Automata-Theoretic LTL Model-Checking

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Determines Patterns on Infinite Traces

Atomic Propositions
Boolean Operations
Temporal operators



→ a "a is true now"

X a "a is true in the neXt state"

"a will be true in the Future"

"a will be Globally true in the future"

"a will hold true Until b becomes true"



Fa

Ga

a U b

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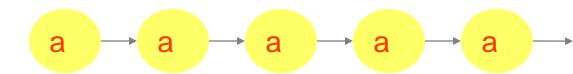
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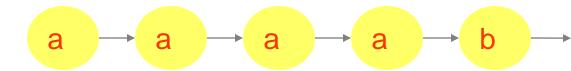
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Outline

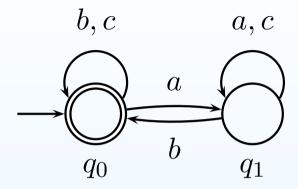
- Automata-Theoretic Model-Checking
 - Finite Automata and Regular Languages
 - Automata over infinite words: Büchi Automata
 - Representing models and formulas with automata
 - Model checking as language emptiness

Finite Automata

A finite automaton \mathcal{A} (over finite words) is a tuple $(\Sigma, Q, \Delta, Q^0, F)$, where

- Σ is a finite alphabet
- Q is a finite set of states
- $\Delta \subseteq Q \times \Sigma \times Q$ is a transition relation
- $Q^0 \subseteq Q$ is a set of initial states
- $F \subseteq Q$ is a set of final states

Finite Automaton: An Example

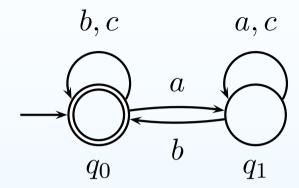


$$\Sigma = \{a, b, c\}, Q = \{q_0, q_1\}, Q^0 = \{q_0\}, F = \{q_1\}$$

A Run

- A run of $\mathcal A$ over a word $v \in \Sigma^*$ of length |v| is a mapping $\rho: \{0,1,...,|v|\} \to Q$ s.t.
 - \circ First state is the initial state: $\rho(0) \in Q^0$
 - \circ States are related by transition relation: $\forall 0 \leq i \leq |v| \cdot (\rho(i), v(i), \rho(i+1)) \in \Delta$
- A run is a path in \mathcal{A} from q_0 to a state $\rho(|v|)$ s.t. the edges are labeled with letters in v
- A run is *accepting* if it ends in an accepting state: $\rho(|v|) \in F$.
- \mathcal{A} accepts v iff exists an accepting run of \mathcal{A} on v.

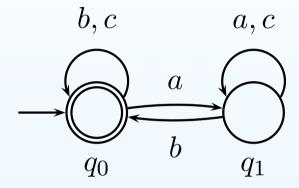
An Example of a Run



- A run q_0, q_1, q_1, q_1, q_0 on aacb is accepting
- A run q_0, q_0, q_0, q_0, q_0 on bbbb is accepting
- A run q_0, q_0, q_1, q_1, q_1 on baac is rejecting

Language

The language $\mathcal{L}(\mathcal{A})\subseteq \Sigma^*$ is the set of all words in Σ^* accepted by $\mathcal{A}.$



The language is $\{\epsilon, b, bb, ccc, bab, \ldots\}$

That is, a regular expression: $\epsilon + a(a+c)^*b(b+c)^*$

Regular Languages

- A set of strings is *regular* if is a language of a finite automaton (i.e., recognizable by a finite automaton)
- An automaton is deterministic if the transition relation is deterministic for every letter in the alphabet:

$$\forall a \cdot (q, a, q') \in \Delta \land (q, a, q'') \in \Delta \Rightarrow q' = q''$$

otherwise, it is non-deterministic.

 NFA = DFA: Every non-deterministic finite automaton (NFA) can be translated into a language-equivalent deterministic automaton (DFA)

Automata on Infinite Words

- Reactive programs execute forever need infinite sequences of states to model them!
- Solution: finite automata over infinite words.
- Simplest case: Büchi automata
 - Same structure as automata on finite words
 - ... but different notion of acceptance
 - Recognize words from Σ^{ω} (not $\Sigma^*!$)

```
• \Sigma = \{a, b\} v = abaabaaab...
```

• $\Sigma = \{a, b, c\}$ $\mathcal{L}_1 = \{v \mid \text{in } v \text{ after every } a \text{ there is a } b\}$ Some words in \mathcal{L}_1 :

```
ababab\cdots \qquad aaabaaab\cdots \\ abbabbabb\cdots \qquad accbaccb\cdots
```

