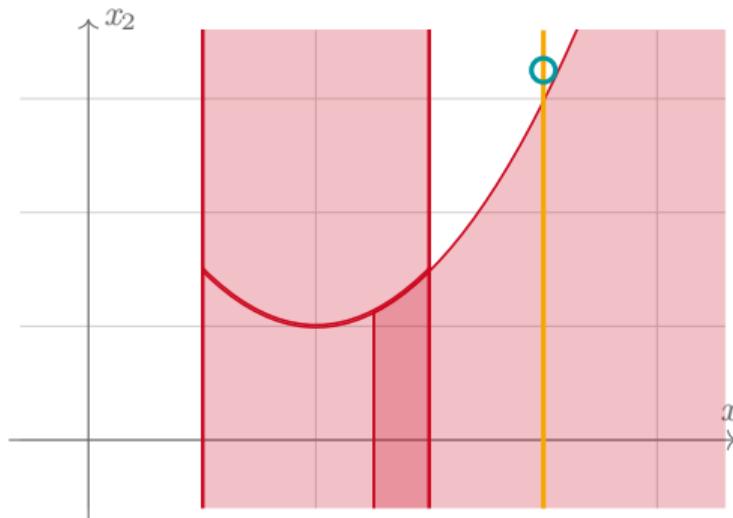
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Model-Constructing Satisfiability Calculus



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Model-Constructing Satisfiability Calculus



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Model-Constructing Satisfiability Calculus



[Jovanović + 2012] [Moura + 2013]

Model-Constructing Satisfiability Calculus

(Lazy) SMT solver

[Jovanović + 2012] [Moura + 2013]

Model-Constructing Satisfiability Calculus

(Lazy) SMT solver

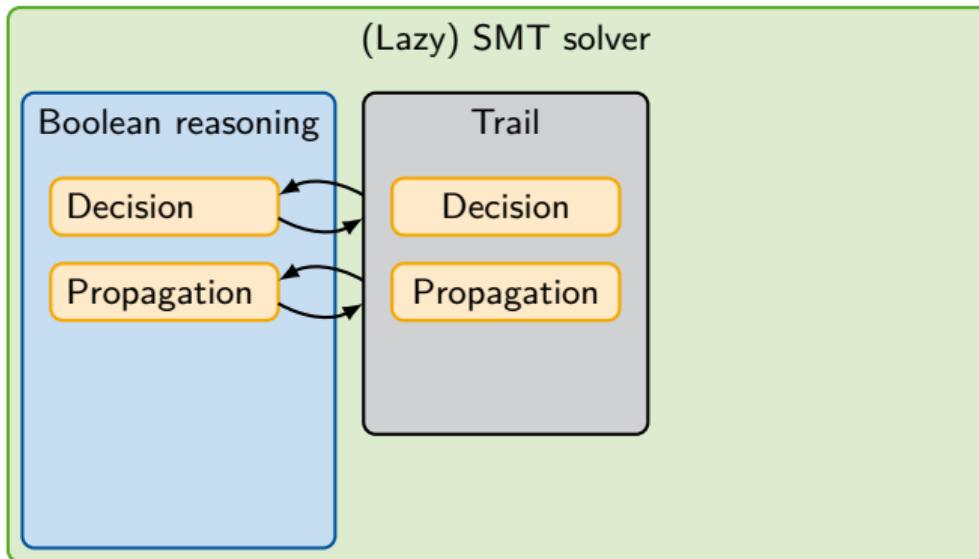
Boolean reasoning

Decision

Propagation

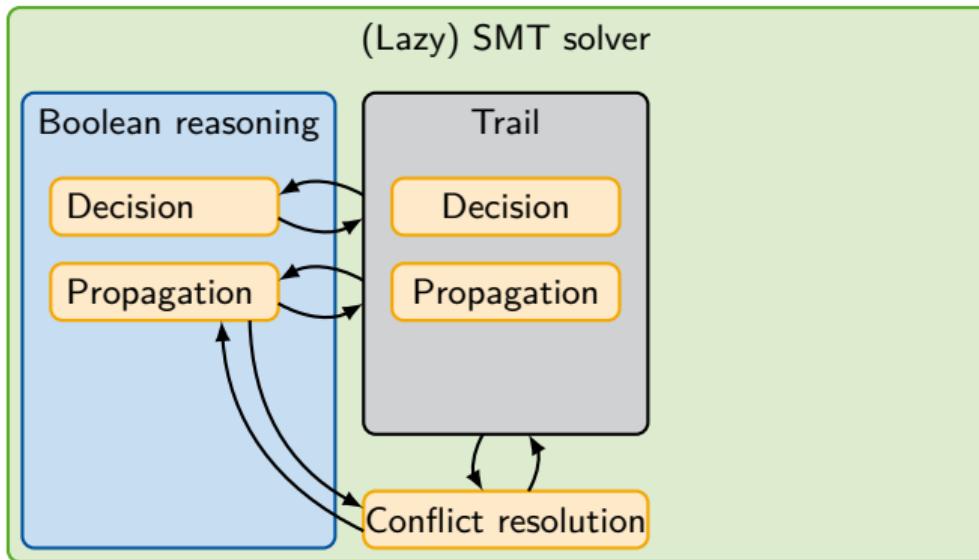
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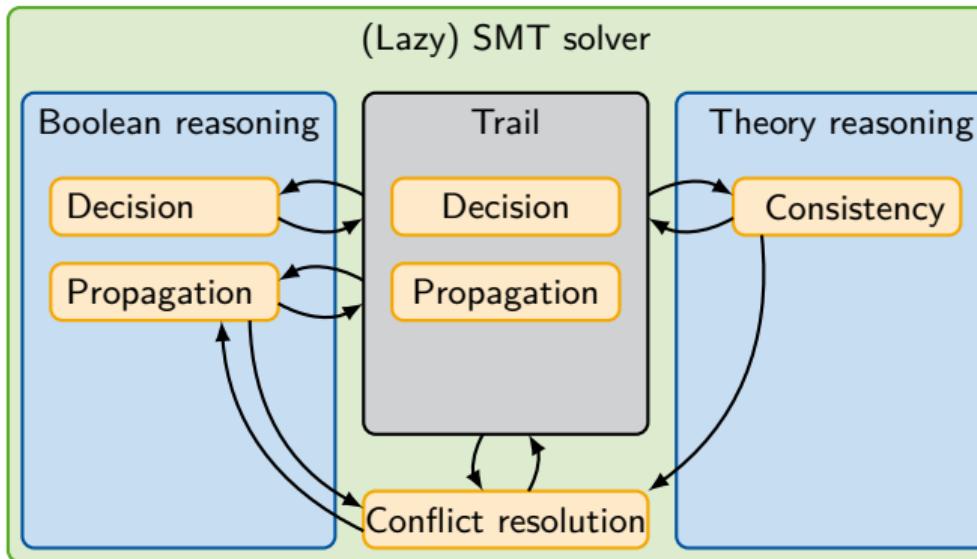
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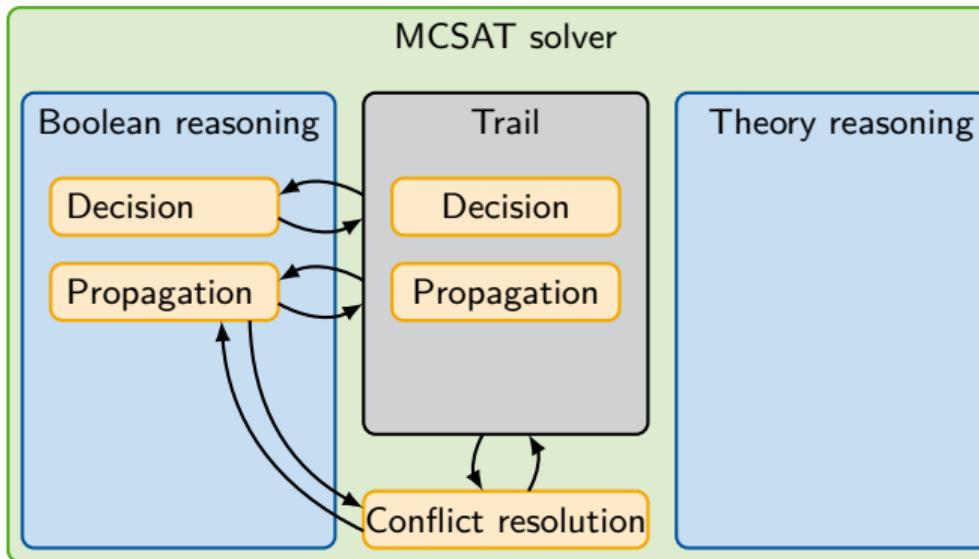
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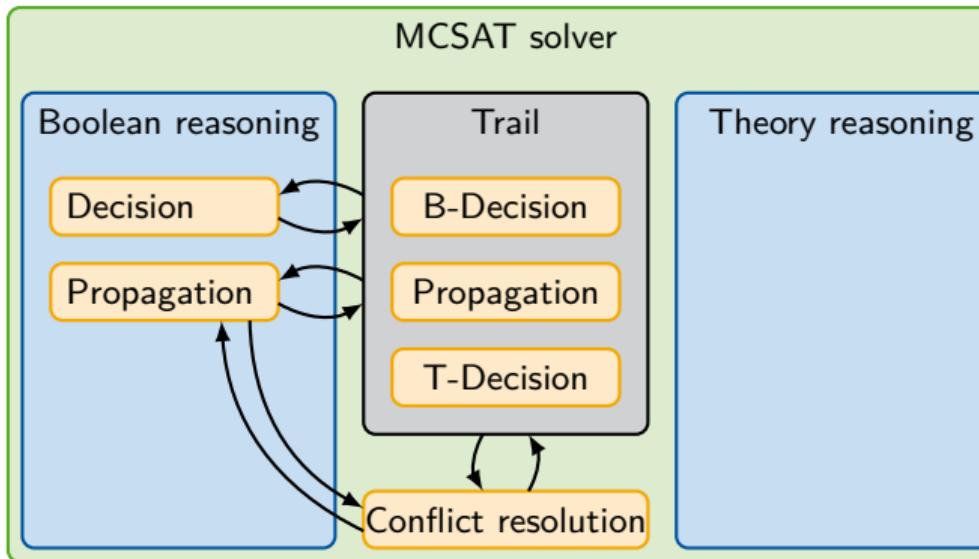
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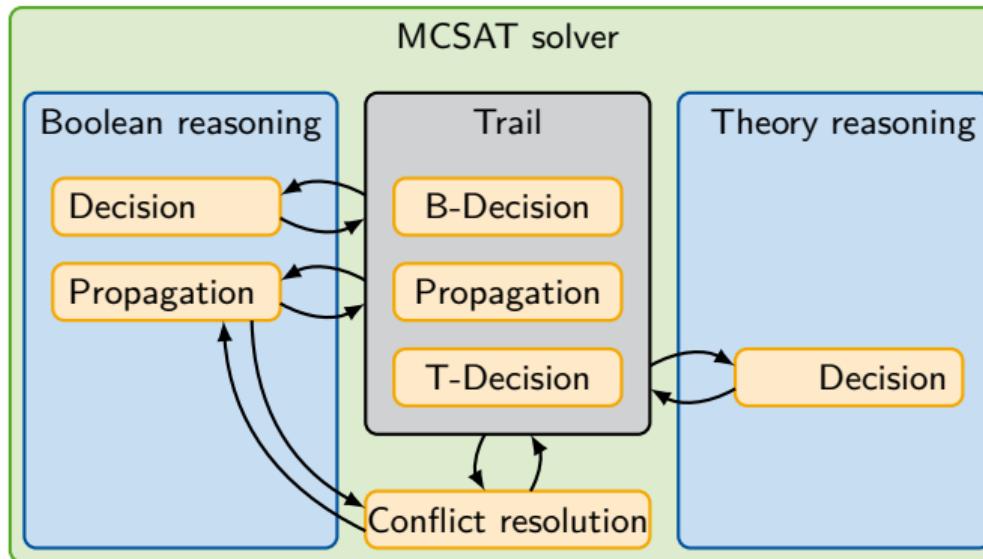
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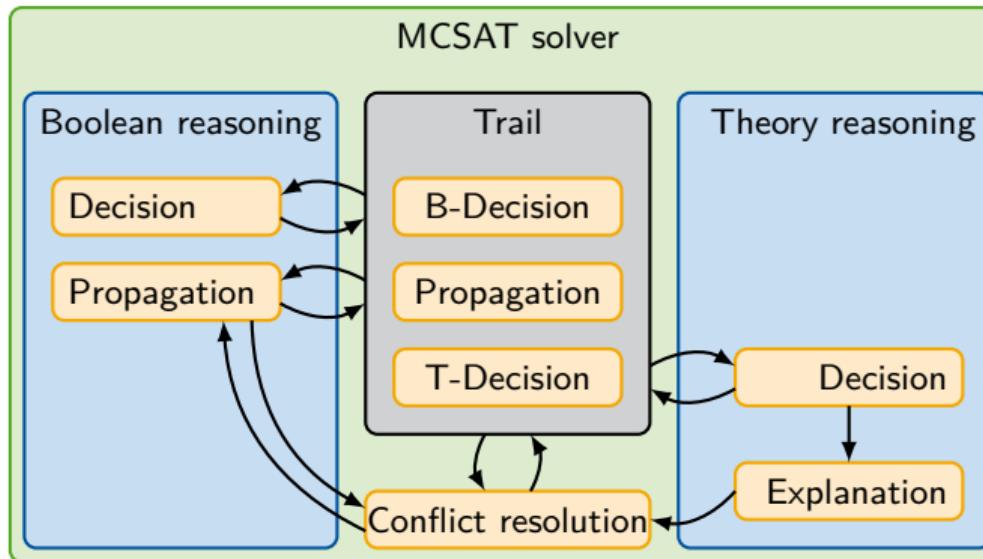
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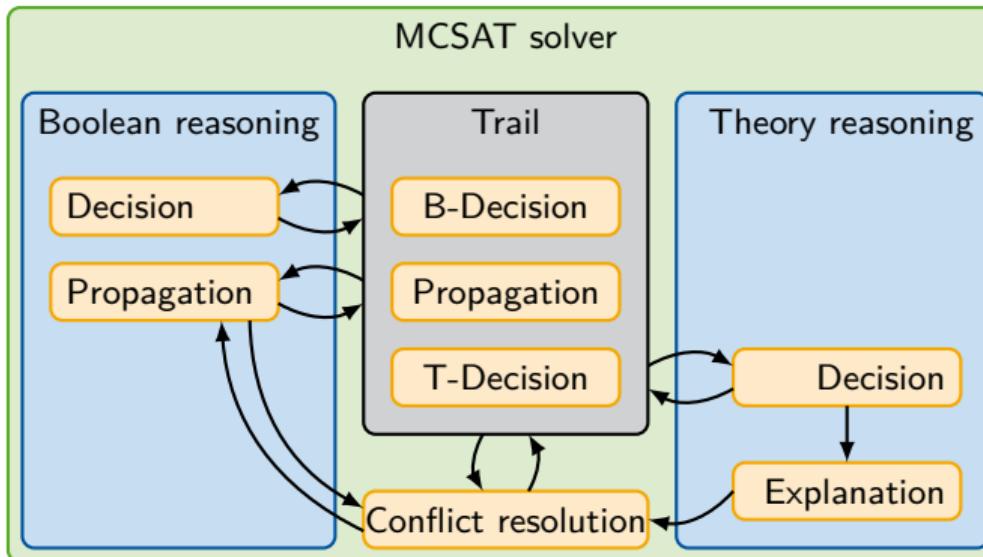
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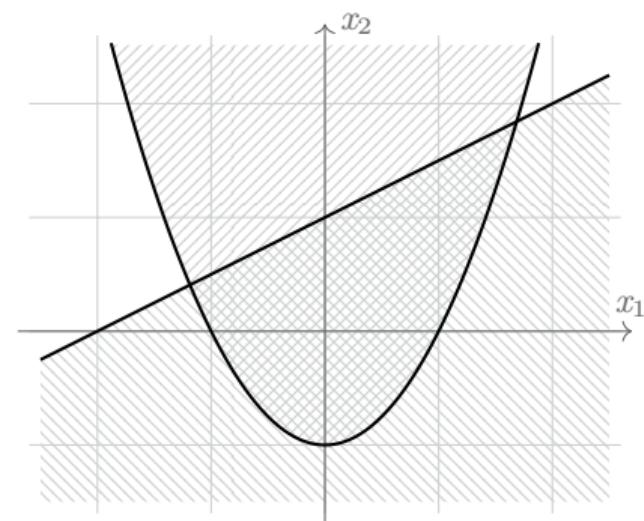


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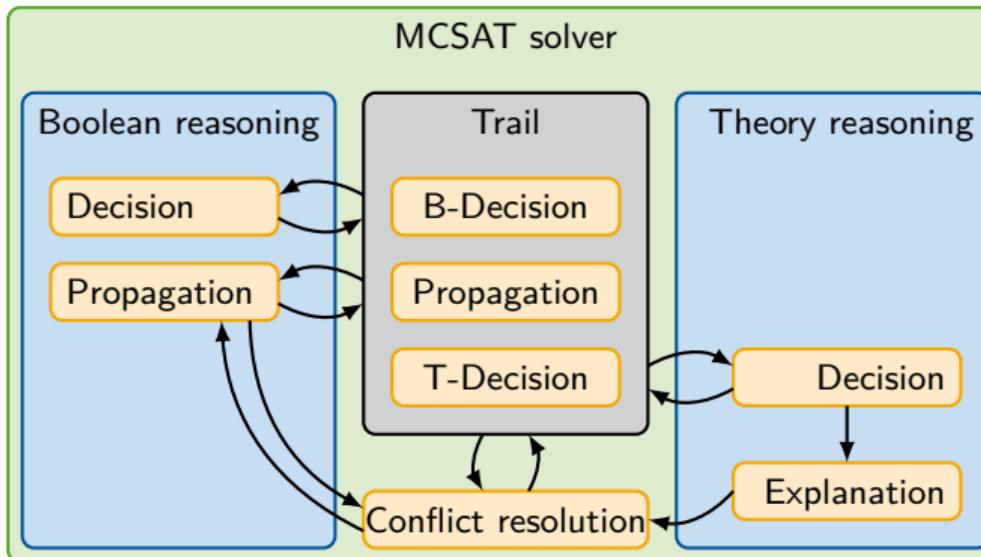


