view_frames Result Recorded at time: 498.295 odom Broadcaster: /gazebo Average rate: 10.208 Hz Most recent transform: 498.202 (0.093 sec old) Buffer length: 4.800 sec robot_footprint Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (498.295 sec old) Buffer length: 0.000 sec chassis Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10.206 Hz Average rate: 10.206 Hz Most recent transform: 0.000 (498.295 sec old) Most recent transform: 0.000 (498.295 sec old) Most recent transform: 498.201 (0.094 sec old) Most recent transform: 498.201 (0.094 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.801 sec Buffer length: 4.801 sec hokuyo left_wheel right_wheel camera