

---

# **Neoliberalism and local consistency**

**Tomáš Nagy**

**Jagiellonian University**

**joint work with Michael Pinsker**

---

**AAA 105, Prague, 1st June 2024**

Views and opinions expressed do not reflect necessarily those of the author or of any other human being, dead or alive – in particular not of the co-author.

No individual or organisation can be held responsible for them.

# Infinite structures

$\mathbb{B}$  homogeneous if every orbit under  $\text{Aut}(\mathbb{B})$  determined by relations

**Example:**  $(\mathbb{Q}; <, =)$ :  $O = \{(a, b, c, d) \in \mathbb{Q}^4 \mid a < d, d < b, b = c\}$

# Infinite structures

$\mathbb{B}$  *homogeneous* if every orbit under  $\text{Aut}(\mathbb{B})$  determined by relations

**Example:**  $(\mathbb{Q}; <, =)$ :  $O = \{(a, b, c, d) \in \mathbb{Q}^4 \mid a < d, d < b, b = c\}$

$\mathbb{B}$  *finitely bounded* if every description works

unless one of finitely many conditions (bounds) is satisfied

# Infinite structures

$\mathbb{B}$  *homogeneous* if every orbit under  $\text{Aut}(\mathbb{B})$  determined by relations

**Example:**  $(\mathbb{Q}; <, =)$ :  $O = \{(a, b, c, d) \in \mathbb{Q}^4 \mid a < d, d < b, b = c\}$

$\mathbb{B}$  *finitely bounded* if every description works

unless one of finitely many conditions (bounds) is satisfied

"No surprises in the eternity."  $\Rightarrow$  seems to be what we desire

# Infinite structures

$\mathbb{B}$  *homogeneous* if every orbit under  $\text{Aut}(\mathbb{B})$  determined by relations

**Example:**  $(\mathbb{Q}; <, =)$ :  $O = \{(a, b, c, d) \in \mathbb{Q}^4 \mid a < d, d < b, b = c\}$

$\mathbb{B}$  *finitely bounded* if every description works

unless one of finitely many conditions (bounds) is satisfied

"No surprises in the eternity."  $\Rightarrow$  seems to be what we desire

**Example:**  $(\mathbb{Q}; <)$ :  $<$  irreflexive (forbids  $x < x$ ), transitive (forbids  $x < y < z$  without relations between  $x, z$  or with  $x = z$ ), total (forbids  $x, y$  without relations)

# Infinite structures

$\mathbb{B}$  homogeneous if every orbit under  $\text{Aut}(\mathbb{B})$  determined by relations

**Example:**  $(\mathbb{Q}; <, =)$ :  $O = \{(a, b, c, d) \in \mathbb{Q}^4 \mid a < d, d < b, b = c\}$

$\mathbb{B}$  finitely bounded if every description works

unless one of finitely many conditions (bounds) is satisfied

"No surprises in the eternity."  $\Rightarrow$  seems to be what we desire

**Example:**  $(\mathbb{Q}; <)$ :  $<$  irreflexive (forbids  $x < x$ ), transitive (forbids  $x < y < z$  without relations between  $x, z$  or with  $x = z$ ), total (forbids  $x, y$  without relations)

$\mathbb{B}$  has finite duality if every incomplete description gives union of orbits unless one of finitely many conditions (homomorphic bounds) satisfied

# Infinite structures

$\mathbb{B}$  homogeneous if every orbit under  $\text{Aut}(\mathbb{B})$  determined by relations

**Example:**  $(\mathbb{Q}; <, =)$ :  $O = \{(a, b, c, d) \in \mathbb{Q}^4 \mid a < d, d < b, b = c\}$

$\mathbb{B}$  finitely bounded if every description works

unless one of finitely many conditions (bounds) is satisfied

"No surprises in the eternity."  $\Rightarrow$  seems to be what we desire

**Example:**  $(\mathbb{Q}; <)$ :  $<$  irreflexive (forbids  $x < x$ ), transitive (forbids  $x < y < z$  without relations between  $x, z$  or with  $x = z$ ), total (forbids  $x, y$  without relations)

$\mathbb{B}$  has finite duality if every incomplete description gives union of orbits unless one of finitely many conditions (homomorphic bounds) satisfied

"No surprises in the eternity even without full self-knowledge."