Trail: $\llbracket c_1, c_2 \rrbracket$



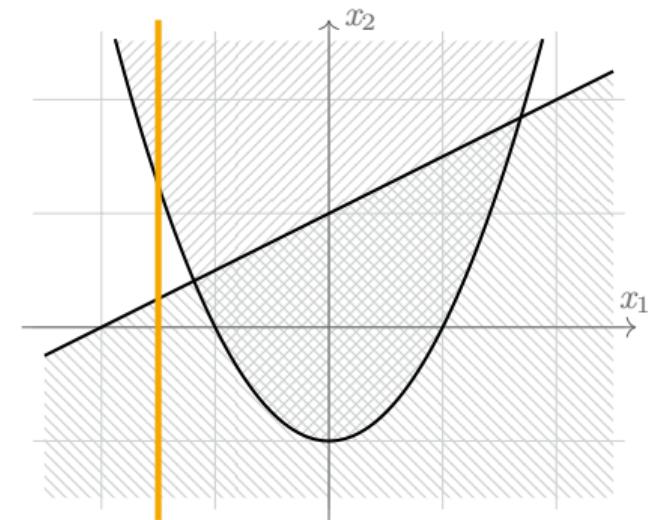
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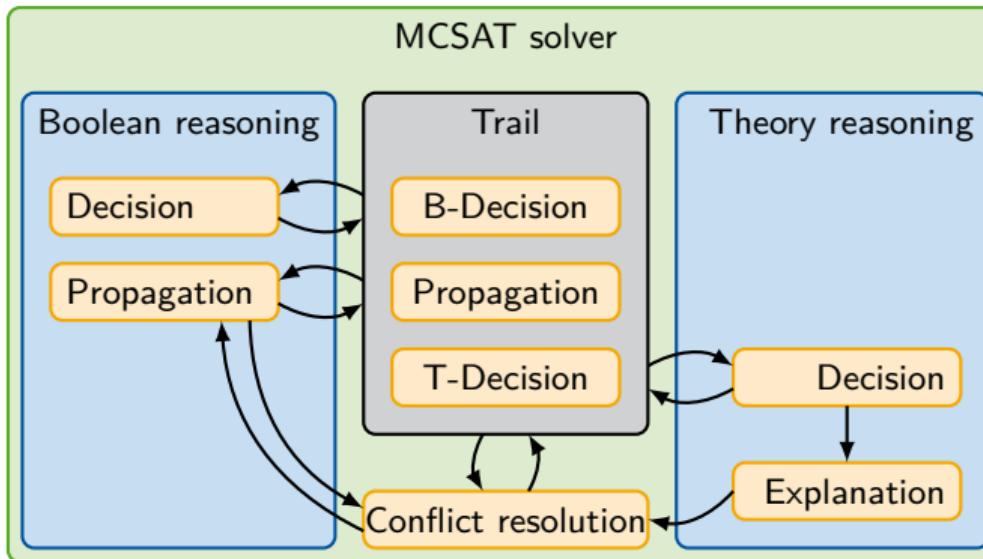
Guess: $x_1 \mapsto -1.5$

Trail: $\llbracket c_1, c_2, x_1 \mapsto -1.5 \rrbracket$

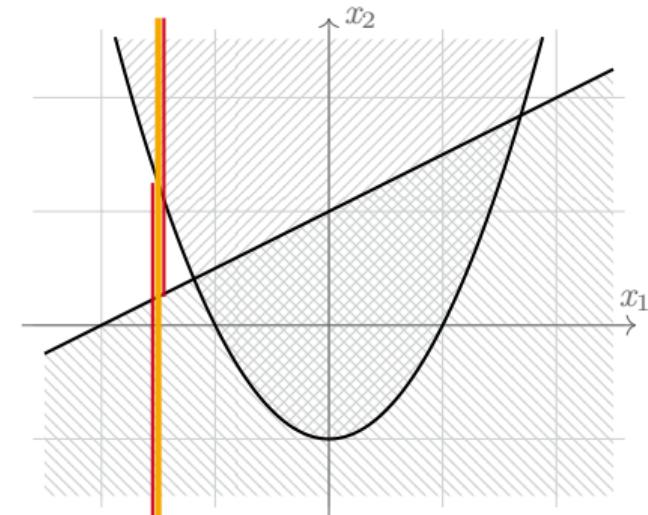


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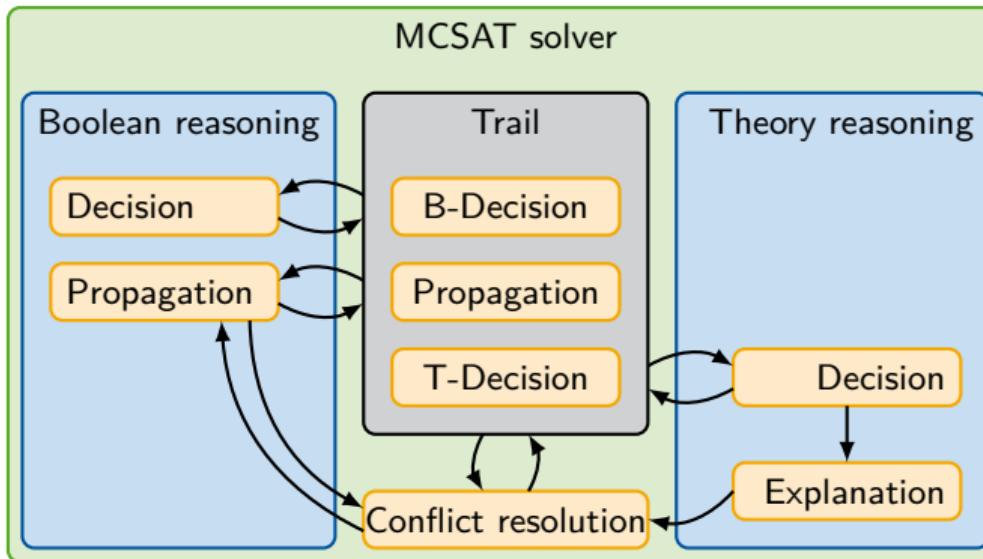


No assignment for x_2 . Reason: c_1, c_2
 Trail: $\llbracket c_1, c_2, x_1 \mapsto -1.5 \rrbracket$

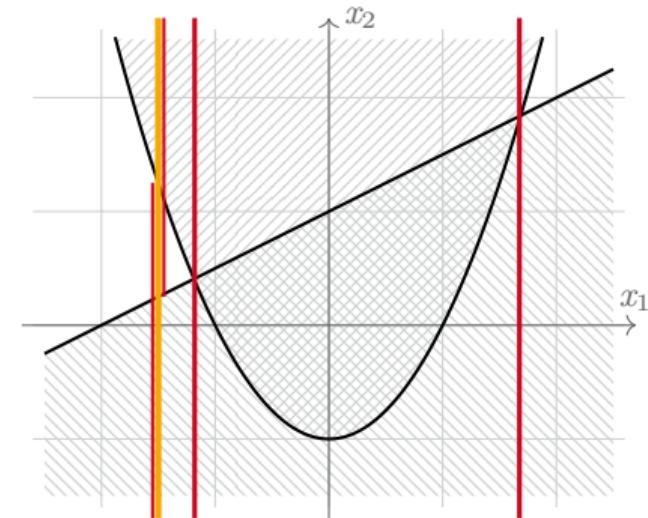


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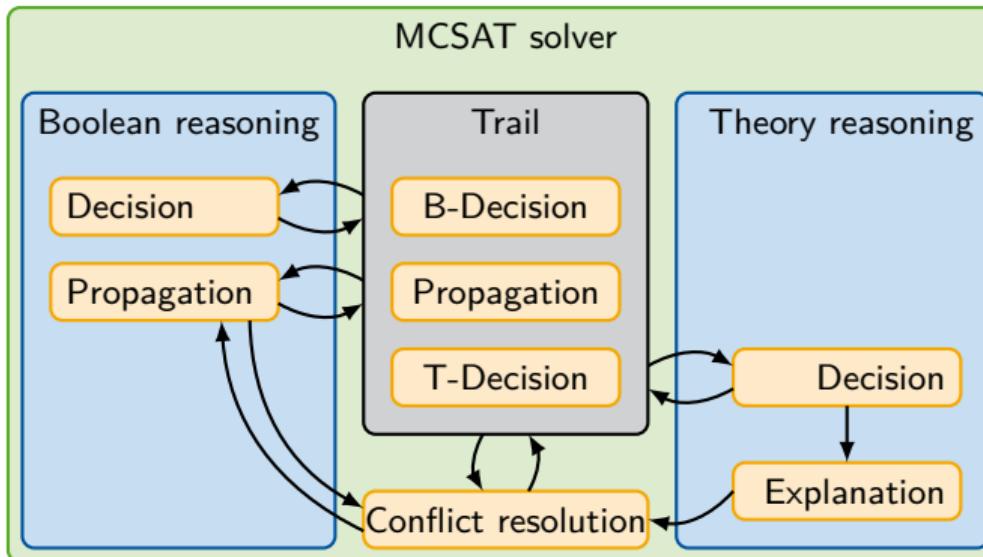


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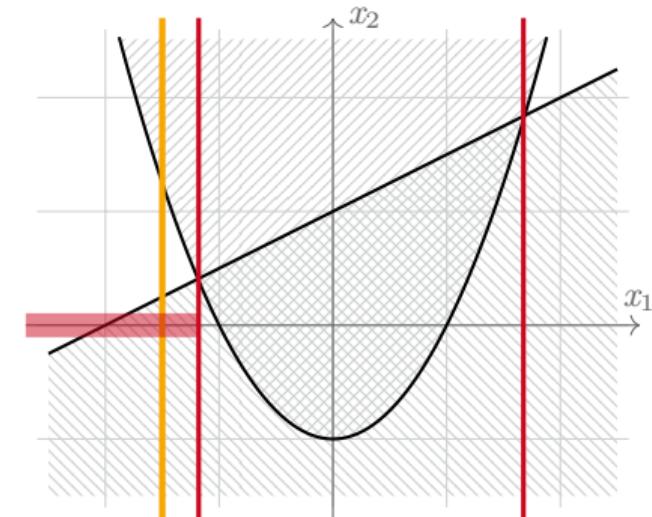


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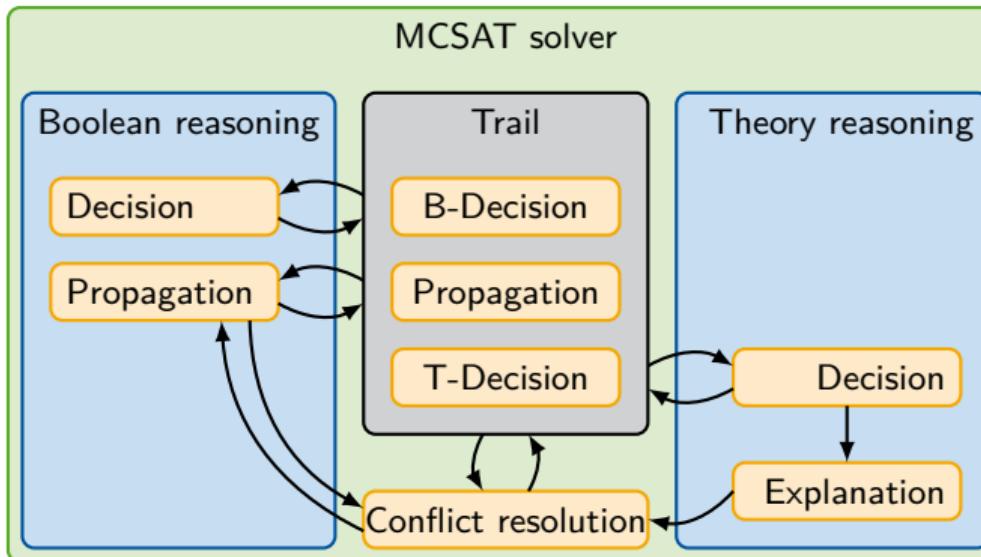


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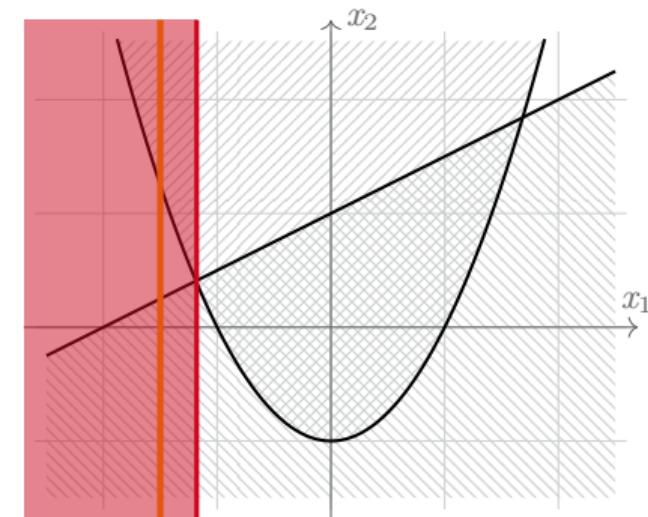
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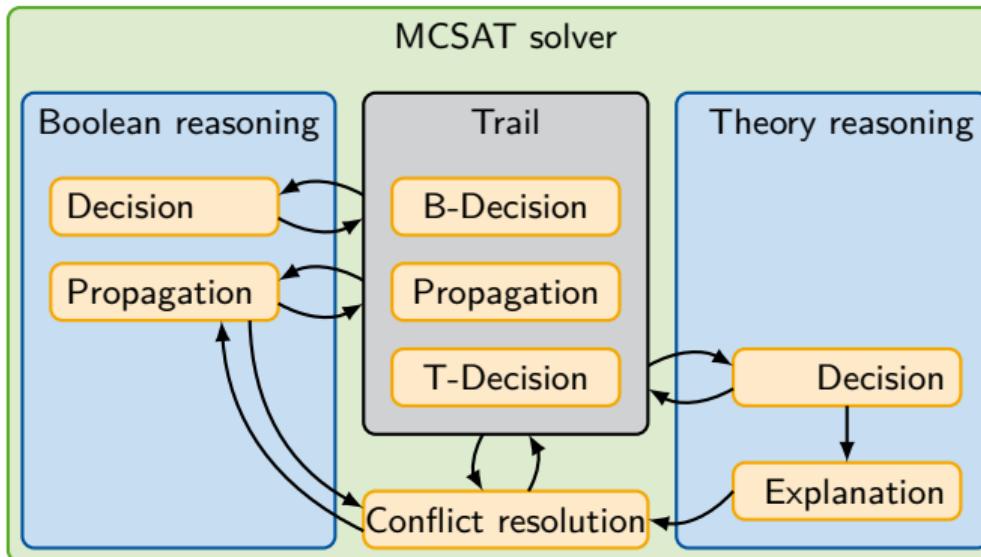
$$(c_1 \wedge c_2) \rightarrow (\alpha_2 \leq x_1)$$

Trail: $\llbracket c_1, c_2 \rrbracket$



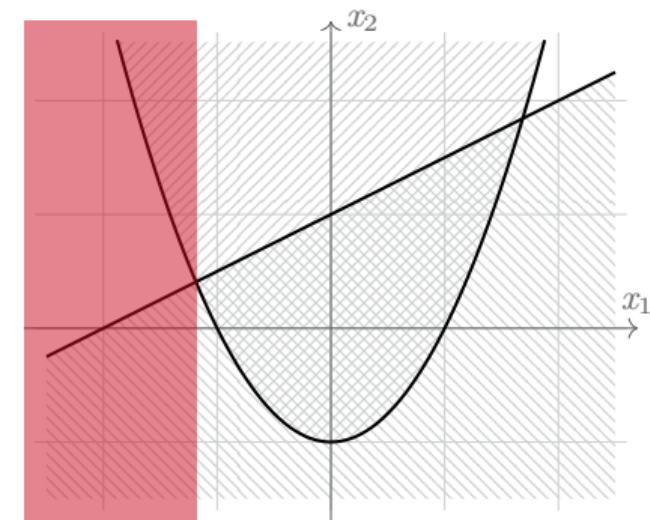
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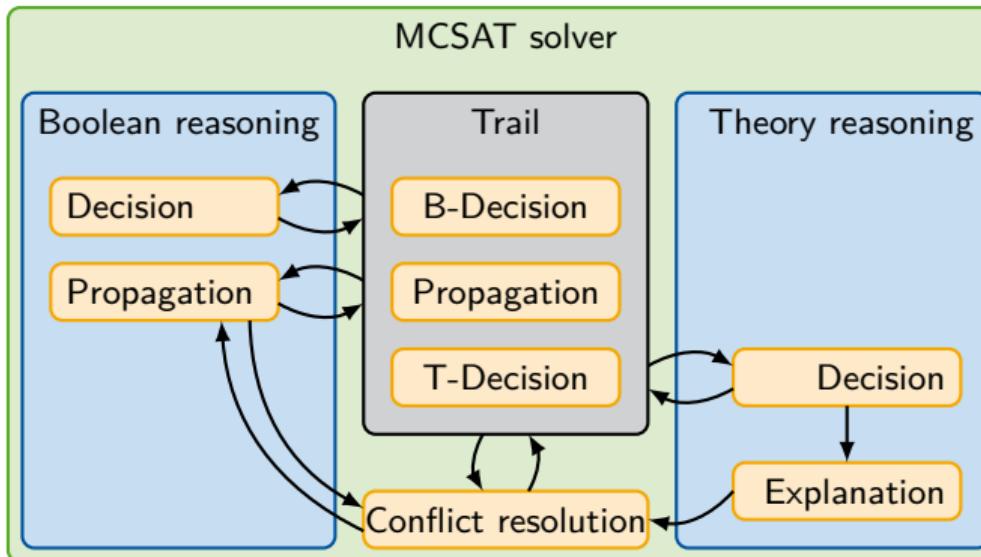
Conflict resolution

