ベクトル解析

1 円柱座標

1.1 準備

基本事項の整理。直交座標との関係性。

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$z = z$$
(1)

上から分かる以下二つの式。

$$r = \sqrt{x^2 + y^2}$$

$$\theta = \tan^{-1} \frac{y}{x}$$
(2)

1.2 勾配

勾配の成分を一つ一つ計算していく。まずはx成分から

$$\frac{\partial}{\partial x} = \frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial}{\partial \theta} + \frac{\partial z}{\partial x} \frac{\partial}{\partial z}$$
 (3)

$$\frac{\partial r}{\partial x} = \frac{\partial}{\partial x} \sqrt{x^2 + y^2} = \frac{x}{\sqrt{x^2 + y^2}} = \frac{x}{r} = \cos \theta \tag{4}$$

$$\frac{\partial \theta}{\partial x} = \frac{\partial}{\partial x} \tan^{-1} \frac{y}{x} = -\frac{y}{x} \cdot \frac{1}{1 + (\frac{y}{x})^2} = -\frac{y}{x^2 + y^2} = -\frac{\sin \theta}{r}$$
 (5)

$$\frac{\partial z}{\partial x} = 0 \tag{6}$$

(4)(5)(6) を (3) の式に代入すると

$$\frac{\partial}{\partial x} = \cos\theta \frac{\partial}{\partial r} - \frac{\sin\theta}{r} \frac{\partial}{\partial \theta} \tag{7}$$

y成分も同様に計算します。

$$\frac{\partial}{\partial y} = \frac{\partial r}{\partial y}\frac{\partial}{\partial r} + \frac{\partial \theta}{\partial y}\frac{\partial}{\partial \theta} + \frac{\partial z}{\partial y}\frac{\partial}{\partial z}$$
 (8)

$$\frac{\partial r}{\partial y} = \frac{\partial}{\partial y} \sqrt{x^2 + y^2} = \frac{y}{\sqrt{x^2 + y^2}} = \frac{y}{r} = \sin \theta \tag{9}$$

$$\frac{\partial \theta}{\partial y} = \frac{\partial}{\partial y} \tan^{-1} \frac{y}{x} = \frac{1}{x} \cdot \frac{1}{1 + (\frac{y}{x})^2} = \frac{x}{x^2 + y^2} = \frac{\cos \theta}{r}$$
 (10)

$$\frac{\partial z}{\partial y} = 0 \tag{11}$$

(9)(10)(11) を (8) の式に代入すると

$$\frac{\partial}{\partial y} = \sin \theta \frac{\partial}{\partial r} + \frac{\cos \theta}{r} \frac{\partial}{\partial \theta} \tag{12}$$

z 成分は

$$\frac{\partial}{\partial z}$$
 (13)

以上より

$$\nabla = \frac{\partial}{\partial x} \mathbf{e}_{x} + \frac{\partial}{\partial y} \mathbf{e}_{y} + \frac{\partial}{\partial z} \mathbf{e}_{z}$$

$$= \left(\cos\theta \frac{\partial}{\partial r} - \frac{\sin\theta}{r} \frac{\partial}{\partial \theta}\right) \mathbf{e}_{x} + \left(\sin\theta \frac{\partial}{\partial r} + \frac{\cos\theta}{r} \frac{\partial}{\partial \theta}\right) \mathbf{e}_{y} + \frac{\partial}{\partial z} \mathbf{e}_{z}$$

$$= \left(\cos\theta \frac{\partial}{\partial r} - \frac{\sin\theta}{r} \frac{\partial}{\partial \theta}\right) (\mathbf{e}_{r} \cos\theta - \mathbf{e}_{\theta} \sin\theta) + \left(\sin\theta \frac{\partial}{\partial r} + \frac{\cos\theta}{r} \frac{\partial}{\partial \theta}\right) (\mathbf{e}_{r} \sin\theta + \mathbf{e}_{\theta} \cos\theta) + \frac{\partial}{\partial z} \mathbf{e}_{z}$$

$$= \frac{\partial}{\partial r} \mathbf{e}_{r} + \frac{1}{r} \frac{\partial}{\partial \theta} \mathbf{e}_{\theta} + \frac{\partial}{\partial z} \mathbf{e}_{z}$$
(14)

