

Artificial Intelligence

CS4365 --- Fall 2022

Knowledge Representation and Reasoning

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Summary of Propositional Logic

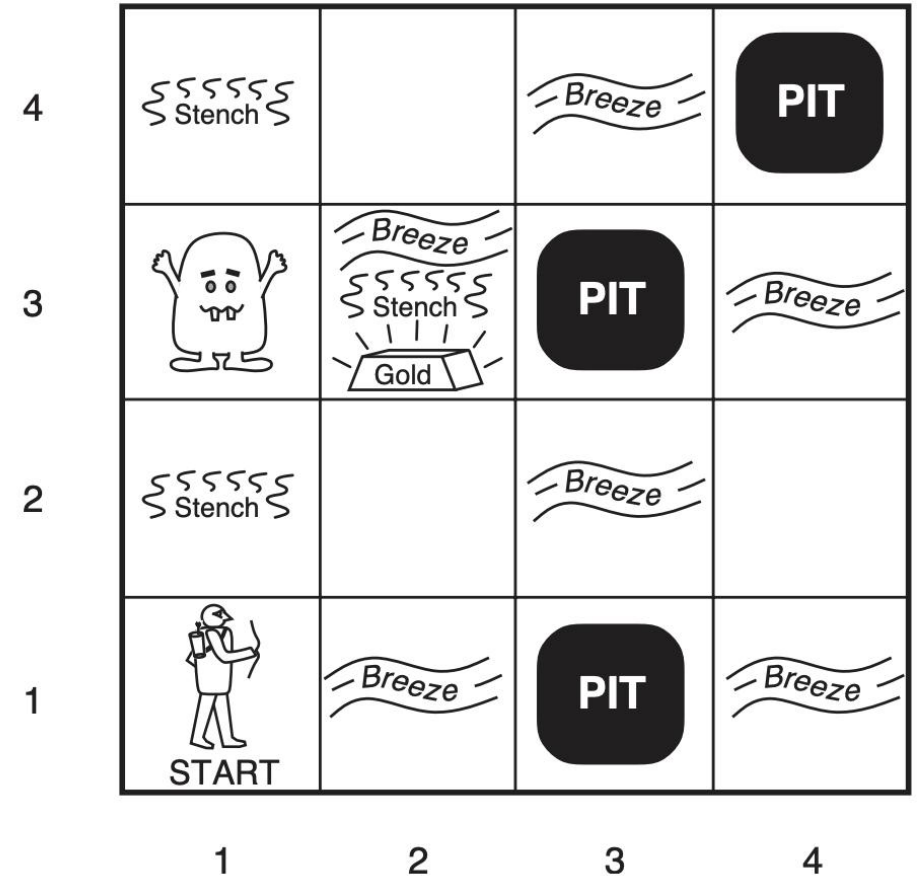
- **Syntax**
 - literals
 - Connectives
 - Clauses
 - CNF
- **Semantics**
 - Model
- **Inference**
 - Semantically: Model Checking
 - Syntactically: Inference rules and axioms
 - Modus Ponens
 - Resolution

Agent Based on Propositional Logic

- Construct wumpus world agents that use **propositional logic**.
- Enable the agent to **deduce**, to the extent possible, **the state of the world** given its percept history

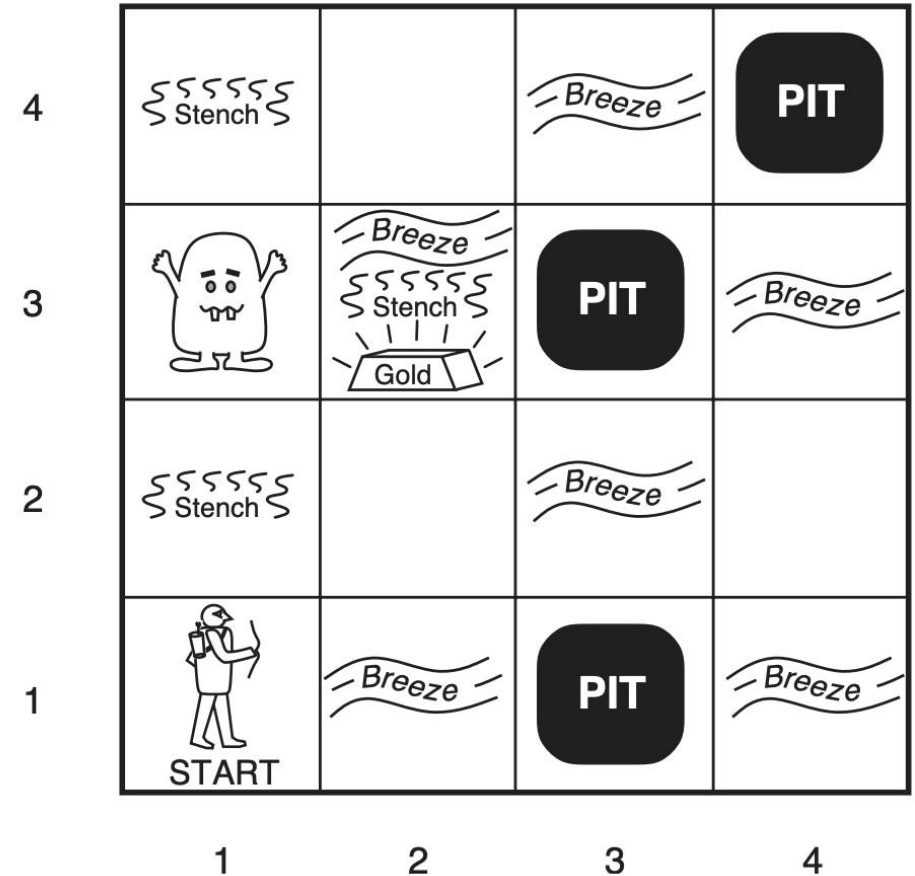
The Wumpus World

- Performance measure:
 - gold +1000, death -1000
 - -1 per step, -10 for using the arrow



The Wumpus World

- Environment
 - Squares adjacent to wumpus are **smelly**
 - Squares adjacent to pit are **breezy**
 - **Glitter** iff gold is in the same square
 - Shooting kills wumpus if you are facing it
 - Shooting uses up the only arrow
 - Grabbing picks up gold if in same square
 - Releasing drops the gold in same square
- Actuators: Left turn, Right turn, Forward, Grab, Release, Shoot
- Sensors: Stench, Breeze, Glitter, Bump, Scream (shot Wumpus)

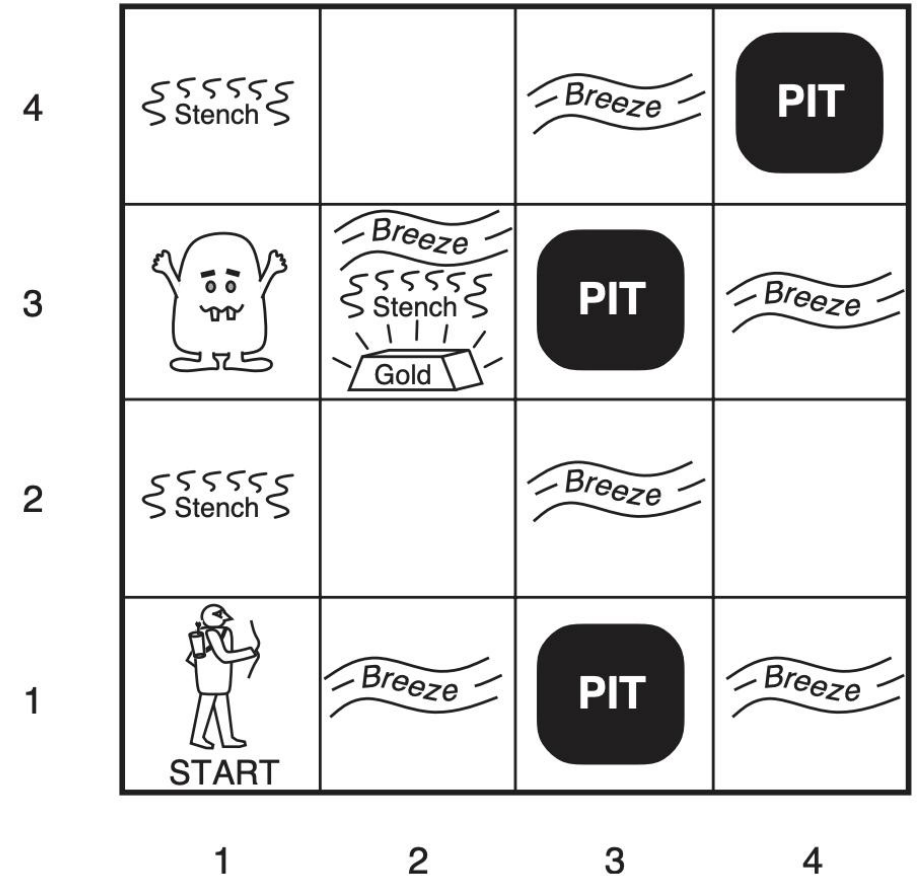


Wumpus world characterization

- Fully Observable?
 - No – only local perception
- Deterministic?
 - Yes – outcomes exactly specified
- Episodic?
 - No – sequential at the level of actions
- Static?
 - Yes – Wumpus and Pits do not move
- Discrete?
 - Yes
- Single-agent?
 - Yes – Wumpus is essentially a natural feature

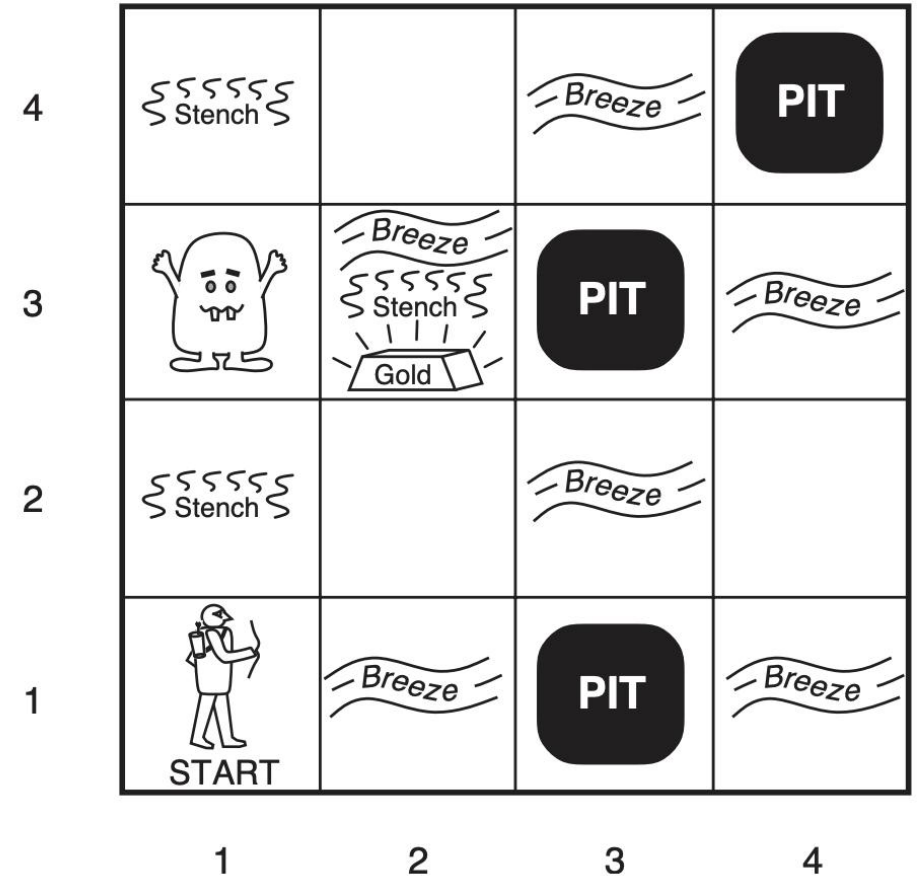
The Wumpus World

- A decision-maker needs to represent **knowledge** of the world and **reason** with it in order to safely explore this world.
- **Principle Difficulty**: agent is initially ignorant of the configuration of the environment – going to have to reason to figure out where the gold is without getting killed!



