# Temperaturas em Manhattan

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**SME0205** 

#### **Problema**

$$\frac{\partial T(x,t)}{\partial t} = \alpha \frac{\partial^2 T(x,t)}{\partial x^2}$$

$$T(x+1) = T(x) + T'(x) + \frac{T''(x)}{2} + \frac{T^{(3)}(x)}{6} + \frac{T^{(4)}(x)}{24} + \cdots$$

$$T(x-1) = T(x) - T'(x) + \frac{T''(x)}{2} - \frac{T^{(3)}(x)}{6} + \frac{T^{(4)}(x)}{24} - \cdots$$

$$T(x-1) = T(x) - T'(x) + \frac{T''(x)}{2} - \frac{T^{(3)}(x)}{6} + \frac{T^{(4)}(x)}{24} - \cdots$$

Série de Taylor

$$T(x+1) + T(x-1) = 2T(x) + T''(x) + \frac{T^{(4)}(x)}{12} + \cdots$$

$$T''(x) = T(x+1) - 2T(x) + T(x-1) - \mathcal{O}(1)$$

$$\frac{dT_i(t)}{dt} = \alpha(T_{i+1}(t) - 2T_i(t) + T_{i-1}(t))$$

#### **Problema**

$$LT = \begin{pmatrix} \begin{bmatrix} G_1 & 0 & 0 & \cdots & 0 \\ 0 & G_2 & 0 & \cdots & 0 \\ 0 & 0 & G_3 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & G_n \end{bmatrix} - \begin{bmatrix} & & & \\ & & & \\ & & & \\ & & & \end{bmatrix} \begin{pmatrix} T_1 \\ T_2 \\ T_3 \\ \vdots \\ T_n \end{pmatrix}_{n \times n} = \begin{bmatrix} C_1 \\ C_2 \\ C_3 \\ \vdots \\ C_n \end{bmatrix}_{n \times n}$$

$$C_i = G_i T_i - \sum_{j \to i} T_j$$

$$\frac{dT_i(t)}{dt} = \alpha(T_{i+1}(t) - 2T_i(t) + T_{i-1}(t)) = -\alpha(2T_i(t) - T_{i-1}(t) - T_{i+1}(t)) = -\alpha(G_iT_i(t) - \sum_{j \to i} T_j(t)) = -\alpha(LT)_i$$

$$\frac{dT}{dt} = -\alpha LT$$

$$(L+P)T = Pb$$

#### Métodos Diretos

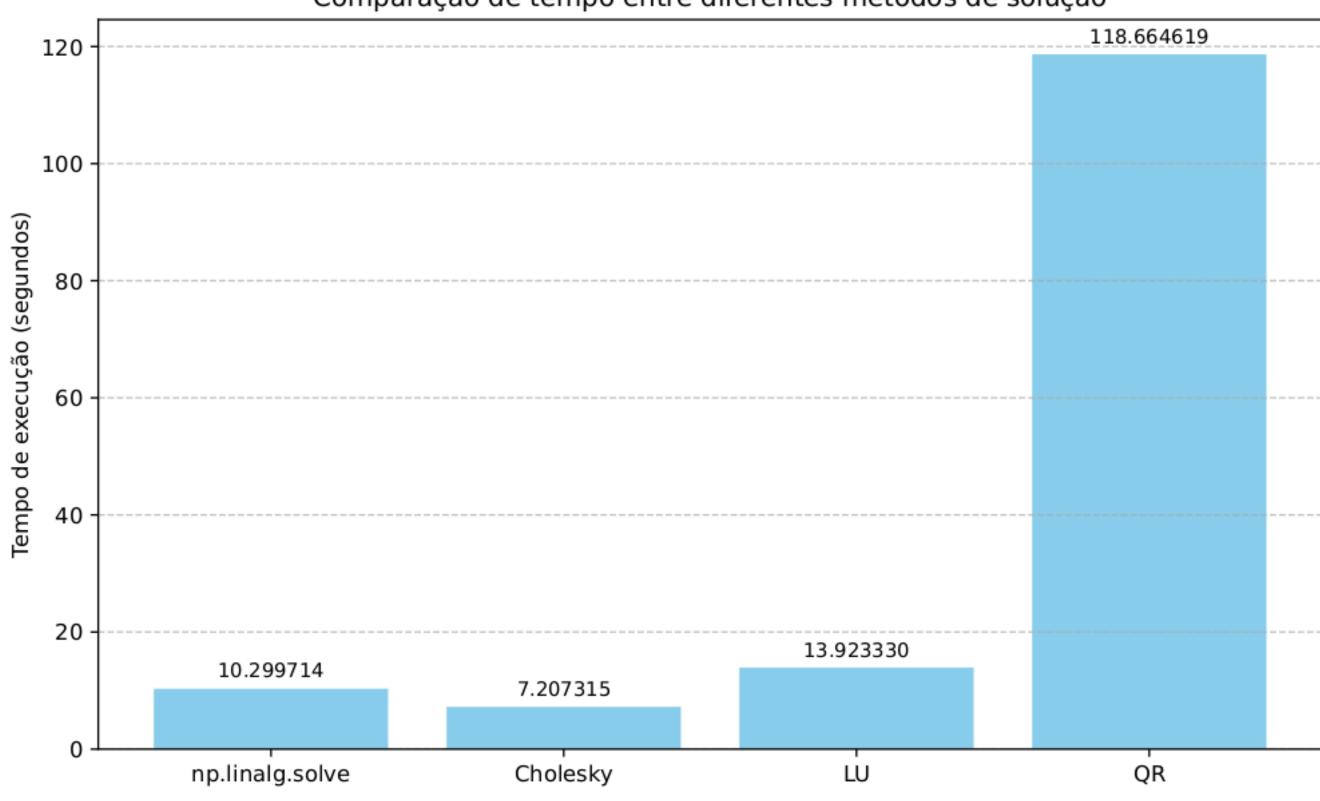
Cholesky: 
$$M = LL^T \longrightarrow O(\frac{1}{3}N^3)$$
 
