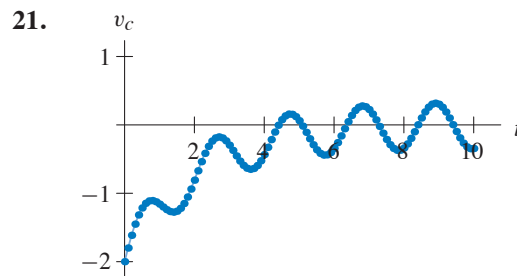


Graph of approximate solution obtained using Euler's method with  $\Delta t = 0.1$ .



Graph of approximate solution obtained using Euler's method with  $\Delta t = 0.1$ .

## EXERCISES FOR SECTION 1.5

1. Since the constant function  $y_1(t) = 3$  for all  $t$  is a solution, then the graph of any other solution  $y(t)$  with  $y(0) < 3$  cannot cross the line  $y = 3$  by the Uniqueness Theorem. So  $y(t) < 3$  for all  $t$  in the domain of  $y(t)$ .
2. Since  $y(0) = 1$  is between the equilibrium solutions  $y_2(t) = 0$  and  $y_3(t) = 2$ , we must have  $0 < y(t) < 2$  for all  $t$  because the Uniqueness Theorem implies that graphs of solutions cannot cross (or even touch in this case).
3. Because  $y_2(0) < y(0) < y_1(0)$ , we know that

$$-t^2 = y_2(t) < y(t) < y_1(t) = t + 2$$

for all  $t$ . This restricts how large positive or negative  $y(t)$  can be for a given value of  $t$  (that is, between  $-t^2$  and  $t + 2$ ). As  $t \rightarrow -\infty$ ,  $y(t) \rightarrow -\infty$  between  $-t^2$  and  $t + 2$  ( $y(t) \rightarrow -\infty$  as  $t \rightarrow -\infty$  at least linearly, but no faster than quadratically).

4. Because  $y_1(0) < y(0) < y_2(0)$ , the solution  $y(t)$  must satisfy  $y_1(t) < y(t) < y_2(t)$  for all  $t$  by the Uniqueness Theorem. Hence  $-1 < y(t) < 1 + t^2$  for all  $t$ .
5. The Existence Theorem implies that a solution with this initial condition exists, at least for a small  $t$ -interval about  $t = 0$ . This differential equation has equilibrium solutions  $y_1(t) = 0$ ,  $y_2(t) = 1$ , and  $y_3(t) = 3$  for all  $t$ . Since  $y(0) = 4$ , the Uniqueness Theorem implies that  $y(t) > 3$  for all  $t$  in the domain of  $y(t)$ . Also,  $dy/dt > 0$  for all  $y > 3$ , so the solution  $y(t)$  is increasing for all  $t$  in its domain. Finally,  $y(t) \rightarrow 3$  as  $t \rightarrow -\infty$ .
6. Note that  $dy/dt = 0$  if  $y = 0$ . Hence,  $y_1(t) = 0$  for all  $t$  is an equilibrium solution. By the Uniqueness Theorem, this is the only solution that is 0 at  $t = 0$ . Therefore,  $y(t) = 0$  for all  $t$ .
7. The Existence Theorem implies that a solution with this initial condition exists, at least for a small  $t$ -interval about  $t = 0$ . Because  $1 < y(0) < 3$  and  $y_1(t) = 1$  and  $y_2(t) = 3$  are equilibrium solutions

of the differential equation, we know that the solution exists for all  $t$  and that  $1 < y(t) < 3$  for all  $t$  by the Uniqueness Theorem. Also,  $dy/dt < 0$  for  $1 < y < 3$ , so  $dy/dt$  is always negative for this solution. Hence,  $y(t) \rightarrow 1$  as  $t \rightarrow \infty$ , and  $y(t) \rightarrow 3$  as  $t \rightarrow -\infty$ .

8. The Existence Theorem implies that a solution with this initial condition exists, at least for a small  $t$ -interval about  $t = 0$ . Note that  $y(0) < 0$ . Since  $y_1(t) = 0$  is an equilibrium solution, the Uniqueness Theorem implies that  $y(t) < 0$  for all  $t$ . Also,  $dy/dt < 0$  if  $y < 0$ , so  $y(t)$  is decreasing for all  $t$ , and  $y(t) \rightarrow -\infty$  as  $t$  increases. As  $t \rightarrow -\infty$ ,  $y(t) \rightarrow 0$ .