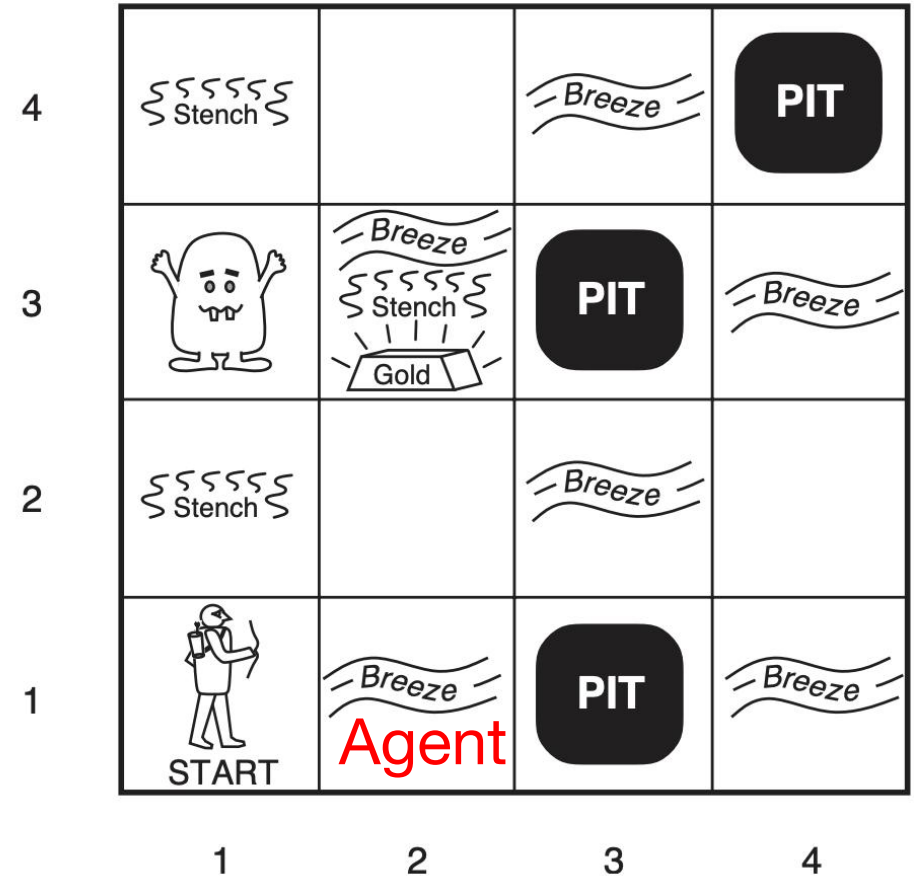
The Wumpus World

- Define the **propositional symbols**:
 - $P_{x,y}$: true if there is a **pit** in $[x,y]$
 - $W_{x,y}$: true if there is a **wumpus** in $[x, y]$, dead or alive
 - $B_{x,y}$: true if the agent perceives a **breeze** in $[x, y]$
 - $S_{x,y}$: true if the agent perceives a **stench** in $[x,y]$



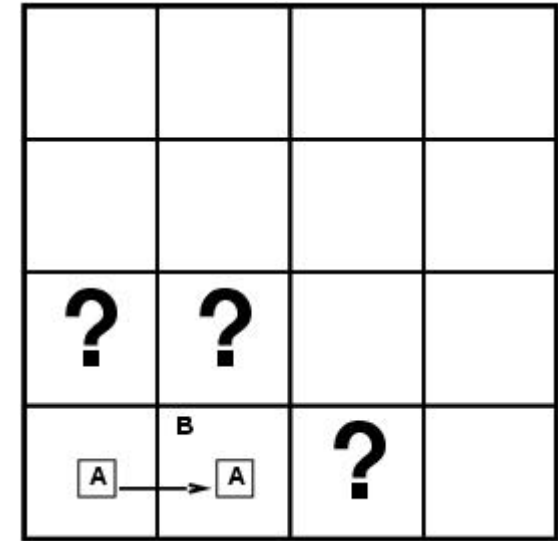
Knowledge Base

- Build the **knowledge base**:
 - There is no **pit** in [1,1]:
 - R1: $\neg P_{1,1}$
 - For each square, it knows that the square is **breezy** if and only if a neighboring square has a **pit**;
 - R2: $B_{1,1} \Leftrightarrow (P_{1,2} \vee P_{2,1})$
 - R3: $B_{2,1} \Leftrightarrow (P_{1,1} \vee P_{2,2} \vee P_{3,1})$
 - Percepts:
 - R4: $\neg B_{1,1}$
 - R5: $B_{2,1}$

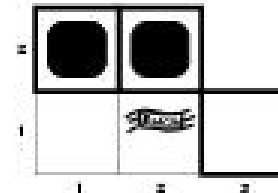
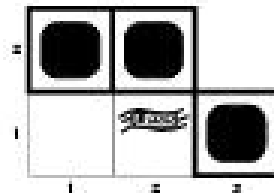
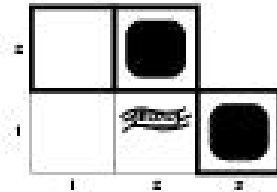
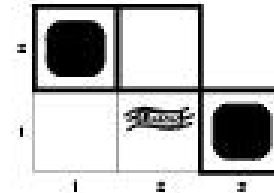
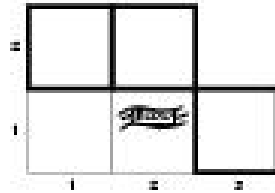
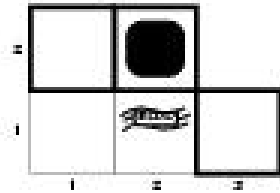
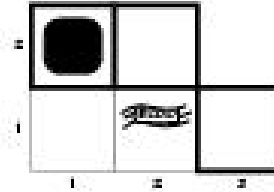
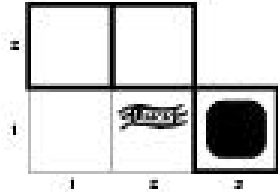


Entailment in the Wumpus World

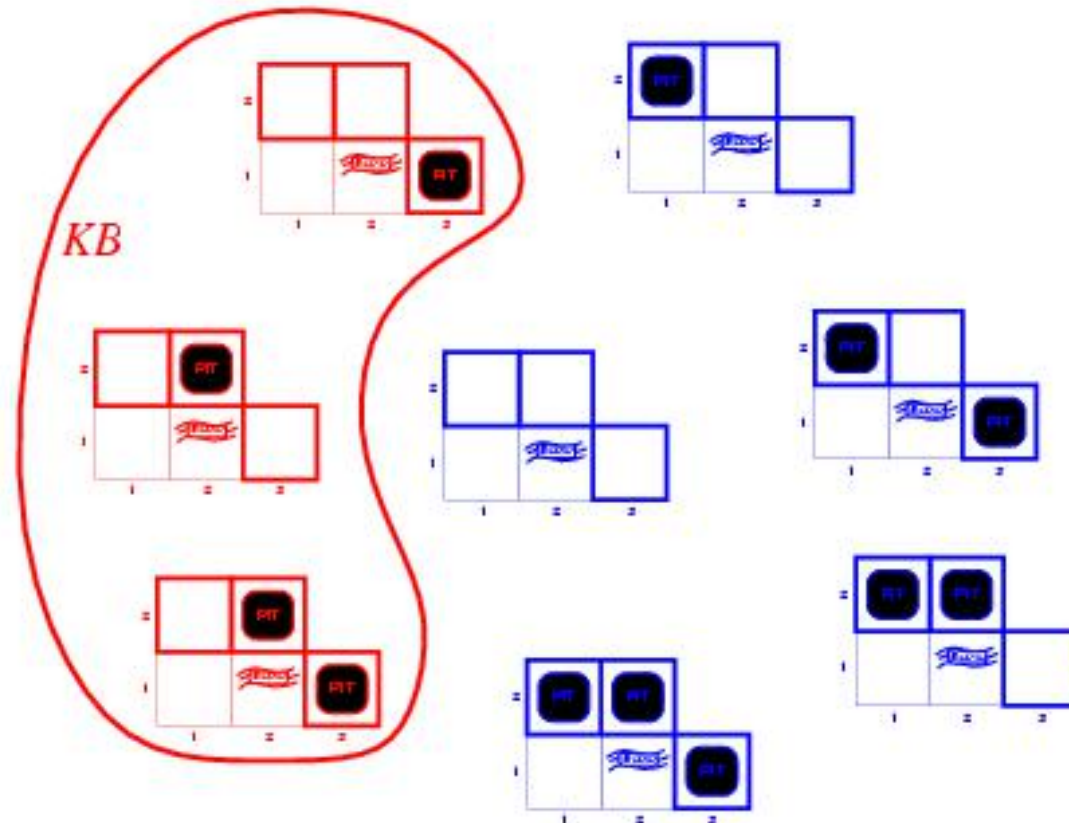
- Situation after detecting nothing in [1,1], moving right **breeze** in [2,1]
- Consider possible models for KB assuming only **pits**
- 3 **Boolean** choices \Rightarrow 8 possible models