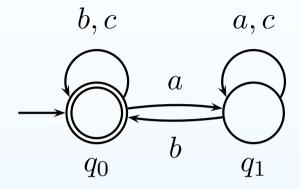
Infinite Run and Acceptance

- Recall, F is the set of accepting states
- A $run \rho$ of a Büchi automaton A is over an infinite word $v \in \Sigma^{\omega}$. Domain of the run is the set of all natural numbers.
- Let $inf(\rho)$ be the set of states that appear infinitely often in ρ :

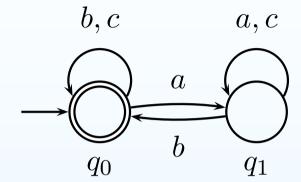
$$inf(\rho) = \{q \mid \forall i \in \mathbb{N} \cdot \exists j \ge i \cdot \rho(j) = q\}$$

- A run ρ is accepting (Büchi accepting) iff $inf(\rho) \cap F \neq \emptyset$.
- A set of strings is ω -regular iff it is recognizable by a Büchi automaton

Example



Example



Language of the automaton is: $((b+c)^{\omega}a(a+c)^*b)^{\omega}$

This is an ω -regular expression

Examples

Let $\Sigma = \{0, 1\}$. Define Büchi automata for the following languages:

- 1. $L = \{v \mid 0 \text{ occurs in } v \text{ exactly once}\}$
- 2. $L = \{v \mid \text{after each 0 in } v \text{ there is a 1} \}$
- 3. $L = \{v \mid v \text{ contains finitely many 1's}\}$
- **4.** $L = (01)^n \Sigma^{\omega}$
- 5. $L = \{v \mid 0 \text{ occurs in every even position of } v\}$

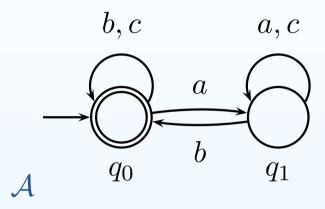
Closure Properties

Büchi-recognizable languages are closed under ...

- (alphabet) projection and union
 - Same algorithms as Finite Automata
- intersection
 - Different construction from Finite Automata
- complement
 - \circ i.e., from a Büchi automaton \mathcal{A} recognizing \mathcal{L} one can construct an automaton $\overline{\mathcal{A}}$ recognizing $\Sigma^{\omega} \mathcal{L}$.
 - \circ $\overline{\mathcal{A}}$ has order of $O(2^{QlogQ)})$ states, where Q are states in \mathcal{A} [Safra's construction]

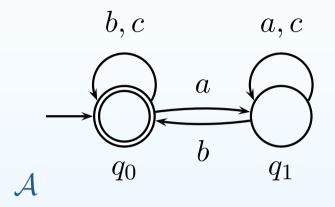
Complementation: Example

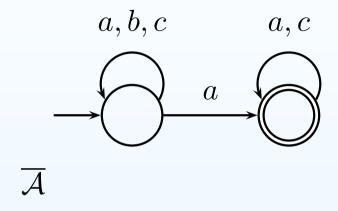
Complement is easy for deterministic Büchi automata:



Complementation: Example

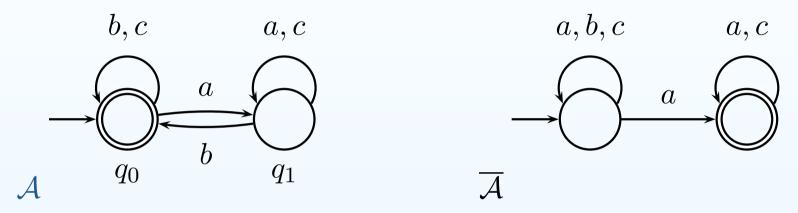
Complement is easy for deterministic Büchi automata:





Complementation: Example

Complement is easy for deterministic Büchi automata:



But, Büchi automata are not closed under determinization!!!



Intersection (Special Case)

Büchi automata are closed under intersection [Chouka74]:

• given two Büchi automata (note all states of \mathcal{B}_1 are accepting):

$$\mathcal{B}_1 = (\Sigma, Q_1, \Delta_1, Q_1^0, Q_1)$$
 $\mathcal{B}_2 = (\Sigma, Q_2, \Delta_2, Q_2^0, F_2)$

- Define $\mathcal{B}_{\cap} = (\Sigma, Q_1 \times Q_2, \Delta', Q_1^0 \times Q_2^0, Q_1 \times F_2)$, where $((s_1, s_2), a, (s_1', s_2')) \in \Delta'$ iff $(s_i, a, s_i') \in \Delta_i$, i = 1, 2
- Then, $\mathcal{L}(\mathcal{B}_{\cap}) = \mathcal{L}(\mathcal{B}_1) \cap \mathcal{L}(\mathcal{B}_2)$

