

Temperaturas em Manhattan

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MÉTODOS DE CÁLCULO NUMÉRICO I

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1 Modelagem do Problema

2 Métodos diretos

- Tempos
- Erros

3 Métodos iterativos

- Tempos
- Erros

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Modelagem do problema

$$\frac{\partial T(x, t)}{\partial t} = \alpha \frac{\partial^2 T(x, t)}{\partial x^2}$$

$$T(x+1) = T(x) + T'(x) + \frac{T''(x)}{2} + \frac{T^{(3)}(x)}{6} + \frac{T^{(4)}(x)}{24} + \dots$$

$$T(x-1) = T(x) - T'(x) + \frac{T''(x)}{2} - \frac{T^{(3)}(x)}{6} + \frac{T^{(4)}(x)}{24} - \dots$$

$$T(x+1) + T(x-1) = 2T(x) + T''(x) + \frac{T^{(4)}(x)}{12} + \dots$$

$$T''(x) = T(x+1) - 2T(x) + T(x-1) - \mathcal{O}(1)$$

$$\frac{dT_i(t)}{dt} = \alpha(T_{i+1}(t) - 2T_i(t) + T_{i-1}(t))$$

Modelagem do problema

$$LT = \left(\begin{bmatrix} G_1 & 0 & \cdots & 0 \\ 0 & G_2 & \cdots & 0 \\ 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & G_n \end{bmatrix} - \begin{bmatrix} & & & \\ & & & \\ & & & \\ & & & \\ & & & \end{bmatrix} \right)_{n \times n} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \\ \vdots \\ T_n \end{bmatrix}_{n \times 1} = \begin{bmatrix} C_1 \\ C_2 \\ C_3 \\ \vdots \\ C_n \end{bmatrix}_{n \times 1}$$

$$C_i = G_i T_i - \sum_{j \rightarrow i} T_j$$

$$\frac{dT_i(t)}{dt} = -\alpha C_i = -\alpha (LT)_i$$

$$\frac{dT}{dt} = -\alpha LT$$

$$0 = \alpha LT \iff \alpha LT = b \iff (L + P)T = Pb$$

$$\text{Cholesky: } M = L \cdot L^T \longrightarrow \mathcal{O}\left(\frac{1}{3}n^3\right)$$

$$M \cdot T = c$$

$$(L \cdot L^T) \cdot T = c \quad \left\{ \begin{array}{l} y = L^T \cdot T \\ L \cdot y = c \end{array} \right.$$

$$\text{LU: } P \cdot M = L \cdot U \longrightarrow \mathcal{O}\left(\frac{2}{3}n^3\right)$$

$$M \cdot T = c$$

$$P \cdot M \cdot T = P \cdot c$$

$$(L \cdot U) \cdot T = P \cdot c \quad \left\{ \begin{array}{l} y = U \cdot T \\ L \cdot y = P \cdot c \end{array} \right.$$

$$\text{QR: } M = Q \cdot R \longrightarrow \mathcal{O}\left(\frac{4}{3}n^3\right)$$

