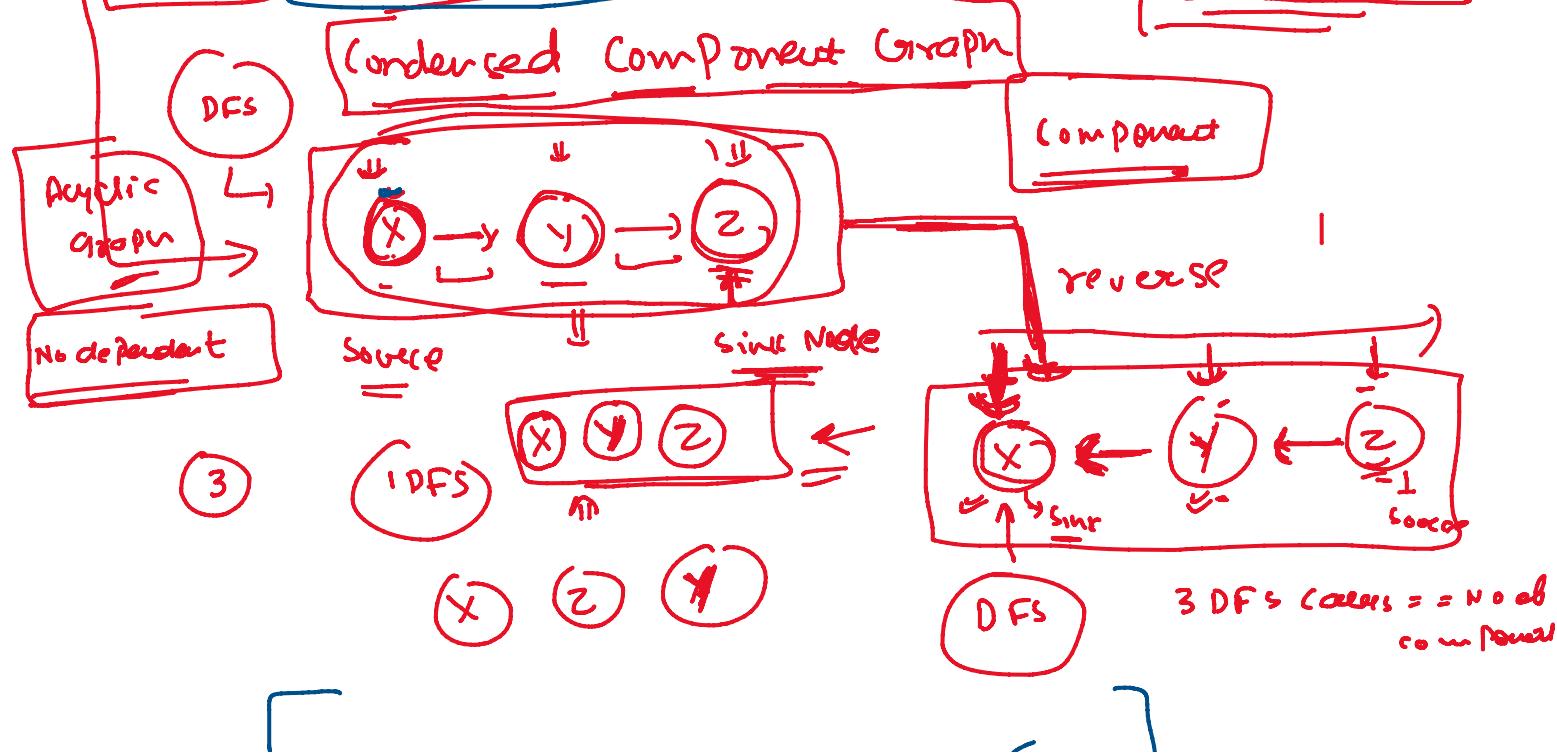