Intersection (General Case)

- Main problem: determining accepting states
 - $^{\circ}$ need to go through accepting states of \mathcal{B}_1 and \mathcal{B}_2 infinite number of times

Intersection (General Case)

- Main problem: determining accepting states
 - \circ need to go through accepting states of \mathcal{B}_1 and \mathcal{B}_2 infinite number of times
- Key idea: make 3 copies of the automaton:
 - 1st copy: start and accept here
 - \circ 2nd copy: move from here from 1 when accepting state from B_1 has been seen
 - \circ 3rd copy: move here from 2 when accepting state from B_2 has been seen, then go back to 1

Intersection (General Case)

Given two Büchi automata:

$$\mathcal{B}_1 = (\Sigma, Q_1, \Delta_1, Q_1^0, F_2)$$
 $\mathcal{B}_2 = (\Sigma, Q_2, \Delta_2, Q_2^0, F_2)$

Define

$$\mathcal{B}_{\cap} = (\Sigma, Q_1 \times Q_2 \times \{0, 1, 2\}, \Delta', Q_1^0 \times Q_2^0 \times \{0\}, Q_1 \times Q_2 \times \{2\}),$$
 where

- $((s_1, s_2, 0), a, (s_1', s_2', 0)) \in \Delta'$ iff $(s_i, a, s_i') \in \Delta_i$, i = 1, 2, and $s_1' \notin F_1$
- $((s_1, s_2, 1), a, (s_1', s_2', 1)) \in \Delta'$ iff $(s_i, a, s_i') \in \Delta_i$, i = 1, 2, and $s_2' \not\in F_2$
- $((s_1, s_2, 0), a, (s_1', s_2', 1)) \in \Delta'$ iff $(s_i, a, s_i') \in \Delta_i$, i = 1, 2, and $s_1' \in F_1$
- $((s_1, s_2, 1), a, (s_1', s_2', 2)) \in \Delta'$ iff $(s_i, a, s_i') \in \Delta_i$, i = 1, 2, and $s_2' \in F_2$
- $((s_1, s_2, 2), a, (s'_1, s'_2, 0)) \in \Delta' \text{ iff } (s_i, a, s'_i) \in \Delta_i, i = 1, 2$

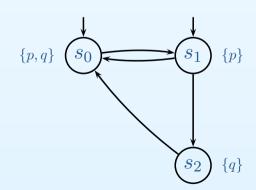
Then,
$$\mathcal{L}(\mathcal{B}_{\cap}) = \mathcal{L}(\mathcal{B}_1) \cap \mathcal{L}(\mathcal{B}_2)$$

Complexity

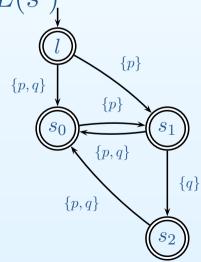
- The emptiness problem for Büchi automata is decidable
 - $\circ \mathcal{L}(\mathcal{A}) \neq \emptyset$
 - logspace-complete for NLOGSPACE, i.e., solvable in linear time [Vardi, Wolper]) – see later in the lecture.
- Nonuniversality problem for Büchi automata is decidable
 - $\circ \mathcal{L}(\mathcal{A}) \neq \Sigma^{\omega}$
 - logspace-complete for PSPACE [Sistla, Vardi, Wolper]

Modeling Systems Using Automata

- A system is a set of all its executions. So, every state is accepting!
- Transform Kripke structure (S, R, S_0, L) , where $L: S \rightarrow 2^{AP}$
- ...into automaton $\mathcal{A} = (\Sigma, S \cup \{\ell\}, \Delta, \{\ell\}, S \cup \{\ell\}),$
 - \circ where $\Sigma = 2^{AP}$
 - $\circ (\ell, \alpha, s') \in \Delta \text{ iff } s \in S_0 \text{ and } \alpha = L(s)$
 - $\circ \ (s,\alpha,s) \in \Delta \ \text{iff} \ (s,s') \in R \ \text{and} \ \alpha = L(s')$



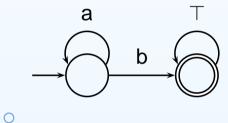
Kripke structure



Automaton

LTL and Büchi Automata

- Specification also in the form of an automaton!
- Büchi automata can encode all LTL properties.
- Examples:



a U b

- Other examples:
 - $\circ \Box \diamond p$
 - $\circ \Box \diamond (p \lor q)$
 - $\circ \neg \Box \diamond (p \lor q)$
 - $\circ \neg (\Box (p\ U\ q))$

