### **Neural Tangent Kernel**

#### **Convergence and Generalization of DNNs**

Arthur Jacot, Franck Gabriel, Berfin Şimşek, Francesco Spadaro, Clément Hongler

Ecole Polytechnique Fédérale de Lausanne

July 15, 2020

### **Neural Networks**

■ L+1 layers of  $n_\ell$  neurons with activations  $\alpha^{(\ell)}(x) \in \mathbb{R}^{n_\ell}$ 

$$\alpha^{(0)}(x) = x$$

$$\tilde{\alpha}^{(\ell+1)}(x) = \frac{1}{\sqrt{n_{\ell}}} W^{(\ell)} \alpha^{(\ell)}(x) + \beta b^{(\ell)}$$

$$\alpha^{(\ell+1)}(x) = \sigma \left( \tilde{\alpha}^{(\ell+1)}(x) \right)$$

- Parameters  $\theta = (W^{(0)}, b^{(0)}, \dots, W^{(L-1)}, b^{(L-1)})$ :
  - lacksquare connections weights  $W^{(\ell)} \in \mathbb{R}^{n_\ell \times n_{\ell+1}}$  and bias  $b^{(\ell)} \in \mathbb{R}^{n_{\ell+1}}$ .
- Weights / bias balance:  $\beta$ .
- Non-linearity:  $\sigma : \mathbb{R} \to \mathbb{R}$ .
- Network function  $f_{\theta}(x) = \tilde{\alpha}^{(L)}(x)$ .

### Initialization: DNNs as Gaussian processes

- In the infinite width limit  $n_1, ..., n_{L-1} \to \infty$ .
- Initialize the parameters  $\theta \sim \mathcal{N}(0, Id_P)$ .
- The preactivations  $\tilde{\alpha}_i^{(\ell)}(\cdot;\theta):\mathbb{R}^{n_0}\to\mathbb{R}$  converge to iid Gaussian processes of covariance  $\Sigma^{(\ell)}$  (Lee et al., 2018; Neal, 1996):

$$\Sigma^{(1)}(x,y) = \frac{1}{n_0} x^T y + \beta^2$$
  
$$\Sigma^{(\ell+1)}(x,y) = \mathbb{E}_{\alpha \sim \mathcal{N}(0,\Sigma^{(\ell)})} [\sigma(\alpha(x))\sigma(\alpha(y))] + \beta^2$$

■ The network function  $f_{\theta} = \tilde{\alpha}^{(L)}$  is also asymptotically Gaussian.

### **Training: Neural Tangent Kernel**

- Training set  $X = (x_1, ..., x_N)$  and outputs  $Y_\theta = (f_\theta(x_1), ..., f_\theta(x_N))$ .
- Convex cost C(Y) defined on labels  $Y \in \mathbb{R}^N$ .
- Gradient descent on (non-convex)  $\theta \mapsto C(Y_{\theta})$

$$\partial_t \theta = -\nabla C(Y_\theta) = \frac{1}{N} \sum_{i=1}^N \nabla f_\theta(x_i) \partial_{Y_i} C(Y_\theta).$$

# **Training: Neural Tangent Kernel**

- Training set  $X = (x_1, ..., x_N)$  and outputs  $Y_\theta = (f_\theta(x_1), ..., f_\theta(x_N))$ .
- Convex cost C(Y) defined on labels  $Y \in \mathbb{R}^N$ .
- Gradient descent on (non-convex)  $\theta \mapsto C(Y_{\theta})$

$$\partial_t \theta = -\nabla C(Y_\theta) = \frac{1}{N} \sum_{i=1}^N \nabla f_\theta(x_i) \partial_{Y_i} C(Y_\theta).$$

**E**volution of  $f_{\theta}$ :

$$\partial_t f_{\theta}(x) = (\nabla f_{\theta}(x))^T \partial_t \theta = \frac{1}{N} \sum_{i=1}^N \underbrace{(\nabla f_{\theta}(x))^T \nabla f_{\theta}(x_i)}_{\Theta^{(L)}(x,x_i)} \partial_{Y_i} C(Y_{\theta}).$$

■ Neural Tangent Kernel (NTK):

$$\Theta^{(L)}(x,y) := (\nabla f_{\theta}(x))^T \nabla f_{\theta}(y).$$



# **Asymptotics of the NTK**

#### **Theorem**

As  $n_1, \ldots, n_{L-1} \to \infty$ , there exist a fixed deterministic limiting kernel  $\Theta_{\infty}^{(L)}$  s.t.