$$M \cdot T = c$$

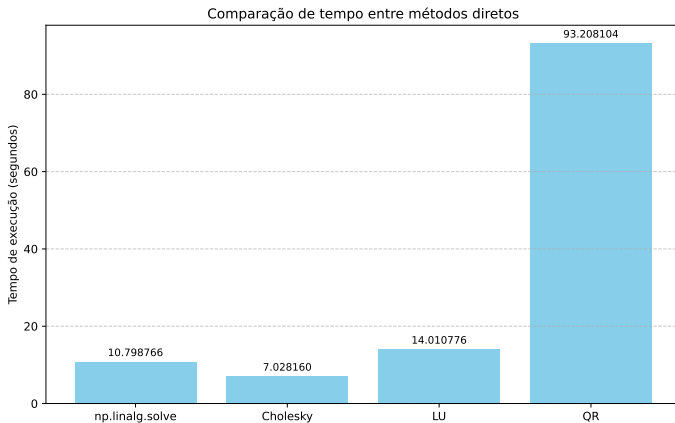
$$(Q \cdot R) \cdot T = c$$

$$Q^T \cdot (Q \cdot R \cdot T) = Q^T \cdot c$$

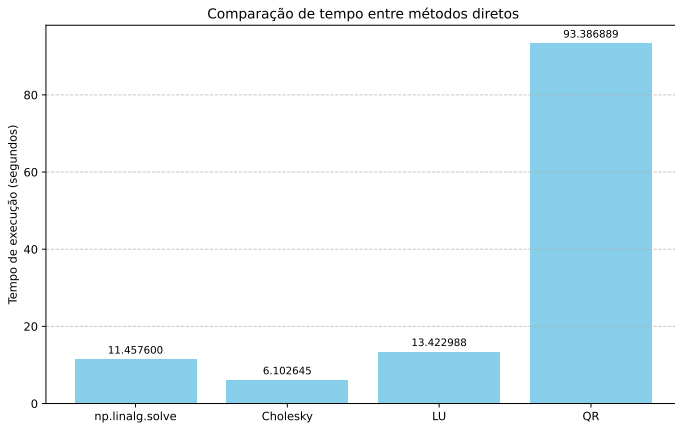
$$(Q^T \cdot Q) \cdot R \cdot T = Q^T \cdot c$$

$$R \cdot T = Q^T \cdot c$$

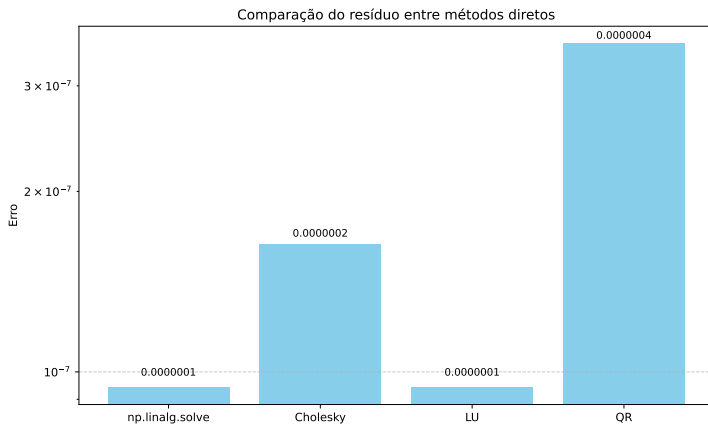
Quando fixamos 9 pontos dentre os 8708, obtemos



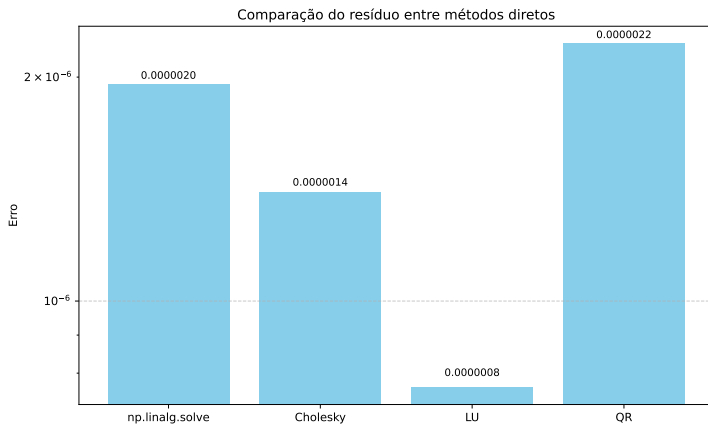
Quando fixamos 435 pontos dentre os 8708, obtemos



Quando fixamos 9 pontos dentre os 8708, obtemos



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Se fizermos D a matriz diagonal de M , temos