LTL to Büchi Automata

• Theorem [Wolper, Vardi, Sistla 83]: Given an LTL formula ϕ , one can build a Büchi automaton $\mathcal{S}=(\Sigma,Q,\Delta,Q_0,F)$, where

$$\Sigma = 2^{\text{Prop}}$$

- the number of automatic propositions, variables, etc. in ϕ
- $|Q| \leq 2^{O(|\phi|)}$, where $|\phi|$ is the length of the formula
- ... s.t. $\mathcal{L}(S)$ is exactly the set of computations satisfying the formula ϕ .
- Algorithm: see Section 9.4 of Model Checking book or try one of the online tools:
 - o http://spot.lip6.fr/ltl2tgba.html
 - http://www.lsv.ens-cachan.fr/~gastin/ltl2ba/index.php
- But Büchi automata are more expressive than LTL!

Automata-theoretic Model Checking

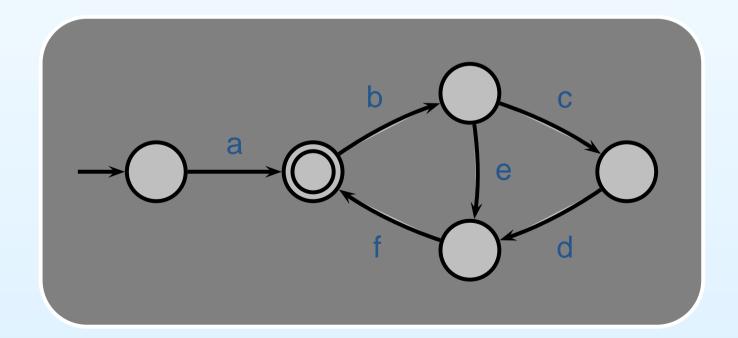
- The system $\mathcal A$ satisfies the specification $\mathcal S$ when
 - \circ $\mathcal{L}(\mathcal{A}) \subseteq \mathcal{L}(\mathcal{S})$
 - ... each behavior of the system is among the allowed behaviours
- Alternatively,
 - \circ let $\overline{\mathcal{L}(\mathcal{S})}$ be the language $\Sigma^{\omega} \mathcal{L}(\mathcal{S})$. Then,
 - $\mathcal{L}(\mathcal{A}) \subseteq \mathcal{L}(\mathcal{S}) \iff \mathcal{L}(\mathcal{A}) \cap \overline{\mathcal{L}(\mathcal{S})} = \emptyset$
 - no behavior of A is prohibited by S
 - If the intersection is not empty, any behavior in it corresponds to a counterexample.
 - \circ Counterexamples are always of the form uv^{ω} , where u and v are finite words.

Complexity

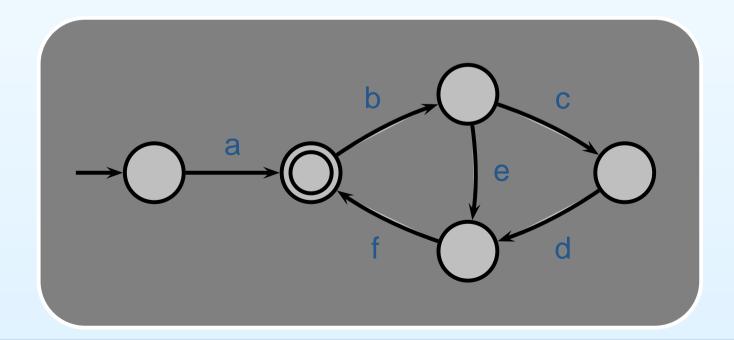
- Checking whether a formula ϕ is satisfied by a finite-state model K can be done in time $O(||K|| \times 2^{O(|\phi|)})$ or in space $O((log||K|| + ||\phi||)^2)$.
- i.e., checking is polynomial in the size of the model and exponential in the size of the specification.

