

Techniques for NRA

How to solve Nonlinear Real Arithmetic

and a lot of references







Contains mostly other peoples work! Contains joint work with: Erika Ábrahám, Florian Corzilius, James Davenport, Matthew England, Rebecca Haehn, Jasper Nalbach



Satisfiability modulo theories

Let's skip that...



Here: Theory of the Reals



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Nonlinear Real Arithmetic:

- ightharpoonup real variables $v := x_i \in \mathbb{R}$
- $\blacktriangleright \ \ \text{constants} \ c := q \in \mathbb{Z}$
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Linear arithmetic: essentially a solved problem. Use Simplex (or sometimes Fourier-Motzkin)



Theory of the Reals in a nutshell

- complete (we have decision procedures that are sound and complete)
- admits quantifier elimination (quantifiers are conceptually easy)



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Some methods:

- ► [Tarski 1951] Tarski: first complete method, non-elementary complexity
- ► [Buchberger 1965] Gröbner bases: limited applicability, standard tool in CA
- ► [Collins 1974] CAD: complete, doubly exponential complexity
- ► [Weispfenning 1988] VS: up to bounded degree, singly exponential complexity
- ► [Gao et al. 2013] ICP: heuristic interval reasoning, incomplete
- ► [Fontaine et al. 2017] Subtropical satisfiability: incomplete reduction to LRA
- ► [Irfan 2018] Linearization: incomplete, axiom instantiation
- ► [Ábrahám et al. 2020] CDCAC: conflict-driven CAD
- and some more...



Overview

- SMT for NRA
- 2 Linearization
- 3 Interval Constraint Propagation
- 4 Subtropical Satisfiability
- **6** Gröbner Bases
- **6** Virtual Substitution
- 7 Cylindrical Algebraic Decomposition
- **8** Conflict-Driven Cylindrical Algebraic Coverings
- Related topics



Linearization by example

[Irfan 2018] [Cimatti et al. 2018]

- Linearize atoms
- Solve
- Identify conflicts
- ► Instantiate axioms
- Add as lemmas
- Repeat



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$$x \cdot y \leq 0 \land x < 0 \land x + y = 0$$
 linearize: $z \leq 0 \land x < 0 \land x + y = 0$ $z := x \cdot y$ atoms: $z \leq 0 \land x < 0 \land x + y = 0$ solve: $x \mapsto -1, y \mapsto 1, z \mapsto 0$ conflict: $0 \neq -1 \cdot 1$ axiom: $z = 0 \Rightarrow (x = 0 \lor y = 0)$

add axiom as lemma, proceed to next theory call

atoms:
$$z \le 0 \land x < 0 \land x + y = 0 \land z \ne 0$$

solve: $x \mapsto -1, y \mapsto 1, z \mapsto -1$
SAT!



[Irfan 2018] [Cimatti et al. 2018]

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More axioms: zeroes, monotonicity, commutativity, symmetry w.r.t. signs, tangent planes, . . .



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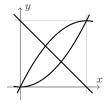
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Extensions:

- Repair model (if easily possible)
- ► Transcendental functions
- extended operators in general

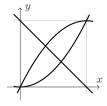




$$y > x^2 \wedge y < -x^2 + 2x \wedge y \le 1 - x$$

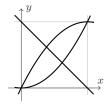
 $x \times y$





$$\begin{aligned} y > x^2 & \wedge & y < -x^2 + 2x & \wedge & y \le 1 - x \\ y > x^2 \Rightarrow y \in (0, \infty) & (-\infty, \infty) \times (0, \infty) \end{aligned}$$





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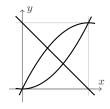
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$$(-\infty, \infty) \times (0, \infty)$$

$$x > 0.5x^{2} + y \Rightarrow x \in (0, \infty)$$

$$(0, \infty) \times (0, \infty)$$





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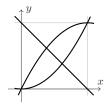
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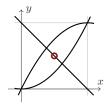
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$$\begin{array}{lll} y>x^2 & \wedge & y<-x^2+2x & \wedge & y\leq 1-x & x\times y \\ y>x^2\Rightarrow y\in (0,\infty) & (-\infty,\infty)\times (0,\infty) \\ x>0.5x^2+y\Rightarrow x\in (0,\infty) & (0,\infty)\times (0,\infty) \\ x\leq -y+1\Rightarrow x\in (0,1) & (0,1)\times (0,\infty) \\ y\leq -x+1\Rightarrow y\in (0,1) & (0,1)\times (0,1) \end{array}$$



