

Prepare a table for each and every motor type you encountered during the Robot Motion lectures. The table should include the following for comparison.

- a. Torque
- b. Speed
- c. Phases
- d. Commutation
- e. Rotor
- f. Stator
- g. Terminals
- h. Magnetic field generation
- i. Angular resolution
- j. Motor complexity
- k. Control mechanism
- l. Control complexity
- m. Use of H bridges
- n. Driving modes
- o. Cost
- p. Advantages
- q. Disadvantages
- r. Commercially available product

Note

- Some terms may not have meaning for certain types of motors. Use “not applicable or (N/A)” for those cells.
- You can use terms such as “high, low, moderate etc.” for comparison. Or else you can mention few words.