

Traffic Sign Recognition Classifier

Build a Traffic Sign Recognition Classifier

The goals / steps of this project are the following:

- Load the data set (see below for links to the project data set)
- Explore, summarize and visualize the data set
- Design, train and test a model architecture
- Use the model to make predictions on new images
- Analyze the softmax probabilities of the new images
- Summarize the results with a written report

Rubric Points - Justification

Files Submitted:

- Submission Files :
 - Ipython notebook with code - [Traffic_Sign_Classifier.ipynb](#)
 - HTML output of the code - [Traffic_Sign_Classifier.html](#)
 - Writeup report

Dataset Exploration:

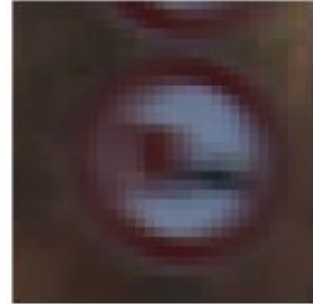
- Dataset Summary
 - Loaded the provided training, test & validation dataset. Based on the dataset, identified the unique set of classes.

```
Number of training examples = 34799
Number of testing examples = 12630
Image data shape = (34799, 32, 32, 3)
Number of classes = 43
```
- Exploratory Visualization
 - Based on the class identifier, identified corresponding sign names from signnames.csv and plotted few images for reference.

Right-of-way at the next intersection



No passing for vehicles over 3.5 metric tons



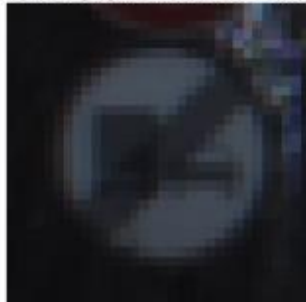
Speed limit (120km/h)



Road work



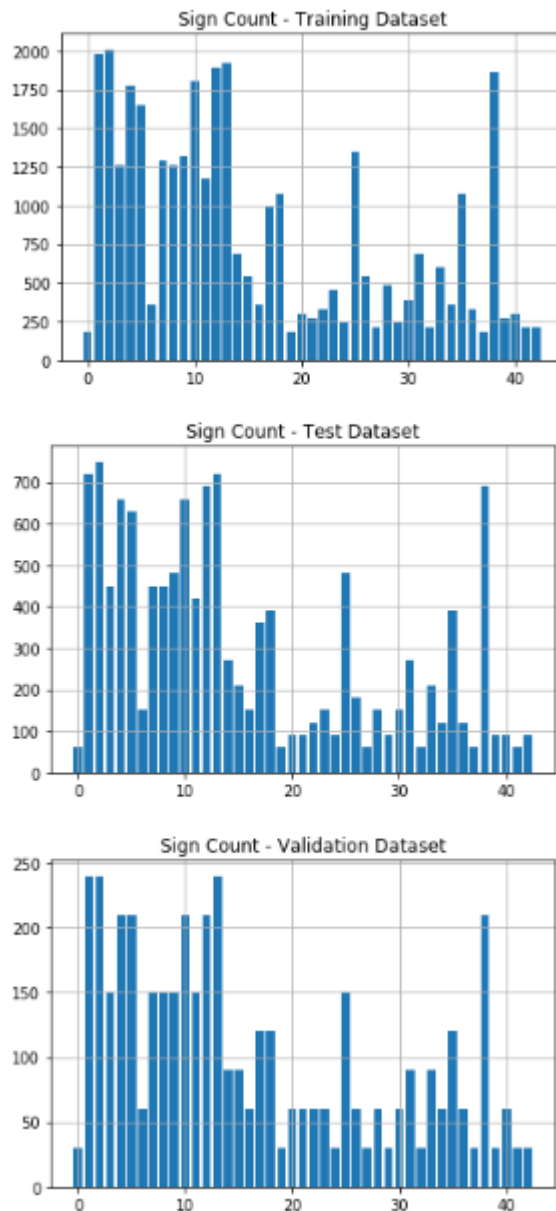
End of no passing by vehicles over 3.5 metric tons



Speed limit (80km/h)



For visualization, grouped the dataset classification class wise and charted using `matplotlib.pyplot.bar` function.