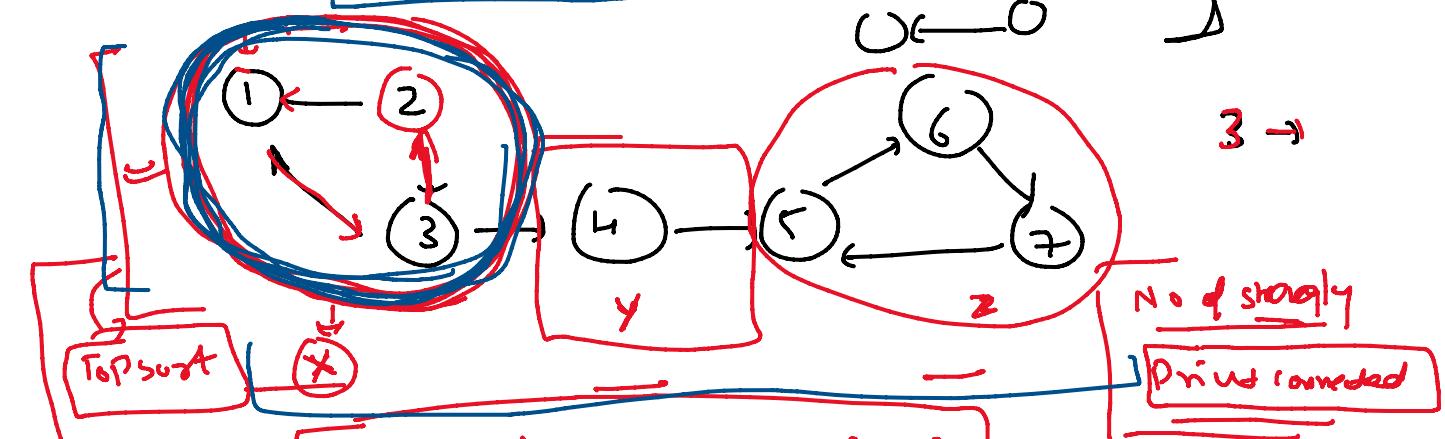
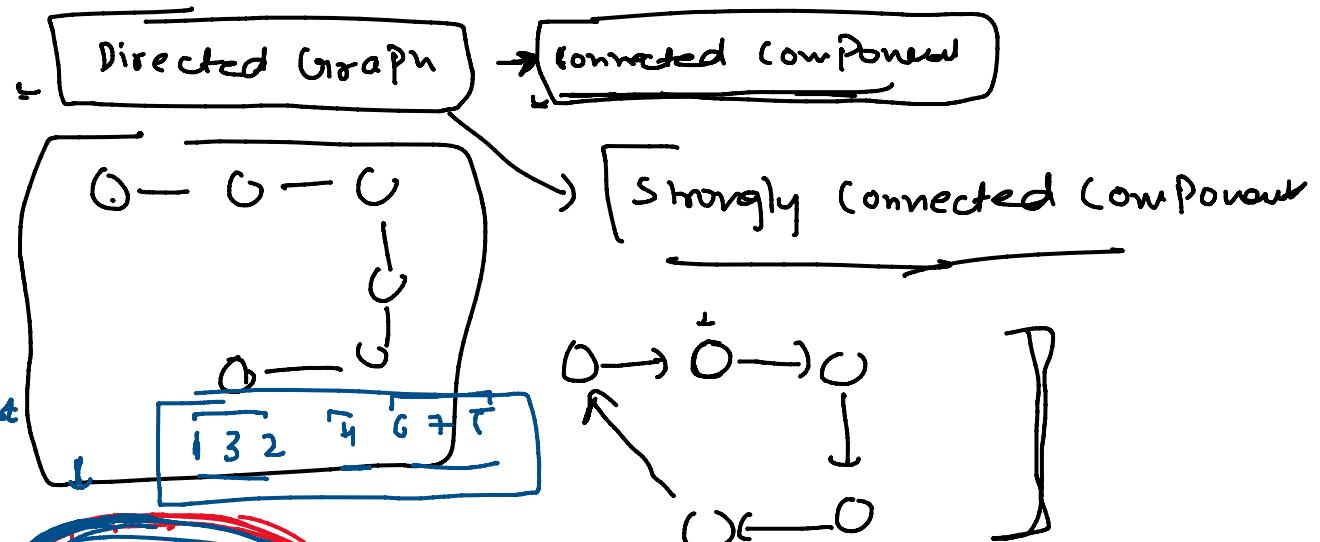
