

# Data Bus

- # It provides a medium for the exchange of data and information between various Avionics subsystems
- # Integration of Avionics subsystems in military or civil aircraft and spacecraft.

# TYPES OF PROTOCOLS

**Command/Response** : Centralized Control Method

**Token Passing** : Decentralized Control Method

**CSMA/CA** : Random Access Method

# Topology

**How the systems are interconnected in a particular fashion**

## **LINEAR NETWORK**

**Linear Cable**

**All the systems are connected in across the Cable**

## **RING NETWORK**

**Point to Point interconnection**

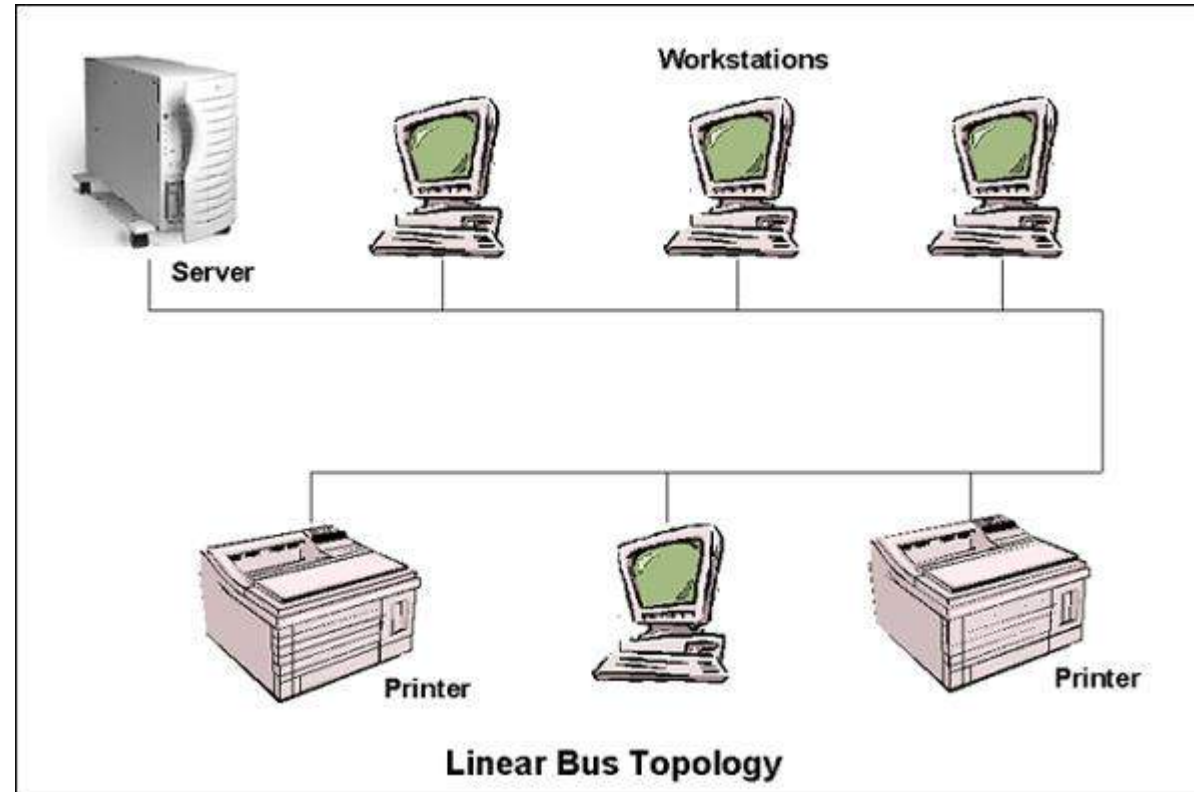
**Datas flow through the next system from previous system**

