



NAKUJA PROJECT PROGRESS REPORT INTERNSHIP 2022 WEEK 7

FLIGHT CONTROL

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TASKS LAST WEEK

- [#101] Fabrication of the reaction wheel mounting case.
- [#29] Log operation data.
- [#25] Test reaction Wheel on test bench with current firmware.
- Creating interfaces to hide implementation details, make for easier following, debugging and library changes.



[#101] Fabrication of the reaction wheel mounting case.



[#25] Test reaction Wheel on test bench with current firmware.

- Testing done, and data logged.
- PID tuning ongoing.

Options:

- Ziegler Nichols method tried.

$$K_P = 0.6 * K_u$$

$$T_i = T_u / 2;$$

$$T_d = T_u / 8;$$

K_u = ultimate gain for neutral stability.

T_u = period of oscillation at neutral stability.

$$K_i = K_p / T_i$$

$$K_d = K_p * T_d$$

These can be set from a lookup table for different controller requirements (No overshoot, PD, PI, classical PID).

- Root locus of the mathematical model.
- Trial and error method on Matlab with Simulink blocks.

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- Performance not verified because ESC needs recalibration.

Full_forward = 1832;

Neutral = 1488;

Full_reverse = 1312;



[#29] Log operation data.

- Data logged is yaw, pitch, roll, PID output and PWM values.
- PID output scaled from 0-255, scaled to PWM values for ESC by map
`pwm = map(Output, 0, 255, 1488, 1832)`
- Relogging after ESC recalibration.
- ASIDE: Future work on implementing and using cyclic FIFO buffer to ensure no data loss during times SD is still being written to.



TASKS THIS WEEK



Static Test



TIMELINE

Timeline

Month	Week	Tasks
January	Week1	Familiarising with the N1/N2 project Soldering of prototype flight control PCB Research on the design of reaction wheel
	Week2	Design of the N2 reaction wheel Logging of data onto the SD card
February	Week1	Design of the mounting case and safety cage of the reaction wheel
	Week2	Research on Kalman Filter and ways to improve it
	Week3	Libraries overhaul and reimplementation.