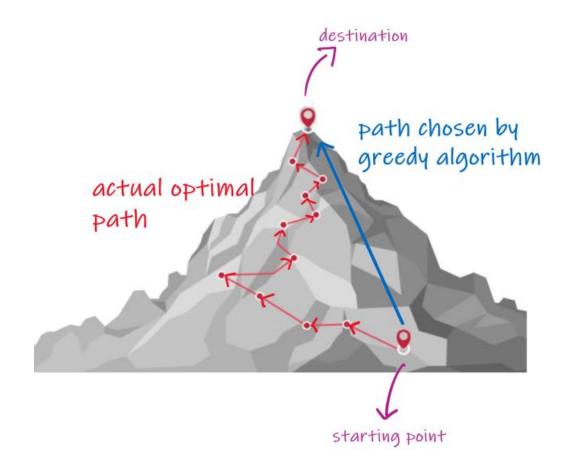
DSE 2256 DESIGN & ANALYSIS OF ALGORITHMS

Lecture 36, 37, 38

Greedy Technique

Prim's Algorithm Kruskal's Algorithm Dijkstra's Algorithm Huffman Coding



Greedy Technique

- Constructs a solution to an optimization problem piece by piece through a sequence of choices that are:
 - **Feasible**, i.e. satisfying the problem constraints
 - Locally optimal (It has to be the best local choice among all choices in that step)
 - Greedy (in terms of some measure), and irrevocable (cannot be changed in subsequent steps)

For some problems, it yields a globally optimal solution for every instance. For most, does not give globally optimal solution, but can be useful for fast approximations.

Applications of the Greedy Strategy

- Optimal solutions:
 - Change making for "normal" coin denominations
 - Minimum spanning tree (MST)
 - Single-source shortest paths
 - Huffman codes
- Approximations/heuristics:
 - Traveling salesman problem (TSP)
 - Knapsack problem
 - Other combinatorial optimization problems

3

Minimum Spanning Tree (MST)

• Spanning tree of a connected graph G = (V, E) is a connected acyclic subgraph of G that includes all of G's vertices with the minimum possible no. of edges.

Some useful properties of spanning trees:

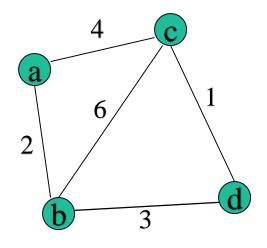
- The spanning tree of a graph G has |V| 1 edges (where, |V| = the total no. of vertices in G).
- For any given graph, multiple spanning trees are possible.
- For a cycle graph (a graph with a single cycle) with n vertices, a total of n spanning trees are possible.
- For a complete graph (K_n) with n vertices a total of $n^{(n-2)}$ spanning trees are possible.
- Minimum spanning tree of a weighted, connected graph G: is a spanning tree of G of the minimum total weight.

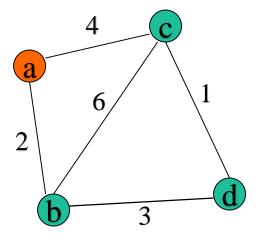
Prim's MST algorithm

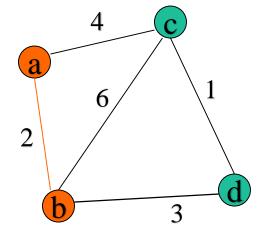
• Start with tree T_1 consisting of one (any) vertex and "grow" tree one vertex at a time to produce MST through a series of expanding subtrees $T_1, T_2, ..., T_n$

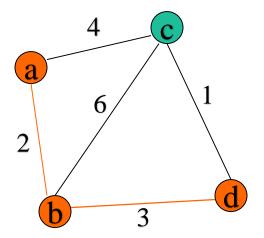
• On each iteration, construct T_{i+1} from T_i by adding vertex not in T_i that is closest to those already in T_i (this is a "greedy" step!)