Trail: $\llbracket c_1, c_2 \rrbracket$



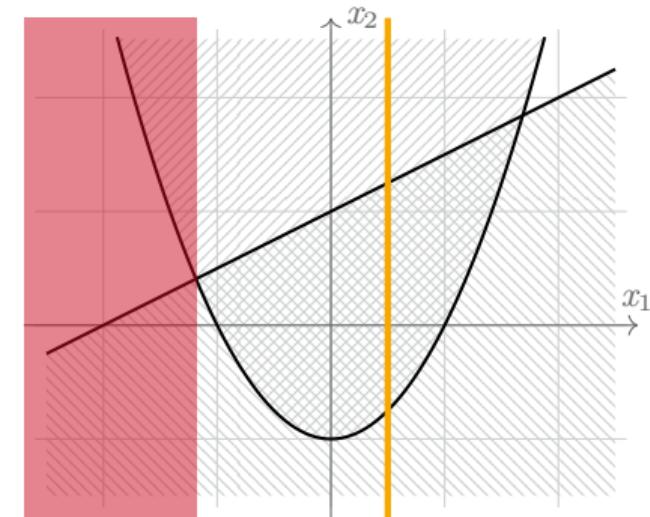
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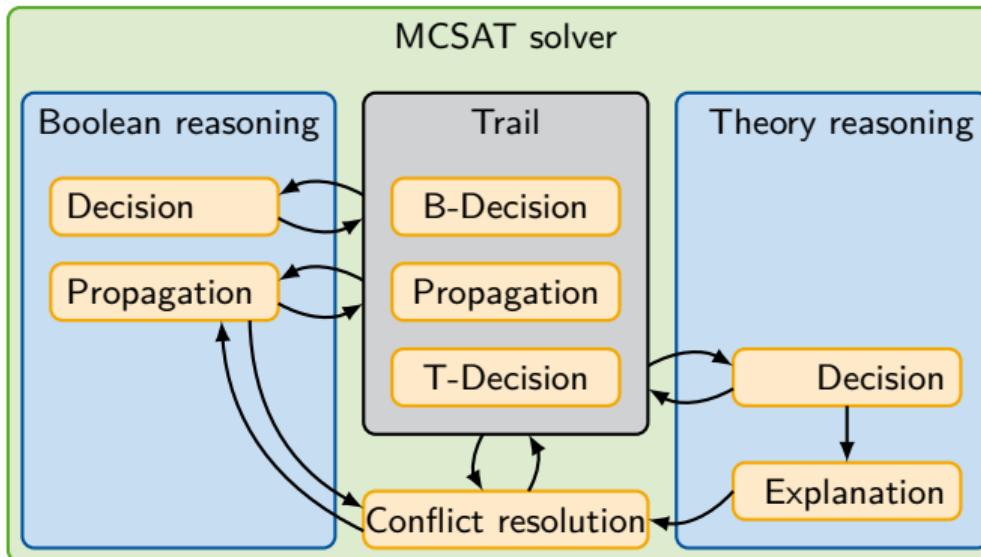
Guess: $x_1 \mapsto 0.5$

Trail: $\llbracket c_1, c_2, x_1 \mapsto 0.5 \rrbracket$



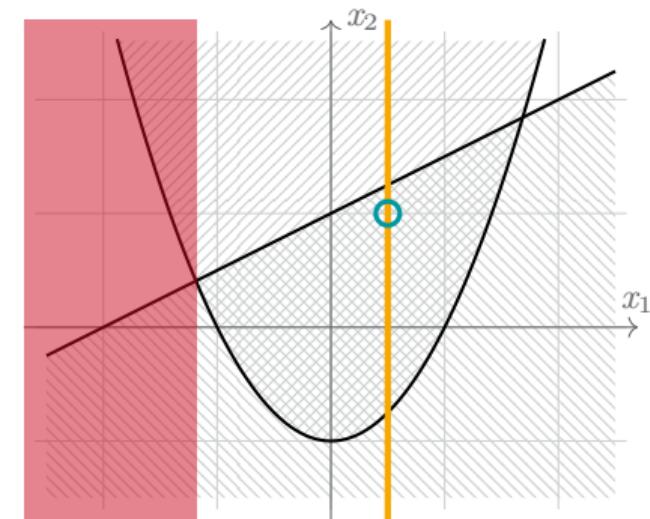
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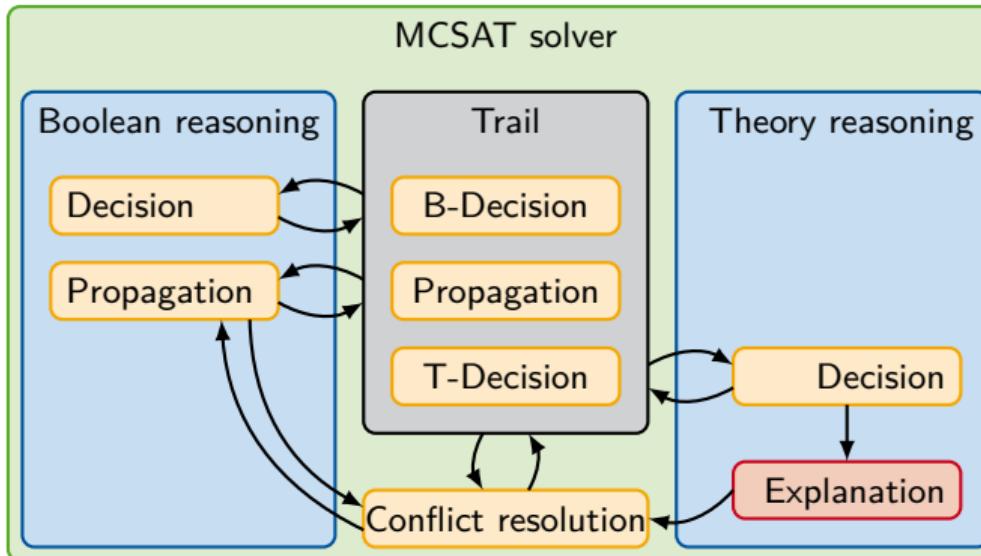
Guess: $x_2 \mapsto 1$

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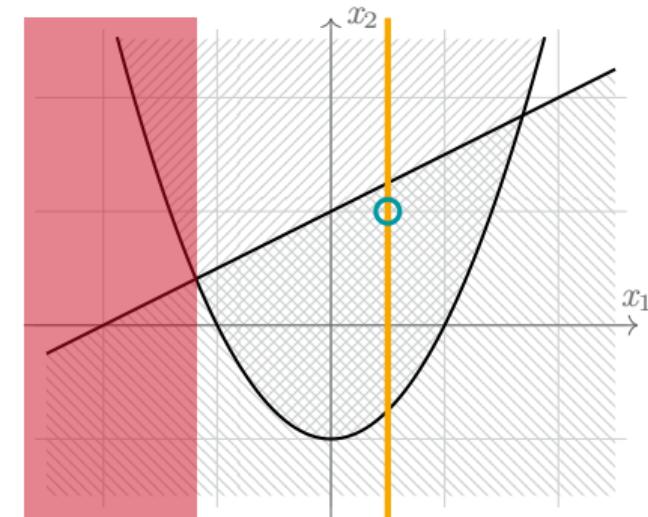
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Model-Constructing Satisfiability Calculus



Guess: $x_2 \mapsto 1$

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[Jovanović + 2012] [Moura + 2013]

Explanation functions

Definition (Explanation function)

Let $\mathcal{A} = \{x_1 \mapsto \alpha_1, \dots, x_k \mapsto \alpha_k\}$ and $C = \{c_1, \dots\}$ constraints over x_1, \dots, x_{k+1} .
Assume that $\nexists \alpha_{k+1}. \{x_1 \mapsto \alpha_1, \dots, x_{k+1} \mapsto \alpha_{k+1}\} \models C$.

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We need to get rid of x_{k+1} : **Quantifier elimination**

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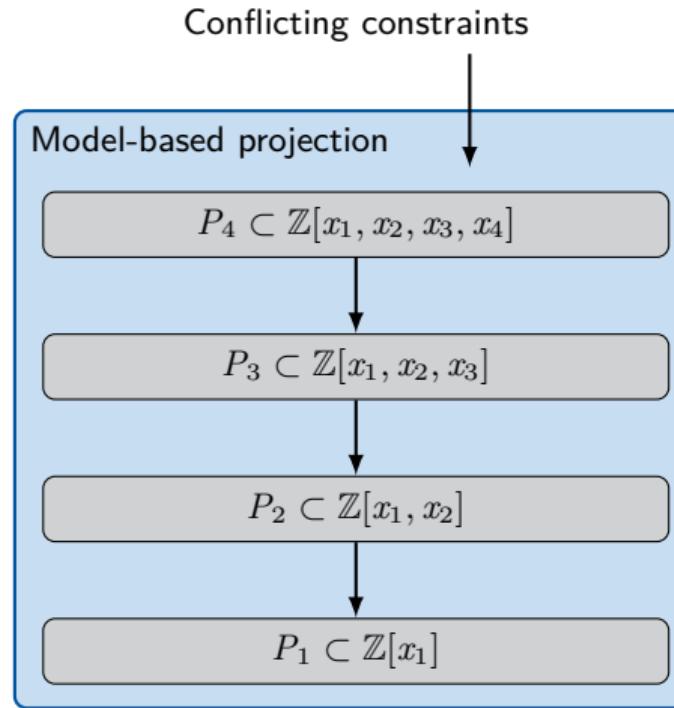
Model-based CAD [Jovanović + 2012], Fourier-Motzkin [Jovanović + 2013]

CAD-based / NLSAT

Conflicting constraints

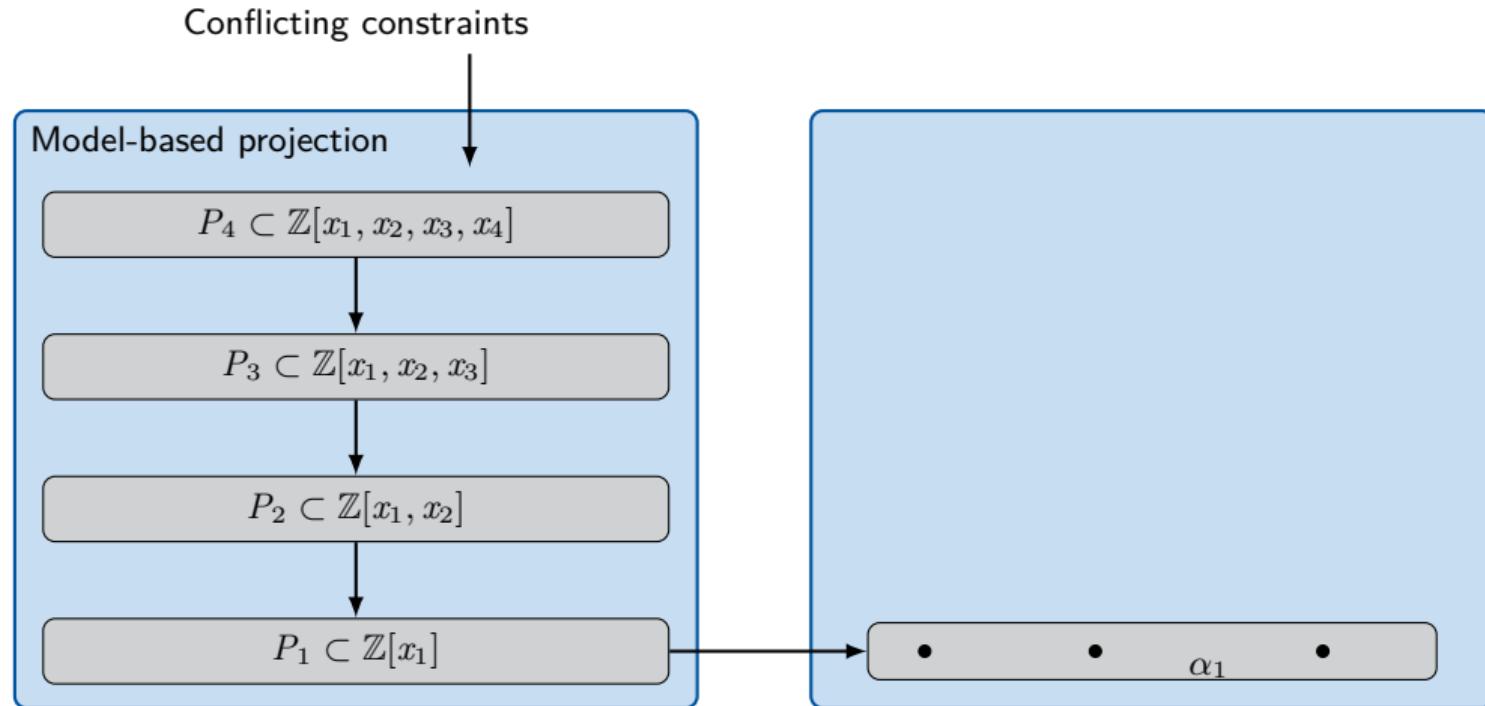
[Jovanović + 2012]

