

## *Lesson 3*

# *Boundary Value Problems for ODEs*

*3.1 Well-posedness*

*3.2 Shooting Method*



# Boundary Value Problems: Shooting Method



Recall the following discussion in the **contest** of solvability of two-point BVP

$$y' = f(t, y), \quad a < t < b,$$

with boundary conditions

$$g(y(a), y(b)) = 0.$$

We noted that if  $y(t; x)$  denotes the solution to the IVP  $y' = f(t, y)$ ,  $y(a) = x$ ,  $x \in \mathbb{R}^n$ , then this solution is a solution to the BVP if

$$g(x, y(b; x)) = 0.$$

Thus, one approach to solve the BVP therefore is to find an  $x$  that solves the system of nonlinear algebraic equations  $h(x) = 0$ , where  $h(x) = g(x, y(b; x))$ .

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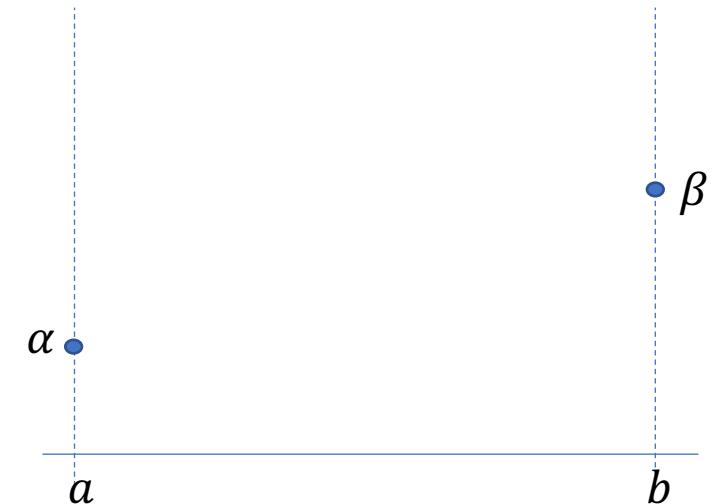
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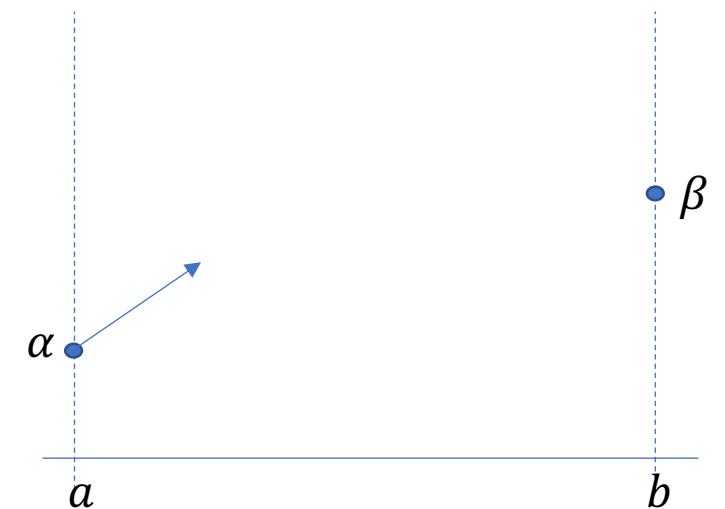
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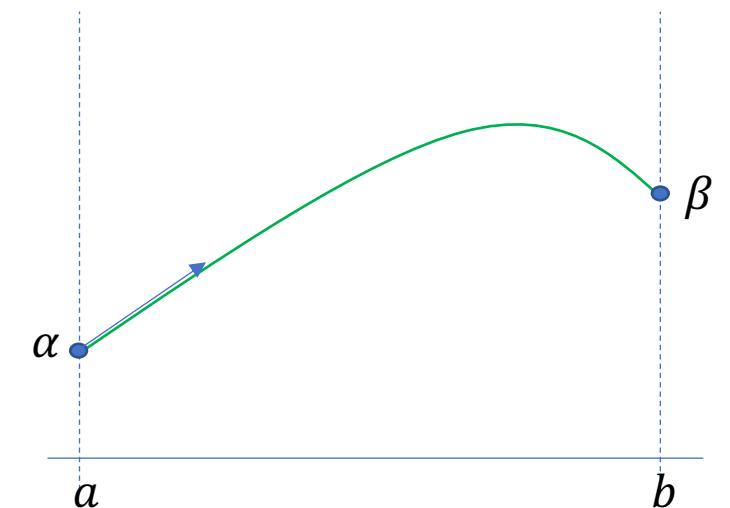