Wumpus possible models

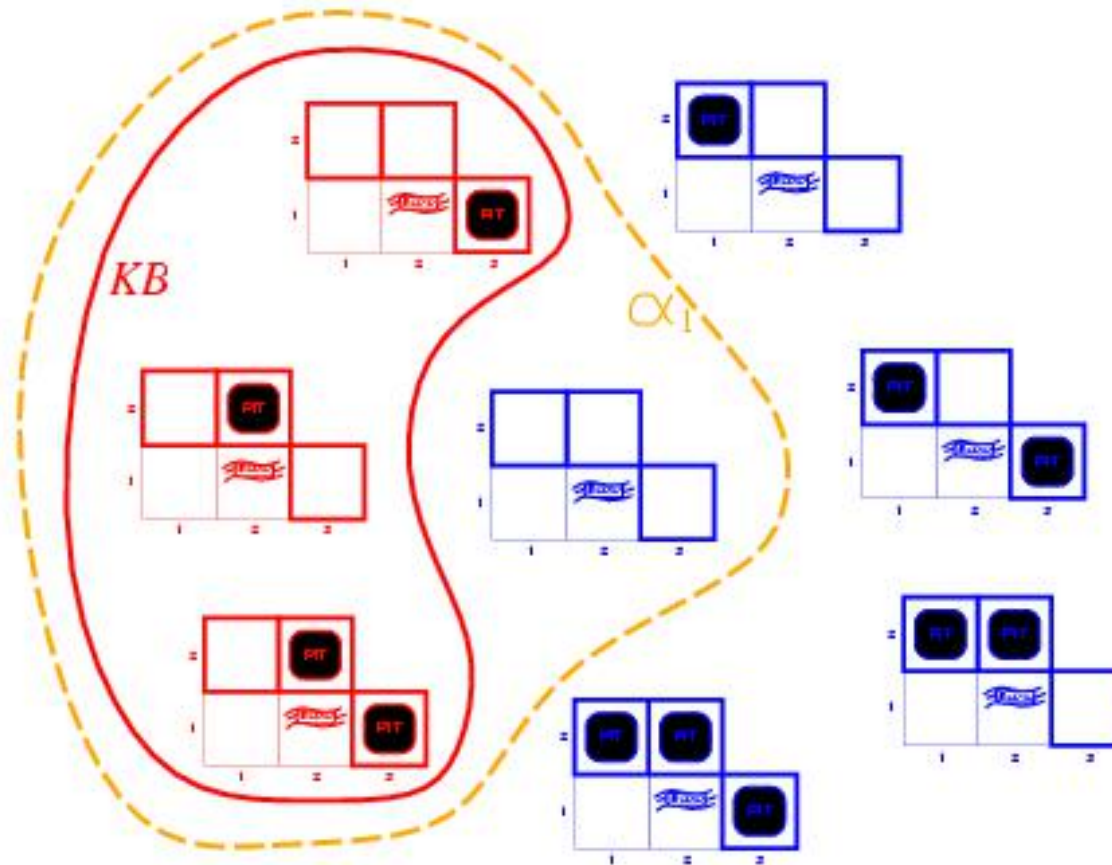


Wumpus models



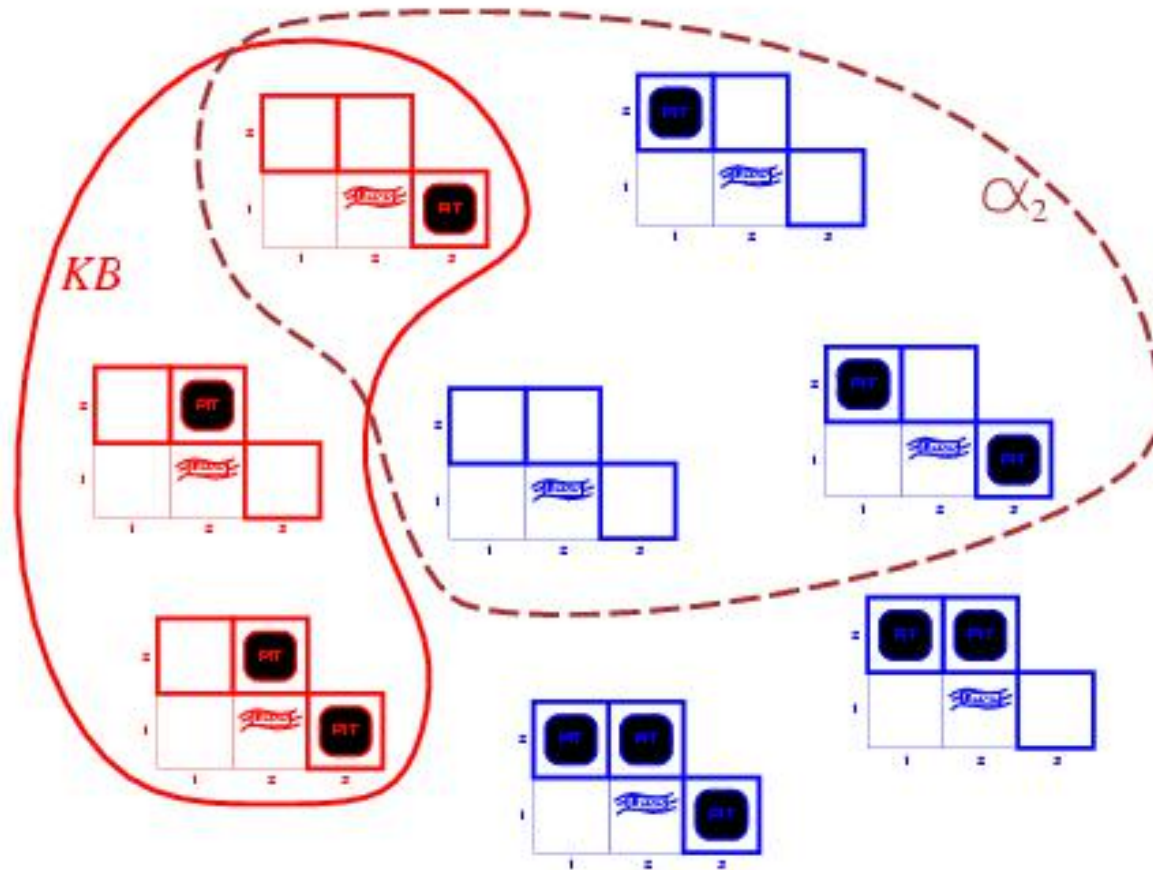
KB = wumpus-world rules + observations

Wumpus models



- KB = wumpus-world rules + observations
- α_1 = “there is no pit in [1,2]”, $KB \models \alpha_1$, proved by **model checking**

Wumpus models



- KB = wumpus-world rules + observations
- α_2 = "there is no pit in [2,2]"

Inference

- Proof $\neg P1,2$ and $\neg P2,1$:
- R2: $B1,1 \Leftrightarrow (P1,2 \vee P2,1)$
- R6: $(B1,1 \Rightarrow (P1,2 \vee P2,1)) \wedge ((P1,2 \vee P2,1) \Rightarrow B1,1)$
- R7: $(P1,2 \vee P2,1) \Rightarrow B1,1$
- R8: $\neg B1,1 \Rightarrow \neg(P1,2 \vee P2,1)$
- R9: $\neg(P1,2 \vee P2,1)$
- R10: $\neg P1,2 \wedge \neg P2,1$

And elimination

Contrapositive
Modus Ponens
De Morgan

1,4	2,4	3,4	4,4
1,3	2,3	3,3	4,3
1,2 OK	2,2	3,2	4,2
1,1 <input type="checkbox"/> A OK	2,1 OK	3,1	4,1

Action and Percept

- Move to [2, 1]
- B2,1 is True
- There is a **pit** in [2,2] or [3,1]

1,4	2,4	3,4	4,4
1,3	2,3	3,3	4,3
1,2 OK	2,2 P?	3,2	4,2
1,1 V OK	2,1 <div>A</div> B OK	3,1 P?	4,1

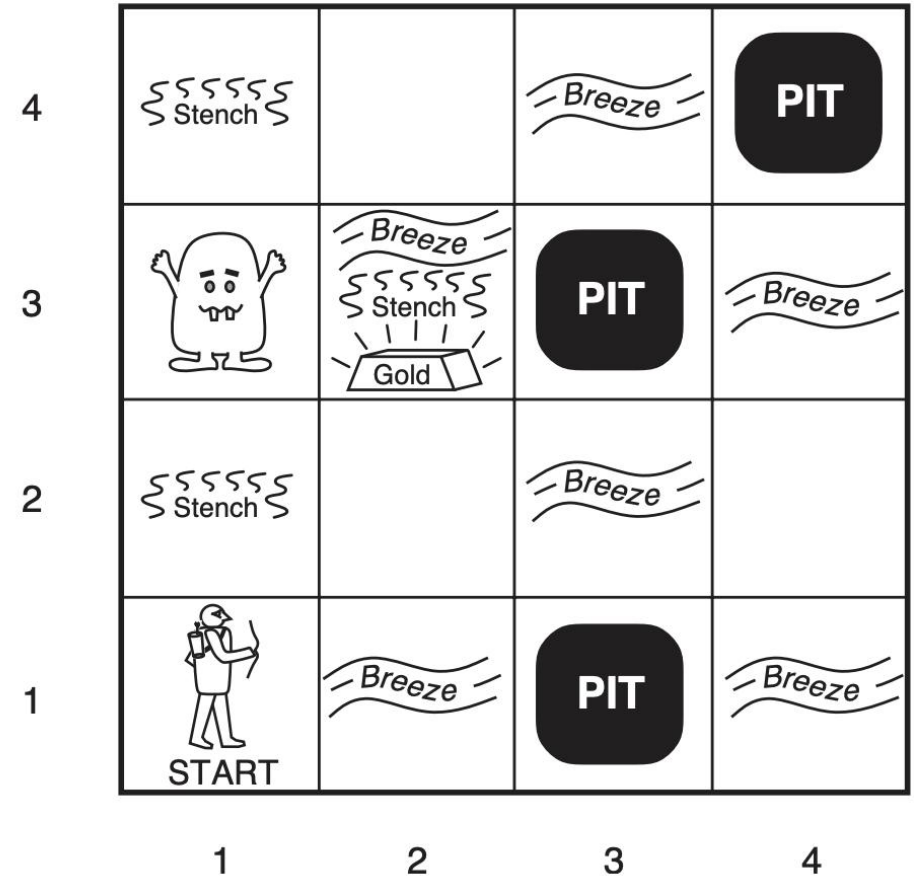
Inference

- The agent return from [2,1] to [1,1] and then moves to [1, 2]
 - R11: $\neg B_{1,2}$
 - R12: $B_{1,2} \Leftrightarrow (P_{1,1} \vee P_{2,2} \vee P_{1,3})$
 - R13: $\neg P_{2,2}$
 - R14: $\neg P_{1,3}$
 - R3: $B_{2,1} \Leftrightarrow (P_{1,1} \vee P_{2,2} \vee P_{3,1})$
 - R5: $B_{2,1} \rightarrow$ R15: $P_{1,1} \vee P_{2,2} \vee P_{3,1}$
 - R16: $P_{1,1} \vee P_{3,1}$ (**resolve** R13 with R15)
 - R17: $P_{3,1}$ (**resolve** R1 with R16)

