

# CS 685 - Project 3 Report

## Comparison between Flood and Trickle in Reliability

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### 1 Introduction:

In this project we implemented two different retasking algorithms. The first algorithm is simple flood and the second algorithm is trickle. There are many elements we use to compare the two algorithms: number of messages, power usage, Latency, and network overhead are some of them. From my point of view the most important thing is the algorithm's reliability.

### 2 Algorithm:

#### 2.1 Flood:

In the flooding algorithm the base station sends re-task messages to the network. Each node that hears the re-task message applies the new update then resends the message to the other nodes in the network. If the node hears a message that it already dealt with it should ignore these messages.

#### 2.2 Trickle:

In trickle the base station sends the re-task messages to the network. Each node hears this re-task, applies the new update and resumes working in the application without resending the re-task messages. In trickle each node waits for a sometime to check if it didn't hear a metadata message similar to the metadata it has it will send a meta-data message. If a node hears a meta-data newer than the meta-data it has it will send its meta-data. If the node hears older meta-data it will send a re-task message to the network.

### 3 Experiment :

#### 3.1 Setup:

##### 3.1.1 Base Station:

The host application in the base station will send a re-task message then wait for 20 seconds before sending another re-task message. The base station will send 50 re-task messages into the network. The base station will collect the temperature, log, and statistics from the spots.

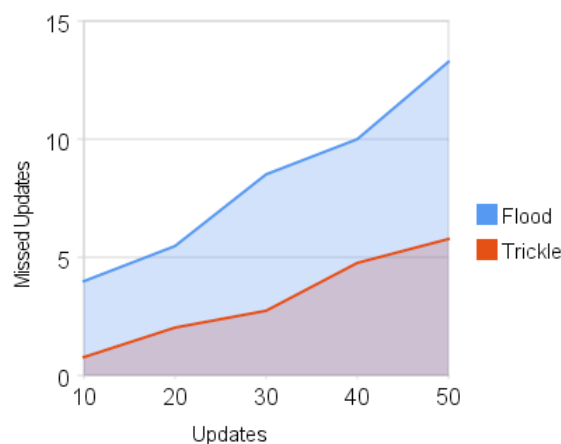
##### 3.1.2 SPOTs:

##### 3.1.2.1 Topology:

I arrange the spot to be in a multi-hop network contains 3 levels A, B and C. Level A spots can communicate directly with the base station and level B spots. The level B spots can communicate with level A and C spots. Finally level C spots can communicate only with level B spots.

##### 3.1.2.2 Software:

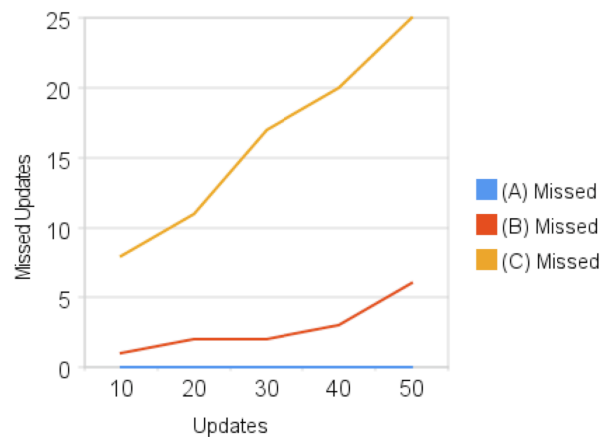
Each spot will collect information about the received updates and send this data with the temperature to the base station. For trickle setup I set  $k=1$ ,  $T_l=5$ ,  $T_h=80$ , and  $T=20$ .



#### 3.2 Results:

As we can see from the above graph in flood the spots missed many messages which was expected. In flood algorithm there is no acknowledges sent to the base station and no resending procedure in the algorithm. On the other hand trickle missed some updates which wasn't expected. This happened only in this experiment because trickle is slow. The spots far from the

base station may not get the update until the next frame or even more. Which means it missed one or more updates. It is clear from the graph that flood lost more updates than trickle.



From the above graph we can see where flood lose updates. We can see that the (A) level spots didn't missed any updates. With the (B) level spots missed up to 10% of the updates while the level (C) spots missed up to 50% of the updates. It is clear that when the spots are located near the source it loses less updates and the lost increase while we move further.

#### 4 Conclusion:

Trickle may be slower than flood in implementing the updates and causing more network traffic. But from this comparison we can say that we can relay more on trickle to deliver the updates properly.