- An automation is non-empty iff
 - there exists a path to a cycle containing an accepting state

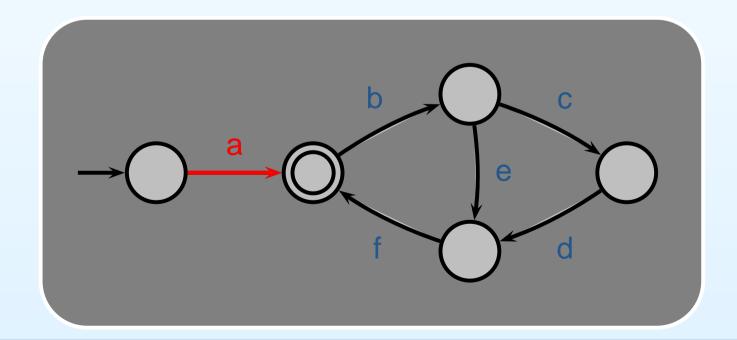
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 - \circ No it accepts $a(bef)^{\omega}$

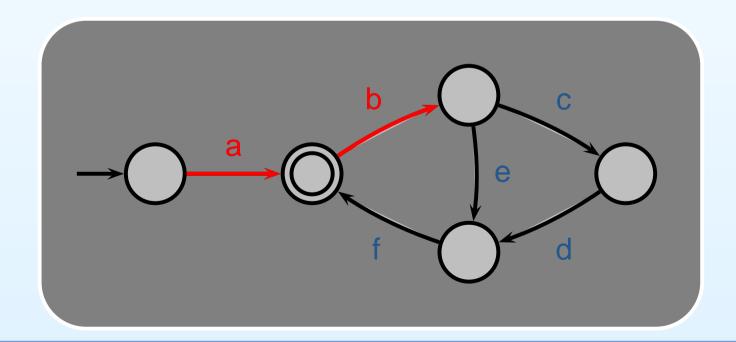


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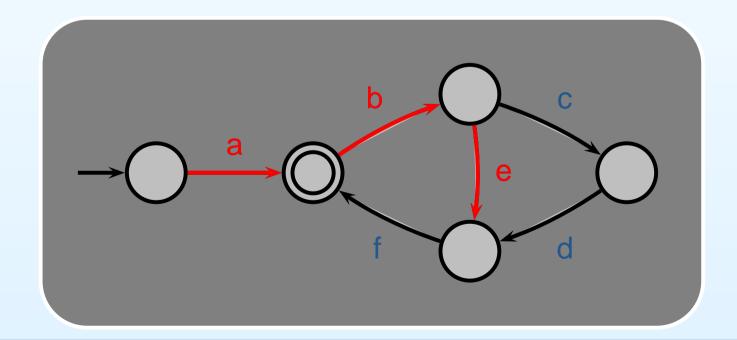
Emptiness of Büchi Automata

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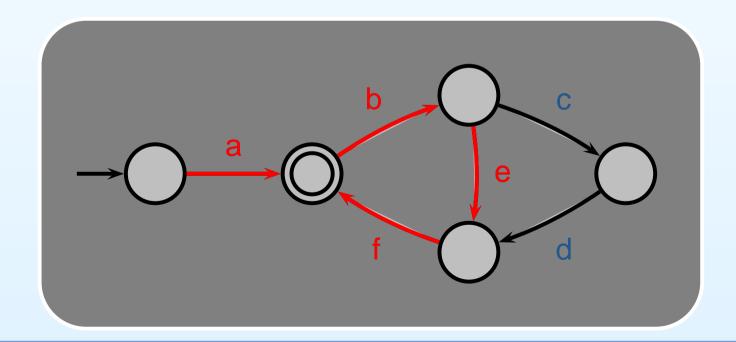
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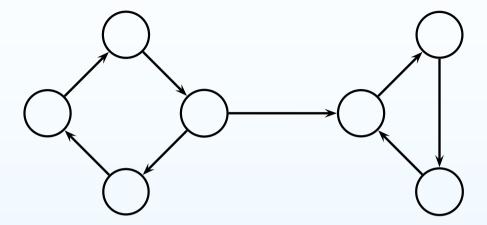
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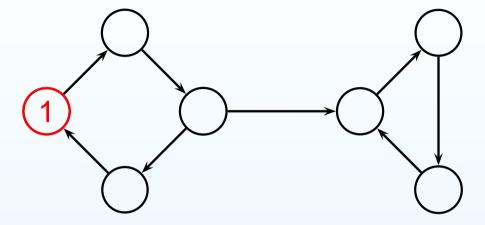
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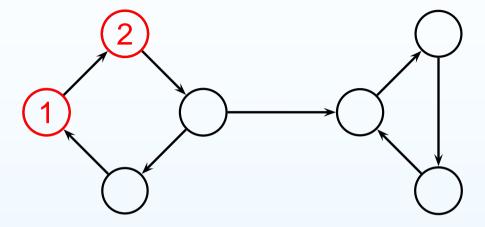


