

B.M.S. College of Engineering, Bengaluru-560019

Autonomous Institute Affiliated to VTU

April 2024 Semester End Main Examinations

Programme: B.E.

Branch: CS, IS and AI & ML

Course Code: 22MA4BSLIA

Course: Linear Algebra

Semester: IV

Duration: 3 hrs.

Max Marks: 100

Instructions: 1. Answer any FIVE full questions, choosing one full question from each unit.
2. Missing data, if any, may be suitably assumed.

Important Note: Completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages. Revealing of identification, appeal to evaluator will be treated as malpractice.			UNIT - I	CO	PO	Marks
	1	a)	Determine whether the set $V = \{(x, y) \mid x, y \in \mathbb{R}\}$ is a vector space over the field of reals when the vector addition is the standard vector addition and the scalar multiplication is defined as $k \cdot (x, y) = (0, ky)$.	CO1	PO1	6
		b)	Find the basis of row space, Column space, null space for the matrix $A = \begin{bmatrix} 1 & -3 & 4 & -2 & 5 & 4 \\ 2 & -6 & 9 & -1 & 8 & 2 \\ 2 & -6 & 9 & 1 & 9 & 7 \\ -1 & 3 & -4 & 2 & -5 & 4 \end{bmatrix}$.	CO1	PO1	7
		c)	Find a homogeneous system whose solution set W is spanned by $\{u_1, u_2, u_3\} = \{(1, -2, 0, 3), (1, -1, -1, 4), (1, 0, -2, 5)\}$.	CO1	PO1	7
			UNIT - II			
	2	a)	Verify whether the linear transformation $T: P_2(t) \rightarrow M_{2 \times 2}$ defined by $T(at^2 + bt + c) = \begin{bmatrix} a & 2b \\ 0 & a \end{bmatrix}$ is one-one and onto.	CO1	PO1	6
		b)	Verify Rank-Nullity theorem for the linear transformation $G: R^3 \rightarrow R^3$ defined by $G(x, y, z, t) = (x - y + z + t, 2x - 2y + 3z + 4t, 3x - 3y + 4z + 5t)$.	CO1	PO1	7
		c)	Let T be a linear operator defined on R^3 through $T(x, y, z) = (2x, 4x - y, 2x + 3y - z)$. Is T invertible? If so, find a formula for T^{-1} and T^{-2} .	CO1	PO1	7
			OR			

3	a)	Discuss the following maps on R^2 and represent them graphically: i) Horizontal contraction ii) Vertical contraction iii) Horizontal shear.	COI	POI	6
	b)	Let $T:P_1(t) \rightarrow P_2(t)$ be the linear transformation defined by $T[f(t)] = t f(t)$. Find the matrix of linear transformation with respect to the standard basis of $P_1(t)$ and $B = \{1+t, t-1, t^2\}$ for $P_2(t)$.	COI	POI	7
	c)	Consider the mapping $F:R^2 \rightarrow R^2$ defined by $F(x, y) = (3y, 2x)$. Let 'S' be the unit circle in R^2 , that is the solution of $x^2 + y^2 = 1$. i) Identify $F(S)$, ii) Find $F^{-1}(S)$.	COI	POI	7
UNIT - III					
4	a)	Apply Cayley –Hamilton theorem to find A^4 if $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 5 \\ 3 & 5 & 6 \end{bmatrix}$.	COI	POI	6
	b)	Obtain the Eigen space for the linear transformation $T:R^3 \rightarrow R^3$ defined by $T(x, y, z) = (2x + y, y - z, 2y + 4z)$.	COI	POI	7
	c)	Find all possible Jordan canonical form of linear transformation T, whose minimal polynomial is $(t-8)^2(t+8)^2$ and algebraic multiplicity of the eigen values -8 and 8 are 5 and 4 respectively.	COI	POI	7
OR					
5	a)	Apply Cayley –Hamilton theorem to find A^{-1} and A^{-2} if $A = \begin{bmatrix} 4 & 6 & 6 \\ 1 & 3 & 2 \\ -1 & -4 & -3 \end{bmatrix}$.	COI	POI	6
	b)	Obtain the Eigen space for the linear transformation $T:P_2 \rightarrow P_2$ defined by $T(at^2 + bt + c) = (2a - c)t^2 + (2a + b - 2c)t + (-a + 2c)$.	COI	POI	7
	c)	Find the characteristic and minimal polynomials of the matrix $A = \begin{bmatrix} 3 & 2 & 0 & 0 & 0 \\ 1 & 4 & 0 & 0 & 0 \\ 0 & 0 & 3 & 1 & 0 \\ 0 & 0 & 1 & 3 & 0 \\ 0 & 0 & 0 & 0 & 4 \end{bmatrix}$.	COI	POI	7