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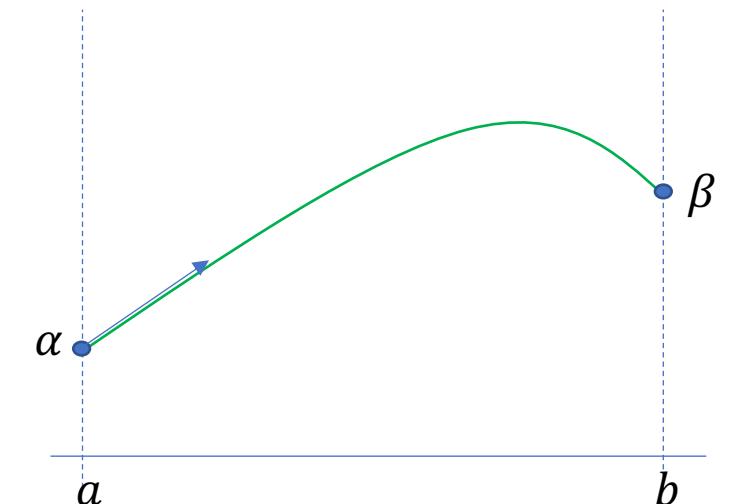
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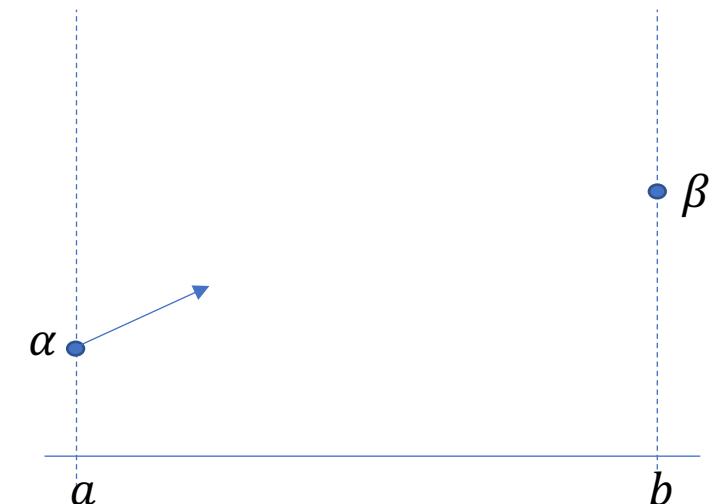
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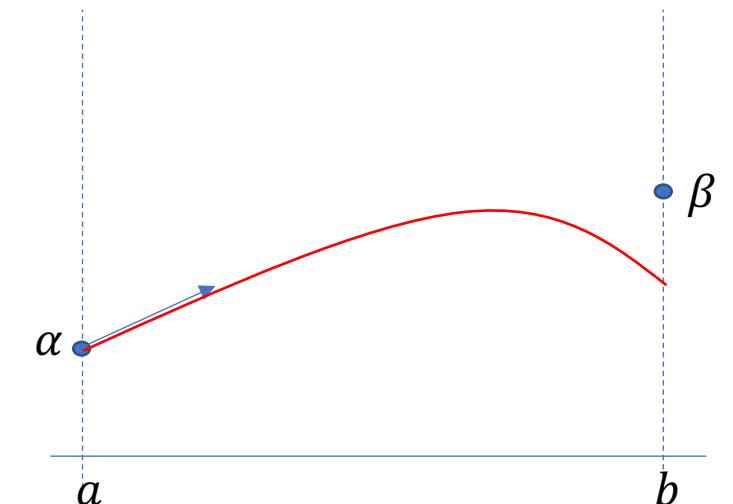
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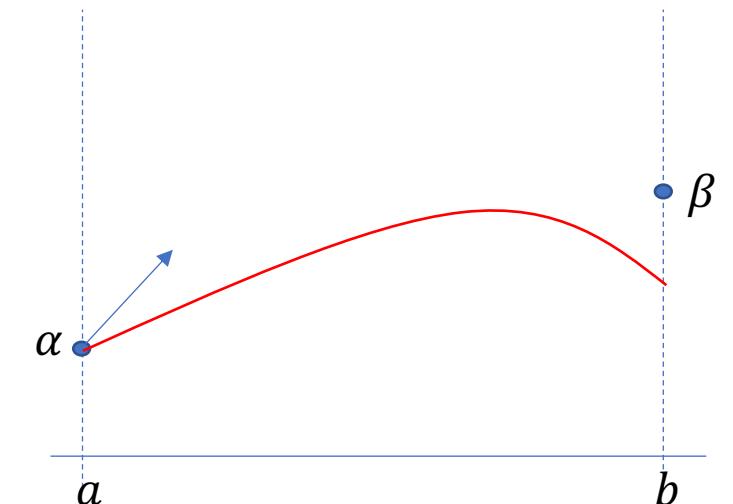
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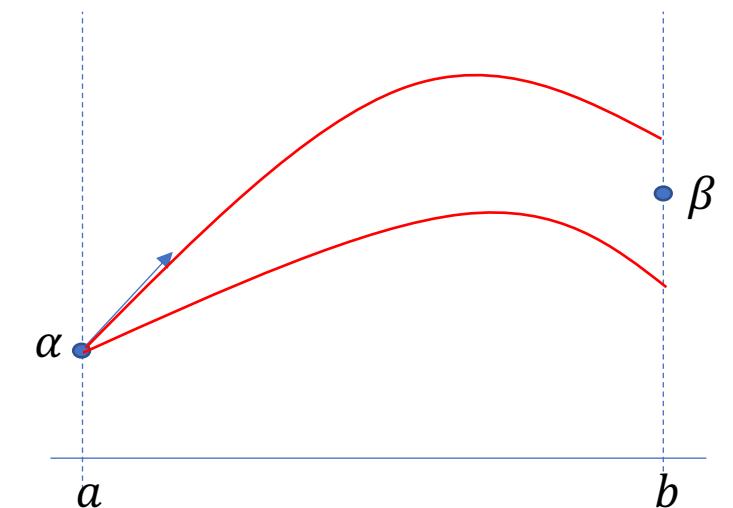
