import cv2

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import numpy as np
        from skimage import img_as_ubyte
                             orginal image
     img = cv2.imread("C:\\Users\najmeh \
         \Downloads\\Noise dnoise.jpg", 0)
                             img = img/255
          cv2.imshow('original image', img)
                            cv2.waitKey(0)
                  ()cv2.destroyAllWindows
                               blank image
                            x,y = img.shape
        g = np.zeros((x,y), dtype=np.float32)
                   salt and pepper amount
   نویز 50 درصد میباشد... برای 10 درصد فقط کافی
    است پپر را 0.05 و برای 25 درصد 0.125 بنویسیا
                             pepper = 0.25
                           salt = 1 - pepper
        create salt and pepper noise image
                            :for i in range(x)
                         :for j in range(y)
              ()rnd=np.random.random
                        :if rnd < pepper
                            g[i][j] = 0
                         :elif rnd > salt
                            g[i][j] = 1
                                  :else
                      g[i][j] = img[i][j]
         cv2.imshow('image with noise', g)
                             cv2.waitKey(0)
                  ()cv2.destroyAllWindows
                             img_noise = g
                            denoise image
                      mean filter (average)
                                      m = 5
                                       n = 5
denoise_mean = cv2.blur(img_noise, (m,n))
                              median filter
 img_noise_median = np.clip(img_noise, -1,
                       1) #pixel value range
                       img_noise_median =
img_as_ubyte(img_noise_median) #convert
                                    to uint8
                         denoise_median =
     cv2.medianBlur(img_noise_median, 5)
               cv2.imshow('Denoise Mean',
                            denoise_mean)
```

cv2.imshow('Denoise Median', denoise median)

> cv2.waitKey(0) ()cv2.destroyAllWindows