Interval Constraint Propagation in a nutshell

[Benhamou et al. 2006] [Gao et al. 2013] [Scheibler et al. 2013] [Schupp 2013] [Tung et al. 2017]

Core idea:

- Maintain interval assignment (that represents the current box)
- Perform over-approximating contractions until
 - ► the current box is empty (UNSAT),
 - ► we can guess a model (SAT), or
 - we reach a threshold.
- When reaching a threshold
 - we terminate with unknown or
 - ▶ split: $x \in [0,5] \rightsquigarrow (x < 3 \lor x \ge 3)$



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 - ▶ split: $x \in [0, 5] \rightsquigarrow (x < 3 \lor x \ge 3)$
- Incomplete solving procedure
- Used as preprocessor for other techniques [Loup et al. 2013]
- ▶ Delicate tuning of heuristics (splitting, thresholds, model guessing)



[Fontaine et al. 2017] [Fontaine et al. 2018]

Core idea: reduce p=0 to a linear problem in the exponents of p

- Assume p(1, ..., 1) < 0 (otherwise consider -p)
- ▶ Find $x \in \mathbb{R}^n_+$ such that p(x) > 0
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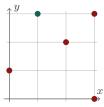
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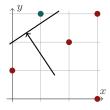
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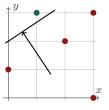
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Find hyperplane that separates a positive node Encoding in QF_LRA

Growing degree only impacts coefficient size





Gröbner basis

[Buchberger 1965] [Junges 2012]

- Canonical generators for a polynomial ideal
- For us: Normal form for sets of polynomials
- ► Maintains set of common complex roots
- ► The workhorse of computer algebra for polynomial equalities
- ► Mature implementations (every CAS)
- ▶ Doubly exponential in worst case, but usually much faster.



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Relevant for SMT: $\exists x \in \mathbb{C}^n.p(x) = 0$

But: What about inequalities? How to go from $\mathbb C$ to $\mathbb R$? see [Junges 2012] for some approaches.



Virtual Substitution

[Weispfenning 1988] [Weispfenning 1997] [Košta et al. 2015] [Košta 2016] [Nalbach 2017]

Core idea:

- lackbox Use solution formula to solve polynomial equation for x
- ► Substitute value for *x* into remaining equations
- Repeat for remaining variables



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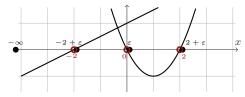
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What about inequalities?

- lacktriangle Construct test candidates for all sign-invariant regions in x
- Always try the roots and the smallest values of the intermediate intervals



Introduces special terms $t + \varepsilon$ and $-\infty$



Virtual Substitution

Algorithmic core: a collection of substitution rules Example: Substitute $e+\varepsilon$ for x into $a\cdot x^2+b\cdot x+c>0$:



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Algorithmic core: a collection of substitution rules Example: Substitute $e + \varepsilon$ for x into $a \cdot x^2 + b \cdot x + c > 0$:

Not always applicable:

- Solution formulas only exist up to degree four
- ► The above rule may introduce a degree growth
- Efficient if applicable
- ► [Košta et al. 2015] uses FO formulas, allows arbitrary but fixed degrees (needs precomputed substitution rules obtained by quantifier elimination)



The core idea: sign-invariance (or rather truth-table equivalence)

$$sgn(p(a)) = sgn(p(b)) \ \forall p \in \varphi \quad \Rightarrow \quad \varphi(a) = \varphi(b)$$

For our purpose, a and b are equivalent!



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Abstraction: \mathbb{R}^n to finite set of cells, consider a single $a \in C$ per cell.



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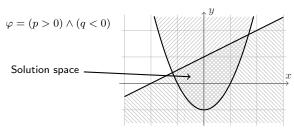
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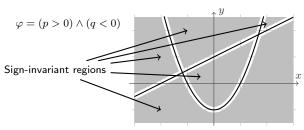
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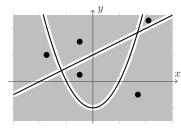
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$$\varphi = (p > 0) \land (q < 0)$$

Sample points





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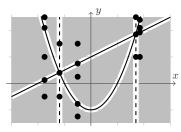
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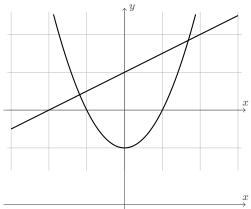
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Actual sample points