1,4	2,4	3,4	4,4
1,3 W!	2,3	3,3	4,3
1,2 A S OK	2,2 OK	3,2	4,2
1,1 V OK	2,1 B V OK	3,1 P! Pit	4,1

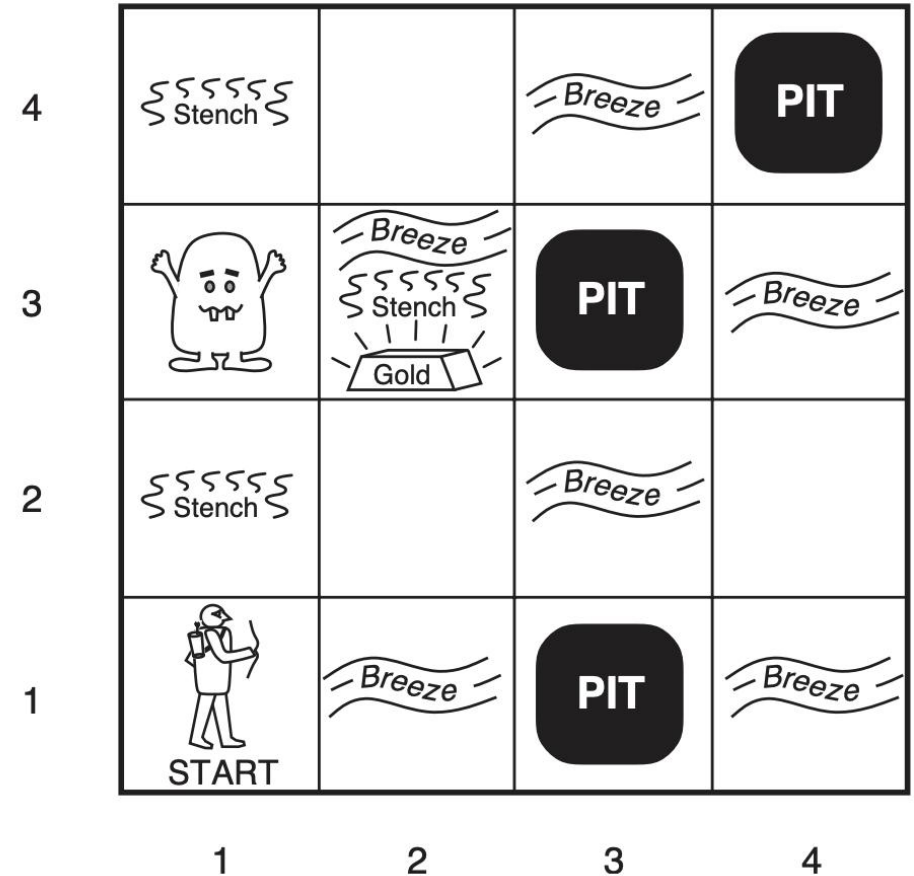
The current state of the world

- Collecting **axioms**:
 - $\neg P_{1,1}$
 - $\neg W_{1,1}$
 - For each square, it knows that the square is **breezy** if and only if a neighboring square has a **pit**:
 - $B_{1,1} \Leftrightarrow (P_{1,2} \vee P_{2,1})$
 - ...
 - Square is **smelly** if and only if a neighboring square has a **wumpus**.
 - $S_{1,1} \Leftrightarrow (W_{1,2} \vee W_{2,1})$
 - ...



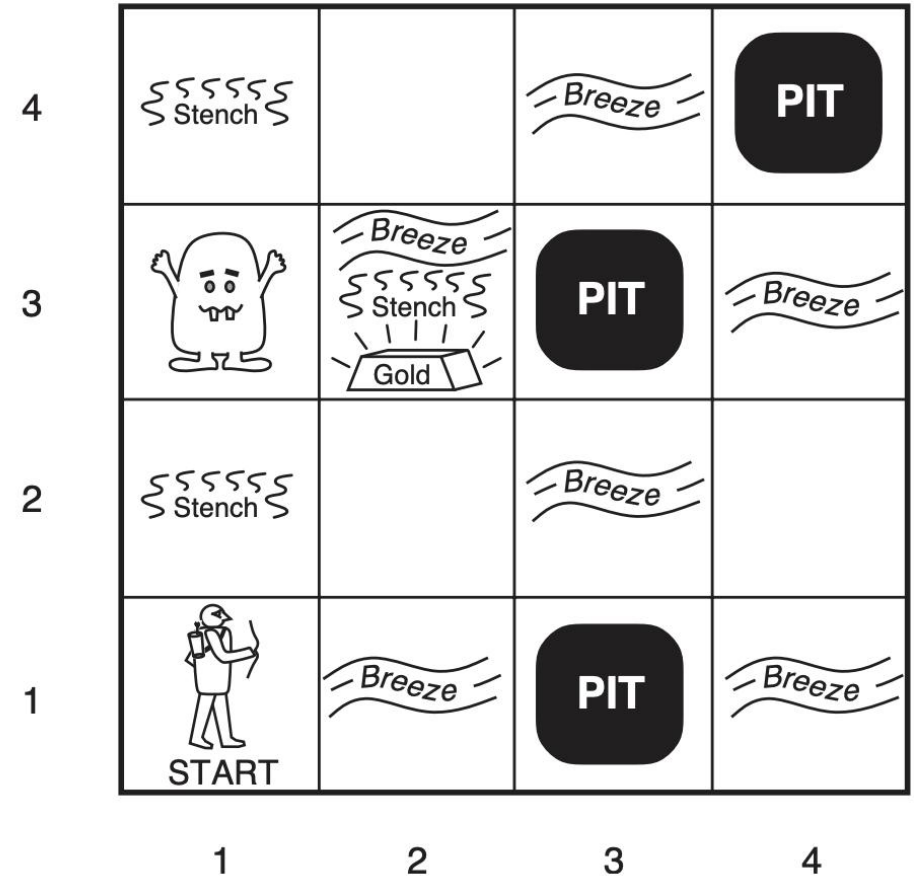
The current state of the world

- There is exactly one wumpus
 - $W_{1,1} \vee W_{1,2} \vee \dots, W_{4,3} \vee W_{4,4}$
- There is at most one wumpus
 - $\neg W_{1,1} \vee \neg W_{1,2}$
 - $\neg W_{1,1} \vee \neg W_{1,3}$
 - ...
 - $\neg W_{4,3} \vee \neg W_{4,4}$



The current state of the world

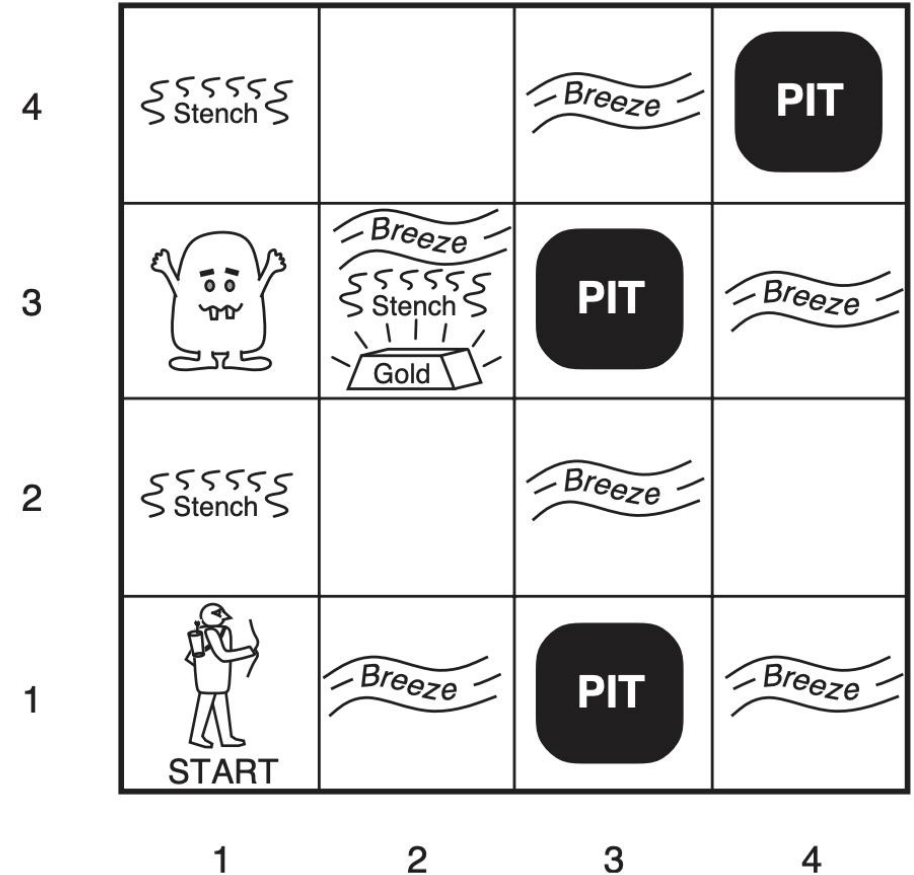
- **Fluent**: associating propositions with time steps extends to any aspect of the world that **changes over time**
 - $L^0_{1,1}$: the agent is at square [1,1] at time 0
- Consider **time stamp for percepts**
 - $\neg \text{Stench}^3$
 - Stench^4



The current state of the world

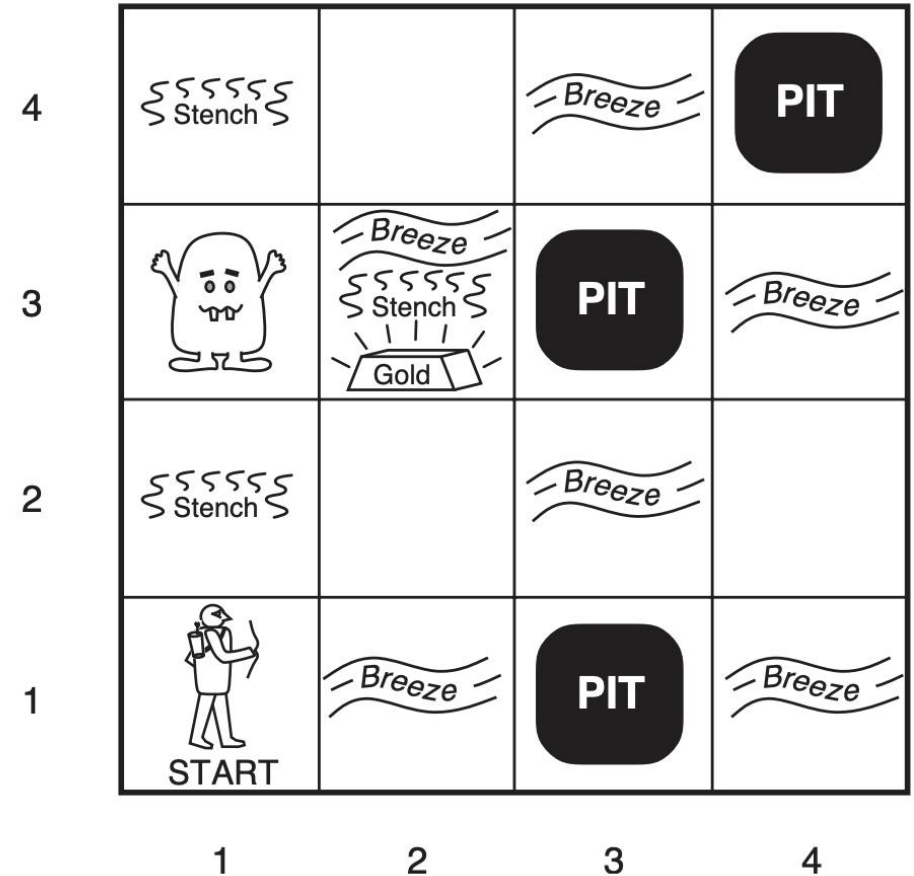
- For any time step t and any square $[x, y]$, we have