## **SWITCHED NETWORK**

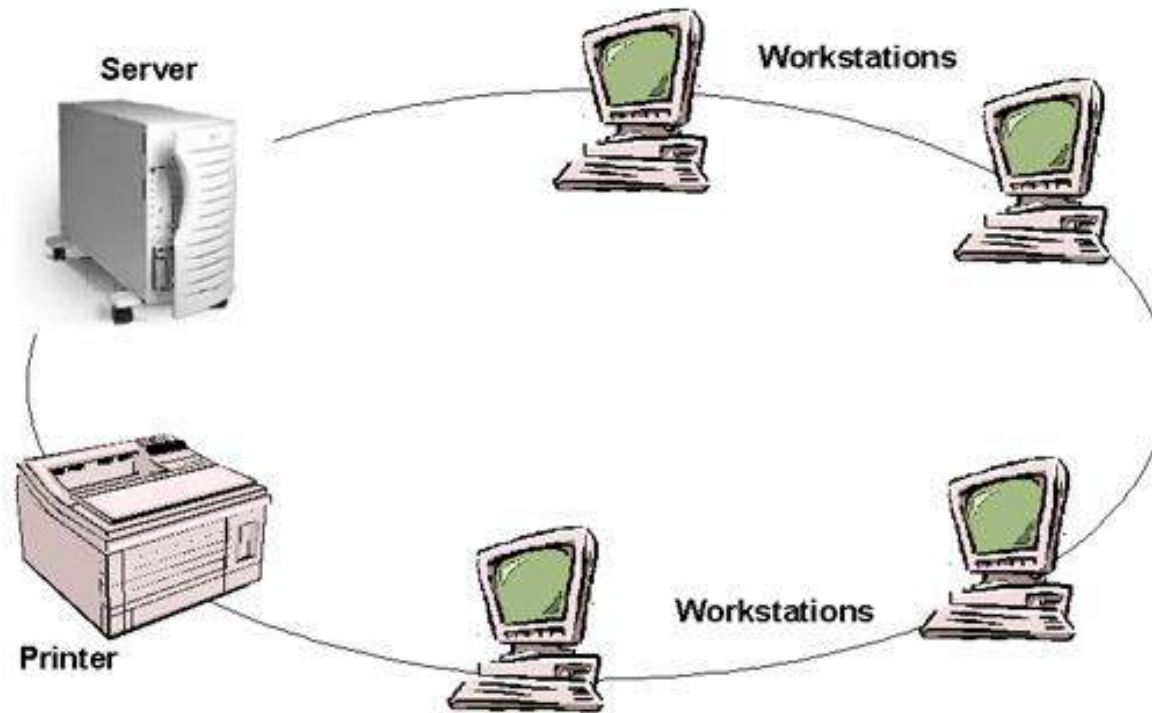
**Similar to telephone network**

**Provides communications paths between terminals**

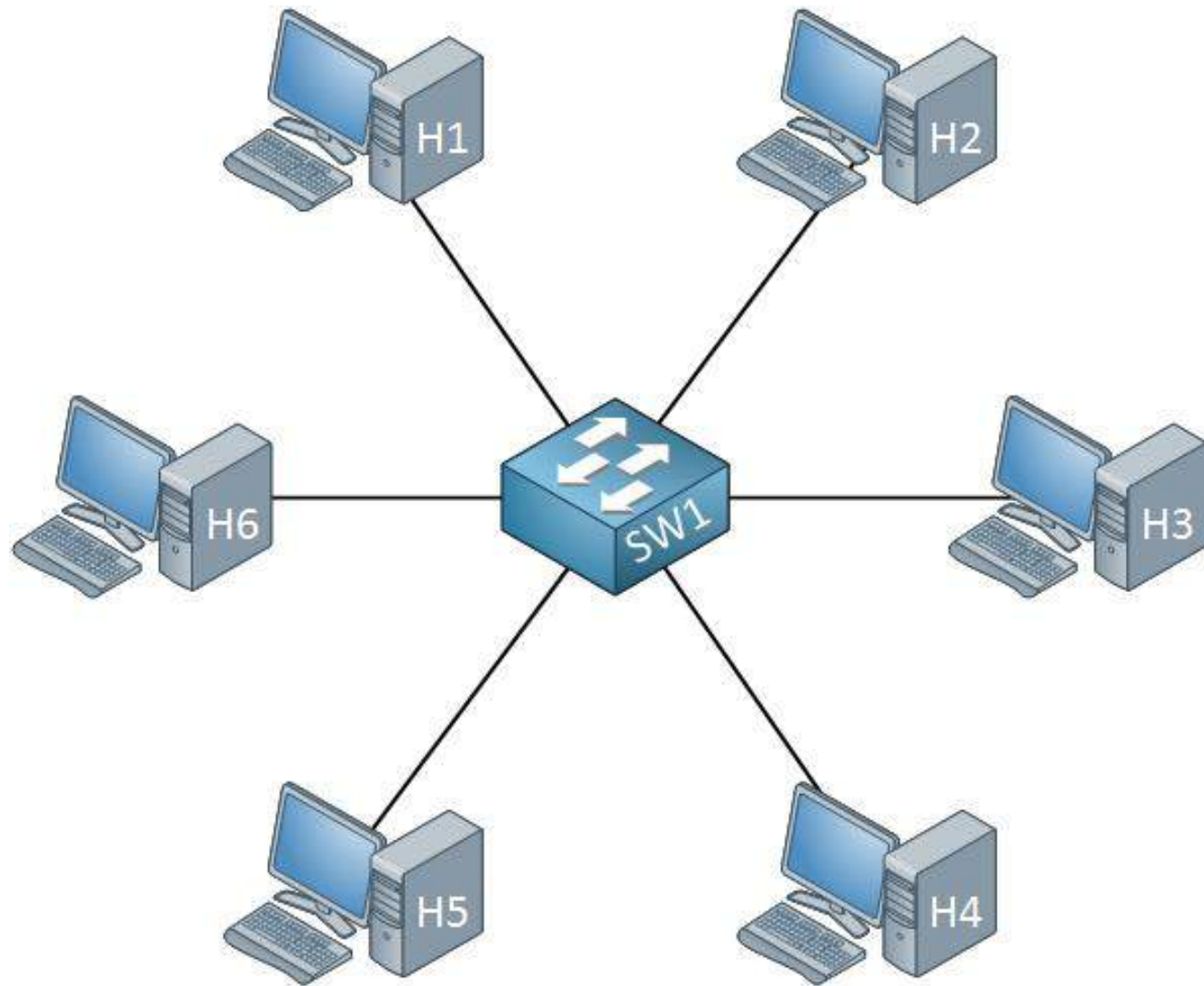
# Linear



# Ring



# Switched



**MIL-STD 1553B**

- **Developed at Wright Patterson Air Force Base in 1970s**
- **Published First Version 1553A in 1975**
- **Introduced in service on F-15 Program**
- **Published Second version 1553B in 1978**



● **MIL-STD-1553, *Command / Response Aircraft Internal Time Division Multiplex Data Bus***, is a Military standard which has become one of the basic tools being used today for integration of Avionics subsystems

● This standard describes the method of communication and the electrical interface requirements for the subsystems connected in the data bus

