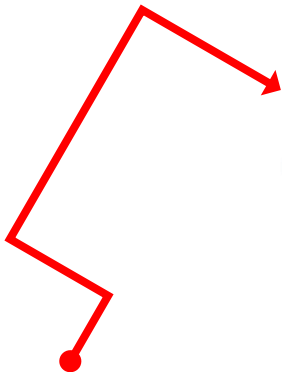
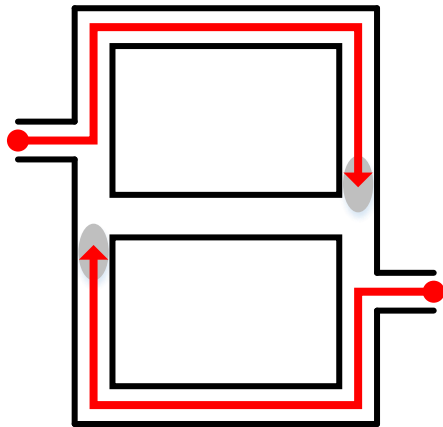


**Floor map**

+



**Trajectory**



 **:Possible location**