- $L_{x,y}^t \Rightarrow (\text{Breeze}^t \Leftrightarrow B_{x,y})$
- $L_{x,y}^t \Rightarrow (\text{Stench}^t \Leftrightarrow S_{x,y})$



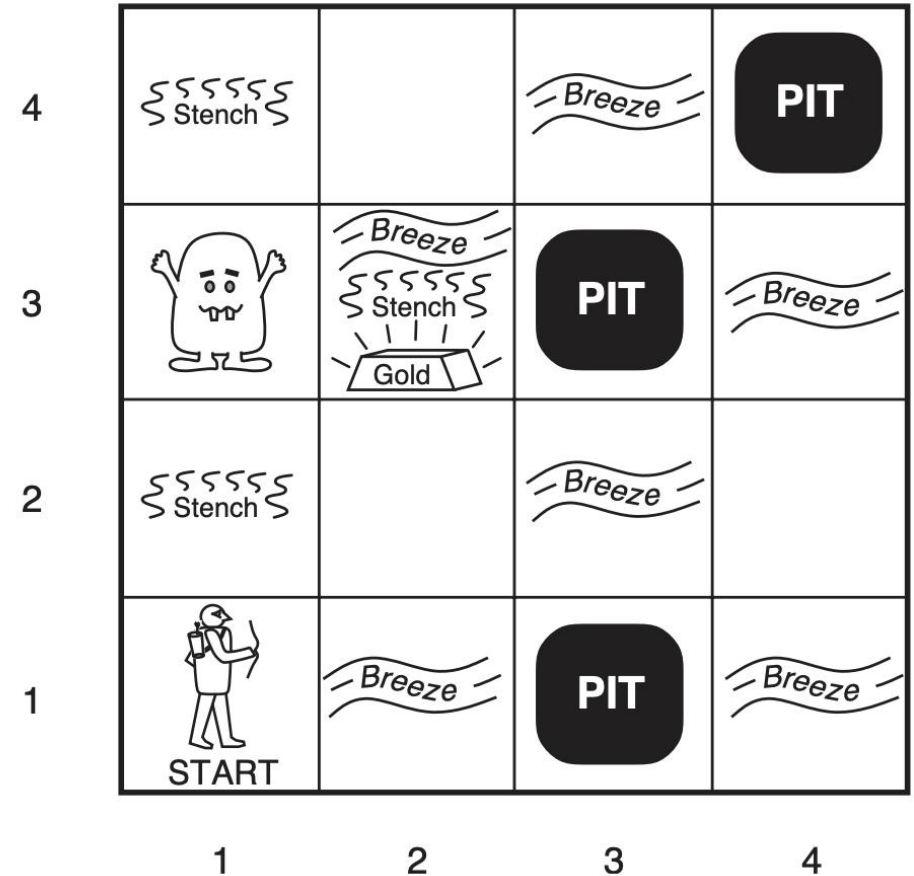
The current state of the world

- **Proposition symbols** for the occurrences of **actions**
 - Forward_0
- The **percept** for a given time step happens first, followed by the **action** for that time step, followed by a **transition** to the next time step.



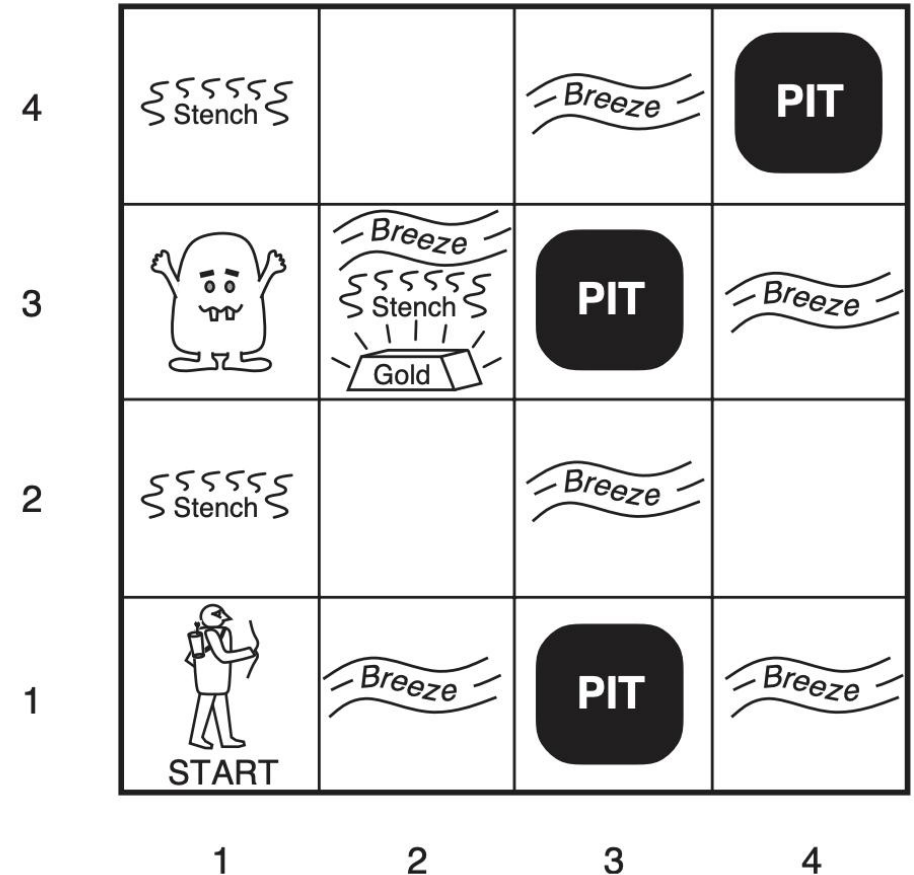
The current state of the world

- **Effect axioms**: describe how the world changes,
 - $L^0_{1,1} \wedge \text{FaceEast}_0 \wedge \text{Forward}_0 \Rightarrow (L^1_{2,1} \wedge \neg L^1_{1,1})$
- Need to specify for each **action**, **time step**, **location** and **orientation**



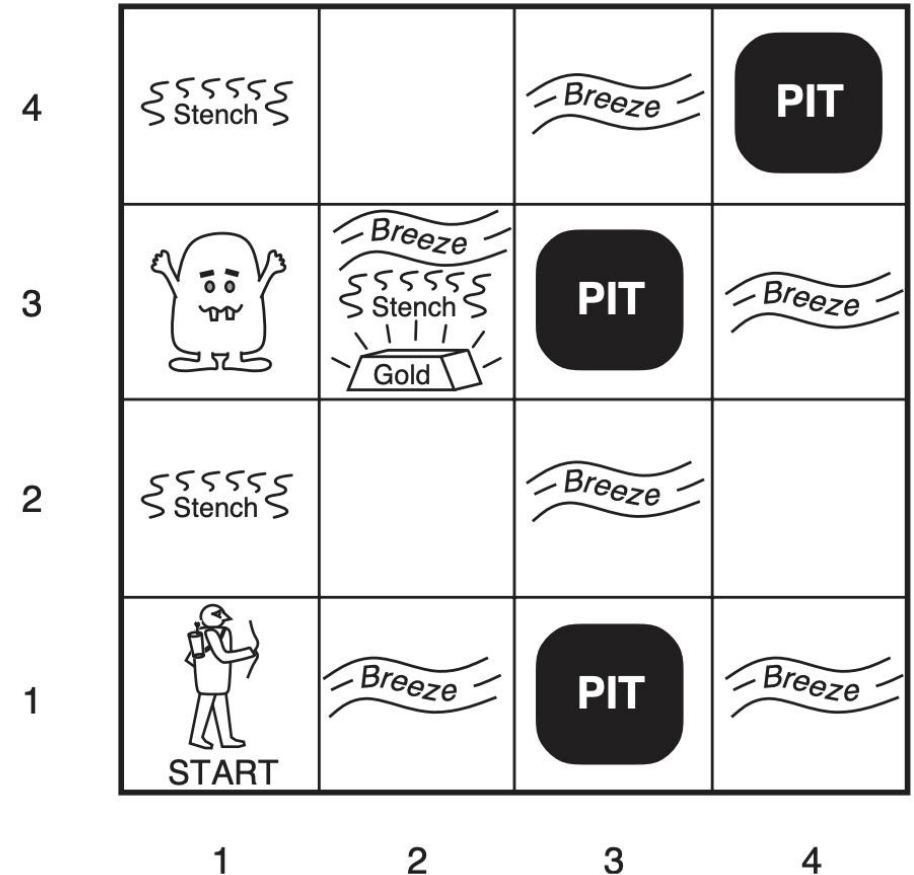
The current state of the world

- **Frame problem:**
 - $\text{ASK}(\text{KB}, \text{HaveArrow}^1)$
 - The information has been lost because the effect axiom fails to state what remains **unchanged** as the result of an action
- Add **frame axioms:**
 - $\text{Forward}^t \Rightarrow (\text{HaveArrow}^t \Leftrightarrow \text{HaveArrow}^{t+1})$
 - $\text{Forward}^t \Rightarrow (\text{WumpusAlive}^t \Leftrightarrow \text{WumpusAlive}^{t+1})$
- For m **actions** and n **fluents**, needs $O(mn)$



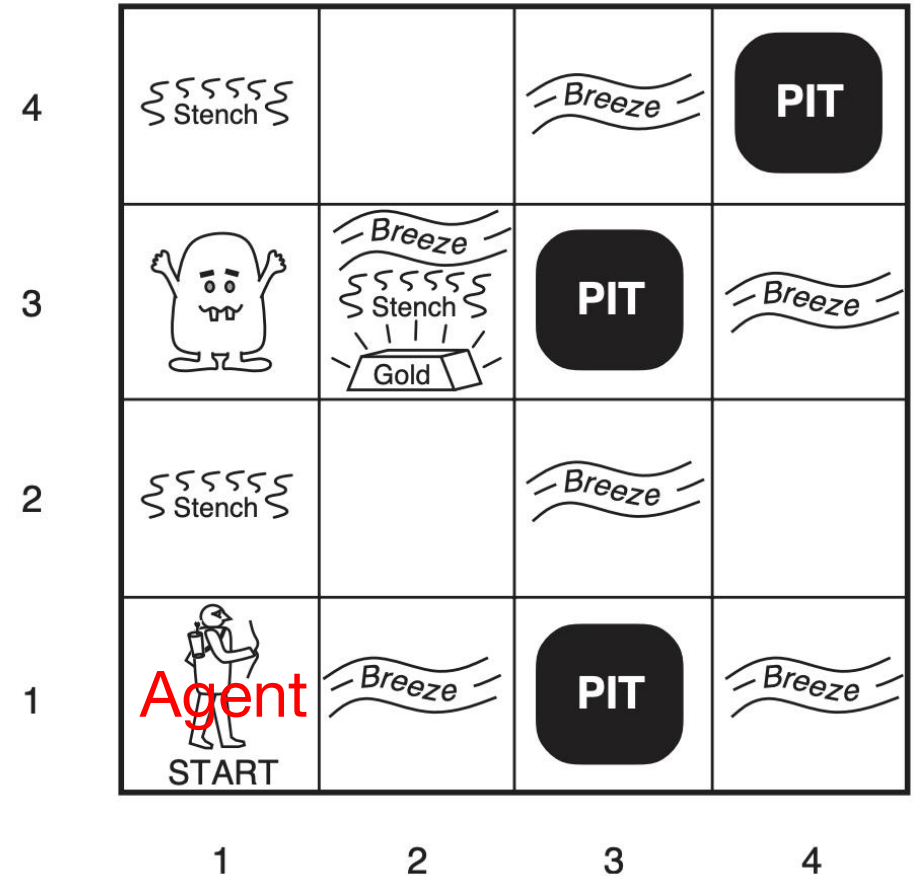
The current state of the world

- Writing axioms about **fluents**
- **Successor-state axiom:**
 - $F^{t+1} \Leftrightarrow \text{ActionCauses}F^t \vee (F^t \wedge \text{ActionCausesNot}F^t)$
 - ...
 - $\text{HaveArrow}^{t+1} \Leftrightarrow (\text{HaveArrow}^t \Leftrightarrow \neg \text{Shoot}^t)$
 - $L^{t+1}_{1,1} \Leftrightarrow (L^{t}_{1,1} \wedge (\neg \text{Forward}^t \vee \text{Bump}^{t+1})) \vee (L^{t}_{1,2} \wedge (\text{South}^t \wedge \text{Forward}^t)) \vee (L^{t}_{2,1} \wedge (\text{West}^t \wedge \text{Forward}^t))$