Design and Test a Model Architecture:

- Preprocessing

Under preprocessing phase, below actions are performed

- Grayscale conversion
- Visualize the images for reference

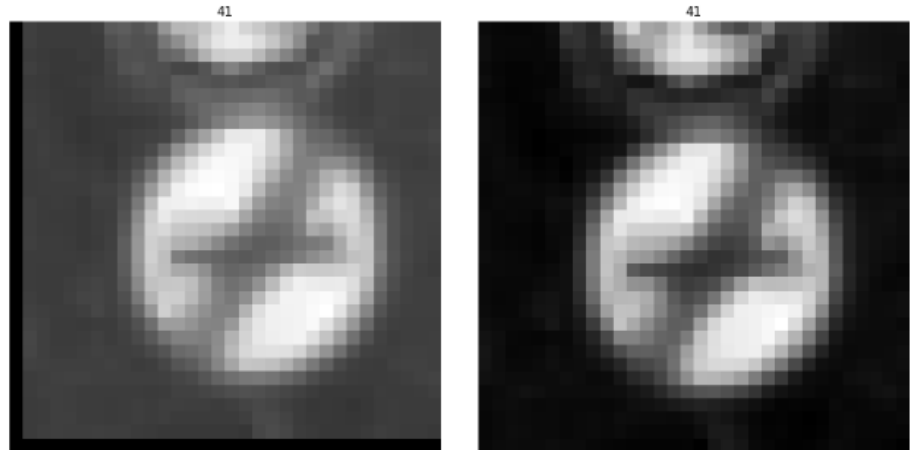
No passing for vehicles over 3.5 metric tons



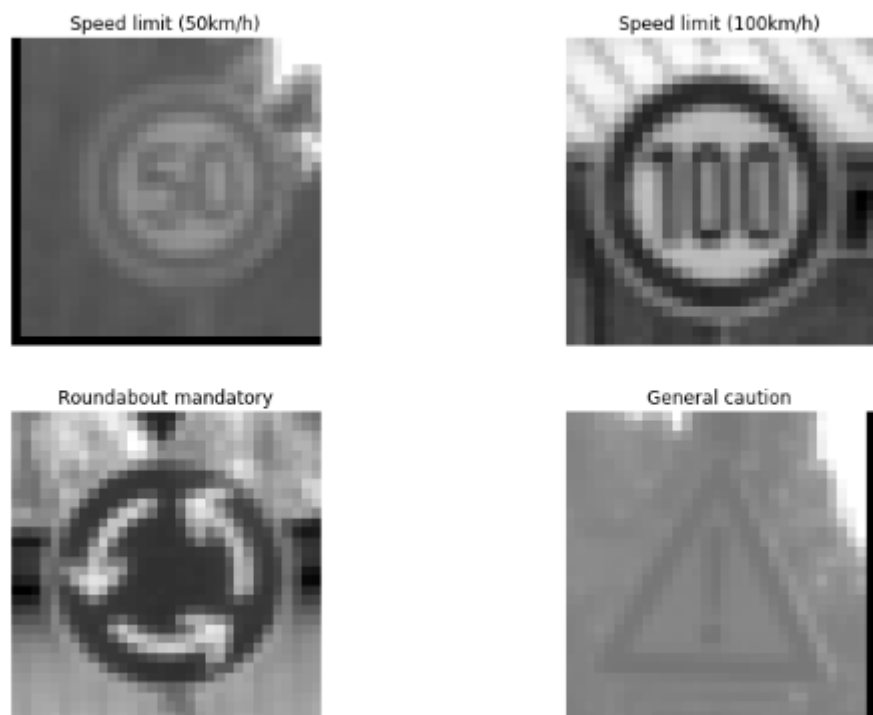
Turn right ahead



- Apply transformations like affine & perspective transformation for retaining lines/planes and convert image from 3D space to 2D space



- Normalize the dataset using log function



- Model Architecture

Modelled a five layer architecture which consists of two convolutional layers with max pool, two ReLU activation function layers and finally added bias.