# SPECIFICATION OVERVIEW

**Data Rate**

**1 Mbps**

**Word Length**

**20 Bits**

**Message Length**

**32 Word Strings(maximum)**

**Data Bits per Word**

**16 Bits**

**Transmission Technique**

**Half - Duplex**

**Encoding**

**Manchester II Bi-phase**

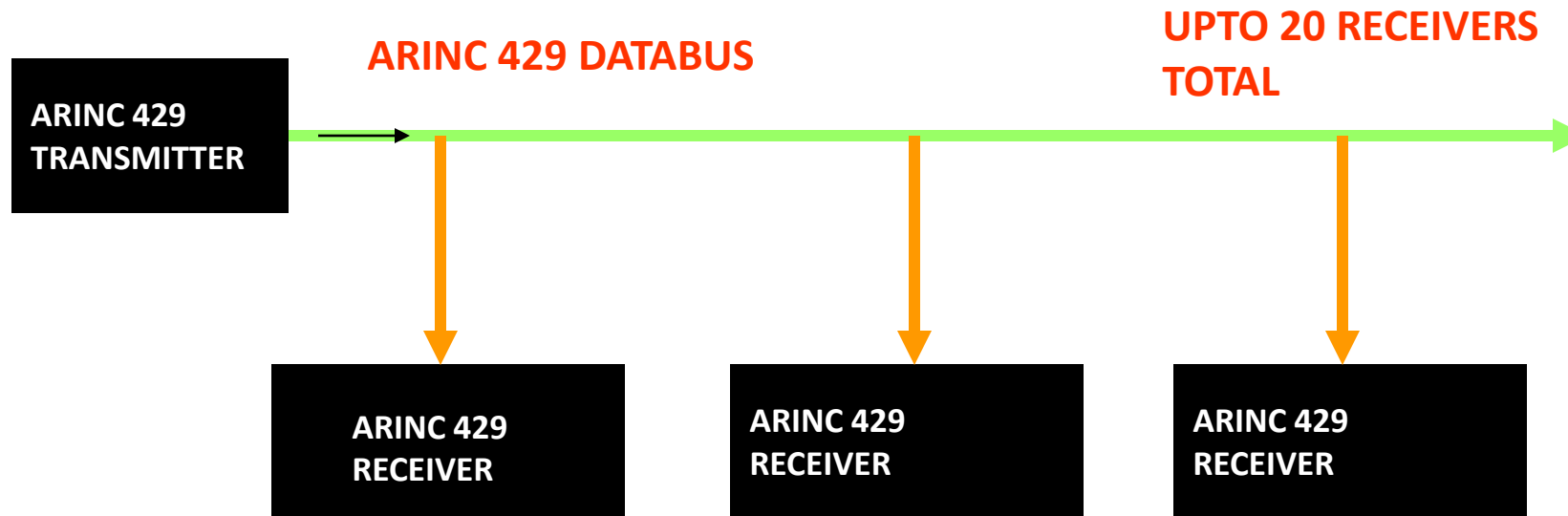
**Protocol**

**Command Response**

**Transmission Mode**

**Voltage Mode**

# ARINC 429



# ARNIC 629

**1977**      => Boeing began to work on “DATAC” project

**1977 - 85** => DATAC Emerged as ARINC 629

**1989**      => ARINC 629 was adopted by AEEC

**1990**      => ARINC 629 was first implemented in BOEING-777

# SPECIFICATION OVERVIEW

**Data Rate**

**2 Mbps**

**Word Length**

**20 Bits**

**Message Length**

**31 Word Strings(maximum)**

**Data Bits per Word**

**16 Bits**

**Transmission Technique**

**Half - Duplex**

**Encoding**

**Manchester II Bi-phase**

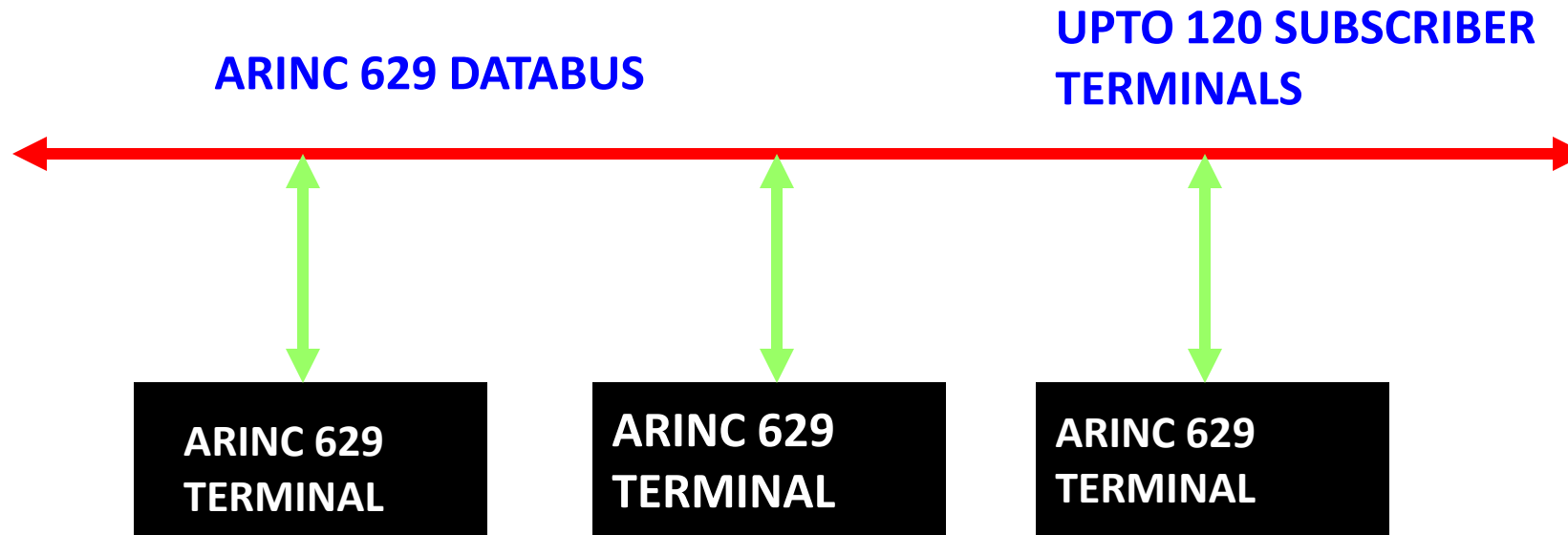
**Protocol**

**Carrier Sense Multiple Access  
Collision avoidance**

**Transmission Mode**

**Voltage Mode,Current Mode, Fiber Optic  
Mode**

# *ARNIC 629 ARCHITECTURE*



# *AFDX [ARNIC 664]*



**Avionics Fully Duplex Switched Ethernet** is an advanced Protocol Standard to interconnect avionics subsystems



It can accommodate future system bandwidth demands



Increase flexibility in Avionics design



Reduce aircraft wire counts, thus lowering aircraft weight and cost

- Since the Ethernet is a switched architecture rather than a point-point link, aircraft designers can create redundant sub networks
- Faults can be isolated and analysed without impacting the system as a whole
- ARINC 429 data bus may still be used but the main Avionics data pipe will be Ethernet (AFDX) of 100 Mbps



# HSDB

- Used in F-22 Advanced tactical fighter
- Generic version SAE Aerospace Standard 4074.1
- 50 Mbps- linear bus
- for optical medium implementation – star topology
- HSDB uses distributed control in which each terminal is permitted to transmit only when it receives the token frame.