		UNIT - IV																	
6	a)	Consider the following polynomial in $P_2(t)$ with the inner product $\langle f \mid g \rangle = \int_{-1}^1 f(t)g(t)dt \quad f(t)=t+2, \quad g(t)=t^2-3t+4.$ Find the matrix of $\langle f \mid g \rangle$ with respect to the basis $\{1, t, t^2\}$.	COI	POI	6														
	b)	Find QR decomposition of the matrix $A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$.	COI	POI	7														
	c)	A sales organization obtains the following data relating the number of salespersons to annual sale. Let x and y denotes the number of salespersons and annual sales respectively. Find the least square line of the form $y = a + bx$ and estimate the annual sales when there are 14 salespersons. <table border="1"><tr><td>x</td><td>5</td><td>6</td><td>7</td><td>8</td><td>9</td><td>10</td></tr><tr><td>y</td><td>2.3</td><td>3.2</td><td>4.1</td><td>5.0</td><td>6.1</td><td>7.2</td></tr></table>	x	5	6	7	8	9	10	y	2.3	3.2	4.1	5.0	6.1	7.2	COI	POI	7
x	5	6	7	8	9	10													
y	2.3	3.2	4.1	5.0	6.1	7.2													
		UNIT-V																	
7	a)	Compute the Hessian matrix at the point $(1, 1, 1)$ of the function $f(x, y, z) = x^2y^2 + z^3 + 2xy + 3xz + x^2 + 3.$	COI	POI	4														
	b)	Determine the modal matrix that reduces the quadratic form $3x^2 + 3y^2 + 3z^2 - 2yz + 2zx + 2xy$ to its canonical form and hence find the nature of the quadratic form.	COI	POI	8														
	c)	Given the data in table, reduce the dimension from 2 to 1 using principal component analysis. <table border="1"><tr><td>X</td><td>4</td><td>8</td><td>13</td><td>7</td></tr><tr><td>Y</td><td>11</td><td>4</td><td>5</td><td>14</td></tr></table>	X	4	8	13	7	Y	11	4	5	14	COI	POI	8				
X	4	8	13	7															
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B.M.S. College of Engineering, Bengaluru-560019

Autonomous Institute Affiliated to VTU

October 2024 Supplementary Examinations

Programme: B.E.

Branch: CS cluster except AIML

Course Code: 23MA4BSLAO

Course: Linear Algebra and Optimization

Semester: IV

Duration: 3 hrs.

Max Marks: 100

Instructions: 1. Answer any FIVE full questions, choosing one full question from each unit.
2. Missing data, if any, may be suitably assumed.

Important Note: Completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages. Revealing of identification, appeal to evaluator will be treated as malpractice.			UNIT – 1	CO	PO	Marks
	1	a)	Find the gradient of matrix $f = \begin{bmatrix} x_0^2 x_1 \log(x_2) & \frac{x_1^2 x_2}{x_3} \\ x_3^2 + x_1 x_3 & x_2^3 + x_1 \end{bmatrix}$ with respect to the matrix $x = \begin{bmatrix} x_0 & x_1 \\ x_2 & x_3 \end{bmatrix}$ and hence verify $\frac{\partial [\text{Trace}(f(x))]}{\partial x} = \text{Trace} \left(\frac{\partial f(x)}{\partial x} \right)$.	1	1	7
		b)	Given $f = x^2 + y^2 + z^2 + xy + yz + zx - 4x - 4y - 4z - 5$, i) find all the stationary points of the function, ii) find the Hessian matrix and iii) classify the stationary points and find its extreme value.	1	1	7
		c)	Find the equation of hyperplane normal to the vector $n = \begin{bmatrix} 3 \\ 1 \\ -2 \end{bmatrix}$ that separates the sets $A = \left\{ \begin{bmatrix} 2 \\ -1 \\ 5 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \\ 3 \end{bmatrix}, \begin{bmatrix} -1 \\ 6 \\ 0 \end{bmatrix} \right\}$ and $B = \left\{ \begin{bmatrix} 0 \\ 5 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ -3 \\ -2 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} \right\}$. Does this hyperplane strictly separate these sets?	1	1	6
			UNIT – 2			
	2	a)	Apply Newtons method to find the minimum value of the function $f = 4x_1^2 + x_2^2 - 2x_1 x_2 + x_1 + x_2$ near $(1, 1)$. Carry out two iterations.	1	1	6
		b)	An asteroid is entering the atmosphere of moon. The shape of the asteroid is described by the equation $4x^2 + y^2 + 4z^2 = 16$. The temperature on the surface of the asteroid after one month was observed to be represented by equation $8x^2 + 4yz - 16z + 600$. Is it possible to find the point on surface of asteroid with maximum temperature? If yes, find it?	1	1	6
		c)	Derive the KKT conditions to minimize the function $f(x, y) = xy$ subject to the constraints $x + y^2 \leq 2$ and $x, y \geq 0$. Also find the optimum values of the function.	1	1	8