$$Mx = k$$
 
$$(LL^T)x = k \quad \begin{cases} y = L^Tx \\ Ly = k \end{cases}$$
 LU:  $M = PLU \longrightarrow O(\frac{2}{3}N^3)$  
$$MT = c$$
 
$$PLUT = c \quad \begin{cases} UT = y \\ Ly = Pc \end{cases}$$

#### Métodos Diretos

QR: 
$$M=QR \longrightarrow O(\frac{4}{3}N^3)$$
 
$$MT=c$$
 
$$QRT=c \qquad Q^T(QRT)=Q^Tc$$
 
$$(Q^TQ)RT=Q^Tc$$
 
$$IRT=Q^Tc$$
 
$$RT=Q^Tc$$

### Métodos Diretos - Tempos

Comparação de tempo entre diferentes métodos de solução



#### Métodos Iterativos

Gauss-Jacobi:

$$Mx = c$$
  $D$  é a diagonal de  $M$  
$$(M - D + D)x = c$$
 
$$(M - D)x + Dx = c$$
 
$$(M - D)x^{(k)} + Dx^{(k+1)} = c$$
 
$$Dx^{(k+1)} = (D - M)x^{(k)} + c$$
 
$$x^{(k+1)} = D^{-1}(D - M)x^{(k)} + D^{-1}c$$
 
$$x^{(k+1)} = (I - D^{-1}M)x^{(k)} + D^{-1}c$$
 
$$x^{(k+1)} = Cx^{(k)} + q$$

#### Métodos Iterativos

Gauss-Seidel:

$$Mx = c$$

$$(L+R)x = c$$

$$Lx + Rx = c$$

$$Lx^{(k+1)} + Rx^{(k)} = c$$

$$Lx^{(k+1)} = -Rx^{(k)} + c$$

$$x^{(k+1)} = (-L^{-1}R)x^{(k)} + L^{-1}c$$

$$x^{(k+1)} = Cx^{(k)} + g$$

L é a matriz triangular inferior de M e R, a triangular superior sem a diagonal

#### Métodos Iterativos

#### Gradientes Conjugados:

$$f(x) = \frac{1}{2}x^T M x - c^T x$$

$$\nabla f(x) = Mx - c$$

- 1. Chute inicial  $x_0$ ;
- 2.  $p_0 = r_0 = c Mx_0$ ;
- 3.  $\alpha = \frac{r_k^T \cdot r_k}{p_k^T \cdot M \cdot p_k};$
- 4.  $x_{k+1} = x_k + \alpha p_k$ ;
- 5.  $r_{k+1} = r_k \alpha(M \cdot p_k);$
- 6.  $\beta = \frac{r_{k+1}^T \cdot r_{k+1}}{r_k^T \cdot r_k};$
- 7.  $p_{k+1} = r_{k+1} + \beta p_k$ ;
- 8. Volta para o passo 3, enquanto  $||r_{k+1}|| > \text{tol.}$

