

Fourier transform on the real line

The treatment is based on analogies: recall the discrete and the periodic models.

The function space

The signal: $x : \mathbb{R} \rightarrow \mathbb{C}$

Proper function space: $L^1(\mathbb{R})$, $L^2(\mathbb{R})$, etc. (Lebesgue–integral).

Instead: a more simple mathematical model.

We assume (improper Riemann–integral)

$$\exists \int_{-\infty}^{\infty} |x(u)|^k du = \lim_{t \rightarrow \infty} \int_{-t}^t |x(u)|^k du < \infty,$$

where $k = 1$ or 2 . Notation: $x \in R^k(-\infty, +\infty)$.

The trigonometric system

$$e_{\lambda}(t) = e^{2\pi i \lambda t} \quad (\lambda \in \mathbb{R}).$$

Fourier transform

$$\widehat{x} : \mathbb{R} \rightarrow \mathbb{C}, \quad x \in R^1(-\infty, +\infty), \quad \widehat{x}(\lambda) = \int_{-\infty}^{\infty} x(t) e^{-i2\pi\lambda t} dt.$$

The spectrum is "continuous".

Inversion

The Fourier transform is invertible.

Inversion formula: If $x, \widehat{x} \in R(-\infty, \infty)$, then

$$x(t) = \int_{-\infty}^{\infty} \widehat{x}(\lambda) e^{i2\pi\lambda t} d\lambda.$$

Remark: The inversion formula holds in the case if $x \in R^1(-\infty, \infty)$ piecewise (finite many pieces) continuously differentiable and $x' \in R^1(-\infty, \infty)$.

Examples

1. $x(t) = e^{-a|t|}, \quad \widehat{x}(\lambda) = \frac{2a}{a^2 + 4\pi^2\lambda^2};$

2. $x(t) = \begin{cases} e^{-at} & , t > 0 \\ 0 & , t < 0 \end{cases}, \quad \widehat{x}(\lambda) = \frac{1}{a + 2i\pi\lambda};$

3. $\text{rect } t := \chi_{[-0.5, 0.5]}, \quad \text{sinc } \lambda := \begin{cases} \frac{\sin \pi\lambda}{\pi\lambda} & , \lambda \neq 0 \\ 1 & , \lambda = 0 \end{cases}$

$$x(t) = \text{rect } t, \quad \widehat{x}(\lambda) = \text{sinc } \lambda;$$

Note that $\text{sinc} \notin R^1(-\infty, \infty)$.

4. $x(t) = e^{-\pi t^2}, \quad \widehat{x}(\lambda) = e^{-\pi \lambda^2}.$

The Gauss–function is eigenfunction of the Fourier transform.

Remark: The inversion formula can be generalized: $\widehat{\widehat{\text{sinc}}} = \text{rect}$.

Properties

1. Translation: $y(t) = x(t - \tau)$ $\hat{y}(u) = e^{-2\pi i \tau} \hat{x}(u)$.

2. Modulation: $y(t) = e^{2\pi i \lambda} x(t)$ $\hat{y}(u) = \hat{x}(u - \lambda)$.

These are similar to the discrete and the periodic cases.

3. Dilation: $y(t) = x(at)$ $\hat{y}(u) = \frac{1}{|a|} \hat{x}\left(\frac{u}{a}\right)$.

This is new. "Uncertainty relations"

4. Convolution: $z(t) = (x * y)(t)$ $\hat{z}(u) = \hat{x}(u) \hat{y}(u)$.

5. Multiplication: $z(t) = x(t)y(t)$ $\hat{z}(u) = (\hat{x} * \hat{y})(u)$.

In both cases convolution on the real line:

$$(x * y)(t) = \int_{-\infty}^{\infty} x(t - u) y(u) du.$$