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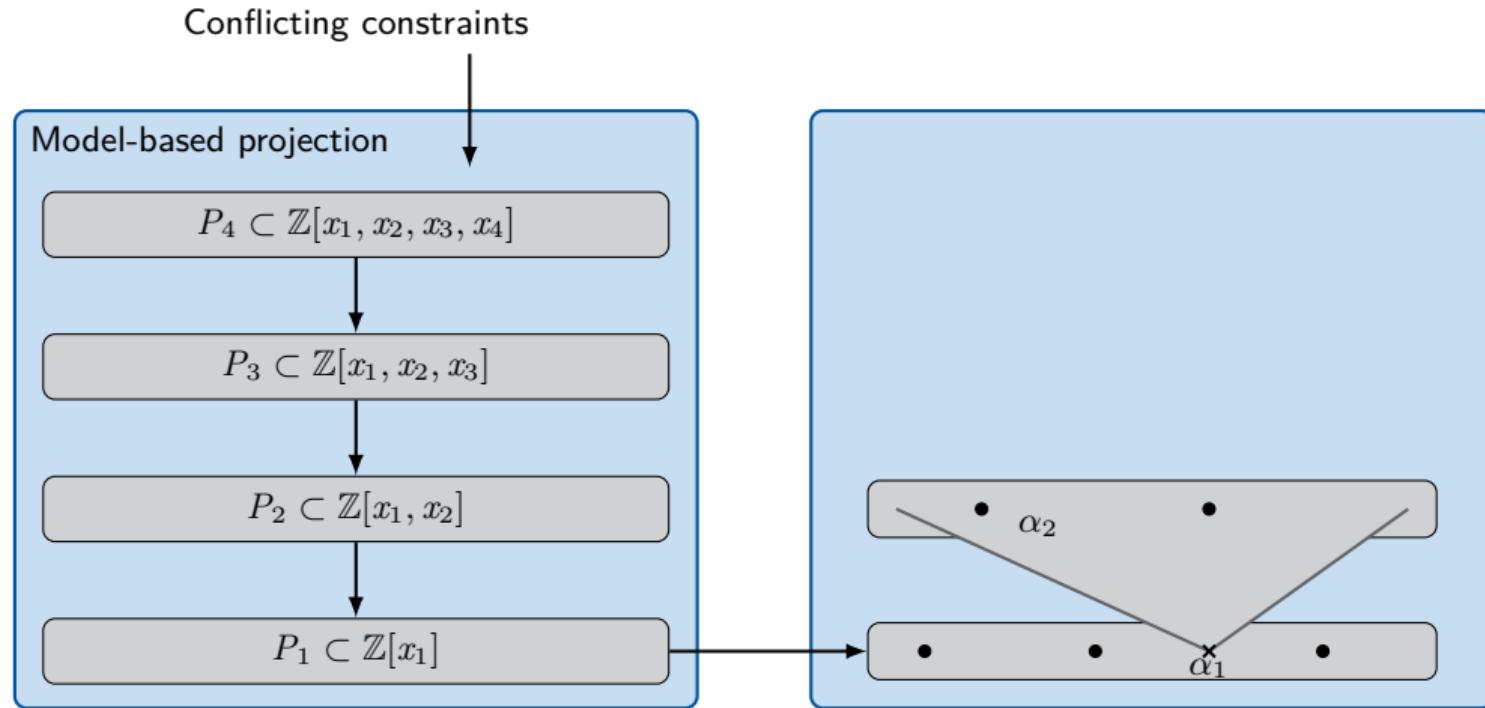
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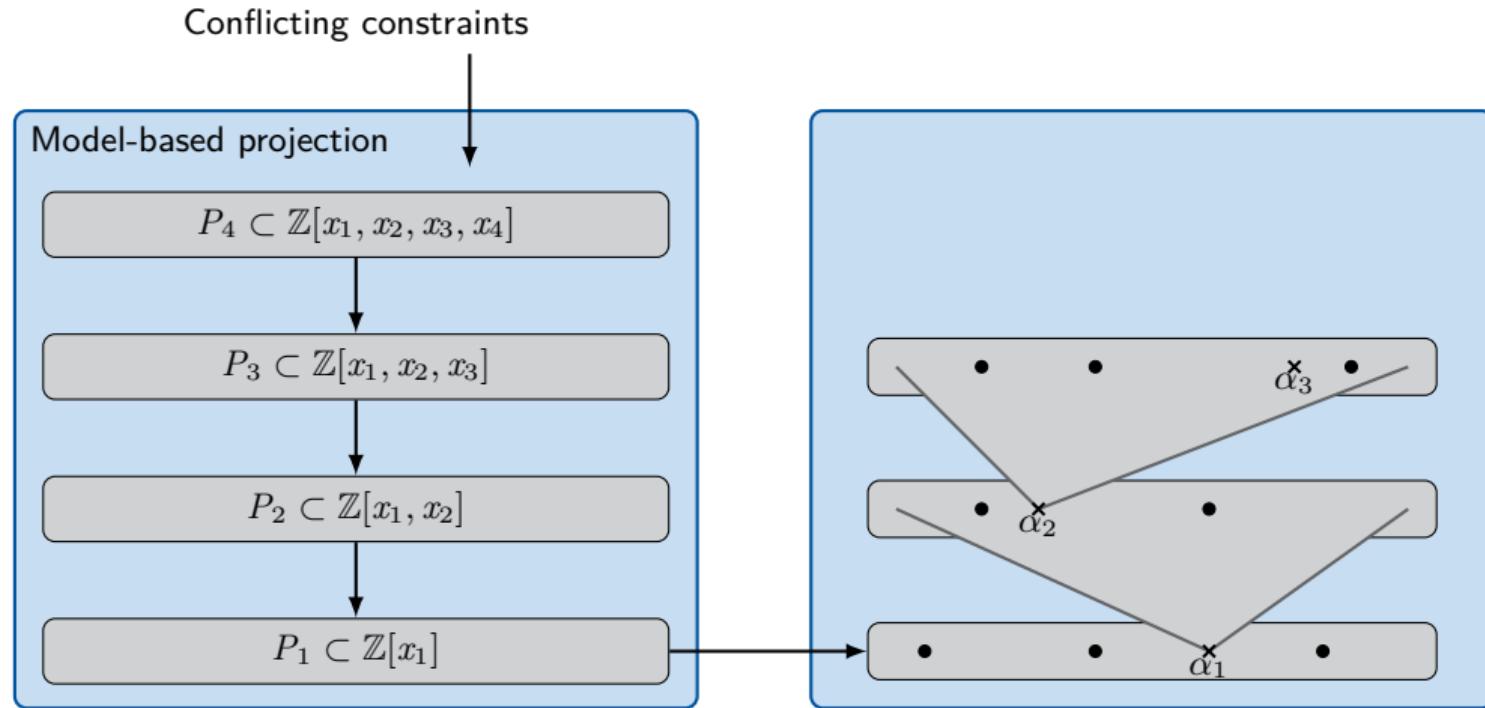
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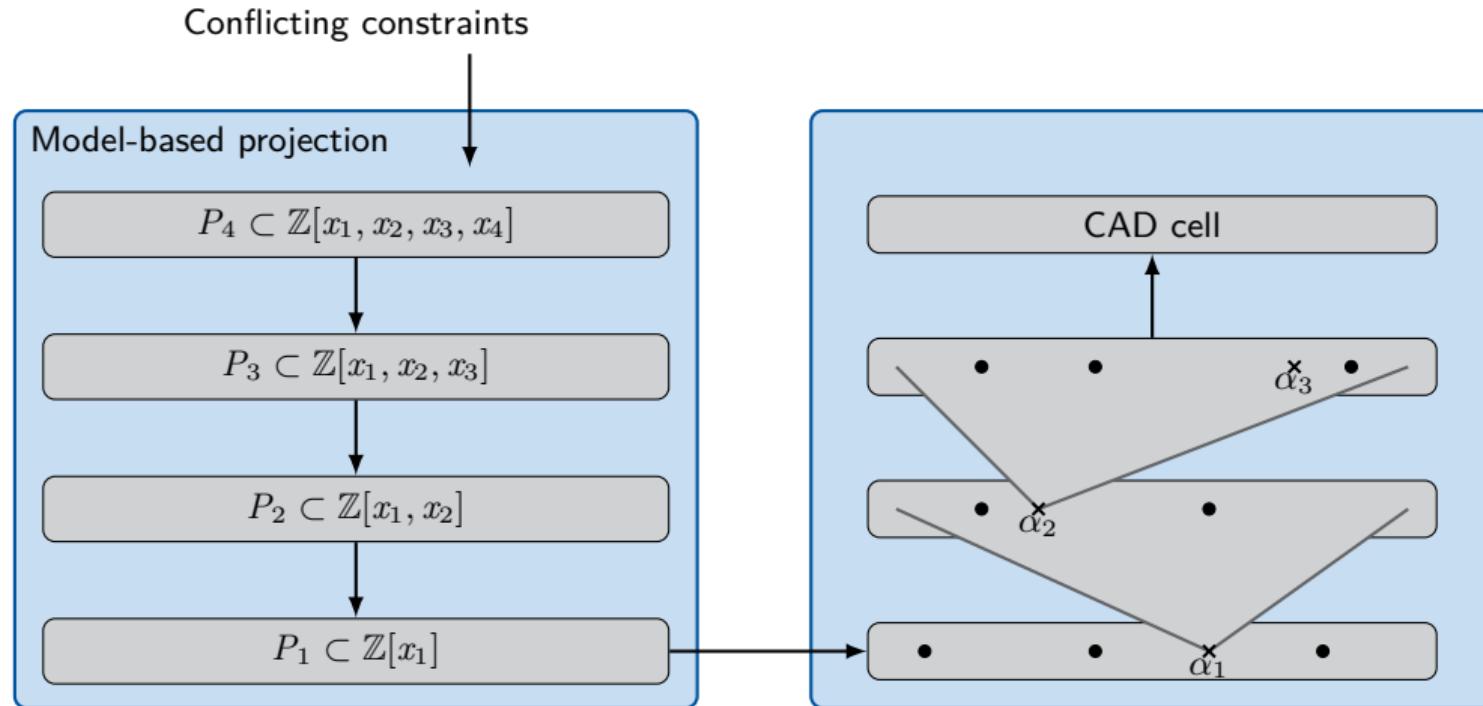
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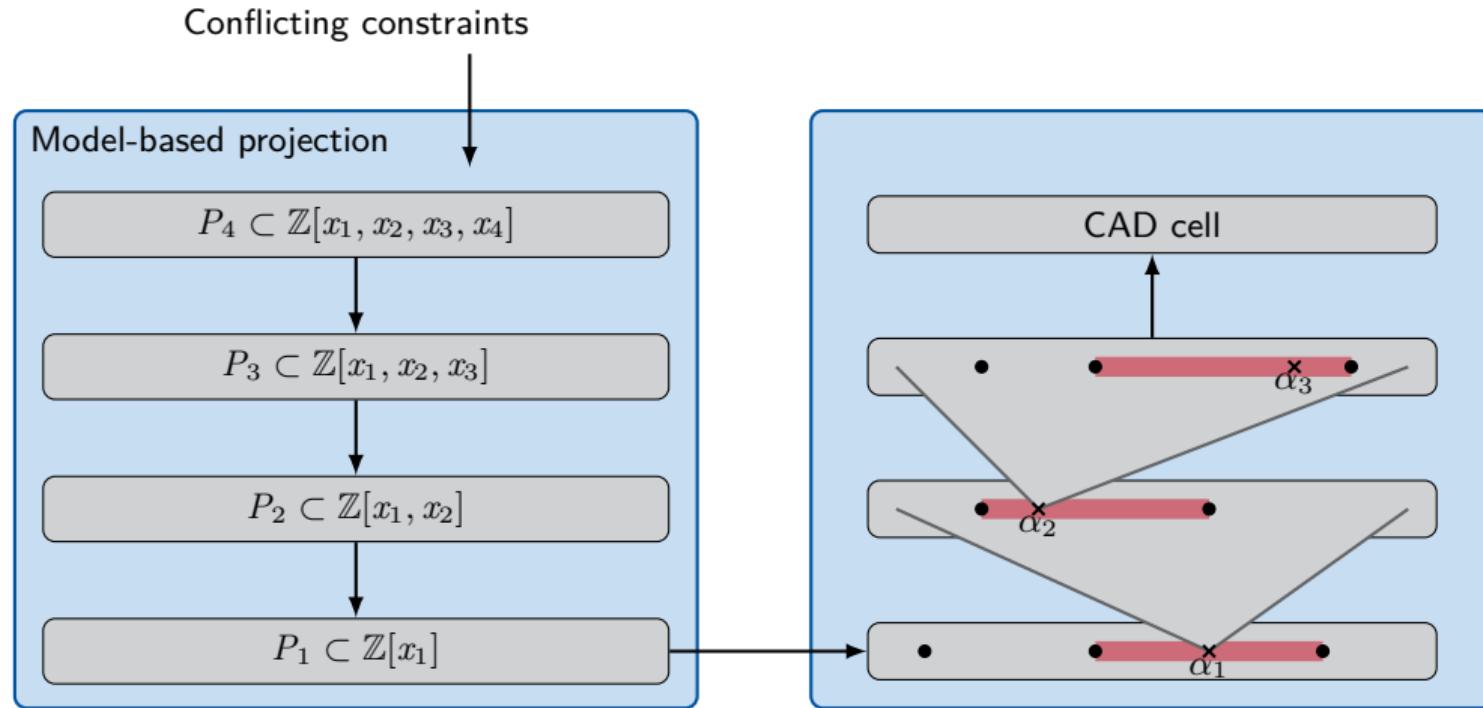
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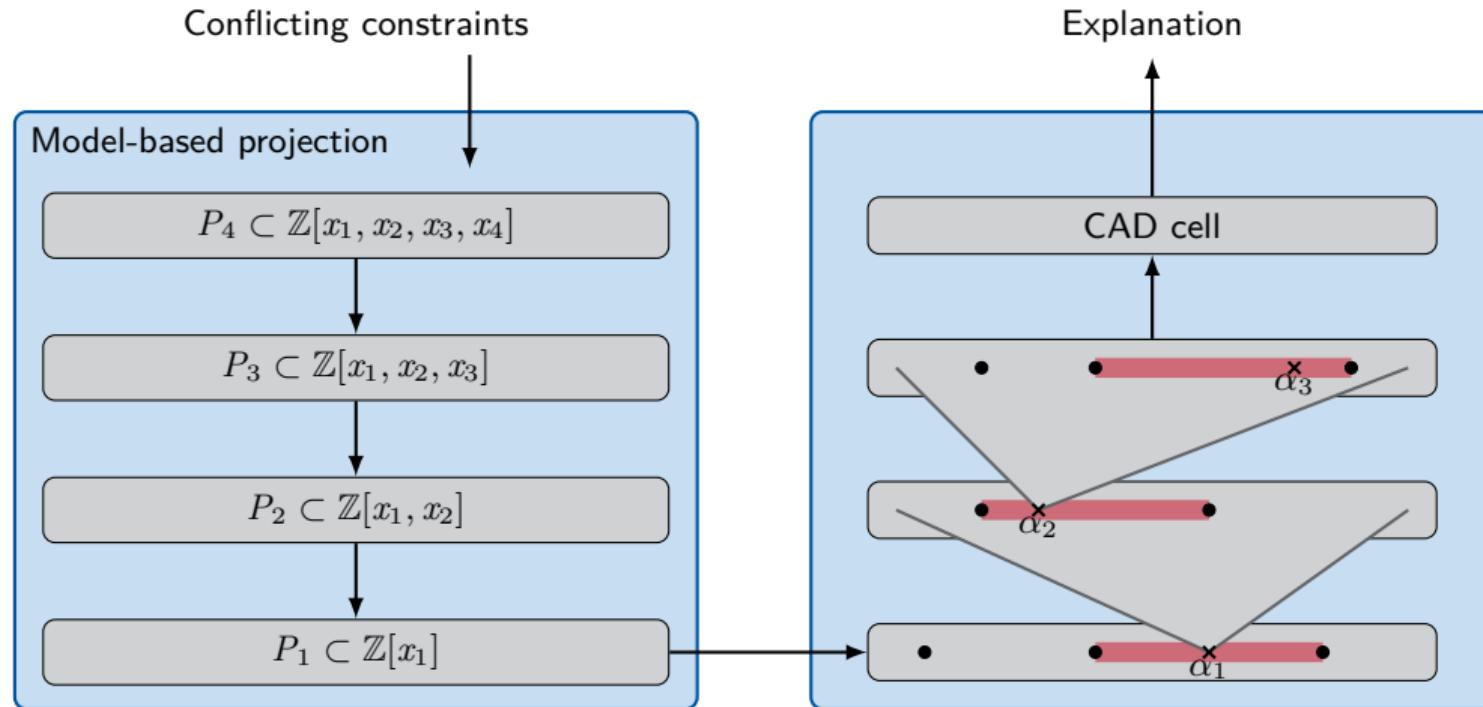
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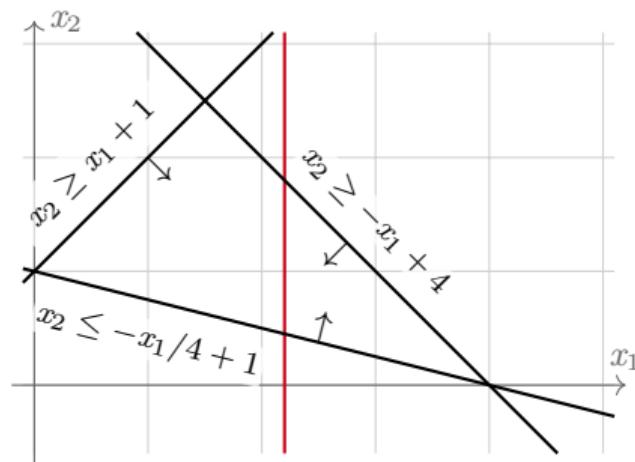
CAD-based / NLSAT



[Jovanović + 2012]

Fourier-Motzkin

[Bartolomé 2018]

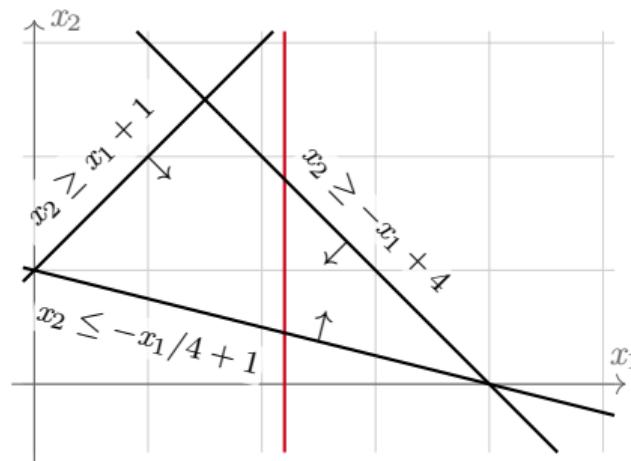


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Conflicting constraints



[Jovanović + 2013]

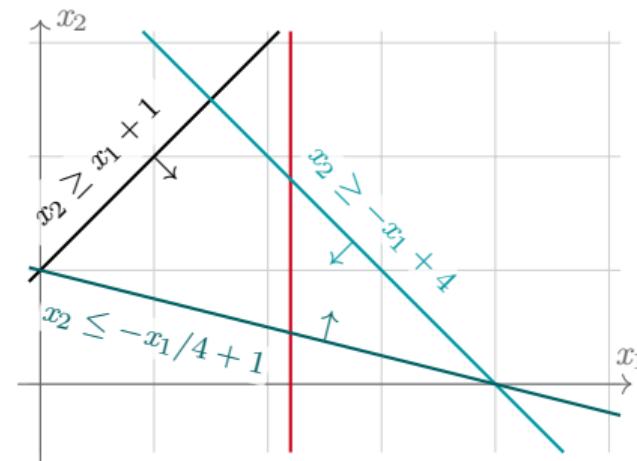
Fourier-Motzkin

[Bartolomé 2018]

Conflicting constraints

Identify lower and upper bounds

$$-x_1 + 4 \leq x_2 \leq -x_1/4 + 1$$



[Jovanović + 2013]

Fourier-Motzkin

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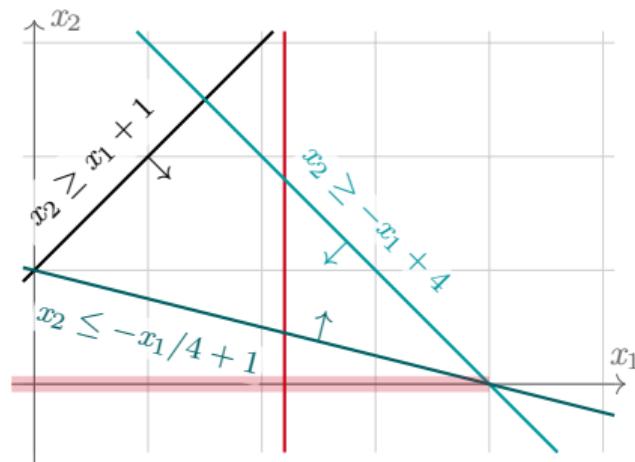
Conflicting constraints

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Combine bounds

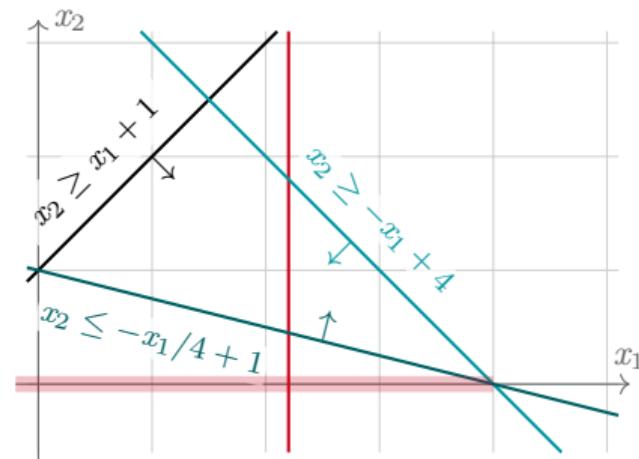
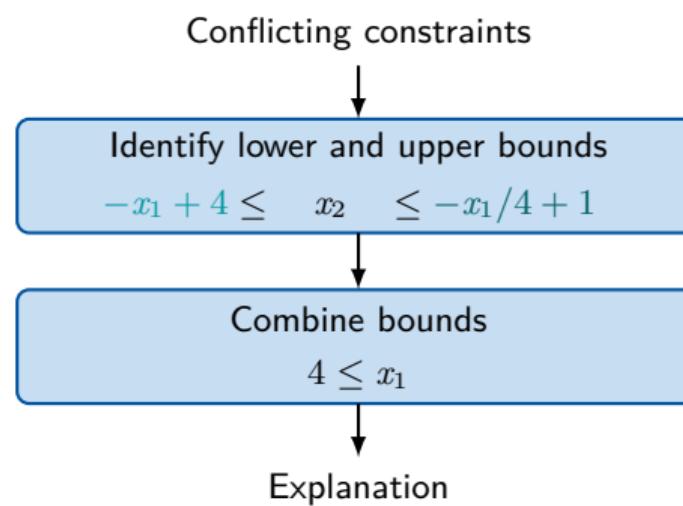
$$4 \leq x_1$$