9. (a) To check that  $y_1(t) = t^2$  is a solution, we compute

$$\frac{dy_1}{dt} = 2t$$

and

$$\begin{aligned} -y_1^2 + y_1 + 2y_1t^2 + 2t - t^2 - t^4 &= -(t^2)^2 + (t^2) + 2(t^2)t^2 + 2t - t^2 - t^4 \\ &= 2t. \end{aligned}$$

To check that  $y_2(t) = t^2 + 1$  is a solution, we compute

$$\frac{dy_2}{dt} = 2t$$

and

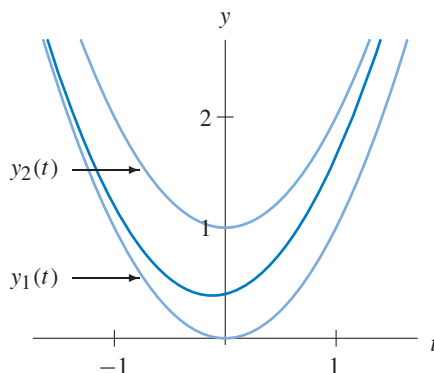
$$\begin{aligned} -y_2^2 + y_2 + 2y_2t^2 + 2t - t^2 - t^4 &= -(t^2 + 1)^2 + (t^2 + 1) + 2(t^2 + 1)t^2 \\ &\quad + 2t - t^2 - t^4 \\ &= 2t. \end{aligned}$$

- (b) The initial values of the two solutions are  $y_1(0) = 0$  and  $y_2(0) = 1$ . Thus if  $y(t)$  is a solution and  $y_1(0) = 0 < y(0) < 1 = y_2(0)$ , then we can apply the Uniqueness Theorem to obtain

$$y_1(t) = t^2 < y(t) < t^2 + 1 = y_2(t)$$

for all  $t$ . Note that since the differential equation satisfies the hypothesis of the Existence and Uniqueness Theorem over the entire  $ty$ -plane, we can continue to extend the solution as long as it does not escape to  $\pm\infty$  in finite time. Since it is bounded above and below by solutions that exist for all time,  $y(t)$  is defined for all time also.

(c)



10. (a) If  $y(t) = 0$  for all  $t$ , then  $dy/dt = 0$  and  $2\sqrt{|y(t)|} = 0$  for all  $t$ . Hence, the function that is constantly zero satisfies the differential equation.
- (b) First, consider the case where  $y > 0$ . The differential equation reduces to  $dy/dt = 2\sqrt{y}$ . If we separate variables and integrate, we obtain

$$\sqrt{y} = t - c,$$

where  $c$  is any constant. The graph of this equation is the half of the parabola  $y = (t - c)^2$  where  $t \geq c$ .

Next, consider the case where  $y < 0$ . The differential equation reduces to  $dy/dt = 2\sqrt{-y}$ . If we separate variables and integrate, we obtain

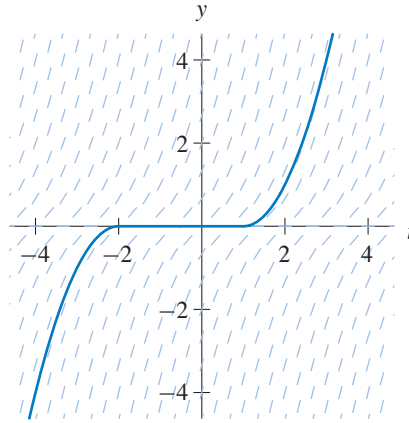
$$\sqrt{-y} = d - t,$$

where  $d$  is any constant. The graph of this equation is the half of the parabola  $y = -(d - t)^2$  where  $t \leq d$ .

To obtain all solutions, we observe that any choice of constants  $c$  and  $d$  where  $c \geq d$  leads to a solution of the form

$$y(t) = \begin{cases} -(d - t)^2, & \text{if } t \leq d; \\ 0, & \text{if } d \leq t \leq c; \\ (t - c)^2, & \text{if } t \geq c. \end{cases}$$

(See the following figure for the case where  $d = -2$  and  $c = 1$ .)