$$\Theta^{(L)}(t) \to \Theta^{(L)}_{\infty}.$$

### **Asymptotic dynamics:**

$$egin{aligned} f_{ heta(0)} &\sim \mathcal{N}(0, \Sigma^{(L)}) \ \partial_t f_{ heta(t)}(x) &= rac{1}{N} \sum_{i=1}^N \Theta_{\infty}^{(L)}(x, x_i) \partial_{Y_i} C(f_{ heta}(X)) \end{aligned}$$

# Asymptotics of the NTK

#### **Theorem**

As  $n_1, \ldots, n_{L-1} \to \infty$ , there exist a fixed deterministic limiting kernel  $\Theta_{\infty}^{(L)}$  s.t.

$$\Theta^{(L)}(t) \to \Theta^{(L)}_{\infty}.$$

### **Asymptotic dynamics:**

$$egin{aligned} f_{ heta(0)} &\sim \mathcal{N}(0, \Sigma^{(L)}) \ \partial_t f_{ heta(t)}(x) &= rac{1}{N} \sum_{i=1}^N \Theta_{\infty}^{(L)}(x, x_i) \partial_{Y_i} C(f_{ heta}(X)) \end{aligned}$$

Guarantee of convergence: NTK Gram matrix  $\Theta_{\infty}^{(L)}(X,X)$ 

$$\partial_t C(f_{\theta}(X)) = -(\nabla C)^T \Theta_{\infty}^{(L)}(X, X) \nabla C \leq -\lambda_0 \|\nabla C\|^2.$$



## **Asymptotics of the NTK**

- 1 First proof Jacot et al., 2018: sequential limit  $n_1 \to \infty, ..., n_{L-1} \to \infty$ .
- Simultaneous limit ( $n_1 = n_{L-1} = w \to \infty$ ), finite width bounds Arora et al., 2019; Lee et al., 2019

$$\left|\Theta^{(L)}(0) - \Theta_{\infty}^{(L)}\right| = O(w^{-\frac{1}{2}})$$
$$\left|\Theta^{(L)}(0) - \Theta^{(L)}(t)\right| = O(w^{-\frac{1}{2}}).$$

3 Tight rates Huang and Yau, 2019

$$\left|\Theta^{(L)}(0)-\Theta^{(L)}(t)\right|=O(w^{-1}).$$



### **MSE Loss**

MSE loss  $C(Y) = \frac{1}{N} ||Y - Y^*||^2$  for some true labels  $Y^*$ .

Linear ODE on the training set

$$\partial_t Y_{\theta(t)} = \frac{2}{N} \Theta_{\infty}^{(L)}(X, X) \left( Y^* - Y_{\theta(t)} \right).$$

2 Solution:  $f_{\theta(t)}$  is Gaussian for all t with mean

$$\mathbb{E}\left[f_{\theta}(x)\right] = \Theta_{\infty}^{(L)}(x, X) \left(\Theta_{\infty}^{(L)}(X, X)\right)^{-1} \left(I_{N} - e^{-\frac{2t}{N}\Theta_{\infty}^{(L)}(X, X)}\right) Y^{*}.$$



### **MSE Loss**

MSE loss  $C(Y) = \frac{1}{N} ||Y - Y^*||^2$  for some true labels  $Y^*$ .

1 Linear ODE on the training set

$$\partial_t Y_{\theta(t)} = \frac{2}{N} \Theta_{\infty}^{(L)}(X, X) \left( Y^* - Y_{\theta(t)} \right).$$

2 Solution:  $f_{\theta(t)}$  is Gaussian for all t with mean

$$\mathbb{E}\left[f_{\theta}(x)\right] = \Theta_{\infty}^{(L)}(x,X) \left(\Theta_{\infty}^{(L)}(X,X)\right)^{-1} \left(I_{N} - e^{-\frac{2t}{N}\Theta_{\infty}^{(L)}(X,X)}\right) Y^{*}.$$

**11** As  $t \to \infty$  the mean converges to the ridgless kernel predictor w.r.t. the NTK

$$\Theta_{\infty}^{(L)}(x,X)\left(\Theta_{\infty}^{(L)}(X,X)\right)^{-1}Y^{*}.$$

"Wide DNNs perform NTK Kernel Ridge Regression"