$\Rightarrow$  what we actually desire

# Infinite structures

$\mathbb{B}$  homogeneous if every orbit under  $\text{Aut}(\mathbb{B})$  determined by relations

**Example:**  $(\mathbb{Q}; <, =)$ :  $O = \{(a, b, c, d) \in \mathbb{Q}^4 \mid a < d, d < b, b = c\}$

$\mathbb{B}$  finitely bounded if every description works

unless one of finitely many conditions (bounds) is satisfied

"No surprises in the eternity."  $\Rightarrow$  seems to be what we desire

**Example:**  $(\mathbb{Q}; <)$ :  $<$  irreflexive (forbids  $x < x$ ), transitive (forbids  $x < y < z$  without relations between  $x, z$  or with  $x = z$ ), total (forbids  $x, y$  without relations)

$\mathbb{B}$  has finite duality if every incomplete description gives union of orbits unless one of finitely many conditions (homomorphic bounds) satisfied

"No surprises in the eternity even without full self-knowledge."

$\Rightarrow$  what we actually desire

**Example:**  $(\mathbb{Q}; <)$  does NOT have finite duality:

all cycles forbidden  $x_1 < x_2 < \dots < x_n < x_1$ .

the universal homogeneous triangle-free graph has finite duality

# Infinite-domain CSPs

$\mathbb{B}$  - finitely bounded, homogeneous

$\mathbb{A}$  - first-order definable in  $\mathbb{B}$

CSP( $\mathbb{A}$ ):

**Input:**  $\Phi = \phi_1 \wedge \dots \wedge \phi_k$  - conjunction of atomic formulas over the signature of  $\mathbb{A}$

**Question:**  $\Phi$  satisfiable?

$\mathbb{B}$  - finitely bounded, homogeneous

$\mathbb{A}$  - first-order definable in  $\mathbb{B}$

CSP( $\mathbb{A}$ ):

**Input:**  $\Phi = \phi_1 \wedge \dots \wedge \phi_k$  - conjunction of atomic formulas over the signature of  $\mathbb{A}$

**Question:**  $\Phi$  satisfiable?

Finite formulation:

maxarity( $\mathbb{B}$ ) =  $k$ ,  $\tau$  - signature of  $\mathbb{B}$

**Given:**

- "values":  $O_1, \dots, O_m$  -  $k$ -orbits under  $\text{Aut}(\mathbb{B})$ ,
- "constraints": constraints given by  $\Phi$  (quantifier-free  $\tau$ -formulas) +  $\{F_1, \dots, F_n\}$  - finite forbidden  $\tau$ -structures (bounds)

**Want:** assign to every  $k$ -tuple of free variables of  $\Phi$  an orbit  $O_i$  s.t. no  $F_i$  embeds to the resulting structure and s.t.  $\Phi$  is satisfied

# Liberalism vs neoliberalism, 1/2

Ⓑ is *liberal* if its relations correspond to orbits of pairs  
and it does not have bounds of size 3 – 6  
*"If you are not free, you at least do not notice it."*

# Liberalism vs neoliberalism, 1/2

$\mathbb{B}$  is *liberal* if its relations correspond to orbits of pairs  
and it does not have bounds of size  $3 - 6$

*"If you are not free, you at least do not notice it."*

$k \geq 2$ ,  $\mathbb{B}$  is *k-neoliberal* if

- it is homogeneous and  
its relations correspond to orbits of  $k$ -tuples, and
  - $\rightsquigarrow$  every orbit determined by  $k$ -ary relations
  - *clear and concise regulations*

$\mathbb{B}$  is *liberal* if its relations correspond to orbits of pairs and it does not have bounds of size  $3 - 6$   
“*If you are not free, you at least do not notice it.*”

$k \geq 2$ ,  $\mathbb{B}$  is *k-neoliberal* if

- it is homogeneous and its relations correspond to orbits of  $k$ -tuples, and
  - $\rightsquigarrow$  every orbit determined by  $k$ -ary relations
  - *clear and concise regulations*
- it has only one orbit of injective  $(k - 1)$ -tuples, and
  - *free market – money can be transported between orbits by automorphisms without restrictions*

$\mathbb{B}$  is *liberal* if its relations correspond to orbits of pairs and it does not have bounds of size  $3 - 6$   
“If you are not free, you at least do not notice it.”