- (c) The partial derivative  $\partial f / \partial y$  of  $f(t, y) = \sqrt{|y|}$  does not exist along the  $t$ -axis.
- (d) If  $y_0 = 0$ , `HPGSolver` plots the equilibrium solution that is constantly zero. If  $y_0 \neq 0$ , it plots a solution whose graph crosses the  $t$ -axis. This is a solution where  $c = d$  in the formula given above.
11. The key observation is that the differential equation is not defined when  $t = 0$ .
- (a) Note that  $dy_1/dt = 0$  and  $y_1/t^2 = 0$ , so  $y_1(t)$  is a solution.

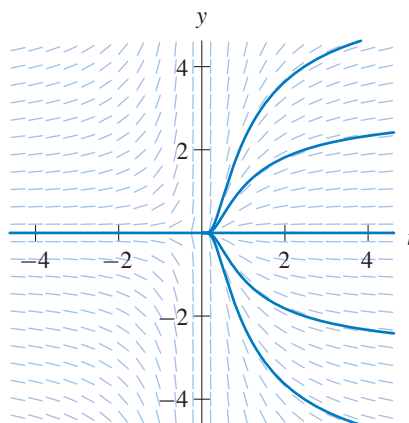
(b) Separating variables, we have

$$\int \frac{dy}{y} = \int \frac{dt}{t^2}.$$

Solving for  $y$  we obtain  $y(t) = ce^{-1/t}$ , where  $c$  is any constant. Thus, for any real number  $c$ , define the function  $y_c(t)$  by

$$y_c(t) = \begin{cases} 0 & \text{for } t \leq 0; \\ ce^{-1/t} & \text{for } t > 0. \end{cases}$$

For each  $c$ ,  $y_c(t)$  satisfies the differential equation for all  $t \neq 0$ .



There are infinitely many solutions of the form  $y_c(t)$  that agree with  $y_1(t)$  for  $t < 0$ .

- (c) Note that  $f(t, y) = y/t^2$  is not defined at  $t = 0$ . Therefore, we *cannot* apply the Uniqueness Theorem for the initial condition  $y(0) = 0$ . The “solution”  $y_c(t)$  given in part (b) actually represents two solutions, one for  $t < 0$  and one for  $t > 0$ .

12. (a) Note that

$$\frac{dy_1}{dt} = \frac{d}{dt} \left( \frac{1}{t-1} \right) = -\frac{1}{(t-1)^2} = -(y_1(t))^2$$

and

$$\frac{dy_2}{dt} = \frac{d}{dt} \left( \frac{1}{t-2} \right) = -\frac{1}{(t-2)^2} = -(y_2(t))^2,$$

so both  $y_1(t)$  and  $y_2(t)$  are solutions.

- (b) Note that  $y_1(0) = -1$  and  $y_2(0) = -1/2$ . If  $y(t)$  is another solution whose initial condition satisfies  $-1 < y(0) < -1/2$ , then  $y_1(t) < y(t) < y_2(t)$  for all  $t$  by the Uniqueness Theorem. Also, since  $dy/dt < 0$ ,  $y(t)$  is decreasing for all  $t$  in its domain. Therefore,  $y(t) \rightarrow 0$  as  $t \rightarrow -\infty$ , and the graph of  $y(t)$  has a vertical asymptote between  $t = 1$  and  $t = 2$ .

15. (a) The equation is separable. We separate, integrate

$$\int (y + 2)^2 dy = \int dt,$$

and solve for  $y$  to obtain the general solution

$$y(t) = (3t + c)^{1/3} - 2,$$

where  $c$  is any constant. To obtain the desired solution, we use the initial condition  $y(0) = 1$  and solve

$$1 = (3 \cdot 0 + c)^{1/3} - 2$$

for  $c$  to obtain  $c = 27$ . So the solution to the given initial-value problem is

$$y(t) = (3t + 27)^{1/3} - 2.$$

- (b) This function is defined for all  $t$ . However,  $y(-9) = -2$ , and the differential equation is not defined at  $y = -2$ . Strictly speaking, the solution exists only for  $t > -9$ .  
 (c) As  $t \rightarrow \infty$ ,  $y(t) \rightarrow \infty$ . As  $t \rightarrow -9^+$ ,  $y(t) \rightarrow -2$ .