# SCI

- IEEE –STD-1596-1992
- SCI is an interconnect system for both backplane and LAN usage.
- It is a system of rings and switches in its basic format
- Operates at 1 Gbps
- Electrical links upto 30m and optical links upto several kms.
- Same Bandwidth as today's 155Mbits/sec ATM links , 32 times that of today's fiber optic channel and 800 times that of Ethernet.

## Signaling Rate

1553B - 1Mbps

Ethernet(AFDX) - 100Mbps

ARINC 429 - 100Kbps or 12-14.5Kbps

ARINC 629 - 2Mbps

*MIL-STD 1553*

# WHY OPTICAL FIBER?

- Though 1553B is used in various modern aircraft, it is recognised that buses operate in extremely severe environment like
- EMI from intersystem and intrasystem
- Lightning
- Electrostatic discharge
- High Altitude Electromagnetic pulse

- Fiber-optic version of 1553B
- It also operates at the rate of 1Mbps
- It also have the same 20 bit word and three words such as command word, status word and data word
- stronger immunity to radiation-induced electromagnetic interference

# CAN BUS

- Controller Area Network (CAN) is the network Established among microcontrollers.
- Carrier-sense multiple access with collision avoidance (CSMA/CA) Protocol
- Two wire high speed network system which was firstly Established to overcome the problems (wire harness,Communication) faced in automobiles.
- Linked up to 2032 devices(assuming one node with one identifier) on a single network.
- CAN offers high speed communication up to 1 Mbps, thus allowing real time control.

# Digibus

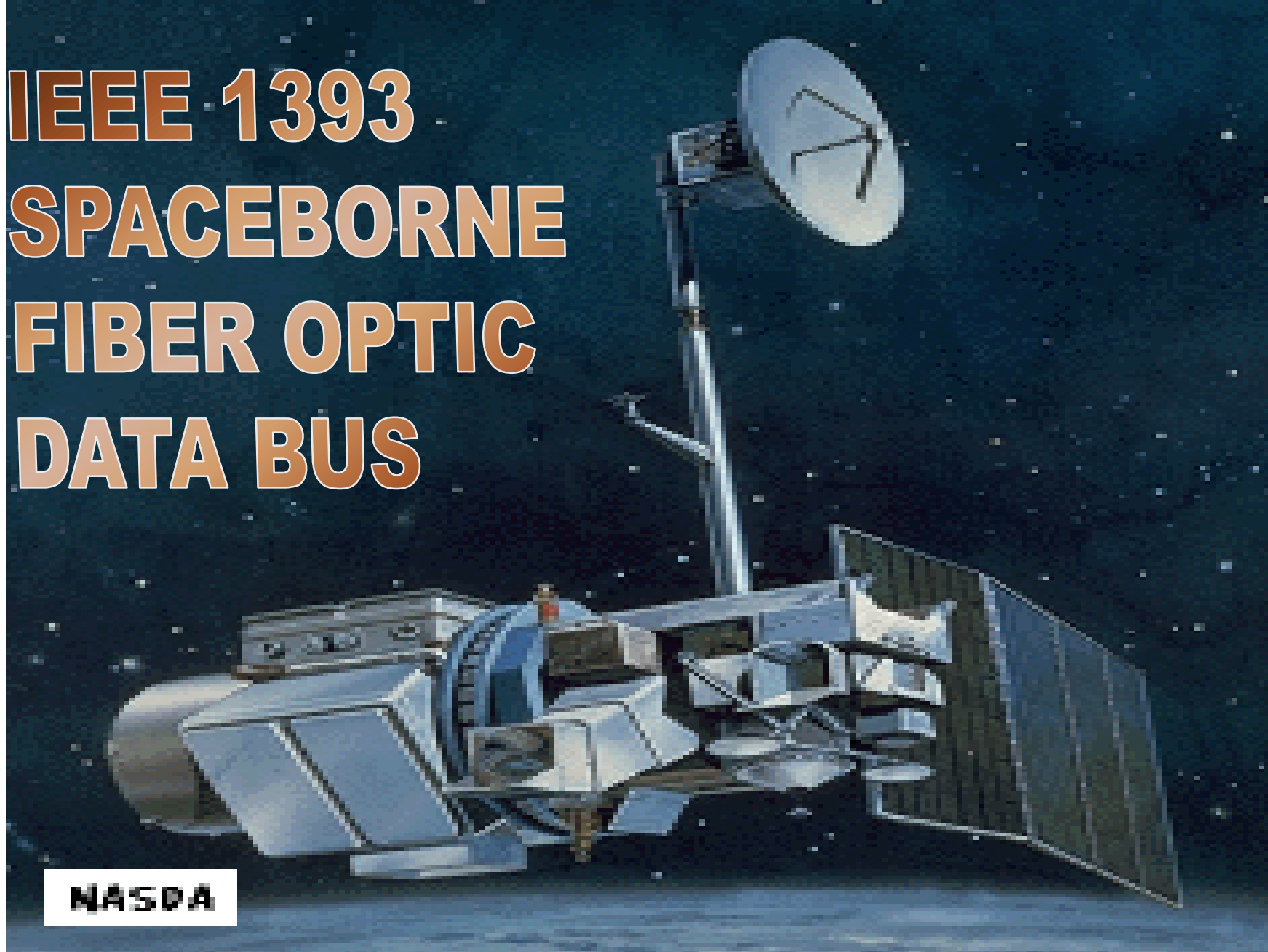
- Originally **Ginabus** (Gestion des Informations Numeriques Aeroportees – Airborne Digital Data Management)
- Designed jointly by Electronique Serge Dassault (ESD) and Avions Marcel Dassault- Breguet Aviation (AMD-BA) and SAGEM between 1973 and 76
- Digibus is now standard for all branches of French Military.