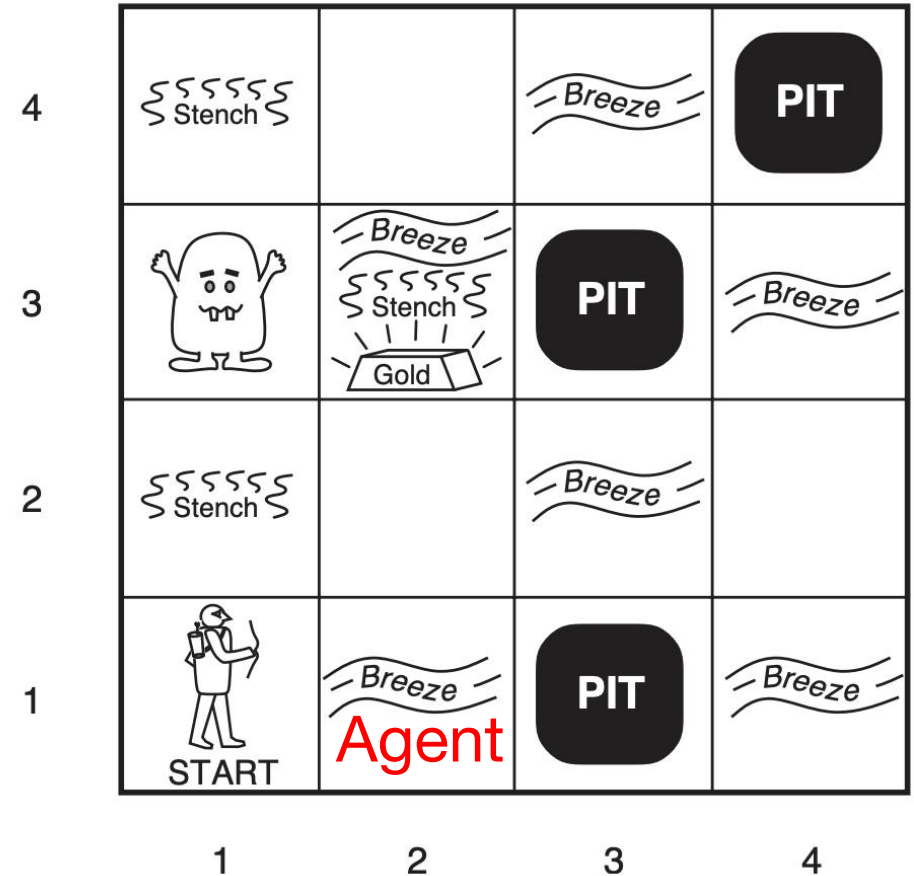
The current state of the world

- $\neg \text{Stench}^0 \wedge \neg \text{Breeze}^0 \wedge \neg \text{Glitter}^0$
 $\wedge \neg \text{Bump}^0 \wedge \neg \text{Scream}^0$
- Forward^0



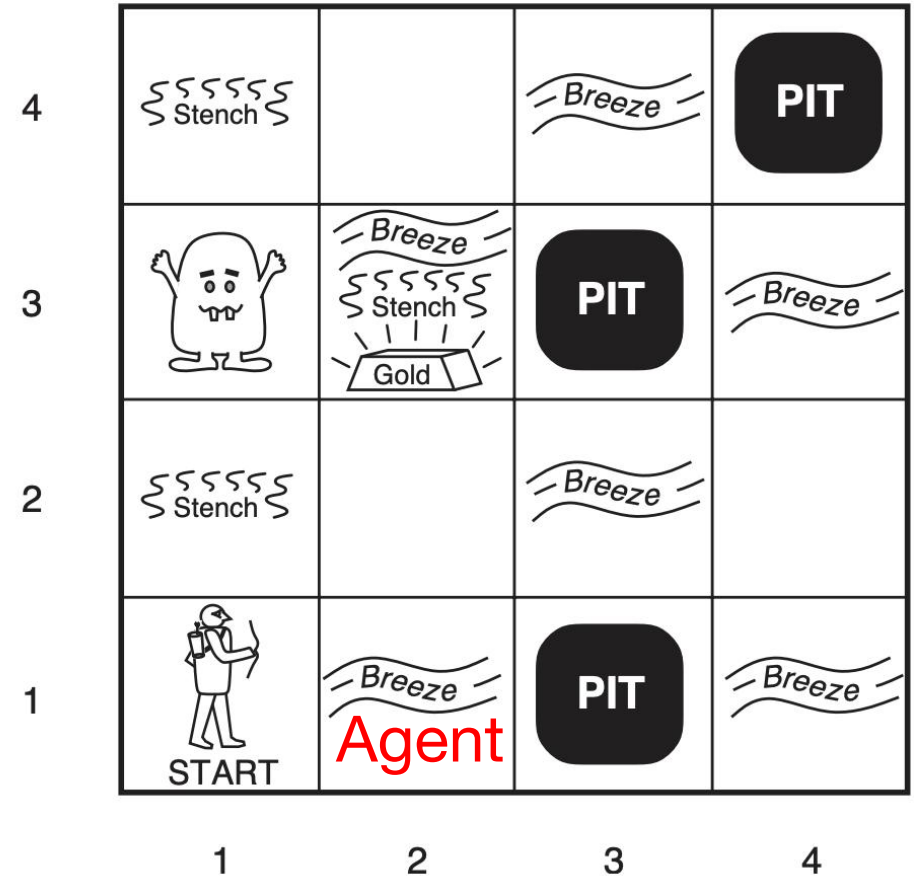
The current state of the world

- $\neg \text{Stench}^1 \wedge \text{Breeze}^1 \wedge \neg \text{Glitter}^1$
 $\wedge \neg \text{Bump}^1 \wedge \neg \text{Screem}^1$
- TurnRight^1



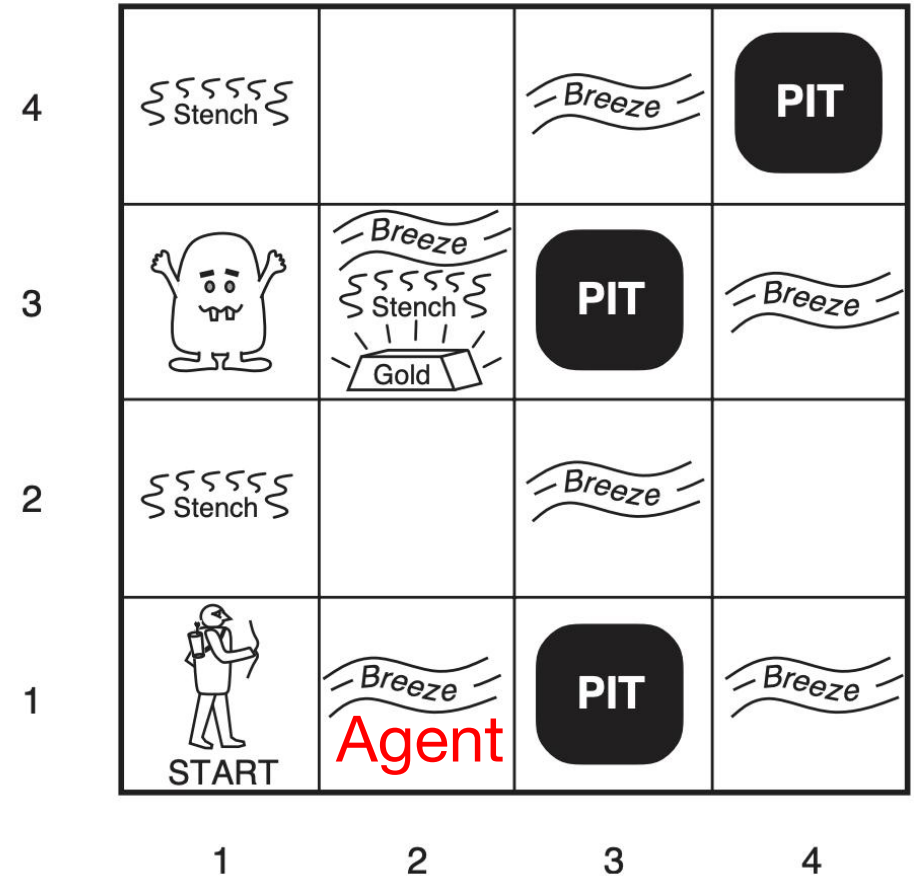
The current state of the world

- $\neg \text{Stench}^2 \wedge \text{Breeze}^2 \wedge \neg \text{Glitter}^2$
 $\wedge \neg \text{Bump}^2 \wedge \neg \text{Scream}^2$
- TurnRight^2