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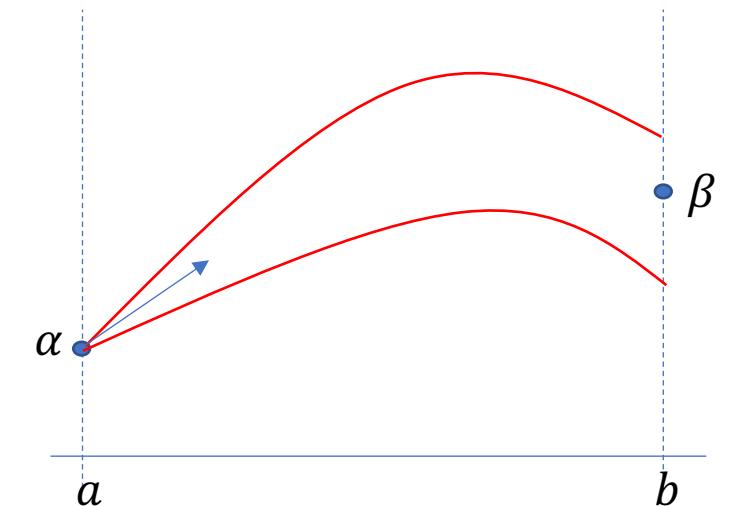
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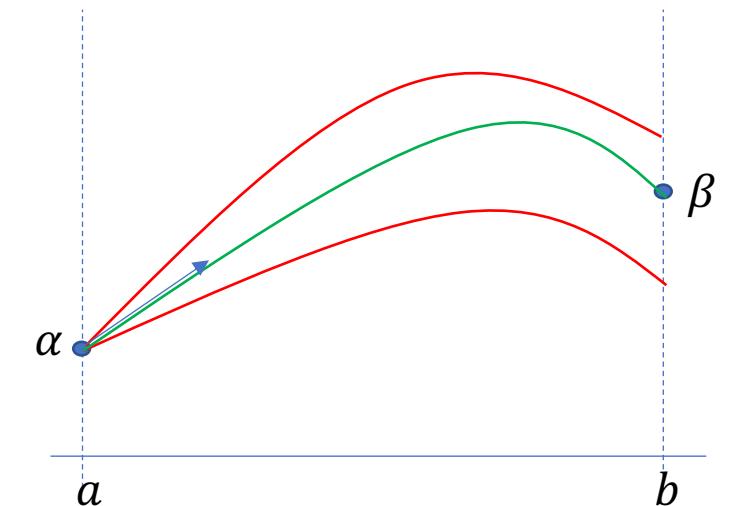
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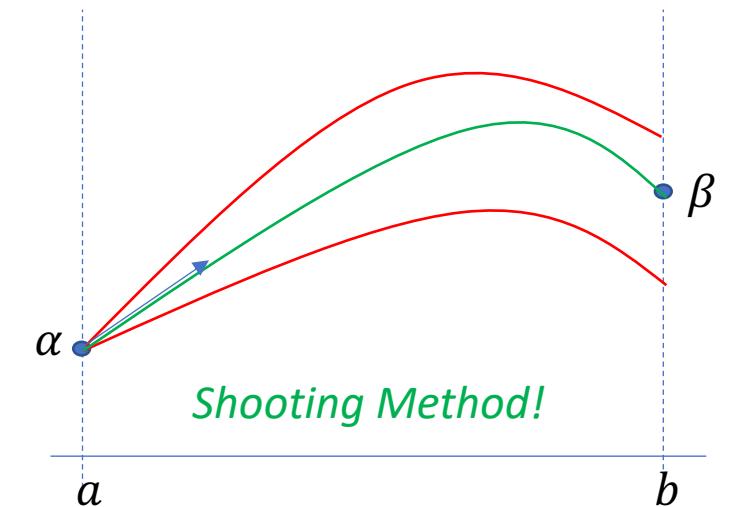
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$$\begin{aligned} u'' &= f(t, u, u'), \quad a < t < b, \\ a_0 u(a) - a_1 u'(a) &= \alpha, \quad b_0 u(b) + b_1 u'(b) = \beta, \end{aligned}$$