# **DATA BUSES IN SPACE APPLICATIONS**

# IEEE 1393 SPACEBORNE FIBER OPTIC DATA BUS



**NASDA**

# MDM DATA BUS

- Serial point to point communication

Between space shuttle payload general support computer and various subsystems

- MDM interface consists of a serial data bus and three discretes (Message in, Message out and word)
- Discrete contains the timing , direction and No. of words on the serial data bus

# **AVIONICS ARCHITECTURE**

# AVIONICS SYSTEM ARCHITECTURE

- Establishing the basic architecture is the first and the most fundamental challenge faced by the designer
- The architecture must conform to the overall aircraft mission and design while ensuring that the avionics system meets its performance requirements
- These architectures rely on the data buses for intra and intersystem communications
- The optimum architecture can only be selected after a series of exhaustive design tradeoffs that address the evaluation factors

# AVIONICS ARCHITECTURE

## First Generation Architecture ( 1940's –1950's)

- Disjoint or Independent Architecture ( MiG-21)
- Centralized Architecture (F-111)

## Second Generation Architecture ( 1960's –1970's)

- Federated Architecture (F-16 A/B)
- Distributed Architecture (DAIS)
- Hierarchical Architecture (F-16 C/D, EAP)

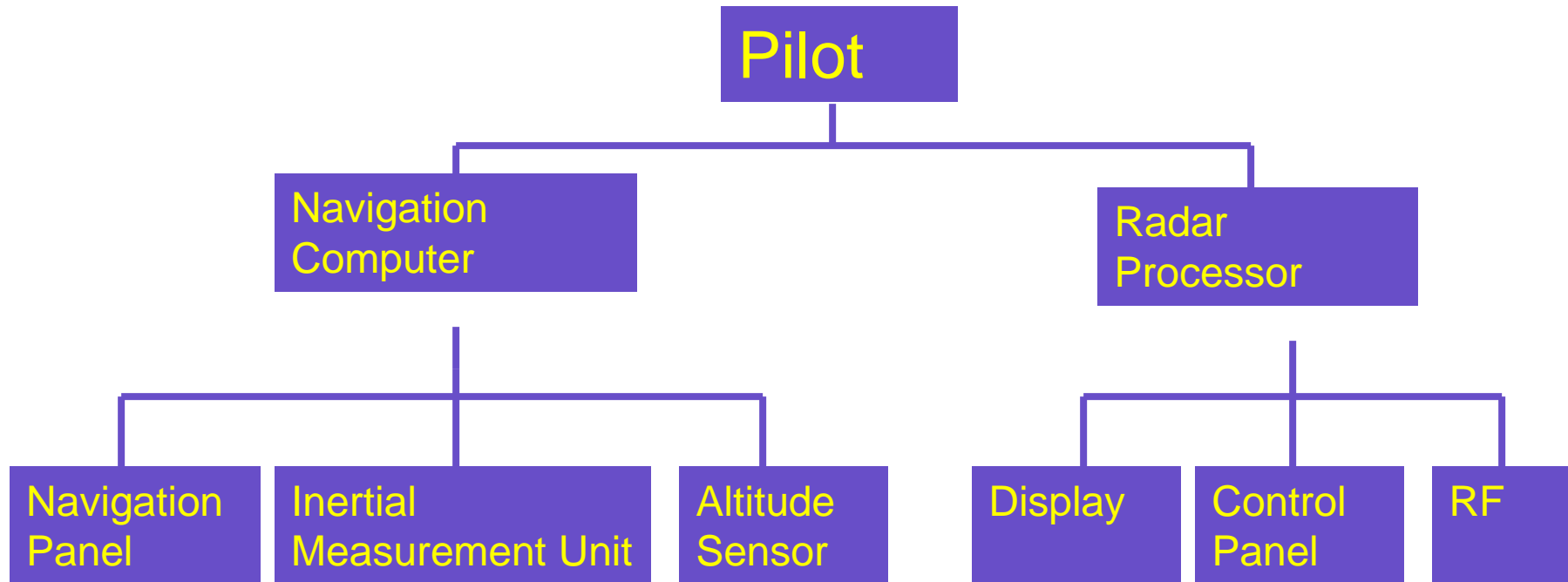
## Third Generation Architecture ( 1980's –1990's)

- Pave Pillar Architecture ( F-22)

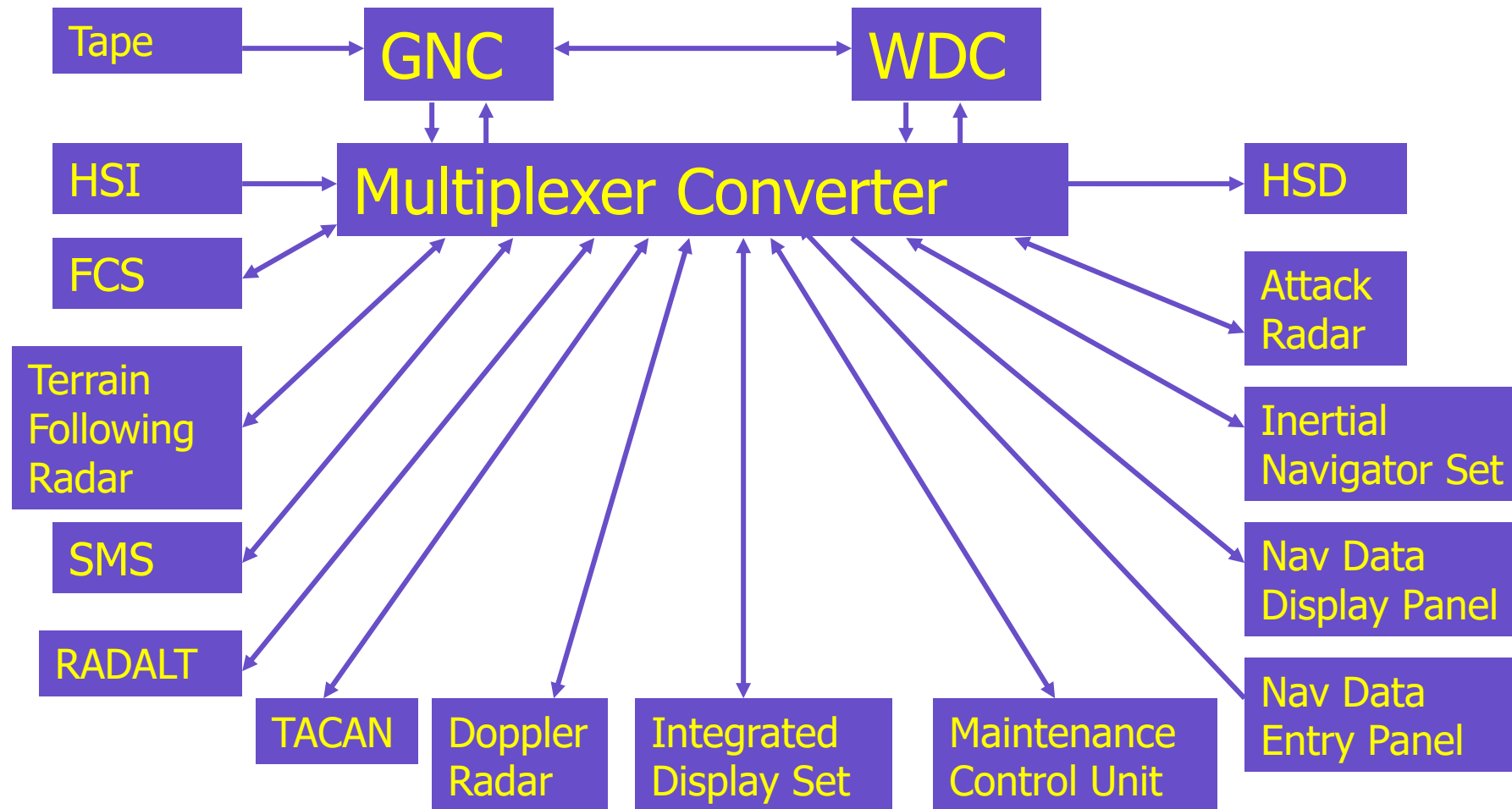
## Fourth Generation Architecture (Post 2005)