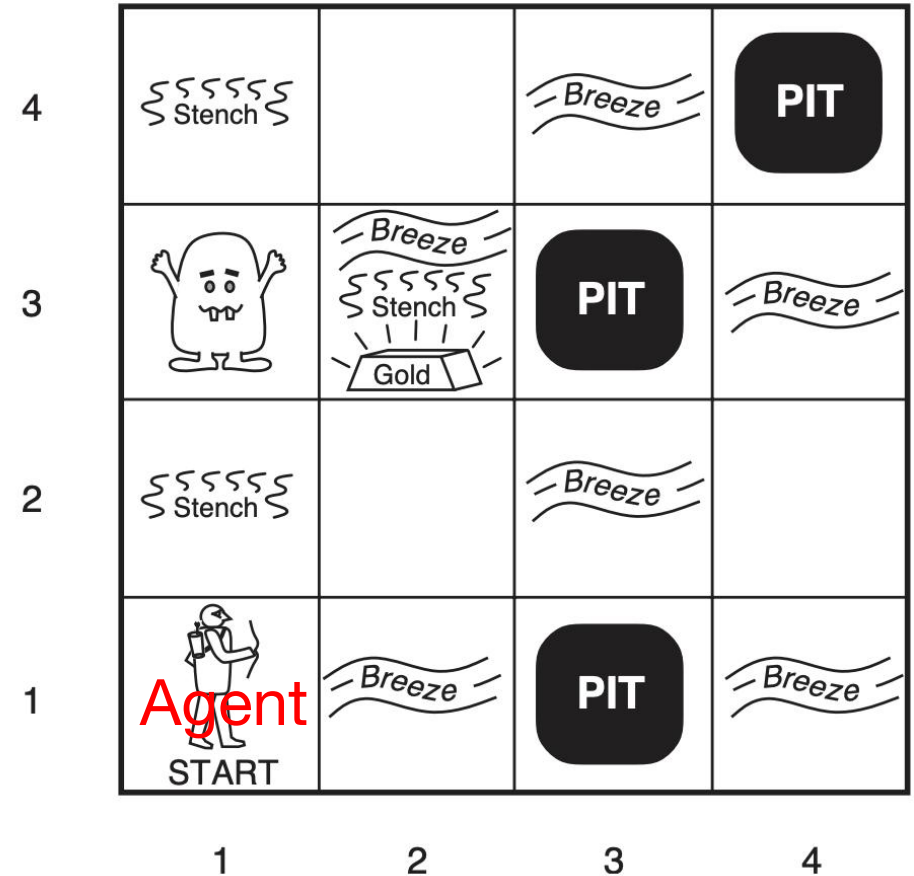
The current state of the world

- $\neg \text{Stench}^3 \wedge \text{Breeze}^3 \wedge \neg \text{Glitter}^3$
 $\wedge \neg \text{Bump}^3 \wedge \neg \text{Scream}^3$
- Forward³



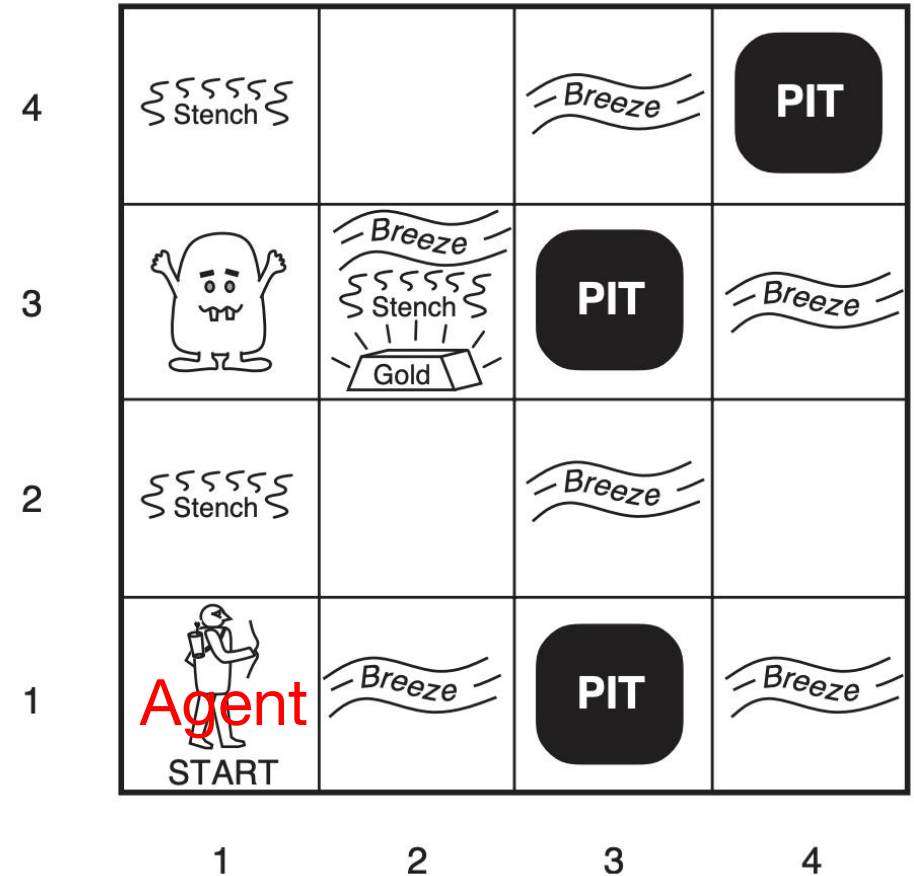
The current state of the world

- $\neg \text{Stench}^4 \wedge \neg \text{Breeze}^4 \wedge \neg \text{Glitter}^4$
 $\wedge \neg \text{Bump}^4 \wedge \neg \text{Screem}^4$
- TurnRight^4



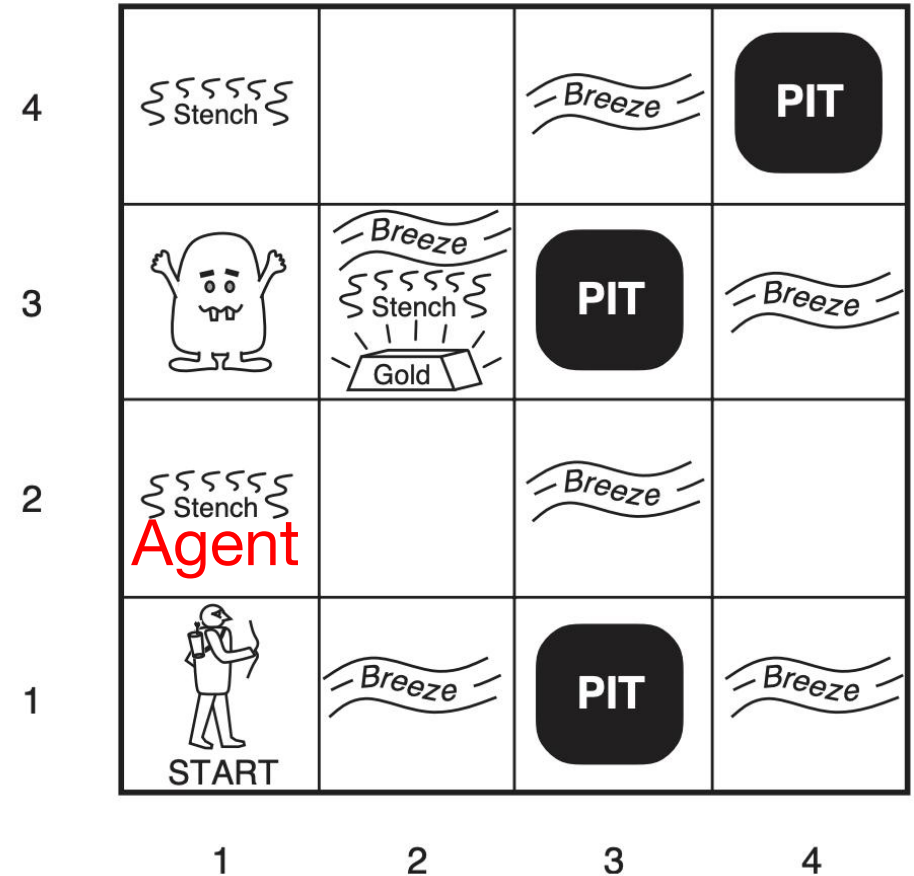
The current state of the world

- $\neg \text{Stench}^5 \wedge \neg \text{Breeze}^5 \wedge \neg \text{Glitter}^5$
 $\wedge \neg \text{Bump}^5 \wedge \neg \text{Scream}^5$
- Forward⁵



The current state of the world

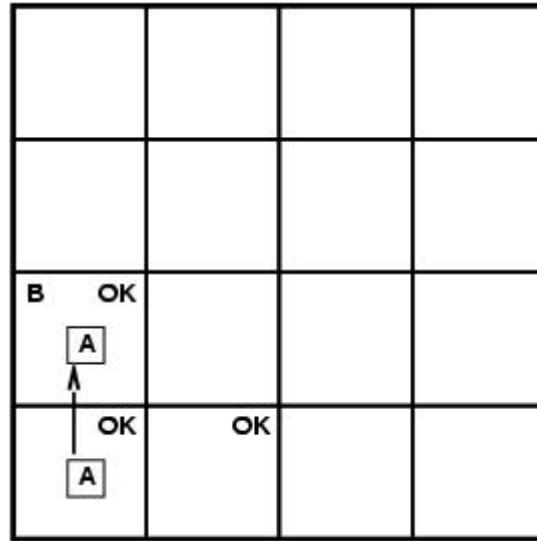
- $\text{Stench}^6 \wedge \neg \text{Breeze}^6 \wedge \neg \text{Glitter}^6$
 $\wedge \neg \text{Bump}^6 \wedge \neg \text{Screem}^6$
- $\text{Ask}(\text{KB}, L_{1,2}^6) = \text{True}$
- $\text{Ask}(\text{KB}, W_{1,3}) = \text{True}$
- $\text{Ask}(\text{KB}, P_{3,1}) = \text{True}$