$k \geq 2$ ,  $\mathbb{B}$  is  $k$ -neoliberal if

- it is homogeneous and its relations correspond to orbits of  $k$ -tuples, and
  - $\rightsquigarrow$  every orbit determined by  $k$ -ary relations
  - *clear and concise regulations*
- it has only one orbit of injective  $(k - 1)$ -tuples, and
  - *free market – money can be transported between orbits by automorphisms without restrictions*
- for any injective orbit  $O$  of  $k$ -tuples, any injective  $(k - 1)$ -tuple can be extended to a tuple in  $O$  in at least two ways
  - *it is easy to divert money and avoid taxes*

# Liberalism vs neoliberalism, 1/2

$\mathbb{B}$  is *liberal* if its relations correspond to orbits of pairs and it does not have bounds of size  $3 - 6$   
“*If you are not free, you at least do not notice it.*”

$k \geq 2$ ,  $\mathbb{B}$  is *k-neoliberal* if

- it is homogeneous and its relations correspond to orbits of  $k$ -tuples, and
  - $\rightsquigarrow$  every orbit determined by  $k$ -ary relations
  - *clear and concise regulations*
- it has only one orbit of injective  $(k - 1)$ -tuples, and
  - *free market – money can be transported between orbits by automorphisms without restrictions*
- for any injective orbit  $O$  of  $k$ -tuples, any injective  $(k - 1)$ -tuple can be extended to a tuple in  $O$  in at least two ways
  - *it is easy to divert money and avoid taxes*

liberal  $\Rightarrow$  2-neoliberal

## Examples:

- $(\mathbb{Q}; <, =)$  is 2-neoliberal but not liberal
  - orbits determined by  $<, =$ ,
  - any  $a \in \mathbb{Q}$  can be moved by an automorphism to any other  $b \in \mathbb{Q}$   
 $\Rightarrow$  one orbit of elements,
  - for any  $a \in \mathbb{Q}$ , there exist  $b \neq c \in \mathbb{Q}$  with  $a < b, a < c$ ,
  - transitivity enforced by a bound of size 3  $\Rightarrow$  not liberal.

## Examples:

- $(\mathbb{Q}; <, =)$  is 2-neoliberal but not liberal
  - orbits determined by  $<, =$ ,
  - any  $a \in \mathbb{Q}$  can be moved by an automorphism to any other  $b \in \mathbb{Q}$   
 $\Rightarrow$  one orbit of elements,
  - for any  $a \in \mathbb{Q}$ , there exist  $b \neq c \in \mathbb{Q}$  with  $a < b, a < c$ ,
  - transitivity enforced by a bound of size 3  $\Rightarrow$  not liberal.
- graph  $G$  consisting of infinitely many isolated edges is NOT 2-neoliberal
  - for any  $a \in G$ , there is a unique  $b$  connected by an edge to  $a$ 
    - $\Rightarrow$  impossible to divert money

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$  – instance of  $\text{CSP}(\mathbb{A})$

**How to solve  $\text{CSP}(\mathbb{A})$ ?**

*Local consistency:* Derive information locally,  
constraints have to agree on small subsets of variables

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$  – instance of CSP( $\mathbb{A}$ )

**How to solve CSP( $\mathbb{A}$ )?**

*Local consistency:* Derive information locally,  
constraints have to agree on small subsets of variables

**“Example”:** Computing the transitive closure of a binary relation  $R$ .  
 $\phi_i : R(x, y), \phi_j : R(y, z) \Rightarrow$  add  $\phi := R(x, z)$  to  $\Phi$

~ looking on *triples*, deriving information about *pairs* of variables

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$  – instance of  $\text{CSP}(\mathbb{A})$

**How to solve  $\text{CSP}(\mathbb{A})$ ?**

*Local consistency:* Derive information locally,  
constraints have to agree on small subsets of variables

**“Example”:** Computing the transitive closure of a binary relation  $R$ .  
 $\phi_i : R(x, y), \phi_j : R(y, z) \Rightarrow$  add  $\phi := R(x, z)$  to  $\Phi$

~ looking on *triples*, deriving information about *pairs* of variables

$R^{\mathbb{A}}$  irreflexive, transitive and we derive  $R(x, x) \Rightarrow \Phi$  not satisfiable.

