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Math 534H. The Weak Maximum Principle

Let $\Omega \subset \mathbb{R}^d$, $\Omega_T = (0, T) \times \Omega$ is a space-time cylinder and its parabolic boundary is $\partial\Omega_T := (\bar{\Omega} \times \{t=0\}) \cup S_T$

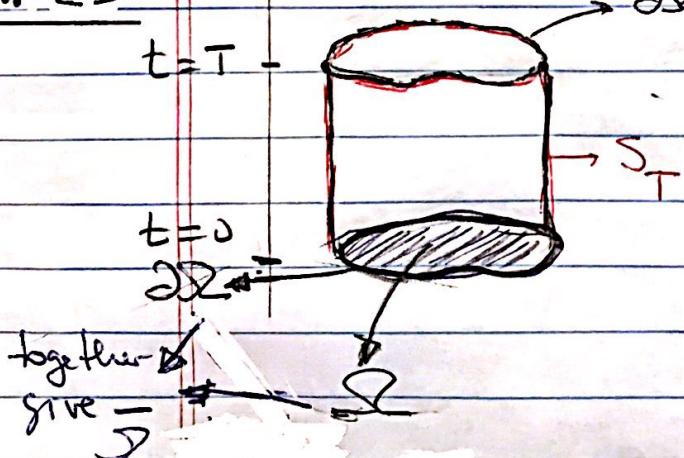
where $S_T := \partial\Omega \times (0, T]$

(here $\partial\Omega$ means the boundary of the domain Ω and $\bar{\Omega}$ means the closure of Ω . Here

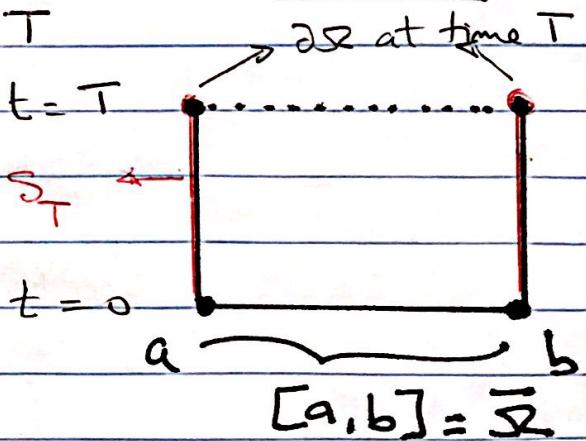
you may think as $\bar{\Omega}$ being Ω union its boundary: $\bar{\Omega} = \Omega \cup \partial\Omega$)

For example:

In 2D



In 1D



Consider a function $f = f(x, t) \leq 0$ $x \in \Omega$ $0 < t < T$

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and suppose that $u \in C^{2,1}(\bar{Q}_T) \cap C(\bar{\Omega}_T)$
 is a solution to the (possible inhomogeneous)
 heat/diffusion equation in $\mathcal{D} \times (0, T)$:

$$u_t - k \Delta u = f \quad (\text{recall } f \leq 0) \quad (k > 0).$$

Then: $u(x, t)$ obtains its maximum in
 the region \bar{Q}_T on $\partial\bar{Q}_T$ (That is at the
 bottom or lateral sides)

Similarly suppose that $\tilde{u} \in C^{2,1}(\bar{Q}_T) \cap C(\bar{\Omega})$
 is a solution to the (possible inhomogeneous)
 heat/diffusion equation in $\mathcal{D} \times (0, T)$

$$\tilde{u}_t - k \Delta \tilde{u} = \tilde{f} \quad (k > 0)$$

where now $\tilde{f} = \tilde{f}(x, t) \geq 0$ on $\mathcal{D} \times (0, T)$

Then $\tilde{u}(x, t)$ obtains its minimum in the
 region \bar{Q}_T on $\partial\bar{Q}_T$.

Remark: Suppose that $f \equiv 0$ in (MAX)
 and $\tilde{f} \equiv 0$ in (MIN) and suppose that

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$u \in C^{2,1}(\bar{Q}_T) \cap C(\bar{\bar{Q}}_T)$ is a solution

to

$$u_t - k \Delta u = 0 \quad \text{in } Q \times (0, T) \quad (k > 0).$$

Then; one has both in this case:

$$\max_{\bar{Q}_T} u(x, t) = \max_{\partial Q_T} u(x, t)$$

and

$$\min_{\bar{Q}_T} u(x, t) = \min_{\partial Q_T} u(x, t)$$

NOTE: In the above recall that $C^{2,1}(\bar{Q}_T)$ means that u is C^2 in x and C^1 in t for $(x, t) \in Q_T$.

Since \bar{Q}_T is closed and bounded in \mathbb{R}^d
it is in fact uniformly continuous in \bar{Q}_T

While $C(\bar{\bar{Q}}_T)$ means that $u(x, t)$ is continuous for (x, t) in $\bar{\bar{Q}}_T$ (including at the boundary).

We will prove (MAX). Once we have (MAX)
the proof of (MIN) follows by applying the (MAX)

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maximum principle to $-u(x,t)$ ($= \tilde{u}(x,t)$)
 with $-f(x,t)$ ($= \tilde{f}(x,t)$).

Proof (MAX) : For simplicity here in this course we consider only the proof in 1D.
 (The proof in higher D is similar but a bit more involved).

Let $\varepsilon > 0$ and let $w := u - \varepsilon t$

We wish to obtain the information we seek about the max of u by studying $w(x,t)$ and then letting $\varepsilon \rightarrow 0^+$.

