LIQUID PROPULSION

WEEK 10 REPORT

Tasks assigned for week 10

- **▶** #**137** -> Calibration of :
- Pressure sensor
- Temperature Sensor
- #138 -> Addition of rails into test stand
- ► #139 -> Remote operation

Calibration of Temperature Sensor

► Test device : Infrared Temperature Sensor





Used standard temperature(Measured temperature):

- Water at room temperature(23.2 degrees celcius)
- Boiling water at 100 degrees celcius.
- Repeated the same for different temperatures -> 55, 60, 90

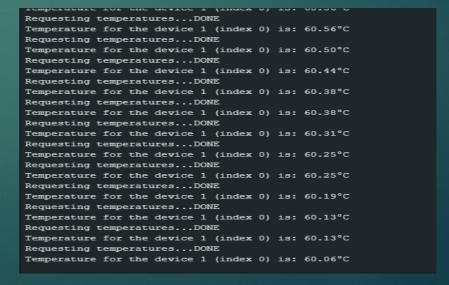
Readings during calibration





Temperature for the device 1 (index 0) is: 23.31°C Requesting temperatures...DONE Temperature for the device 1 (index 0) is: 23.31°C Requesting temperatures...DONE Temperature for the device 1 (index 0) is: 23.25°C Requesting temperatures...DONE Temperature for the device 1 (index 0) is: 23.19°C Requesting temperatures...DONE Temperature for the device 1 (index 0) is: 23.19°C Requesting temperatures...DONE Temperature for the device 1 (index 0) is: 23.19°C Requesting temperatures...DONE Temperature for the device 1 (index 0) is: 23.12°C Requesting temperatures...DONE Temperature for the device 1 (index 0) is: 23.19°C Requesting temperatures...DONE Temperature for the device 1 (index 0) is: 23.12°C Requesting temperatures...DONE Temperature for the device 1 (index 0) is: 23.12°C

Reading at 23.2 degree celcius



Reading at 60 degree celcius

Calibration of Pressure Sensor

To calibrate we used the following parameters:

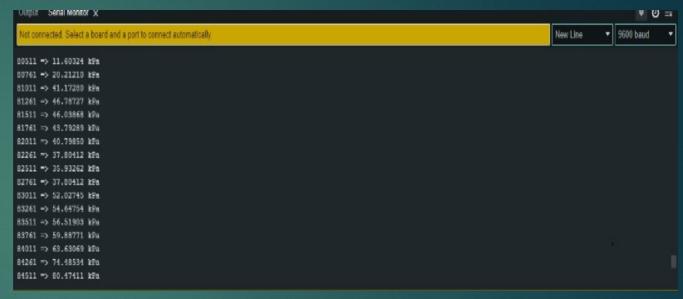
- Voltage range that the sensor can output(From the datasheet) = (0.5 4.5)V
- Microcontroller maps these within a range of 4096 values.
- Minimum Pressure (Pmin) gets mapped onto -> (0.5 * 4096)/5 = 409.6
- Max Pressure (Pmax) gets mapped onto -> (4.5 * 4096)/5 = 3686.4
- Pressure range(Prange) the pressure sensor can read is 1.2MPa

Actual Pressure Read = * Prange

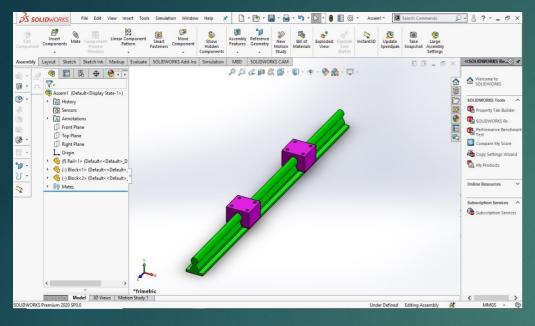
Pressure read from pressure dial **VS** Pressure Sensor Reading







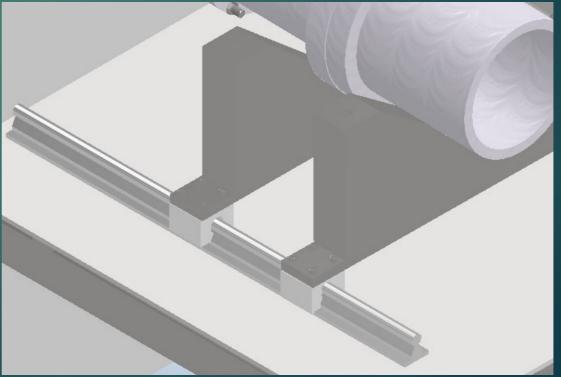
Addition of rails into test stand



This linear load rating is for the static load. And can handle the dynamic load of 2kn.

We chose a linear rail of specifiactions:

1kN to support a load of 2kN of thrust



Next Weeks Tasks

- ▶ 1. Development of the Remote operation Feature.
- 2. Going through the PID diagram to integrate the available sensors to our circuitry.
- 3. Overall integration of Safety features to our circuitry.

THANK YOU