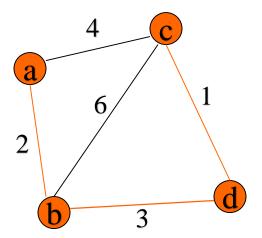
Stop when all vertices are included







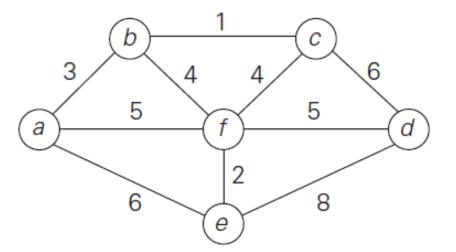




Prim's MST algorithm

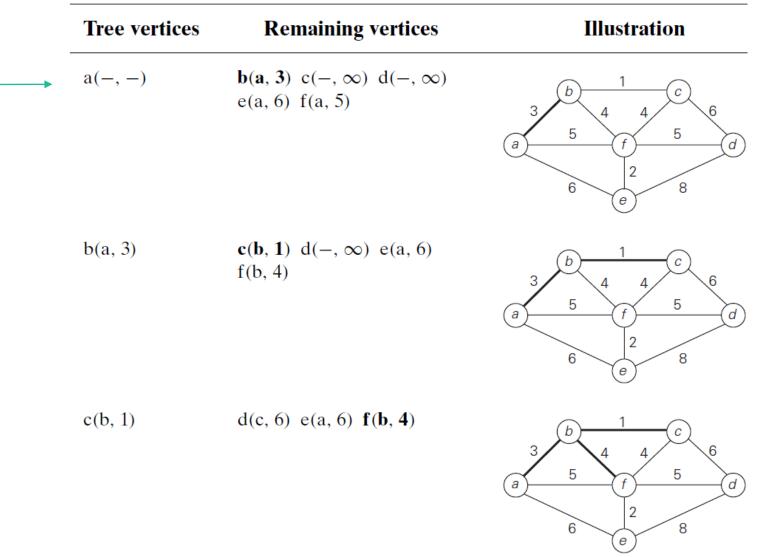
```
ALGORITHM Prim(G)
    //Prim's algorithm for constructing a minimum spanning tree
    //Input: A weighted connected graph G = \langle V, E \rangle
    //Output: E_T, the set of edges composing a minimum spanning tree of G
    V_T \leftarrow \{v_0\} //the set of tree vertices can be initialized with any vertex
    E_T \leftarrow \emptyset
    for i \leftarrow 1 to |V| - 1 do
         find a minimum-weight edge e^* = (v^*, u^*) among all the edges (v, u)
         such that v is in V_T and u is in V - V_T
         V_T \leftarrow V_T \cup \{u^*\}
         E_T \leftarrow E_T \cup \{e^*\}
    return E_T
```

Apply Prim's algorithm to the following graph to find the minimum spanning tree



Start with any arbitrary vertex. Here, let us start with **a**

- At any step check whether there is a connection between all the intermediate tree vertices and the remaining vertices of the input graph.
- If so, choose the connection with the minimum cost.
- Repeat until there are no remaining graph vertices to be considered.
- The resultant tree obtained will be a spanning tree with the minimum total weight (MST).



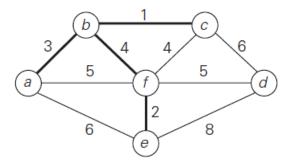
f(b, 4)

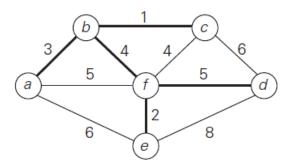
d(f, 5) e(f, 2)

e(f, 2)

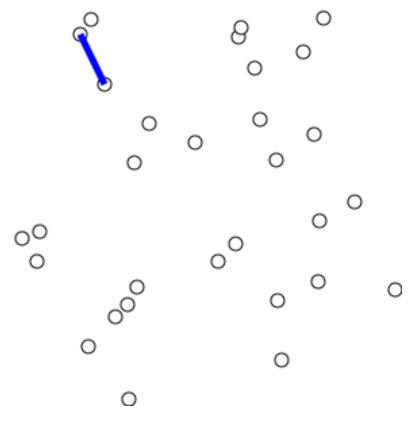
d(f, 5)

d(f, 5)





10



Courtesy - Shiyu Ji (Wikipedia)

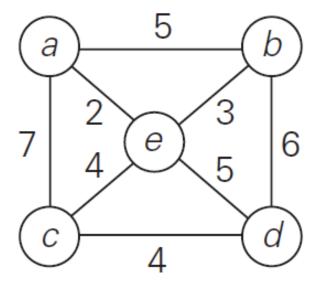
Prim's MST algorithm: Efficiency

- Depends on data structures chosen for graph.
- Generally implemented using priority queue (which contains the priorities of the remaining graph vertices based on their distances to the nearest tree vertices).
- I. If the graph is implemented using weighted adjacency matrix and the priority queue is implemented using arrays, then Prim's algorithm's running time will be: $O(|V|^2)$
- II. If the graph is implemented using adjacency lists and the priority queue is implemented as a minheap, then the algorithm performs |V|-1 deletions of the smallest element and makes |E| verifications. In this case, the running time of the Prim's algorithm is in:

 $(|V|-1+|E|) O(\log |V|) = O(|E| \log |V|)$ (because in a connected graph, |V|-1 < =|E|)

Exercise I

Apply Prim's algorithm to the following graph to find the minimum spanning tree.