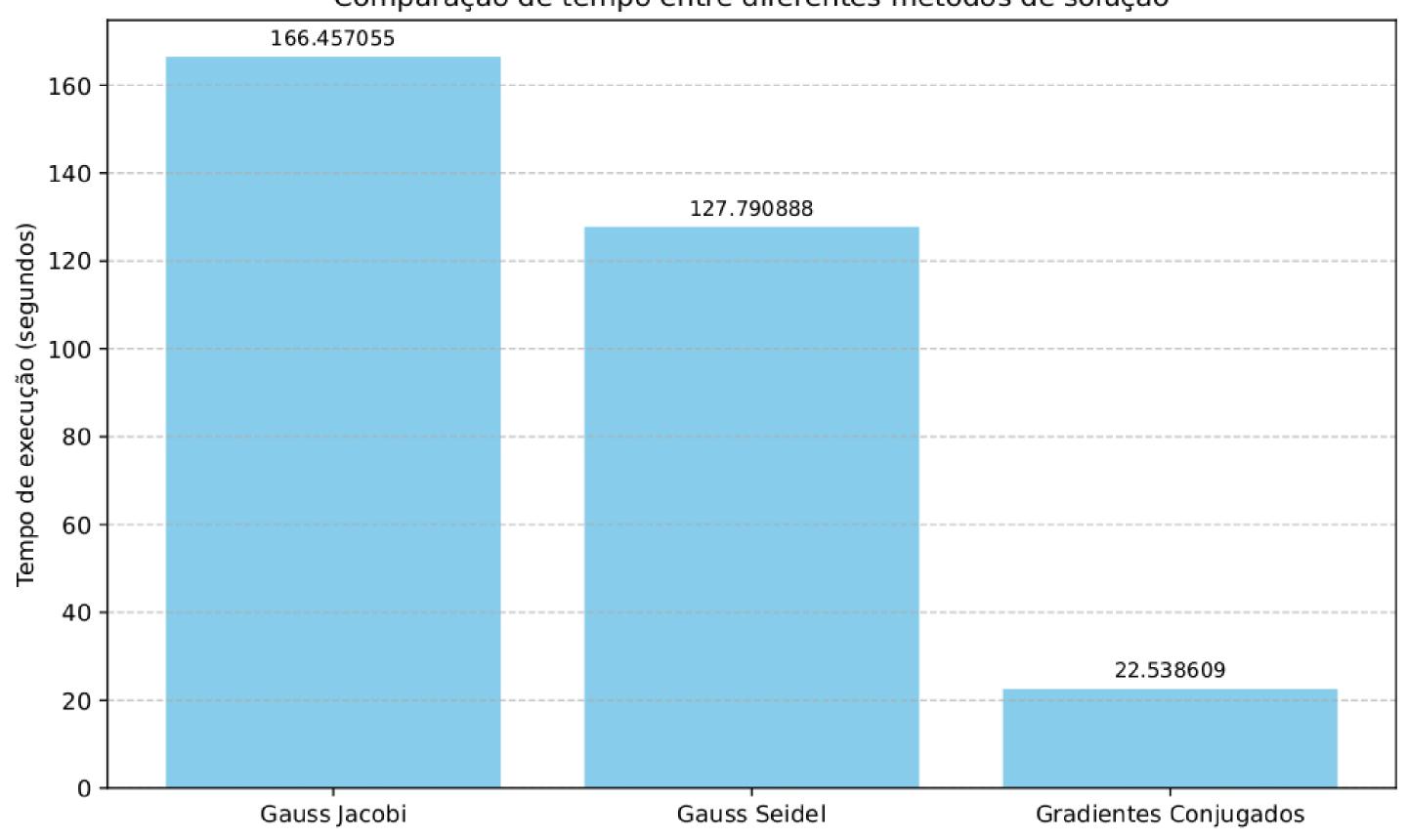
## Métodos Iterativos - Tempos

Tolerância:  $\pm 10^{-3}$ .

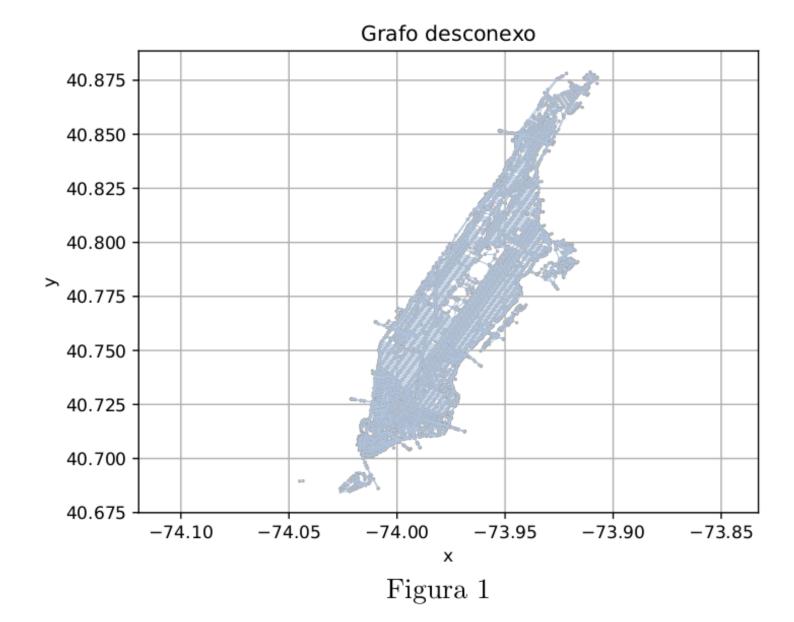
	Gauss-Jacobi	Gauss-Seidel	Gradientes Conjugados
k	1280	657	255
tempo	3min	2min	30s