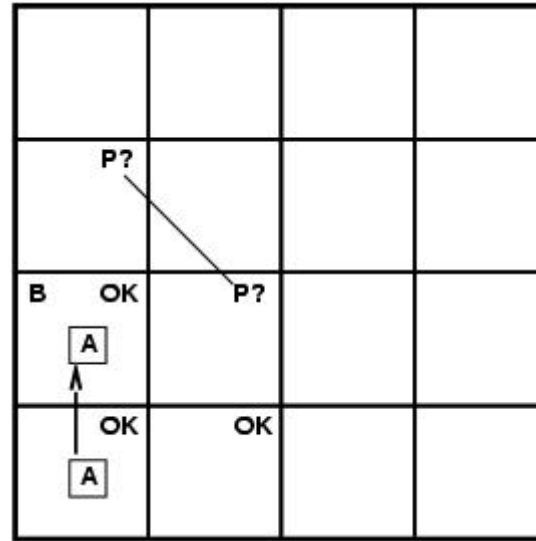
The current state of the world

OK			
OK <div>A</div>	OK		

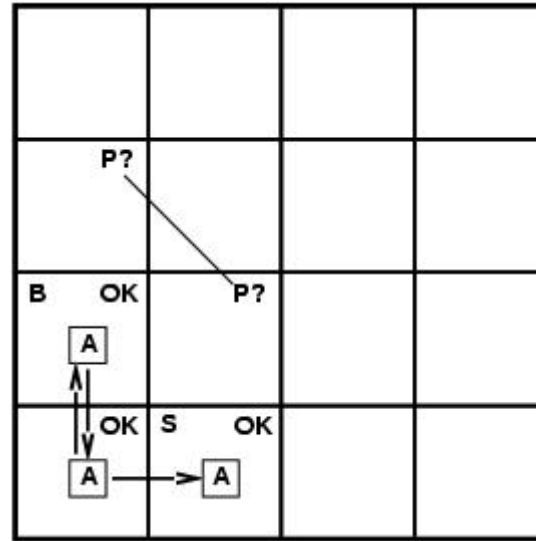
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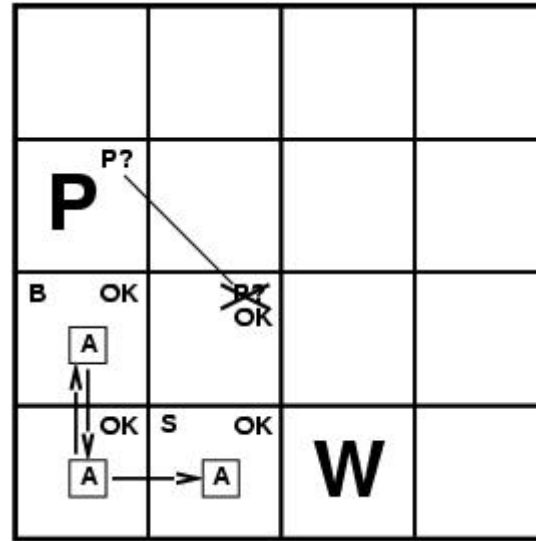
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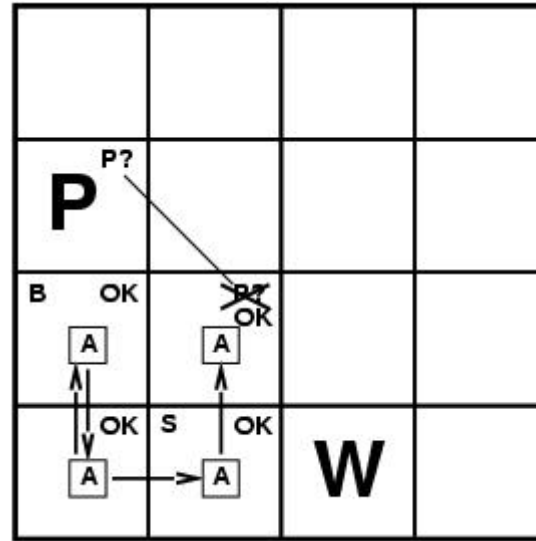
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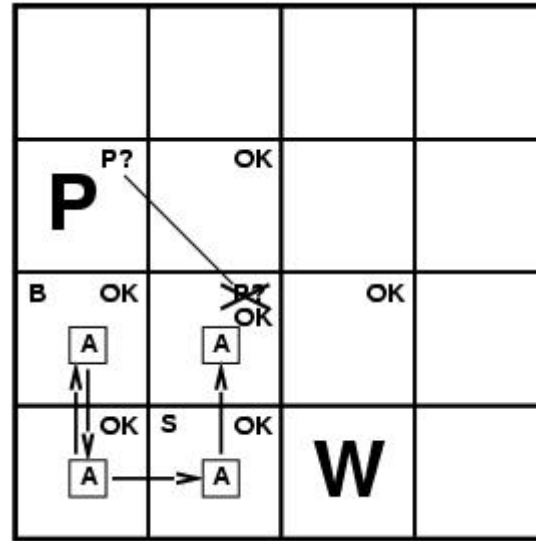
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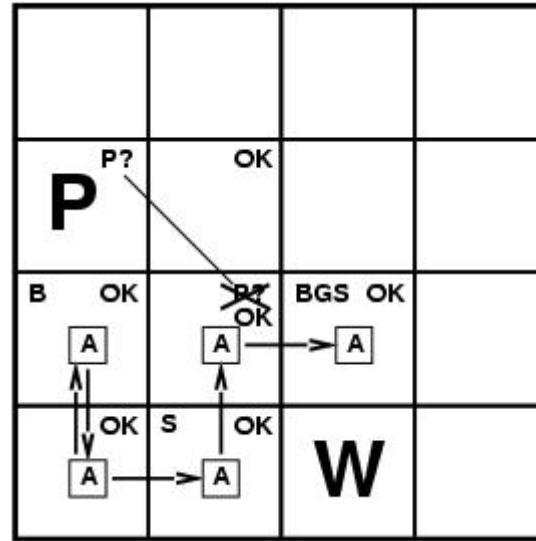
The current state of the world



The current state of the world

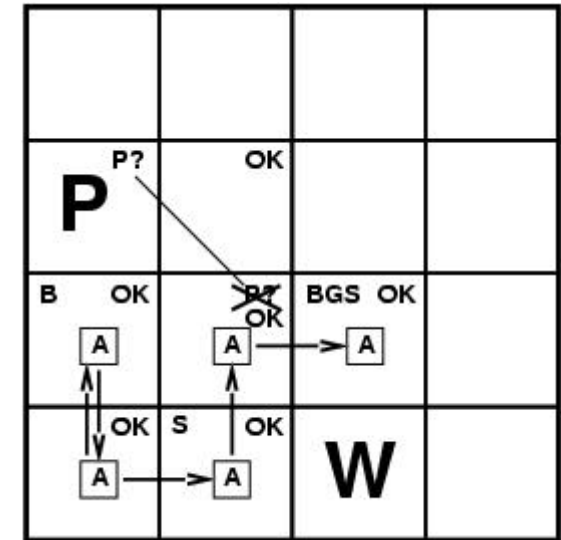


The current state of the world



The current state of the world

- In each case where the agent draws a conclusion from the available Information, that **conclusion is guaranteed to be correct if the available Information is correct.**
- This is a fundamental property of **logical reasoning**



A Hybrid Agent

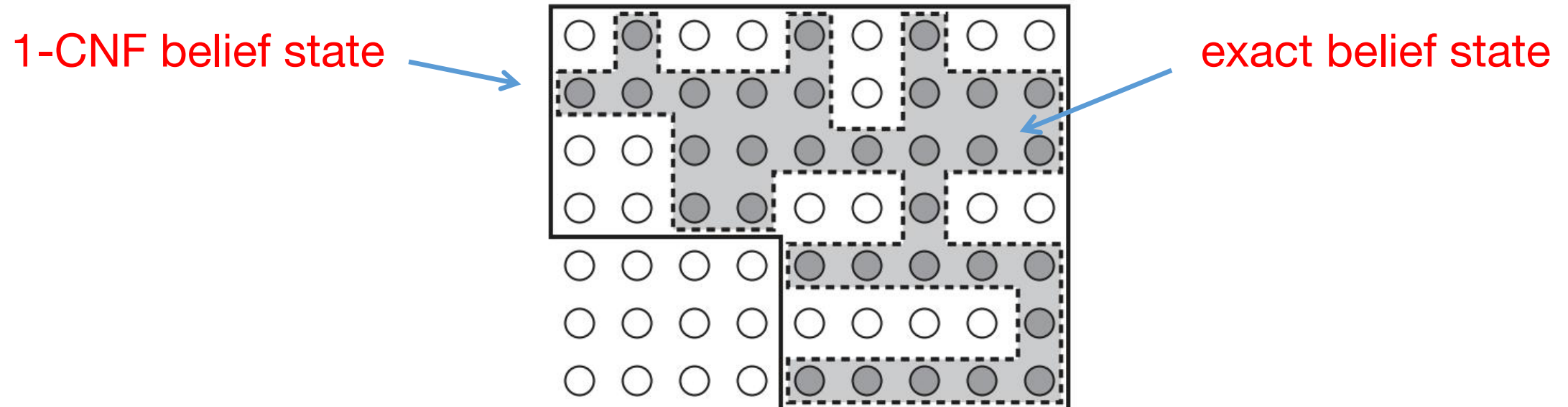
- The agent program maintains and updates a **knowledge base** as well as a **current plan**.
- A* search
 - First, if there is a glitter, the program **constructs a plan** to grab the gold, follow a route back to the initial location.
 - Otherwise, if there is no current plan, the program plans a route to the **closest safe square** that it has not visited yet, making sure the route goes through only safe squares.

Logical State Estimation

- Constant update time of the knowledge base
 - Using a **cache** to store the results of inference.
- **Belief state**:
 - the **short-term memory** of the agent.
 - all of the information the agent has remembered from the previous time at time t
 - every possible set of physical states.
- The set of states of at time 1:
 - $\text{WumpusAlive} \wedge L^1_{2,1} \wedge B_{2,1} \wedge (P_{2,1} \vee P_{2,2})$
- **State estimation**
 - The process of updating the belief state as new percepts arrive

Logical State Estimation

- Approximate state estimation
 - represent belief states as conjunctions of literals, that is, **1-CNF formulas**
- Prove X_t and $\neg X_t$ for each symbol X_t given the belief state at $t - 1$



Example

- Which of the following is correct?
 - $\text{False} \models \text{True}$ **True**
 - $\text{True} \models \text{False}$ **False**
 - $(A \wedge B) \models (A \Leftrightarrow B)$ **True**
 - $A \Leftrightarrow B \models A \vee B$ **False**
 - $A \Leftrightarrow B \models \neg A \vee B$ **True**
 - $(A \vee B) \wedge \neg(A \Rightarrow B)$ is satisfiable **True**
 - $(A \Leftrightarrow B) \wedge (\neg A \vee B)$ is satisfiable **True**

Example

- Consider a vocabulary with only four propositions, A, B, C, D. How many **models** are there for the following sentences?

- $B \vee C$ **12**

- $\neg A \vee \neg B \vee \neg C \vee \neg D$ **15**

Example

- Prove, or find a counterexample to, each of the following assertions

1. If $\alpha \models \gamma$ or $\beta \models \gamma$ (or both) then $(\alpha \wedge \beta) \models \gamma$ **True**

2. If $\alpha \models (\beta \wedge \gamma)$ then $\alpha \models \gamma$ and $\alpha \models \beta$ **True**

3. If $\alpha \models (\beta \vee \gamma)$ then $\alpha \models \gamma$ or $\alpha \models \beta$ (or both) **False**

Example

- A propositional **2-CNF** expression is a conjunction of clauses, each containing exactly 2 literals, e.g.,

$$(A \vee B) \wedge (\neg A \vee C) \wedge (\neg B \vee D) \wedge (\neg C \vee G) \wedge (\neg D \vee G)$$

1. Prove using **resolution** that the above sentence entails G

- Add $\neg G$. Resolve with the last two clauses to produce $\neg C$ and $\neg D$.
- Resolve with the second and third produce $\neg A$ and $\neg B$
- Resolve with the first clause to produce the **empty clause**

Example

- A propositional **2-CNF** expression is a conjunction of clauses, each containing exactly 2 literals, e.g.,

$$(A \vee B) \wedge (\neg A \vee C) \wedge (\neg B \vee D) \wedge (\neg C \vee G) \wedge (\neg D \vee G)$$

2. Two clauses are **semantically distinct** if they are not logically equivalent. How many semantically distinct 2-CNF clauses can be constructed from **n** proposition symbols?

- There are $C(2n, 2) = (2n)(2n-1)/2 = 2n^2-n$ clauses with **two different literals**
- $\neg A \vee A \dots$ are equivalent. So we have $2n^2-2n+1$
- Add $A \vee A \dots$, so we have $2n^2+1$