- Pave Pace Architecture- JSF
- Open System Architecture

## FGA - DISJOINT ARCHITECTURE

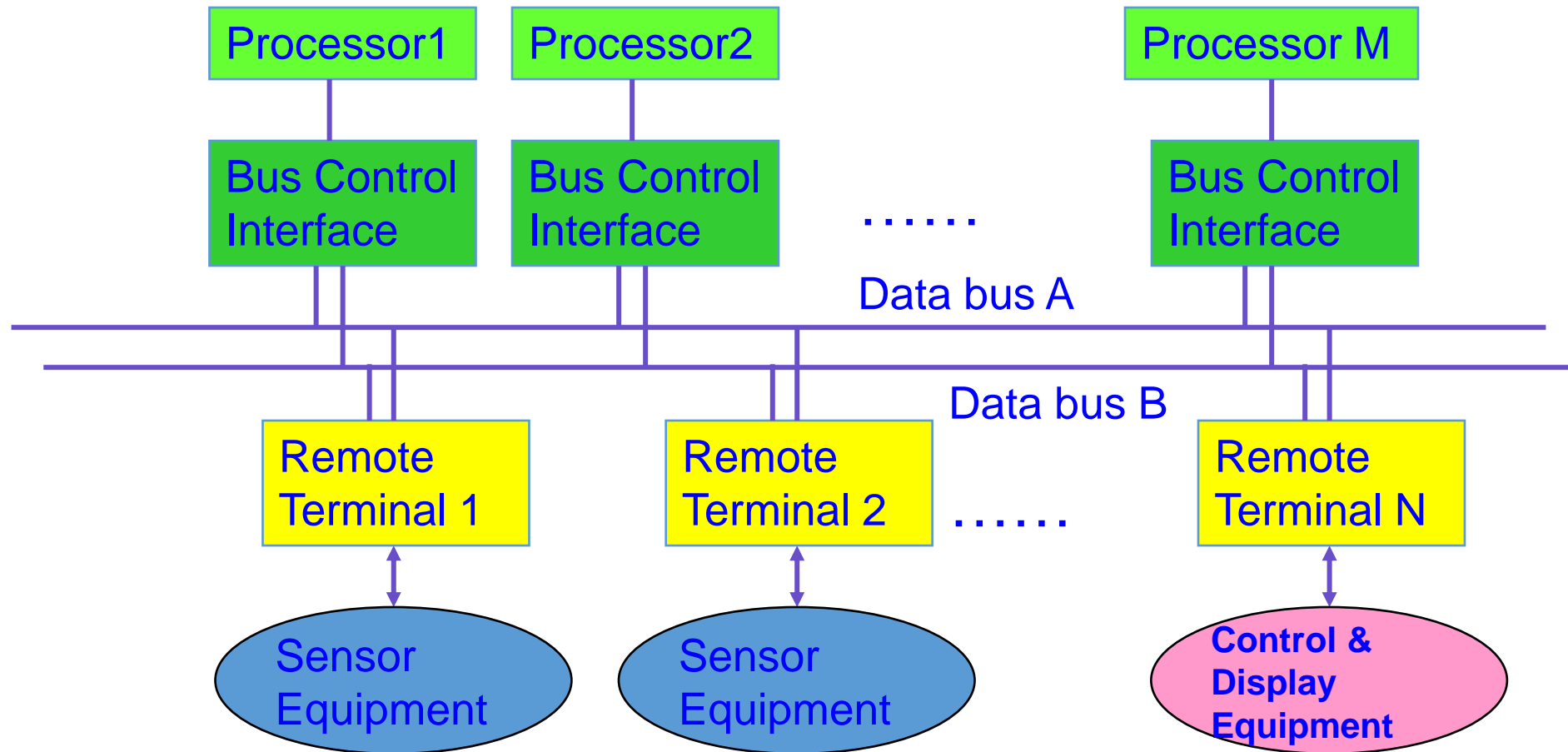


## FGA - CENTRALIZED ARCHITECTURE

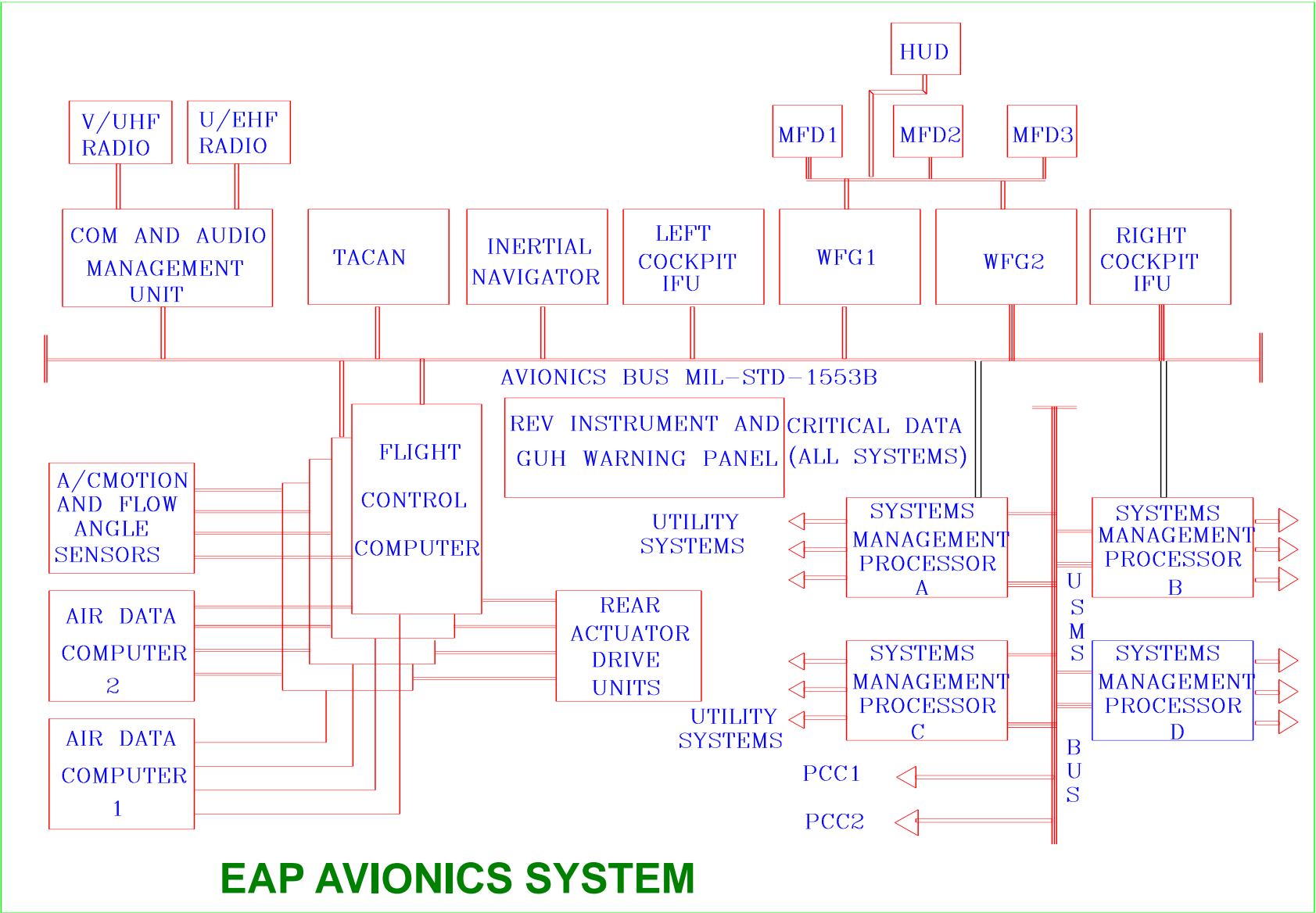




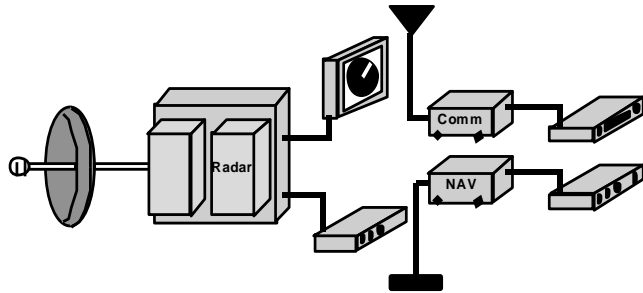