Gauss-Jacobi: $M \cdot T = c$

$$(M - D + D) \cdot T = c$$

$$(M - D) \cdot T + D \cdot T = c$$

$$(M - D) \cdot T^{(k)} + D \cdot T^{(k+1)} = c$$

$$D \cdot T^{(k+1)} = (D - M) \cdot T^{(k)} + c$$

$$T^{(k+1)} = D^{-1} \cdot (D - M) \cdot T^{(k)} + D^{-1} \cdot c$$

$$T^{(k+1)} = (I - D^{-1} \cdot M) \cdot T^{(k)} + D^{-1} \cdot c$$

$$T^{(k+1)} = C \cdot T^{(k)} + g$$

Se fizermos L a matriz diagonal inferior de M e R , a triangular superior sem a diagonal, temos

Gauss-Seidel:

$$\begin{aligned}M \cdot T &= c \\(L + R) \cdot T &= c \\L \cdot T + R \cdot T &= c \\L \cdot T^{(k+1)} + R \cdot T^{(k)} &= c \\L \cdot T^{(k+1)} &= -R \cdot T^{(k)} + c \\T^{(k+1)} &= (-L^{-1} \cdot R) \cdot T^{(k)} + L^{-1} \cdot c \\T^{(k+1)} &= C \cdot T^{(k)} + g\end{aligned}$$

Gradientes Conjugados:

1. Chute inicial x_0 ;

2. $p_0 = r_0 = c - Mx_0$;

3. $\alpha = \frac{r_k^T \cdot r_k}{p_k^T \cdot M \cdot p_k}$;

$$f(x) = \frac{1}{2}x^T Mx - c^T x$$

4. $x_{k+1} = x_k + \alpha p_k$;

$$\nabla f(x) = Mx - c$$

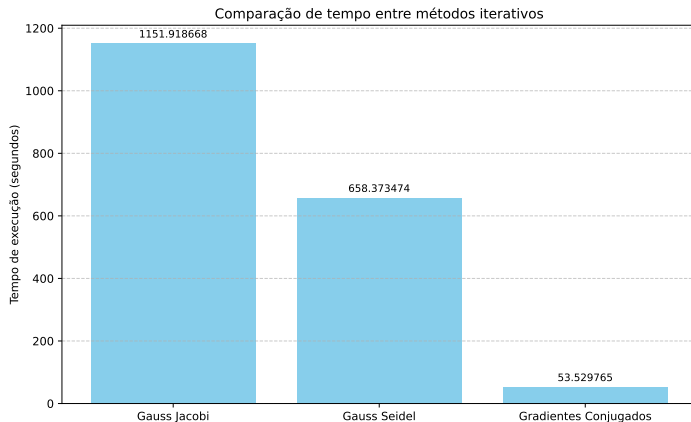
5. $r_{k+1} = r_k - \alpha(M \cdot p_k)$;

6. $\beta = \frac{r_{k+1}^T \cdot r_{k+1}}{r_k^T \cdot r_k}$;

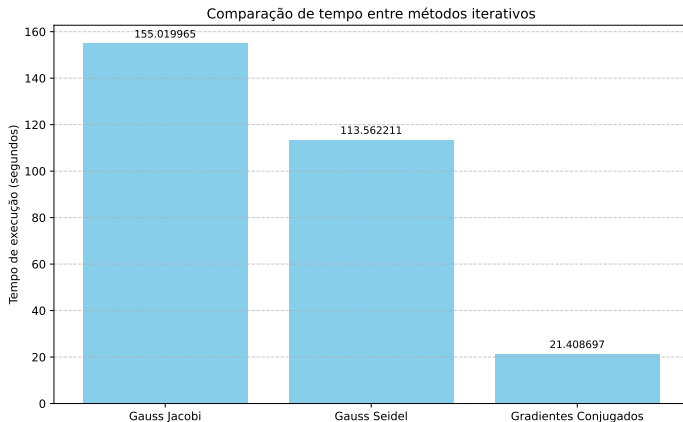
7. $p_{k+1} = r_{k+1} + \beta p_k$;