		UNIT – 3																	
3	a)	If $u = (1, 3, -4, 2)$, $v = (4, -2, 2, 1)$ and $w = (5, -1, -2, 6)$ are vectors in \mathbb{R}^4 then: i) verify the $\langle 3u - 2v, w \rangle = 3\langle u, w \rangle - 2\langle v, w \rangle$ and ii) find $\frac{\ 3u - 2v\ }{\ w\ }$.	1	1	6														
	b)	Find an orthogonal basis of the subspace W spanned by the following vectors $S = \{1, t, t^2\}$ of $P_2(t)$ given $\langle f, g \rangle = \int_0^1 f(t)g(t)dt$.	1	1	7														
	c)	A sales organization obtains the following data relating the number of salespersons to annual sales. <table border="1"><tr><td>x: Number of salespersons</td><td>5</td><td>6</td><td>7</td><td>8</td><td>9</td><td>10</td></tr><tr><td>y: Annual Sales (millions of dollars)</td><td>2.3</td><td>3.2</td><td>4.1</td><td>5.0</td><td>6.1</td><td>7.2</td></tr></table> Find the least squares line of the form $y = a + bx$ and hence estimate the annual sales when there are 14 salespersons.	x : Number of salespersons	5	6	7	8	9	10	y : Annual Sales (millions of dollars)	2.3	3.2	4.1	5.0	6.1	7.2	1	1	7
x : Number of salespersons	5	6	7	8	9	10													
y : Annual Sales (millions of dollars)	2.3	3.2	4.1	5.0	6.1	7.2													
		OR																	
4	a)	Find the value of α such that the matrices $A = \begin{bmatrix} \alpha & 8 & -7 \\ 6 & 5\alpha & 4 \end{bmatrix}$ and $B = \begin{bmatrix} 1 & 2 & 3 \\ -4 & 5 & 6\alpha \end{bmatrix}$ are orthogonal with respect to an inner product $\langle A, B \rangle = \text{Tr}(B^T A)$. Hence find $\ A\ $ and $\ B\ $.	1	1	6														
	b)	Show that $S = \{u_1, u_2, u_3, u_4\}$ where $u_1 = (1, 1, 1, 1)$, $u_2 = (1, 1, -1, -1)$, $u_3 = (1, -1, 1, -1)$, $u_4 = (1, -1, -1, 1)$ is orthogonal and a basis of \mathbb{R}^4 . Find the coordinates of the arbitrary vector $v = (a, b, c, d)$ in \mathbb{R}^4 relative to the basis S .	1	1	7														
	c)	Obtain the QR factorization of the following matrix $A = \begin{bmatrix} 1 & -1 \\ 2 & 0 \\ 3 & 1 \end{bmatrix}$.	1	1	7														
		UNIT - 4																	
5	a)	Apply Cayley-Hamilton theorem to find A^4 given $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 5 \\ 3 & 5 & 6 \end{bmatrix}$.	1	1	6														
	b)	Given $M = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$ and eigenvalues of M are $\lambda = 0, 2$. Find the eigenvalues and the eigenspace corresponding to each eigenvalue of $A = M^2 + \frac{1}{2}M$. Hence determine whether A is defective matrix or not.	1	1	7														
	c)	Determine all possible Jordan canonical forms or blocks of linear transformation T with characteristic polynomial $f(t) = (t - 4)^3$ and specify the geometric multiplicity in each case.	1	1	7														

		OR													
6	a)	Determine the inverse of the matrix $A = \begin{bmatrix} 4 & 6 & 6 \\ 1 & 3 & 2 \\ -1 & -4 & -3 \end{bmatrix}$ by using Cayley-Hamilton theorem.	1	1	6										
	b)	Find an eigenspace of the linear transformation $T: P_2(t) \rightarrow P_2(t)$ given by $T(at^2 + bt + c) = (a + 3b + 3c)t^2 - (3a + 5b + 3c)t + (3a + 3b + c)$.	1	1	7										
	c)	Find the characteristic and minimal polynomial of the matrix $A = \begin{bmatrix} 2 & 5 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 4 & 2 & 0 \\ 0 & 0 & 3 & 5 & 0 \\ 0 & 0 & 0 & 0 & 7 \end{bmatrix}$.	1	1	7										
		UNIT - 5													
7	a)	Find the nature and write the canonical form of the quadratic form $3x^2 + 3y^2 + 3z^2 + 2xy + 2xz - 2yz$.	1	1	5										
	b)	Assume that the USN is XYZ2222 and then construct a matrix A of size 2×2 by taking last four digits of the USN given and hence find the singular value decomposition. Also write comment on the dimension reduction.	1	1	8										
	c)	Apply principal component analysis to given data to reduce from two-dimension to 1-dimension: <table border="1"><tr><td>x</td><td>4</td><td>8</td><td>13</td><td>7</td></tr><tr><td>y</td><td>11</td><td>4</td><td>5</td><td>14</td></tr></table>	x	4	8	13	7	y	11	4	5	14	1	1	7
x	4	8	13	7											
y	11	4	5	14											

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B.M.S. College of Engineering, Bengaluru-560019

Autonomous Institute Affiliated to VTU

September / October 2024 Supplementary Examinations

Programme: B.E.