- Model Training

Prepared Logits with the above LeNet architecture.

With the help of Softmax cross entropy & AdamOptimizer functions, I was training the dataset by fine tuning the hyper parameters like Epochs, Batch_Size & Learning_Rate.

Finally stuck with the below values for hyper parameters,

Epochs – 20 (tried values like 10, 15, 18, 20, 24)

Batch_Size – 200 (tried values like 150, 180, 200, 210, 250)

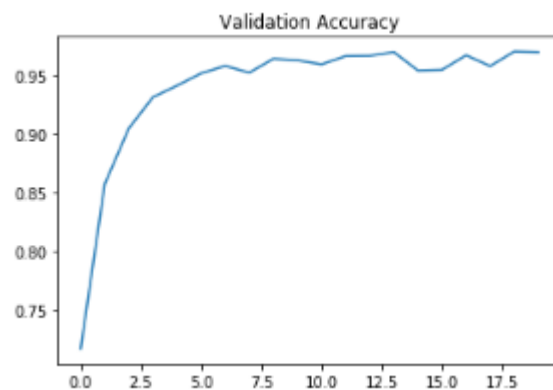
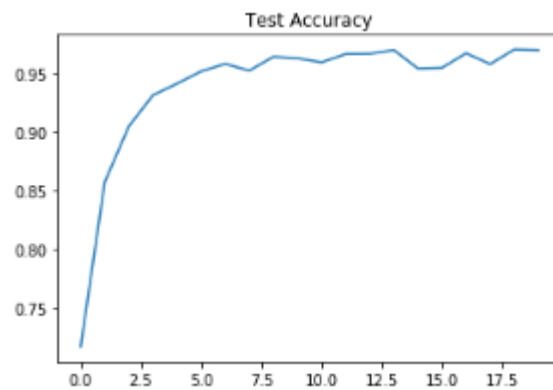
Learning_Rate – 0.001 (tried values like 0.0003, 0.0008, 0.0009, 0.01)

Dropout – 1.0

I was able to observe deviations between test & validation accuracy with different parameter values,

- Solution Approach

I was using the similar LeNet architecture which was explained during the classroom. I have added one sub convolution layer in Layer 2 convolution to improve the accuracy of the LeNet pipeline. Hyper parameters are tuned based on the accuracy resulted below.



```
INFO:tensorflow:Restoring parameters from ./lenet_arch
Train Dataset Accuracy = 0.999
Validation Dataset Accuracy = 0.970
Test Dataset Accuracy = 0.943
```

Test a Model on New Images:

- Acquiring New Images

Downloaded few images of traffic signs from internet and loaded with corresponding labels for evaluation.



Characteristics of the images (3.png & 5.png) that would make the model difficult to classify are,

- Image capture angle & rotation
- Lighting conditions

Pre-processing step would have prepared the test images for better prediction that resulted in 100% accuracy.

- Performance on New Images

With the arrived LeNet Architecture, I've evaluated the test images and resulted with appropriate prediction as below.

Priority road



Speed limit (30km/h)



Turn left ahead



Keep right



Road work



General caution



```
INFO:tensorflow:Restoring parameters from ./lenet_arch
Image 1
Image Accuracy = 1.000

INFO:tensorflow:Restoring parameters from ./lenet_arch
Image 2
Image Accuracy = 1.000

INFO:tensorflow:Restoring parameters from ./lenet_arch
Image 3
Image Accuracy = 1.000

INFO:tensorflow:Restoring parameters from ./lenet_arch
Image 4
Image Accuracy = 1.000

INFO:tensorflow:Restoring parameters from ./lenet_arch
Image 5
Image Accuracy = 1.000

INFO:tensorflow:Restoring parameters from ./lenet_arch
Image 6
Image Accuracy = 1.000
```

- Model Certainty - Softmax Probabilities

The model was able to correctly guess 5 of the 5 traffic signals, which resulted in 100% accuracy.

INFO:tensorflow:Restoring parameters from ./lenet_arch