where the function  $f$  is assumed to satisfy the following Lipschitz conditions:

$$\begin{aligned} |f(t, u_1, v) - f(t, u_2, v)| &\leq K|u_1 - u_2|, \\ |f(t, u, v_1) - f(t, u, v_2)| &\leq K|v_1 - v_2|, \end{aligned}$$

for all points  $(t, u_i, v), (t, u, v_j) \in R := [a, b] \times \mathbb{R} \times \mathbb{R}$ . In addition, assume that on  $R$ ,  $f$  satisfies

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for some  $M > 0$ . For the boundary conditions, assume

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### Theorem

The BVP, under these assumptions, has a unique solution.

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How do we solve the BVP using the shooting method?



Consider the two-point BVP

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# Boundary Value Problems: Shooting Method



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Let  $y(t; s)$  be the solution to the IVP

$$\begin{aligned} y'' &= f(t, y, y'), & a < t < b, \\ y(a) &= a_1 s - c_1 \alpha, & y'(a) = a_0 s - c_0 \alpha \end{aligned}$$

depending on the parameter  $s$ , where  $c_0, c_1$  are arbitrary constants satisfying  $a_1 c_0 - a_0 c_1 = 1$ . Note that  $a_0 y(a; s) - a_1 y'(a; s) = \alpha$ .

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For  $y(t; s)$  to be the solution to the BVP, it must satisfy

$$h(s) := b_0 y(b; s) + b_1 y'(b; s) - \beta = 0.$$

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$$h(s) := b_0 y(b; s) + b_1 y'(b; s) - \beta = 0.$$

For solution of this equation using the Newton's method, we have

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$$z_s''(t) = f_2(t, y(t; s), y'(t; s))z_s(t) + f_3(t, y(t; s), y'(t; s))z'_s(t), \quad z_s(a) = a_1, \quad z'_s(a) = a_0.$$

The functions  $f_2$  and  $f_3$  denote the partial derivatives of  $f(t, u, v)$  with respect to  $u$  and  $v$  respectively.

## Example

Consider the two-point BVP

$$\begin{aligned} u'' &= -u + \frac{2(u')^2}{u}, \quad -1 < t < 1, \\ u(-1) &= u(1) = (e + e^{-1})^{-1}. \end{aligned}$$

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$n = 2/h$	$s_* - s_*^h$	Ratio	$E^h = \max_{0 \leq i \leq n}  u(t_i) - y^h(t_i; s_*^h) $	Ratio
4	$4.01 \times 10^{-3}$	—	$2.83 \times 10^{-2}$	—
8	$1.52 \times 10^{-3}$	2.64	$7.30 \times 10^{-3}$	3.88
16	$4.64 \times 10^{-4}$	3.28	$1.82 \times 10^{-3}$	4.01
32	$1.27 \times 10^{-4}$	3.64	$4.54 \times 10^{-4}$	4.01
64	$3.34 \times 10^{-5}$	3.82	$1.14 \times 10^{-4}$	4.00



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For approximate solution of the BVP, we form

$$u^h(t_j) = u_1^h(t_j) + s^h u_2^h(t_j), \quad t_j = a + jh, \quad j = 0, 1, \dots, J, \quad h = (b - a)/J.$$

where

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$$s^h - s = - \frac{(b_0 e_1(t_J) + b_1 \varepsilon_1(t_J)) + s (b_0 e_2(t_J) + b_1 \varepsilon_2(t_J))}{(b_0 u_2^h(t_J) + b_1 v_2^h(t_J))}.$$

**Example**

For approximate solution of the BVP, we form

$$u^h(t_j) = u_1^h(t_j) + s^h u_2^h(t_j), \quad t_j = a + jh, \quad j = 0, 1, \dots, J, \quad h = (b - a)/J.$$

where

$$s^h = \frac{\beta - (b_0 u_1^h(t_J) + b_1 v_1^h(t_J))}{(b_0 u_2^h(t_J) + b_1 v_2^h(t_J))}, \quad v_i^h(t_j) \approx u'_i(t_j), i = 1, 2.$$

Let the numerical errors be

$$e_i(t_j) = u_i^h(t_j) - u_i(t_j), \quad \varepsilon_i(t_j) = v_i^h(t_j) - u'_i(t_j), \quad i = 1, 2.$$

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If  $|e_i(t_j)| = O(h^p)$  and  $|\varepsilon_i(t_j)| = O(h^p)$ , then (why?)

$$|e(t_j)| = O(h^p).$$



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