Branch: CS / IS / AIML

Course Code: 22MA4BSLIA

Course: LINEAR ALGEBRA

Semester: IV

Duration: 3 hrs.

Max Marks: 100

Instructions: 1. Answer any FIVE full questions, choosing one full question from each unit.
2. Missing data, if any, may be suitably assumed.

Important Note: Completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages. Revealing of identification, appeal to evaluator will be treated as malpractice.			UNIT - 1	CO	PO	Marks
	1	a)	Check whether $b = \begin{bmatrix} 3 \\ -7 \\ -3 \end{bmatrix}$ can be expressed as a linear combination of the columns of $A = \begin{bmatrix} 1 & -4 & 2 \\ 0 & 3 & 5 \\ -2 & 8 & -4 \end{bmatrix}$.	1	1	6
		b)	Let $v_1 = \begin{bmatrix} 1 \\ -3 \\ 4 \end{bmatrix}$, $v_2 = \begin{bmatrix} 6 \\ 2 \\ -1 \end{bmatrix}$, $v_3 = \begin{bmatrix} 2 \\ -2 \\ 3 \end{bmatrix}$ and $v_4 = \begin{bmatrix} -4 \\ -8 \\ 9 \end{bmatrix}$. Find a basis for the subspace W spanned by $\{v_1, v_2, v_3, v_4\}$.	1	1	7
		c)	Given $B = \{t^3 + t^2, t^2 + t, t + 1, 1\}$ is an ordered basis of vector space $P_3(t)$. Find the co-ordinate vector of $f(t)$ relative to B where $f(t) = 2t^3 + t^2 - 4t + 2$.	1	1	7
			UNIT - 2			
	2	a)	Find the matrix of the linear transformation $T: V_2(R) \rightarrow V_3(R)$ defined by $T(x, y) = (x + y, x, 3x - y)$ with respect to $B_1 = \{(1, 1), (3, 1)\}$ and $B_2 = \{(1, 1, 1), (1, 1, 0), (1, 0, 0)\}$.	1	1	6
		b)	Find the basis and dimension of the Image and Kernel of the linear transformation $F: R^4 \rightarrow R^3$ defined by $F(x, y, z, t) = (x - y + z + t, 2x - 2y + 3z + 4t, 3x - 3y + 4z + 5t)$.	1	1	7
		c)	Verify rank-nullity theorem for the linear transformation defined by the matrix $A = \begin{bmatrix} 1 & 1 & 2 & 3 \\ 3 & 4 & -1 & 2 \\ -1 & -2 & 5 & 4 \end{bmatrix}$.	1	1	7
			OR			
	3	a)	Find the linear transformation $T: V_3(R) \rightarrow V_4(R)$ which maps $T(1, 0, 0) = (0, 1, 0, 2)$, $T(0, 1, 0) = (0, 1, 1, 0)$ and $T(0, 0, 1) = (0, 1, -1, 4)$.	1	1	6
		b)	Show that $T: P_1(t) \rightarrow P_3(t)$ is a linear transformation if $T(at + b) = at^3 + bt^2 + at + b$ and hence find the image of $p(t) = 2 - t$.	1	1	7

	c)	Determine the basis and dimension of the null space of the linear transformation defined by $A = \begin{bmatrix} 1 & 4 & -1 & 3 \\ 2 & 9 & -1 & 7 \\ 2 & 8 & -2 & 6 \end{bmatrix}$.	1	1	7
		UNIT - 3			
4	a)	Find the eigenvalues and the corresponding eigenspaces of the linear operator $A = \begin{bmatrix} 5 & 0 \\ 2 & 1 \end{bmatrix}$.	1	1	6
	b)	Find the characteristic and minimal polynomial of the matrix $A = \begin{bmatrix} 2 & 5 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 4 & 2 & 0 \\ 0 & 0 & 3 & 5 & 0 \\ 0 & 0 & 0 & 0 & 7 \end{bmatrix}$.	1	1	7
	c)	Determine the Jordan canonical form for the matrix $\begin{bmatrix} 1 & 2 & 0 & 0 \\ 2 & 4 & 0 & 0 \\ 0 & 0 & -1 & 2 \\ 0 & 0 & 2 & -4 \end{bmatrix}$.	1	1	7
		OR			
5	a)	Find the eigenvalue and the corresponding eigenvectors of the linear transformation $T: V_2(R) \rightarrow V_2(R)$, given $A = \begin{pmatrix} 3 & 3 \\ 1 & 5 \end{pmatrix}$.	1	1	6
	b)	Apply Cayley-Hamilton theorem to find A^{-1} if $A = \begin{bmatrix} 1 & 1 & -2 \\ -1 & 2 & 1 \\ 0 & 1 & -1 \end{bmatrix}$.	1	1	7
	c)	Compute the Jordan canonical form for the matrix $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & -2 \\ 0 & 1 & 3 \end{bmatrix}$.	1	1	7
		UNIT - 4			
6	a)	Find the projection of $(1, 2, 3)$ on to the subspace W spanned by $S = \{u_1, u_2\}$ where $u_1 = (2, 5, -1)$ and $u_2 = (-2, 1, 1)$.	1	1	5
	b)	Find the equation of line that will be best approximation of the points $(-3, 70)$, $(1, 21)$, $(-7, 110)$ and $(5, -35)$ using the method of least squares.	2	1	7
	c)	Determine the QR-decomposition of the matrix $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 3 \\ 1 & -1 & 4 \end{bmatrix}$.	2	1	8
		UNIT- 5			
7	a)	Orthogonally diagonalize the matrix $A = \begin{bmatrix} 3 & -2 & 4 \\ -2 & 6 & 2 \\ 4 & 2 & 3 \end{bmatrix}$.	2	1	10
	b)	Find the singular value decomposition of $A = \begin{bmatrix} 4 & 11 & 14 \\ 8 & 7 & -2 \end{bmatrix}$.	2	1	10