## **Kernel Ridge Regression**

- Random inputs  $x \sim \mathcal{D}$  in a compact domain  $\Omega$ .
- Labels  $Y_i^* = f^*(x_i) + \epsilon e_i$  for  $e_i \sim \mathcal{N}(0, 1)$ .
- For a kernel K and ridge  $\lambda > 0$ , the KRR predictor is

$$\hat{f}_{\lambda}(x) = K(x, X) \left( K(X, X) + \lambda I_{N} \right)^{-1} Y^{*}$$

# **Kernel Ridge Regression**

- Random inputs  $x \sim \mathcal{D}$  in a compact domain  $\Omega$ .
- Labels  $Y_i^* = f^*(x_i) + \epsilon e_i$  for  $e_i \sim \mathcal{N}(0, 1)$ .
- For a kernel K and ridge  $\lambda > 0$ , the KRR predictor is

$$\hat{f}_{\lambda}(x) = K(x,X) \left(K(X,X) + \lambda I_N\right)^{-1} Y^*$$

- Risk  $R(\hat{f}_{\lambda}) = \mathbb{E}_{x \sim \mathcal{D}}\left[\left(\hat{f}_{\lambda}(x) f^*(x)\right)^2\right] + \epsilon^2 = \left\|\hat{f}_{\lambda} f^*\right\|_{\mathcal{D}}^2 + \epsilon^2.$
- Empirical Risk  $\hat{R}(\hat{t}_{\lambda}) = \frac{1}{N} \|\hat{Y}_{\lambda} Y^*\|^2$ .

### **Objects of interest**

- Random Sampling operator  $\mathcal{O}(f) = (f(x_1), ..., f(x_N))^T$  from  $\mathcal{F}$  to  $\mathbb{R}^N$ .
- Noiseless predictor  $\epsilon = 0$  (for  $K : \mathcal{F}^* \to \mathcal{F}$  and  $\mathcal{O}^T : \mathbb{R}^N \to \mathcal{F}^*$ ):

$$\hat{f}_{\lambda} = \frac{1}{N} K \mathcal{O}^{T} \left( \frac{1}{N} \mathcal{O} K \mathcal{O}^{T} + \lambda I_{N} \right)^{-1} \mathcal{O} f^{*}$$

### **Objects of interest**

- Random Sampling operator  $\mathcal{O}(f) = (f(x_1), ..., f(x_N))^T$  from  $\mathcal{F}$  to  $\mathbb{R}^N$ .
- Noiseless predictor  $\epsilon = 0$  (for  $K : \mathcal{F}^* \to \mathcal{F}$  and  $\mathcal{O}^T : \mathbb{R}^N \to \mathcal{F}^*$ ):

$$\hat{f}_{\lambda} = \frac{1}{N} K \mathcal{O}^{T} \left( \frac{1}{N} \mathcal{O} K \mathcal{O}^{T} + \lambda I_{N} \right)^{-1} \mathcal{O} f^{*}$$

$$= \frac{1}{N} K \mathcal{O}^{T} \mathcal{O} \left( \frac{1}{N} K \mathcal{O}^{T} \mathcal{O} + \lambda I_{F} \right)^{-1} f^{*}$$

## **Objects of interest**

- Random Sampling operator  $\mathcal{O}(f) = (f(x_1), ..., f(x_N))^T$  from  $\mathcal{F}$  to  $\mathbb{R}^N$ .
- Noiseless predictor  $\epsilon = 0$  (for  $K : \mathcal{F}^* \to \mathcal{F}$  and  $\mathcal{O}^T : \mathbb{R}^N \to \mathcal{F}^*$ ):

$$\hat{f}_{\lambda} = \frac{1}{N} K \mathcal{O}^{T} \left( \frac{1}{N} \mathcal{O} K \mathcal{O}^{T} + \lambda I_{N} \right)^{-1} \mathcal{O} f^{*}$$

$$= \frac{1}{N} K \mathcal{O}^{T} \mathcal{O} \left( \frac{1}{N} K \mathcal{O}^{T} \mathcal{O} + \lambda I_{\mathcal{F}} \right)^{-1} f^{*}$$

$$\xrightarrow{N \to \infty} \underbrace{T_{K} \left( T_{K} + \lambda I_{\mathcal{F}} \right)^{-1}}_{\tilde{A}_{\lambda}} f^{*}$$

for the *integral operator*  $(T_K f)(x) = \mathbb{E}_{w \sim \mathcal{D}} [K(x, w) f(w)].$ 

- Mercer's Theorem:
  - $\blacksquare$   $T_K$  has eigenvalues  $d_k$  and eigenfunctions  $f^{(k)}$ .
  - $T_K$  is trace class  $\sum_{k=1}^{\infty} d_k < \infty$ .