[Jovanović + 2013]

Fourier-Motzkin

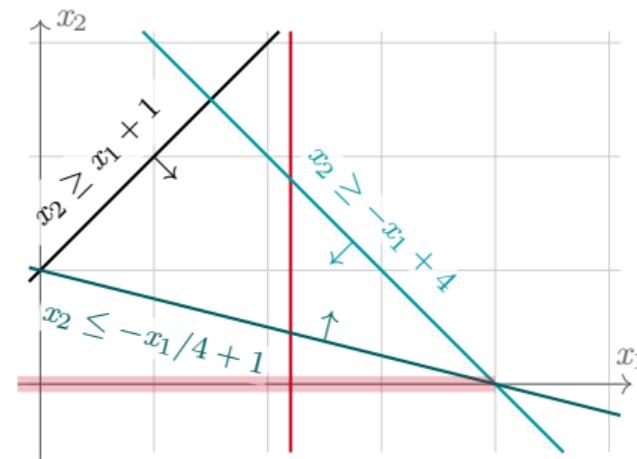
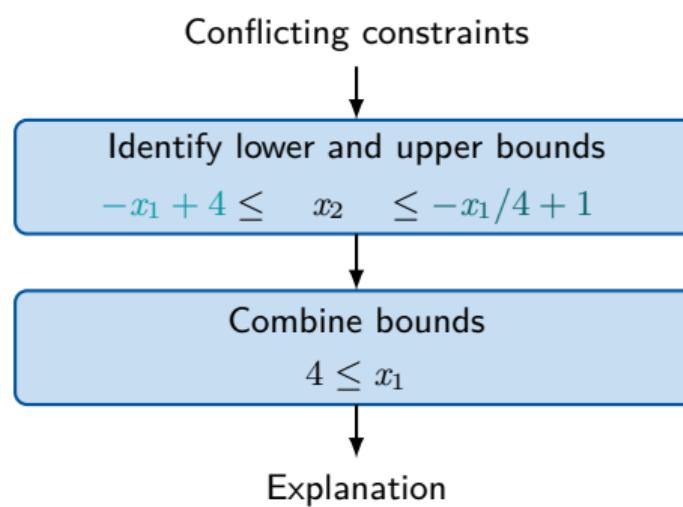
[Bartolomé 2018]



[Jovanović + 2013]

Fourier-Motzkin

[Bartolomé 2018]



- Strict inequalities
- Disequalities
- Nonlinear coefficients

$$2x_1 + 1 < x_2 < x_1 + 2 \quad x_1 \mapsto 2$$

$$2x_1 + 1 \leq x_2 \leq x_1 + 2 \wedge x_2 \neq 3 \quad x_1 \mapsto 1$$

$$x_1^2 + 3 \leq x_2 \leq 2x_1 \quad x_1 \mapsto 1$$

[Jovanović + 2013]

Other explanation functions

Virtual cubstitution

[SC² 2017]

- Nonlinear but low-degree
- Flexible dimensionality of generated cells

[Brown 2013] [Brown + 2015]

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OneCell

[Neuß 2018]

- CAD tailored to construct a single cell
- Larger cells (and thus excludes more)

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Composition of explanation functions

- SMT-RAT: modular composition
- Sequential & parallel

Other explanation functions

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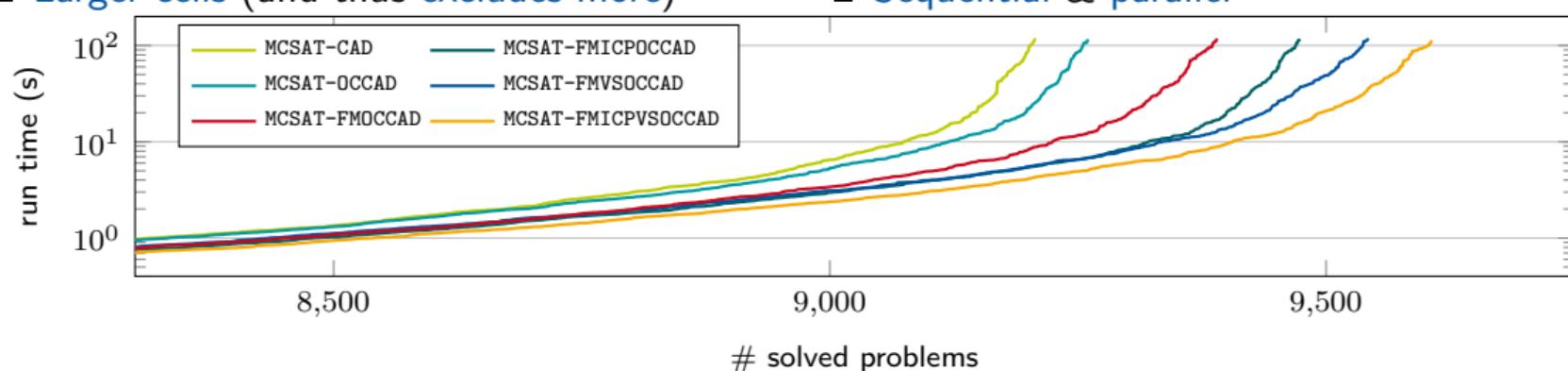
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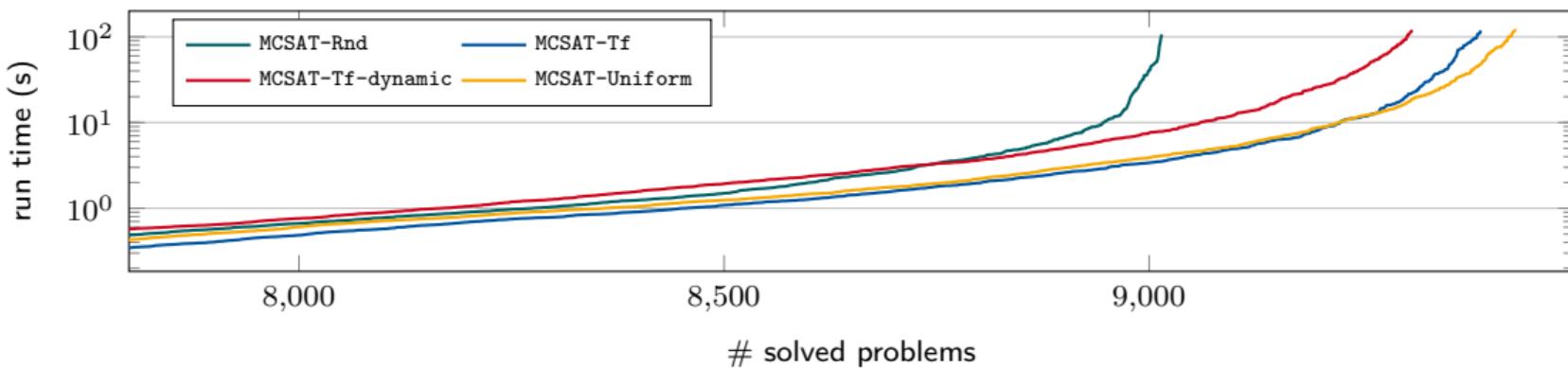
Theory variable ordering

[SC² 2019]

- Well-known: variable ordering is crucial for CAD, VS, FM,
- Usually: **static** ordering for theory reasoning
- Goal: use **dynamic** ordering for MCSAT [Jovanović + 2013]

Theory variable ordering

- Well-known: variable ordering is crucial for CAD, VS, FM,
- Usually: static ordering for theory reasoning
- Goal: use dynamic ordering for MCSAT [Jovanović + 2013]
- Observation: MCSAT-Tf and MCSAT-Uniform perform best
- But: MCSAT-Tf-dynamic is worse



Comparison of lazy SMT and MCSAT

[SC² 2019]

- Two similar proof systems: lazy SMT and MCSAT
- Experience: MCSAT better for nonlinear
- Goal: theoretic comparison of lazy SMT and MCSAT

Comparison of lazy SMT and MCSAT

[SC² 2019]

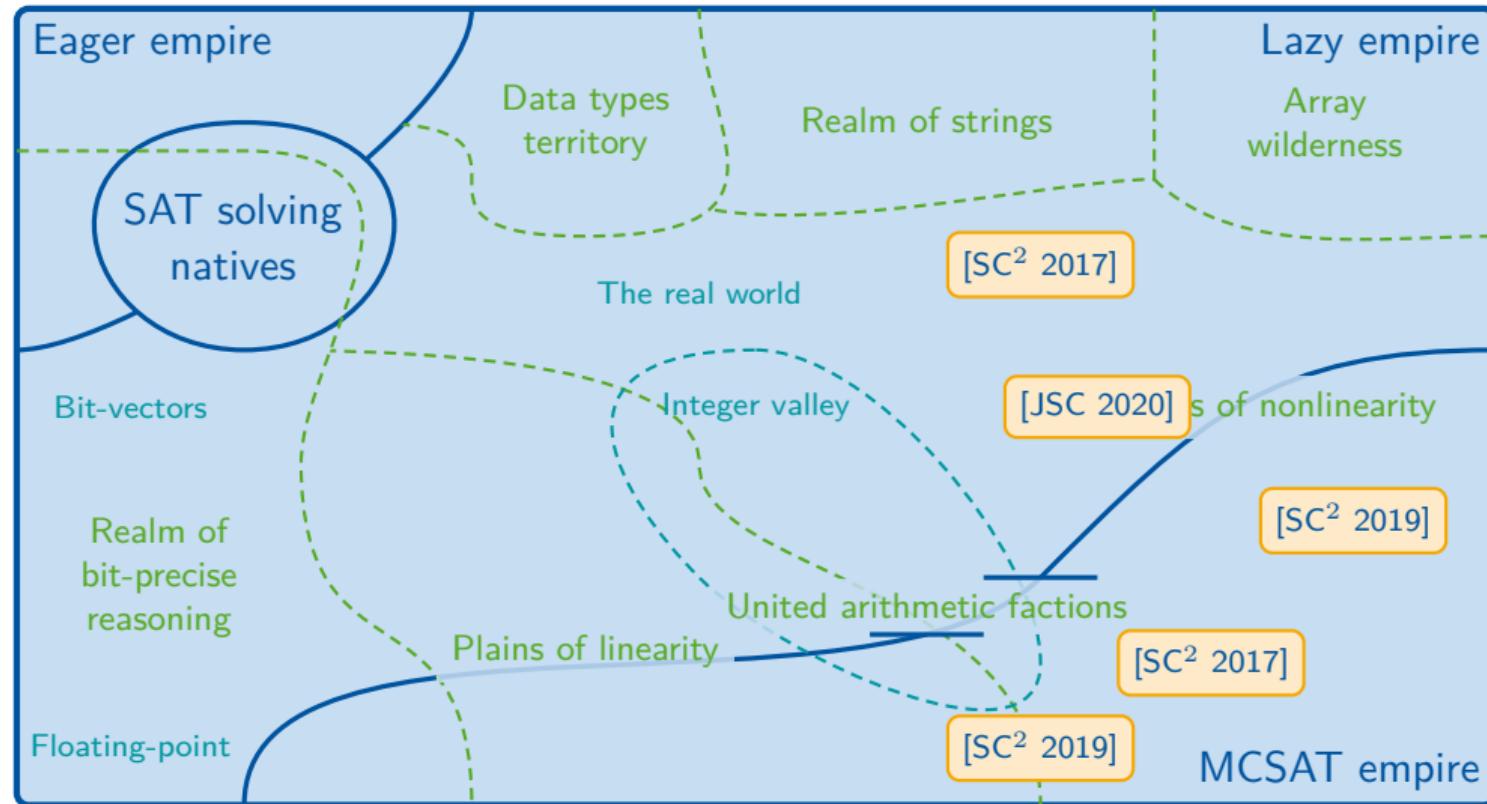
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Theorem

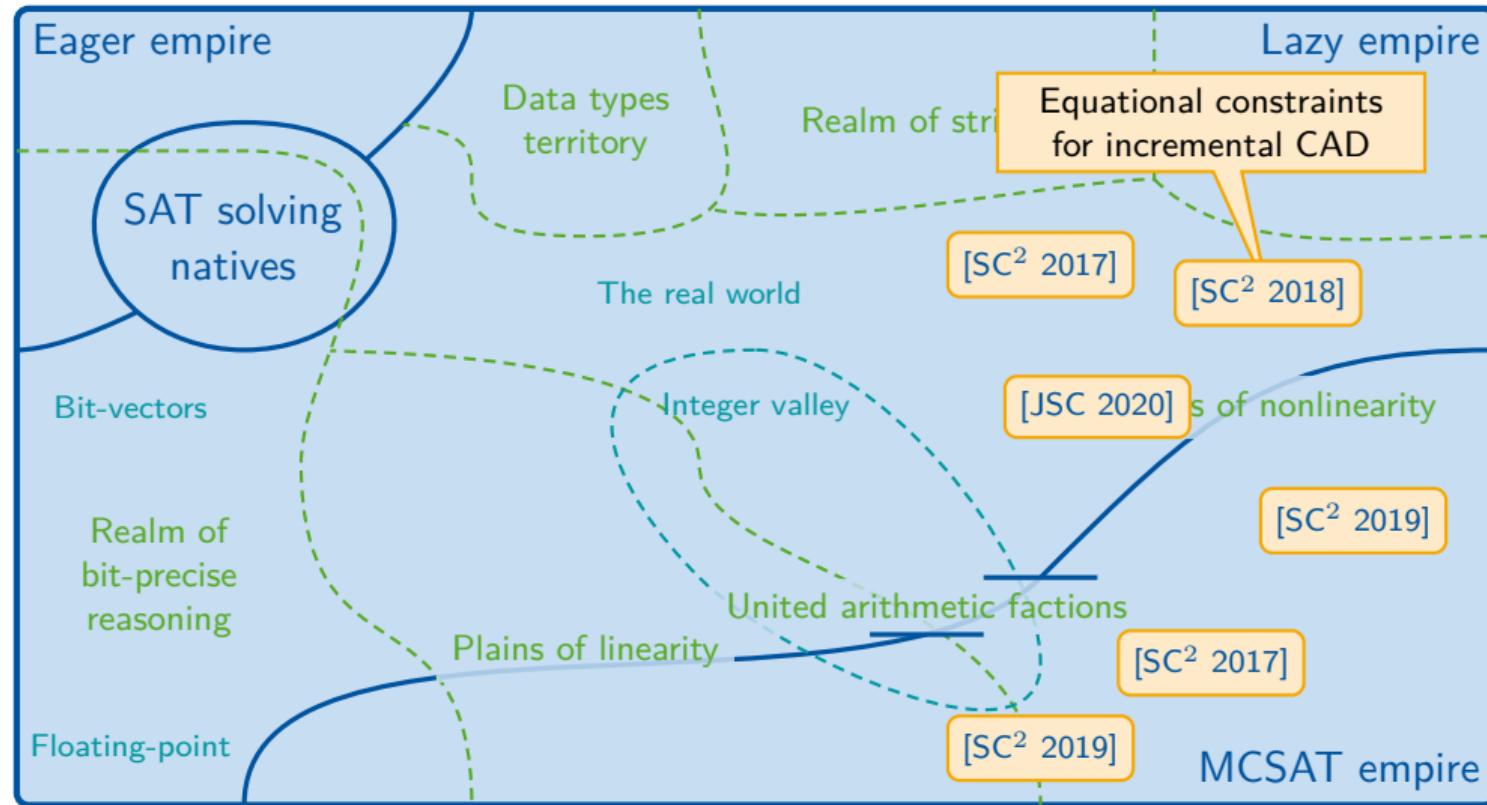
*Lazy SMT and MCSAT are algorithmically equivalent**.