B.M.S. College of Engineering, Bengaluru-560019

Autonomous Institute Affiliated to VTU

October 2023 Semester End Main Examinations

Programme: B.E.

Branch: CSE/ISE

Course Code: 19MA4BSLIA

Course: Linear Algebra

Semester: IV

Duration: 3 hrs.

Max Marks: 100

Instructions: 1. Answer any FIVE full questions, choosing one full question from each unit.
2. Missing data, if any, may be suitably assumed.

Important Note: Completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages. Revealing of identification, appeal to evaluator will be treated as malpractice.			UNIT - I	CO	PO	Marks
	1	a)	Solve the system of equations $x + 2y + 3z = 14$, $4x + 5y + 7z = 35$ and $3x + 3y + 4z = 21$ for complete solution. Also mention the free variables and the pivot variables.	CO1	PO1	7
		b)	Solve the system of equations $x + y + z = 1$, $3x + y - 3z = 5$ and $x - 2y - 5z = 10$ by LU-Decomposition method.	CO1	PO1	7
		c)	Find the basis and dimension for Column space and Row space of the matrix $A = \begin{bmatrix} 1 & 2 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 2 & 0 & 1 \end{bmatrix}$.	CO1	PO1	6
			OR			
	2	a)	Solve the system of equations $u + 3v + 3w + 2y = 1$, $2u + 6v + 9w + 7y = 5$ and $-u - 3v + 3w + 4y = 5$ for the complete solution.	CO1	PO1	7
		b)	Solve the system of equations $x + y + z = 9$, $2x + 5y + 7z = 52$ and $2x + y - z = 0$ by Gauss elimination method.	CO1	PO1	7
		c)	Check linearly dependency or linearly independency of following set of vectors. i) $A = \{(1, -3, 2), (2, 1, -3), (-3, 2, 1)\}$ and ii) $B = \{(2, 1, 3), (1, 3, 2), (3, 2, 1)\}$.	CO1	PO1	6
			UNIT - II			
	3	a)	Find the matrix representation of linear transformation $T: R^2 \rightarrow R^2$ defined by $T(x, y) = (2x + 3y, 4x - 5y)$ relative to $\{(1, 2), (2, 5)\}$ for both vector space in domain and codomain.	CO1	PO1	7
		b)	If $T: R^2 \rightarrow R^3$ is defined by $T(x, y) = (x, y, x + y)$. Show that T is linear transformation and also find its kernel.	CO1	PO1	7
		c)	Show that the linear transformation $T: R^2 \rightarrow R^2$ defined as $T(x, y) = (3x - 5y, -3x - 6y)$ is invertible and find T^{-1} .	CO1	PO1	6