8. Volta para o passo 3, enquanto $\|r_{k+1}\| > \text{tol}$.

Quando fixamos 9 pontos dentre os 8708 e uma tolerância de 10^{-1} , obtemos



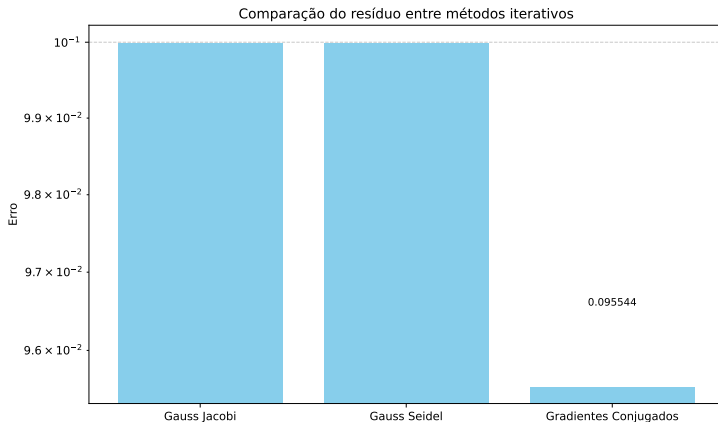
Quando fixamos 435 pontos dentre os 8708 e uma tolerância de 10^{-3} , obtemos



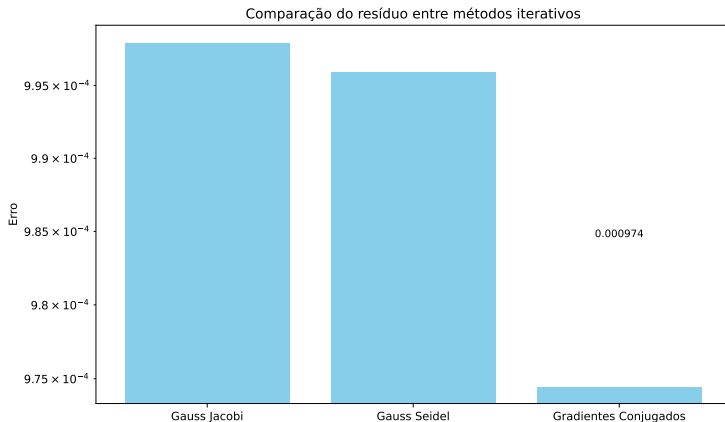
Obtivemos também a quantidade de passos necessários para convergir

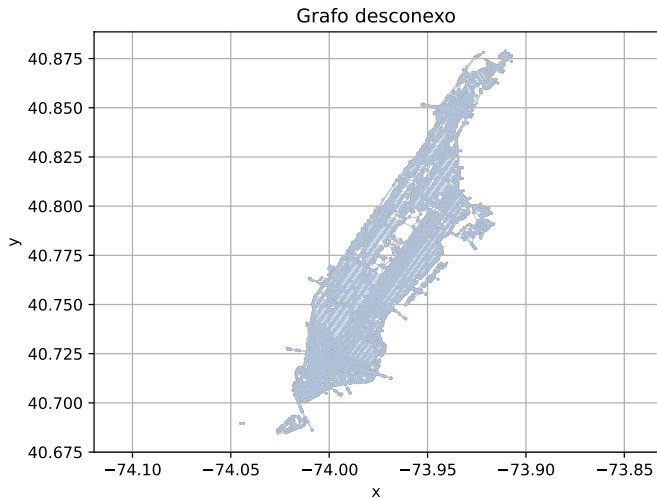
Pontos	Tolerância		Gauss-Jacobi	Gauss-Seidel	Gradientes Conjugados
9	10^{-1}	k	13000	7129	630
		t	19 min	11 min	1 min
435	10^{-3}	k	1261	647	251
		t	3 min	2 min	30 s

