

## Midterm topics

- ➤ Computer arithmetic
- > Root finding
- **→** Interpolation
- **→** Integration

### Not covered topics

- -Splines
- -Adaptive Simpson
- -Quadrature

### Midterm exam

- 5 major problems with subproblems
- Some conceptual questions (T/F and multiple choice)
- No pseudo code



# Computer Arithmetic



### Concepts

- Absolute error v.s. Relative error
- Taylor series and Taylor Theorem
- Deflating p(x) = (x r)q(x) + p(r) (synthetic division)

- Floating point representation
- Machine number
- Loss of significance



## Float-point rep.

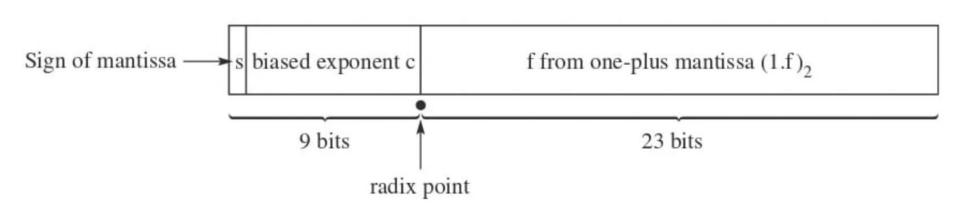
• If  $x \neq 0$ , it can be written as

$$x = \pm q \times 2^m \ (\frac{1}{2} \le q < 1)$$

The mantissa would be expressed a sequence of binary values (0 or 1)

$$q = (0.b_1b_2b_3\cdots)_2$$

•  $b_1 \neq 0 \rightarrow b_1 = 1 \rightarrow q \geq \frac{1}{2}$ .





## Loss of significance

• It occurs in the subtraction of two nearly equal numbers, which produces a result much smaller than either one.

#### Theorem

Let x and y be normalized floating-point machine numbers, where x > y > 0. If  $2^{-p} \le 1 - (y/x) \le 2^{-q}$  for some positive integers p and q, then at most p and at least q significant binary bits are lost in the subtraction x - y.

### How to avoid?

- Double precision
- Taylor series
- Rationalization
- Trigonometric identities
- Logarithmic properties
- Range reduction



# Root finding

**Bisection** 

Newton's

Secant



# **Algorithms**

Bisection method

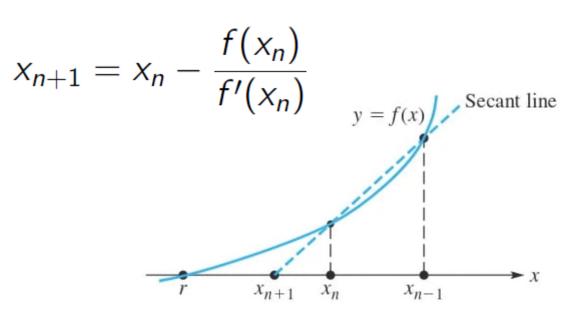
Secant method

$$x_{n+1} = x_n - \left(\frac{x_n - x_{n-1}}{f(x_n) - f(x_{n-1})}\right) f(x_n)$$

Newton's method

$$y = f(x)$$
Tangent line
$$y = \ell(x)$$

$$x$$





## Convergence analysis

If the bisection algorithm is applied to a continuous function f on an interval [a, b], where f(a) f(b) < 0, then, after n steps, an approximate root will have been computed with error at most  $(b - a)/2^{n+1}$ .

#### **Newton's Method Theorem**

If f, f', and f'' are continuous in a neighborhood of a root r of f and if  $f'(r) \neq 0$ , then there is a positive  $\delta$  with the following property: If the initial point in Newton's method satisfies  $|r - x_0| \leq \delta$ , then all subsequent points  $x_n$  satisfy the same inequality, converge to r, and do so quadratically; that is,

$$|r - x_{n+1}| \le c(\delta)|r - x_n|^2$$

Fixed-point iteration

$$x_{n+1} = g(x_n)$$
  
Locally convergent if  $x^* = g(x^*)$ ,  $|g'| < 1$ .



### Convergence rate

• Linear convergence: 
$$C \in [0,1)$$
  
 $|x_{n+1} - x^*| \le C|x_n - x^*|$ 

Bisection is not linear

• Superlinear convergence:  $\alpha \in (1,2)$  $|x_{n+1} - x^*| \le C|x_n - x^*|^{\alpha}$ 

Secant

Quadratic convergence

$$|x_{n+1} - x^*| \le C|x_n - x^*|^2$$

Newton's



# Interpolation

Vandermonde matrix

Lagrange form

Divided difference



### Vandermonde Matrix

$$p_n(x) = c_0 + c_1 x + c_2 x^2 + \dots + c_n x^n$$

$$\begin{bmatrix} 1 & x_0 & x_0^2 & \cdots & x_0^n \\ 1 & x_1 & x_1^2 & \cdots & x_1^n \\ 1 & x_2 & x_2^2 & \cdots & x_2^n \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_n & x_n^2 & \cdots & x_n^n \end{bmatrix} \begin{bmatrix} c_0 \\ c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix} = \begin{bmatrix} y_0 \\ y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

$$\begin{bmatrix} c_0 \\ c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix} = \begin{bmatrix} y_0 \\ y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

Can be used to prove the existence and uniqueness!

