

# **Real-time task models in Linux**

**Assignment 1: Report**

*Submitted for the Subject:*  
**Real Time Embedded Systems**  
**CSE522**

*By:*  
**Nagarjun chinnari (1213287788)**  
**Nisarg Trivedi (1213314867)**

*Under the guidance of:*  
**Prof. Yann-Hang Lee**



**Arizona State University**  
**Tempe Campus, AZ**  
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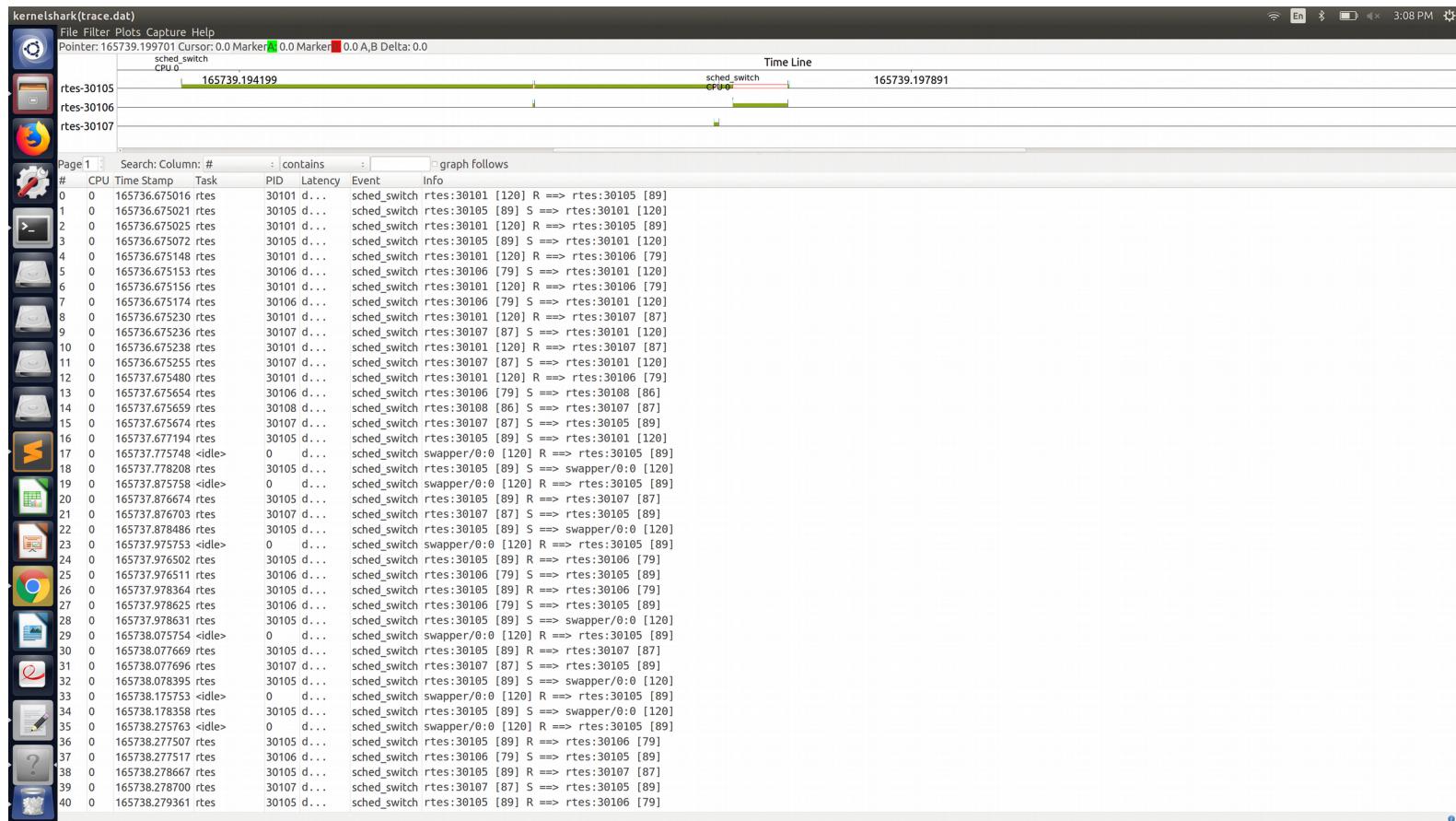
Thank You.