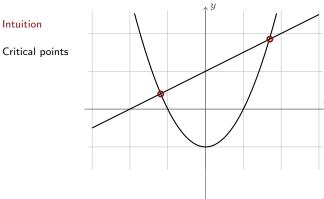
Arranged in cylinders



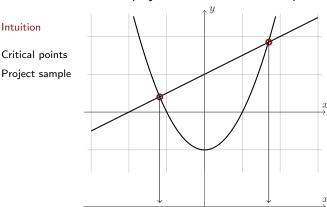




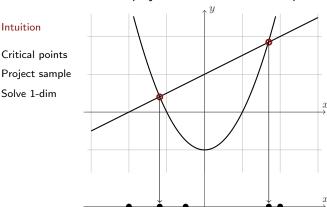




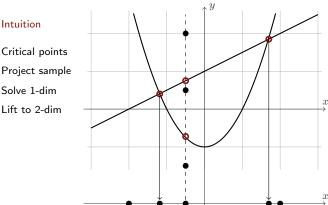






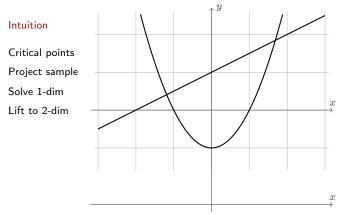






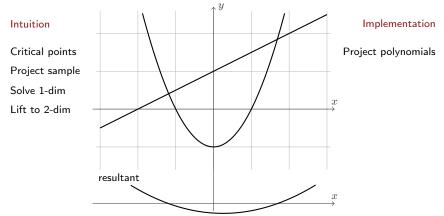


Proceed dimension-wise: project to lower-dimensional problem, lift results.

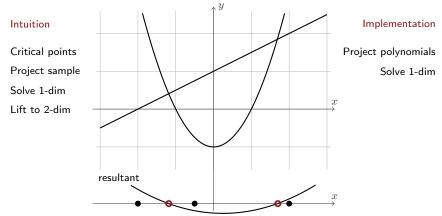


Implementation



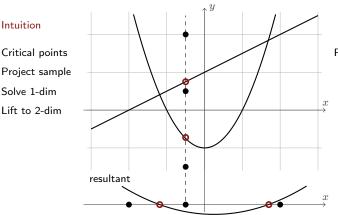








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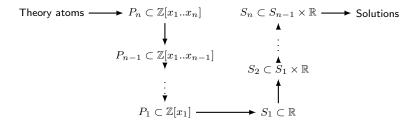
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Project polynomials

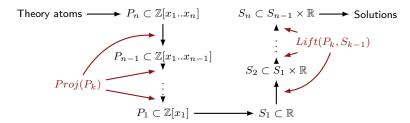
Solve 1-dim

Lift to 2-dim

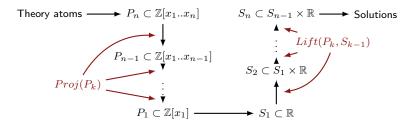












Projection:

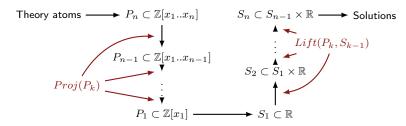
- ► Intersections (resultants)
- ► Flipping points (discriminants)
- ► Singularities (coefficients)









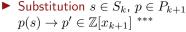


Projection:

- ► Intersections (resultants)
- ► Flipping points (discriminants)
- ► Singularities (coefficients)













Final notes on CAD

- Asymptotic complexity: $(n \cdot m)^{2^r}$ (r variables, m polynomials of degree n)
- Oftentimes way faster, but worst-case occurs in practice!
- Best complete method that is known and implemented. [Hong 1991]
- Active research:
 - Projection [McCallum 1984] [McCallum 1988] [Hong 1990] [Lazard 1994] [Brown 2001] [McCallum 2001] [McCallum et al. 2016] [McCallum et al. 2019]; [Strzeboński 2000] [Seidl et al. 2003] [Jovanović et al. 2012] [Brown 2013] [Strzeboński 2014] [Brown et al. 2015]
 - ► Lifting [Collins 1974] [Lazard 1994] [McCallum et al. 2016] [McCallum et al. 2019]
 - ► Equational constraints [Collins 1998] [McCallum 1999] [McCallum 2001] [England et al. 2015] [Haehn et al. 2018] [Nair et al. 2019]
 - Variable ordering [England et al. 2014] [Huang et al. 2014] [Nalbach et al. 2019] [Florescu et al. 2019]
 - Adaptions [Jovanović et al. 2012] [Brown 2013] [Brown 2015] [Ábrahám et al. 2020]
- ► Implementation needs groundwork: polynomial computation (resultants, multivariate gcd, optionally multivariate factorization), real algebraic numbers (representation, multivariate root isolation)



Conflict-Driven Cylindrical Algebraic Coverings

[Ábrahám et al. 2020]

Core idea: use CAD techniques in a conflict-driven way.