*: terms and conditions apply

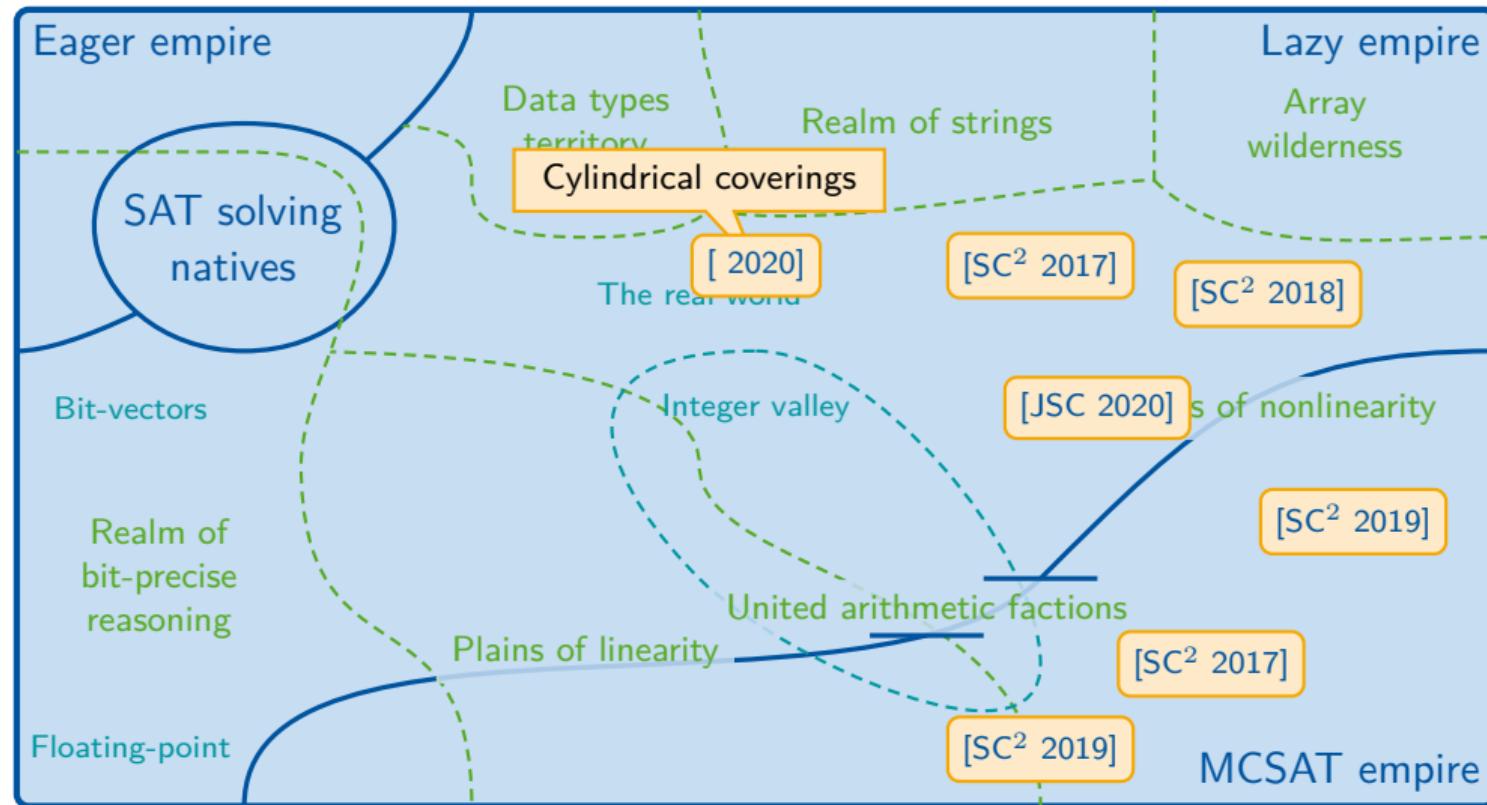
Summary



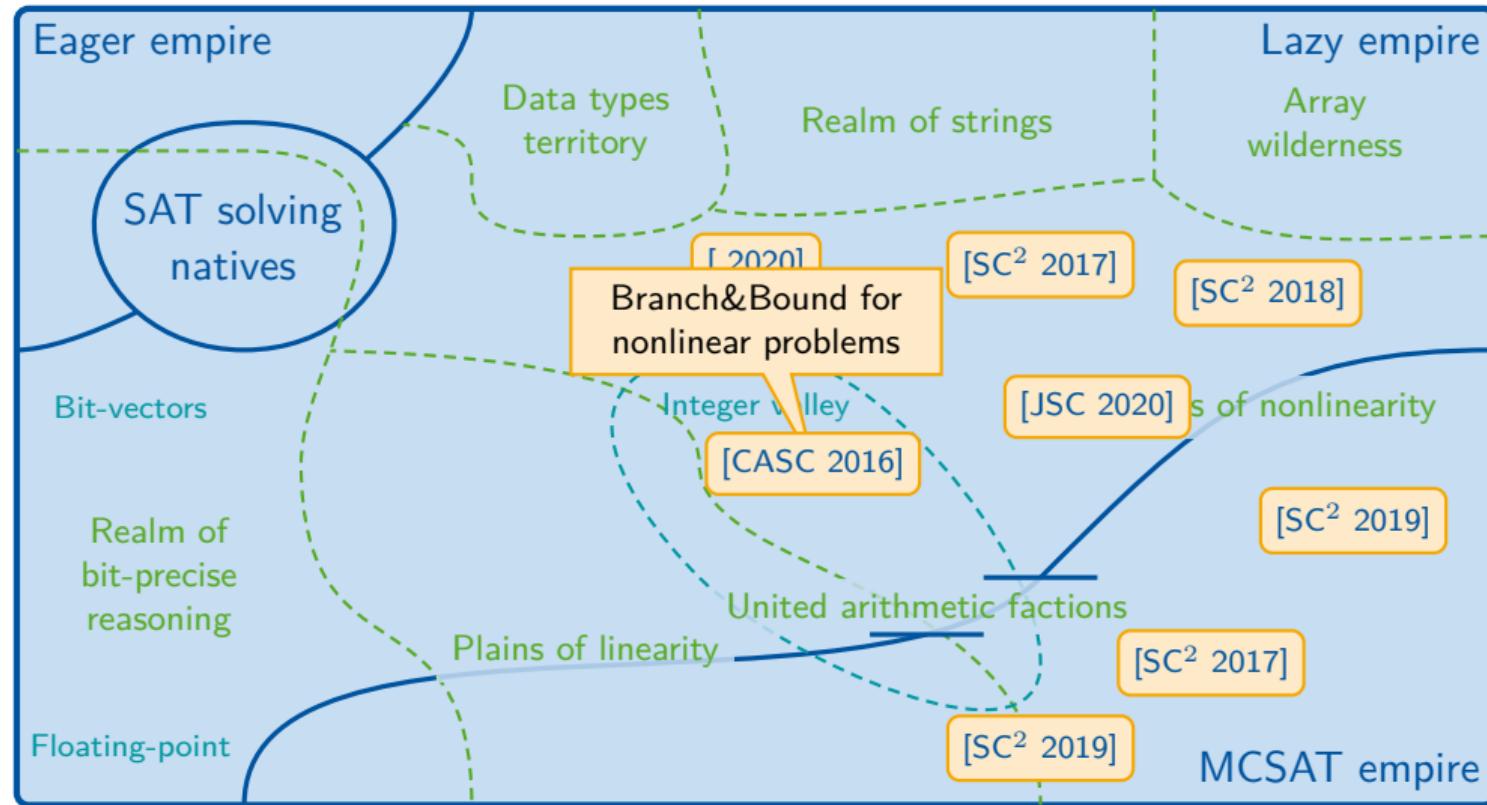
Summary



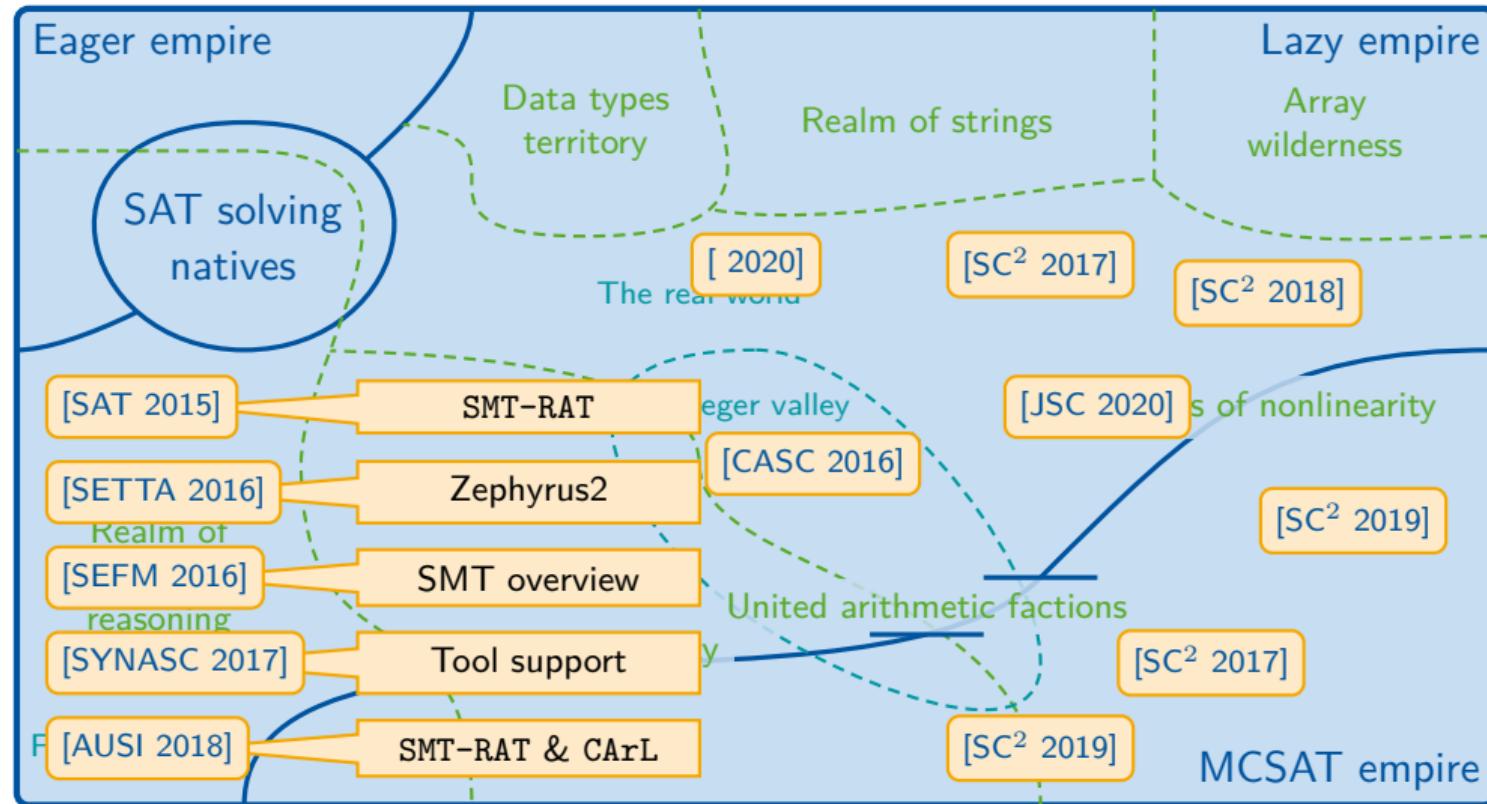
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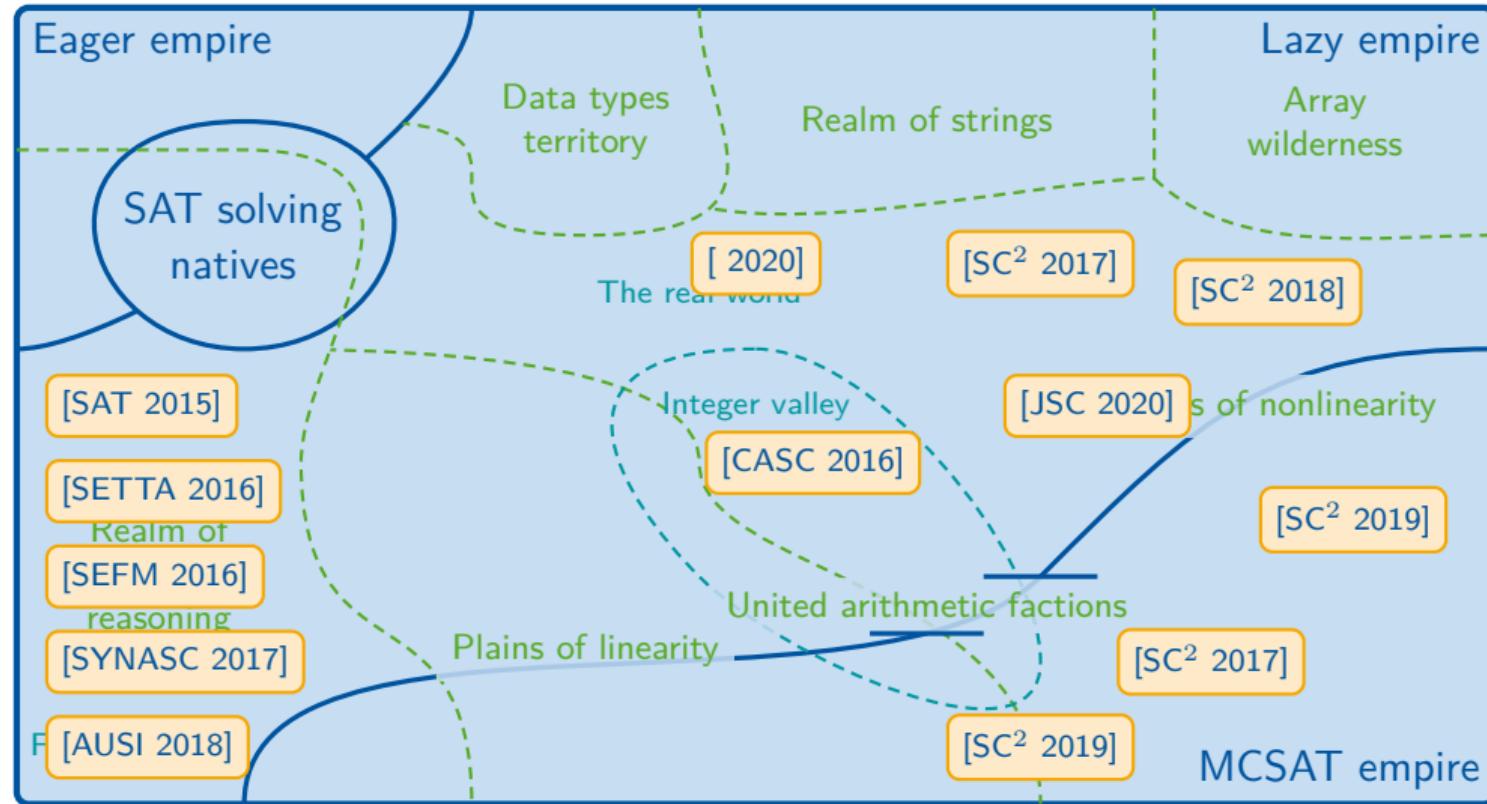
Summary



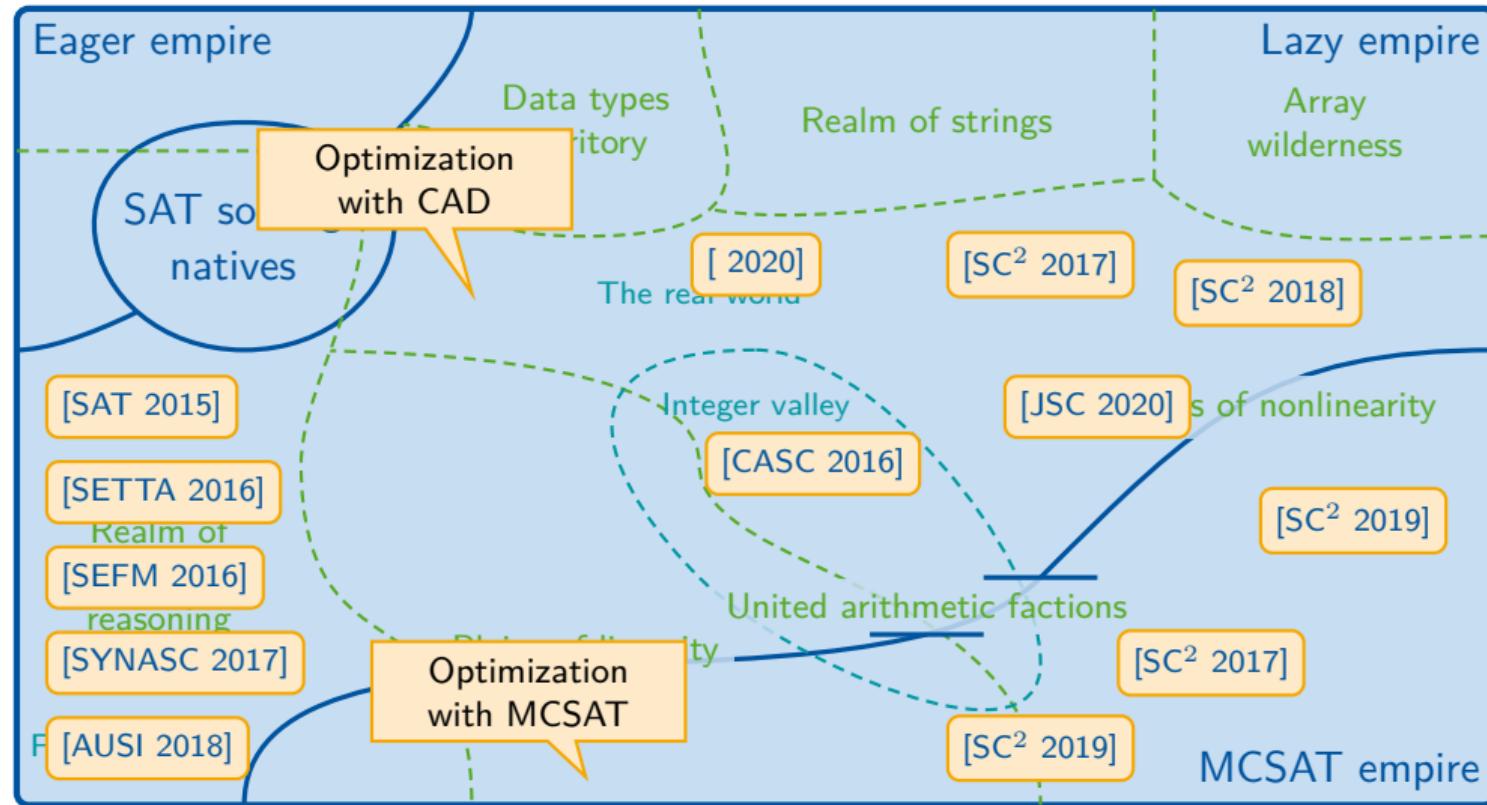
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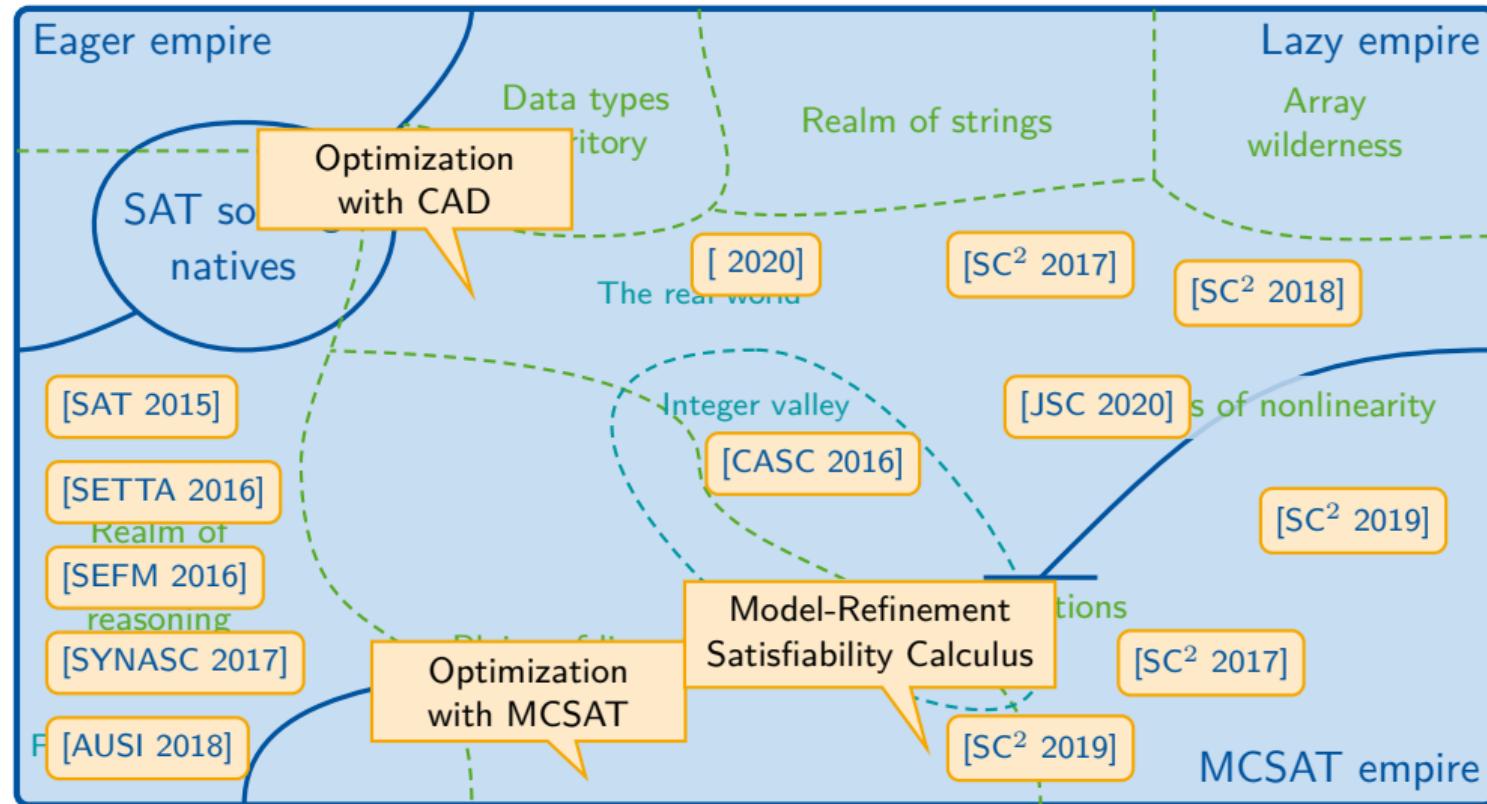
Summary



