

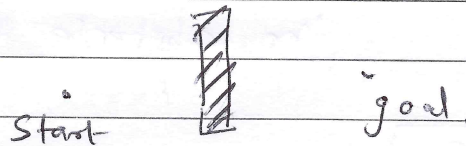
①

Homework 1

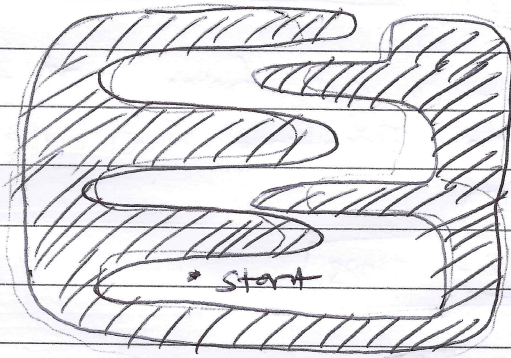
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Problem 1

- ① Bug 1 travels more than Bug 2



- ② Bug 2 travels more than Bug 1
goal.

Problem 3

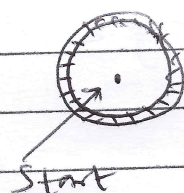
- Bug 0 →
- ① head towards goal
 - ② Follow obstacle until you can head towards goal again
 - ③ Continue

Completeness →

An algorithm is complete, if in finite time it finds a path if such a path exists or terminates with failure if it does not.

②

Consider the following scenario \rightarrow



• goal

• A path does not exist.

But Bug0 fails to terminate since it keeps following the obstacle indefinitely.

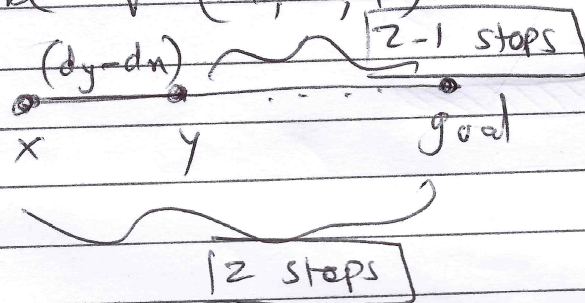
\therefore NOT COMPLETE

Problem 2

* discussed idea with Kevin Yu.

Let optimal value to go from x to goal in z steps with starting fuel value of f .

be $v^*(x, z, f)$



Optimal x = optimal y in z steps + cost(x, y) in $z-1$ steps

DP equation can be formulated as follows \rightarrow

$\therefore v^*(x, z, f) =$

$$\min \begin{cases} v^*(y, z-1, 0) + P_x \cdot (d_y - d_x - f) & P_y \leq P_x \\ v^*(y, z-1, B - (d_y - d_x)) + P_x \cdot (B - f) & P_x > P_y \end{cases}$$

3

∴ if $P_i \leq P_{i+1} \quad \forall i \in 1 \dots n$

we fill the gas full tank at i th station

if $P_i \geq P_{i+1} \quad \forall i \in 1 \dots n$

we fill just enough gas to reach the $i+1$ th gas station.

Initial condition:

- ↳ Starting vertex x_0
- ↳ Starting fuel level B
- ↳ Reach goal in $n-1$ stops. (n including x_0)

Problem 4

- ↳ Comments are inline
- ↳ README has the instructions to execute