## SGA - DAIS HARDWARE ARCHITECTURE



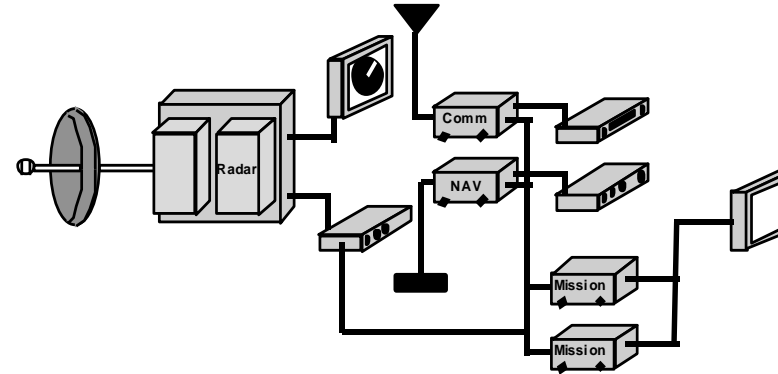
SGA - **HIERARCHICAL SYSTEM**



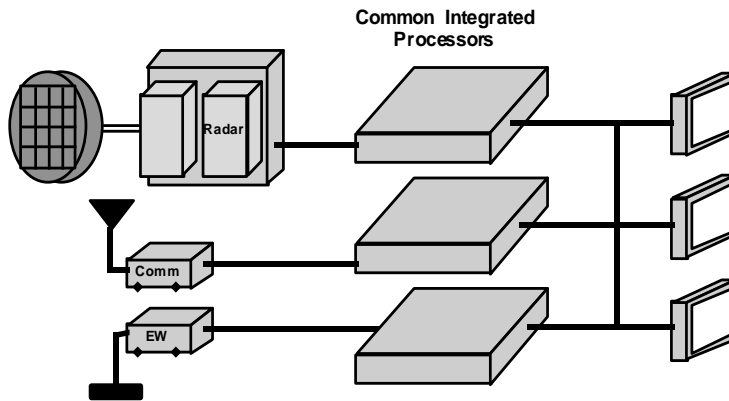
# AVIONICS SYSTEM EVOLUTION



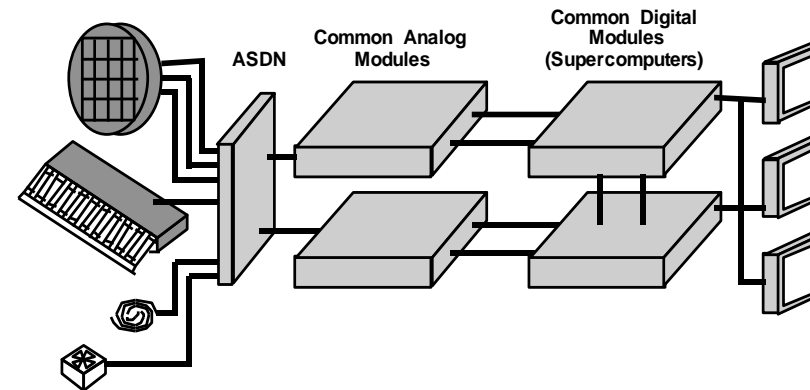
**Independent Avionics**  
(40's - 50's)