My intuition: MCSAT turned into a theory solver.



Conflict-Driven Cylindrical Algebraic Coverings

[Ábrahám et al. 2020]

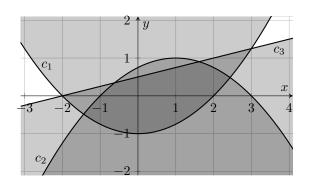
Core idea: use CAD techniques in a conflict-driven way.

My intuition: MCSAT turned into a theory solver.

- ► Fix a variable ordering
- For the kth variable
 - ► Use constraints to exclude unsatisfiable intervals
 - ightharpoonup Guess a value for the kth variable
 - ightharpoonup Recurse to k+1st variable and obtain
 - ► a full variable assignment (→ return SAT)
 - ightharpoonup or a covering for the k+1st variable
 - ► Use CAD machinery to infer an interval for the kth variable
- ▶ Until the collected intervals form a covering for the kth variable



$$c_1: 4 \cdot y < x^2 - 4$$
 $c_2: 4 \cdot y > 4 - (x - 1)^2$ $c_3: 4 \cdot y > x + 2$



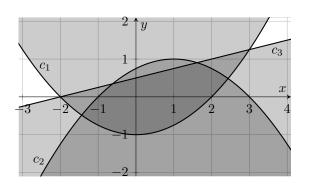


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$$c_3: 4 \cdot y > x + 2$$

No constraint for x

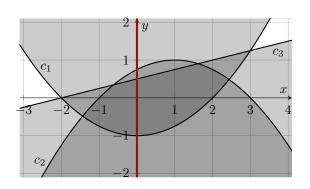




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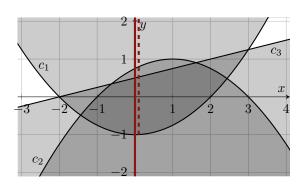
No constraint for xGuess $x \mapsto 0$



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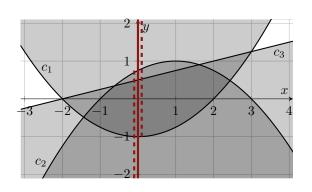
No constraint for xGuess $x \mapsto 0$ $c_1 \to y \notin (-1, \infty)$



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No constraint for xGuess $x \mapsto 0$ $c_1 \to y \notin (-1, \infty)$ $c_2 \rightarrow y \notin (-\infty, 0.75)$ $c_1: 4 \cdot y < x^2 - 4$ $c_2: 4 \cdot y > 4 - (x - 1)^2$ $c_3: 4 \cdot y > x + 2$



An example

No constraint for
$$x$$

Guess $x \mapsto 0$
 $c_1 \to y \notin (-1, \infty)$
 $c_2 \to y \notin (-\infty, 0.75)$
 $c_3 \to y \notin (-\infty, 0.5)$

 $c_1: 4 \cdot y < x^2 - 4$ $c_2: 4 \cdot y > 4 - (x - 1)^2$ $c_3: 4 \cdot y > x + 2$



An example

No constraint for
$$x$$
 Guess $x \mapsto 0$ $c_1 \to y \not\in (-1, \infty)$ $c_2 \to y \not\in (-\infty, 0.75)$ $c_3 \to y \not\in (-\infty, 0.5)$ Construct covering $(-\infty, 0.5), (-1, \infty)$