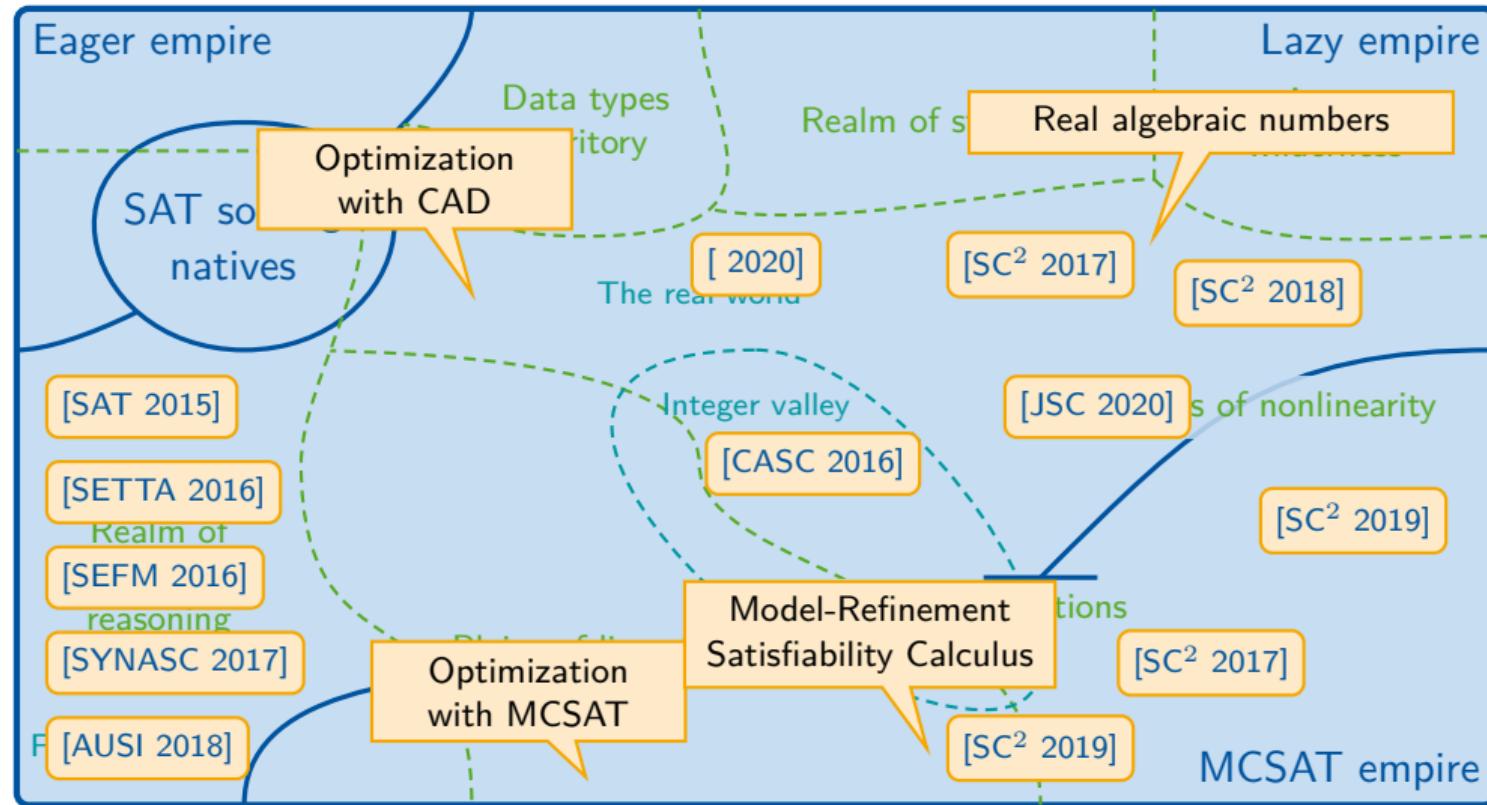
Summary



Summary



Summary



Conclusion

- CAD is suitable for lazy SMT solving

- Incrementality is very beneficial

- Backtracking is efficient

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Directions for future research:

- Optimize CAD integration: better scheduling, NuCAD, parallelization, ...
- Novel adaptations of CAD: CAC [2020], NuCAD [Brown 2015], ...
- New methods for MCSAT: explanations, orderings, assignment finders, ...
- More applications: optimization, dedicated heuristics, ...

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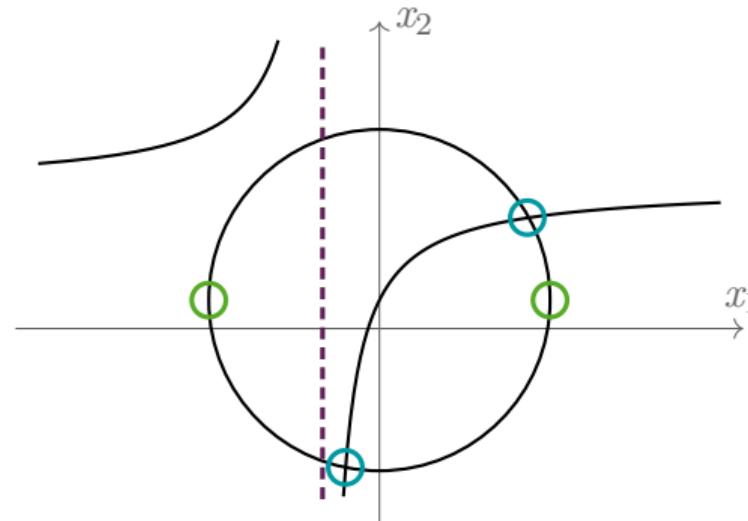
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CAD projection

Example: McCallum

$$\begin{aligned} \text{Proj}(P) = & \{\text{coeffs}(p), \text{disc}(p) \mid p \in P\} \\ & \cup \{\text{res}(p, q) \mid p, q \in P\} \end{aligned}$$



[McCallum 1985]

Minimal Infeasible Subsets

[Hentze 2017]

- Set of constraints $\{c_1, c_2, \dots\}$ is infeasible

[Jaroschek + 2015] [Chvátal 1979]

Minimal Infeasible Subsets

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- Set of constraints $\{c_1, c_2, \dots\}$ is infeasible
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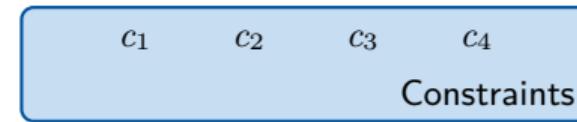
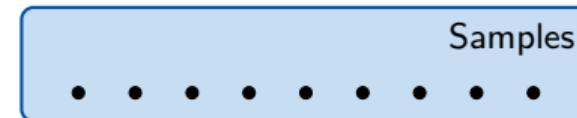
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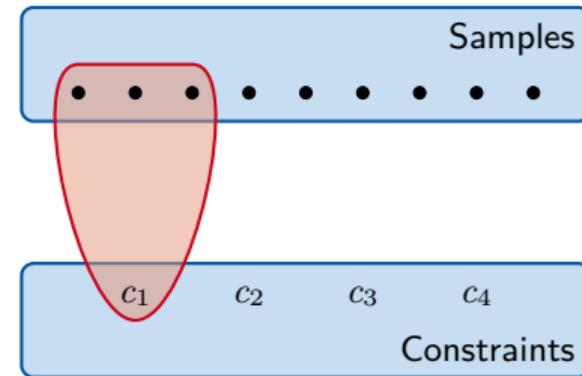


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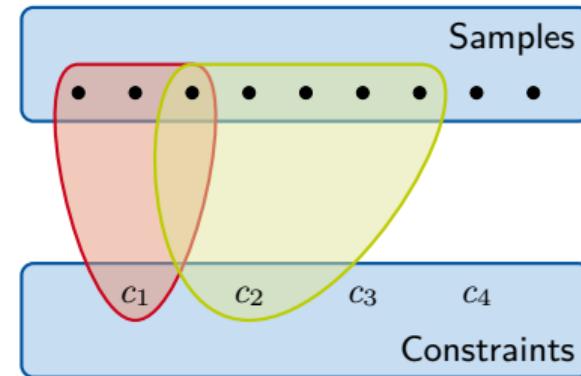


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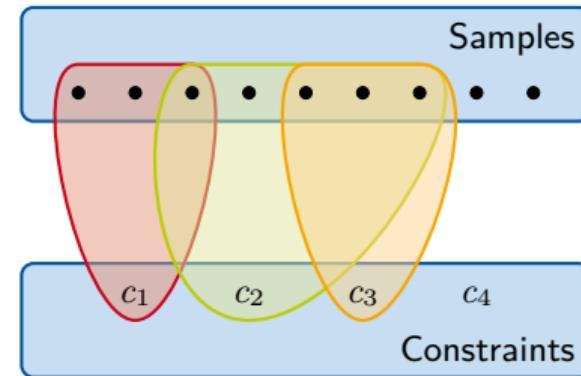


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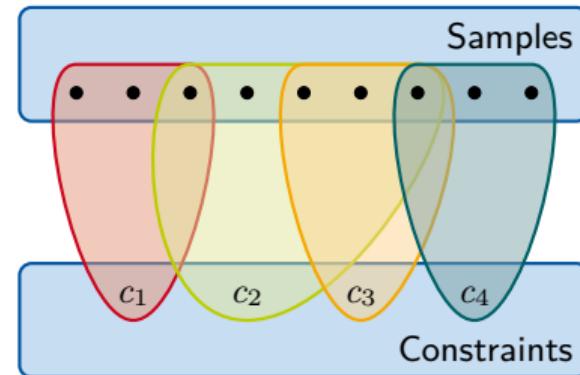


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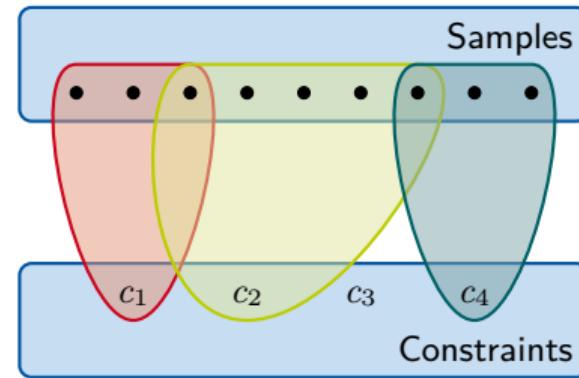


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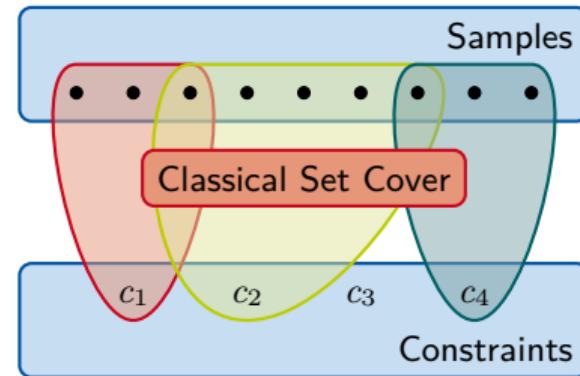


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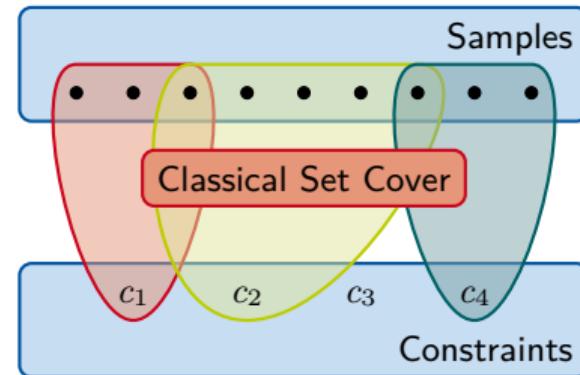


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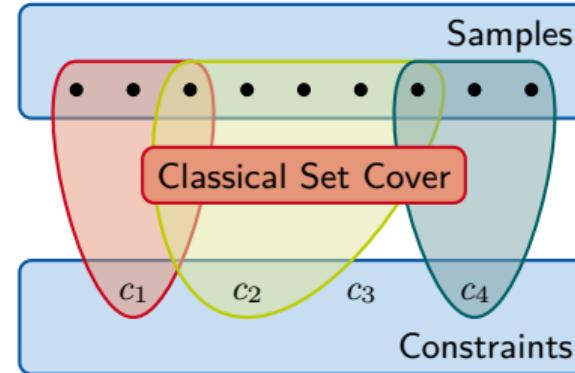
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- Huge improvements (in other logics...)
- How to construct?
- Significant improvements for MIS ...
- but no effect on solver performance

[Jaroschek + 2015] [Chvátal 1979]



Solver	SAT	UNSAT	overall
Greedy-PP	4327	4249	8576
Greedy-Weighted	4329	4247	8576
Hybrid	4328	4248	8576
Trivial	4325	4251	8576
Exact	4328	4249	8577
Greedy	4328	4250	8578

Using CAD for ...

...Quantifier Elimination

[Neuhäuser 2018]

$$(\exists x. \forall y. \varphi(x, y, z)) \Leftrightarrow \varphi'(z)$$

- Validation of our CAD implementation
- Show reuse of implementation
- Results comparable to QEPCAD B

[Brown 2003] [Fuhs + 2007]

Using CAD for ...