### **Expected Predictor**

### Theorem (Jacot et al., 2020)

For  $\lambda > 0$  we have

$$\mathbb{E}\left[\hat{f}_{\lambda}(x)\right] \approx \tilde{A}_{\vartheta}f^* = T_{K}\left(T_{K} + \vartheta I_{\mathcal{F}}\right)^{-1}f^*$$

where the Signal Capture Threshold  $\vartheta(\lambda, N, T_K)$  is the unique positive solution of

$$\vartheta = \lambda + \frac{\vartheta}{N} \operatorname{Tr} \left[ T_{\mathcal{K}} (T_{\mathcal{K}} + \vartheta I_{\mathcal{F}})^{-1} \right].$$

### **Expected Predictor**

### Theorem (Jacot et al., 2020)

For  $\lambda > 0$  we have

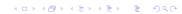
$$\mathbb{E}\left[\hat{f}_{\lambda}(x)\right] \approx \tilde{A}_{\vartheta}f^* = T_K \left(T_K + \vartheta I_{\mathcal{F}}\right)^{-1} f^*$$

where the Signal Capture Threshold  $\vartheta(\lambda, N, T_K)$  is the unique positive solution of

$$\vartheta = \lambda + \frac{\vartheta}{N} \operatorname{Tr} \left[ T_{\mathcal{K}} (T_{\mathcal{K}} + \vartheta I_{\mathcal{F}})^{-1} \right].$$

For  $f^* = \sum_k b_k f^{(k)}$  we have  $\mathbb{E}\left[\hat{f}_{\lambda}(x)\right] \approx \sum_k \frac{d_k}{d_k + \vartheta} b_k f^{(k)}$ :

- When  $d_k \gg \vartheta$ ,  $\frac{d_k}{d_k + \vartheta} \simeq 1 \Longrightarrow$  signal is captured.
- When  $d_k \ll \vartheta$ ,  $\frac{d_k}{d_{k+1}\vartheta} \simeq 0 \Longrightarrow$  signal is lost.



### **Expected Risks**

#### **Theorem**

$$egin{aligned} R\left(\mathbb{E}\left[\hat{f}_{\lambda}
ight]
ight) &pprox \left\|(I_{\mathcal{F}}- ilde{\mathcal{A}}_{artheta})f^{*}
ight\|_{\mathcal{D}}^{2}+\epsilon^{2} \ &\mathbb{E}\left[R\left(\hat{f}_{\lambda}
ight)
ight] &pprox \partial_{\lambda}artheta\left(\left\|(I_{\mathcal{F}}- ilde{\mathcal{A}}_{artheta})f^{*}
ight\|_{\mathcal{D}}^{2}+\epsilon^{2}
ight). \end{aligned}$$

For 
$$f^* = \sum_k b_k f^{(k)}$$
,  $\left\| (I_{\mathcal{F}} - \tilde{A}_{\vartheta}) f^* \right\|_{\mathcal{D}}^2 = \sum_k \frac{\vartheta^2}{(d_k + \vartheta)^2} b_k^2$ .

# **Expected Risks**

#### **Theorem**

$$egin{aligned} R\left(\mathbb{E}\left[\hat{f}_{\lambda}
ight]
ight) &pprox \left\|(I_{\mathcal{F}}- ilde{\mathcal{A}}_{artheta})f^{*}
ight\|_{\mathcal{D}}^{2}+\epsilon^{2} \ &\mathbb{E}\left[R\left(\hat{f}_{\lambda}
ight)
ight] &pprox \partial_{\lambda}artheta\left(\left\|(I_{\mathcal{F}}- ilde{\mathcal{A}}_{artheta})f^{*}
ight\|_{\mathcal{D}}^{2}+\epsilon^{2}
ight). \end{aligned}$$

For 
$$f^* = \sum_k b_k f^{(k)}$$
,  $\left\| (I_{\mathcal{F}} - \tilde{A}_{\vartheta}) f^* \right\|_{\mathcal{D}}^2 = \sum_k \frac{\vartheta^2}{(d_k + \vartheta)^2} b_k^2$ .