$\Rightarrow$  sometimes, local consistency *solves*  $\text{CSP}(\mathbb{A})$

## Local consistency, 2/4

$$1 \leq m \leq n$$

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$  – instance of  $\text{CSP}(\mathbb{A})$ , variable set  $\mathcal{V}$

*scope*  $S$  of  $\phi_i$ : all variables of  $\phi_i$

*projection* of  $\phi_i$  to  $X \subseteq S$ :  $\exists x_1 \dots x_\ell \phi_i$ , where  $S \setminus X = \{x_1, \dots, x_\ell\}$

## Local consistency, 2/4

$$1 \leq m \leq n$$

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$  – instance of  $\text{CSP}(\mathbb{A})$ , variable set  $\mathcal{V}$

*scope*  $S$  of  $\phi_i$ : all variables of  $\phi_i$

*projection* of  $\phi_i$  to  $X \subseteq S$ :  $\exists x_1 \dots x_\ell \phi_i$ , where  $S \setminus X = \{x_1, \dots, x_\ell\}$

$\Phi$   $(m, n)$ -minimal if

- for every set of  $\leq n$  variables from  $\mathcal{V}$ ,  
some  $\phi_i$  contains all these variables in its scope, and
- for every set  $V$  of  $\leq m$  variables from  $\mathcal{V}$  and for all  $\phi_i, \phi_j$   
containing all variables from  $V$  in their scopes,  
the projections to  $V$  agree.

## Local consistency, 2/4

$$1 \leq m \leq n$$

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$  – instance of CSP( $\mathbb{A}$ ), variable set  $\mathcal{V}$

*scope*  $S$  of  $\phi_i$ : all variables of  $\phi_i$

*projection* of  $\phi_i$  to  $X \subseteq S$ :  $\exists x_1 \dots x_\ell \phi_i$ , where  $S \setminus X = \{x_1, \dots, x_\ell\}$

$\Phi$   $(m, n)$ -minimal if

- for every set of  $\leq n$  variables from  $\mathcal{V}$ ,  
some  $\phi_i$  contains all these variables in its scope, and
- for every set  $V$  of  $\leq m$  variables from  $\mathcal{V}$  and for all  $\phi_i, \phi_j$   
containing all variables from  $V$  in their scopes,  
the projections to  $V$  agree.

↪ possible to compute an  $(m, n)$ -minimal “instance” from  $\Phi$   
effectively, we do not lose solutions

## Local consistency, 2/4

$$1 \leq m \leq n$$

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$  – instance of  $\text{CSP}(\mathbb{A})$ , variable set  $\mathcal{V}$

*scope*  $S$  of  $\phi_i$ : all variables of  $\phi_i$

*projection* of  $\phi_i$  to  $X \subseteq S$ :  $\exists x_1 \dots x_\ell \phi_i$ , where  $S \setminus X = \{x_1, \dots, x_\ell\}$

$\Phi$   $(m, n)$ -minimal if

- for every set of  $\leq n$  variables from  $\mathcal{V}$ ,  
some  $\phi_i$  contains all these variables in its scope, and
- for every set  $V$  of  $\leq m$  variables from  $\mathcal{V}$  and for all  $\phi_i, \phi_j$   
containing all variables from  $V$  in their scopes,  
the projections to  $V$  agree.

↪ possible to compute an  $(m, n)$ -minimal “instance” from  $\Phi$   
effectively, we do not lose solutions

$\Phi$  is *non-trivial* if every  $\phi_i$  satisfiable

## Local consistency, 2/4

$$1 \leq m \leq n$$

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$  – instance of  $\text{CSP}(\mathbb{A})$ , variable set  $\mathcal{V}$

scope  $S$  of  $\phi_i$ : all variables of  $\phi_i$

projection of  $\phi_i$  to  $X \subseteq S$ :  $\exists x_1 \dots x_\ell \phi_i$ , where  $S \setminus X = \{x_1, \dots, x_\ell\}$

$\Phi$   $(m, n)$ -minimal if

- for every set of  $\leq n$  variables from  $\mathcal{V}$ ,  
some  $\phi_i$  contains all these variables in its scope, and
- for every set  $V$  of  $\leq m$  variables from  $\mathcal{V}$  and for all  $\phi_i, \phi_j$   
containing all variables from  $V$  in their scopes,  
the projections to  $V$  agree.

~ possible to compute an  $(m, n)$ -minimal “instance” from  $\Phi$   
effectively, we do not lose solutions

$\Phi$  is non-trivial if every  $\phi_i$  satisfiable

$\mathbb{A}$  has (relational) width  $(m, n)$  if every non-trivial  
 $(m, n)$ -minimal instance satisfiable

~ local consistency solves  $\text{CSP}(\mathbb{A})$

## Examples:

- $(\mathbb{Q}; =, <)$  has width  $(2, 3)$ 
  - Idea: ensure that the transitive closure of  $<$  is irreflexive.
  - looking on *triples* of variables, comparing projections on *pairs*