		UNIT – III			
4	a)	Find all the eigenvalues and corresponding eigenvectors of the matrix $A = \begin{bmatrix} 8 & -6 & 2 \\ -6 & 7 & -4 \\ 2 & -4 & 3 \end{bmatrix}$.	CO2	PO1	7
	b)	Diagonalize the matrix $A = \begin{bmatrix} -1 & 3 \\ -2 & 4 \end{bmatrix}$ and hence find A^4 .	CO2	PO1	7
	c)	Find minimal polynomial and characteristic polynomial of the matrix $A = \begin{bmatrix} 3 & -1 & 0 \\ 0 & 2 & 0 \\ 1 & -1 & 2 \end{bmatrix}$.	CO2	PO1	6
		OR			
5	a)	Compute the eigenspace of the linear transformation $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ defined by the matrix $A = \begin{bmatrix} 7 & -2 & 0 \\ -2 & 6 & -2 \\ 0 & -2 & 5 \end{bmatrix}$.	CO2	PO1	7
	b)	Verify Cayley-Hamilton theorem for the matrix $A = \begin{bmatrix} -1 & 3 \\ -2 & 4 \end{bmatrix}$ also compute A^{-1} and A^4 .	CO2	PO1	7
	c)	Write the Jordan canonical form of matrix whose characteristic and minimal polynomial are respectively $(x - 1)^3(x - 2)^2$ and $(x - 1)^2(x - 2)$.	CO2	PO1	6
		UNIT – IV			
6	a)	Apply Gram-Schmidt orthogonalization to construct the orthonormal basis of the vector space spanned by the vectors $(1 \ 0 \ 1), (1,0,0), (2,1,0)$.	CO3	PO1	7
	b)	Find QR decomposition of the matrix $\begin{bmatrix} 1 & 0 & -1 \\ 1 & 2 & 1 \\ 2 & 2 & 3 \end{bmatrix}$.	CO3	PO1	7
	c)	Find the least square solution of the system of equations $-x + 2y = 3, x + y = 4, x - 2y = 0$ and $3x + 2y = 2$.	CO3	PO1	7
		UNIT – IV			
7	a)	Determine the orthogonal modal matrix and hence diagonalize the matrix $\begin{bmatrix} 1 & 5 & -2 \\ 5 & 4 & 5 \\ -2 & 5 & 1 \end{bmatrix}$.	CO3	PO1	8
	b)	Obtain the canonical form and hence classify the nature of the quadratic form $7x^2 + 6y^2 + 5z^2 - 4xy - 4yz$.	CO3	PO1	4
	c)	Find singular value decomposition of the matrix $A = \begin{bmatrix} 2 & 2 \\ -1 & 1 \end{bmatrix}$.	CO3	PO1	8

B.M.S. College of Engineering, Bengaluru-560019

Autonomous Institute Affiliated to VTU

December 2023 Supplementary Examinations

Programme: B.E.

Branch: CS, IS and AI&ML

Course Code: 22MA4BSLIA

Course: Linear Algebra

Semester: IV

Duration: 3 hrs.

Max Marks: 100

Instructions: 1. Answer any FIVE full questions, choosing one full question from each unit.
2. Missing data, if any, may be suitably assumed.

Important Note: Completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages. Revealing of identification, appeal to evaluator will be treated as malpractice.			UNIT - I	CO	PO	Marks
	1	a)	Show that the set $M = \left\{ \begin{bmatrix} 0 & a \\ b & 0 \end{bmatrix} \mid a, b \in \mathbb{R} \right\} \subset M_{2 \times 2}$ satisfies all the properties of a vector space over the field of reals under standard matrix addition and scalar multiplication.	CO1	PO1	6
		b)	Does there exist non-zero scalars c_1, c_2, c_3 and c_4 which proves that the vectors $v_1 = (0, 1, 2, 3, 0)$, $v_2 = (1, 3, -1, 2, 1)$, $v_3 = (2, 6, -1, -3, 1)$ and $v_4 = (4, 0, 1, 0, 2)$ in \mathbb{R}^5 are linearly dependent? If yes, find them.	CO1	PO1	7
		c)	Determine a subset of $S = \{p_1, p_2, p_3, p_4\} \subset P_3(t)$, the vector space of polynomials that forms a basis of $W = \text{span}(S)$ if $p_1 = t^3 + t^2$, $p_2 = 2t^3 + 2t - 2$, $p_3 = t^3 - 6t^2 + 3t - 3$ and $3t^2 - t + 1$.	CO1	PO1	7
			UNIT - II			
	2	a)	Consider the matrix $A = \begin{bmatrix} 2 & 4 \\ 5 & 6 \end{bmatrix}$ which defines a linear operator on \mathbb{R}^2 . Find the matrix of the linear transformation relative to the basis $S = \{u_1, u_2\} = \{(1, -2), (3, -7)\}$.	CO1	PO1	6
		b)	Find the basis for the range space $R(T)$, null space $N(T)$ for the linear transformation $T: \mathbb{R}^4 \rightarrow \mathbb{R}^3$ given by $T(x, y, z, t) = (x - y + z + t, x + 2z + t, x + y + 3z - 3t)$ and also verify rank-nullity theorem.	CO1	PO1	7
		c)	Let $G: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ given by $G(x, y, z) = (x + y, x + z, y + z)$. (i) Show that G is invertible. (ii) Find G^{-1} .	CO1	PO1	7
			OR			