**Federated Avionics**  
(60's - 70's)



**Integrated Avionics**  
(80's - 90's)



**Advanced Integrated Avionics**  
(Post 2000)

## KEY OBSERVATIONS

### AVIONICS ARCHITECTURAL EVOLUTION

- Increased Digitization of Functions
- Increased sharing and modularization of functions
- Integration/ sharing concepts increased to the skin of the aircraft
- Functionality has increasingly obtained through software
- Complex hardware architecture modules
- Complex software modules
- Increased network complexity and speed

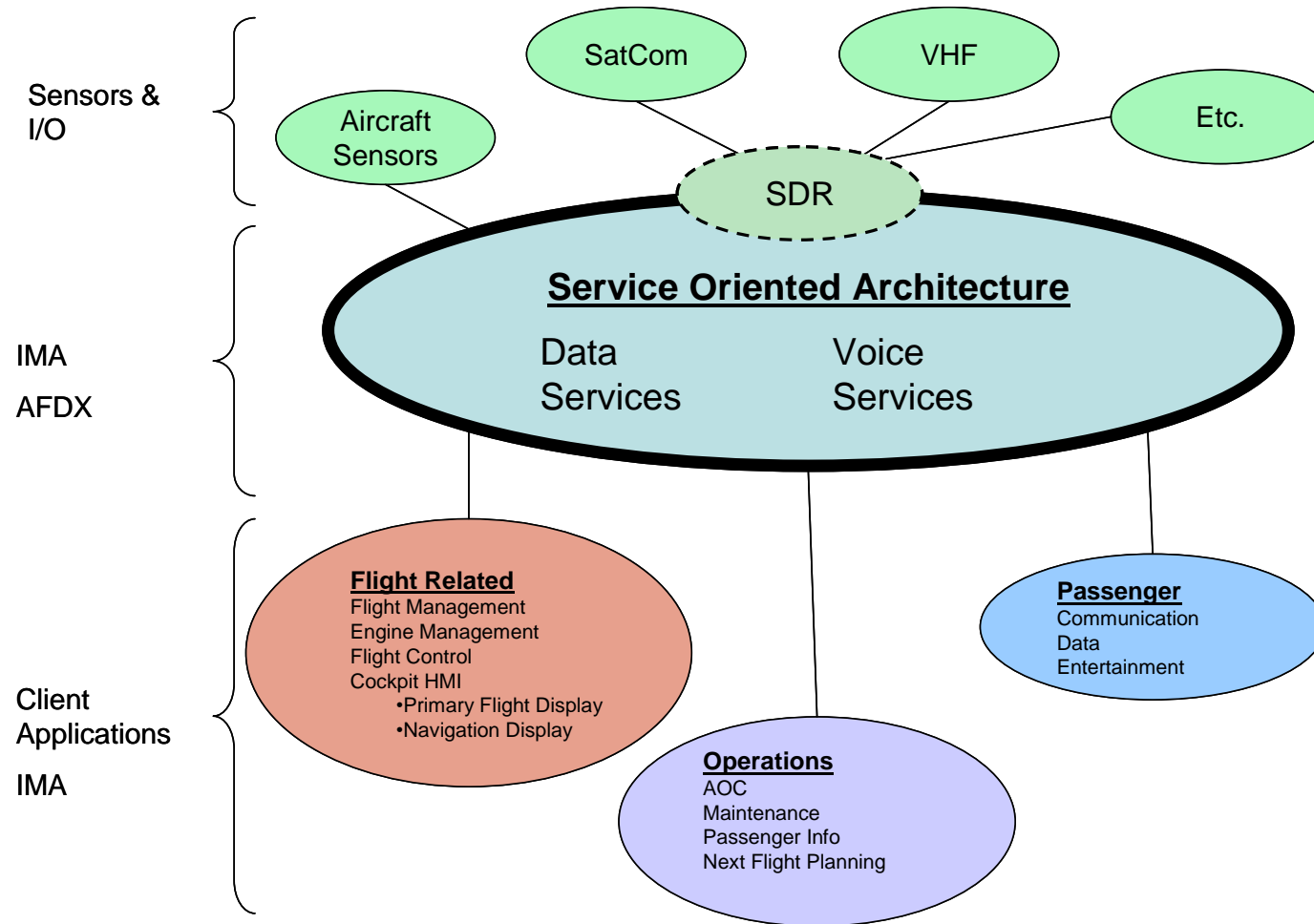
# Current avionics

- **Many Line Replaceable Units (LRU)**
  - Communication systems – multiple VHF radios, HF, satellite, etc
  - Similarly for navigation and surveillance
- **Multimode units will reduce unit count**
  - Multimode navigation system already
  - Multimode communications systems are expected
- **Integration of communication, navigation and surveillance data only takes place in the cockpit HMI and is performed by the pilot at the moment**
  - New architectures will enable closer information integration

# New aircraft architectures

- Boeing and Airbus have adopted new network-based approach to interconnection on their new aircraft – **B787 and A380**
  - Enabled through Integrated Modular Avionics (IMA)
- Flexible Application Environment
  - Data is shared more widely with a range of applications
  - Sensors provide data for use by a wide range of applications
- Service-oriented architecture (SOA)
  - Enables integration with current systems in a phased approach without any major architectural changes

# Future Avionics Architecture



Thank You