## Examples:

- $(\mathbb{Q}; =, <)$  has width  $(2, 3)$ 
  - Idea: ensure that the transitive closure of  $<$  is irreflexive.
  - looking on *triples* of variables, comparing projections on *pairs*
- $(\{0, 1\}; \{x + y + z = 0\}, \{x + y + z = 1\})$   
does not have bounded width
  - linear equations cannot be solved by deriving local information

## Examples:

- $(\mathbb{Q}; =, <)$  has width  $(2, 3)$ 
  - Idea: ensure that the transitive closure of  $<$  is irreflexive.
  - looking on *triples* of variables, comparing projections on *pairs*
- $(\{0, 1\}; \{x + y + z = 0\}, \{x + y + z = 1\})$   
does not have bounded width
  - linear equations cannot be solved by deriving local information

Local consistency: only small, local and necessary changes,  
does not waste resources  $\Rightarrow$  *conservative*

## Examples:

- $(\mathbb{Q}; =, <)$  has width  $(2, 3)$ 
  - Idea: ensure that the transitive closure of  $<$  is irreflexive.
  - looking on *triples* of variables, comparing projections on *pairs*
- $(\{0, 1\}; \{x + y + z = 0\}, \{x + y + z = 1\})$   
does not have bounded width
  - linear equations cannot be solved by deriving local information

Local consistency: only small, local and necessary changes,  
does not waste resources  $\Rightarrow$  *conservative*

Linear equations: costly, ineffective (Gaussian elimination),  
constantly invents something new that never works out  
(more effective algorithms)  $\Rightarrow$  *socialist*

## Examples:

- $(\mathbb{Q}; =, <)$  has width (2, 3)
  - Idea: ensure that the transitive closure of  $<$  is irreflexive.
  - looking on *triples* of variables, comparing projections on *pairs*
- $(\{0, 1\}; \{x + y + z = 0\}, \{x + y + z = 1\})$   
does not have bounded width
  - linear equations cannot be solved by deriving local information

Local consistency: only small, local and necessary changes,  
does not waste resources  $\Rightarrow$  *conservative*

Linear equations: costly, ineffective (Gaussian elimination),  
constantly invents something new that never works out  
(more effective algorithms)  $\Rightarrow$  *socialist*

**Fun fact:** Finite-domain CSP solved by a combination  
of local consistency and linear equations (Bulatov, Zhuk, 2017)

## Examples:

- $(\mathbb{Q}; =, <)$  has width (2, 3)
  - Idea: ensure that the transitive closure of  $<$  is irreflexive.
  - looking on *triples* of variables, comparing projections on *pairs*
- $(\{0, 1\}; \{x + y + z = 0\}, \{x + y + z = 1\})$   
does not have bounded width
  - linear equations cannot be solved by deriving local information

Local consistency: only small, local and necessary changes,  
does not waste resources  $\Rightarrow$  *conservative*

Linear equations: costly, ineffective (Gaussian elimination),  
constantly invents something new that never works out  
(more effective algorithms)  $\Rightarrow$  *socialist*

**Fun fact:** Finite-domain CSP solved by a combination  
of local consistency and linear equations (Bulatov, Zhuk, 2017)  
 $\Rightarrow$  Grand coalition (“building bridges”)

$\mathbb{A}$  finite  $\Rightarrow \mathbb{A}$  has width  $(m, n) \Leftrightarrow$  it has width  $(2, 3)$   
*Collapse* (Barto, 2016)  
bounded width has an algebraic characterization

$\mathbb{A}$  finite  $\Rightarrow \mathbb{A}$  has width  $(m, n) \Leftrightarrow$  it has width  $(2, 3)$

*Collapse* (Barto, 2016)

bounded width has an algebraic characterization

$\mathbb{A}$  infinite  $\Rightarrow$  no uniform bound, no algebraic characterization

$\mathbb{A}$  finite  $\Rightarrow \mathbb{A}$  has width  $(m, n) \Leftrightarrow$  it has width  $(2, 3)$

*Collapse* (Barto, 2016)

bounded width has an algebraic characterization

$\mathbb{A}$  infinite  $\Rightarrow$  no uniform bound, no algebraic characterization

**Question:**  $\mathbb{A}$  fo-definable in a finitely bounded homogeneous  $\mathbb{B}$ ,  
 $\mathbb{A}$  has bounded width.