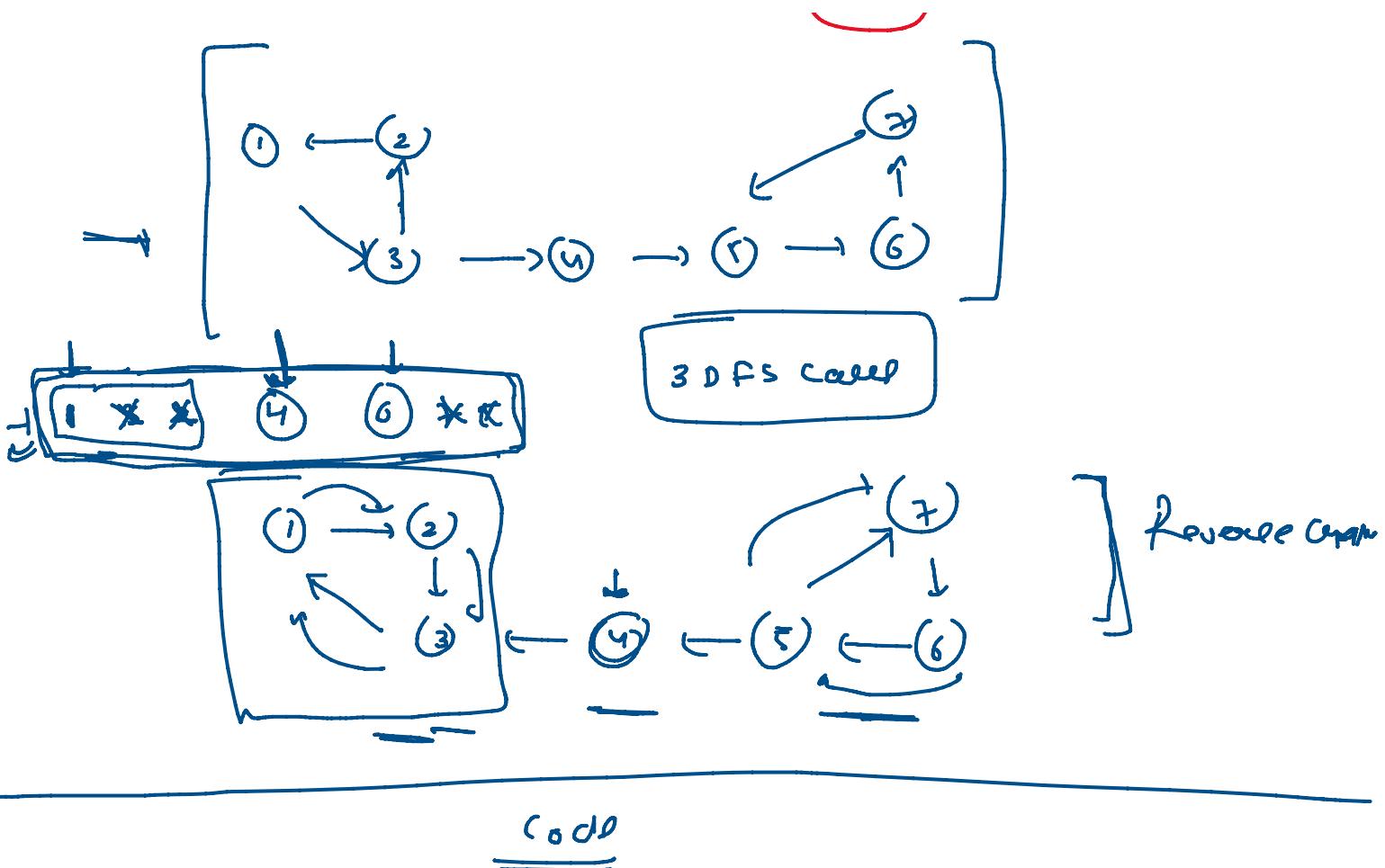