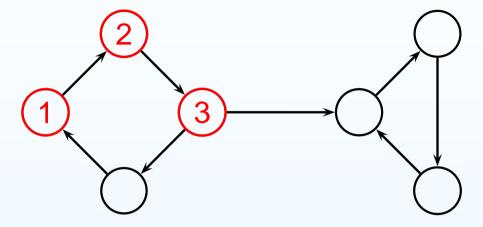
LTL Model-Checking

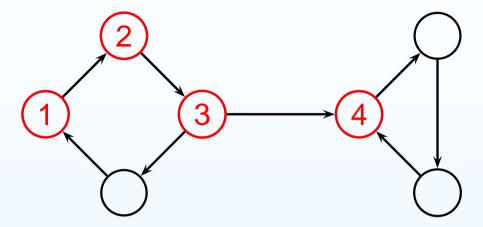
- LTL Model-Checking = Emptiness of Büchi automata
 - a tiny bit of automata theory +
 - trivial graph-theoretic problem
 - typical solution use depth-first search (DFS)
- Problem: state-explosion
 - the graph is *HUGE*
- End result:
 - LTL model-checking a very elaborate DFS

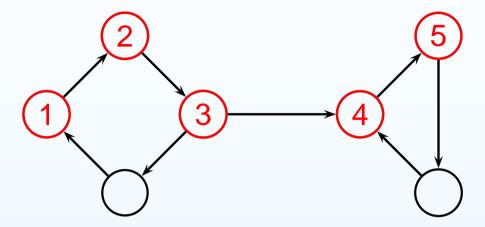


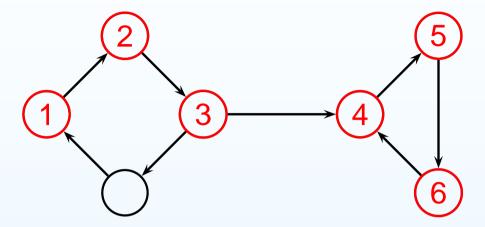


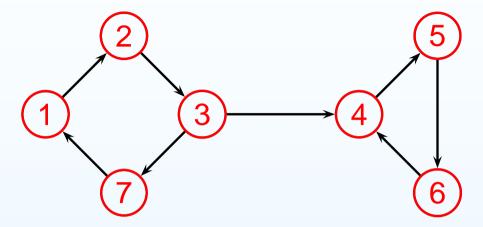


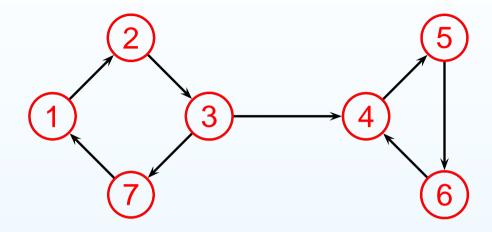




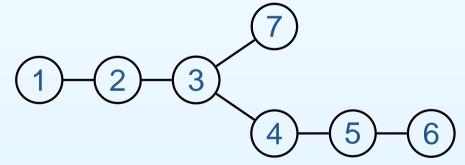








Depth-first tree



DFS – The Algorithm

```
1: time := 0
 2: proc DFS(v)
 3: add v to Visited
 4: d[v] := time
 5: time := time + 1
 6: for all w \in succ(v) do
        if w \notin Visited then
          DFS(w)
        end if
 9:
10: end for
11: f[v] := time
12: time := time + 1
13: end proc
```

DFS – Data Structures

- implicit STACK
 - stores the current path through the graph
- Visited table
 - stores visited nodes
 - used to avoid cycles
- for each node
 - discovery time array d
 - \circ finishing time array f

What we want

- Running time
 - at most linear anything else is not feasible
- Memory requirements
 - sequentially accessed (for the STACK)
 - disk storage is good enough
 - assume unlimited supply so can ignore
 - randomly accessed (for hash tables)
 - must use RAM
 - limited resource minimize
 - why cannot use virtual memory?

Additionally...

- Counterexamples
 - o an automaton is non-empty iff exists an accepting run
 - this is the counterexample we want it
- Approximate solutions
 - partial result is better than nothing!

DFS – Complexity

- Running time
 - each node is visited once
 - linear in the size of the graph
- Memory
 - the STACK
 - accessed sequentially
 - can store on disk ignore
 - Visited table
 - randomly accessed important
 - | Visited| = $S \times n$
 - n number of nodes in the graph
 - S number of bits needed to represent each node

Take 1 – Tarjan's SCC algorithm

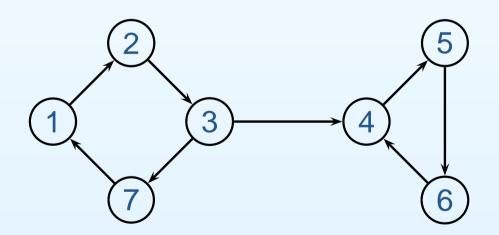
- Idea: find all maximal SCCs: SCC₁, SCC₂, etc.
 - an automaton is non-empty iff exists SCC_i containing an accepting state