*Does there exist a bound on the width of  $\mathbb{A}$  depending only on  $\mathbb{B}$ ?*

## Bounds on width, 1/2

$\mathbb{A}$  fo-definable in  $\mathbb{B}$

$k - \text{maxarity}(\mathbb{B})$ ,  $\ell - \text{size of the biggest bound}$

*Does there exist a bound on the width of  $\mathbb{A}$  depending only on  $\mathbb{B}$ ?*

**Assume:**  $\mathbb{A}$  has a relation for every orbit of  $k$ -tuples under  $\text{Aut}(\mathbb{B})$ .

*What is the minimal possible width of  $\mathbb{A}$ ?*

## Bounds on width, 1/2

$\mathbb{A}$  fo-definable in  $\mathbb{B}$

$k - \text{maxarity}(\mathbb{B})$ ,  $\ell - \text{size of the biggest bound}$

*Does there exist a bound on the width of  $\mathbb{A}$  depending only on  $\mathbb{B}$ ?*

**Assume:**  $\mathbb{A}$  has a relation for every orbit of  $k$ -tuples under  $\text{Aut}(\mathbb{B})$ .

*What is the minimal possible width of  $\mathbb{A}$ ?*

- Need  $(k, \text{something})$  to check that no tuple lies in two orbits.

## Bounds on width, 1/2

$\mathbb{A}$  fo-definable in  $\mathbb{B}$

$k - \text{maxarity}(\mathbb{B})$ ,  $\ell - \text{size of the biggest bound}$

*Does there exist a bound on the width of  $\mathbb{A}$  depending only on  $\mathbb{B}$ ?*

**Assume:**  $\mathbb{A}$  has a relation for every orbit of  $k$ -tuples under  $\text{Aut}(\mathbb{B})$ .

*What is the minimal possible width of  $\mathbb{A}$ ?*

- Need  $(k, \text{something})$  to check that no tuple lies in two orbits.
- Need  $(\text{something}, \ell)$  to get all constraints given by bounds.

## Bounds on width, 1/2

$\mathbb{A}$  fo-definable in  $\mathbb{B}$

$k - \text{maxarity}(\mathbb{B})$ ,  $\ell - \text{size of the biggest bound}$

*Does there exist a bound on the width of  $\mathbb{A}$  depending only on  $\mathbb{B}$ ?*

**Assume:**  $\mathbb{A}$  has a relation for every orbit of  $k$ -tuples under  $\text{Aut}(\mathbb{B})$ .

*What is the minimal possible width of  $\mathbb{A}$ ?*

- Need  $(k, \text{something})$  to check that no tuple lies in two orbits.
- Need  $(\text{something}, \ell)$  to get all constraints given by bounds.
- If = among relations of  $\mathbb{A} \Rightarrow$  need  $(k, k + 1)$  to exclude

$$(x_1, \dots, x_k) \in O, (x_1, \dots, x_{k-1}, y) \in P, x_k = y$$

for  $O \neq P$

$\rightsquigarrow \mathbb{A}$  has relational width at least  $(k, \max(k + 1, \ell))$ .

## Bounds on width, 2/2

$\mathbb{A}$  fo-definable in  $\mathbb{B}$

$k$  – maxarity( $\mathbb{B}$ ),  $\ell$  – size of the biggest bound

*Does there exist a bound on the width of  $\mathbb{A}$  depending only on  $\mathbb{B}$ ?*

**Know:** natural lower bound:  $(k, \max(k + 1, \ell))$

## Bounds on width, 2/2

$\mathbb{A}$  fo-definable in  $\mathbb{B}$

$k$  – maxarity( $\mathbb{B}$ ),  $\ell$  – size of the biggest bound

*Does there exist a bound on the width of  $\mathbb{A}$  depending only on  $\mathbb{B}$ ?*

**Know:** natural lower bound:  $(k, \max(k + 1, \ell))$

$\mathbb{A}$  finite with  $n$  elements  $\Rightarrow \mathbb{A}$  fo-definable from

$\mathbb{B} := (\{1, \dots, n\}, \{1\}, \dots, \{n\})$

Collapse  $\sim$   $\mathbb{A}$  has relational width  $(2, 3)$ .

## Bounds on width, 2/2

$\mathbb{A}$  fo-definable in  $\mathbb{B}$

$k$  – maxarity( $\mathbb{B}$ ),  $\ell$  – size of the biggest bound

*Does there exist a bound on the width of  $\mathbb{A}$  depending only on  $\mathbb{B}$ ?*

**Know:** natural lower bound:  $(k, \max(k+1, \ell))$

$\mathbb{A}$  finite with  $n$  elements  $\Rightarrow \mathbb{A}$  fo-definable from

$\mathbb{B} := (\{1, \dots, n\}, \{1\}, \dots, \{n\})$

Collapse  $\sim$   $\mathbb{A}$  has relational width  $(2, 3)$ .