Vandermond matrix



### Lagrange Form

The Lagrange form of the interpolation polynomial is given by

$$p_n(x) = \sum_{i=0}^n \ell_i(x) f(x_i)$$

$$\ell_i(x) = \left(\frac{x - x_0}{x_i - x_0}\right) \left(\frac{x - x_1}{x_i - x_1}\right) \cdots \left(\frac{x - x_{i-1}}{x_i - x_{i-1}}\right) \left(\frac{x - x_{i+1}}{x_i - x_{i+1}}\right) \cdots \left(\frac{x - x_n}{x_i - x_n}\right)$$



## Example

$$\ell_0(x) = \frac{\left(x - \frac{1}{4}\right)(x - 1)}{\left(\frac{1}{3} - \frac{1}{4}\right)\left(\frac{1}{3} - 1\right)} = -18\left(x - \frac{1}{4}\right)(x - 1)$$

$$\ell_1(x) = \frac{\left(x - \frac{1}{3}\right)(x - 1)}{\left(\frac{1}{4} - \frac{1}{3}\right)\left(\frac{1}{4} - 1\right)} = 16\left(x - \frac{1}{3}\right)(x - 1)$$

$$\ell_2(x) = \frac{\left(x - \frac{1}{3}\right)\left(x - \frac{1}{4}\right)}{\left(1 - \frac{1}{3}\right)\left(1 - \frac{1}{4}\right)} = 2\left(x - \frac{1}{3}\right)\left(x - \frac{1}{4}\right)$$

$$p_2(x) = -36\left(x - \frac{1}{4}\right)(x - 1) - 16\left(x - \frac{1}{3}\right)(x - 1) + 14\left(x - \frac{1}{3}\right)\left(x - \frac{1}{4}\right)$$



### Divided Difference

Concise notation

$$p_n(x) = \sum_{i=0}^n a_i \prod_{j=0}^{i-1} (x - x_j)$$

with 
$$\prod_{j=0}^{-1} (x - x_j) = 1$$

Nested form

$$p(x) = a_0 + (x - x_0)(a_1 + (x - x_1)(a_2 + \cdots + (x - x_{n-1})a_n))\cdots)$$

X	f[]	f[,]	f[,,]	f[,,,]
$x_0$	$f[x_0]$	<i>f</i> [1]		
$x_1$	$f[x_1]$	$f[x_0, x_1]$	$f[x_0, x_1, x_2]$	
$x_2$		$f[x_1, x_2]$	$f[x_1, x_2, x_3]$	$f[x_0, x_1, x_2, x_3]$
$x_3$	$f[x_3]$	$f[x_2, x_3]$	J [31, 32, 33]	



## Example

Let 
$$f(x) = x^3 + 2x^2 + x + 1$$
.

- a) Find the polynomial of degree 4 that interpolates the values of f at  $\pm 2$ ,  $\pm 1$ , 0.
- b) Find the polynomial of degree 2 that interpolates the values of f at  $\pm 1$ , 0.

$$p_4(x) = -1 + 2(x+2) - (x+2)(x+1) + (x+2)(x+1)x$$
$$p_2(x) = 1 + 2(x+1)x$$



## Interpolation errors

#### First Interpolation Error Theorem

If p is the polynomial of degree at most n that interpolates f at the n + 1 distinct nodes  $x_0, x_1, \ldots, x_n$  belonging to an interval [a, b] and if  $f^{(n+1)}$  is continuous, then for each x in [a, b], there is a  $\xi$  in (a, b) for which

$$f(x) - p(x) = \frac{1}{(n+1)!} f^{(n+1)}(\xi) \prod_{i=0}^{n} (x - x_i)$$
 (2)

### **Second Interpolation Error Theorem**

Let f be a function such that  $f^{(n+1)}$  is continuous on [a, b] and satisfies  $|f^{(n+1)}(x)| \le M$ . Let p be the polynomial of degree  $\le n$  that interpolates f at n+1 equally spaced nodes in [a, b], including the endpoints. Then on [a, b],

$$|f(x) - p(x)| \le \frac{1}{4(n+1)} M h^{n+1}$$
 (6)

where h = (b - a)/n is the spacing between nodes.

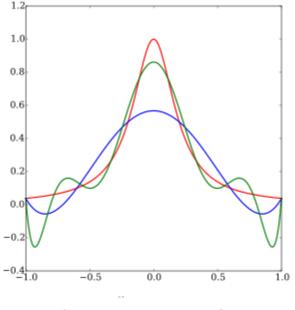


## Runge's phenomenon

- A polynomial of degree n has n roots. If all roots are real, the curve crosses the x-axis n times.
- These many turns result in wide oscillations.
- A specific example is provided by Runge function

$$f(x) = (1 + 25x^2)^{-1}$$

 Replace the equispaced nodes by Chebyshev nodes



$$\lim_{n o\infty}\left(\max_{-1\le x\le 1}|f(x)-P_n(x)|
ight)=\infty.$$



# Integration

Trapezoid

Simpson's



### Formula

Trapezoid

$$\int_{a}^{b} f(x) \, dx \approx \frac{1}{2} (b - a) [f(a) + f(b)]$$

• Simpson's 1/3 Rule

$$\int_a^b f(x) dx \approx \frac{1}{6} (b-a) \Big[ f(a) + 4f \Big( \frac{a+b}{2} \Big) + f(b) \Big]$$

No need to memorize 3/8 rule



# Error analysis

#### Theorem on Precision of Composite Trapezoid Rule

If f'' exists and is continuous on the interval [a, b] and if the composite trapezoid rule T with uniform spacing h is used to estimate the integral  $I = \int_a^b f(x) dx$ , then for some  $\zeta$  in (a, b),

$$I - T = -\frac{1}{12}(b - a)h^2 f''(\zeta) = \mathcal{O}(h^2)$$

Simpson's 1/3 Rule: 
$$-\frac{1}{180}(b-a)h^4f^{(4)}(\xi)$$

Simpson's 3/8 rule has the same order but lower in accuracy.