

Numerical Analysis & Scientific Computing II

Lesson 3

Boundary Value Problems for ODEs

3.1 Well-posedness

3.2 Shooting Method



Boundary Value Problems: Shooting Method

Recall the following discussion in the **contest** of solvability of two-point BVP

$$y' = f(t, y), \quad a < t < b,$$

with boundary conditions

$$g(y(a), y(b)) = 0.$$

We noted that if $y(t; x)$ denotes the solution to the IVP $y' = f(t, y)$, $y(a) = x$, $x \in \mathbb{R}^n$, then this solution is a solution to the BVP if

$$g(x, y(b; x)) = 0.$$

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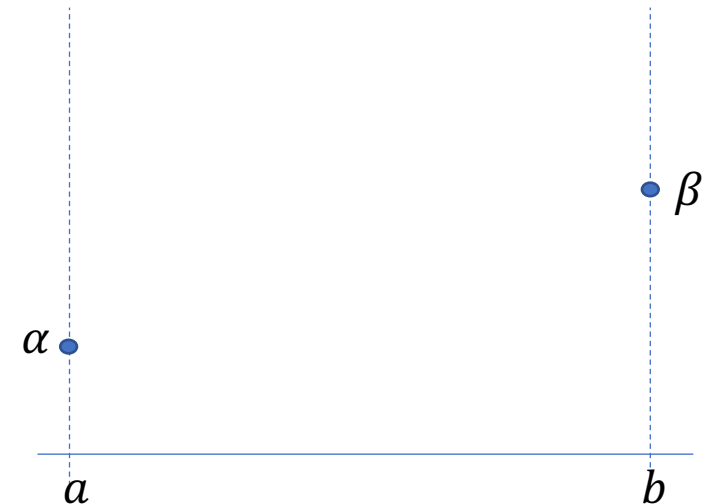
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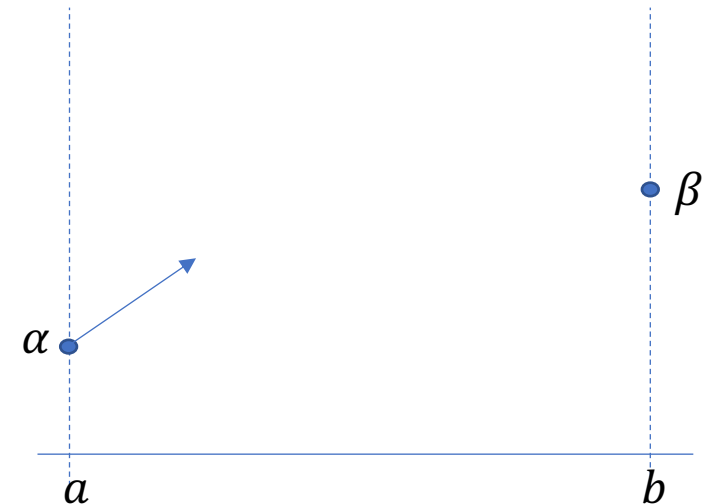
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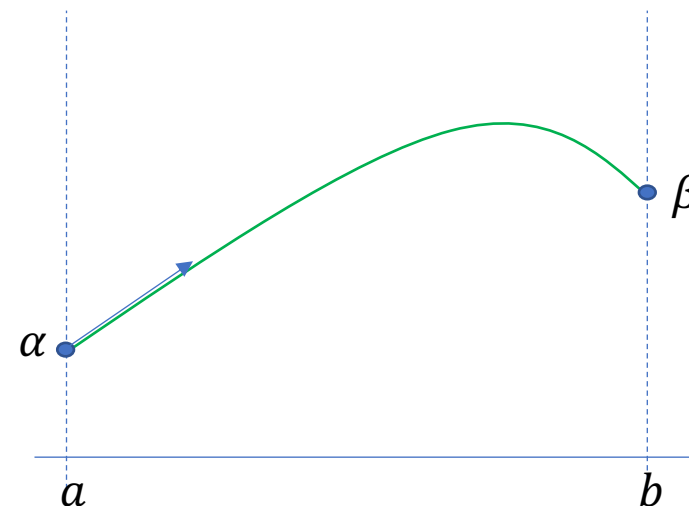
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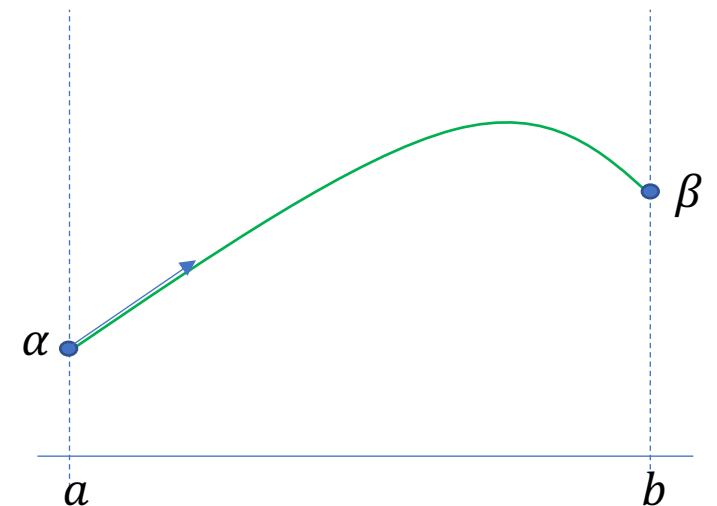
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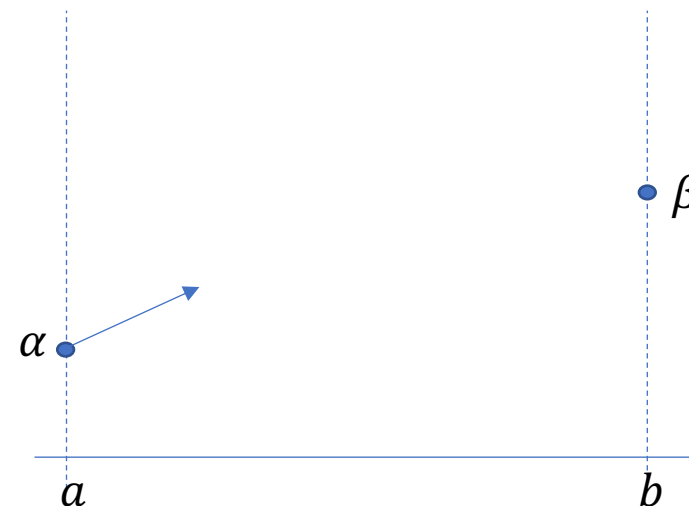
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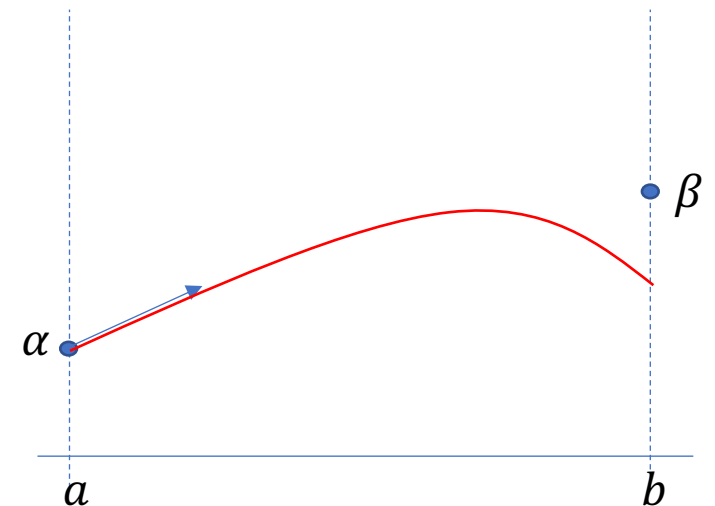