1.3 発散

$$\mathbf{A} = A_r \mathbf{e_r} + A_\theta \mathbf{e_\theta} + A_z \mathbf{e_z} \tag{15}$$

ここで

$$\nabla \cdot \mathbf{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z} \tag{16}$$

右辺第一項

$$\frac{\partial A_x}{\partial x} = \frac{\partial r}{\partial x} \frac{\partial A_x}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial A_x}{\partial \theta} + \frac{\partial z}{\partial x} \frac{\partial A_x}{\partial z}$$

$$= \cos \theta \frac{\partial A_x}{\partial r} - \frac{\sin \theta}{r} \frac{\partial A_x}{\partial \theta}$$

$$= \cos \theta \left(\frac{\partial A_r}{\partial r} \cos \theta - \frac{A_\theta}{\partial r} \sin \theta \right) - \frac{\sin \theta}{r} \left(-A_r \sin \theta + \frac{\partial A_r}{\partial \theta} \cos \theta - A_\theta \cos \theta - \frac{A_\theta}{\partial \theta} \sin \theta \right)$$
(17)

右辺第二項

$$\frac{\partial A_y}{\partial y} = \frac{\partial r}{\partial y} \frac{\partial A_y}{\partial r} + \frac{\partial \theta}{\partial y} \frac{\partial A_y}{\partial \theta} + \frac{\partial z}{\partial y} \frac{\partial A_y}{\partial z}$$

$$= \sin \theta \frac{\partial A_y}{\partial r} + \frac{\cos \theta}{r} \frac{\partial A_y}{\partial \theta}$$

$$= \sin \theta \left(\frac{\partial A_r}{\partial r} \sin \theta + \frac{A_\theta}{\partial r} \cos \theta \right) + \frac{\cos \theta}{r} \left(A_r \cos \theta + \frac{\partial A_r}{\partial \theta} \sin \theta - A_\theta \sin \theta + \frac{A_\theta}{\partial \theta} \cos \theta \right)$$
(18)

右辺第三項

$$\frac{\partial A_z}{\partial z} \tag{19}$$

これらの変形において、(4)(5)(6) を使用した。これらの結果を、(16) に代入して整理すると

$$\nabla \cdot \mathbf{A} = \frac{\partial A_r}{\partial r} + \frac{A_r}{r} + \frac{1}{r} \frac{\partial A_{\theta}}{\partial \theta} + \frac{\partial A_z}{\partial z}$$

$$= \frac{1}{r} \frac{\partial}{\partial r} (rA_r) + \frac{1}{r} \frac{\partial A_{\theta}}{\partial \theta} + \frac{\partial A_z}{\partial z}$$
(20)

1.4 ラプラシアン

$$\Delta f = \nabla \cdot (\nabla f) = \nabla \cdot \left(\frac{\partial f}{\partial r} e_r + \frac{1}{r} \frac{\partial f}{\partial \theta} e_{\theta} + \frac{\partial f}{\partial z} e_z \right)$$
 (21)

ただし、勾配の式を利用した。ここで

$$A_{r} = \frac{\partial f}{\partial r}$$

$$A_{\theta} = \frac{1}{r} \frac{\partial f}{\partial \theta}$$

$$A_{z} = \frac{\partial f}{\partial z}$$
(22)

と考えて、(20)を適用すると

$$\Delta f = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial f}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2} + \frac{\partial^2 f}{\partial z^2}$$
 (23)

2 極座標

基本事項の整理。直交座標との関係性。

$$x = r \sin \theta \cos \phi$$

$$y = r \sin \theta \sin \phi$$

$$z = r \cos \theta$$
(24)

上から分かる以下3つの式。

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\phi = \tan^{-1} \frac{y}{x}$$

$$\theta = \cos^{-1} \frac{z}{\sqrt{x^2 + y^2 + z^2}}$$
(25)