Kosaraju Algorithm

Connected Component





```
vector<vector<int>> adj(n);
```

```
vector<int> top;
```

```
vector<int> vis(n, 0);
```

```
for (int i = 1; i <= n; i++)
```

```
{ if (!vis[i])
```

```
    dfs(i, top, adj, vis);
```

```
}
```

$\Rightarrow$  [reverse (top.begin(), top.end())]

```
vector<vector<int>> traversal(n + 1);
```

```
void dfs (int node, vector<int> adj, vector<int> &vis)
```

```
{ vis[node] = 1;
```

```
for (auto i : adj[node])
```

```
{ if (!vis[i])
```

```
    dfs(i, --);
```

```
    top.push_back(node);
```

```
vector<vector<int>> transpose(until);
```

```
for (int i = 1; i <= r; i++)
```

```
{ for (auto j : adj[i])
```

```
    transpose[i].push_back(j);
```

```
    "
```

$i \leftrightarrow j$

Reverse  
Graph

```
vector<int> vis2(n, 0); int count = 0;
```

```
for (int i = 0; i < top.size(); i++)
```

```
{ if (!vis2[top[i]])
```

```
{ dfs2(top[i], vis2, transpose);  
    count++; }
```

```
"
```

```
void dfs2(int node,  
          vector<int>& vis,
```

```
vector<vector<int>> transpose)
```

```
; { vis[node] = 1;
```

```
cout << node << " ";
```

```
for (auto i : transpose[node])
```

```
{ if (vis[i] == 0)
```

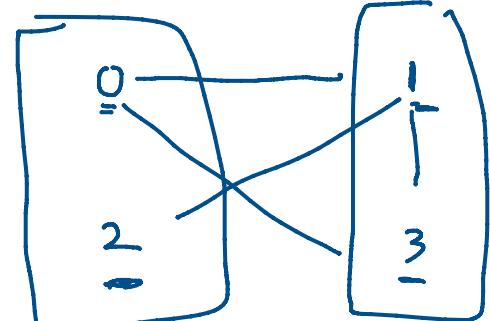
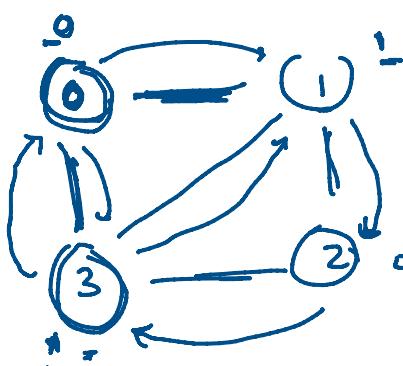
```
dfs2(i, vis, transpose);
```

```
"
```

Euler Path, Euler Circuit

Hamiltonian Cycle

0, 1



Bipartite

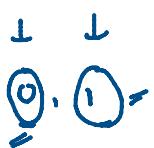
# Bipartite

```

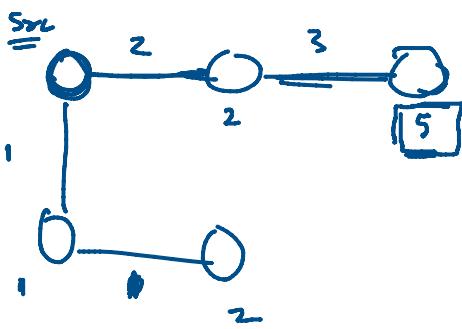
bool bip(vector<vector<int>>& graph,int node,vector<int>& color,int col)
{
    color[node]=col;
    for(auto i:graph[node])
    {
        if(color[i]==-1)
        {
            if(color[i]==col) return false;
        }
        else
        {
            if(bip(graph,i,color,col^1))
            {
                ;
            }
            else return false;
        }
    }
    return true;
}

bool isBipartite(vector<vector<int>>& graph) {
    int i,j,k,n;
    n=graph.size();
    vector<int> color(n,-1);
    for(i=0;i<n;i++)
    {
        if(color[i]==-1)
        {
            bool ans=bip(graph,i,color,0);
            if(!ans) return false;
        }
    }
    return true;
}

```



visAns



BFS

Direction

Min distance Node

Set

Priority queue

MinHeap