**Idea:**  $k = 1, \ell = 2$  (forbid  $a \in \{i\} \cap \{j\}, a, b \in \{i\}$ )

$\Rightarrow$  Natural guess for upped bound on the width of  $\mathbb{A}$ :  $(2k, \max(3k, \ell))$

*Is this true also for infinite  $\mathbb{A}$  ???*

## Bounds on width, 2/2

$\mathbb{A}$  fo-definable in  $\mathbb{B}$

$k$  – maxarity( $\mathbb{B}$ ),  $\ell$  – size of the biggest bound

*Does there exist a bound on the width of  $\mathbb{A}$  depending only on  $\mathbb{B}$ ?*

**Know:** natural lower bound:  $(k, \max(k+1, \ell))$

$\mathbb{A}$  finite with  $n$  elements  $\Rightarrow \mathbb{A}$  fo-definable from

$\mathbb{B} := (\{1, \dots, n\}, \{1\}, \dots, \{n\})$

Collapse  $\sim$   $\mathbb{A}$  has relational width  $(2, 3)$ .

**Idea:**  $k = 1, \ell = 2$  (forbid  $a \in \{i\} \cap \{j\}, a, b \in \{i\}$ )

$\Rightarrow$  Natural guess for upped bound on the width of  $\mathbb{A}$ :  $(2k, \max(3k, \ell))$

*Is this true also for infinite  $\mathbb{A}$  ???*

Often YES.

No counterexample known!

## Strict width

$$m \geq 1$$

$\mathbb{A}$  has *strict width*  $m$  if there exists  $n \geq m$   
s. t. for every  $(m, n)$ -minimal instance,  
any *local solution* can be extended to a global one.

## Strict width

$m \geq 1$

$\mathbb{A}$  has *strict width  $m$*  if there exists  $n \geq m$   
s. t. for every  $(m, n)$ -minimal instance,  
any *local solution* can be extended to a global one.

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$  – instance of  $\text{CSP}(\mathbb{A})$  over variables  $\mathcal{V}$

**Want:** for any  $U \subseteq \mathcal{V}$ , any assignment  $f: U \rightarrow A$  satisfying projection  
of every  $\phi_i$  to  $U$  can be extended to a satisfying assignment for  $\Phi$ .

## Strict width

$$m \geq 1$$

$\mathbb{A}$  has *strict width*  $m$  if there exists  $n \geq m$

s. t. for every  $(m, n)$ -minimal instance,

any *local solution* can be extended to a global one.

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$  – instance of  $\text{CSP}(\mathbb{A})$  over variables  $\mathcal{V}$

**Want:** for any  $U \subseteq \mathcal{V}$ , any assignment  $f: U \rightarrow A$  satisfying projection of every  $\phi_i$  to  $U$  can be extended to a satisfying assignment for  $\Phi$ .

$\Rightarrow$  far-right (extreme local consistency, controls too much,  
kills everybody who doesn't contribute to the intended global solution)

## Strict width

$m \geq 1$

$\mathbb{A}$  has *strict width  $m$*  if there exists  $n \geq m$   
s. t. for every  $(m, n)$ -minimal instance,  
any *local solution* can be extended to a global one.

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$  – instance of  $\text{CSP}(\mathbb{A})$  over variables  $\mathcal{V}$

**Want:** for any  $U \subseteq \mathcal{V}$ , any assignment  $f: U \rightarrow A$  satisfying projection  
of every  $\phi_i$  to  $U$  can be extended to a satisfying assignment for  $\Phi$ .

$\Rightarrow$  far-right (extreme local consistency, controls too much,  
kills everybody who doesn't contribute to the intended global solution)

**Example:** the universal triangle-free graph has strict width 2  
(need  $(2, 3)$ -minimality)

# Strict width

$m \geq 1$

$\mathbb{A}$  has *strict width  $m$*  if there exists  $n \geq m$   
s. t. for every  $(m, n)$ -minimal instance,  
any *local solution* can be extended to a global one.

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$  – instance of  $\text{CSP}(\mathbb{A})$  over variables  $\mathcal{V}$

**Want:** for any  $U \subseteq \mathcal{V}$ , any assignment  $f: U \rightarrow A$  satisfying projection  
of every  $\phi_i$  to  $U$  can be extended to a satisfying assignment for  $\Phi$ .