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13

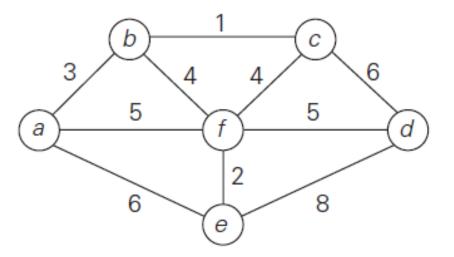
Kruskal's Algorithm

- Another greedy algorithm for computing the Minimum Spanning Tree.
- Developed by Joseph Kruskal in 1956.

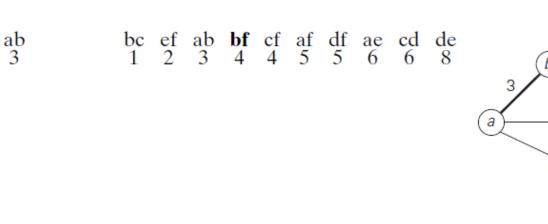
Kruskal's Algorithm (Working):

- Sort the edges in nondecreasing order of lengths
- "Grow" tree one edge at a time to produce MST through a series of expanding forests* F_1 , F_2 , ..., F_{n-1}
- On each iteration, add the next edge on the sorted list unless this would create a cycle. (If it would, skip the edge.)

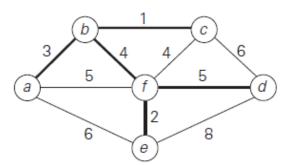
Apply Kruskal's algorithm to the following graph to find the minimum spanning tree



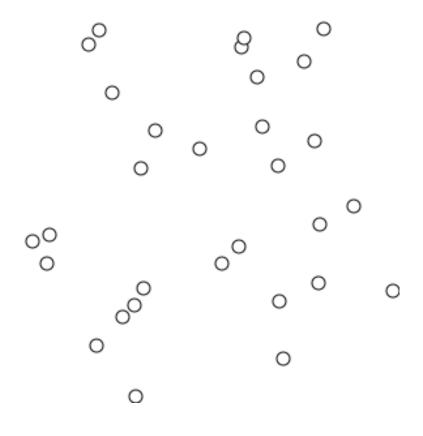
Tree edges	Sorted list of edges								Illustration		
	bc 1	ef 2	ab 3	bf 4	cf 4	af 5	df 5	ае 6	cd 6	de 8	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$
bc 1	bc 1	ef 2	ab 3	bf 4	cf 4	af 5	df 5	ae 6	cd 6	de 8	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$
ef 2	bc 1	ef 2	ab 3	bf 4	cf 4	af 5	df 5	ае 6	cd 6	de 8	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$



bf bc ef ab bf cf af **df** ae cd de 1 2 3 4 4 5 5 6 6 8



df 5



Courtesy - Shiyu Ji (Wikipedia)

Kruskal's Algorithm and its efficiency

ALGORITHM Kruskal(G)

```
//Kruskal's algorithm for constructing a minimum spanning tree //Input: A weighted connected graph G = \langle V, E \rangle //Output: E_T, the set of edges composing a minimum spanning tree of G sort E in nondecreasing order of the edge weights w(e_{i_1}) \leq \cdots \leq w(e_{i_{|E|}}) E_T \leftarrow \varnothing; ecounter \leftarrow 0 //initialize the set of tree edges and its size k \leftarrow 0 //initialize the number of processed edges while ecounter < |V| - 1 do k \leftarrow k + 1 if E_T \cup \{e_{i_k}\} is acyclic E_T \leftarrow E_T \cup \{e_{i_k}\}; ecounter \leftarrow ecounter + 1 return E_T
```

Time Complexity:

Where,
$$T_{check_acyclic} = T_{create_subsets} + T_{union_find}$$

$$T_{check_acyclic} = O(|V|) + O(|E| \log |E|) = O(|E| \log |E|)$$

and

$$T_{\text{sort_edges}} = O(|E| \log |E|)$$

Therefore, $T_{kruskal (worst case)} = O(|E| log |E|)$

Dijkstra's Algorithm

- It is applied to **Single source shortest problem**: for a given vertex called the source in weighted connected graph, find shortest paths to its other vertices.
- Introduced by Edsger W. Dijkstra in 1956.
- Applicable to both directed and undirected graphs with non-negative weights.