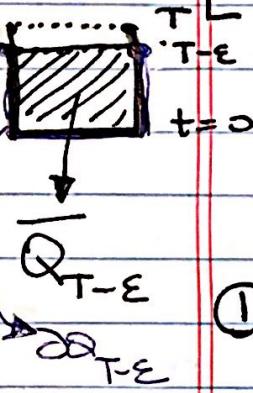
Note that on $\overline{Q_T}$ we have } $w \leq u$
 $u \leq w + \varepsilon T$

and that on Q_T^c we have :

$$\begin{aligned}
 (†) \quad w_t - k w_{xx} &= u_t - \varepsilon - k u_{xx} \\
 &= \underbrace{u_t - k u_{xx}}_{\text{(strictly negative)}} - \varepsilon \\
 &= \tilde{f} - \varepsilon < 0
 \end{aligned}$$

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CLAIM We would like to prove next that the MAX of W on $\overline{Q}_{T-\varepsilon}$ occurs on $\partial Q_{T-\varepsilon}$:



Suppose that $w(x,t)$ has its maximum at $(x_0, t_0) \in \overline{Q}_{T-\varepsilon}$.

- ① • And suppose that $0 < t_0 \leq T - \varepsilon$; since if $t_0 = 0$ the claim is obviously true. (since $t_0 = 0$ is part of $\partial Q_{T-\varepsilon}$)

Under this assumption, we have that

$$\left\{ \begin{array}{l} W(x,t) < u(x,t) \\ u(x,t) < W(x,t) + \varepsilon T \end{array} \right.$$

- ② • Suppose also that $x_0 \in \mathcal{X}$; since if $x_0 \in \partial \mathcal{X}$, then $(x_0, t_0) \in \partial Q_{T-\varepsilon}$ and the claim would be obviously true.

We would like to draw a contradiction from assuming ① and ② since that contradiction would imply the CLAIM above

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Under ① and ② :

From calculus $\nabla_x W(x_0, t_0) = 0$; and

- ① • $W_t(x_0, t_0) = 0$ if $t_0 < T - \varepsilon$
- ② • $W_t(x_0, t_0) \geq 0$ if $t_0 = T - \varepsilon$:

Indeed:

$$W_t(x_0, t_0) = \lim_{\substack{\delta \rightarrow 0^+ \\ (\text{if } t_0 = T - \varepsilon)}} \frac{W(x_0, t_0) - W(x_0, t_0 - \delta)}{\delta}$$

≥ 0 since
 $\delta > 0$ and also
 $W(x_0, t_0) \geq W(x_0, t_0 - \delta)$
 (where MAX is.)

- Since $W(x_0, t_0)$ is the maximum value, we can apply Taylor's remainder theorem in x to obtain that for x near x_0 we have :

$$0 \geq W(x_1, t_0) - W(x_0, t_0) =$$

$$W_x \left| \cdot (x - x_0) + \frac{W_{xx}}{2} (x - x_0)^2 \right|$$

\downarrow MAX \downarrow positive

$\underbrace{(x_0, t_0)}_{= 0}$ $\underbrace{(x_1^*, t_0)}_{}$

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Where x^* is some point between x and x_0 .

Therefore we must have that $W_{xx}(x^*, t_0) \leq 0$ (from ④) and by taking the limit as $x \rightarrow x_0$ it follows that $x^* \rightarrow x_0$ and then

③ • $W_{xx}(x_0, t_0) \leq 0$ (we are using that W_{xx} is continuous in x)

But then we have all in all (from ①②③) in all cases

$$W_t(x_0, t_0) - R W_{xx}(x_0, t_0) \geq 0$$

which contradicts (7) in page ④.

Hence the claim at the top of page ⑤ follows.

Now using $W(x, t) \leq u(x, t)$ and the fact

that $\partial Q_{T-\varepsilon} \subset \partial Q_T$ we have thus shown that:

$$(7) \quad \max_{\overline{Q}_{T-\varepsilon}} W = \max_{\partial Q_{T-\varepsilon}} W \leq \max_{\partial Q_{T-\varepsilon}} u \leq \max_{\partial Q_T} u$$

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Using (ft) above and that $u \leq w + ET$
we also have :

$$(ftt) \quad \max_{\overline{Q}_{T-\varepsilon}} u \leq \max_{\overline{Q}_T} w + ET \leq ET + \max_{\partial Q_T} u$$

Now since u is uniformly continuous on \overline{Q}_T
we have that

$$\max_{\overline{Q}_{T-\varepsilon}} u \xrightarrow{\text{as } \varepsilon \rightarrow 0^+} \max_{\overline{Q}_T} u$$

(converges in an increasing
fashion).

Thus allowing $\varepsilon \rightarrow 0^+$ in (ftt) we deduce
that :

$$\begin{aligned} \max_{\overline{Q}_T} u &= \lim_{\varepsilon \rightarrow 0^+} \max_{\overline{Q}_{T-\varepsilon}} u \leq \lim_{\varepsilon \rightarrow 0^+} (ET + \max_{\partial Q_T} u) \\ &= \max_{\partial Q_T} u \end{aligned}$$

This means they must
all be equal in this chain

$$\leftarrow \leq \max_{\overline{Q}_T} u \Rightarrow$$

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$$\max_{\overline{Q_T}} u = \max_{\partial Q_T} u$$

as we wanted to show. #.

We record here a Corollary :

Corollary (Comparison Principle and Stability)

Suppose that v and u are solutions

to $v_t - k v_{xx} = f$ and

$u_t - k u_{xx} = g$ respectively

(no assumptions on the signs of f or g).

Then: i) (Comparison Principle): If
 $v \geq u$ on ∂Q_T and $f \geq g$ then

$v \geq u$ on all of Q_T

ii) (Stability):

$$\max_{\overline{Q_T}} |v-u| \leq \max_{\partial Q_T} |v-u| + T \max_{Q_T} |f-g|$$