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## **Question 4**

```
In [1]: import numpy as np
         x = np.array([[1, 1, 1, 1], [4, -2, 3, -5]]).T
Out[1]: array([[ 1, 4],
                [1, -2],
                [ 1, 3],
                [ 1, -5]])
In [5]: P = x@np.linalg.inv(x.T@x)@x.T
Out[5]: array([[ 0.5462963 , 0.10185185, 0.47222222, -0.12037037],
                [0.10185185, 0.32407407, 0.13888889, 0.43518519],
                [ 0.47222222, 0.13888889, 0.41666667, -0.02777778],
                [-0.12037037, 0.43518519, -0.02777778, 0.71296296]])
In [8]: M = np.identity(P.shape[0]) - P
Out[8]: array([[ 0.4537037 , -0.10185185, -0.47222222, 0.12037037],
                [-0.10185185, 0.67592593, -0.13888889, -0.43518519],
                [-0.47222222, -0.13888889, 0.58333333, 0.02777778],
                [0.12037037, -0.43518519, 0.02777778, 0.28703704]])
In [9]: M@P # Almost equal to zero
Out[9]: array([[ 2.34199567e-17, -3.03636098e-18, 1.62639249e-17,
                -2.13401922e-17],
                [-3.03636098e-18, 4.98762744e-18, -4.01199421e-18,
                 4.53645656e-17],
                [-1.14916507e-17, -4.01199421e-18, 1.24750176e-18,
                -1.60051442e-17],
                [-2.82790861e-17, 3.14867778e-17, -1.42704207e-17,
                 3.60555969e-17]])
In [10]: # (a)
         np.isclose(M@P, 0)
Out[10]: array([[ True, True, True, True],
               [ True, True, True],
                [ True, True, True],
                [ True, True, True]])
         (a) MP = 0
In [11]: Q = np.array([[1, 3], [2, 8]])
Out[11]: array([[1, 3],
                [2, 8]])
In [15]: x2 = x@Q
```

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(b) P and M are unchanged after the transformation (multiplication by Q)