...Quantifier Elimination

[Neuhäuser 2018]

$$(\exists x. \forall y. \varphi(x, y, z)) \Leftrightarrow \varphi'(z)$$

...Integer problems

[CASC 2016]

$$\exists x. \varphi(x) \quad x \in \mathbb{Z}$$

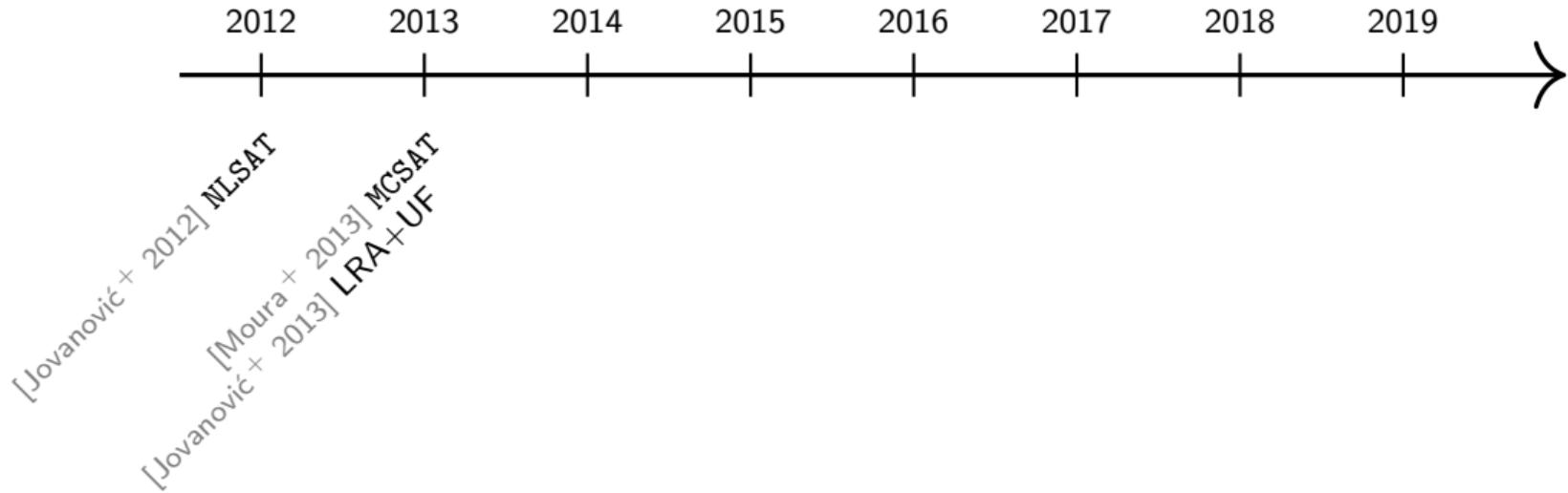
- Validation of our CAD implementation
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- Common approach: bit-blasting
mostly aims for small domains
- Our approach: Branch & Bound
mostly aims for algebraically easy problems & UNSAT

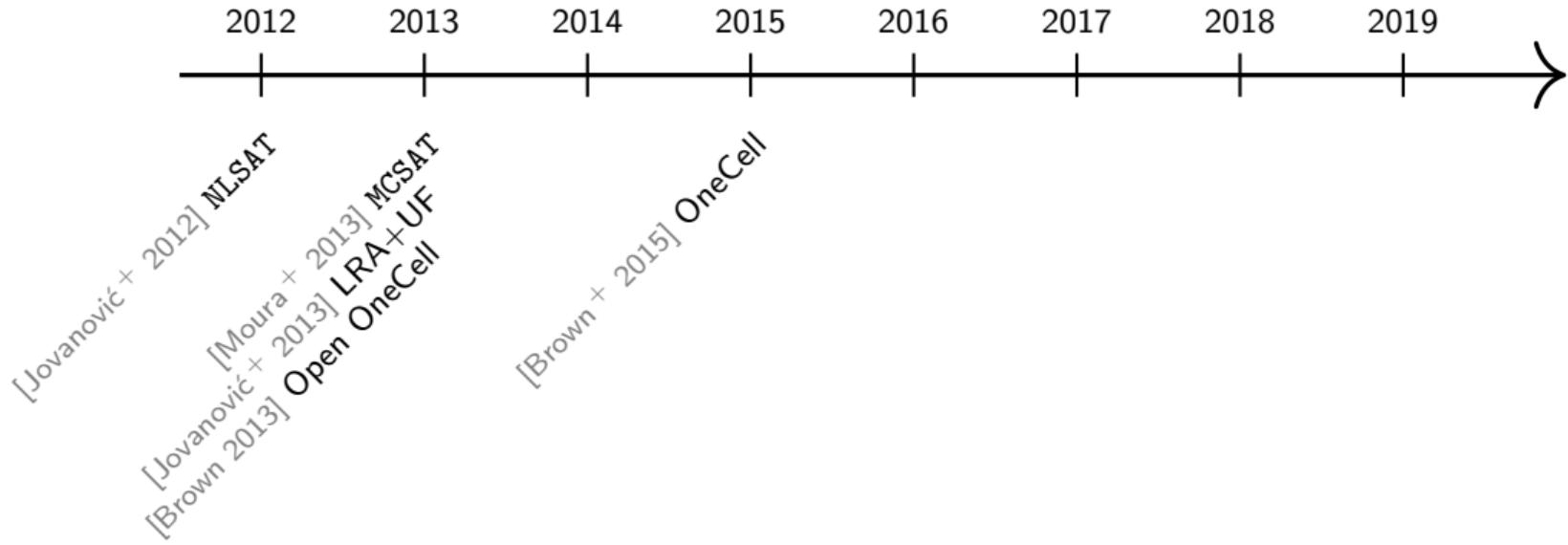
Solver	SAT	UNSAT	overall
NIA-B&B	1044	518	1562
NIA-Blast	4367	26	4393
NIA-Full	4490	508	4998

[Brown 2003] [Fuhs + 2007]

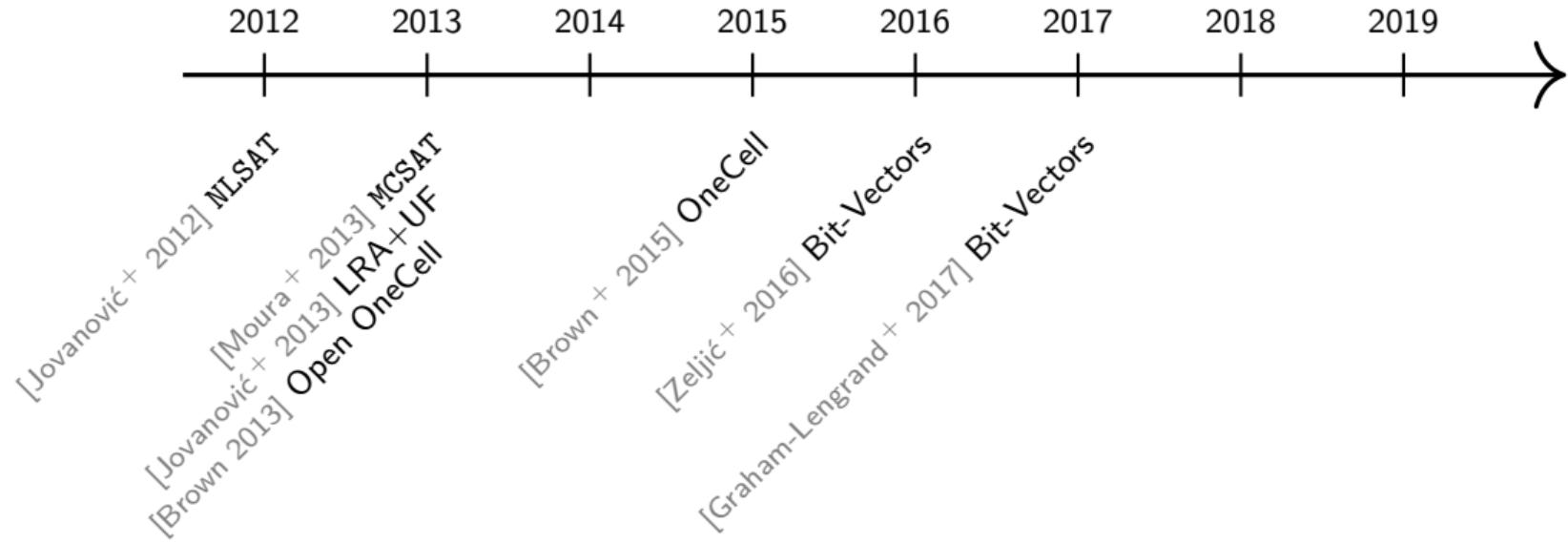
MCSAT history



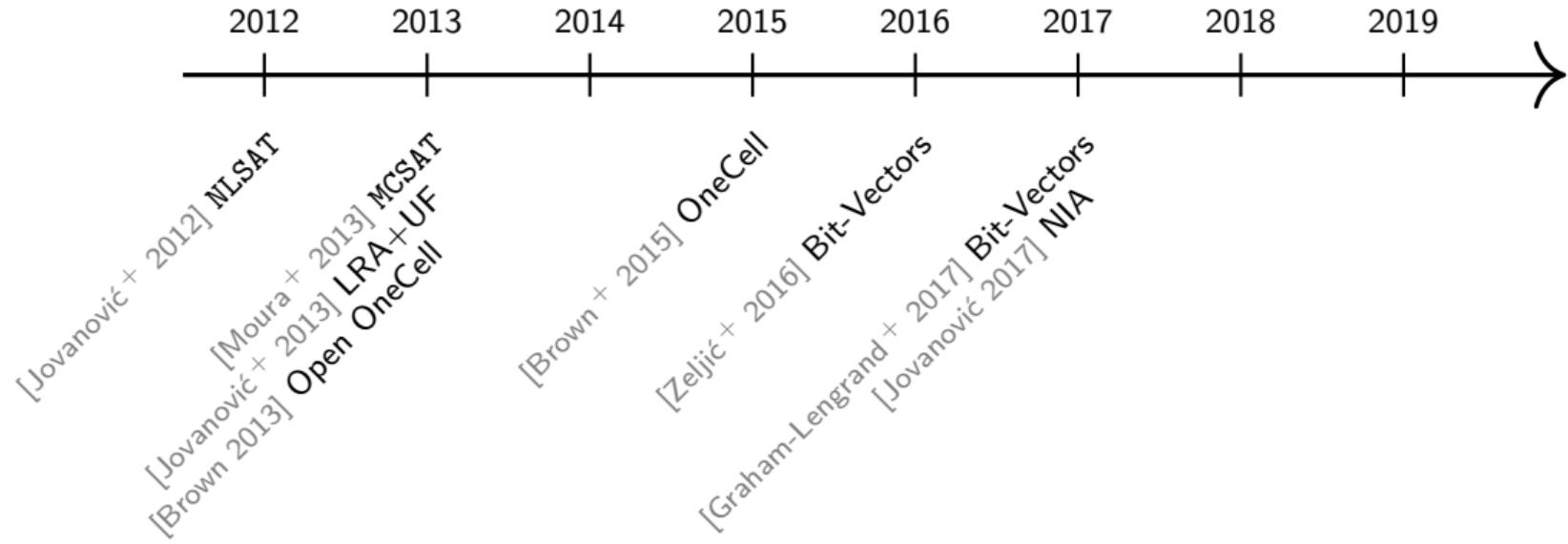
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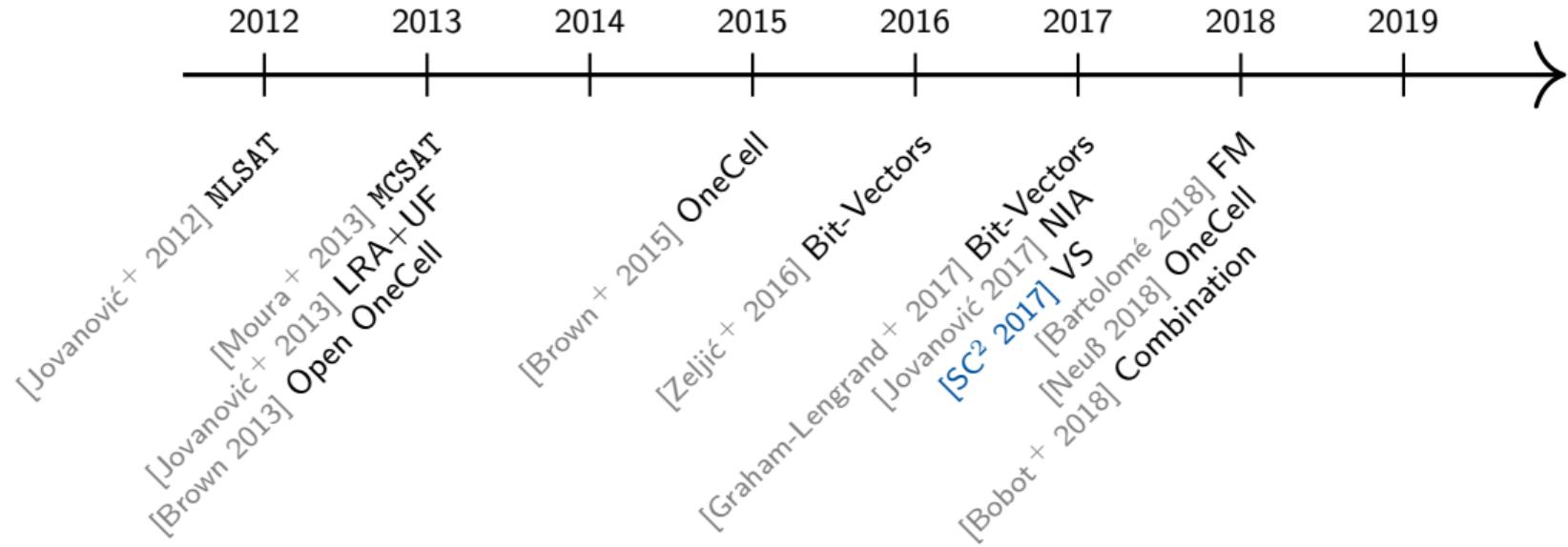
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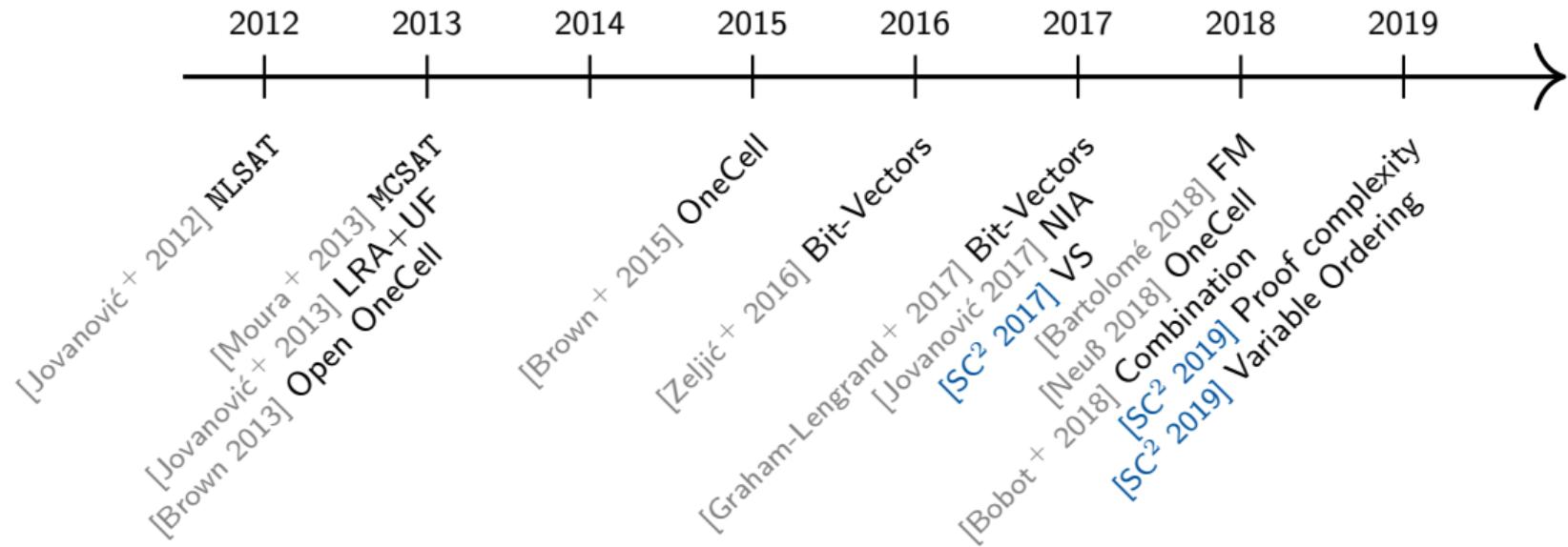
MCSAT history



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Theory decisions

Regular assignment finder

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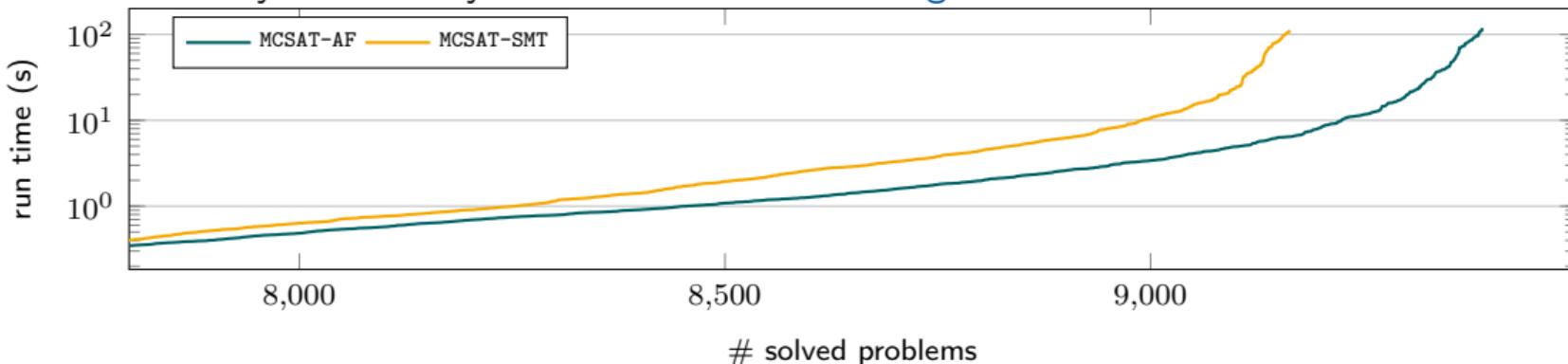
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[SC² 2019]

- Two similar proof systems: CDCL*(T) and MCSAT
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- Algorithmic equivalence: polynomial simulation of another method
- CDCL*(T) and MCSAT simulate each other*
- The proofs are logically equivalent

*: terms and conditions apply