Activity Diagram

October 13, 2019

Ishan Patel
UID: 116169103

Nakul Patel
UID: 116334877

Suyash Yeotikar
UID: 116188456

getWheelBase()	getAxleWidth()	getSteeringAngle()	getCarVelocity()	getCarState()	setWheelBase(double l)	setAxleWidth(double w)	setSteeringAngle(double phi)	setCarVelocity(double s)	setCarState(std::vector<double> state)	calcAckermanParameters()	checkAngleContraints()