Applied Computational Intelligence Lecture 7



Welcome back



- ☐ Project Stage 2
- ☐ Assignment 1
- ☐ Pop quiz

This Session

- Types of Learning Strategies in ML
 - o Unsupervised
 - o Supervised
 - o Reinforcement

Outline

Supervised, Unsupervised, and Reinforcement Learning

- Supervised: Training data includes desired output (labels can be in the form of continuous or discrete).
 - o The agent has access to both input and output percepts.
- Unsupervised: Training data does not include desired output.
 - o The agent has no hint at all about the correct outputs
- Reinforcement: The model is not trained on sample data. Rather, an agent performs sequence of actions interacting with an environment and learns by itself through rewards or penalties (trial and error)
 - o The agent receives some evaluation of its action (penalty, like a hefty bill for rear-ending the car in front)

Types of Machine Learning Problems

- Clustering (generally unsupervised)
 - o K-means
 - o Mean-shift
 - o Probabilistic mixture models (e.g., GMM)

- Classification (generally supervised)
 - o Logistic regression
 - o SVM
 - OANN

Types of Machine Learning Problems Cont.

- Regression (generally supervised)
 - o Linear regression
 - o Polynomial regression
 - o Random forests

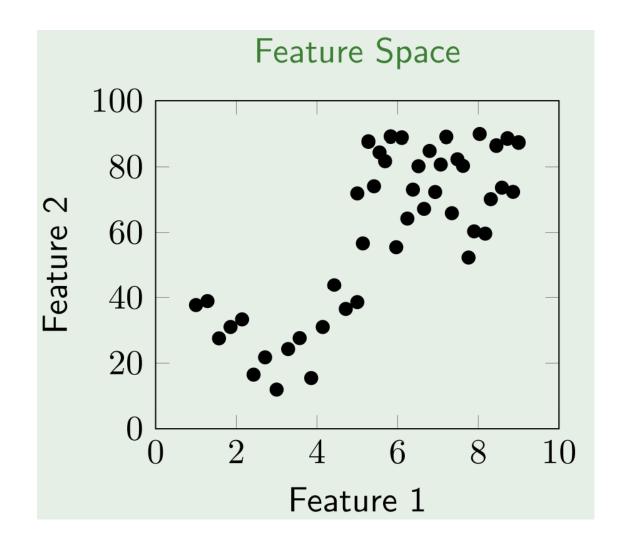
- Association (generally unsupervised)
 - o Association rule
 - o Apriori

Clustering

Clustering

- It can be considered the most important unsupervised learning problem; it deals with finding a structure in a collection of unlabeled data.
- There are no predictions made. Rather, finding the similarities between objects based on the attributes and group similar objects into clusters.
 - o organizing objects into groups whose members are similar in some way.
 - o objects are "similar" between them within a cluster and are "dissimilar" to the objects belonging to other clusters.
 - Intra-class distances are minimized while inter-class distances are maximized.
- Applied in marketing, economics, and various branches of science.

Clustering – Example

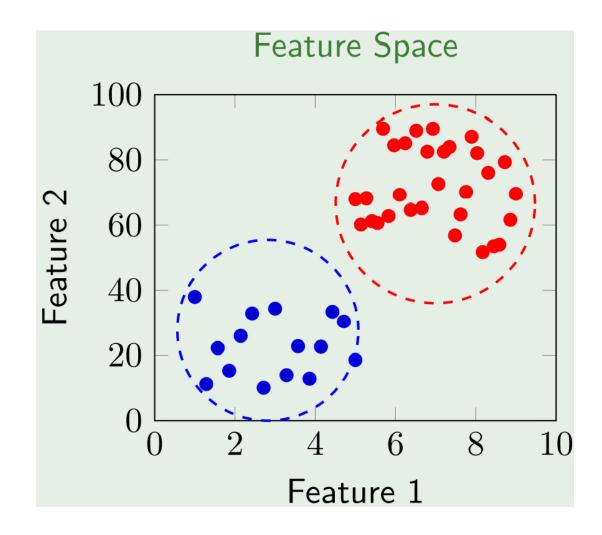




Question:

- How many clusters can be identified into which the data can be divided?
- Based on what similarity are the clusters formed?

Clustering – Example Cont.





Ans:

• Two clusters, based on objects' proximity measure (e.g., L₁ distance) two clusters can be identified.