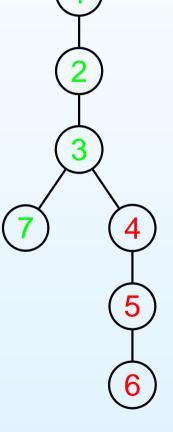
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- Fact: each SCC is a sub-tree of DFS-tree
 - need to find roots of these sub-trees

Take 1 – Tarjan's SCC algorithm

- Idea: find all maximal SCCs: SCC₁, SCC₂, etc.
 - an automaton is non-empty iff exists SCC_i containing an accepting state
- Fact: each SCC is a sub-tree of DFS-tree
 - need to find roots of these sub-trees





Finding a Root of an SCC

- For each node v, compute lowlink[v]
- lowlink[v] is the minimum of
 - \circ discovery time of v
 - \circ discovery time of w, where
 - ullet w belongs to the same SCC as v
 - the length of a path from v to w is at least 1
- Fact: v is a root of an SCC iff
 - $\circ d[v] = low link[v]$

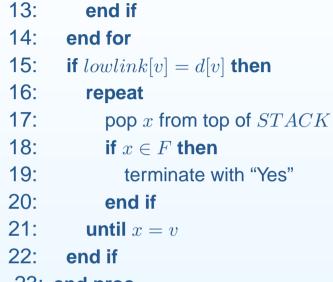
Finally: the algorithm

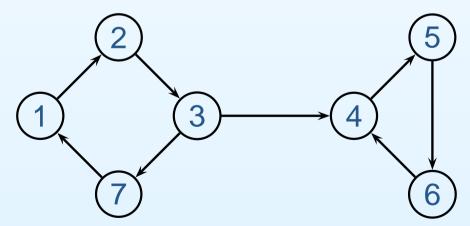
```
1: proc SCC\_SEARCH(v)
      add v to Visited
 3:
      d[v] := time
      time := time + 1
 5:
      lowlink[v] := d[v]
 6:
      push v on STACK
      for all w \in succ(v) do
 8:
        if w \notin Visited then
 9:
           SCC\_SEARCH(w)
10:
           low link[v] := min(low link[v], low link[w])
        else if d[w] < d[v] and w is on STACK then
11:
12:
           lowlink[v] := min(d[w], lowlink[v])
```

```
13:
        end if
14:
      end for
15:
      if low link[v] = d[v] then
16:
        repeat
17:
           pop x from top of STACK
18:
           if x \in F then
19:
             terminate with "Yes"
20:
           end if
21:
        until x = v
22:
      end if
23: end proc
```

Finally: the algorithm

```
13:
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                                                                 14:
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 9:
           SCC\_SEARCH(w)
                                                                 21:
10:
           low link[v] := min(low link[v], low link[w])
                                                                 22:
11:
        else if d[w] < d[v] and w is on STACK then
                                                                  23: end proc
12:
           low link[v] := min(d[w], low link[v])
```





Tarjan's SCC algorithm – Analysis

- Running time
 - linear in the size of the graph
- Memory
 - STACK sequential, ignore
 - $\circ Visited O(S \times n)$
 - $\circ lowlink log n \times n$
 - \circ n is not known a priori
 - assume n is at least $\geq 2^{32}$
- Counterexamples
 - can be extracted from the STACK
 - even more get multiple counterexamples
- If we sacrifice some of generality, can we do better?

Take 2 – Two Sweeps

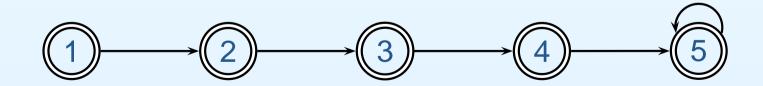
- Don't look for maximal SCCs
- Find a reachable accepting state that is on a cycle
- Idea: use two sweeps
 - sweep one: find all accepting states
 - sweep two: look for cycles from accepting states

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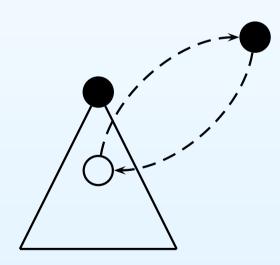


Fixing non-linearity

- Graph Theoretic Result: let v and u be two nodes, such that
 - $\circ f[v] < f[u]$
 - \circ v is not on a cycle
 - $^{\circ}$ then, no cycle containing u contains nodes reachable from v