$\Rightarrow$  far-right (extreme local consistency, controls too much,  
kills everybody who doesn't contribute to the intended global solution)

**Example:** the universal triangle-free graph has strict width 2  
(need  $(2, 3)$ -minimality)

**Algebraic characterization:** finite or infinite ( $\omega$ -cat.)  $\mathbb{A}$   
has strict width  $k \Leftrightarrow$  for every finite  $F \subseteq A$ ,  
 $\exists$  a  $(k + 1)$ -ary *polymorphism* of  $\mathbb{A}$  which is a *near-unanimity* on  $F$ :  
 $x \approx f(x, \dots, x) \approx f(y, x, \dots, x) \approx \dots \approx f(x, \dots, x, y)$

# Strict width

$m \geq 1$

$\mathbb{A}$  has *strict width  $m$*  if there exists  $n \geq m$   
s. t. for every  $(m, n)$ -minimal instance,  
any *local solution* can be extended to a global one.

$\Phi = \phi_1 \wedge \dots \wedge \phi_k$  – instance of  $\text{CSP}(\mathbb{A})$  over variables  $\mathcal{V}$

**Want:** for any  $U \subseteq \mathcal{V}$ , any assignment  $f: U \rightarrow A$  satisfying projection  
of every  $\phi_i$  to  $U$  can be extended to a satisfying assignment for  $\Phi$ .

$\Rightarrow$  far-right (extreme local consistency, controls too much,  
kills everybody who doesn't contribute to the intended global solution)

**Example:** the universal triangle-free graph has strict width 2  
(need  $(2, 3)$ -minimality)

**Algebraic characterization:** finite or infinite ( $\omega$ -cat.)  $\mathbb{A}$

has strict width  $k \Leftrightarrow$  for every finite  $F \subseteq A$ ,

$\exists$  a  $(k + 1)$ -ary *polymorphism* of  $\mathbb{A}$  which is a *near-unanimity* on  $F$ :  
 $x \approx f(x, \dots, x) \approx f(y, x, \dots, x) \approx \dots \approx f(x, \dots, x, y)$

No collapse even for finite  $\mathbb{A}$ !

# A contribution to the progress of the human race

$k \geq 3$ ,

$\mathbb{B}$  –  $k$ -neoliberal, has finite duality,

$\ell$  – size of the biggest bound for  $\mathbb{B}$

$\mathbb{A}$  – fo-definable in  $\mathbb{B}$ , has all relations of  $\mathbb{B}$

Theorem. [N., Pinsker]

If  $\mathbb{A}$  has bounded strict width

$\Rightarrow \mathbb{A}$  has relational width  $(k, \max(k + 1, \ell))$ .

# A contribution to the progress of the human race

$k \geq 3$ ,

$\mathbb{B}$  –  $k$ -neoliberal, has finite duality,

$\ell$  – size of the biggest bound for  $\mathbb{B}$

$\mathbb{A}$  – fo-definable in  $\mathbb{B}$ , has all relations of  $\mathbb{B}$

Theorem. [N., Pinsker]

If  $\mathbb{A}$  has bounded strict width

$\Rightarrow \mathbb{A}$  has relational width  $(k, \max(k + 1, \ell))$ .

$\Rightarrow \mathbb{A}$  has as low relational width as possible

**Idea:** using the algebraic characterization of strict width,  
show that certain “implications”  $R(x_1, \dots, x_m) \Rightarrow S(y_1, \dots, y_n)$   
not preserved by near-unanimity

# A contribution to the progress of the human race

$k \geq 3$ ,

$\mathbb{B}$  –  $k$ -neoliberal, has finite duality,

$\ell$  – size of the biggest bound for  $\mathbb{B}$

$\mathbb{A}$  – fo-definable in  $\mathbb{B}$ , has all relations of  $\mathbb{B}$

Theorem. [N., Pinsker]

If  $\mathbb{A}$  has bounded strict width

$\Rightarrow \mathbb{A}$  has relational width  $(k, \max(k + 1, \ell))$ .

$\Rightarrow \mathbb{A}$  has as low relational width as possible

**Idea:** using the algebraic characterization of strict width,  
show that certain “implications”  $R(x_1, \dots, x_m) \Rightarrow S(y_1, \dots, y_n)$   
not preserved by near-unanimity

*“Neoliberalism implies that if a problem can be solved  
by installing a fascist regime (strict width),  
it can be solved in a much easier way and with less resources  
using conservative policies (relational width).”*



Thank you for your attention!