### Priority inversion:

It is a peculiar scheduling scenario where a high priority tasks is denied execution opportunity because of synchronization lock acquisition by a thread running at a low priority.

Imagine a case when a thread with priority higher than the low priority thread but lower than the high priority thread becomes ready for execution. Here, if this middle thread is not trying to acquire the same mutex, it can easily preempting the low priority thread and further delaying the execution of high priority thread by execution time of the middle thread.

This situation is termed as 'Priority Inversion' and it can delay execution of a high priority thread indefinitely. The same can be seen below



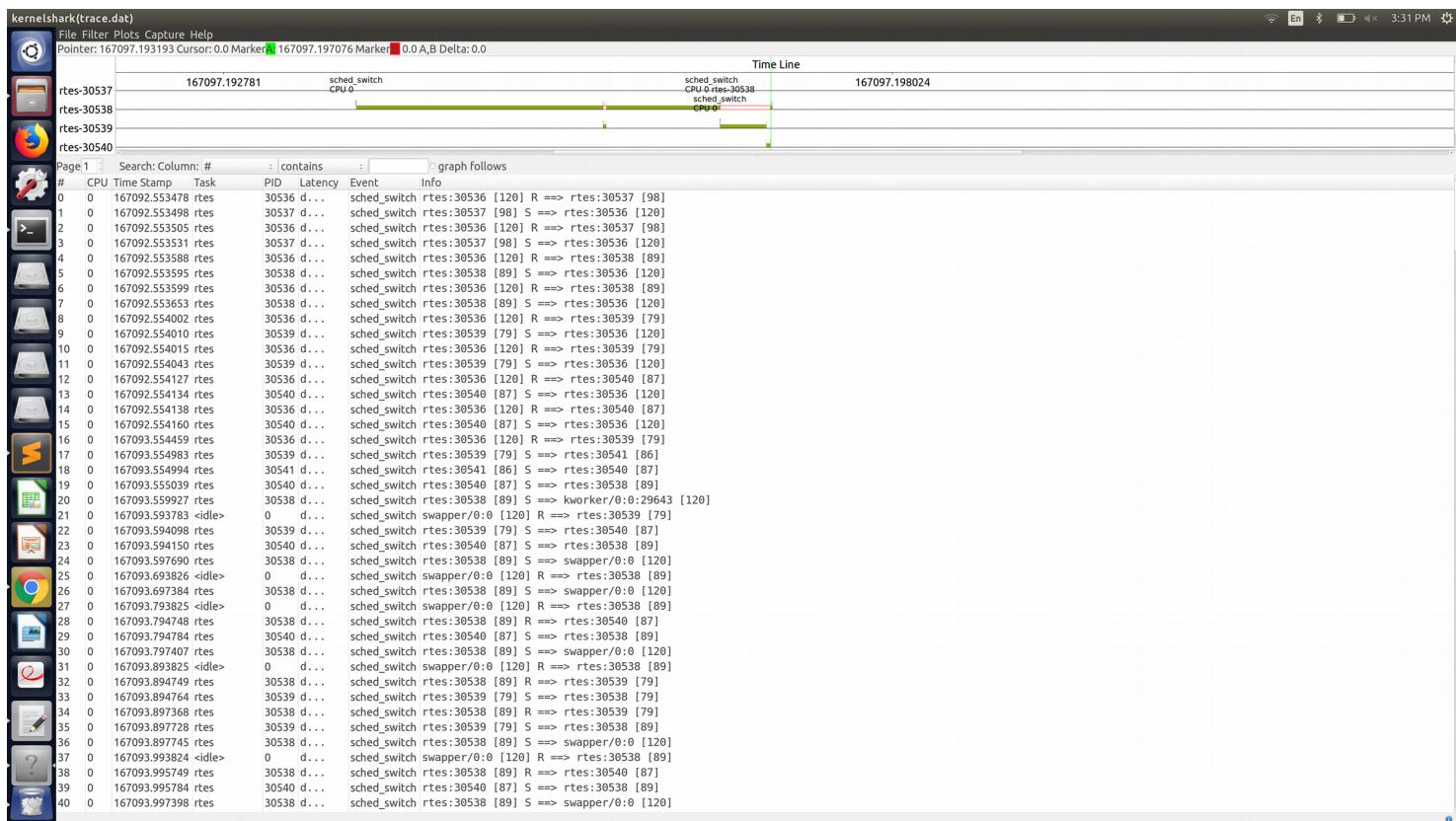
ID 30105: Lowest priority thread

ID 30106: Highest priority thread

ID 30107: Medium priority thread

the above shown image is a kernelshark screen shot from host and shows the priority inversion where the high priority thread is locked out because low priority thread executes and then medium priority executes and then high priority executes.the same can also be inferred from pi\_disabled.txt which was collected from galileo board using Ftracecmd.