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The main algorithm

```
function get_unsat_cover((s_1, \ldots, s_{i-1}))
I := get_unsat_intervals(s)
while \bigcup_{I \subset \mathbb{T}} I \neq \mathbb{R} do
  s_i := \mathtt{sample\_outside}(\mathbb{I})
  if i = n then return (SAT, (s_1, \ldots, s_{i-1}, s_i))
  (f, O) := \mathtt{get\_unsat\_cover}((s_1, \ldots, s_{i-1}, s_i))
  if f = SAT then return (SAT, O)
  else if f = \text{UNSAT} then
    R := \text{construct\_characterization}((s_1, \dots, s_{i-1}, s_i), O)
    J := interval\_from\_characterization((s_1, ..., s_{i-1}), s_i, R)
    \mathbb{I} := \mathbb{I} \cup \{J\}
  end
end
return (UNSAT, I)
```



```
function get_unsat_cover((s_1, \ldots, s_{i-1}))
                                                                 Real root isolation over a
I := get_unsat_intervals(s)
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                                                                  Select sample from \mathbb{R} \setminus \mathbb{I}
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                                                               CAD-style projection:
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                                                               still applicable
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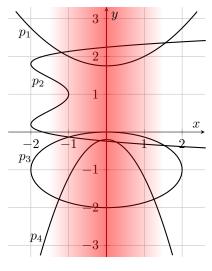
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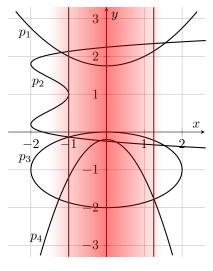
construct_characterization



Identify region around sample



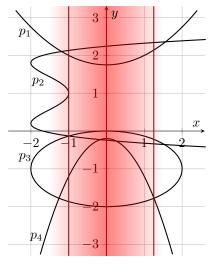
construct_characterization



Identify region around sample



${\tt construct_characterization}$



Identify region around sample CAD projection:

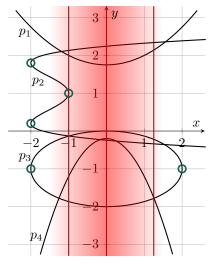
Resultants

Discriminants (and coefficients)

Gereon Kremer | Stanford University | October 22, 2020



${\tt construct_characterization}$



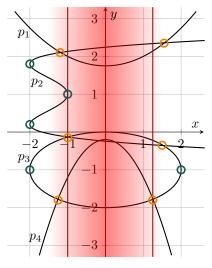
Identify region around sample CAD projection:

Discriminants (and coefficients)

Resultants



${\tt construct_characterization}$



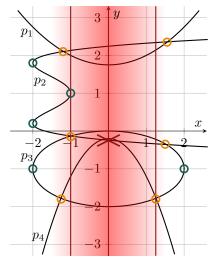
Identify region around sample CAD projection:

Discriminants (and coefficients)

Resultants



construct_characterization



Identify region around sample CAD projection:

Discriminants (and coefficients)
Resultants

Improvement over CAD:

Resultants between neighbouring intervals only!



Other methods for (QF_)NRA

- Numerical methods [Kremer 2013]: focus on good approximation, but no formal guarantees
- ► Tarski's method [Tarski 1951]: theoretical breakthrough only, non-elementary complexity
- ▶ Grigor'ev and Vorobjov [Grigor'ev et al. 1988], Renegar [Renegar 1988]: singly exponentional, but impractical (see [Hong 1991])
- ▶ Basu, Pollack and Roy [Basu et al. 1996]: "realizable sign conditions", has not been implemented (yet)
- ► Other CAD-based methods: Regular Chains [Chen et al. 2009], NuCAD [Brown 2015]



Beyond QF_NRA

- Quantifiers:
 - ► Theory of the Reals admits quantifier elimination
 - ► CAD constructs φ' for $Q_x \varphi(x, y) \Leftrightarrow \varphi'(y)$
- ► Theory combination with Array, BV, FP, String, ... [Nelson et al. 1979]
- ► Transcendentals: extend linearization [Cimatti et al. 2018] [Irfan 2018]
- ► Optimization: CAD can optimize for an objective [Kremer 2020]
- ▶ Integers: Branch&Bound complements BitBlasting [Kremer et al. 2016]



Beyond CDCL(T)-style SMT

Other approaches for (QF_)NRA:

- ► MCSAT / NLSAT:
 - Theory model construction integrated in the core solver
 - ► SMT-RAT, yices, z3 [Jovanović et al. 2012] [Jovanović et al. 2013] [Moura et al. 2013] [Nalbach et al. 2019] [Kremer 2020]
- ► CAD is a stand-alone tool:
 - ► Maple / RegularChains [Chen et al. 2009]
 - ► Mathematica [Strzeboński 2014]
 - ► QEPCAD B [Brown 2003]
 - ► Redlog / Reduce [Dolzmann et al. 1997]

These can be integrated as theory solvers [Fontaine et al. 2018] [Kremer 2018]



in CVC4

- ► Linearization (--nl-ext)
- ► CDCAC (--nl-cad)
- ► Also: ICP-style propagations (--nl-icp)



in CVC4

- Linearization (--nl-ext)
- ► CDCAC (--nl-cad)
- ► Also: ICP-style propagations (--nl-icp)

in progress / future work:

- Better integration of Linearization, CDCAC and ICP
- Preprocessing for nonlinear arithmetic
- Add proofs
- ► Improve incrementality (in particular CDCAC)
- ► Improvements within CDCAC (heuristics, factorization, ...)



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