2.1 勾配

勾配の成分を一つ一つ計算していく。まずはx成分から

$$\frac{\partial}{\partial x} = \frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial}{\partial \theta} + \frac{\partial \phi}{\partial x} \frac{\partial}{\partial \phi}$$
 (26)

$$\frac{\partial r}{\partial x} = \frac{\partial}{\partial x} \sqrt{x^2 + y^2 + z^2} = \frac{x}{\sqrt{x^2 + y^2 + z^2}} = \frac{x}{r} = \sin\theta\cos\phi \tag{27}$$

$$\frac{\partial \theta}{\partial x} = \frac{\partial}{\partial x} \cos^{-1} \frac{z}{\sqrt{x^2 + y^2 + z^2}} = \frac{1}{r \sin \theta} \cdot \frac{r \cos \theta}{r^2} \cdot (r \sin \theta \cos \phi) = \frac{\cos \theta \cos \phi}{r}$$
 (28)

$$\frac{\partial \phi}{\partial x} = -\frac{y}{x^2 + y^2} = -\frac{r \sin \theta \sin \phi}{r^2 \sin^2 \theta} = -\frac{\sin \phi}{r \sin \theta}$$
 (29)

(27)(28)(29) を (26) の式に代入すると

$$\frac{\partial}{\partial x} = \sin \theta \cos \phi \frac{\partial}{\partial r} + \frac{1}{r} \cos \theta \cos \phi \frac{\partial}{\partial \theta} - \frac{\sin \phi}{r \sin \theta} \frac{\partial}{\partial \phi}$$
 (30)

y成分も同様に計算します。

$$\frac{\partial}{\partial y} = \sin \theta \sin \phi \frac{\partial}{\partial r} + \frac{1}{r} \cos \theta \sin \phi \frac{\partial}{\partial \theta} + \frac{\cos \phi}{r \sin \theta} \frac{\partial}{\partial \phi}$$
 (31)

z成分は

$$\frac{\partial}{\partial z} = \cos \theta \frac{\partial}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta}$$
 (32)

以上より

$$\nabla = \frac{\partial}{\partial x} \mathbf{e_x} + \frac{\partial}{\partial y} \mathbf{e_y} + \frac{\partial}{\partial z} \mathbf{e_z}$$
 (33)

を計算していく。ここで基底変換に対して以下の式が成立。

$$e_{x} = \sin \theta \cos \phi e_{r} + \cos \theta \cos \phi e_{\theta} - \sin \phi e_{\phi}$$

$$e_{y} = \sin \theta \sin \phi e_{r} + \cos \theta \sin \phi e_{\theta} + \cos \phi e_{\phi}$$

$$e_{z} = \cos \theta e_{r} - \sin \theta e_{\theta}$$
(34)

よって(30)、(31)、(32)、(34)を(33)に代入して整理すると

$$\nabla f = \frac{\partial f}{\partial r} e_r + \frac{1}{r} \frac{\partial f}{\partial \theta} e_{\theta} + \frac{1}{r \sin \theta} \frac{\partial f}{\partial \phi} e_{\phi}$$
 (35)

2.2 発散

$$\mathbf{A} = A_r \mathbf{e_r} + A_\theta \mathbf{e_\theta} + A_\phi \mathbf{e_\phi} \tag{36}$$

ここで

$$\nabla \cdot \mathbf{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$$
(37)

右辺第一項

$$\frac{\partial A_x}{\partial x} = \frac{\partial r}{\partial x} \frac{\partial A_x}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial A_x}{\partial \theta} + \frac{\partial \phi}{\partial x} \frac{\partial A_x}{\partial \phi}$$

$$= \sin \theta \cos \phi \frac{\partial A_x}{\partial r} + \frac{1}{r} \cos \theta \cos \phi \frac{\partial A_x}{\partial \theta} - \frac{\sin \phi}{r \sin \theta} \frac{\partial A_x}{\partial \theta}$$

$$= \sin \theta \cos \phi \left(\sin \theta \cos \phi \frac{\partial A_r}{\partial r} + \cos \theta \cos \phi \frac{A_\theta}{\partial r} - \sin \phi \frac{\partial A_\phi}{\partial r} \right)$$