## Priority Inheritance:



ID 30538 Low priority thread

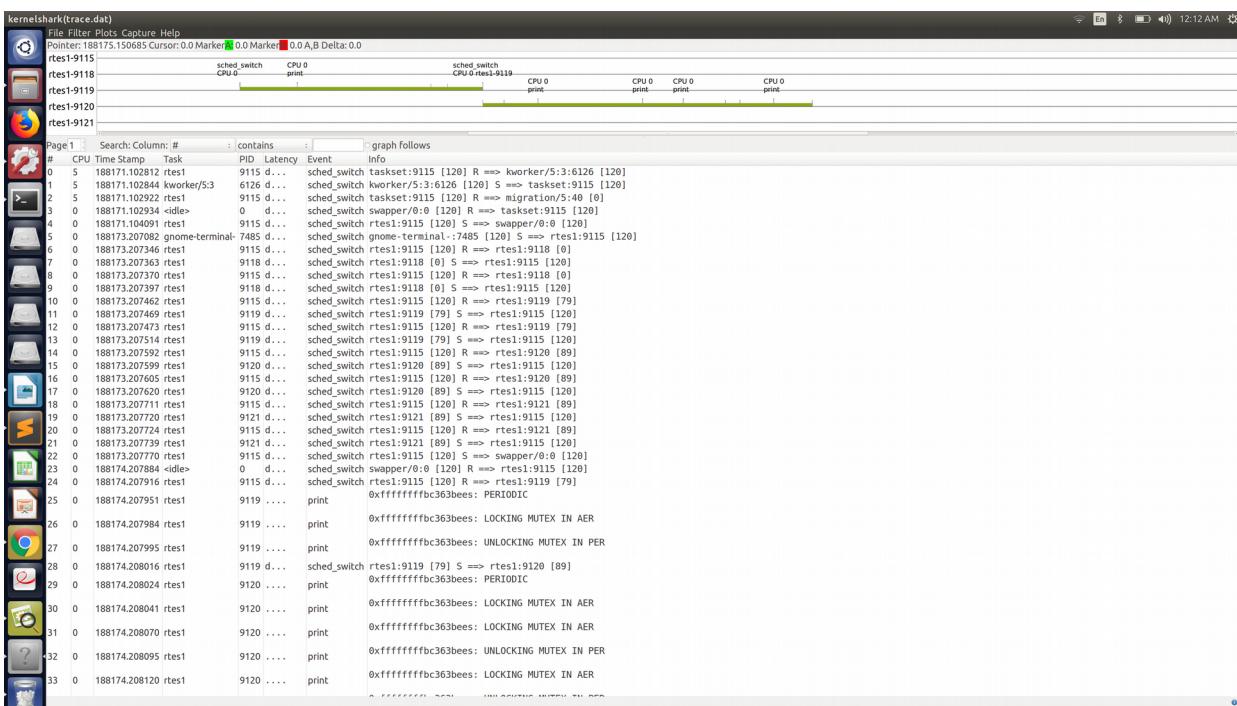
ID 30539: High priority thread

ID 30540: Middle priority thread

As we can see from the figure, low priority thread is running in critical section by acquiring a PI enabled mutex. High priority thread arrives by preempting low priority thread. As soon as it tries to acquire the mutex, it gets blocked and control is momentarily given to middle thread which is preempted by the then low priority thread because it now has the priority of the high priority thread.

Now, low priority thread finishes execution first, then transfers control to high priority thread when it releases the mutex; and only when high priority thread finishes execution, only then the middle and other threads will get a chance to execute. The same can be inferred from text file pi\_enabled.txt which was collected from galileo board using Ftracecmd.

## FIFO SCHEDULING:



In the above image thread with thread id 9119 has a high priority and thread with thread id 9120 has low priority as they are scheduled as FIFO the higher priority thread is runned first and then lower priority runs.