### Métodos Iterativos - Tempos

Comparação de tempo entre diferentes métodos de solução



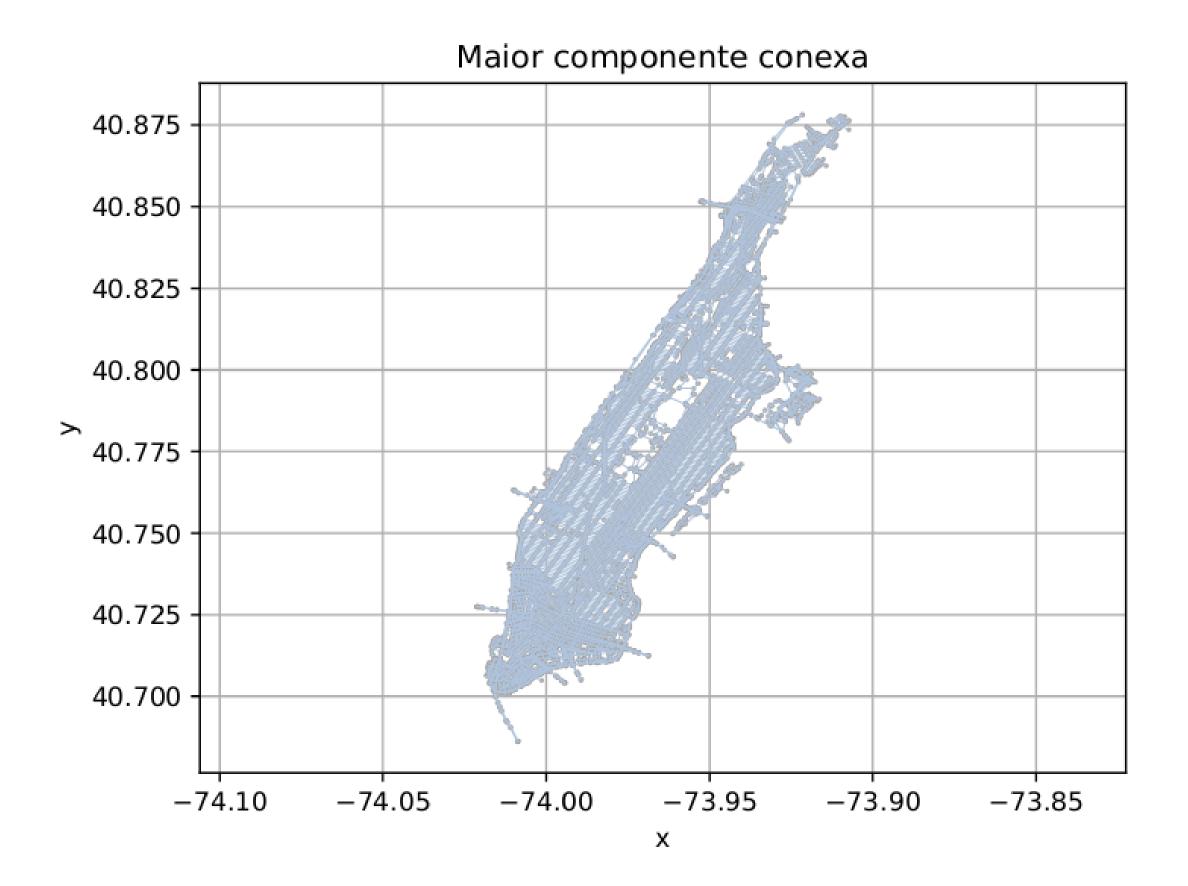
#### Resultados



Componente conexa 2 Componente conexa 3 Componente conexa 1 40.6975 40.69050 -40.875 0.69025 40.850 40.6950 40.69000 40.825 40.6925 40.68975 40.800 40.6900 40.68950 40.775 40.6875 40.68925 40.750 40.6850 40.68900 -40.725 40.6825 40.68875 -40.700 40.6800 -74.05074.02574.00073.97573.95073.92573.900 -74.02674.02474.02274.02074.01474.01674.01474.012 -0.00500.00470.00450.00420.00400.00370.00350 Componente conexa 5 +4.087el Componente conexa 4 1e-5+4.07044e1 0.00900 0.00875 0.00850 0.00800 0.00775 0.00750 -0.002000.001750.001500.001250.001040.00075 -9.0 -8.5 -8.0 -7.5 -7.0 -6.5 -6.0 -5.5 -7.391e1 1e-5-7.39936e1

-7.404e1

### Resultados



#### Resultados

