- 1. A binary image A and a structuring element h are shown below.
  - a. Compute the erosion of h over A. The resulting image should have the same size as the original image. To do that, assume any pixel beyond the border of the image has value 0.
  - b. Explain which are the effects of erosion in the mask of an undetermined object. You can base your explanation on the resulting image from  $question \ a$ .

|   |   |   |   | A |   |   |   |   |
|---|---|---|---|---|---|---|---|---|
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 0 | 1 | 0 | 0 | 1 | 1 | 1 | 1 | 0 |
| 0 | 1 | 1 | 0 | 1 | 1 | 1 | 1 | 0 |
| 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 |
| 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 |
| 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 |
| 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 0 |
| 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

| h |   |   |  |  |  |  |  |  |
|---|---|---|--|--|--|--|--|--|
| 1 | 1 | 1 |  |  |  |  |  |  |
| 1 | 1 | 1 |  |  |  |  |  |  |
| 1 | 1 | 1 |  |  |  |  |  |  |

- 2. An MxN data matrix is presented below, where M denotes the number of samples and N denotes the number of descriptors. Threre are also two centroids. They come from running the K-means algorithm just after a specific iteration. Starting at this point, compute the next iteration of the K-means algorithm. To do that:
  - a. Do the cluster assignment of the examples to the centroids you have received.
  - b. Compute the new centroids from the cluster assignment of the previous section.

$$X = \begin{bmatrix} 3 & 1 \\ 2 & 0 \\ 1 & 2 \\ 3 & 4 \\ -2 & 1 \\ -1 & 3 \\ -3 & 2 \\ 0 & 5 \end{bmatrix}; c_1 = \begin{bmatrix} 0 \\ 2 \end{bmatrix}; c_2 = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

- 3. Consider a classification problem where the considered classes are:
  - i. Apples of different colors
  - ii. Bananas

Discuss if you would use the following descriptors for the task:

- a. Mean luminance
- b. Eccentricity
- c. Perimeter of the object / Perimeter of its convex hull ratio
- d. Mean of a and b components from Lab colorspace
- e. Variance of luminance (texture)

Assume the segmentations are always correct. Justify your answers.

4. The following data matrices are presented:

$$X_{train} = \begin{bmatrix} -1 & 1 \\ 0 & -1 \\ -2 & -1 \\ -1 & -2 \\ 0 & 1 \\ 3 & -1 \\ 2 & 1 \\ 1 & 2 \end{bmatrix}, y_{train} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \\ 1 \\ 1 \end{bmatrix}, X_{test} = \begin{bmatrix} 0 & 3 \\ -1 & 0 \\ -2 & -3 \\ 2 & -1 \end{bmatrix}, y_{test} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}$$

It was decided to use the **Nearest Neighbor** classifier to get the predictions for the  $X_{test}$  data matrix. The chosen distance measure was the euclidean distance:

$$d(p,q) = \sqrt{(x_p - x_q)^2 + (y_p - y_q)^2}$$

Questions:

- a. Compute the predictions vector for both data matrices. Remember you can draw a coordinate axis and plot the dots to evaluate the distances.
- b. Compute the accuracy for both subsets.  $Accuracy = \frac{TP+TN}{TP+TN+FP+FN}$
- 5. A set of statements is presented. Verify if each of them is true or false. Justify your answer.
  - a. The most reliable evaluation measure of the performance of a classifier should be obtained from the training set.
  - b. The test set can contain a few data vectors previously seen in training.
  - c. We say a classifier has overfitted the data when there is a considerable difference between training and test performance.
  - d. The area under the ROC curve is bounded between 0 and 1.
  - e. Assume a binary classification problem. The descriptor vectors have dimension 3 and the classifier is Gaussian. To train the system, the parameters that define the class-Gaussians are to be estimated. Counting means and covariances, 18 parameters will be estimated.