Applications:

- Transportation planning.
- Packet routing in communication networks.
- Shortest paths social networks, robotics, speech recognition, document formatting, robotics, compilers, airline crew scheduling.
- Path finding in video games, puzzles etc.

Dijkstra's Algorithm

It is similar to Prim's MST algorithm, with a different way of computing numerical labels:

Among vertices not already in the tree, it finds vertex u with the smallest sum

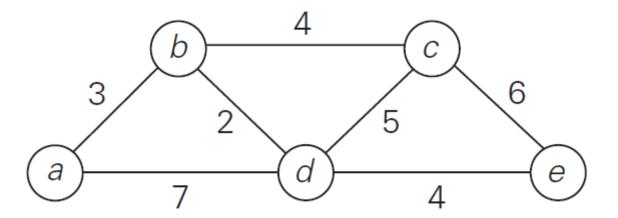
$$d_v + w(v,u)$$

Where,

- **v** is a vertex for which shortest path has been already found on preceding iterations (such vertices form a tree rooted at s)
- d_v is the length of the shortest path from source s to v
- w(v,u) is the length (weight) of edge from v to u

Dijkstra's Algorithm: Example

Apply Dijkstra's algorithm to the following graph to find the shortest paths from source vertex "a" to all other vertices.

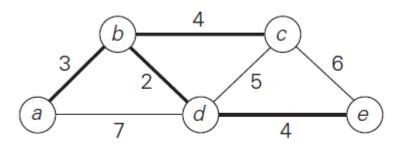


Dijkstra's Algorithm: Example

Tree vertices	Remaining vertices	Illustration
a(-, 0)	b (a , 3) $c(-, \infty) d(a, 7) e(-, \infty)$	3 2 4 C 6 F 6 P 7 P 8 P 8 P 8 P 8 P 8 P 8 P 8 P 8 P 8
b(a, 3)	$c(b, 3+4) d(b, 3+2) e(-, \infty)$	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$
d(b, 5)	c(b, 7) e(d, 5+4)	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$

Dijkstra's Algorithm: Example

c(b, 7) e(d, 9)



e(d, 9)

from a to b: a - b of length 3

from a to d: a - b - d of length 5

from a to c: a - b - c of length 7

from a to e: a - b - d - e of length 9

Dijkstra's Algorithm

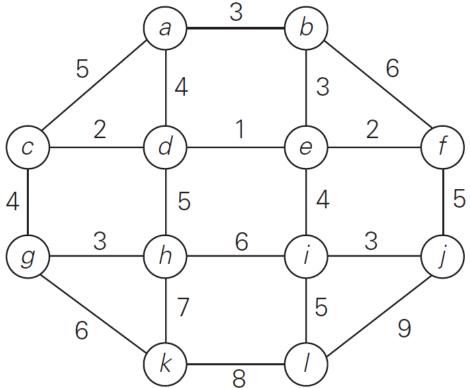
```
ALGORITHM Dijkstra(G, s)
     //Dijkstra's algorithm for single-source shortest paths
     //Input: A weighted connected graph G = \langle V, E \rangle with nonnegative weights
               and its vertex s
     //Output: The length d_v of a shortest path from s to v
                 and its penultimate vertex p_v for every vertex v in V
     Initialize(Q) //initialize priority queue to empty
     for every vertex v in V
         d_v \leftarrow \infty; p_v \leftarrow \text{null}
          Insert(Q, v, d_v) //initialize vertex priority in the priority queue
     d_s \leftarrow 0; Decrease(Q, s, d_s) //update priority of s with d_s
     V_T \leftarrow \varnothing
     for i \leftarrow 0 to |V| - 1 do
          u^* \leftarrow DeleteMin(Q) //delete the minimum priority element
          V_T \leftarrow V_T \cup \{u^*\}
          for every vertex u in V - V_T that is adjacent to u^* do
               if d_{u^*} + w(u^*, u) < d_u
                   d_u \leftarrow d_{u^*} + w(u^*, u); \quad p_u \leftarrow u^*
                    Decrease(Q, u, d_u)
```

Time Complexity is similar to Prim's Algorithm
If implemented using:

- Weighted adjacency matrix + array-based priority queue, the complexity is O(|V|²)
- Adjacency lists + Min-heap based priority queue, the complexity is O(|E| log |E|)

Exercise II

Apply Prim's, Kruskal's and Dijkstra's algorithms to the following graph (assume starting/source vertex as "a" for Prim's and Dijkstra's).



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26

Thank you!

Any queries?