# Active Accuracy Estimation on Large Datasets

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## Outline

- Setup
  - A classifier  $C(\mathbf{x})$  deployed on
  - A large unlabeled dataset D
- Estimate true accuracy  $\mu$  of  $C(\mathbf{x})$  on D
- Given
  - A labeled set L : small or unrepresentative of D
  - ullet Measured accuracy on labeled set eq True accuracy on data
  - A human labeler

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  - existing work assumes that  $C(\mathbf{x})$  is probabilistic and can output well-calibrated  $\Pr(y|\mathbf{x})$  values.
- Provide interactive speed to user in loop even when D is very large
  - even a full sequential scan on *D* may not be practical.
  - D can be accessed only via an index.
- Require user to label as few additional instances as possible
  - Similar to active learning but different ...
    - Active learning usually used in the context of learning classifiers
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The problem has two aspects

- Accuracy estimation (What this talk is about)
  - Given a fixed L what is the best estimator of  $\mu$ ?
  - How to do this scalably on large D?
- 2 Instance selection (Not covered in this talk, details in paper)
  - Selecting instances from D to be labeled by a human and adding to L. Performed in a loop.

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- Simple averaged estimate :  $\hat{\mu}_R = \frac{1}{n} \sum_{i \in L} a_i$  is poor when L is small or biased
- A classical solution : stratified estimate
  - Stratify L and D into B buckets  $(L_1, D_1), \ldots, (L_B, D_B)$
  - Measure accuracy  $\hat{\mu}_b$  of  $L_b$  in each bucket b
  - Estimate weight  $w_b$  as fraction of instances in  $D_b$
  - Stratified estimate  $\hat{\mu}_S = \sum_b w_b \hat{\mu}_b$

Error of  $\hat{\mu}_S <<$  Error of  $\hat{\mu}_R$  if instances within a bucket are homogeneous

- Selecting a stratification strategy that puts instances with same error in the same bucket
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  - F(x, C): A feature representation of the input x and the result of deploying C on x
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  - ? penalizes large (small) hamming distance between similar (dissimilar) points. Issue: Bad local minimas. Poor results
  - ? specifies hash function in kernel form & params are coefficients of these kernels. Solved using co-ordinate descent
  - ? proposes to sequentially update one hyperplane at a time. Also re-weight misclassified pairs of points while learning each subsequent hyperplane
- Our approach : Learn one hyperplane at a time
  - Relaxation : Make use of the fact distance measure is over accuracy that usually takes 0/1 value
  - Optimization: Allow groups formed by existing hyperplanes to choose their +ve & -ve side after optimizing for new hyperplane
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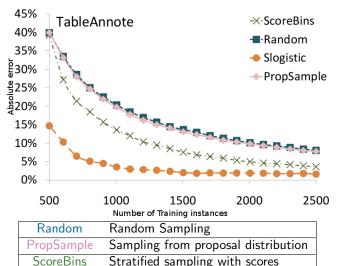
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Summary of datasets used

- **TableAnnote** : Annotate columns of Web tables to type nodes of an ontology
- **Spam** : Classifying web-pages as spam or not
- DNA : Binary DNA classification task
- HomeGround, HomePredicted: Dataset of (entity, web-page) instances and decide if web-page was a homepage for the entity

Dataset	#	Size		Accuracy (%)	
	Features	Seed(L)	Unlabeled $(D)$	Seed(L)	True(D)
TableAnnote	42	541	11,954,983	56.4	16.5
Spam	1000	5000	350,000	86.4	93.2
DNA	800	100,000	50,000,000	72.2	77.9
HomeGround	66	514	1060	50.4	32.8
HomePredicted	66	8658	13,951,053	83.2	93.9

Comparison of estimation strategies on the TableAnnote dataset



Comparison of estimation strategies on remaining datasets

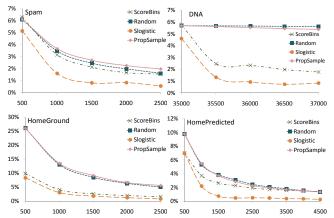
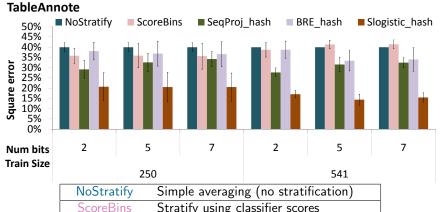


Figure: Absolute error (on the Y axis) of different estimation algorithms against increasing number of labeled instances (on the X axis)

Comparison of different stratification methods on the TableAnnote dataset



NoStratify	Simple averaging (no stratification)		
ScoreBins	Stratify using classifier scores		
SeqProj_hash	Learn hyperplanes using method in (?)		
BRE_hash	Learn hyperplanes using method in (?)		

Comparison of different stratification methods on remaining datasets

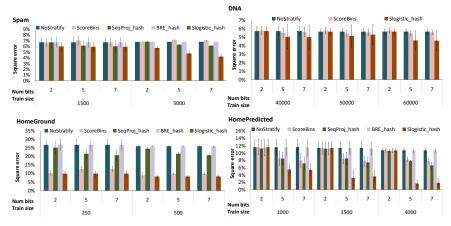


Figure: Error of different stratification methods against increasing training sizes and for different number of bits

Comparison of methods of sampling from indexed data for estimating bucket weights

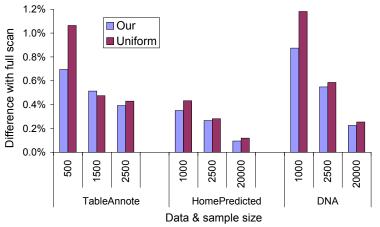


Figure: Comparing methods of sampling from indexed data for estimating bucket weights

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- Addressed the challenge of calibrating a classifier's accuracy on large unlabeled datasets given small amounts of labeled data and a human labeler
- Proposed a stratified sampling-based method for accuracy estimation that provides better estimates than simple averaging & better selection of instances for labeling than random sampling
- 3 Between 15% and 62% relative reduction in error achieved compared to existing approaches
- Algorithm made scalable by proposing optimal sampling strategies for accessing indexed unlabeled data directly
- **6** Close to optimal performance while reading three orders of magnitude fewer instances on large datasets

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