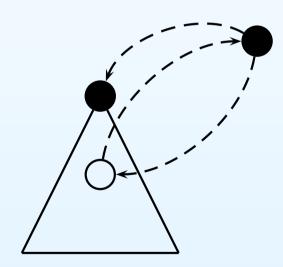
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Take 3 – Double DFS

```
1: proc DFS1(v)
      add v to Visited
 3:
      for all w \in succ(v) do
                                                                      1: proc SWEEP2(Q)
 4:
        if w \notin Visited then
                                                                           while Q \neq [] do
 5:
          DFS1(w)
                                                                             f := dequeue(Q)
 6:
        end if
                                                                          DFS2(f, f)
      end for
                                                                           end while
 8:
      if v \in F then
                                                                           terminate with "No"
 9:
        add v to Q
                                                                      7: end proc
10:
      end if
11: end proc
 1: proc DFS2(v, f)
      add v to Visited
                                                                      1: proc DDFS(v)
 3:
      for all w \in succ(v) do
                                                                           Q = \emptyset
 4:
        if v = f then
                                                                          Visited = \emptyset
 5:
           terminate with "Yes"
                                                                      4:
                                                                          DFS1(v)
        else if w \not\in Visited then
 6:
                                                                      5:
                                                                           Visited = \emptyset
          DFS2(w, f)
                                                                      6:
                                                                           SWEEP2(Q)
 8:
        end if
                                                                      7: end proc
 9:
      end for
10: end proc
```

Double DFS - Analysis

- Running time
 - linear! (single Visited table for different final states, so no state is processed twice)
- Memory requirements
 - $\circ O(n \times S)$
- Problem
 - where is the counterexample?!

Take 4 – Nested DFS

- Idea
 - when an accepting state is finished
 - stop first sweep
 - start second sweep
 - if cycle is found, we are done
 - otherwise, restart the first sweep
- As good as double DFS, but
 - does not need to always explore the full graph
 - counterexample is readily available
 - a path to an accepting state is on the stack of the first sweep
 - a cycle is on the stack of the second

A Few More Tweaks

- No need for two Visited hashtables
 - empty hashtable wastes space
 - merge into one by adding one more bit to each node
 - $(v,0) \in Visited \text{ iff } v \text{ was seen by the first sweep}$
 - $(v,1) \in Visited \text{ iff } v \text{ was seen by the second sweep}$
- Early termination condition
 - nested DFS can be terminated as soon as it finds a node that is on the stack of the first DFS

Nested DFS

```
1: \operatorname{proc} DFS1(v)

2: \operatorname{add}(v,0) to Visited

3: \operatorname{for\ all\ } w \in succ(v) do

4: \operatorname{if\ } (w,0) \not\in Visited then

5: DFS1(w)

6: \operatorname{end\ if\ } 7: \operatorname{end\ for\ } 8: \operatorname{if\ } v \in F then

9: DFS2(v,v)

10: \operatorname{end\ if\ } 1: \operatorname{end\ proc\ } p
```

```
1: \operatorname{proc} DFS2(v,f)

2: \operatorname{add}(v,1) to Visited

3: \operatorname{for\ all\ } w \in succ(v) do

4: \operatorname{if\ } v = f then

5: \operatorname{terminate\ with\ "Yes"}

6: \operatorname{else\ if\ } (w,1) \not\in Visited then

7: DFS2(w,f)

8: \operatorname{end\ if\ }

9: \operatorname{end\ for\ }

10: \operatorname{end\ proc\ }
```

On-the-fly Model-Checking

- Typical problem consists of
 - \circ description of several process P_1, P_2, \dots
 - \circ property φ in LTL
- Before applying DFS algorithm
 - \circ construct graph for $P = \prod_{i=1}^{n} P_i$
 - \circ construct Büchi automaton $A_{\neg \varphi}$ for $\neg \varphi$
 - \circ construct Büchi automaton for $P \cap A_{\neg \varphi}$

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 - \circ construct Büchi automaton for $P \cap A_{\neg \varphi}$
- But,
 - all constructions can be done in DFS order
 - combine everything with the search
 - result: on-the-fly algorithm, only the necessary part of the graph is built

Symbolic LTL Model-Checking

- LTL Model-Checking = Finding a reachable cycle
- Represent the graph symbolically
 - and use symbolic techniques to search
- There exists an infinite path from s, iff $s \models EG$ true
 - the graph is finite
 - infinite ⇒ cyclic!
 - exists a cycle containing an accepting state a iff a occurs infinitely often
 - use fairness to capture accepting states
- LTL Model-Checking = EG true under fairness!