3	a)	Let $A = \begin{bmatrix} 1 & -3 \\ 3 & 5 \\ -1 & 7 \end{bmatrix}$, $u = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$, $b = \begin{bmatrix} 3 \\ 2 \\ -5 \end{bmatrix}$ and $c = \begin{bmatrix} 3 \\ 2 \\ 5 \end{bmatrix}$. Define a linear transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ by $T(X) = AX$, for $X \in \mathbb{R}^2$. (i) Find the image of u under the transformation T . (ii) Find an $X \in \mathbb{R}^2$ whose image is b . Is there more than one $X \in \mathbb{R}^2$ whose image is b ? (iii) Determine if c is in the range of the transformation.	CO1	PO1	6
	b)	Derive the matrix of the linear transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$, which results in horizontal shear of $(x, y) \in \mathbb{R}^2$ by 0.5 units. Determine if there exist i) a preimage of $(1, -3)$. ii) an image of $(3, -1)$.	CO1	PO1	7
	c)	Find the basis for the range space $R(T)$ and the Kernel $N(T)$ of the linear transformation $T: \mathbb{R}^4 \rightarrow \mathbb{R}^3$ given by the matrix $A = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 1 & 3 & 5 & -2 \\ 3 & 8 & 13 & -3 \end{bmatrix}$. Hence verify the rank-nullity theorem. Is T a one-one mapping? Justify.	CO1	PO1	7
UNIT - III					
4	a)	Apply Cayley-Hamilton theorem to compute A^{-1} of $A = \begin{bmatrix} 1 & 1 & -2 \\ -1 & 2 & 1 \\ 0 & 1 & -1 \end{bmatrix}$.	CO1	PO1	6
	b)	Find the eigenvalues and the eigenvectors of the linear transformation $T: P_1(t) \rightarrow P_1(t)$ defined $T(at + b) = (a + 2b)t + (4a + 3b)$.	CO1	PO1	7
	c)	Find the characteristic and minimal polynomial of $\begin{bmatrix} 2 & 5 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 4 & 2 & 0 \\ 0 & 0 & 3 & 5 & 0 \\ 0 & 0 & 0 & 0 & -7 \end{bmatrix}$.	CO1	PO1	7
OR					
5	a)	Apply Cayley-Hamilton theorem to compute A^4 if $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 5 \\ 3 & 5 & 6 \end{bmatrix}$.	CO1	PO1	6
	b)	Determine the eigenspaces of the linear transformation $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ defined by $T(x, y, z) = (x + y - z, 0, x + 2y + 3z)$.	CO1	PO1	7

	c)	Write all possible Jordan canonical form of the linear transformation $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ when $\Delta(t) = (t+5)^2(t-7)^3$ is the characteristic polynomial.	COI	POI	7														
		UNIT – IV																	
6	a)	Find a basis of W of \mathbb{R}^4 orthogonal to $u_1 = (1, -2, 3, 4)$ and $u_2 = (3, -5, 7, 8)$.	COI	POI	4														
	b)	Find an orthogonal basis and hence an orthonormal basis of the subspace W spanned by $S = \{1, 1-t, t^2\}$ of $P_2(t)$ given $\langle f, g \rangle = \int_0^1 f(t)g(t)dt$.	COI	POI	9														
	c)	<p>In an experiment designed to determine the extent of a person's natural orientation, a subject is put in a special room and kept there for a certain length of time. He is then asked to find a way of a maze and record is made of the time it takes the subject to accomplish this task. The following data are obtained.</p> <table border="1"><tr><td>Time in Room (hours)</td><td>1</td><td>2</td><td>3</td><td>4</td><td>5</td><td>6</td></tr><tr><td>Time to find way out of maze(minutes)</td><td>0.8</td><td>2.1</td><td>2.6</td><td>2.0</td><td>3.1</td><td>3.3</td></tr></table> <p>Let x denote the number of hours in the room and let y denote the number of minutes that it takes the subject to find his way out.</p> <p>i. Find the least squares line of the form $y = a + bx$.</p> <p>ii. Estimate the time it will take the subject to find his way out of the maze after 10 hours in the room using the equation obtained.</p>	Time in Room (hours)	1	2	3	4	5	6	Time to find way out of maze(minutes)	0.8	2.1	2.6	2.0	3.1	3.3	COI	POI	7
Time in Room (hours)	1	2	3	4	5	6													
Time to find way out of maze(minutes)	0.8	2.1	2.6	2.0	3.1	3.3													
		UNIT – V																	
7	a)	Determine the modal matrix that reduces the quadratic form $x^2 + 3y^2 + 3z^2 - 2yz$ to its canonical form and hence discuss the nature the quadratic form.	COI	POI	10														
	b)	Obtain the singular value decomposition of $A = \begin{bmatrix} -3 & 1 \\ 6 & -2 \\ 6 & -2 \end{bmatrix}$.	COI	POI	10														

B.M.S. College of Engineering, Bengaluru-560019

Autonomous Institute Affiliated to VTU

September / October 2023 Supplementary Examinations

Programme: B.E

Branch: CS/IS/AIML

Course Code: 19MA4BSLIA

Course: Linear Algebra

Semester: IV

Duration: 3 hrs.

Max Marks: 100

Date: 14.09.2023

Instructions: 1. Answer any FIVE full questions, choosing one full question from each unit.
2. Missing data, if any, may be suitably assumed.

