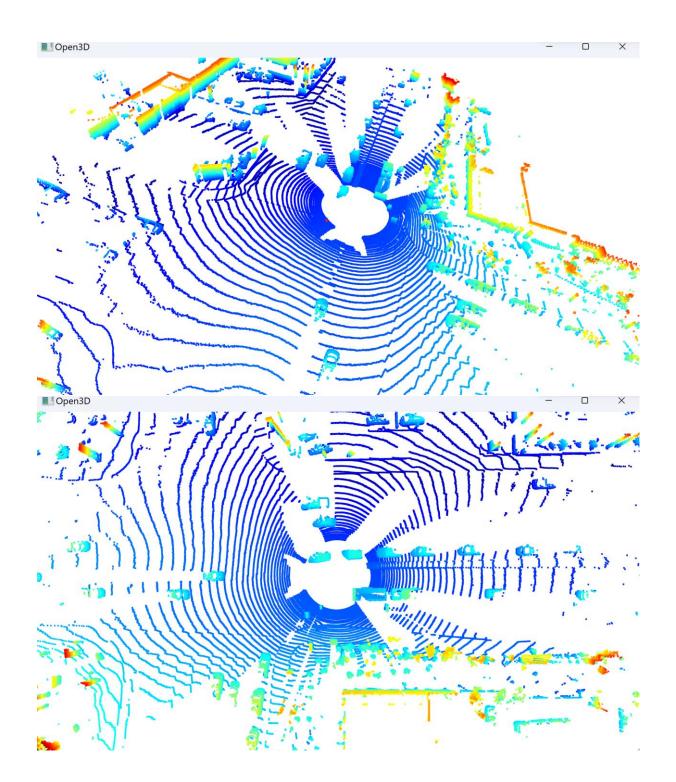# Visualize lidar point-cloud (ID_S1_EX2)

Images with varying visibility have been displayed below. The Different visibility patterns examined are:

- Cars in the same lane.
- Cars in adjacent lane.
- Cars behind the ego vehicle.
- Cars on incoming lane.
- Cars at faraway distance

Different features examined are:

- Tyres
- Rear view mirror
- Front bumper pattern
- Rear bumper
- Car roof
- Car windows