
```
function [ j] = getRevJ( z,on,o )
%Nathaniel Goldfarb 2/16/14
%getRevJ returns the Jacobian of a revolute joint
%inputs:
%z: 1X3 matrix
%on: last joint 'o' 1x3 matrix
%o: current 'o' joint 1x3 matrix
```

```
a= cross(z,(on-o));
j= [a;z];
```

```
end
```

Not enough input arguments.

Error in getRevJ (line 9)
a= cross(z,(on-o));

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