K-means Clustering

- A computationally faster unsupervised learning method that solves the clustering problem.
- It divides a given dataset based on fixed a priori (k), number of clusters.
- The main idea is to define *k* centroids, one for each cluster, resulting in partition of *n* items into *k* clusters.
- The **centroids** are determined, as the **arithmetic average** (mean) of each cluster's **d-dimensional vector of attributes**.
- In the previous example, d = 2.

→ Algorithm

K-means Clustering – Algorithm

- Four steps.
 - O Initialization: Set initial group centroids $C = \{c_1, c_2, ..., c_k\}$ into the space represented by the dataset $X = \{x_1, x_2, ..., x_n\}$, where x_i represents an individual instances or objects in the space (k < n).
 - Assignment: Assign each instance to the group that has the closest centroid.
 - Update: Recalculate the positions of the centroids, C = C'.
 - Convergence: Repeat Steps 2 and 3 until the centroids are converged (no longer move).

→ Algorithm

K-means – Two Important Computations

Computation of dissimilarity matrix based on a cost function:

1. For each instance x_i :

- Find nearest centroid c_j using $\underset{j}{\arg\min} D(x_i, c_j)$, where $x \in \mathbf{R}^{n \times d}$ and $c \in \mathbf{R}^{K \times d}$. n number of samples, d number of attributes
- D is the $n \times K$ distance matrix between every instance and every centroid.
 - **Note:** Choice of distance measure, e.g., Euclidean distance (L_2) is depends on the data or application.
- Assign the instance x_i to cluster c_j , where $i \in \{1, 2, ..., n\}$ and $j \in \{1, 2, ...K\}$.

K-means – Two Important Computations Cont.

Computation of cluster centroids:

2. For each cluster c_i :

• New centroid $c_j =$ mean of all the instances, let's say set \mathcal{A} assigned to the cluster c_j in the previous step.

$$c_j(a) = \frac{1}{n_{j_{\mathcal{A}_i \to c_j}}} \sum \mathcal{A}_i(a).$$

→ Objective function

K-means - Global Indicator

• Recall: Intra-class distances are to be minimized

Objective function: Global indicator

 Finally, this K-means aims at minimizing a cost function, e.g., a squared error function, like

$$J = \sum_{j=1}^{k} \sum_{i=1}^{n} ||x_i^{(j)} - c_j||^2$$
, where $||x_i^{(j)} - c_j||^2$ is a chosen distance

measure between an instance x_i and the cluster centroid c_j , is an indicator of the distance of the n instances from their **respective** cluster centres.

K-means - Properties

Optimality and complexity:

Characteristics:

- It does not necessarily find the most optimal configuration, corresponding to the global objective function minimum.
- It is sensitive to the initially chosen cluster centroids. It can be run multiple times to reduce this effect.
- Complexity: $O(\#iterations \times \#clusters \times \#instances \times \#attributes)$.

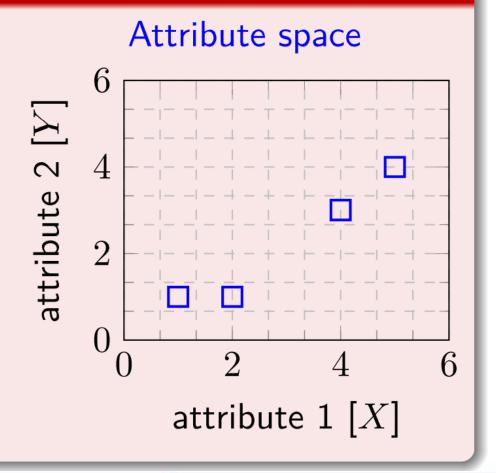
K-means – Working Example

• Task: divide the objects (instances) into two clusters

Input data

Instance	X	Υ
А	1	1
В	2	1
C	4	3
D	5	4

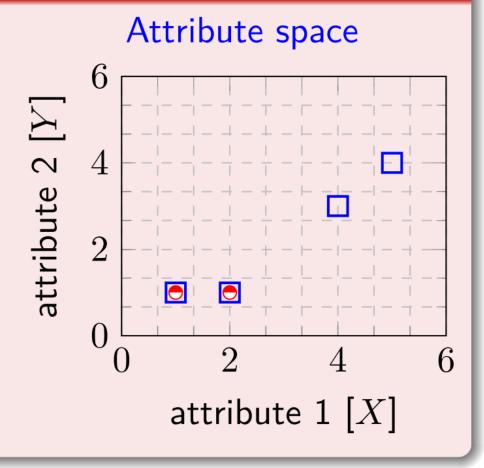
• Each instance represents one point with two-attribute coordinate (X,Y), as in the attribute space shown in the figure.