#### **Theorem**

$$\mathbb{E}\left[\hat{R}\left(\hat{f}_{\lambda}
ight)
ight]pprox\partial_{\lambda}arthetarac{\lambda^{2}}{artheta^{2}}\left(\left\|\left(I_{\mathcal{F}}- ilde{A}_{artheta}
ight)f^{st}
ight\|_{\mathcal{D}}^{2}+\epsilon^{2}
ight).$$

$$\Longrightarrow$$
 relation  $R\left(\hat{f}_{\lambda}\right) \approx \frac{\vartheta^{2}}{\lambda^{2}}\hat{R}\left(\hat{f}_{\lambda}\right)$ .



### **Proposition**

$$\vartheta \approx \frac{1}{\frac{1}{N} \mathrm{Tr} \left[ \left( \frac{1}{N} K(X, X) + \lambda I_N \right)^{-1} \right]}.$$

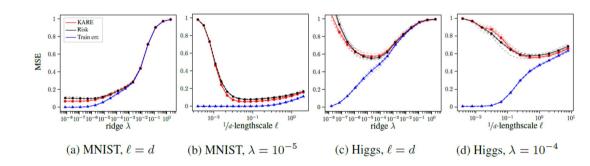
### **Proposition**

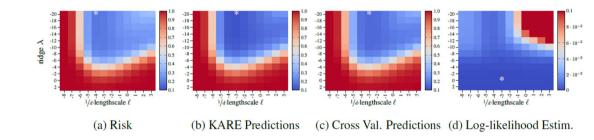
$$\vartheta pprox rac{1}{rac{1}{N} \mathrm{Tr} \left[ \left( rac{1}{N} K(X,X) + \lambda I_N 
ight)^{-1} 
ight]}.$$

#### Kernel Alignement Risk Estimator (KARE)

$$R\left(\hat{f}_{\lambda}\right) \approx \frac{\frac{1}{N}\left(Y^{*}\right)^{T}\left(\frac{1}{N}K(X,X) + \lambda I_{N}\right)^{-2}Y^{*}}{\left(\frac{1}{N}\mathrm{Tr}\left[\left(\frac{1}{N}K(X,X) + \lambda I_{N}\right)^{-1}\right]\right)^{2}}.$$

Bias term is approximated by  $\frac{\frac{1}{N}(Y^*)^T \left(\frac{1}{N}K(X,X) + \lambda I_N\right)^{-2} Y^*}{\frac{1}{N} \mathrm{Tr} \left[\left(\frac{1}{N}K(X,X) + \lambda I_N\right)^{-2}\right]}.$ 





### **Conclusion**

- 1 Wide networks perform Kernel Ridge Regression w.r.t. the NTK.
- 2 Convergence is guaranteed whenever the NTK is positive definite.
- Generalization for a general Kernel:
  - 1 The SCT describes which components are learned.
  - 2 The test loss can be predicted from the training data using the KARE.

### Bibliography I

- Arora, S., Du, S. S., Hu, W., Li, Z., Salakhutdinov, R., and Wang, R. (2019). On exact computation with an infinitely wide neural net. *arXiv* preprint *arXiv*:1904.11955.
- Huang, J. and Yau, H.-T. (2019). Dynamics of deep neural networks and neural tangent hierarchy. *arXiv preprint arXiv:1909.08156*.
- Jacot, A., Şimşek, B., Spadaro, F., Hongler, C., and Gabriel, F. (2020). Kernel alignment risk estimator: Risk prediction from training data.
- Jacot, A., Gabriel, F., and Hongler, C. (2018). Neural Tangent Kernel:
  Convergence and Generalization in Neural Networks. In *Advances in Neural Information Processing Systems 31*, pages 8580–8589. Curran Associates, Inc.

### Bibliography II

- Lee, J., Xiao, L., Schoenholz, S., Bahri, Y., Novak, R., Sohl-Dickstein, J., and Pennington, J. (2019). Wide neural networks of any depth evolve as linear models under gradient descent. In *Advances in neural information processing systems*, pages 8572–8583.
- Lee, J. H., Bahri, Y., Novak, R., Schoenholz, S. S., Pennington, J., and Sohl-Dickstein, J. (2018). Deep Neural Networks as Gaussian Processes. *ICLR*.
- Neal, R. M. (1996). *Bayesian Learning for Neural Networks*. Springer-Verlag New York, Inc., Secaucus, NJ, USA.