16. (a) The equation is separable. Separating variables we obtain

$$\int (y - 2) dy = \int t dt.$$

Solving for  $y$  with help from the quadratic formula yields the general solution

$$y(t) = 2 \pm \sqrt{t^2 + c}.$$

To find  $c$ , we let  $t = -1$  and  $y = 0$ , and we obtain  $c = 3$ . The desired solution is therefore  $y(t) = 2 - \sqrt{t^2 + 3}$

- (b) Since  $t^2 + 2$  is always positive and  $y(t) < 2$  for all  $t$ , the solution  $y(t)$  is defined for all real numbers.  
 (c) As  $t \rightarrow \pm\infty$ ,  $t^2 + 3 \rightarrow \infty$ . Therefore,

$$\lim_{t \rightarrow \pm\infty} y(t) = -\infty.$$

17. This exercise shows that solutions of autonomous equations cannot have local maximums or minimums. Hence they must be either constant or monotonically increasing or monotonically decreasing. A useful corollary is that a function  $y(t)$  that oscillates cannot be the solution of an autonomous differential equation.

- (a) Note  $dy_1/dt = 0$  at  $t = t_0$  because  $y_1(t)$  has a local maximum. Because  $y_1(t)$  is a solution, we know that  $dy_1/dt = f(y_1(t))$  for all  $t$  in the domain of  $y_1(t)$ . In particular,

$$0 = \left. \frac{dy_1}{dt} \right|_{t=t_0} = f(y_1(t_0)) = f(y_0),$$

so  $f(y_0) = 0$ .

- (b) This differential equation is autonomous, so the slope marks along any given horizontal line are parallel. Hence, the slope marks along the line  $y = y_0$  must all have zero slope.
- (c) For all  $t$ ,

$$\frac{dy_2}{dt} = \frac{d(y_0)}{dt} = 0$$

because the derivative of a constant function is zero, and for all  $t$

$$f(y_2(t)) = f(y_0) = 0.$$

So  $y_2(t)$  is a solution.

- (d) By the Uniqueness Theorem, we know that two solutions that are in the same place at the same time are the same solution. We have  $y_1(t_0) = y_0 = y_2(t_0)$ . Moreover,  $y_1(t)$  is assumed to be a solution, and we showed that  $y_2(t)$  is a solution in parts (a) and (b) of this exercise. So  $y_1(t) = y_2(t)$  for all  $t$ . In other words,  $y_1(t) = y_0$  for all  $t$ .
- (e) Follow the same four steps as before. We still have  $dy_1/dt = 0$  at  $t = t_0$  because  $y_1$  has a local minimum at  $t = t_0$ .

18. (a) Solving for  $r$ , we get

$$r = \left( \frac{3v}{4\pi} \right)^{1/3}.$$

Consequently,

$$\begin{aligned} s(t) &= 4\pi \left( \frac{3v}{4\pi} \right)^{2/3} \\ &= cv(t)^{2/3}, \end{aligned}$$

where  $c$  is a constant. Since we are assuming that the rate of growth of  $v(t)$  is proportional to its surface area  $s(t)$ , we have

$$\frac{dv}{dt} = kv^{2/3},$$

where  $k$  is a constant.

- (b) The partial derivative with respect to  $v$  of  $dv/dt$  does not exist at  $v = 0$ . Hence the Uniqueness Theorem tells us nothing about the uniqueness of solutions that involve  $v = 0$ . In fact, if we use the techniques described in the section related to the uniqueness of solutions for  $dy/dt = 3y^{2/3}$ , we can find infinitely many solutions with this initial condition.
- (c) Since it does not make sense to talk about rain drops with negative volume, we always have  $v \geq 0$ . Once  $v > 0$ , the evolution of the drop is completely determined by the differential equation.

What is the physical significance of a drop with  $v = 0$ ? It is tempting to interpret the fact that solutions can have  $v = 0$  for an arbitrary amount of time before beginning to grow as a statement that the rain drops can spontaneously begin to grow at any time. Since the model gives no information about when a solution with  $v = 0$  starts to grow, it is not very useful for the understanding the initial formation of rain drops. The safest assertion is to say the model breaks down if  $v = 0$ .