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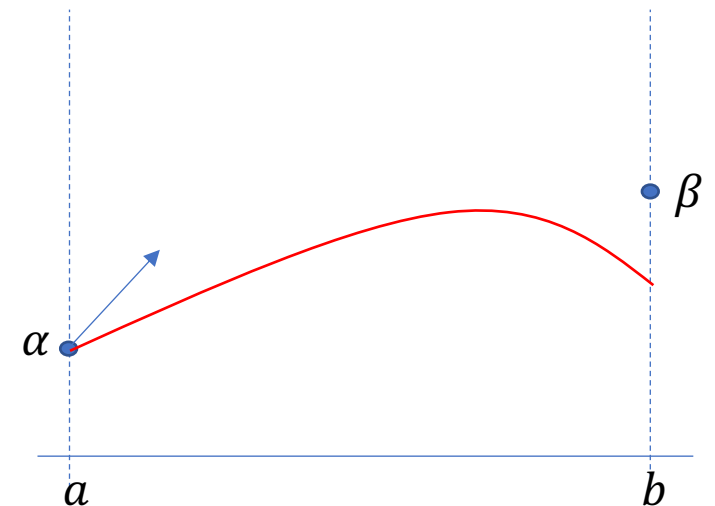
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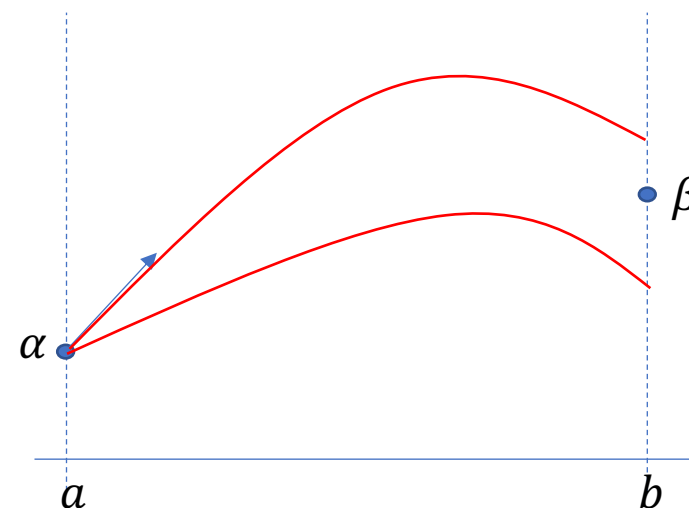
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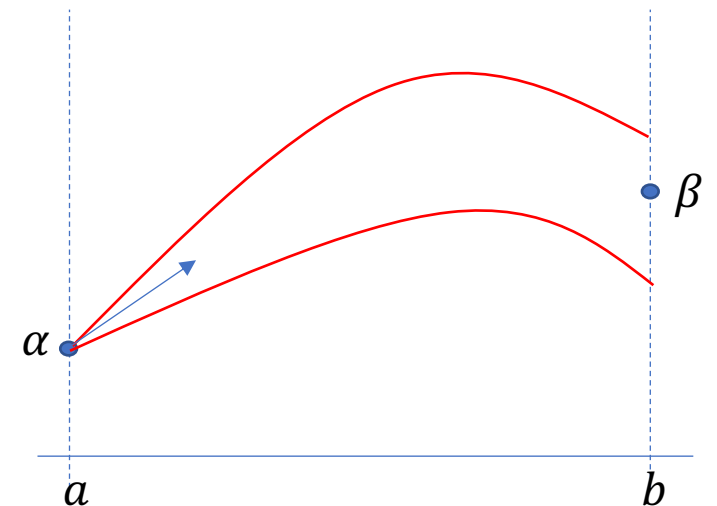
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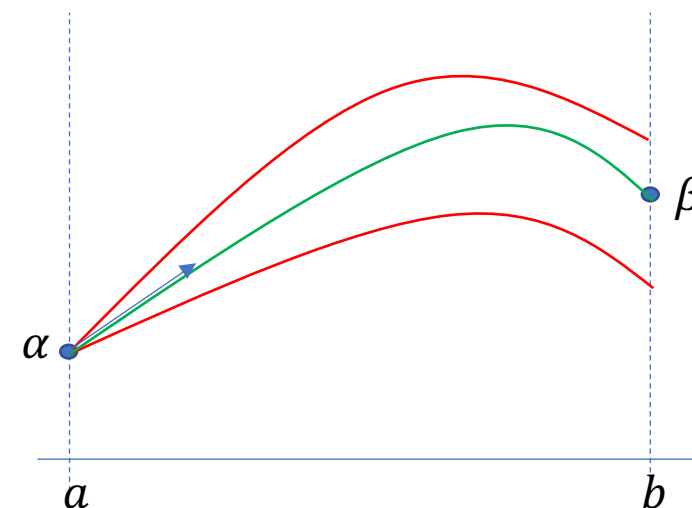
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where the function f is assumed to satisfy the following Lipschitz conditions:

$$\begin{aligned} |f(t, u_1, v) - f(t, u_2, v)| &\leq K|u_1 - u_2|, \\ |f(t, u, v_1) - f(t, u, v_2)| &\leq K|v_1 - v_2|, \end{aligned}$$

for all points $(t, u_i, v), (t, u, v_j) \in R := [a, b] \times \mathbb{R} \times \mathbb{R}$. In addition, assume that on R , f satisfies

$$f_u(t, u, v) = \frac{\partial f(t, u, v)}{\partial u} > 0, \quad |f_v(t, u, v)| = \left| \frac{\partial f(t, u, v)}{\partial v} \right| \leq M,$$

for some $M > 0$. For the boundary conditions, assume

$$a_0 a_1 \geq 0, \quad b_0 b_1 \geq 0, \quad |a_0| + |a_1| \neq 0, \quad |b_0| + |b_1| \neq 0, \quad |a_0| + |b_0| \neq 0.$$

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Theorem

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How do we solve the BVP using the shooting method?

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depending on the parameter s , where c_0, c_1 are arbitrary constants satisfying $a_1 c_0 - a_0 c_1 = 1$. Note that $a_0 y(a; s) - a_1 y'(a; s) = \alpha$.

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We need to find the derivative h' . Note that

$$h'(s) = b_0 z_s(b) + b_1 z'_s(b)$$

where

$$z_s(t) = \frac{\partial y(t; s)}{\partial s}.$$

Boundary Value Problems: Shooting Method

Consider the two-point BVP

$$\begin{aligned} u'' &= f(t, u, u'), & a < t < b, \\ a_0 u(a) - a_1 u'(a) &= \alpha, & b_0 u(b) + b_1 u'(b) = \beta. \end{aligned}$$

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depending on the parameter s , where c_0, c_1 are arbitrary constants satisfying $a_1 c_0 - a_0 c_1 = 1$.

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$$z_s''(t) = f_2(t, y(t; s), y'(t; s)) z_s(t) + f_3(t, y(t; s), y'(t; s)) z'_s(t), \quad z_s(a) = a_1, \quad z'_s(a) = a_0.$$

The functions f_2 and f_3 denote the partial derivatives of $f(t, u, v)$ with respect to u and v respectively.

Boundary Value Problems: Shooting Method



Example

Consider the two-point BVP

$$u'' = -u + \frac{2(u')^2}{u}, \quad -1 < t < 1,$$
$$u(-1) = u(1) = (e + e^{-1})^{-1}.$$

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$$z_s'' = \left\{ -1 - 2 \left(\frac{y'}{y} \right)^2 \right\} z_s + 4 \frac{y'}{y} z_s', \quad -1 < t < 1,$$
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$$s_m \rightarrow s_* = \frac{e - e^{-1}}{(e + e^{-1})^2}.$$

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$$s_m \rightarrow s_*^h \approx s_* = \frac{e - e^{-1}}{(e + e^{-1})^2},$$

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... second-order Runge-Kutta method with stepsize $h = 2/n$ is used, then

$$s_m \rightarrow s_*^h \approx s_* = \frac{e - e^{-1}}{(e + e^{-1})^2},$$

and

$$y^h(t; s_*^h) \rightarrow u(t).$$

$n = 2/h$	$s_* - s_*^h$	Ratio	$E^h = \max_{0 \leq i \leq n} u(t_i) - y^h(t_i; s_*^h) $	Ratio
4	4.01×10^{-3}	—	2.83×10^{-2}	—
8	1.52×10^{-3}	2.64	7.30×10^{-3}	3.88
16	4.64×10^{-4}	3.28	1.82×10^{-3}	4.01
32	1.27×10^{-4}	3.64	4.54×10^{-4}	4.01
64	3.34×10^{-5}	3.82	1.14×10^{-4}	4.00

Boundary Value Problems: Shooting Method



Example

Consider the two-point BVP

$$\begin{aligned} u'' &= p(t)u' + q(t)u + r(t), & a < t < b, \\ a_0u(a) - a_1u'(a) &= \alpha, & b_0u(b) + b_1u'(b) = \beta, & |a_0| + |b_0| \neq 0. \end{aligned}$$

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If $u_1(t)$ solves the IVP

$$u'' = p(t)u' + q(t)u + r(t), \quad u(a) = -\alpha c_1, \quad u'(a) = -\alpha c_0,$$

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$$u(t) = u_1(t) + s u_2(t)$$

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that is (why?)

$$s = \frac{\beta - (b_0u_1(b) + b_1u'_1(b))}{(b_0u_2(b) + b_1u'_2(b))}.$$

Boundary Value Problems: Shooting Method

Example

For approximate solution of the BVP, we form

$$u^h(t_j) = u_1^h(t_j) + s^h u_2^h(t_j), \quad t_j = a + jh, \quad j = 0, 1, \dots, J, \quad h = (b - a)/J.$$

where

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However (*exercise*),

$$s^h - s = - \frac{(b_0 e_1(t_J) + b_1 \varepsilon_1(t_J)) + s (b_0 e_2(t_J) + b_1 \varepsilon_2(t_J))}{(b_0 u_2^h(t_J) + b_1 v_2^h(t_J))}.$$

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If $|e_i(t_j)| = O(h^p)$ and $|\varepsilon_i(t_j)| = O(h^p)$, then (*why?*)
 $|e(t_j)| = O(h^p).$

Boundary Value Problems: Shooting Method



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There is no general guess s_0 for the Newton iterations, and with a poor choice, the iteration may diverge.

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and choose $\gamma > 0$ to minimize

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