UNIT - I

- 1 a) Apply LU decomposition method to solve the system of equations $2x + y + 4z = 12$, $4x + 11y - z = 33$ and $8x - 3y + 2z = 20$. 6
- b) Express the polynomial $v = t^2 + 4t - 3$ in $p(t)$ as a linear combination of the polynomials $p_1 = t^2 - 2t + 5$, $p_2 = 2t^2 - 3t$, $p_3 = t + 3$. 7
- c) Let W be a subspace of \mathbb{R}^4 spanned by the vectors $u_1 = (1, -2, 5, -3)$, $u_2 = (2, 3, 1, -4)$ and $u_3 = (3, 8, -3, -5)$. 7
 - i) Find the basis and dimension of W .
 - ii) Extend the basis of W to a basis of \mathbb{R}^4 .

OR

- 2 a) Show that the vectors $u_1 = (1, 1, 1)$, $u_2 = (1, 2, 3)$, $u_3 = (1, 5, 8)$ span \mathbb{R}^3 . 6
- b) Show that the set $V = \{a + b\sqrt{2} \mid a, b \in \mathbb{Q}\}$ is a vector space over the field of rationals. 7
- c) Find the dimension and a basis of the solution space W of the system of equations $x + 2y + 2z - s + 3t = 0$; $x + 2y + 3z + s + t = 0$ and $3x + 6y + 8z + s + 5t = 0$. 7

UNIT- II

- 3 a) If $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ defined by $T(x, y, z) = (x - y, y + z, x + z)$, find $R(T)$, $N(T)$ and hence verify Rank-Nullity theorem. 6
- b) Let T be a linear operator defined on \mathbb{R}^3 through $T(x, y, z) = (2x + 3y - z, 4y - z, 2z)$. Is T invertible? If so, then find a formula for T^{-1} . 7
- c) Find the matrix of linear transformation $T: V_2(\mathbb{R}) \rightarrow V_3(\mathbb{R})$ defined by $T(x, y) = (-x + 2y, y, -3x + 3y)$ relative to the basis $B_1 = \{(1, 1), (-1, 1)\}$ and $B_2 = \{(1, 1, 1), (1, -1, 1), (0, 0, 1)\}$. 7

Important Note: Completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages. Revealing of identification, appeal to evaluator will be treated as malpractice.

UNIT- III

- 4 a) Find A^4 given $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 5 \\ 3 & 5 & 6 \end{bmatrix}$ using Cayley-Hamilton theorem. **6**
- b) Find the eigen space of the linear transformation $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ defined by $T(x, y, z) = (3x + 2y + z, x + 4y + z, 2y + 4z)$. **7**
- c) Determine all possible Jordan canonical forms of the linear operator $T : V \rightarrow V$ whose characteristic polynomial is $\Delta(t) = (t - 2)^3(t - 5)^2$. **7**

OR

- 5 a) Find the characteristic and minimal polynomial of $A = \begin{bmatrix} 3 & 2 & 0 & 0 & 0 \\ 1 & 4 & 0 & 0 & 0 \\ 0 & 0 & 3 & 1 & 0 \\ 0 & 0 & 1 & 3 & 0 \\ 0 & 0 & 0 & 0 & 4 \end{bmatrix}$. **6**
- b) Find eigenvalues and eigenvectors of the linear transformation $T : V_2(\mathbb{R}) \rightarrow V_2(\mathbb{R})$ defined by $T(x, y) = (2x + 5y, 4x + 3y)$. **7**
- c) Express the initial-value problem $\frac{d^2x(t)}{dt^2} - 2\frac{dx(t)}{dt} - 3x(t) = 0$ subjected to $x(0) = 4, \frac{dx(0)}{dt} = 5$ into fundamental form and hence solve. **7**

UNIT- IV

- 6 a) Let W be a subspace of \mathbb{R}^5 spanned by $u = (1, 2, 3, -1, 2)$ and $v = (2, 4, 7, 2, -1)$. Find a basis of the orthogonal complement W^\perp of W . **6**
- b) Find an orthogonal basis and hence an orthonormal basis of U , the subspace of \mathbb{R}^4 spanned by the vectors $v_1 = (1, 1, 1, 1)$, $v_2 = (1, 1, 2, 4)$ and $v_3 = (1, 2, -4, -3)$ using Gram-Schmidt orthogonalization process. **7**
- c) Obtain the QR factorization of $A = \begin{bmatrix} 1 & 1 & 2 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$. **7**

UNIT- V

- 7 a) Orthogonally diagonalize $\begin{bmatrix} 3 & -2 & 4 \\ -2 & 6 & 2 \\ 4 & 2 & 3 \end{bmatrix}$. **10**
- b) Find a singular value decomposition of $\begin{bmatrix} 1 & -1 \\ -2 & 2 \\ 2 & -2 \end{bmatrix}$. **10**