$$+ \frac{1}{r} \cos \theta \cos \phi \left(\cos \theta \cos \phi A_r + \sin \theta \cos \phi \frac{\partial A_r}{\partial \theta} - \sin \theta \cos \phi A_\theta + \cos \theta \cos \phi \frac{A_\theta}{\partial \theta} - \sin \phi \frac{\partial A_\phi}{\partial \theta} \right)$$

$$- \frac{\sin \phi}{r \sin \theta} \left(-\sin \theta \sin \phi A_r + \sin \theta \cos \phi \frac{\partial A_r}{\partial \phi} - \cos \theta \sin \phi A_\theta + \cos \theta \cos \phi \frac{A_\theta}{\partial \phi} - \cos \phi A_\phi - \sin \phi \frac{\partial A_\phi}{\partial \phi} \right)$$

右辺第二項も同様に計算する。

$$\frac{\partial A_y}{\partial y} = \sin \theta \sin \phi \left(\frac{\partial A_r}{\partial r} \sin \theta \sin \phi + \frac{\partial A_\theta}{\partial r} \cos \theta \sin \phi + \frac{\partial A_\phi}{\partial r} \cos \phi \right)
+ \frac{1}{r} \cos \theta \sin \phi \left(A_r \cos \theta \sin \phi + \sin \theta \sin \phi \frac{\partial A_r}{\partial \theta} - A_\theta \sin \theta \sin \phi + \frac{\partial A_\theta}{\partial \theta} \cos \theta \sin \phi + \frac{\partial A_\phi}{\partial \theta} \cos \phi \right)
+ \frac{\cos \phi}{r \sin \theta} \left(A_r \sin \theta \cos \phi + \frac{\partial A_r}{\partial \theta} \sin \theta \sin \phi + A_\theta \cos \theta \cos \phi + \frac{\partial A_\theta}{\partial \phi} \cos \theta \sin \phi - A_\phi \sin \phi + \frac{\partial A_\phi}{\partial \phi} \cos \phi \right)$$

右辺第三項

$$\frac{\partial A_z}{\partial z} = \cos\theta \left(\frac{\partial A_r}{\partial r} \cos\theta - \frac{\partial A_\theta}{\partial r} \sin\theta \right) - \frac{\sin\theta}{r} \left(-A_r \sin\theta + \frac{\partial A_r}{\partial \theta} \cos\theta - A_\theta \cos\theta - \frac{\partial A_\theta}{\partial \theta} \sin\theta \right)$$
(40)

これらの結果を、(37)に代入して整理すると

$$\nabla \cdot \mathbf{A} = \frac{\partial A_r}{\partial r} + \frac{2}{r} A_r + \frac{\cos \theta}{r \sin \theta} A_\theta + \frac{1}{r} \frac{\partial A_\theta}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial A_\phi}{\partial \phi}$$

$$= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 A_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (A_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial A_\phi}{\partial \phi}$$
(41)

2.3 ラプラシアン

$$\Delta f = \nabla \cdot (\nabla f) = \nabla \cdot \left(\frac{\partial f}{\partial r} e_r + \frac{1}{r} \frac{\partial f}{\partial \theta} e_{\theta} + \frac{1}{r \sin \theta} \frac{\partial f}{\partial \phi} e_{\phi} \right)$$
(42)

ただし、勾配の式を利用した。

$$A_{r} = \frac{\partial f}{\partial r}$$

$$A_{\theta} = \frac{1}{r} \frac{\partial f}{\partial \theta}$$

$$A_{z} = \frac{1}{r \sin \theta} \frac{\partial f}{\partial \phi}$$
(43)

と考えて、(41)を適用すると

$$\Delta f = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial f}{\partial r} \right) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} \left(\frac{1}{r} \frac{\partial f}{\partial \theta} \sin \theta \right) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} \left(\frac{1}{r \sin \theta} \frac{\partial f}{\partial \phi} \right)$$

$$= \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial f}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial f}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 f}{\partial \phi^2}$$

$$(44)$$