Step1: Initialization

Instance	X	Υ
А	1	1
В	2	1
C	4	3
D	5	4

• Suppose we use instance A and instance B as the initial centroids. Let c_1 and c_2 denote the coordinate of the centroids, then $c_1=(1,1)$ and $c_2=(2,1)$.



Step2: Cluster assignment

- Instance-Centroid distance:
 - Calculate the distance between cluster centroid to each instance. Let us use Euclidean measure: $\sqrt{(x_i^{(j)}-c_j)^2}$.
- Column: instance
- 1st row: distance of each instance to the 1st centroid,
- 2nd row: distance of each instance to the 2nd centroid.

- Distance matrix at iteration 0
- $D^{0} = \begin{bmatrix} 0 & 1 & 3.61 & 5 \\ 1 & 0 & 2.83 & 4.24 \end{bmatrix} \begin{array}{c} C_{1} = (1,1) & group1 \\ C_{2} = (2,1) & group2 \\ \end{array}$ $A \quad B \quad C \quad D$ $\begin{bmatrix} 1 & 2 & 4 & 5 \\ 1 & 1 & 3 & 4 \end{bmatrix} \begin{array}{c} X \\ Y \end{array}$
- For example, distance from instance C=(4,3) to 1st centroid $c_1=(1,1)$ is $\sqrt{(4-1)^2+(3-1)^2}=3.61$ and to 2nd centroid $c_2=(2,1)$ is $\sqrt{(4-2)^2+(3-1)^2}=2.83$

Step2: Cluster assignment cont.

Assign each instance based on the minimum distance:

$$I_q \to C_i \quad if \quad ||I_q - c_i||^2 < ||I_q - c_j||^2$$
, i.e., use $\underset{j}{\operatorname{arg\,min}} D(I_q, c_j)$, where $\{i, j\} \in \{1, 2, ..., k \mid (j \neq i) \text{ and } q = 1, 2, ..., Q$.

•
$$D^0 = \begin{bmatrix} 0 & 1 & 3.61 & 5 \\ 1 & 0 & 2.83 & 4.24 \end{bmatrix} \begin{cases} C_1 = (1,1) & group1 \\ C_2 = (2,1) & group2 \end{cases}$$

$$G^0 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \end{bmatrix} \begin{cases} group1 \\ group2 \end{cases}$$

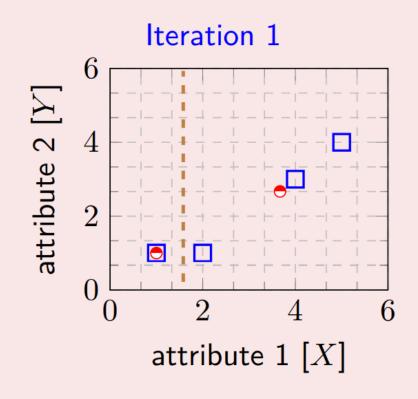
$$A \quad B \quad C \quad D$$

- Thus, instance A is assigned to Group 1, while other instances B, C, and D are assigned to Group 2.
- The element of Group matrix (G) is 1 if and only if the object is assigned to that group.

Step3: Cluster update - Iteration 1

- Update centroids: Knowing the members of each group, now we recompute the new centroid of each group based on these new memberships.
- Group 1 has only one member; thus, the centroid remains in $c_1 = (1, 1)$.
- Group 2 now has three members, thus the updated centroid is the mean coordinate of the attributes among the three members:

$$c_2 = \left(\frac{2+4+5}{3}, \frac{1+3+4}{3}\right) = (3.67, 2.67).$$



Step3: Cluster update - Iteration 1

• Compute the distance of all instances to the **distance new centroids**. Similar to Step 2, the distance matrix at iteration 1 is:

•
$$D^{1} = \begin{bmatrix} 0 & 1 & 3.61 & 5 \\ 3.14 & 2.36 & 0.47 & 1.89 \end{bmatrix} \begin{cases} C_{1} = (1.00, 1.00) & group1 \\ C_{2} = (3.67, 2.67) & group2 \end{cases}$$

$$A \quad B \quad C \quad D$$

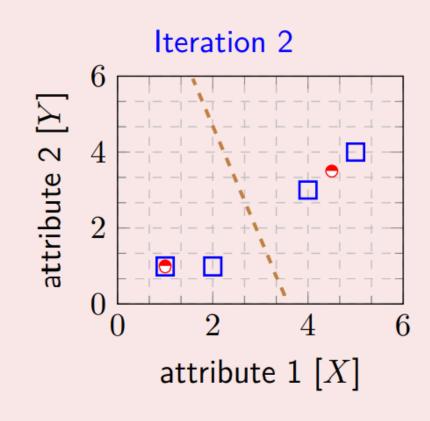
$$\begin{bmatrix} 1 & 2 & 4 & 5 \\ 1 & 1 & 3 & 4 \end{bmatrix} X$$

- Similar to Step 2, each **instance is assigned** to a cluster using $\underset{j}{\arg\min} D(I_q, c_j)$. Based on the new distance matrix, the instance B is assigned to Group 1 while all the other instances remain.
- The new Group matrix: $G^1 = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{array}{c} group1 \\ group2 \end{array}$

Step3: Cluster update - Iteration 2

- Update centroids: Now, repeat calculating the new coordinates of the centroids based on new members assigned in the previous iteration.
- Group 1 and 2 both have two members, thus the new centroids are:

$$c_1 = \left(\frac{1+2}{2}, \frac{1+1}{2}\right) = (1.5, 1)$$
, and $c_2 = \left(\frac{4+5}{2}, \frac{3+4}{2}\right) = (4.5, 3.5)$.



Step3: Cluster update - Iteration 2

Again compute the distance of all instances to the new centroids.
 Similar to Step 2, the distance matrix at iteration 2 is:

•
$$D^1 = \begin{bmatrix} 0.5 & 0.5 & 3.20 & 4.61 \\ 4.30 & 3.54 & 0.71 & 0.71 \end{bmatrix} \begin{cases} C_1 = (1.5, 1.0) & group1 \\ C_2 = (4.5, 3.5) & group2 \end{cases}$$

$$A \quad B \quad C \quad D$$

$$\begin{bmatrix} 1 & 2 & 4 & 5 \\ 1 & 1 & 3 & 4 \end{bmatrix} X$$

• Similar Iteration 1, again, each instance is assigned to a cluster based on the minimum distance. $G^0 = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{array}{c} group1 \\ group2 \end{array}$

Step4: Termination

- Comparing the grouping of last iteration and current iteration reveals that the instances do not move and remain in the same groups.
- Thus, the computation of the K-mean clustering has reached its stability and no more iteration is needed.

• Final clusters:

instance	_ ^	Y	Group
Α	1	1	Group1
В	2	1	Group1
C	4	3	Group2
D	5	4	Group2

Instance | V V | Cusum

Please classify a test sample
$$t = (3, 4)$$
.

- Trained model: final centroids are the the classifier's attributes.
- At Inference time: a test sample will be checked for nearest centroid and assigned to a group, like a nearest neighbor classifier

This Session

- Dimensionality Reduction
 - o Feature Extraction
 - o Feature Selection

Outline 2

Dimensionality Reduction

• Curse of dimensionality:

- O Many complex analysis tasks like regression or classification much more difficult in high-dimensional spaces than in low-dimensional ones.
- O Algorithmic complexity time and memory consumption
- o Workload distribution vectorized, parallel, or distributed architectures
- Hard for visual presentation

• Solution:

o Dimensionality reduction.

Dimensionality Reduction Cont.

- Dimensionality Reduction:
 - OA reduced representation of the data set.
 - o Smaller in volume yet produces the same (or almost the same) results as the raw high dimensional data.
 - o Data encoding schemes:
 - ✓ Attribute subset selection, like removing irrelevant attributes
 - ✓ Attribute construction, like creating a small set of more useful attributes derived from the original set.
 - ✓ Data compression techniques, like principal components analysis or wavelet transforms

Dimensionality Reduction Cont.

• Example:

- \circ **Input** attributes: a, b, c, d
- Target attribute: t
 - \checkmark Model: $m(\{a,b,c,d\},\{t\})$
 - ✓ New attribute: z = f(a, b)
 - \checkmark Model: $m(\{z,c,d\},\{t\})$

⇔Attribute construction

o If we find c has insignificant discriminability between clusters or classes or $c \approx 0$, and can be removed the model.

⇔Attribute subset selection

 $\checkmark M(\{a,b,d\},\{t\})$