Quando fixamos 9 pontos dentre os 8708 e uma tolerância de 10^{-1} , obtemos

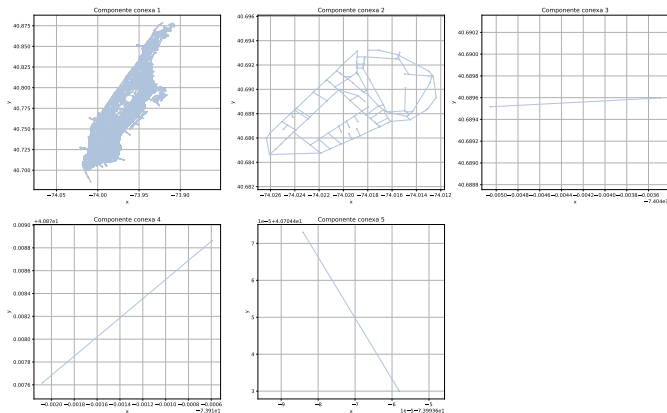


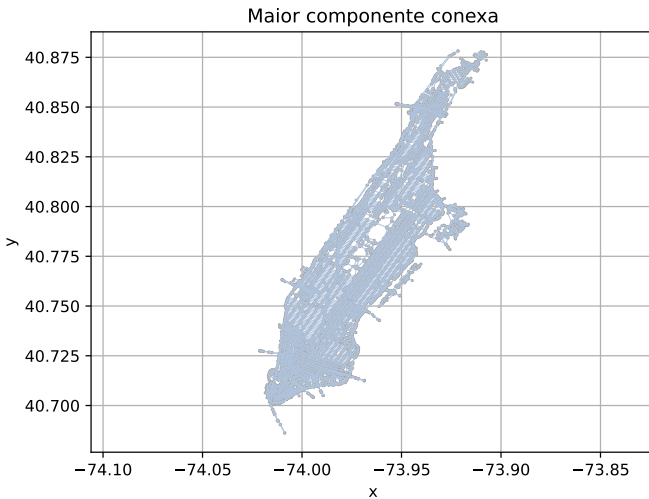
Quando fixamos 435 pontos dentre os 8708 e uma tolerância de 10^{-3} , obtemos



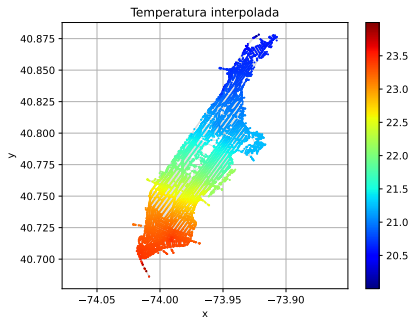
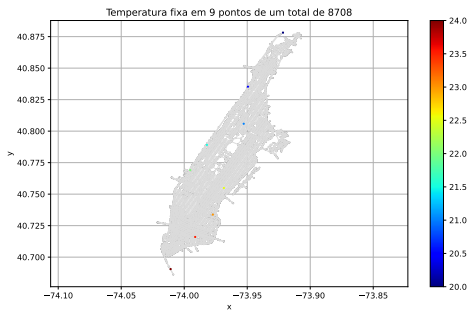


Resultados

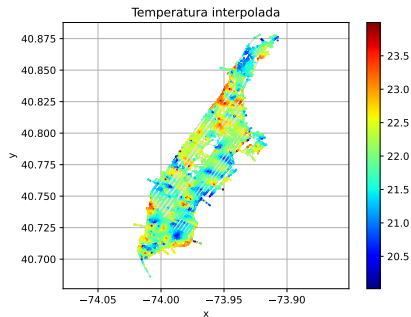
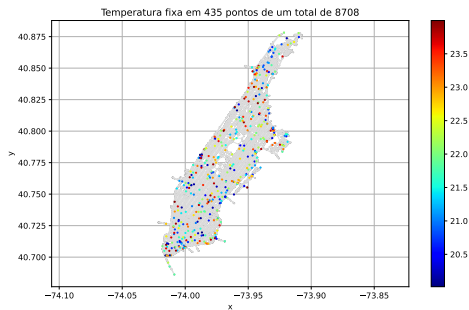




Resultados



Resultados



Dúvidas?