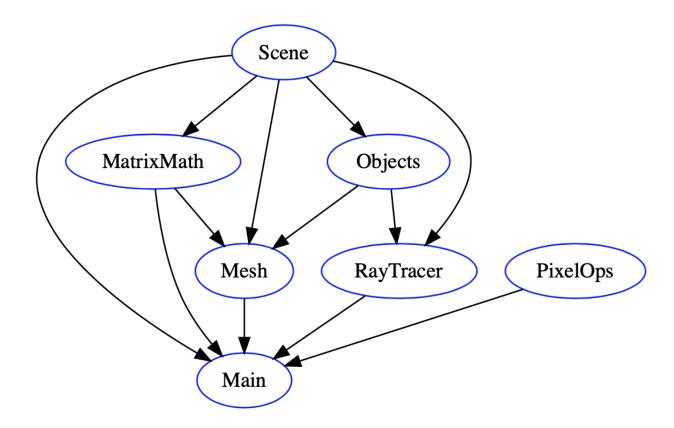
Project Name:

Trace-Ray

Structure of the Code:



- meshes: Contains ply files of different objects that can be rendered
- renders: Contains images that have been rendered by Trace-Ray
- scenes: Contains yaml files of scene descriptions. Each scene description contains the placement of the camera, the view plane, background color, lighting, and objects with their color, material and transformation properties.
- src: This contains the code files
 - Main: This is the entry point of the project which takes in a yaml file name and makes use of other modules to render an image for it.

- MatrixMath: This module contains functions which perform matrix operations to build world and view matrices, and to transform points to world and camera space.
- **Mesh:** This module defines a type to represent triangle meshes. Additionally, it takes in ply files and scene descriptions and creates meshes for each object in the scene.
- **Objects:** This module has type descriptions for vertices, rays and triangles. It also defines a ray-triangle intersection routine.
- **PixelOps:** This module contains helper functions to aid in transforming RGB Color data to ByteStrings which are used to render the image.
- RayTracer: This traces rays through the scene and collects resulting color values for all pixels.
- Scene: This contains types for the elements of our scene description yaml file. It contains definitions to help the YAML parser parse our scene.

Additional Haskell Libraries:

- 1. bmp
- 2. bytestring
- 3. colour
- 4. linear
- 5. ply-loader
- 6. text
- 7. vector
- 8. yaml

Running Trace-Ray:

Questions:

- 1. Is it better to declare types inside their relevant modules or should we make a file containing all the type definitions?
- 2. Besides the absence of multi threading, is there any bottleneck in our code which is hindering performance?
- 3. Are there any Haskell idioms we could use to improve the readability of the code?